

**Department of Engineering Cybernetics,   
Automation Technology Programme**

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| **Course: TELE3001 Bachelor Thesis** | | | | | | **Date:** 28.01.2019 |
| **Project:** Instrumentation of bipedal robotprototype | | | | | | |
| **Activity:** Problem/solution-mapping | | | | | | **Activity nr:03** |
| **Starting date:** 14.01.2019 | | | **End date:** 31.01.2019 | | | |
| **Dependency:** | **Past Activities:** | | Work Packages | | | |
| **Following**  **Activities:** | | Component research | | | |
| **Goal:** Find all viable problems to solve during the project. Consider different solutions for these issues. | | | | | | |
| **Description:** | | | | | | |
| **Total Workload:** | | | **Work distribution:**  Kristoffer  Jakob  Henrik |  | | |
| **Expenses:** | | | | | | |
| **Resources:** | | | | | | |
| **Hazards:** | | | | | | |
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