

**Department of Engineering Cybernetics,   
Automation Technology Programme**

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| **Course: TELE3001 Bachelor Thesis** | | | | | | **Date:** 24.01.2019 |
| **Project:** Instrumentation of bipedal robot prototype | | | | | | |
| **Activity:** Documentation | | | | | | **Activity nr:12** |
| **Starting date:** 04.02.2019 | | | **End date:** 27.05.2019 | | | |
| **Dependency:** | **Past Activities:** | | Finish project description | | | |
| **Following**  **Activities:** | |  | | | |
| **Goal:** To have all work done during project documented and structured in final bachelor thesis report | | | | | | |
| **Description:** Write down all work performed on the robot, and all information required to use components mounted on it. Refer to and explain theory applied during the project with a good structure | | | | | | |
| **Total Workload:** 400 hours | | | **Work distribution:**  Kristoffer  Jakob  Henrik  Jonas  Endre | 80 hours  80 hours  80 hours  80 hours  80 hours | | |
| **Expenses:** | | | | | | |
| **Resources:** Leg mounting bracket, hip stabilizer | | | | | | |
| **Hazards:**  Motor torque,Voltage | | | | | | |
| **Project supervisor:**  Torleif Anstensrud  **Project team members:**  Jakob Karlsen  Jonas Hjulstad  Endre T.Ellingsen  Henrik Baldishol  Kristoffer Nordvik | | **Mail:**  [torleif.anstensrud@ntnu.no](mailto:torleif.anstensrud@ntnu.no)  [jakob-karlsen@outlook.com](mailto:jakob-karlsen@outlook.com)  [jonasbhjulstad@gmail.com](mailto:jonasbhjulstad@gmail.com)  [endre.t.e@hotmail.com](mailto:endre.t.e@hotmail.com)  [henrik.baldishol@gmail.com](mailto:henrik.baldishol@gmail.com)  [kristono@stud.ntnu.no](mailto:kristono@stud.ntnu.no) | | | **Tlf:**  95808760  46676230  40523352  46672181  95300104  99117516 | |