# Multi-Robot Localization Update

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#### Outline

- Goals from Last Meeting
- Goals Achieved
- Issues
- Goals for Next Week
- Priority List
- Questions

# Goals from Last Meeting

- Get the PC to read the Zigbee boards
- Get the Beagle Bone connected to the USB interface and reading information
- Get three Zigbee boards connected in a network and communicating properly

#### Goals Achieved

- Get the (Microsoft)PC to connect and send messages to the Zigbee boards
- Get three Zigbee boards connected in a network and communicating properly

Ran into issue for getting the BBB to connect to the Zigbee board

#### PC Communication

```
Windows PowerShell
Copyright (C) Microsoft Corporation. All rights reserved.
PS C:\Users\Caleb Lu> $port= new-Object System.IO.Ports.SerialPort COM8,9600,None,8,one
PS C:\Users\Caleb Lu> [System.IO.Ports.SerialPort]::getportnames()
COM8
PS C:\Users\Caleb Lu> $port.Open()
PS C:\Users\Caleb Lu> $port.Write($request,0,$request.Count)
PS C:\Users\Caleb Lu> $port.ReadByte()
126
PS C:\Users\Caleb Lu> $port.ReadByte()
PS C:\Users\Caleb Lu> $port.ReadByte()
PS C:\Users\Caleb Lu> $port.ReadByte()
151
PS C:\Users\Caleb Lu> $port.ReadByte()
PS C:\Users\Caleb Lu> $port.ReadByte()
PS C:\Users\Caleb Lu> $port.ReadByte()
PS C:\Users\Caleb Lu> $port.ReadByte()
162
PS C:\Users\Caleb Lu> $port.ReadByte()
PS C:\Users\Caleb Lu> $port.ReadByte()
PS C:\Users\Caleb Lu> $port.ReadByte()
  C:\Users\Caleb Lu> $port.ReadByte()
PS C:\Users\Caleb Lu> $port.ReadByte()
```

#### Issues/Pictures

- BBB was used in the mechatronic class and the student changed the root password
  - Need to reset the board
  - Tried passwords of:
    - root
    - temppwd
    - debian
    - (Nothing)

```
login as: root
root@192.168.7.2's password:
Access denied
root@192.168.7.2's password:
```

### Issues/Pictures

- Another slight issue is that I need another interface board to do some testing.
- One board is connected to my PC, so I can not read the values sent to the other board. Can manage without, but would make things easier.
- Also need to figure out how to parse incoming data. Have been using XCTU frame interpreter.

#### Goals for Next Week

- Get Communication between BBB and the USB interface board
- Write C code to send and receive messages
  - Properly parse messages to interpret message
  - Send and receive specific message to a beacon

# **Specific Actions**

- Need to figure out how to reset the root password to apply some settings/set internet access
- Write C code for 2 features
  - Receiving and sending data
  - Parsing incoming data and interpret that data into usable information

## **Priority List**

- BBB communication to interface board
- 2. C code for communication
- 3. C code for parsing and interpreting information

# Questions?