# BEMOSS and Its Enhanced Applications

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## Outline

- Current Motor Interface
  - Problems
  - Demo

- 2 Improved Motor Interface
- 3 Plans

- Using command nmap -sn 192.168.1.0/24 to perform ping scan
- Command arp -a dumps ARP (Address Resolution Protocol) cache
- Unable to use command sudo nmap -sn 192.168.1.0/24
- User input not accepted in VOLTTRON log terminal

```
□ ramgroup@ramgroup-Latitude-E6510: ~
(192.168.1.48) at <incomplete> on wlp2s0b1
(192.168.1.205) at <incomplete> on wlp2s0b1
(192.168.1.142) at <incomplete> on wlp2s0b1
(192.168.1.75) at <incomplete> on wlp2s0b1
(192.168.1.193) at <incomplete> on wlp2s0b1
(192.168.1.130) at <incomplete> on wlp2s0b1
(192.168.1.95) at <incomplete> on wlp2s0b1
(192.168.1.213) at <incomplete> on wlp2s0b1
(192.168.1.150) at <incomplete> on wlp2s0b1
(192.168.1.108) at <incomplete> on wlp2s0b1
(192.168.1.41) at b8:27:eb:bf:ba:de [ether] on wlp2s0b1
(192.168.1.234) at <incomplete> on wlp2s0b1
(192.168.1.167) at <incomplete> on wlp2s0b1
(192.168.1.96) at <incomplete> on wlp2s0b1
(192.168.1.61) at <incomplete> on wlp2s0b1
(136.176.88.1) at 00:6c:bc:a6:9b:c1 [ether] on eno1
(192,168,1,254) at <incomplete> on wlp2s0b1
(192.168.1.187) at <incomplete> on wlp2s0b1
(192.168.1.116) at <incomplete> on wlp2s0b1
(192.168.1.49) at <incomplete> on wlp2s0b1
(192.168.1.242) at <incomplete> on wlp2s0b1
(192.168.1.143) at <incomplete> on wlp2s0b1
(192.168.1.72) at <incomplete> on wlp2s0b1
(192.168.1.198) at <incomplete> on wlp2s0b1
```

Figure: Use of arp command



- Parse arp output with regex
- Retrieve IP and mac address of Raspberry Pi
- Remove ':' delimiters from MAC address
- Regex in URL mapping to devicedata\_view only searches for a-z, A-Z, and 0-9

#### **Problems**

- Device model, vendor name, username, and password of Pi not easily accessible
- Hardcoded in json file
- Password must be encrypted
- RPi script paths must be specified on BEMOSS host machine

Play video



# Improved Motor Interface



- Implement device identify behavior
- Requires querying the device for information
- Must find a way of checking the status of the remote XBee module
- Toggle visually noticeable device variable twice with pause in between
  - On motor: status
- Replace plugload image with motor image

Figure: Identify device widget



# Improved Motor Interface

- Raspberry Pi remote GPIO server
- Control GPIO pins over the Internet
- gpiozero or pigpio python libraries
- Only requires IP address, no login credentials
- Start server with pigpiod (pigpio daemon)
- Option -n allows only specified hosts to connect
  - Example: sudo pigpiod -n "IP ADDRESS"

## **Plans**

- Find new device to implement with BEMOSS
- Possibly a sensor
- Implement PID control algorithm with motor to control speed

Any questions?

