

**Department of Engineering Cybernetics,   
Automation Technology Programme**

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| **Course: TELE3001 Bachelor Thesis** | | | | | | **Date:** 10.01.2019 |
| **Project:** Instrumentation of bipedal robotprototype | | | | | | |
| **Activity:** Workplan | | | | | | **Activity nr:** 02 |
| **Starting date:** 10.01.2019 | | | **End date:** 21.01.2019 | | | |
| **Dependency:** | **Past Activities:** | |  | | | |
| **Following**  **Activities:** | | Finish project description | | | |
| **Goal:** Create a completion plan containing work distribution and deadlines | | | | | | |
| **Description:** Create Gantt-diagram to visualize how much time is going to be spent on each work load throughout the project. Specify deadlines and special cases where standard workplan can’t be followed. Set general dates for all meetings inside the group and with supervisor. | | | | | | |
| **Total Workload:** 20 hours | | | **Work distribution:**  Kristoffer | 20 hours | | |
| **Expenses:** | | | | | | |
| **Resources:** | | | | | | |
| **Hazards:** | | | | | | |
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