JiaWei Lee

+886 912 911 672 | qw960211@gmail.com | GitHub

Software engineer with 2 years experience in Turing-Drive, dedicated to researching path planning and GNSS positioning, the main programming languages is C++, C, Python

Education

National Yunlin University of Science and Technology — Yunlin, Taiwan
Department of Electrical Engineering — *Sep. 2017 – Jun 2019*

- Mobile robot, Robot Operating System(ROS)

National Formosa University — Yunlin, Taiwan
Department of Electrical Engineering — *Sep. 2015 – Jun 2017*

Professional Experience

Turing Drive Inc ***(C++/C, Python, ROS, Shell, Linux, Path Planning, GNSS)*** — Taipei, Taiwan
Software Engineer — *Nov 2019 – Present*

- Optimized the path planning algorithm and the integrated obstacle information in the Autoware system, execution speed is more than 60% faster, total mileage exceeds 5,000 km, and over 4,000 people have been onboard
- Designed and implemented NMEA parser and NTRIP Caster available to the projects positioning system
- Designed and implemented data log to path planning system, used for algorithm debug, improve on-site work efficiency by about 50%
- Developed a through 2D LiDAR detection person leg and 3D LiDAR camera fusion

Selected Projects & Awards

Quantitative trading ***(Python)*** — May 2022- Present

- Developing the trading strategy
- Get current Cryptocurrency price using the Biance API

Smart trash can ***(C++/C, ROS, Navigation Stack, SLAM, Opencv, PCL)*** — Sep 2017 – May 2019

- Designed and Integrated SLAM module, navigation module and sensor module through the ROS, robot served aperiod of time at the NYUST EC404 laboratory
- Developed 2D LiDAR leg detection to using the Adaboost, the detection accuracy on the empty environment is more than 90%
- Researched and Developed 2D LiDAR SLAM algorithm and Navigation Stack

Skills

Languages: C/C++, Python, Shell scrip
Frameworks: ROS, ROS2
Developer Tools: Git, Docker, VS Code, Vim, Cmake,
Libraries: Eigen, PCL, Opencv, Pandas, NumPy, Matplotlib