



多特征情况: X 为特征矩阵, $\vec{\theta}$ 为参数向量, \vec{y} 为真实值向量
偏差已加入

$$h_{\vec{\theta}}(X) = X\vec{\theta}$$

$$L(\vec{\theta}) = \frac{1}{2m} \|h_{\vec{\theta}}(X) - \vec{y}\|^2$$

$$= \frac{1}{2m} (h_{\vec{\theta}}(X) - \vec{y})^T (h_{\vec{\theta}}(X) - \vec{y})$$

$$= \frac{1}{2m} (X^T \vec{\theta}^T X \vec{\theta} - \vec{\theta}^T X^T \vec{y} - \vec{y}^T X \vec{\theta} + \vec{y}^T \vec{y})$$

$$\frac{\partial L(\vec{\theta})}{\partial \vec{\theta}} = \frac{\partial (X^T \vec{\theta}^T X \vec{\theta} - \vec{\theta}^T X^T \vec{y} - \vec{y}^T X \vec{\theta} + \vec{y}^T \vec{y})}{\partial \vec{\theta}}$$

$$= \frac{\partial X^T \vec{\theta}^T X \vec{\theta}}{\partial \vec{\theta}} - \frac{\partial \vec{\theta}^T X^T \vec{y}}{\partial \vec{\theta}} - \frac{\partial \vec{y}^T X \vec{\theta}}{\partial \vec{\theta}} + \frac{\partial \vec{y}^T \vec{y}}{\partial \vec{\theta}} = 0$$

$$\text{即} \quad = 2\vec{\theta}^T X^T X - \vec{y}^T X - \vec{y}^T X + \vec{0}^T = 0$$

$$2\vec{\theta}^T X^T X - 2\vec{y}^T X = 0$$

$$\vec{\theta} = (X^T X)^{-1} X^T \vec{y}$$

$\vec{\theta}$ 为最优解