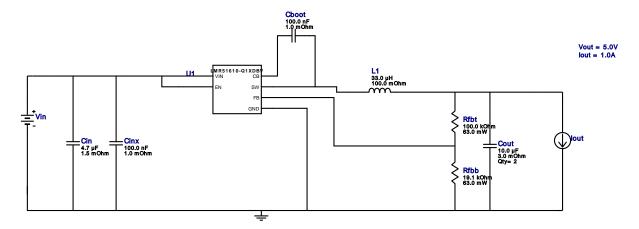


WEBENCH® Design Report

VinMin = 6.0V VinMax = 60.0V Vout = 5.0V lout = 1.0A Device = LMR51610XQDBVRQ1 Topology = Buck Created = 2024-09-24 06:21:52.738 BOM Cost = \$1.78 BOM Count = 9 Total Pd = 1.15W

Design: 58 LMR51610XQDBVRQ1 LMR51610XQDBVRQ1 6V-60V to 5.00V @ 1A



#### **Design Alerts**

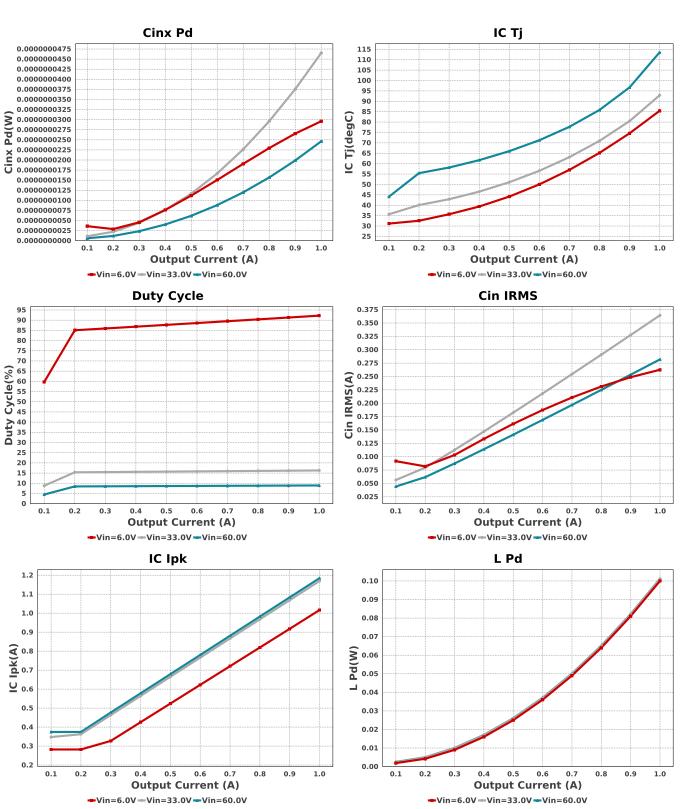
#### **Component Selection Information**

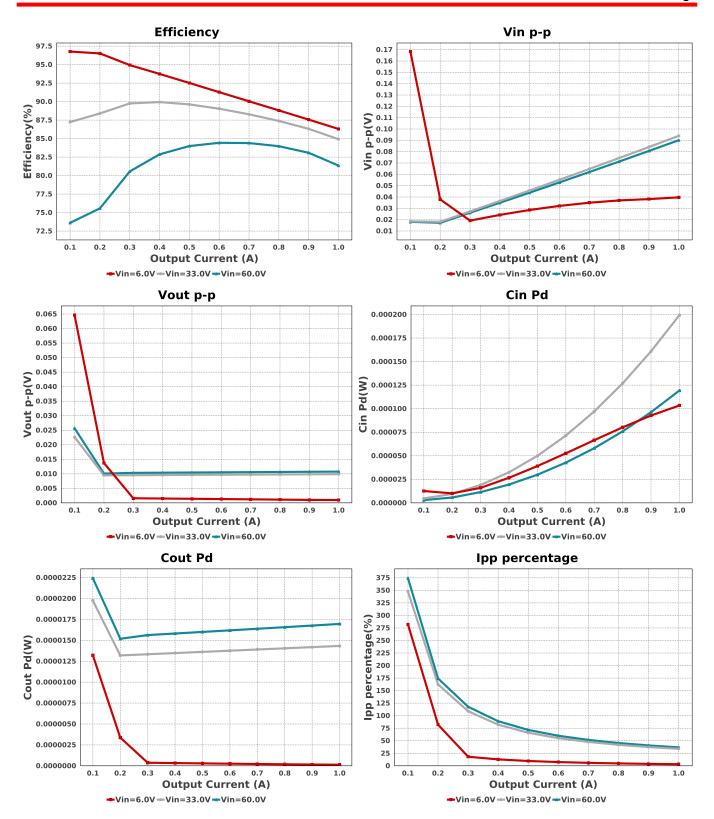
The LMR51610-Q1 is qualified for Automotive applications. All passives and other components selected in this design may not be qualified for Automotive applications. The user is required to verify that all components in the design meet the qualification and safety requirements for their specific application

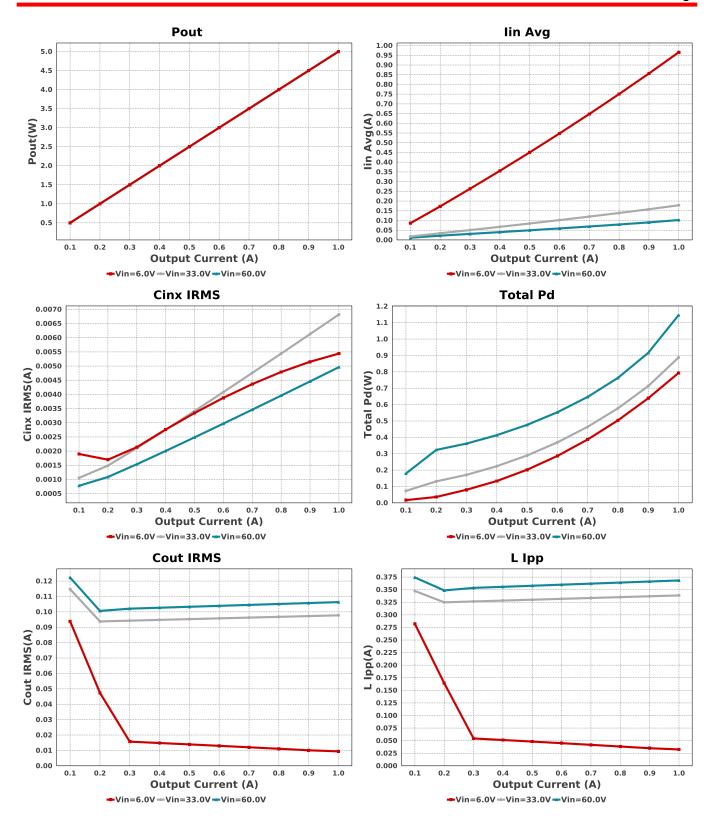
#### **Electrical BOM**

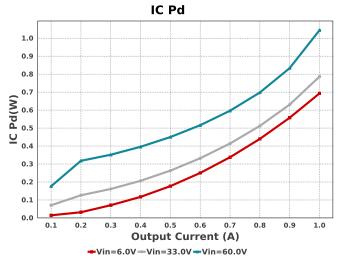
Name	Manufacturer	Part Number	Properties	Qty	Price	Footprint
Cboot	MuRata	GRM155R71C104KA88D Series= X7R	Cap= 100.0 nF ESR= 1.0 mOhm VDC= 16.0 V IRMS= 0.0 A	1	\$0.01	0402 3 mm <sup>2</sup>
Cin	TDK	C5750X7R2A475M230KA Series= X7R	Cap= 4.7 uF ESR= 1.5 mOhm VDC= 100.0 V IRMS= 5.5 A	1	\$0.86	2220_280 54 mm <sup>2</sup>
Cinx	MuRata	GRM188R72A104KA35D Series= X7R	Cap= 100.0 nF ESR= 1.0 mOhm VDC= 100.0 V IRMS= 3.85 A	1	\$0.04	0603 5 mm <sup>2</sup>
Cout	Kemet	C0805C106K8PACTU Series= X5R	Cap= 10.0 uF ESR= 3.0 mOhm VDC= 10.0 V IRMS= 11.43 A	2	\$0.03	0805 7 mm <sup>2</sup>
L1	NIC Components	NPI31W330MTRF	L= 33.0 μH 100.0 mOhm	1	\$0.26	
						IND_NPI31W 172 mm <sup>2</sup>
Rfbb	Vishay-Dale	CRCW040219K1FKED Series= CRCWe3	Res= 19.1 kOhm Power= 63.0 mW Tolerance= 1.0%	1	\$0.01	0402 3 mm <sup>2</sup>
Rfbt	Vishay-Dale	CRCW0402100KFKED Series= CRCWe3	Res= 100.0 kOhm Power= 63.0 mW Tolerance= 1.0%	1	\$0.01	0402 3 mm <sup>2</sup>

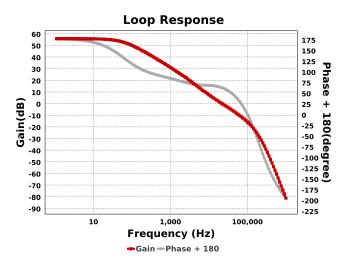
Name	Manufacturer	Part Number	Properties	Qty	Price	Footprint
U1	Texas Instruments	LMR51610XQDBVRQ1	Switcher	1	\$0.53	DBV0006A 15 mm <sup>2</sup>

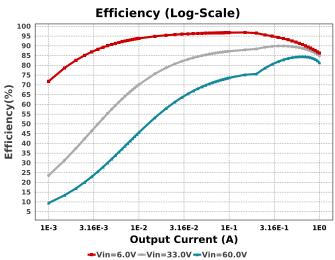












## **Operating Values**

#	Name	Value	Category	Description
1.	Cin IRMS	281.972 mA	Capacitor	Input capacitor RMS ripple current
2.	Cin Pd	119.26 μW	Capacitor	Input capacitor power dissipation
3.	Cinx IRMS	4.963 mA	Capacitor	Bulk capacitor RMS ripple current
4.	Cinx Pd	24.628 nW	Capacitor	Bulk capacitor power dissipation
5.	Cout IRMS	106.333 mA	Capacitor	Output capacitor RMS ripple current
6.	Cout Pd	16.96 μW	Capacitor	Output capacitor power dissipation
7.	IC lpk	1.184 A	IC	Peak switch current in IC
8.	IC Pd	1.044 W	IC	IC power dissipation
9.	IC Tj	113.553 degC	IC	IC junction temperature
10.	IC Tolerance	12.0 mV	IC	IC Feedback Tolerance
11.	ICThetaJA Effective	80.0 degC/W	IC	Effective IC Junction-to-Ambient Thermal Resistance
12.	lin Avg	102.43 mA	IC	Average input current
13.	Ipp percentage	36.835 %	Inductor	Inductor ripple current percentage (with respect to average inductor
	-			current)
14.	L lpp	368.35 mA	Inductor	Peak-to-peak inductor ripple current
15.	L Pd	101.13 mW	Inductor	Inductor power dissipation
16.	Cin Pd	119.26 μW	Power	Input capacitor power dissipation
17.	Cinx Pd	24.628 nW	Power	Bulk capacitor power dissipation
18.	Cout Pd	16.96 μW	Power	Output capacitor power dissipation
19.	IC Pd	1.044 W	Power	IC power dissipation
20.	L Pd	101.13 mW	Power	Inductor power dissipation
21.	Total Pd	1.146 W	Power	Total Power Dissipation
22.	BOM Count	9	System	Total Design BOM count
			Information	•
23.	Cross Freq	21.938 kHz	System	Bode plot crossover frequency
	·		Information	
24.	Duty Cycle	8.93 %	System	Duty cycle
	, ,		Information	• •
25.	Efficiency	81.355 %	System	Steady state efficiency
	•		Information	•
26.	FootPrint	268.0 mm <sup>2</sup>	System	Total Foot Print Area of BOM components
			Information	·

#	Name	Value	Category	Description
27.	Frequency	400.0 kHz	System Information	Switching frequency
28.	Gain Marg	-16.128 dB	System Information	Bode Plot Gain Margin
29.	Inductor ripple current	40.0 %	System	Custom Inductor ripple current (% of average inductor current)
	requirement used for		Information	requirement used for Inductor selection
	Inductor selection			
30.	lout	1.0 A	System	lout operating point
			Information	
31.		d 500.0 mA	System	Custom Transient current step requirement that was used for Cout
	for Cout calculations		Information	selection (A).
32.	Low Freq Gain	55.696 dB	System	Gain at 1Hz
			Information	
33.	Mode	CCM	System	Conduction Mode
0.4	O	70.004 \/	Information	The and Carl Mark Overshard Makes
34.	Overshoot Value	76.964 mV	System	Theoretical Vout Overshoot Value
35.	Dhace Mara	64.419 deg	Information	Pada Blot Dhaga Marain
33.	Phase Marg	64.419 deg	System Information	Bode Plot Phase Margin
36.	Pout	5.0 W	System	Total output power
50.	Tout	3.0 W	Information	rotal output power
37.	Total BOM	\$1.78	System	Total BOM Cost
0		<b>V</b>	Information	1000 2000
38.	Undershoot Value	113.891 mV	System	Theoretical Vout Undershoot Value
			Information	
39.	Vin	60.0 V	System	Vin operating point
			Information	
40.	Vin p-p	90.113 mV	System	Peak-to-peak input voltage
			Information	
41.	Vout	5.0 V	System	Operational Output Voltage
			Information	
42.	Vout Actual	4.988 V	System	Vout Actual calculated based on selected voltage divider resistors
43.	Vout Dinnla	3.0 %	Information	Custom maximum autaut ripals requirement that was used for Court
43.	Vout Ripple requirement used for	3.0 %	System Information	Custom maximum output ripple requirement that was used for Cout selection(% of Vout).
	Cout calculations		IIIIOIIIIalioii	Selection (% of vout).
44.		3,222 %	System	Vout Tolerance based on IC Tolerance (no load) and voltage divider
44.	Vout Tolerance	J.ZZZ /0	Information	resistors if applicable
45.	Vout p-p	10.76 mV	System	Peak-to-peak output ripple voltage
	- · · F F	- +	Information	and the state of t
46.	Vout transient	3.0 %	System	Custom Transient voltage change requirement that was used for Cout
	requirement used for		Information	selection (% of Vout).
	Cout calculations			

## **Design Inputs**

. 9		
Name	Value	Description
lout	1.0	Maximum Output Current
VinMax	60.0	Maximum input voltage
VinMin	6.0	Minimum input voltage
Vout	5.0	Output Voltage
base_pn	LMR51610-Q1	Base Product Number
source	DC	Input Source Type
Та	30.0	Ambient temperature

# WEBENCH® Assembly

### Component Testing

Some published data on components in datasheets such as Capacitor ESR and Inductor DC resistance is based on conservative values that will guarantee that the components always exceed the specification. For design purposes it is usually better to work with typical values. Since this data is not always available it is a good practice to measure the Capacitance and ESR values of Cin and Cout, and the inductance and DC resistance of L1 before assembly of the board. Any large discrepancies in values should be electrically simulated in WEBENCH to check for instabilities and thermally simulated in WebTHERM to make sure critical temperatures are not exceeded.

#### Soldering Component to Board

If board assembly is done in house it is best to tack down one terminal of a component on the board then solder the other terminal. For surface mount parts with large tabs, such as the DPAK, the tab on the back of the package should be pre-tinned with solder, then tacked into place by one of the pins. To solder the tab town to the board place the iron down on the board while resting against the tab, heating both surfaces simultaneously. Apply light pressure to the top of the plastic case until the solder flows around the part and the part is flush with the PCB. If the solder is not flowing around the board you may need a higher wattage iron (generally 25W to 30W is enough).

### Initial Startup of Circuit

It is best to initially power up the board by setting the input supply voltage to the lowest operating input voltage 6.0V and set the input supply's current limit to zero. With the input supply off connect up the input supply to Vin and GND. Connect a digital volt meter and a load if needed to set the minimum lout of the design from Vout and GND. Turn on the input supply and slowly turn up the current limit on the input supply. If the voltage starts to rise on the input supply continue increasing the input supply current limit while watching the output voltage. If the current increases on the input supply, but the voltage remains near zero, then there may be a short or a component misplaced on the board. Power down the board and visually inspect for solder bridges and recheck the diode and capacitor polarities. Once the power supply circuit is operational then more extensive testing may include full load testing, transient load and line tests to compare with simulation results.

#### Load Testing

The setup is the same as the initial startup, except that an additional digital voltmeter is connected between Vin and GND, a load is connected between Vout and GND and a current meter is connected in series between Vout and the load. The load must be able to handle at least rated output power + 50% (7.5 watts for this design). Ideally the load is supplied in the form of a variable load test unit. It can also be done in the form of suitably large power resistors. When using an oscilloscope to measure waveforms on the prototype board, the ground leads of the oscilloscope probes should be as short as possible and the area of the loop formed by the ground lead should be kept to a minimum. This will help reduce ground lead inductance and eliminate EMI noise that is not actually present in the circuit.



#### **Design Assistance**

- 1. The LMR51610-Q1 is qualified for Automotive applications. All passives and other components selected in this design may not be qualified for Automotive applications. The user is required to verify that all components in the design meet the qualification and safety requirements for their specific application
- 2. Master key: 7627B22B384BF7EAE268D1E513DC6F75[v1]
- 3. LMR51610-Q1 Product Folder: http://www.ti.com/product/LMR51610%2DQ1: contains the data sheet and other resources.

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