1EOR 6613

Optimization I

HW #1

1.7, 1.11, 1.20, 2.5, 2.6, 2.10, 2.13, 2.14

Moment problem
$$\frac{Z \in \{D, J, ..., K\}}{Z \in \{D, J, ..., K\}} \quad \text{w.p. Po.,..., PK}$$

$$IE[3] = \sum_{k=0}^{K} k \cdot P_{k}, IE[3^{2}] = \sum_{k=0}^{K} k^{2} \cdot P_{k}$$

$$IE[3^{4}] = \sum_{k=0}^{K} k^{3} \cdot P_{k}$$

$$F_{k} \geq 0 \quad \text{for } k \in \left\{0, 1, ..., k\right\}$$

$$IE\left[2\right] = \sum_{k=0}^{K} k^{k} P_{k}$$

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$$|E[2] = \sum_{k=0}^{K} k^{2} P_{k}$$

$$|E[2^{2}] = \sum_{k=0}^{K} k^{2} P_{k}$$

## [1:11] optimal currency conversion:

Neuroncles, exchange rate (; limit ut that can be exchanged, No arbitrage B currency 1

maximize 
$$x_N$$
  $\iff$   $min - x_N$ 

s.t.  $\sum_{j=2}^{N} c_{ij} \le B$ 

$$\sum_{i=1}^{N} c_{ij} \le u_i$$

$$c_{ij} \ge 0$$

$$x_j = x_j + c_{ij} c_{ij} \text{ for } j = 1,..., N$$

$$x_i = x_i - c_{ij} c_{ij} \text{ for } i = 1,..., N$$

Let S = {Ax | x & IR"} for given A. s is a subspace of 12".

PF;

Pf:

PEF: A nonempty ruleset . S of IR" is a subspace of IR" if ax + by ES Vx, y eS and & a, b e IR.

- (1) By det, DeR. Let x=0. Given any A, A.D. 6 S.
- (ii) Again, trivially, for given notion A , the vector x, + 1R7, and scalar ce1R, c(Ax,) + S. b/c c.Ax, = Ax2 where \*2 = c.x1. Since Ax2 & S by definition, c.Ax, & S. Therefore, & is closed under scalar multiplication.
- (iii) Let a, be IR. choose x, y + IR". Define 7 = ax + by . Clearly, 4 = IR". By def., Az 65°. Now, A2 = A(ax+by) . A.ax + A.by. Hence, S is placed under addition + scalar multiplication. By (i), (ii), ciii), S E IP."
- (b) Assume S is a proporsubspace of IR". Then, 3 matrix B s.t. S = {y \in R" | By = 0}.

Pf: DEF: S is a proper subspace so sis a subspace of RM and Exp IR. Since S is a proper subspace, I non-zero rector a L S s.t. a'x = 0 4x & S. Construct B s.t. its rows are composed of vectors that are orthogonal to vectors in IR" Since y elem, we now have a matrix B st. our propersubspace of IR", S, can be defined as S = {y elem | By = o}

(6) Suppose V is m-dimensional affine subspace of R", m < n. Show I linearly independent vectors as ..., ann and scalars bis..., bam s.t. V= { y| a'y = bis i=15...s n-m}

Since V is an affine subspace of IRM, V=Vo+x = {x+x0 | x6 Vo} for some x0 what V0 is a V is m-dimensional meaning that  $V_0 = V - \chi^0 \neq IR^M$ .  $\Longrightarrow$   $Y_0$  is a proper subspace of  $IR^M$ . In fact, Vo has dimension men and by daf. of a proper subspace, I non-sero vector a L Vo s.t. a'x=0 Vx + Vo. fiven m-dimensionality, 3 n-m linearly independent vectors orthogonal to Vo.

Therefore, Yo = {x | ai'x = 0, i= 1, ..., x-m}

Define y := x + x and b = x. where bi = xi for i=1, ..., n-m. Then, we have linearly independent vectors a, ..., anom is scalars b, ..., b, m s.t. V = {y|a: y = bi, i=1, ..., anon} 2.5 Extreme points of isomorphic polyhedra

DEF: A mapping f is affine if it is of form f(x) = Ax + b, where A is a metrix and b is a vector. Let  $P \in IR^n$ ,  $Q \in IR^m$  where P, Q are polyhedra.

DEF: P and Q are isomorphic if 3 office mappings  $f: P \mapsto Q$  and  $g: Q \mapsto P$  s.t.  $g(f(x)) = x \ \forall x \in P$  and  $f(g(y)) = y \ \forall y \in Q$ .

(a) Let P, R be isomorphic. Then, I enerto-one correspondence b/w their extreme points.

In particular, if f i g are as above, x is an extreme pt. of P (x) f(x) is an extreme pt of Q.

DFF: A vector  $x \in P$ , a polyhedron, is an extreme PP of P if we cannot find two vectors  $y, y \in P$   $y, z \not= x$ , and scalar  $\lambda \in [a, i]$  of  $x = \lambda y + (1-\lambda)y$ . (i.e., not a convex combination of y, y).

Pf:

By THM 2.1, Since Pis a polyhedron, Pis a convex set

By THM 2.3, given a non-empty polyhedron P and x + P, x is a vertex ← x is a

Assume x" be extreme pl. of P. Define y" - f(x")

By THM 2.3, x is a vortex of P. By Def. 2.7, since x is a rortex of P, I rector a sit. a'x < a'x \text{VxEP, xxx.

For any y & Q, y & y", f(g(y)) = y & y = f(x) => g(y) & g(y) = x for g(y) & P. (using P, 0's isomorphic ).

Let offine function g(y) = By +d for B & R nxm and d & R".

Then, c'(By+d) < c'(By+d) \ Yy + Q, y + y . -> (B'c)'y < (B'c)'y + Yy + Q, y + y .

Suppose y' is NOT an extreme pt. of Q.

Then, y' = ly, + (1-2) y = for some y,, y : E Q, y, y = y' and le (0,1) i.e., y' is a convex combine from of two other pts. in Q.

=> / (B'c)'y < (B'c)'y + y = 0, y=y which is a contendiction.

b/c (B'c)'y'= \(B'c)'y, + (1- \)(B'c)'y, <(B'c)'y".

Contradiction  $\Rightarrow$  y' = f(x) is an extreme pt. of Q.

(4)
Assume y'= f(x') is an extreme pt. of Q. => y' is a vertex of P => 7 c s.t. c'y < c'y \* YyeP, y \* y'.

Ret x' = g(y').

For any  $x \in P$ ,  $x \neq x^*$ ,  $g(f(x)) = x \neq x^* = g(y^*) \Rightarrow f(x) \neq f(x^*) = y^*$  for  $f(x) \in P$ . (by isomorphism of P, Q)

Given affine function f(x) := Ax+b for A & IR mxn, b & IR m,

c'(Ax+b) < c'(Ax+b) \xeP, xxx = (A'c)'x < (A'c)'x \xeP, xxx.

Similarly as above, if x is NOT an extreme pt., this above statement would not hold and we would have a contradiction, hence proving the (4) side of the argument. (the only if side)

2.5(b) latroducing slock variables to isomorphic polyhedron

Ret  $P = \{x \in \mathbb{R}^n \mid Ax \ge b, x \ge 0\}$ ,  $A \in \mathbb{R}^{k \times n}$  $O = \{(x, 4) \in \mathbb{R}^{n+k} \mid Ax - 4 = b, x \ge 0, 4 \ge 0\}$ 

P. Q are isomorphic.

Pf: Let f,g be affine mappings for  $P\mapsto Q, Q\mapsto P$ , respectively.

We can see the following:

f(x) & Q.

g(f(x)) = x YxeP.

AND glx, 4) & P.

Thus, by def., P, Q are isomorphic

## 2.6 Carathéody's Theorem

=> A 1 = 4

Al, ... , An are a collection of vectors in 12th.

(a) fat 
$$C = \left\{ \sum_{i=1}^{n} \lambda_{i} A_{i} \mid \lambda_{i}, \lambda_{n} \geq 0 \right\}$$

Show any element of C can be expressed in the form  $\sum_{i=1}^{n} \lambda_i A_i^2 = \sqrt{\lambda_i^2} = 0$  and  $w_i^2$  and  $w_i^2$  of the coefficients  $\lambda_i^2$  being non-zero.

Pf:

The polyhedron 
$$\Delta$$
 is formulated as follows:  $\begin{bmatrix} A_1 & A_2 & ... & A_n \end{bmatrix}$   $\begin{bmatrix} A_1 & A_2 & ... & A_n \end{bmatrix}$   $\begin{bmatrix} A_1 & A_2 & ... & A_n \end{bmatrix}$   $\begin{bmatrix} A_1 & A_2 & ... & A_n \end{bmatrix}$   $\begin{bmatrix} A_1 & A_2 & ... & A_n \end{bmatrix}$   $\begin{bmatrix} A_1 & A_2 & ... & A_n \end{bmatrix}$   $\begin{bmatrix} A_1 & A_2 & ... & A_n \end{bmatrix}$   $\begin{bmatrix} A_1 & A_2 & ... & A_n \end{bmatrix}$   $\begin{bmatrix} A_1 & A_2 & ... & A_n \end{bmatrix}$  and  $A = \begin{bmatrix} A_1 & A_2 & ... & A_n \end{bmatrix}$  and  $A = \begin{bmatrix} A_1 & A_2 & ... & A_n \end{bmatrix}$ 

Assuming full row rank of A: ( rank (A) = m), \ \ \ \ \ = (AT) y.

where  $A^{-1} = \begin{bmatrix} A_B & A_N \end{bmatrix}$  where  $A_B$  has m non-zero vectors and  $A_N$  has n-m zero vectors for their respective columns.

Hence, li has m non-zero coefficients.

In the case where rank(A) <  $m_r$  d; has <  $m_r$  non-zero coefficients b/c  $A^{-1}$  = [AB AN] where AB has rank(A) non-zero vectors as columns and AN has  $n_r$ -rank(A) zero columns.

Therefore, for lizo, li has is m non-zero coefficients.

2.6(b) Carathéodry & THH:

Let P be the convex hull of vectors A:  $P = \left\{ \sum_{i=1}^{n} \lambda_i A_i \middle| \sum_{i=1}^{n} \lambda_{i+1}, \lambda_{i}, ..., \lambda_{n-2} o \right\}$ 

Then, any element of P can be expressed in the form  $\sum_{i=1}^{n} \lambda_i A_i$  where  $\sum_{i=1}^{n} \lambda_i \geq 0$   $\forall i$ , with at most m+1 coefficients x; being non-zero

Pf: Analogous to part (a), consider an element of P:

Let x & P, a point in the convex hall P.

Then, x is a convex combination of a finite number of points in P:  $x = \sum_{i=1}^{n} \lambda_i x_i$ ,  $\sum_{i=1}^{n} \lambda_i x_i = 1$ .  $\lambda_i \in [0, i]$ .

- (i) Trivial case: n = m+1
- (ii) Suppose n>m+1.

Then, consider the linear dependence of \*z-x, ..., xn-x,.

Therefore, FM, .., M, ER S.t. \$ M; (Kj-X1) -0

Define Miss - 5 Mg.

Then, Zwix = 0.

Silly = 0. where notall ly = 0. => 3 My >0 for jeffy , n}

 $x = \sum_{i=1}^{n} \lambda_{i} x_{i} - c \cdot \sum_{i=1}^{n} \mathcal{A}_{i} x_{i} = \sum_{i=1}^{n} (\lambda_{i} - c \mathcal{A}_{i}) x_{i} \quad \text{for some } c \in \mathbb{R}.$ 

Set c:= min { hi/M; : M; > 0} = \frac{\lambda}{M} and the equality will hold.

For ero, to leien, li-chizo. By defining casabove, li-en; = 0

x = \sum\_{i=1}^{\infty} (\lambda: -culis ) xi. where every \lambda: -culiso, \sum\_{i=1}^{\infty} (\lambda: -culi) = 1,

and li-cut = 0.

This means that x is represented as a convex combination of at most in-1 points of P. Since n>m+1, this is equivalent to at most non-zero coefficients of hi.

[2.10] P= {x/Ax=b, x=20}

A = IR man w/ linearly independent rows.

rank (A) = m.

(a) If n=m+1, P har at most 2 BFS.

TRUF.

Pf: m=n-1. The polyhedron Plies in an affine subspace w/ m=n-1 linearly independent constraints

Every solly of Axab takes the form: X1 + CX2 where X1 EP and CEIR, when x2 is a

mon-zero vector. This means the set P is contained in aline. If & 3 BFS, the middle

extreme pt. would be a convex combination be the 2 extreme pts \$300 BFS not an

extreme pt. Contradiction. Therefore, \$\frac{1}{2} \text{SFS for n=mtl.}

(b) The set of all optimal solutions is unbounded.

FALSE.

Pf: Consider minimizing a st. x = a. for arbitrary CGIR. The optimal value is Avel But,
The optimal rol's set x & [0, 00) is unbounded.

(c) At every optimal sol'n, no more than m variables can be positive.

FALSE.

Pf Consider c = 0 in standard form.

Now, we can have on positive viriables (assuming n > m)

(d) If there are several optimal solins, then I at least 2 optimal BFS.

FALSE

Pf: A counter example would be one in which there are many optimal solutions but only only one BFS/vertex/extreme pt. Consider: min x, only the origin is a

s.t. x, 20

only the origin is a

BFS. But, we have

uncountably many sptimul

solutions w/ x<sub>1</sub> = 0.

(e) If there is more than one optimal sol'n, then there are uncounitably many optimal solutions.

TRUE.

Pf: b/c any convex combination of the optimal solutions are Hill optimal.

A line for example has uncountably many pts on the segment blw its 2 endpoints.

(f) Consider minimizing max {c'x, 8'x} over P. If this has optimal sol'n, the optimal is at an extreme pt of P.

FALSE.

Pf: The optimal sol'n need Not occur at an extreme pt.

consider: min f max (1-x1, x1-1)}

s.t. KIZO

The optimal solin is at x1= 2. BUT, the only extreme pt. of Pts at x=0.

2.13  $P = \{ x \mid Ax = b, x \ge 0 \}$ At  $R^{mx}$  w/ linearly independent rows

All BFS are nondegenerate in P.

Let x + P s.t x has exactly m por components.

## (a) x is a BFS

Pf: A is a full row rank (rant(A)=m) and x has exactly m positive components (x e IRm)

=> all equality constraints are active.

=> we have m linearly independent constraints active at x.

By DEF 2.9, x is a basic solution.

All BFS are nondegenerat in  $P \Rightarrow basic sol'n \times elem does not have more than most the constraints active at <math>x$ .

Therefore, & is a basic col' that satisfies all constraints.

=> x is a B.F.S.

## (b) If Frondequeracy assumption, & is not BFS.

We showed above that without the nondegeneracy assumption, we can only prove that x is a basic solution, but not necessarily a BFS.

Suppose x & IRP, x & P is B.F.S.

By DEF 2.9, x satisfies all constraints. + all equality constraints active we are given A & IR men which is linearly independent => full rank => rank (A) = m.

AND x has exactly m positive components.

I (m+1)th constraint active at x. => x not degenerate.

2.14 P is a bounded polyhedron in IRM.

be IR

Define Q := {x e P | a'x = b}

Every extreme pt. of Q is an extreme pt. of P or a convex combination of 2 adjacent extreme pts. of P.

Pf: Given a EIR", b EIR.

is sol'n of a'x = b. Depending on # non-zero components of a, x' can be a pt, a live, a hyperplane.

Q is the set of x' intersecting polyhedron P.

(i) Suppose a has n non-eard components. Then, x is a pt. in P. since & convex combination blow Extreme pts in P, x is an extreme pt. in P. By DEF 2.9, x is a B.F.S. of Q by THM 2.6 since Q hee does NOT contain lines, just 3 et of extreme pts.

(ii) Consider the case that a has « n non-eard components, eall it le < n.

Then, x takes the form of a line or hyperplane.

Geometrically, Q = x 1 P.

Since x now takes the form of a pt. and at least pre vector.

In the directions of a's zero - components, solly i extends.

Yet, P is bounded and conver.

Thus, x' will either hit an extreme pt. of P, otherwise, it will hit an edge which is a cc. of 2 adj. vertices of P.

11 This intersection is an extreme pt. of Q.