

# Snowboard Support System

By Allen Keng, John Mamola, Bran Zhang  
05/20/2024 ECE-196



Team Old vs New



# Problem Definition

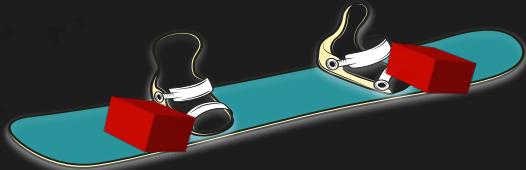
Many snowboarders, particularly beginners, encounter injuries and struggle to identify areas for improvement on their own.



Self-assessment or outside feedback can be very limited due to lack of perspective.



# Proposed Idea



## Device

- Rectangular boxes attached to the snowboard
- Next to their feet
- Inside will be our sensor system



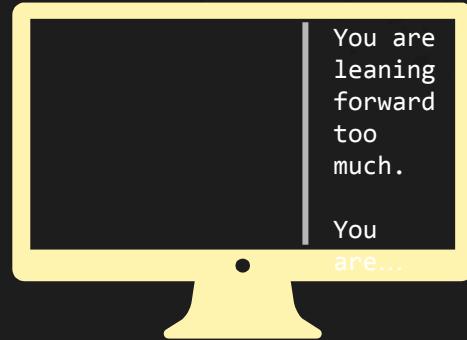
## Features

### Alert System:

- Buzzer that activates when detecting unstable movement

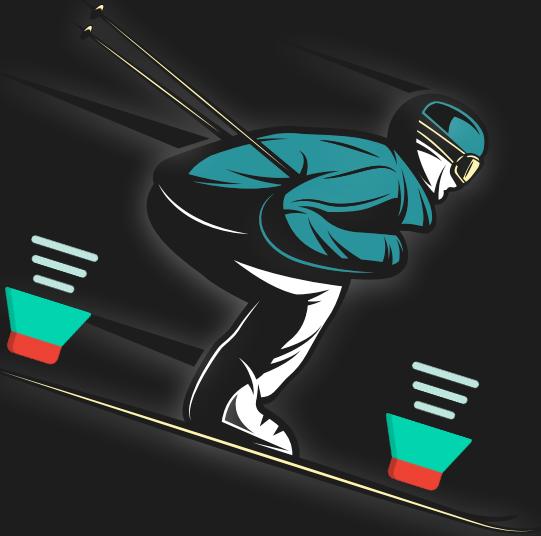
### Personalized Tips:

- Shifting their weight (Balance)
- Slowing down or speeding up (Velocity)



## Application

- Displays the tips to the user
- Tracks their velocity
- Maintains list of all tips provided

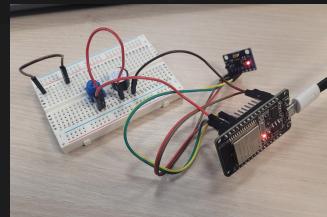


# Testable Hypothesis

- A beginner will use the prototype.
- They should realize that they are moving too fast or are unstable upon hearing the buzzers
  - They do not fall or get hurt
- If they do fall
  - They can check the application and the advice provided to improve

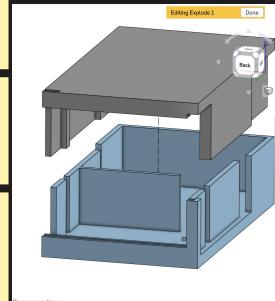
# Milestone Achievements

Milestones	Tasks	Percent Complete	Projected/Completion Date
(1) Planning	PCB Hub Design, Outline for Website and Poster, BLE code setup	100%	Week 6
(2) Assembly	Prototyping, Software for displaying data, Enclosure Design	80%	Week 7
(3) Testing/Printing	Using data to solve the problem. How interpret? Printing enclosure	20%	Week 8/9
(4) Debugging	Ensuring buzzers go off when they are supposed to, correct tips documented	5%	Week 9
(5) Production	Recording our video demo, adding more details/images to poster/website	33%	Week 9

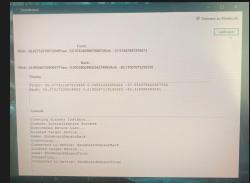


Blown up View of Enclosure

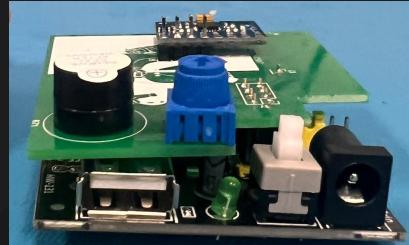
Prototype



User Interface



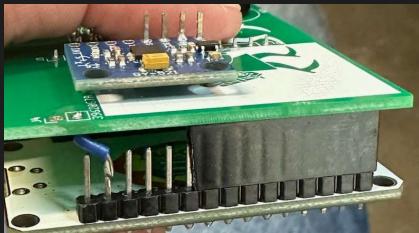
Soldered Hub



# Where We Struggled

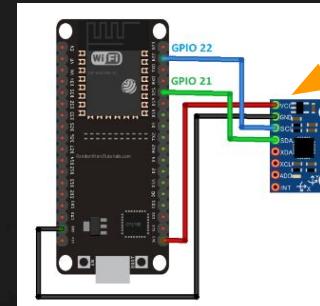
## Dimensions/Positioning

- The PCB hub we designed had a GND pin off by 1 pin.
- Our Enclosure was too tight and needed more tolerance



## Being In A Waiting Period

- After prototyping, coding, and designing, we didn't know what to do.
- Waiting for PCB hub to connect

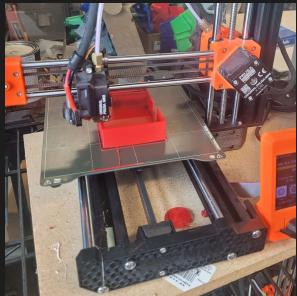


## Software Barriers

- Communication with Accelerometer module
  - Existing MPU6050 libraries did not work



# What's Next?



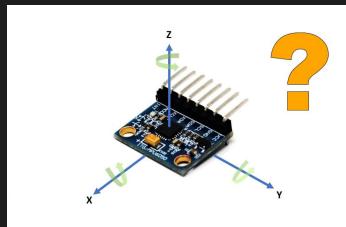
Turning the data we receive to information that can help the user

## Interpretation



## Enclosure Printing

3D printing the enclosure/door



Recording our demo, taking images of the prototype, adding to the website/poster

## Documenting



## TESTING!!



Attach to board and see what happens

# Resources/References

## Connections

- <https://randomnerdtutorials.com/esp32-mpu-6050-accelerometer-gyroscope-arduino/>
  - Figuring out the pins we were going to connect to while designing PCB
- <https://bleak.readthedocs.io/en/latest/api/client.html>
  - Making python act as a BLE receiver.

## I2C Communication

- <https://randomnerdtutorials.com/esp32-i2c-communication-arduino-ide/>
  - Understanding how to read values from an I2C device via “wire” transmission

## Velocity Calculations

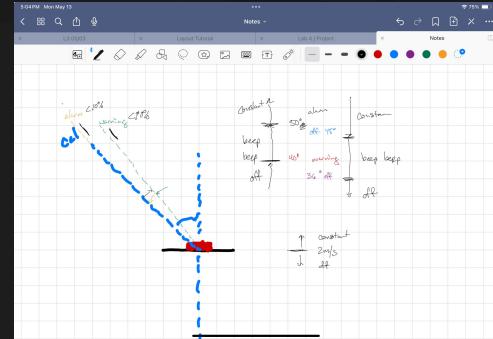
- <https://arduino.stackexchange.com/questions/22798/can-i-measure-velocity-from-an-accelerometer-how-accurately>

## Adin's Python GUI code

- We built our Python receiver code on top of Adin's ControlWithPython assignment.
  - Basically it was our foundation for our GUI, instead of starting from scratch



# Thanks!



- What other features should we include in our UI?
  - How can we improve User Experience?

# Do you have any questions?