

**Department of Engineering Cybernetics,   
Automation Technology Programme**

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| **Course: TELE3001 Bachelor Thesis** | | | | | | **Date:** 10.01.2019 |
| **Project:** Instrumentation of bipedal robotprototype | | | | | | |
| **Activity:** Create Work Packages | | | | | | **Activity nr:** 01 |
| **Starting date:** 10.01.2019 | | | **End date:** 21.01.2019 | | | |
| **Dependency:** | **Past Activities:** | |  | | | |
| **Following**  **Activities:** | | (Component research)  Finish project description | | | |
| **Goal:** | | | | | | |
| **Description:** Divide all objectives into work packages, assign team members to each objective. Describe each objective and its duration. Split total work hours reasonably across all objectives and team members. | | | | | | |
| **Total Workload:** 20 hours | | | **Work distribution:**  Jonas | 20 hours | | |
| **Expenses:** | | | | | | |
| **Resources:** | | | | | | |
| **Hazards:** | | | | | | |
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