### Exercises 4.17

## Exercise 4.17.1

Let  $f(x_1, x_2) = e^{x_1} \sin(x_2)$ , with  $(x_1, x_2) \in (0, 1) \times (0, \frac{\pi}{2})$ .

- a. Show that f is a harmonic function;
- b. Find  $\|\nabla f\|$ ;
- c. Show that the equation  $\nabla f = 0$  does not have any solutions;
- d. Find the maxima and minima for the function f.

### Exercise 4.17.2

Consider the quadratic function  $Q(\mathbf{x}) = \frac{1}{2}\mathbf{x}^T A\mathbf{x} - b\mathbf{x}$ , with A nonsingular square matrix of order n.

- a. Find the gradient  $\|\nabla Q\|$ ;
- b. Write the gradient descent iteration;
- c. Find the Hessian  $H_Q$ ;
- d. Write the iteration by Newton's formula and compute its limit.

## Exercise 4.17.3

Let A be a nonsingular square matrix of order n and  $b \in \mathbb{R}^n$  a given vector. Consider the linear system  $A\mathbf{x} = b$ . The solution can be approximated using the following steps:

- a. Associate the cost function  $C(\mathbf{x}) = \frac{1}{2} ||A\mathbf{x} \mathbf{b}||^2$ . Find its gradient,  $\nabla C(\mathbf{x})$ , and Hessian  $H_C(\mathbf{x})$ ;
- b. Write the gradient descent algorithm iteration which converges to the system solution  $\mathbf{x}$  with the inital value  $\mathbf{x}^0 = 0$ ;
- c. Write Newton's iteration which converges to the system solution  $\mathbf{x}$  with the initial value  $\mathbf{x}^0 = 0$ .

#### Exercise 4.17.4

- a. Let  $(a_n)_n$  be a sequence with  $a_0 > 0$  satisfying the inequality  $a_{n+1} \le \mu a_n + K$ ,  $\forall n \ge 1$ , with  $\mu \in (0,1)$  and K > 0. Show that the sequence  $(a_n)_n$  is bounded from above.
- b. Consider the momentum method equations (4.4.16) (4.4.17), and assume that the function f has a bounded gradient  $\|\nabla f\| \le M$ . Show that the sequence of velocities,  $(v^n)_n$  is bounded.

#### Exercise 4.17.5

a. Let f and g two integrable functions. Verify that

$$\int (f \star g)(x)dx = \int f(x)dx \int g(x)dx$$

- b. Show that  $||f \star g|| \le ||f||_1 ||g||_1$
- c. Let  $f_{\sigma} := f \star G_{\sigma}$  where  $G_{\sigma} = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{x^2}{2\sigma^2}}$ . Prove that  $||f_{\sigma}||_1 \leq ||f||_1$  for  $\sigma > 0$

## Exercise 4.17.6

Show that the convolution of two Gaussians is also a Gaussian:

$$G_{\sigma_1} \star G_{\sigma_2} = G_{\sigma}$$
, where  $\sigma = \sqrt{\sigma_1^2 + \sigma_2^2}$ .

# Exercise 4.17.7

Show that the if n have the sum equal to s,

$$\sigma_1 + \ldots + \sigma_n = s,$$

then the numbers for which the sum of their squares,  $\sum_{j=1}^{n} \sigma_j^2$ , its minimum occurs for the case when all the numbers are equal to  $\frac{s}{n}$ .

### SOLUTIONS

## Exercise 4.17.1 (a)

By definition a function is harmonic when satisfies the condition  $\nabla^2 f = 0$ . Let's corroborate this is indeed fullfilled by the function  $f(x_1, x_2) = e^{x_1} \sin(x_2)$ . For  $\frac{\partial^2}{\partial x_1^2} f$  and  $\frac{\partial^2}{\partial x_2^2} f$  we have:

$$\frac{\partial^2}{\partial x_1^2} e^{x_1} \sin(x_2) = \sin(x_2) \frac{\partial^2}{\partial x_1^2} e^{x_1} = e^{x_1} \sin(x_2)$$
$$\frac{\partial^2}{\partial x_2^2} e^{x_1} \sin(x_2) = e^{x_1} \frac{\partial^2}{\partial x_2^2} \sin(x_2) = -e^{x_1} \sin(x_2)$$

From the latter follows  $\nabla^2 f = \frac{\partial^2}{\partial x_1^2} f + \frac{\partial^2}{\partial x_2^2} f = 0$  i.e the function f is harmonic.

## Exercise 4.17.1 (b)

By the pythagorean identity between the trigonometric functions sin and cos follows:

$$\|\nabla f\| = \sqrt{\nabla f \cdot \nabla f} = \sqrt{(e^{x_1}\cos(x_2))^2 + (e^{x_1}\sin x_2)^2} = e^{x_1}$$

#### Exercise 4.17.1 (c)

$$\nabla f = (e^{x_1}\cos(x_2), e^{x_1}\sin(x_2)) = 0 \iff e^{x_1} = 0$$

The equation  $e^x = 0$  is known to not have a solution. Therefore,  $\nabla f = 0$  is not solvable.

## Exercise 4.17.1 (d)

Let's define the extension of f over the compact  $K := [0,1] \times [0,\frac{\pi}{2}]$  with the same association rule as above. On this set f is also harmonic. Then, f reaches its minimum and maximum on the boundaries of the set K; note that both functions  $e^{x_1}$  and  $\sin(x_2)$  are increasing, then the maxima is met at the point when both functions reach their maximum.

This means the maximum of the function f is met on the point  $(1, \frac{\pi}{2})$  with a value of  $f(1, \pi) = e$ . Likewise, the minimum is reached at the point (0,0) with a value of f(0,0) = 0.

## Exercise 4.17.2 (a)

Computing the gradient we get:  $\nabla Q = \frac{1}{2}(A + A^T)\mathbf{x} - b\mathbf{1}$ . Then, expressing the norm in terms of the interior product we have:

$$\|\nabla Q(\mathbf{x})\| = (\frac{1}{4}\mathbf{x}^T(A+A^T)^2\mathbf{x} - b\mathbf{1}(A+A^T)\mathbf{x} + b^2\mathbf{1}^T\mathbf{1})^{\frac{1}{2}}$$

#### Exercise 4.17.2 (b)

The equations that describe the iterations made in the GDA<sup>1</sup> is the sequence of vectors  $\{\mathbf{x}^n\}_{n\in\mathbb{N}}$  satisfying the following recursion:  $\mathbf{x}^{n+1} = \mathbf{x}^n - \delta(\frac{1}{2}(A+A^T)\mathbf{x}^n - b\mathbf{1})$ 

<sup>&</sup>lt;sup>1</sup>From now on, the learning rate  $\delta$  in the GDA an its variants will be supposed constant, unless is stated otherwise.

## Exercise 4.17.2 (c)

From excercise 4.17.2.a we know that  $\nabla Q = \frac{1}{2}(A + A^T)\mathbf{x} + b\mathbf{1}$ . Note that taking the derivative of a vectorial function is indeed the same as computing its Hessian-matrix. By using the afore mentioned observation, we get:

$$H_Q(\mathbf{x}) = \frac{\partial}{\partial \mathbf{x}} \nabla Q = \frac{1}{2} (A + A^T).$$

## Exercise 4.17.2 (d)

The sequence of iterations produced by Newton's method  $\{\mathbf{x}^n\}_{n\in\mathbb{N}}$  are given with following recurrence relationship:

$$\mathbf{x}^{n+1} = \mathbf{x}^n - (\frac{1}{2}(A + A^T))^{-1}(\frac{1}{2}(A + A^T)\mathbf{x}^n - b\mathbf{1})$$
$$= (\frac{1}{2}(A + A^T))^{-1}b\mathbf{1}.$$

We note that the sequence is a constant. This in turn implies the limit is trivially given by the expression:  $\mathbf{x}^* = (\frac{1}{2}(A + A^T))^{-1}b\mathbf{1}$ .

## Exercise 4.17.3 (a)

Expressing C as a quadratic form and simplifying we get:  $C(\mathbf{x}) = \frac{1}{2}\mathbf{x}^T A^T A \mathbf{x} - \mathbf{b}^T A \mathbf{x} + \frac{1}{2}\mathbf{b}^T \mathbf{b}$ . On the other hand, the fact that the matrix  $A^T A$  is symmetric, yields:

• 
$$\nabla C(\mathbf{x})$$
:  

$$\frac{\partial}{\partial \mathbf{x}} C(\mathbf{x}) = \frac{\partial}{\partial \mathbf{x}} \left[ \frac{1}{2} \mathbf{x}^T A^T A \mathbf{x} - \mathbf{b}^T A \mathbf{x} + \frac{1}{2} \mathbf{b}^T \mathbf{b} \right]$$

$$= A^T A \mathbf{x} - \mathbf{b}^T A$$

• 
$$H_C(\mathbf{x})$$
:  

$$\frac{\partial^2}{\partial^2 \mathbf{x}} C(\mathbf{x}) = \frac{\partial}{\partial \mathbf{x}} \left[ A^T A \mathbf{x} - \mathbf{b}^T A \right]$$

$$= A^T A$$

## Exercise 4.17.3 (b)

Using exercise 4.17.3.a is clear that the iteration in the GDA method is:  $\mathbf{x}^{n+1} = (Id - \delta A^T A)\mathbf{x}^n + \delta \mathbf{b}^T A$ . Iterating the latter equations gives:

$$\mathbf{x}^{n+1} = (Id - \delta A^T A)\mathbf{x}^n + \delta \mathbf{b}^T A$$

$$\vdots$$

$$\mathbf{x}^{n+1} = (Id - \delta A^T A)^n \mathbf{x}^0 + \delta \sum_{k=0}^{n-1} (Id - \delta A^T A)^n \mathbf{b}^T A$$

Note that the eigenvalues of are all positive, and furthermore in absolute value less than one (The proof of this can be found in the Apendix G). Implying the sequence

 $\sum_{k=0}^{n-1} (Id - \delta A^T A)^n \text{ converges, which in turn implies } (Id - \delta A^T A)^n \to \mathbb{O} \text{ and that the limit } \mathbf{x}^{\star} \text{ is well definied and has the value: } \mathbf{x}^{\star} = (A^T A)^{-1} \mathbf{b}^T A.$ 

#### Exercise 4.17.3 (c)

The sequence of Newton's method iterations is given by:

$$\mathbf{x}^{n+1} = \mathbf{x}^n - (A^T A)^{-1} (A^T A \mathbf{x}^n - \mathbf{b}^T A)$$
$$= \mathbf{x}^n - \mathbf{x}^n + (A^T A)^{-1} \mathbf{b}^T A \implies \mathbf{x}^* = \lim_{n \to \infty} \mathbf{x}^n = (A^T A)^{-1} \mathbf{b}^T A.$$

### Exercise 4.17.4 (a)

The sequence  $\{a_n\}_{n\in\mathbb{N}}$  satisfies the inequality  $a_{n+1} \leq \mu a_n + K$ ,  $\forall n \geq 1$ . Then, iterating this inequality we have:

$$a_{n+1} \le \mu a_n + K$$
  
 $\le \mu^2 a_{n-1} + (1+\mu)K \le \dots \le \mu^n a_0 + K \sum_{j=0}^{n-1} \mu^j$ 

By hypothesis  $a_0 > 0$ ,  $\mu \in (0,1)$  and K > 0. Implying the sequence of partials sums  $\{\sum_{j=0}^{n-1} \mu^j\}_{\{n : n \ge 1\}}$  is convergent. Thus the sequence  $\{a_n\}_{n \in \mathbb{N}}$  is bounded by above.

## Exercise 4.17.4 (b)

If the function f satisfies  $\|\nabla f\| \le M$ . Then, the set of equations describying the Momentum GDA (4.4.16-4.4.17) in norm satisfy the following inequalities:

$$\begin{cases} \|\mathbf{x}^{n+1}\| \le \|\mathbf{x}^n\| + \|\mathbf{v}^{n+1}\| \\ \|\mathbf{v}^{n+1}\| \le \mu \|\mathbf{v}^n\| + \eta M \end{cases}$$

An application of the above exercise with  $a_n = ||\mathbf{v}^n||$ ,  $K = \eta M$  yields the desired result.

#### Exercise 4.17.5 (a)

Without loss of generality let's assume that the convolution product  $f \star g$  is being integrated over the whole real line. Then, by the definition of the convolution product we get:

$$\int_{\mathbb{R}} (f \star g)(x) dx = \int_{\mathbb{R}} \int_{\mathbb{R}} f(u)g(u - x) du dx = \int_{\mathbb{R}} \int_{\mathbb{R}} f(v)g(t) dv dt \text{ (applying the substitution: } u = v, u - x = t)$$

$$= \int_{\mathbb{R}} f(v) dv \int_{\mathbb{R}} g(t) dt$$

Where the last equality follows from Fubbini's theorem.

#### Exercise 4.17.5 (b)

An application of the integral triangle inequality to the above identity, yields:

$$\left| \int_{\mathbb{R}} (f \star g)(x) dx \right| = \left| \int_{\mathbb{R}} f(x) dx \right| \left| \int_{\mathbb{R}} g(x) dx \right| \le \int_{\mathbb{R}} |f(x)| dx \int_{\mathbb{R}} |g(x)| dx = \|(f \star g)(x)\|_1 \le \|f(x)\|_1 \|g(x)\|_1$$

# Exercise 4.17.5 (c)

Noting that  $G_{\sigma}$  is a density, then  $||G_{\sigma}(x)||_1 = 1$ . Using the inequality proven in excercise 4.17.5.b we get:

$$||f_{\sigma}(x)||_{1} \le ||f(x)||_{1} ||G_{\sigma}(x)||_{1} \le ||f(x)||_{1}$$

## Exercise 4.17.6

This is in esence what was proven in Exercise 3.15.10.b

## Exercise 4.17.7

Using the Lagrange multipliers method one finds that  $\dots$