

# ROBOT LOCALIZATION SYSTEM

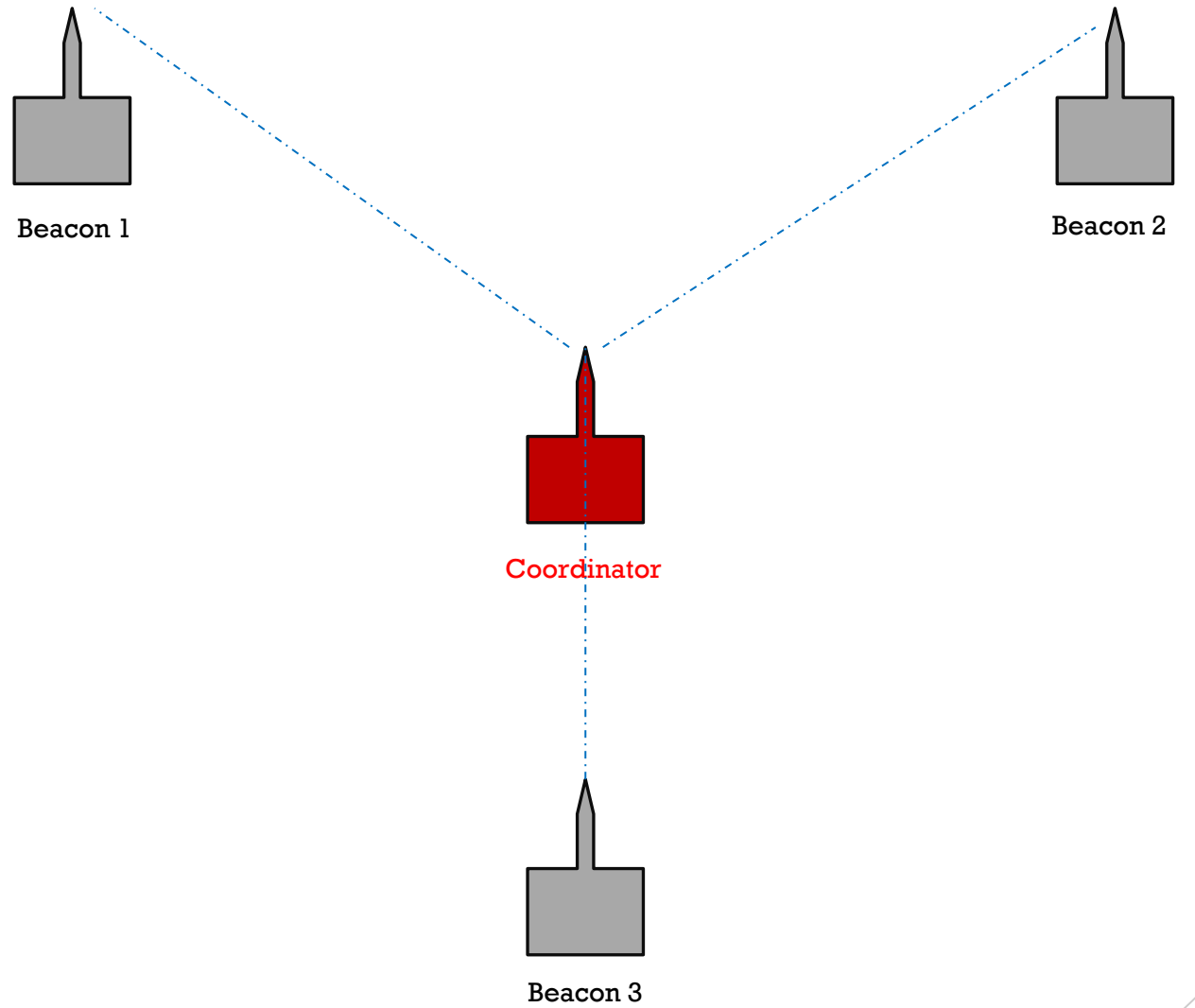
GEORGES SAMAHA

BRIAN LAUER

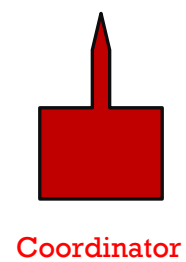
# The Goal

- Implement a localization system for a robot using beacons and trilateration

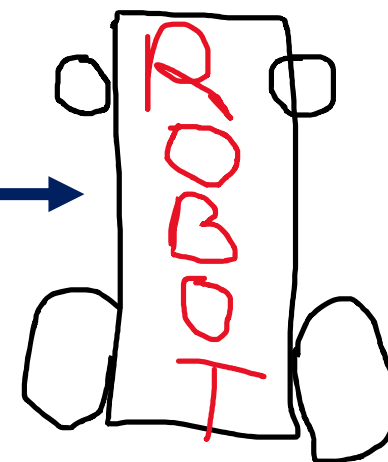
What Does It  
Look Like?



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Look Like?



BeagleBone  
Blue



# Efforts

- Using a library written in Python.
- “[digidotcom/xbee-python](#)”

## Efforts

- Tried connecting coordinator to beacon.
- Coordinator was connected serially to laptop.
- Test did not work properly.

## Efforts

- Ran the same test on a different pair of Xbees
- Test was successful

# Troubleshooting

- Compared configurations of both pairs on XCTU
- Found no relevant differences



## Suspensions

- Problem could be narrowed down to serial connection
- Reason: Transmitting works with XCTU, not in manual
- XCTU could be handling processes behind the scenes

# Progress

- Working on sending AT commands using library

A large red speech bubble graphic with a white border, containing the text "THANK YOU!".

THANK YOU!

- Questions?
- Suggestions?