# Real-Time CAN Communication System with FreeRTOS and IoT Integration

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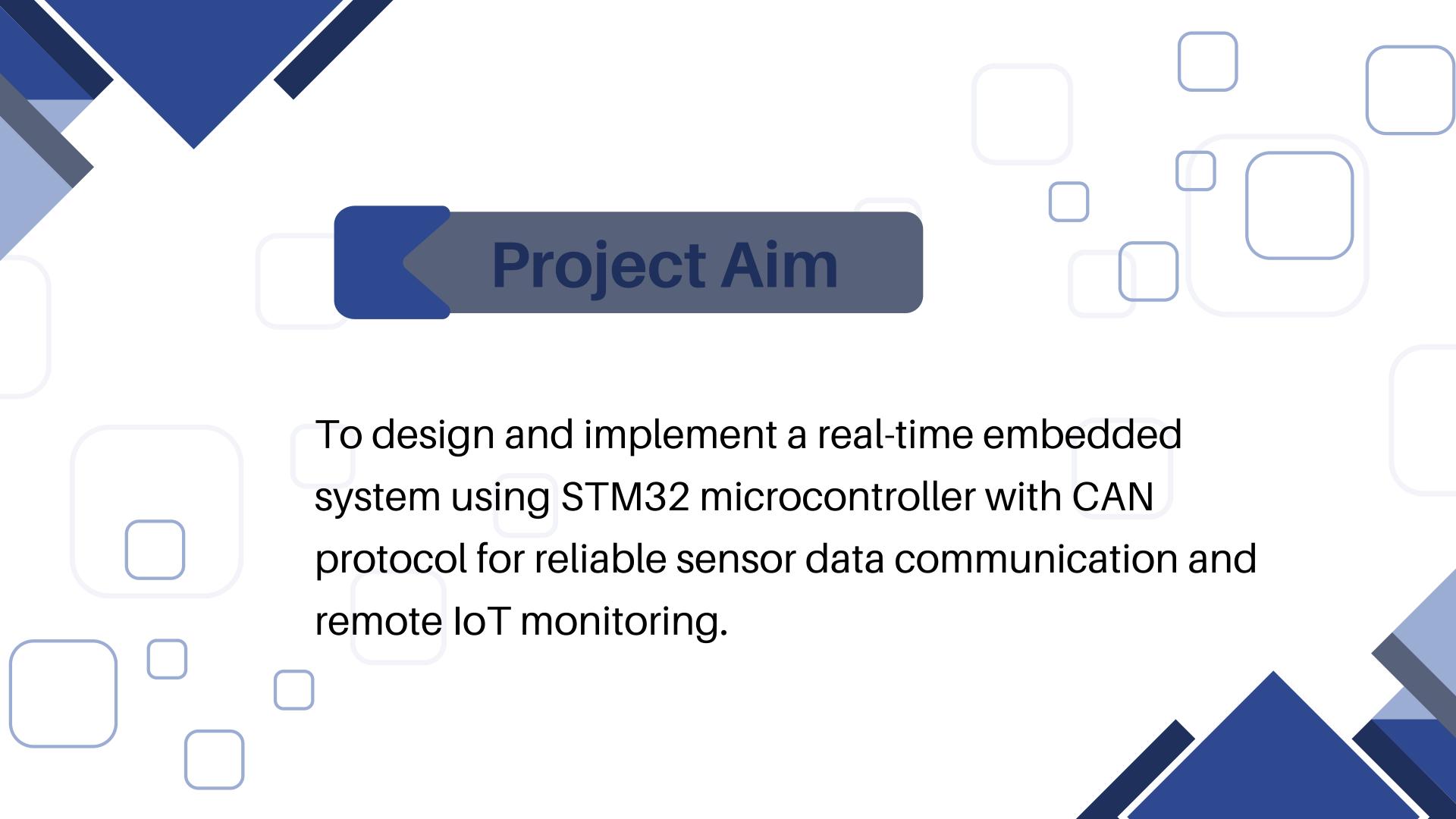
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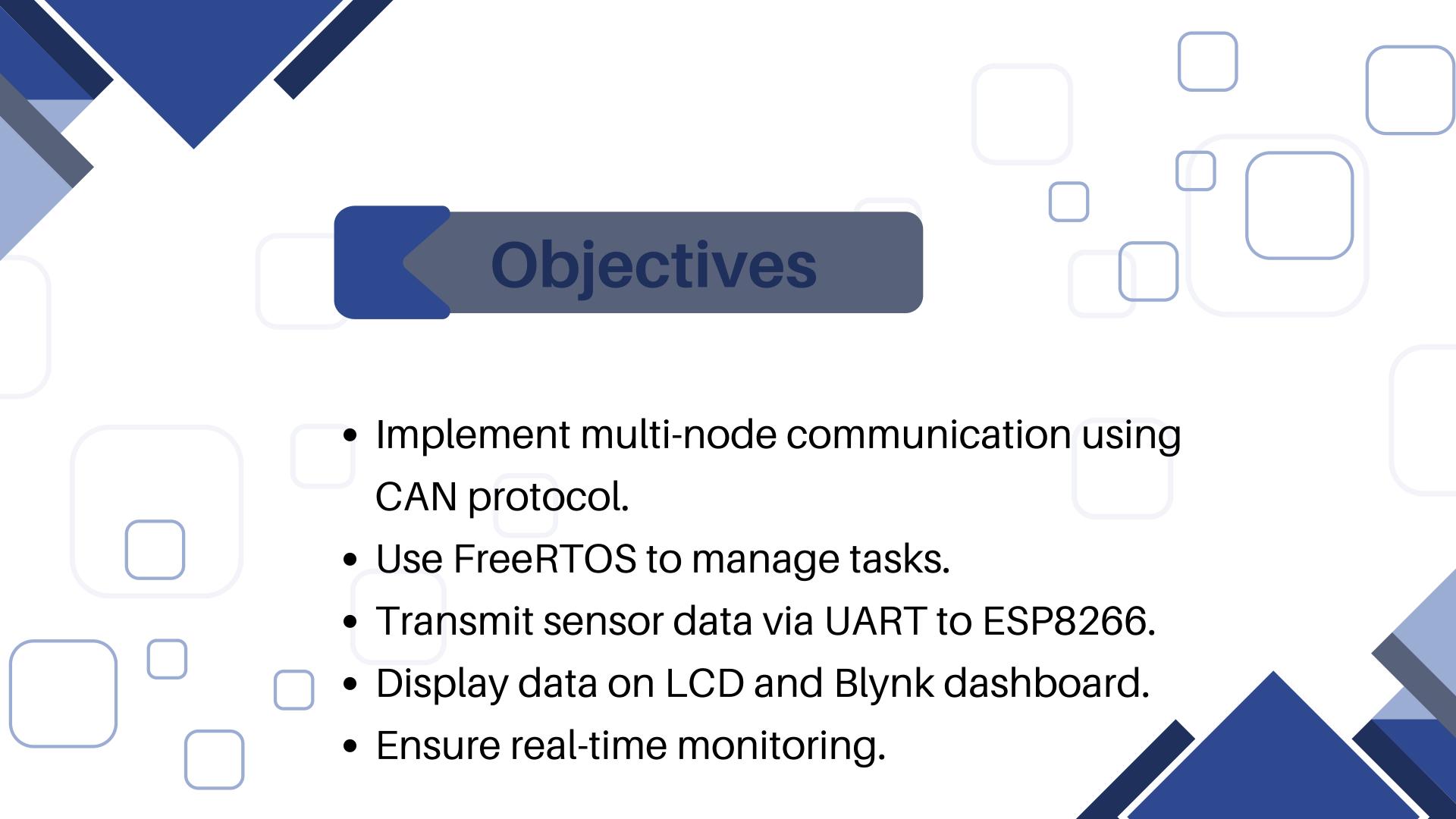
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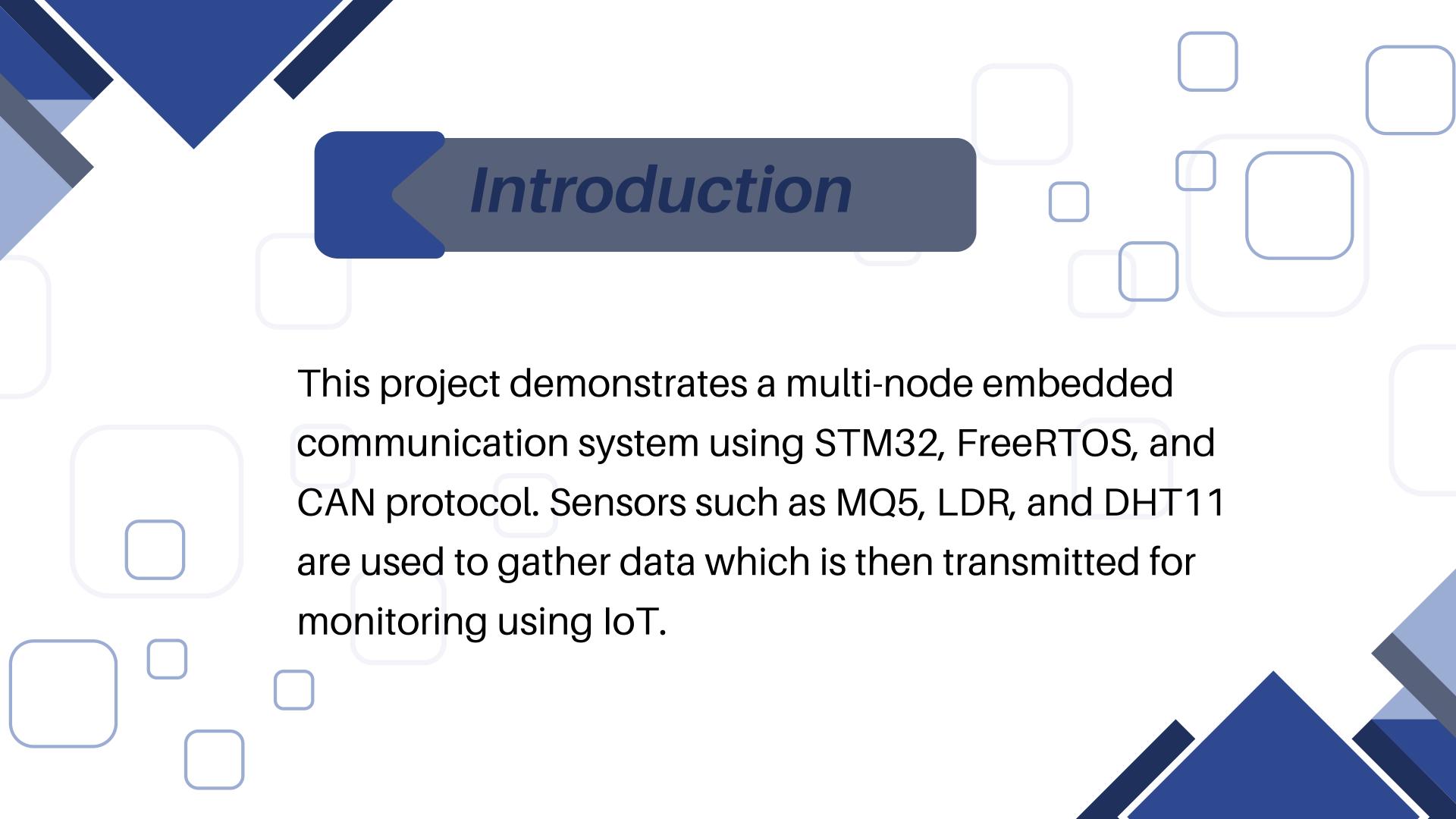
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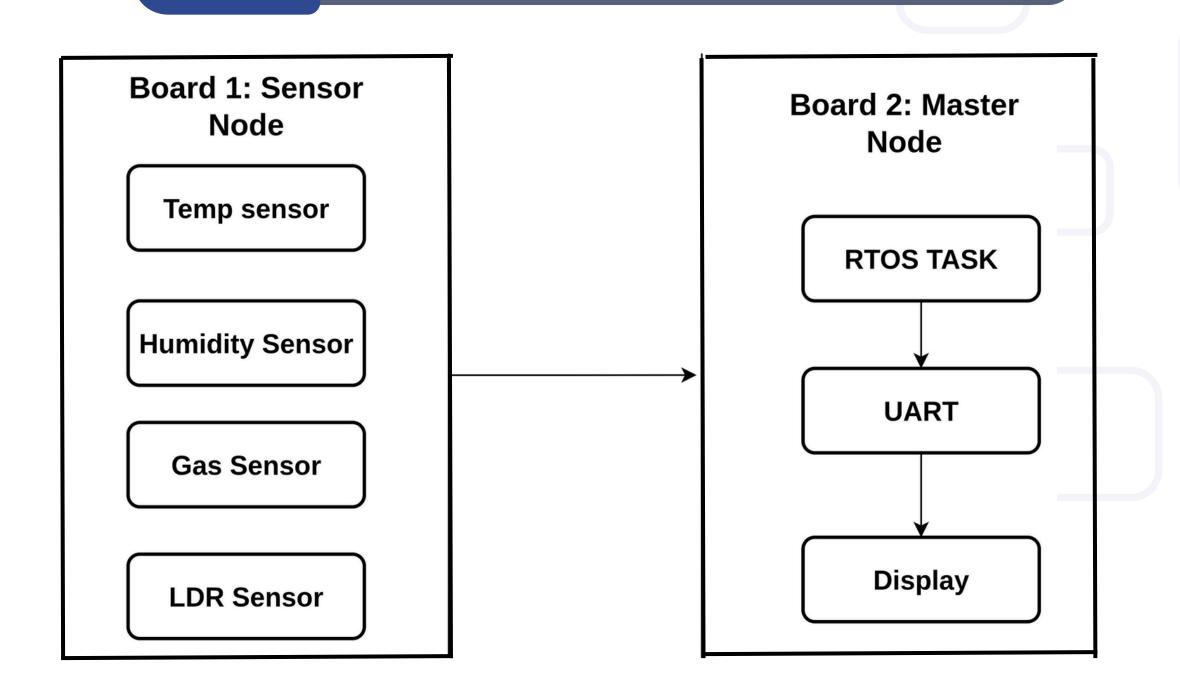
#### Hardware Components

- STM32F407 Microcontrollers (2 nodes).
- MQ5 Gas Sensor, LDR Sensor, DHT11
  Temp and Humidity Sensor.
- CAN Transceivers.
- ESP8266 (NodeMCU).
- 16x2 I2C LCD Display.

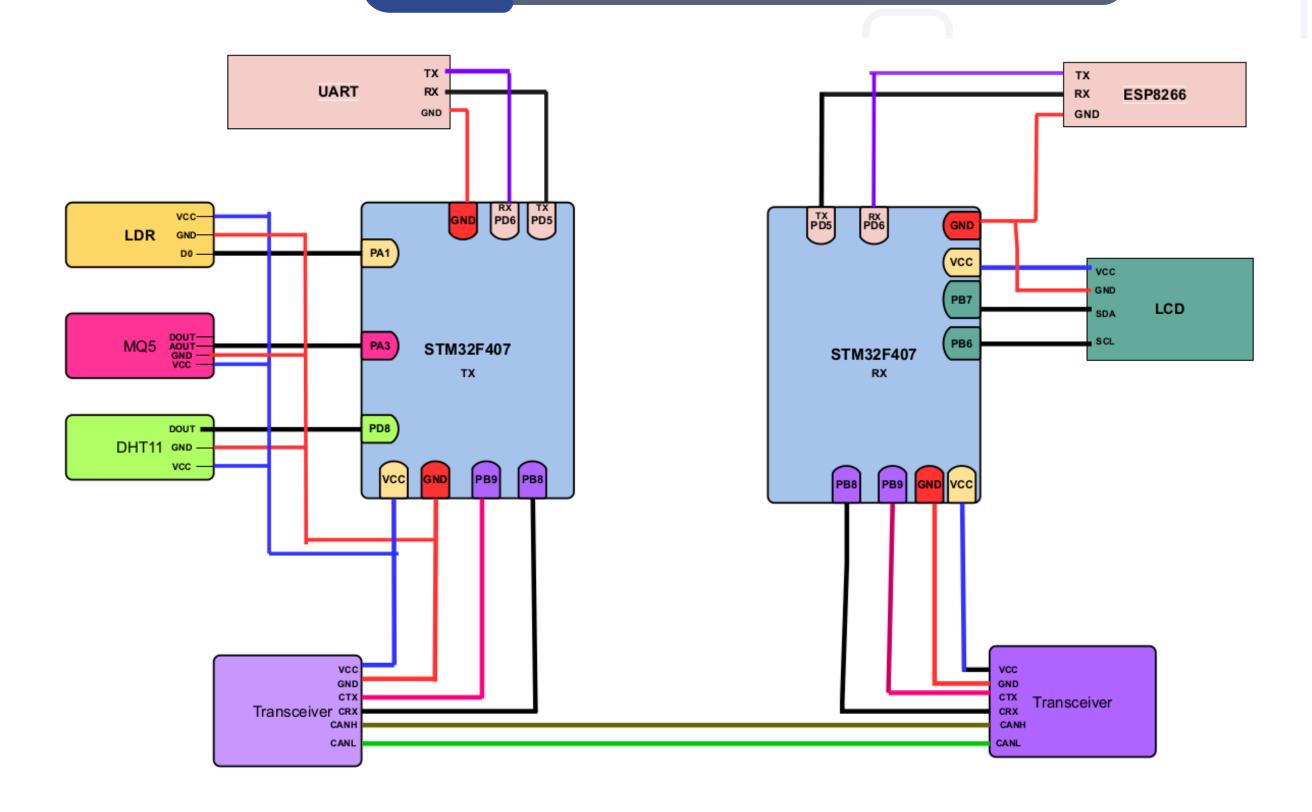
#### Software Technologies

- FreeRTOS for real-time task management
- HAL drivers for ADC, UART, I2C, CAN
- Flask + MySQL server for IoT backend
- Blynk for real-time mobile dashboard

## Block Diagram



# Pin Diagram



#### Project Architecture

- TX Node reads data from sensors → sends Using CAN.
- RX Node receives CAN data → displays on LCD.
- RX Node forwards data using UART to ESP8266.
- ESP8266 uploads data to Flask server and Blynk dashboard.

#### FreeRTOS Tasks

- Sensor Reading Task (MQ5, LDR, DHT11)
- CAN Communication Task (TX and RX)
- LCD Display Task
- UART Communication Task to ESP8266

#### **CAN Communication**

- Used CAN protocol for STM32 to STM32 communication.
- Reliable, real-time, and noise-resistant data transfer.
- Each message contains sensor data packet.
- CAN filtering used to process specific IDs.

### IoT Integration

- ESP8266 sends data to cloud via HTTP.
- Flask server receives and stores in MySQL.
- Blynk app shows live sensor data on phone.
- Remote monitoring enabled over Wi-Fi.

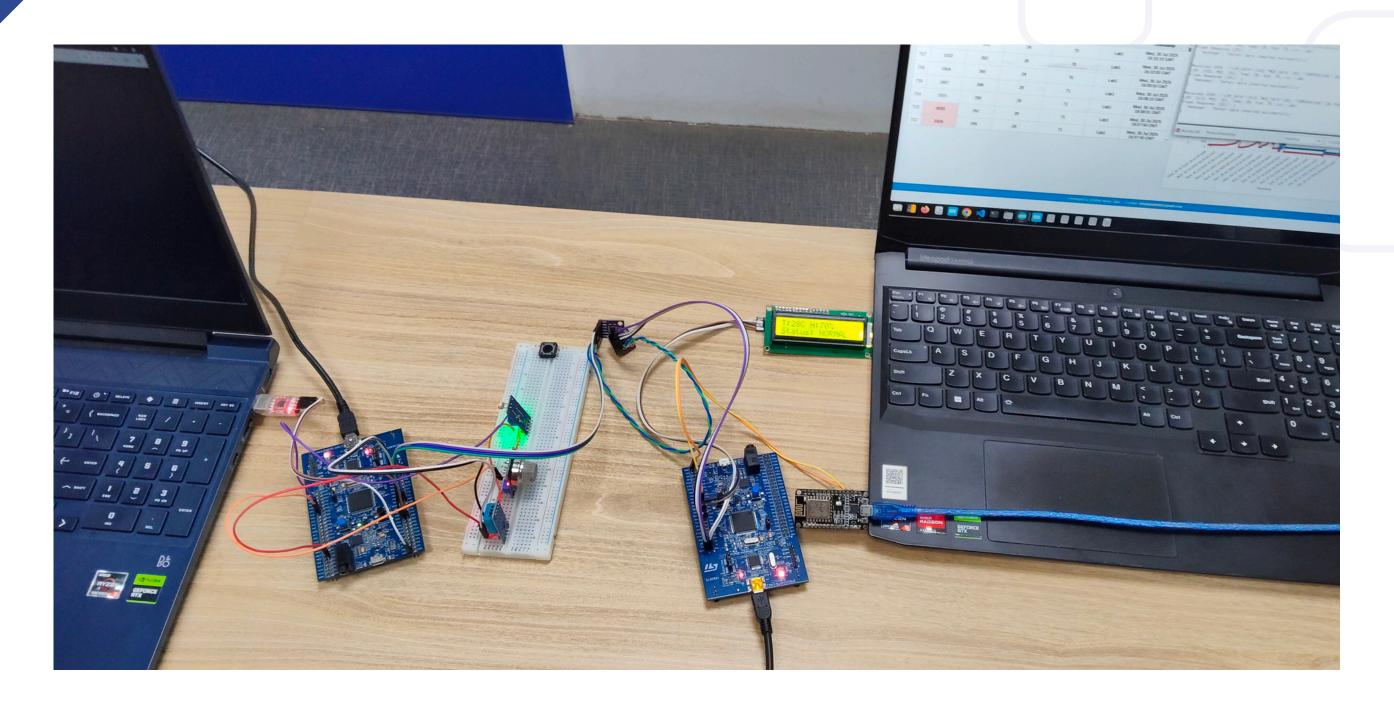
# Future Enhancements Add more sensor nodes on CAN bus.

- Add encryption/security to data transmission.
- Improve calibration for gas sensor.
- Add web-based dashboard for data visualization.

#### Application

- Smart Environment Monitoring System
- Gas Leakage Alert System
- Industrial Safety Systems
- Remote Sensor Data Dashboard

#### OUTPUT



https://drive.google.com/file/d/1YwYvyide56KVHidUxSF0YnXKjhQHA1qU/view?usp=drivesdk

