Feedforward Neural Network

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A feedforward neural network (FFNN) can be used to solve a classification problem. A FFNN is a network of neurons inspired from the biological neural network.

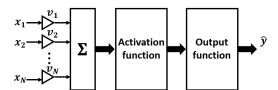
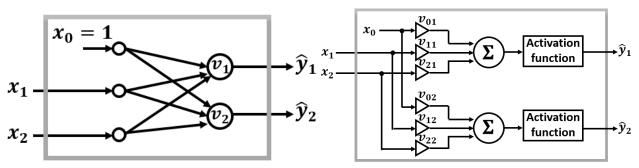


Figure 1: Model for an artificial neuron

1 FFNN of two layers



(a) Feedforward neural network with two layers (b) Feedforward neural network with two layers (explained)

Figure 2: Feedforward neural network with two layers

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2 FFNN of three layers

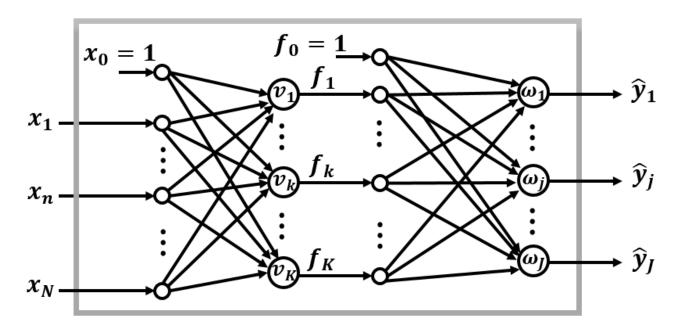


Figure 3: Feedforward neural network with three layers

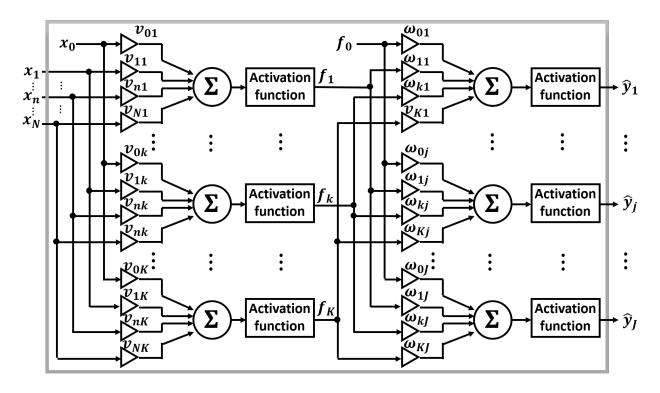


Figure 4: Feedforward neural network with three layers (explained)

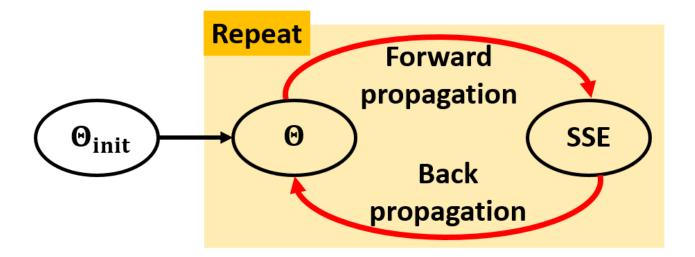


Figure 5: Forward propagation and backpropagation

3 Forward propagation and backpropagation

3.1 Forward propagation

Input data matrix

$$X = \begin{bmatrix} \left(x^{(1)}\right)^T \\ \vdots \\ \left(x^{(I)}\right)^T \end{bmatrix}, \quad \text{where} \quad x^{(i)} \in \mathbb{R}^{N \times 1}$$
 (1)

Extended input data matrix

$$\overline{X} = \begin{bmatrix} \mathcal{I} & X \end{bmatrix} = \begin{bmatrix} \left(\overline{x}^{(1)}\right)^T \\ \vdots \\ \left(\overline{x}^{(I)}\right)^T \end{bmatrix}, \quad \text{where} \quad \mathcal{I} = \begin{bmatrix} 1, \cdots, 1 \end{bmatrix}^T \in \mathbb{R}^{I \times 1}$$
 (2)

$$\overline{\overline{X}} = \overline{X} \cdot v = \begin{bmatrix} \left(\overline{x}^{(1)}\right)^T \cdot v \\ \vdots \\ \left(\overline{x}^{(I)}\right)^T \cdot v \end{bmatrix}$$
(3)

Define

$$F = \left(1 + \exp\left(-\overline{\overline{X}}\right)\right)^{-1} = \begin{bmatrix} \left(f^{(1)}\right)^T \\ \vdots \\ \left(f^{(I)}\right)^T \end{bmatrix}$$

$$\tag{4}$$

where the operator $^{-1}$ represents the elementwise inversion.

$$\overline{F} = \begin{bmatrix} \mathcal{I} & F \end{bmatrix} = \begin{bmatrix} \left(\overline{f}^{(1)}\right)^T \\ \vdots \\ \left(\overline{f}^{(I)}\right)^T \end{bmatrix}, \quad \text{where} \quad \mathcal{I} = [1, \cdots, 1]^T \in \mathbb{R}^{I \times 1}$$
 (5)

$$\overline{\overline{F}} = \overline{F} \cdot \omega = \begin{bmatrix} \left(\overline{f}^{(1)}\right)^T \cdot \omega \\ \vdots \\ \left(\overline{f}^{(I)}\right)^T \cdot \omega \end{bmatrix}$$

$$(6)$$

Define

$$G = \left(1 + \exp\left(-\overline{\overline{F}}\right)\right)^{-1} = \begin{bmatrix} \left(g^{(1)}\right)^T \\ \vdots \\ \left(g^{(I)}\right)^T \end{bmatrix}$$
 (7)

where $^{-1}$ represents once again the elementwise inversion.

Then, one can find the labels using the following algorithm:

Algorithm 1: find labels

- 1 Initialize label;
- 2 for i = 1 : I do
- $\mathbf{a} \mid label(i) \leftarrow \arg\max_{j} G(i, j);$
- 4 return label;

Let us define the sum of squared errors (SSE) as

$$E = \frac{1}{2} \sum_{i=1}^{I} (\hat{y}^{(i)} - y^{(i)})^2 = \frac{1}{2} \sum_{i=1}^{I} \sum_{j=1}^{J} (\hat{y}_j^{(i)} - y_j^{(i)})^2 = \frac{1}{2} \sum_{i=1}^{I} \sum_{j=1}^{J} (g_j^{(i)} - y_j^{(i)})^2$$
(8)

where $g_i^{(i)} = g\left(\overline{f}\left(\overline{x}^{(i)}\right)\right) = g \circ \overline{f}\left(\overline{x}^{(i)}\right)$.

3.2 Backpropagation

In this course, the backpropagation is performed using the batch gradient descent algorithm. The update rules are

$$v_{nk} \leftarrow v_{nk} - \alpha_v \frac{\partial E}{\partial v_{nk}}$$

$$w_{kj} \leftarrow w_{kj} - \alpha_w \frac{\partial E}{\partial w_{kj}}$$
(9)

But, what are $\frac{\partial E}{\partial v_{nk}}$ and $\frac{\partial E}{\partial w_{kj}}$?

Let us compute first $\frac{\partial E}{\partial w_{ki}}$.

$$\frac{\partial E}{\partial w_{kj}} = \frac{\partial}{\partial w_{kj}} \left[\frac{1}{2} \sum_{i=1}^{I} \sum_{j'=1}^{J} \left(g_{j'}^{(i)} - y_{j'}^{(i)} \right)^2 \right] = \sum_{i=1}^{I} \frac{\partial}{\partial w_{kj}} \left[\frac{1}{2} \sum_{j'=1}^{J} \left(g_{j'}^{(i)} - y_{j'}^{(i)} \right)^2 \right] = \sum_{i=1}^{I} \left(g_{j}^{(i)} - y_{j'}^{(i)} \right) \frac{\partial g_{j}^{(i)}}{\partial w_{kj}}$$
(10)

For simplicity, let us drop the notation $^{(i)}$ and compute $\frac{\partial g_j}{\partial w_k}$.

$$\frac{\partial g_j}{\partial w_{kj}} = \frac{\partial}{\partial w_{kj}} \left(\frac{1}{1 + e^{\left(-(\overline{f})^T w_j \right)}} \right)
= \frac{-e^{\left(-(\overline{f})^T w_j \right)}}{\left(1 + e^{\left(-(\overline{f})^T w_j \right)} \right)^2} (-\overline{f}_k)
= \frac{1}{1 + e^{\left(-(\overline{f})^T w_j \right)}} \left(1 - \frac{1}{1 + e^{\left(-(\overline{f})^T w_j \right)}} \right) \overline{f}_k
= g_j (1 - g_j) \overline{f}_k$$
(11)

Hence,

$$\frac{\partial E}{\partial w_{jk}} = \sum_{i=1}^{I} \left(g_j^{(i)} - y_j^{(i)} \right) g_j^{(i)} \left(1 - g_j^{(i)} \right) \overline{f}_k^{(i)} \tag{12}$$

$$w_{kj} \leftarrow w_{kj} - \alpha_1 \sum_{i=1}^{I} \left(g_j^{(i)} - y_j^{(i)} \right) g_j^{(i)} \left(1 - g_j^{(i)} \right) \overline{f}_k^{(i)}$$
(13)

where $k = \{0, 1, \dots, K\}$ and $j = \{1, 2, \dots, J\}$.

Now, let us compute $\frac{\partial E}{\partial v_{nk}}$

$$\frac{\partial E}{\partial v_{nk}} = \frac{\partial}{\partial v_{nk}} \left[\frac{1}{2} \sum_{i=1}^{I} \sum_{j=1}^{J} \left(g_j^{(i)} - y_j^{(i)} \right)^2 \right] = \sum_{i=1}^{I} \sum_{j=1}^{J} \frac{\partial}{\partial v_{nk}} \left[\frac{1}{2} \left(g_j^{(i)} - y_j^{(i)} \right)^2 \right]$$
(14)

Then,

$$\frac{\partial}{\partial v_{nk}} \left[\frac{1}{2} \left(g_j^{(i)} - y_j^{(i)} \right)^2 \right] = \left(g_j^{(i)} - y_j^{(i)} \right) \frac{\partial g_j^{(i)}}{\partial v_{nk}} \tag{15}$$

For simplicity, let us drop the notation $^{(i)}$ and compute $\frac{\partial g_j^{(i)}}{\partial v_{nk}}$.

$$\frac{\partial g_j}{\partial v_{nk}} = \frac{\partial g_j}{\partial \overline{f}_k} \frac{\partial \overline{f}_k}{\partial v_{nk}} \tag{16}$$

On the other hand,

$$\frac{\partial g_{j}}{\partial \overline{f}_{k}} = \frac{\partial}{\partial \overline{f}_{k}} \left(\frac{1}{1 + e^{\left(-(\overline{f})^{T}w_{j}\right)}} \right)
= \frac{-e^{\left(-(\overline{f})^{T}w_{j}\right)}}{\left(1 + e^{\left(-(\overline{f})^{T}w_{j}\right)}\right)^{2}} (-w_{kj})
= \frac{1}{1 + e^{\left(-(\overline{f})^{T}w_{j}\right)}} \left(1 - \frac{1}{1 + e^{\left(-(\overline{f})^{T}w_{j}\right)}} \right) w_{kj}
= g_{j}(1 - g_{j})w_{kj}$$
(17)

Now,

$$\frac{\partial \overline{f}_k}{\partial v_{nk}} = \frac{\partial f_k}{\partial v_{nk}}
= \frac{\partial}{\partial v_{nk}} \left(\frac{1}{1 + e^{(-(\overline{x})^T v_k)}} \right)
= \frac{-e^{\left(-(\overline{x})^T v_k\right)}}{1 + e^{\left(-(\overline{x})^T v_k\right)}} (-\overline{x}_n)
= \frac{1}{1 + e^{\left(-(\overline{x})^T v_k\right)}} \left(1 - \frac{1}{1 + e^{\left(-(\overline{x})^T v_k\right)}} \right) \overline{x}_n
= f_k (1 - f_k) \overline{x}_n$$
(18)

Hence,

$$\frac{\partial E}{\partial v_{nk}} = \sum_{i=1}^{I} \sum_{j=1}^{J} \left\{ \left(g_j^{(i)} - y_j^{(i)} \right) g_j^{(i)} \left(1 - g_j^{(i)} \right) w_{kj} f_k^{(i)} \left(1 - f_k^{(i)} \right) \bar{x}_n^{(i)} \right\}$$
(19)

Now, by considering all training examples,

$$v_{nk} \leftarrow v_{nk} - \alpha_2 \sum_{i=1}^{I} \sum_{j=1}^{J} \left\{ \left(g_j^{(i)} - y_j^{(i)} \right) g_j^{(i)} \left(1 - g_j^{(i)} \right) w_{kj} f_k^{(i)} \left(1 - f_k^{(i)} \right) \bar{x}_n^{(i)} \right\}$$
(20)

where $n = \{0, 1, \dots, N\}$ and $k = \{1, 2, \dots, K\}$.