

# JiaWei Lee

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Software developer with 2 years of experience in a Turing-Drive, dedicated to researching path planning and GNSS positioning, the main programming languages is C++, C, Python

## Education

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### National Yunlin University of Science and Technology

*Department of Electrical Engineering*

- Mobile robot, Robot Operating System(ROS)

Yunlin, Taiwan

*Sep. 2017 – Jun 2019*

### National Formosa University

*Department of Electrical Engineering*

Yunlin, Taiwan

*Sep. 2015 – Jun 2017*

## Professional Experience

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### Turing Drive Inc(*C++/C, Python, ROS, Shell, Linux, Path Planning, GNSS*)

*Software Engineer*

Taipei, Taiwan

*Nov 2019 – Present*

- Optimized the path planning algorithm and the integrated obstacle information in the Autoware system, execution speed is more than 60% faster, total mileage exceeds 5,000 km, and over 4,000 people have been onboard
- Designed and implemented NMEA parser and NTRIP Caster available to the projects positioning system
- Designed and implemented data log to the path planning system used for algorithm debugging and improved on-site work efficiency by about 50%
- Developed a through 2D LiDAR detection person leg and 3D LiDAR camera fusion

## Selected Projects & Awards

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### Quantitative trading(*Python*)

May 2022- Present

- Developing the trading strategy
- Get current Cryptocurrency price using the Binance API

### Smart trash can(*C++/C, ROS, Navigation Stack, SLAM, Opencv, PCL*)

Sep 2017 – May 2019

- Designed and Integrated SLAM module, navigation module and sensor module through the ROS, robot served aperiod of time at the NYUST EC404 laboratory
- Developed 2D LiDAR leg detection to using the Adaboost, the detection accuracy on the empty environment is more than 90%
- Researched and Developed 2D LiDAR SLAM algorithm and Navigation Stack

## Skills

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**Languages:** C/C++, Python, Shell scrip

**Frameworks:** ROS, ROS2

**Developer Tools:** Git, Docker, VS Code, Vim, Cmake,

**Libraries:** Eigen, PCL, Opencv, Pandas, NumPy, Matplotlib