### DC Motor Integration in BEMOSS

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### Outline

- Device API Traslator
- Steps in adding device API
- 3 Steps in adding new device type
- Problems Fixed
- 6 Additions
- 6 Priorities



### Device API Translator



# Steps in adding device API

#### Methods to implement

- API\_info returns list of supported device attributes (device\_model, vendor\_name, html\_template, chart\_template etc.)
- dashboard\_view returns parameters of device to be shown on the BEMOSS dashboard
- ontology maps parameters from device to BEMOSS parameters
- discover is called by the device discovery agent and returns attributes of discovered devices
- getDataFromDevice returns dictionary of device data
- identifyDevice visually identifies the device, triggered by web UI and sends message to control agent
- setDeviceStatus sends control commands to device



# Steps in adding device API

#### Methods in motor API

- argsToPi uses ssh to run XBEEcontrol.py with arguments to control motor and retrieve data
- toggleDeviceStatus queries the device for on/off status then changes settings of the motor, uses getDataFromDevice and setDeviceStatus

# Steps in adding new device type

### Steps

- Select a device type id (1, 2, 3, 4 and 7 are reserved)
- Register new device type in BEMOSS db by updating PROJECT\_DIR/Web\_Server/run/defaultDB.py then running the script
- Update discover\_devices function in Web\_Server/webapps/discovery/views.py
- Add widget for new device in Web\_Server/webapps/ discovery/templates/discovery/manual\_discovery.html
- Update Web\_Server/static/app\_js/discovery.js with code to enable use of the "Set all to 'Approved'" button in the Device Discovery page

## Steps in adding new device type



### Problems Fixed

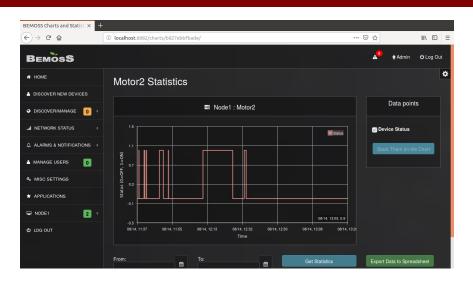


Figure: Fully functional jQuery plot



#### Additions

#### ssh keys

- ssh-keygen generates a public and private key
- Public key copied to RPi, private key kept on host machine
- More secure than using password
- https://www.raspberrypi.org/documentation/ remote-access/ssh/passwordless.md



#### **Priorities**

- Write paper
- Speed control algorithm
- Still looking for new device

