

# **An Overview of the SysML-Modelica Transformation Specification**

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# SysML-Modelica Transformation

## Specification: Context & Objective

- Two complementary languages for Systems Engineering:
  - Descriptive modeling in SysML
  - Formal equation-based modeling for analyses and trade studies in Modelica
- Objective:
  - Leverage the strengths of both SysML and Modelica by integrating them to create a more expressive and formal MBSE language.
  - Define a formal Transformation Specification:
    - a SysML4Modelica profile
    - a Modelica abstract syntax metamodel
    - a mapping between Modelica and the profile

# Presentation Overview

- What is SysML?
- What is Modelica?
- Motivating Example: Design & Analysis of Robot
- SysML-Modelica Transformation Specification
- Transformations in Systems Modeling
- Model reuse and composition
- Summary

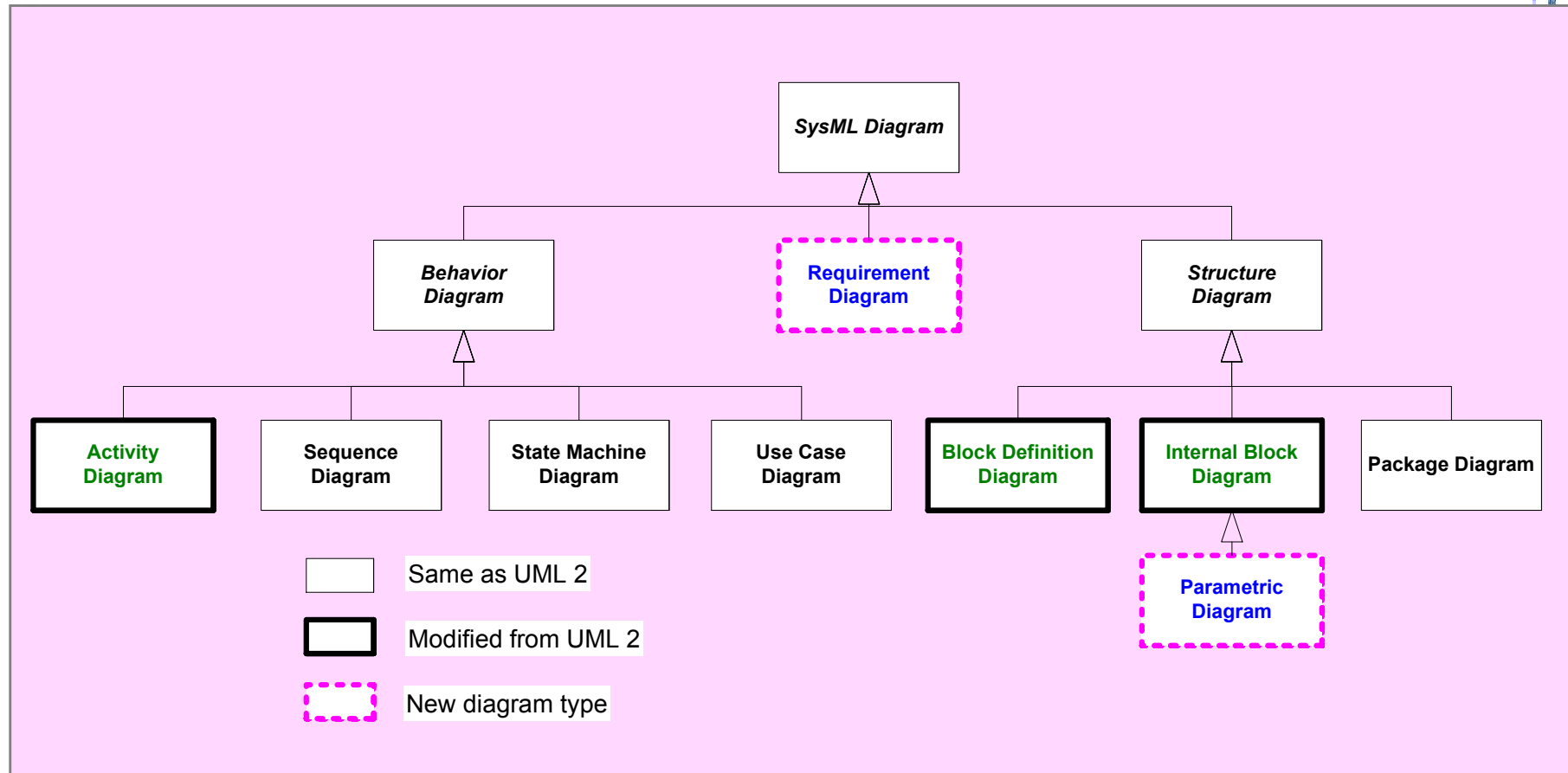
# What is SysML?

- The Systems Modeling Language (OMG SysML™) is a *visual, general purpose modeling language*
- **Is** a modeling language that provides
  - Semantics = meaning
  - Notation = representation of meaning
- **Is not** a methodology or a tool
  - SysML is methodology and tool independent
- Developed by the Object Management Group to support **Model-Based Systems Engineering**

# What Can be Expressed in SysML?

- SysML is a language to express the information and knowledge generated and processed during the application of a systems development methodology
- ◆ Specification
- ◆ Analysis
- ◆ Design
- ◆ Verification
- ◆ Validation
- ◆ Hardware
- ◆ Software
- ◆ Data
- ◆ Personnel
- ◆ Procedures
- ◆ Facilities

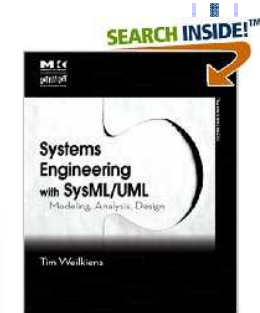
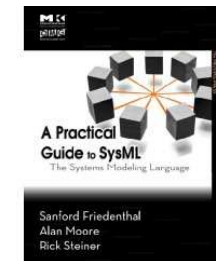
# SysML Diagram Taxonomy



Think of SysML as an integrated collection of languages...

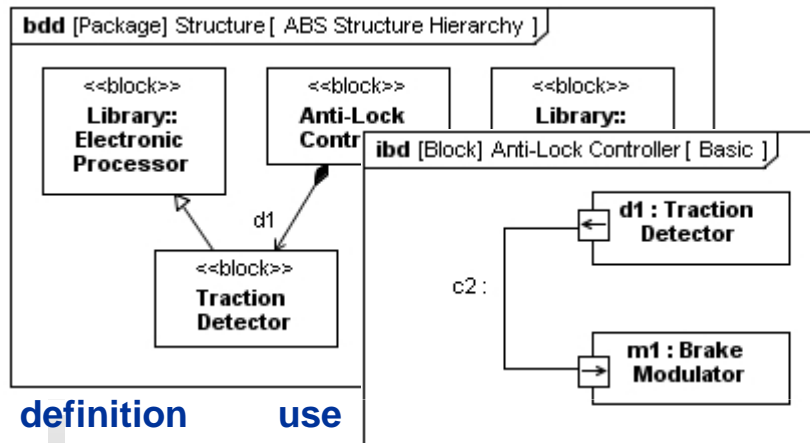
# Some History...

- Specification: <http://www.omg.org/spec/SysML/>
  - v1.0: 2007-09
  - v1.1: 2008-11
  - v1.2: 2010-06
  - v2.x: RFI preparation workshop - 2008-12
- Strong vendor support
  - MagicDraw (No Magic), Artisan Studio (Atego), Enterprise Architect (Sparx Systems), Rhapsody (IBM),...
- Good learning infrastructure
  - Books, short courses, academic courses, INCOSE/OMG tutorial, public examples, etc.
- OMG Certified Systems Modeling Professional
  - <http://www.omg.org/ocsmrp/>



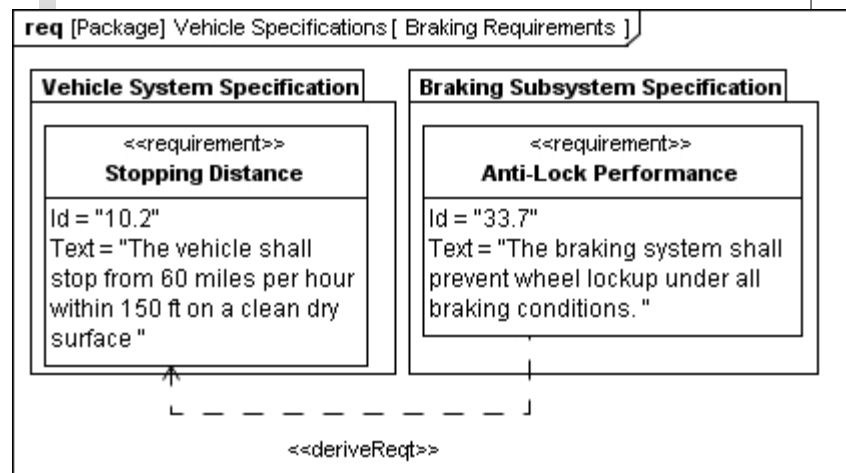
# What is SysML? (www.omgsysml.org)

## 1. Structure



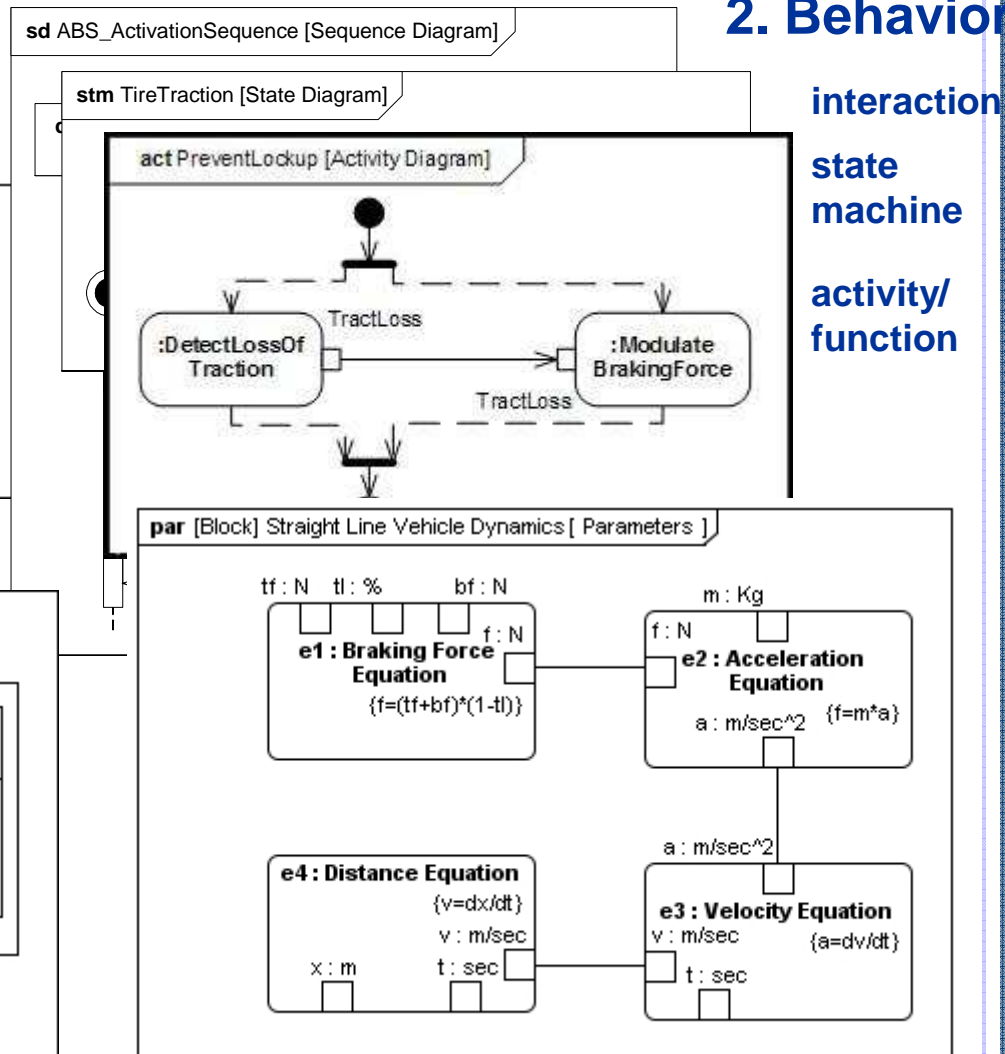
definition

use



## 3. Requirements

## 2. Behavior



interaction

state machine

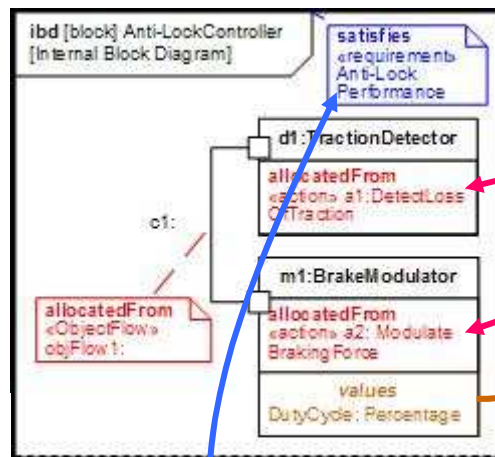
activity/function

## 4. Parametrics

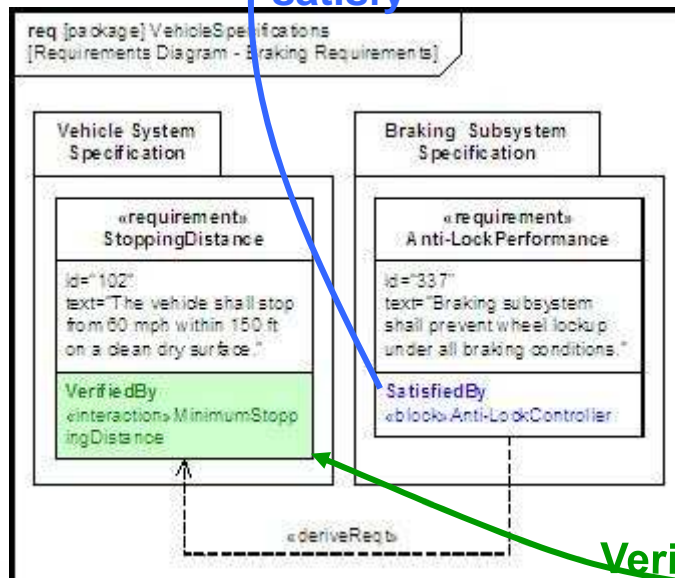


# What is SysML? (www.omgsysml.org)

## 1. Structure

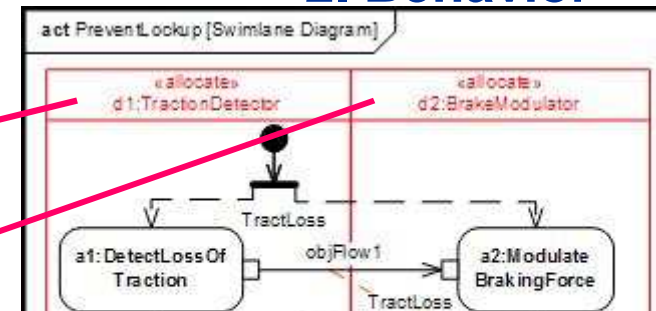


satisfy



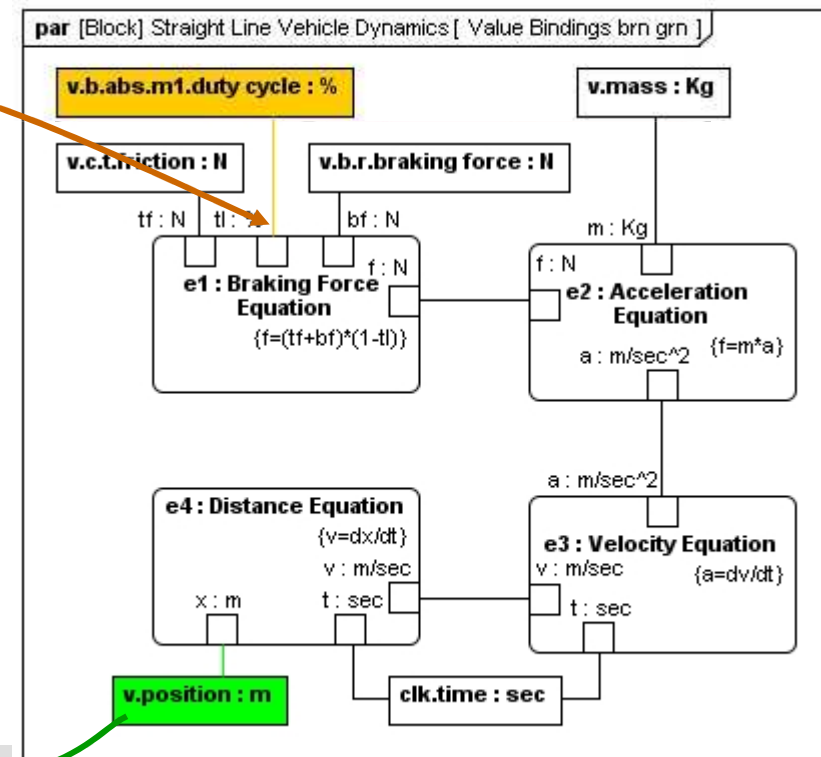
## 3. Requirements (via interaction)

## 2. Behavior



allocate

value binding



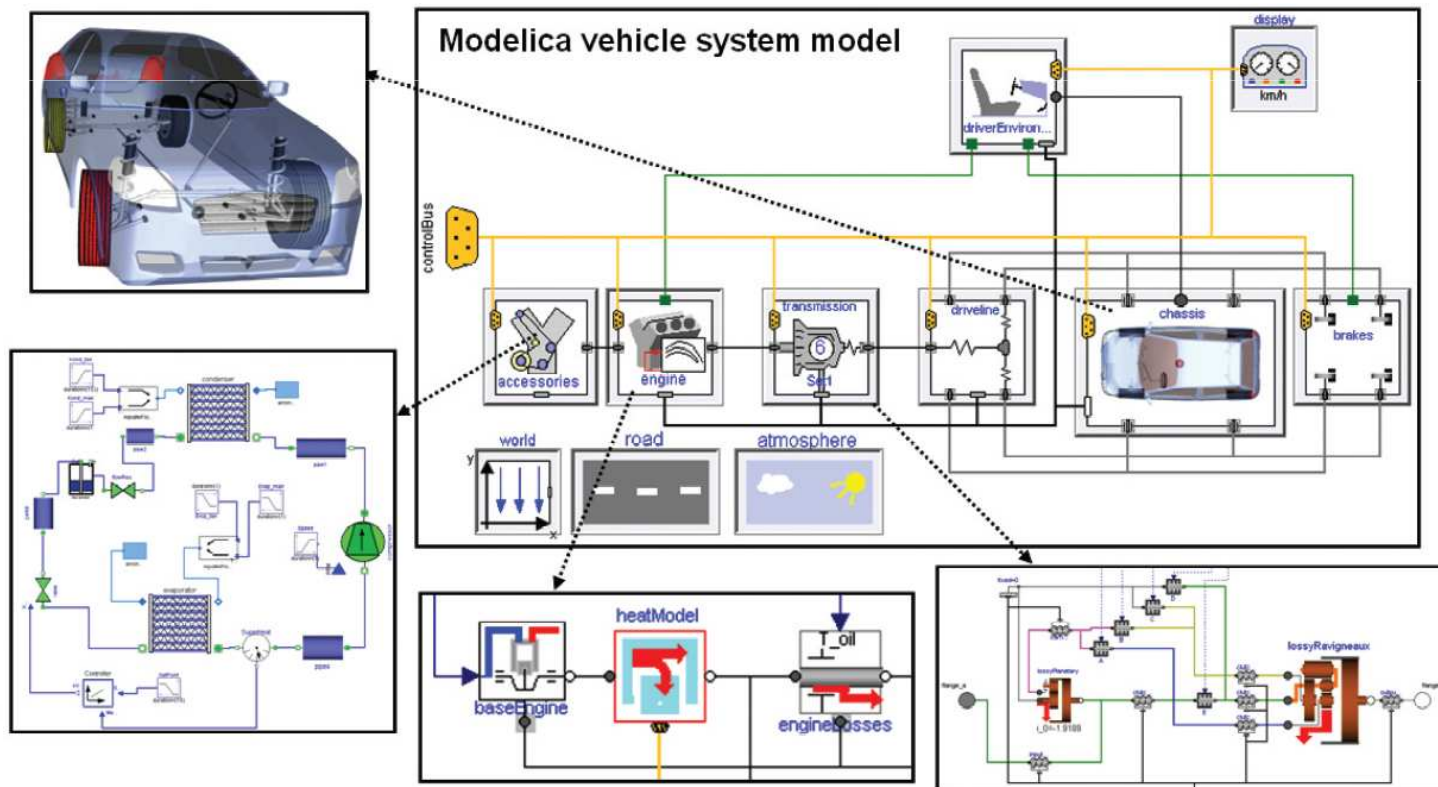
## 4. Parametrics

# What is Modelica? ([www.modelica.org](http://www.modelica.org))

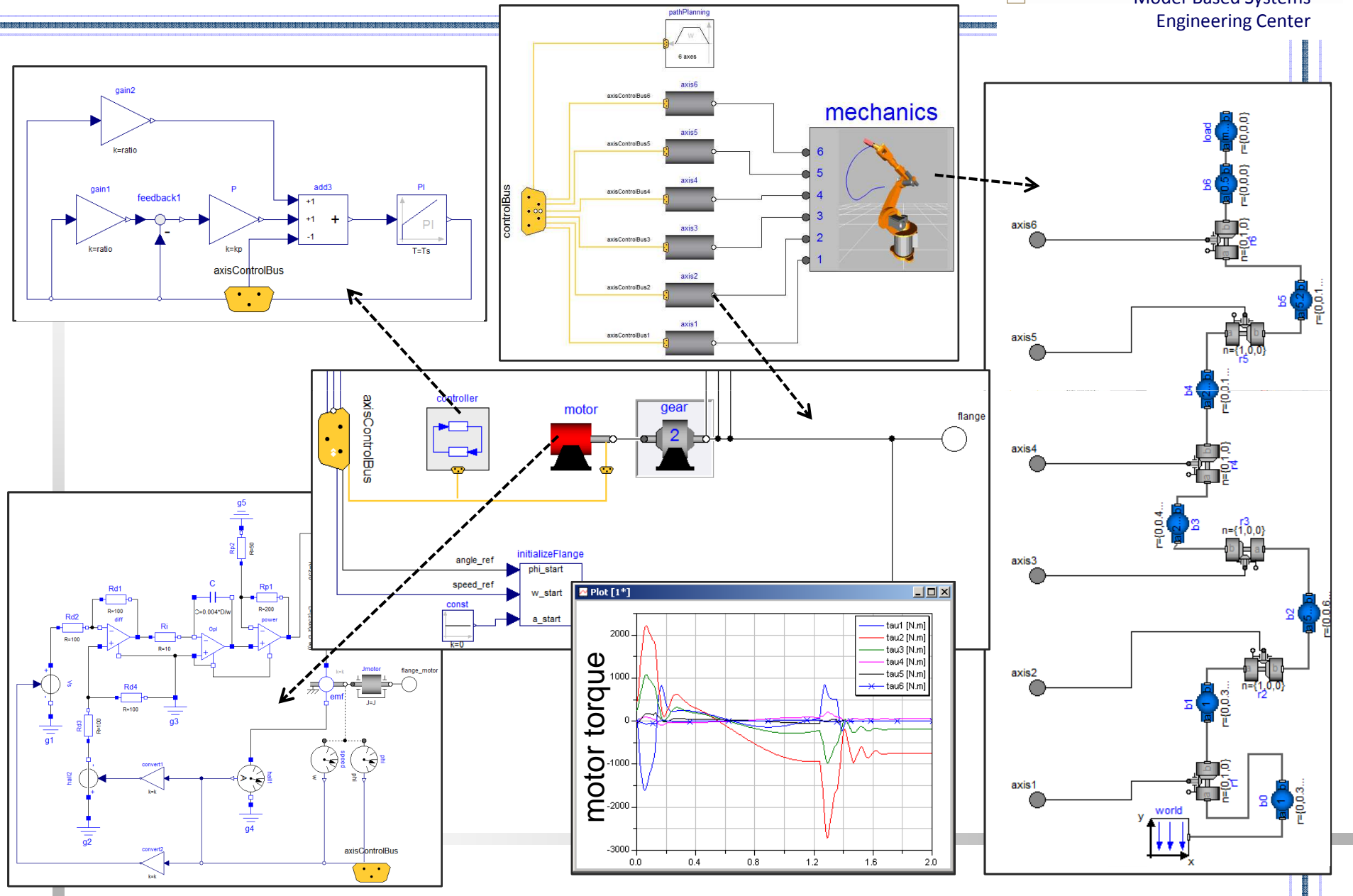
- State-of-the-art Modeling Language for System Dynamics
  - Differential Algebraic Equations (DAE)
  - Discrete Events
- Formal, object-oriented language
- Standardized by the Modelica Association
  - Open language specification – tool independent
- Multi-domain modeling
- Ports represent energy flow (undirected) or signal flow (directed)
- Acausal, equation-based, declarative ( $f-m \cdot a=0$ )

# Modelica: Active and Mature Community

- Modelica association — 20+ free libs ([www.modelica.org](http://www.modelica.org))
- 6 commercial solvers, 3 open-source solvers (Dymola, MapleSim, SimulationX, OpenModelica,...)
- EUROSYSLIB project — 20+ libs under development ([http://www.itea2.org/public/project\\_leaflets/EUROSYSLIB\\_profile\\_oct-07.pdf](http://www.itea2.org/public/project_leaflets/EUROSYSLIB_profile_oct-07.pdf))

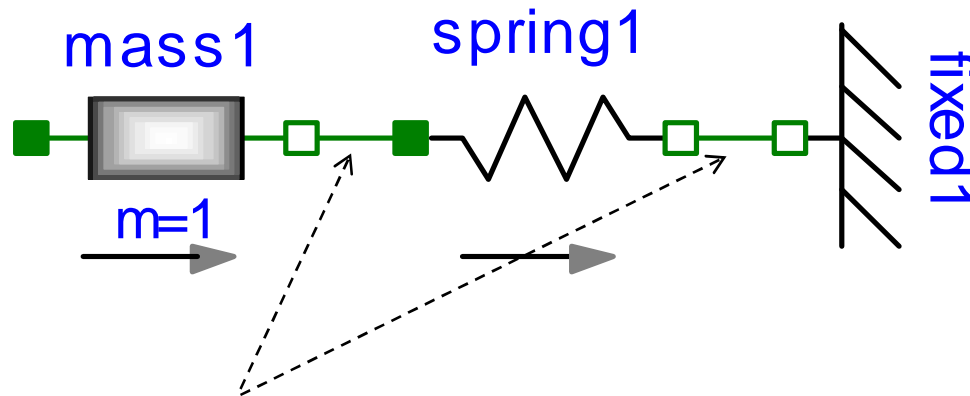


# A Robot Example in Modelica



# Modelica Semantics and Textual Syntax

```
model Spring "Linear 1D translational spring"
  extends Translational.Interfaces.PartialCompliant;
  parameter SI.TranslationalSpringConstant c(final min=0, start = 1)
    "spring constant ";
  parameter SI.Distance s_rel0=0 "unstretched spring length";
equation
  f = c*(s_rel - s_rel0);
end Spring;
```



Graphical symbols  
defined as  
annotations in  
textual models

- Connections represent Kirchhoff semantics
  - Across variables (voltage, pressure,...) are equal
  - Through variables (current, flow rate,...) add to zero

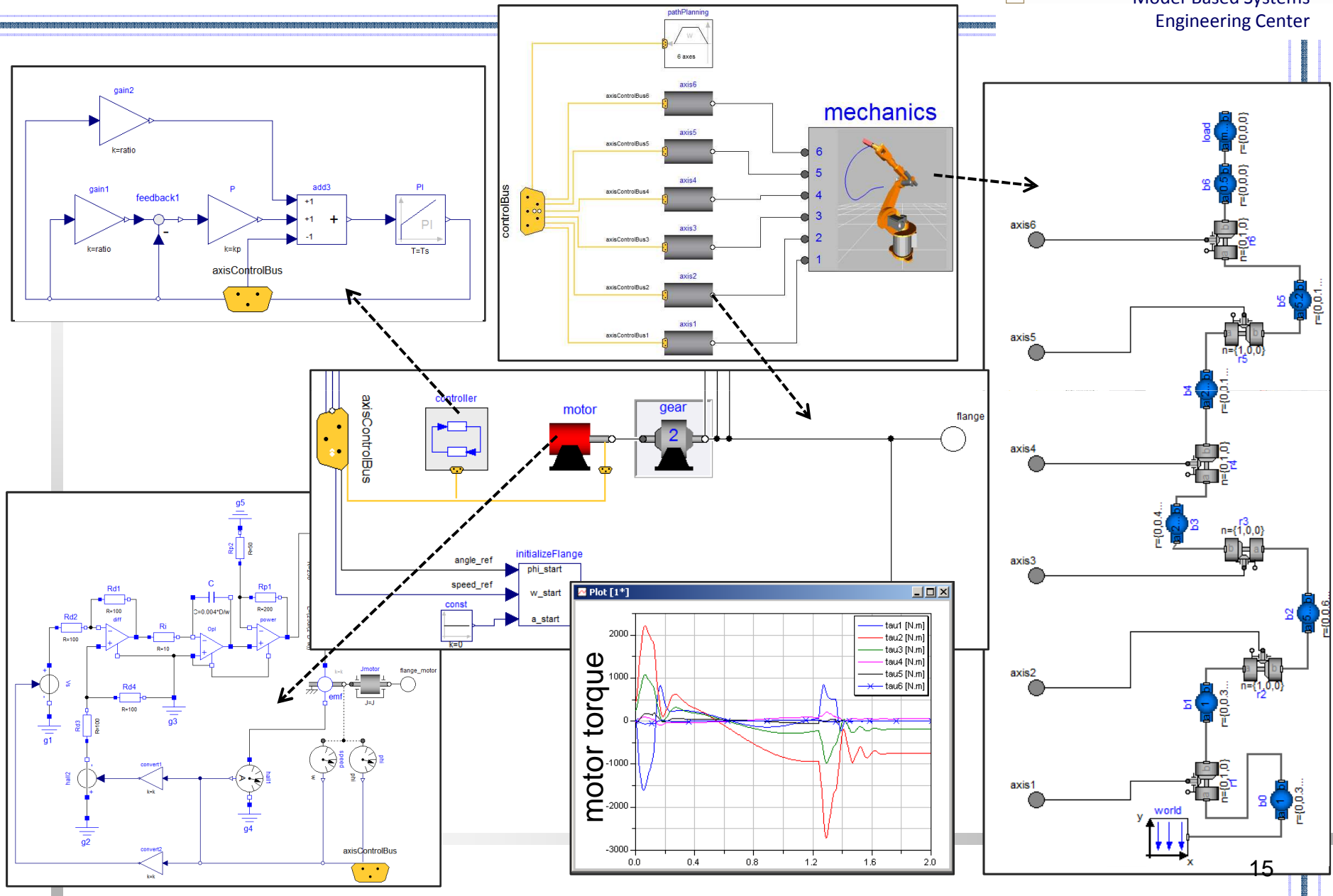
# Presentation Overview

- What is SysML?
- What is Modelica?

## Motivating Example: Design & Analysis of Robot

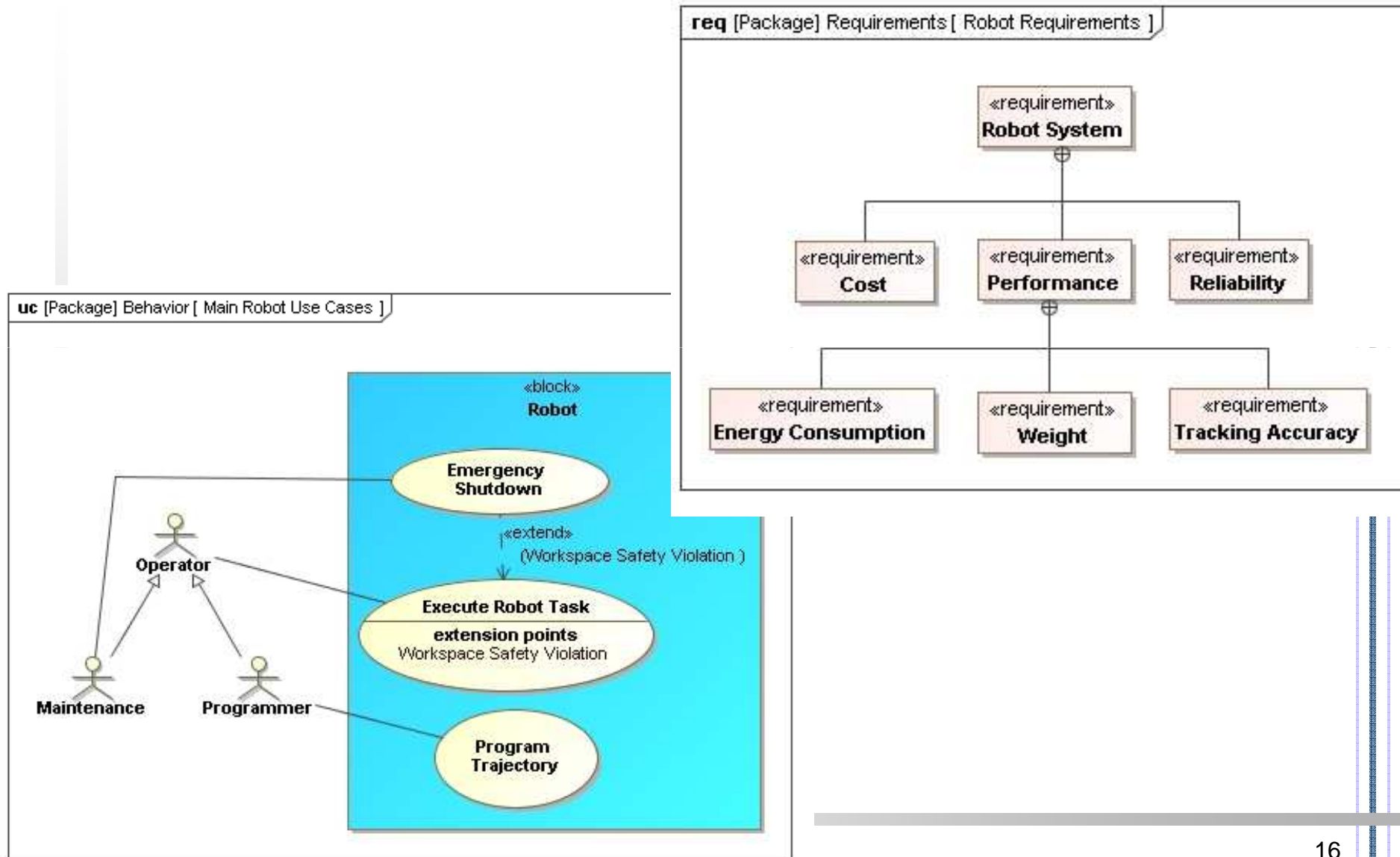
- SysML-Modelica Transformation Specification
- Transformations in Systems Modeling
- Timeline towards Specification Adoption
- Summary

# A Robot Example in Modelica



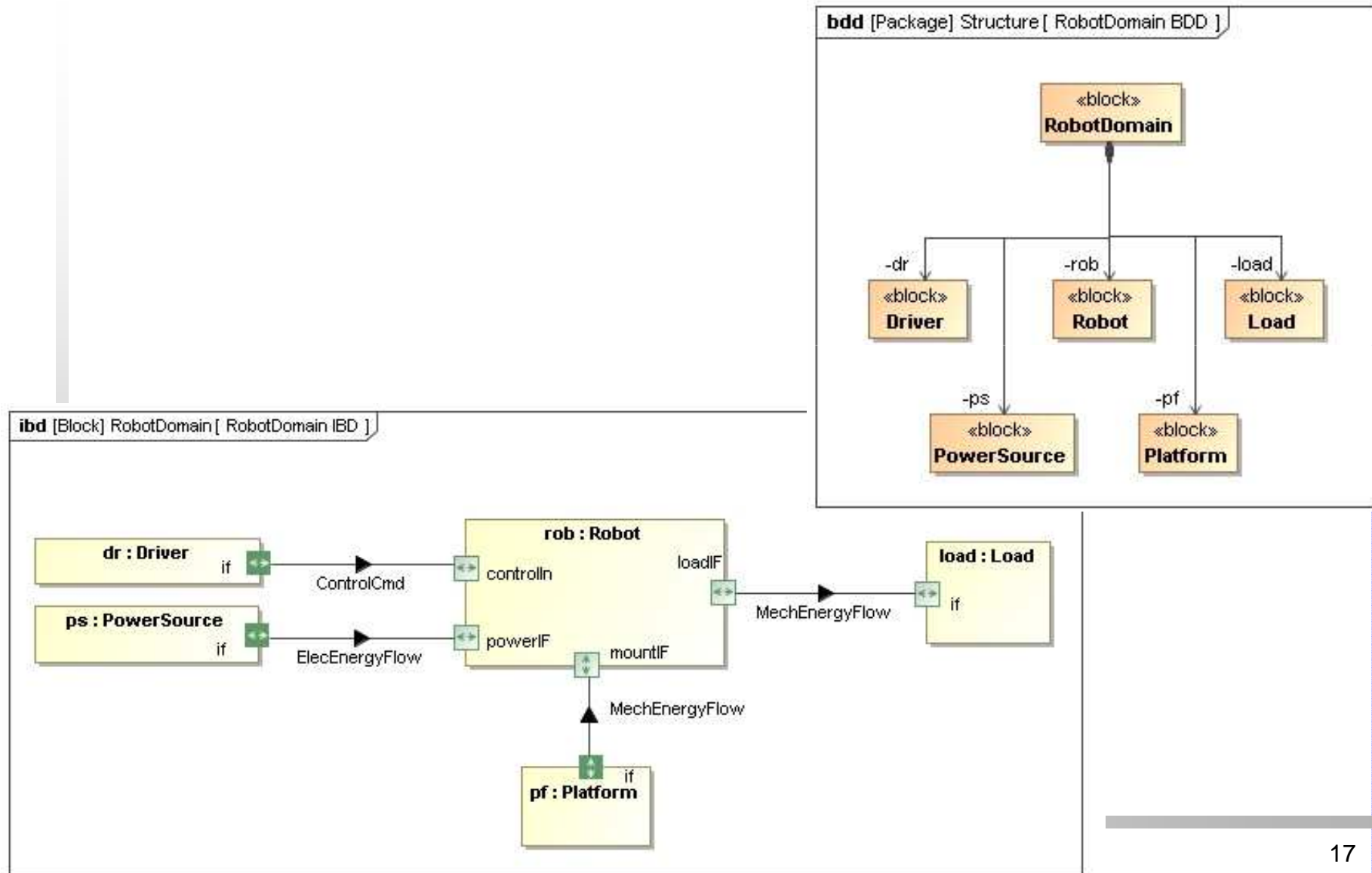


# SysML-Modelica Robot Example: UseCases & Requirements



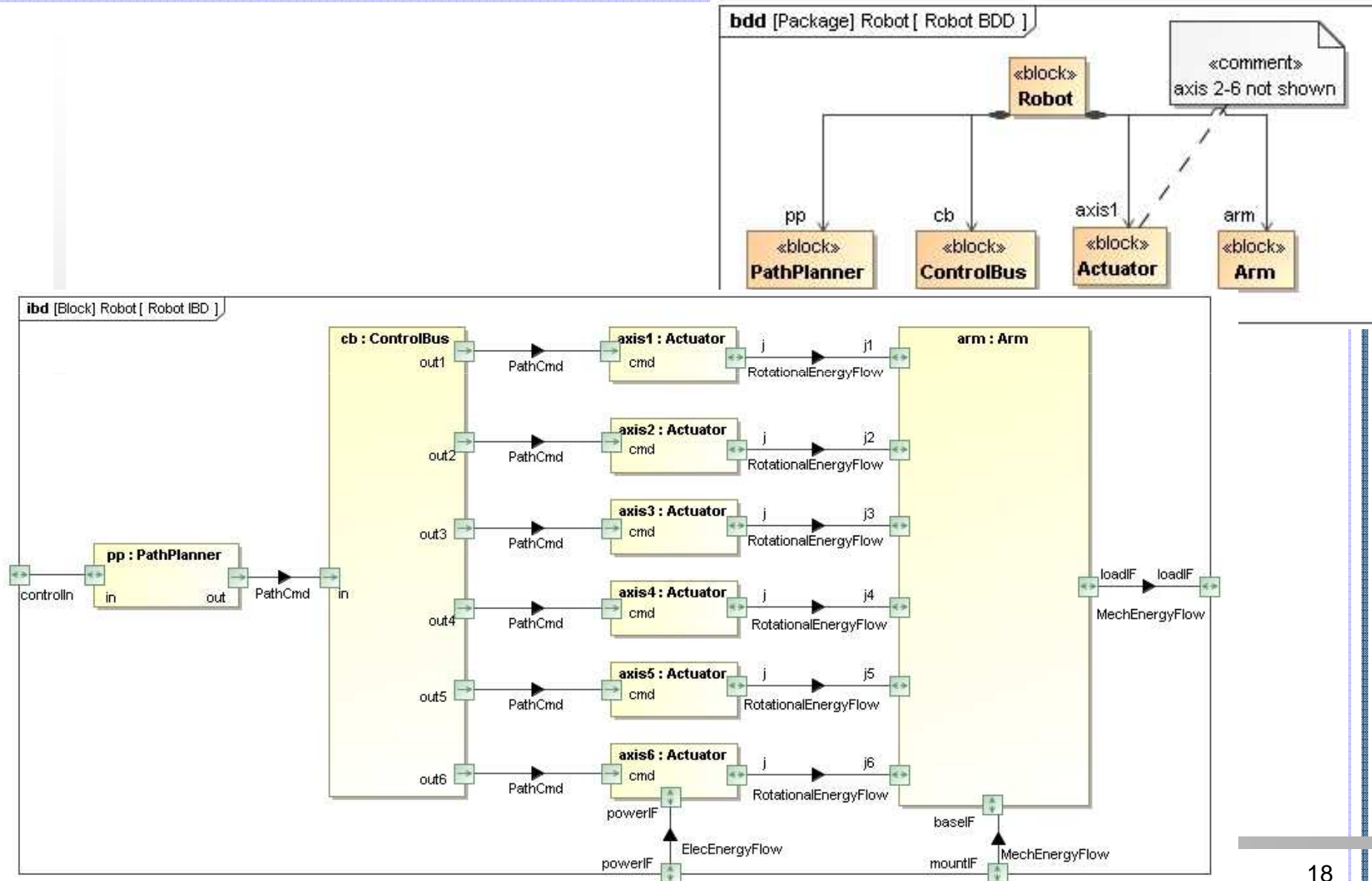


# SysML-Modelica Robot Example: Robot Domain BDD & IBD

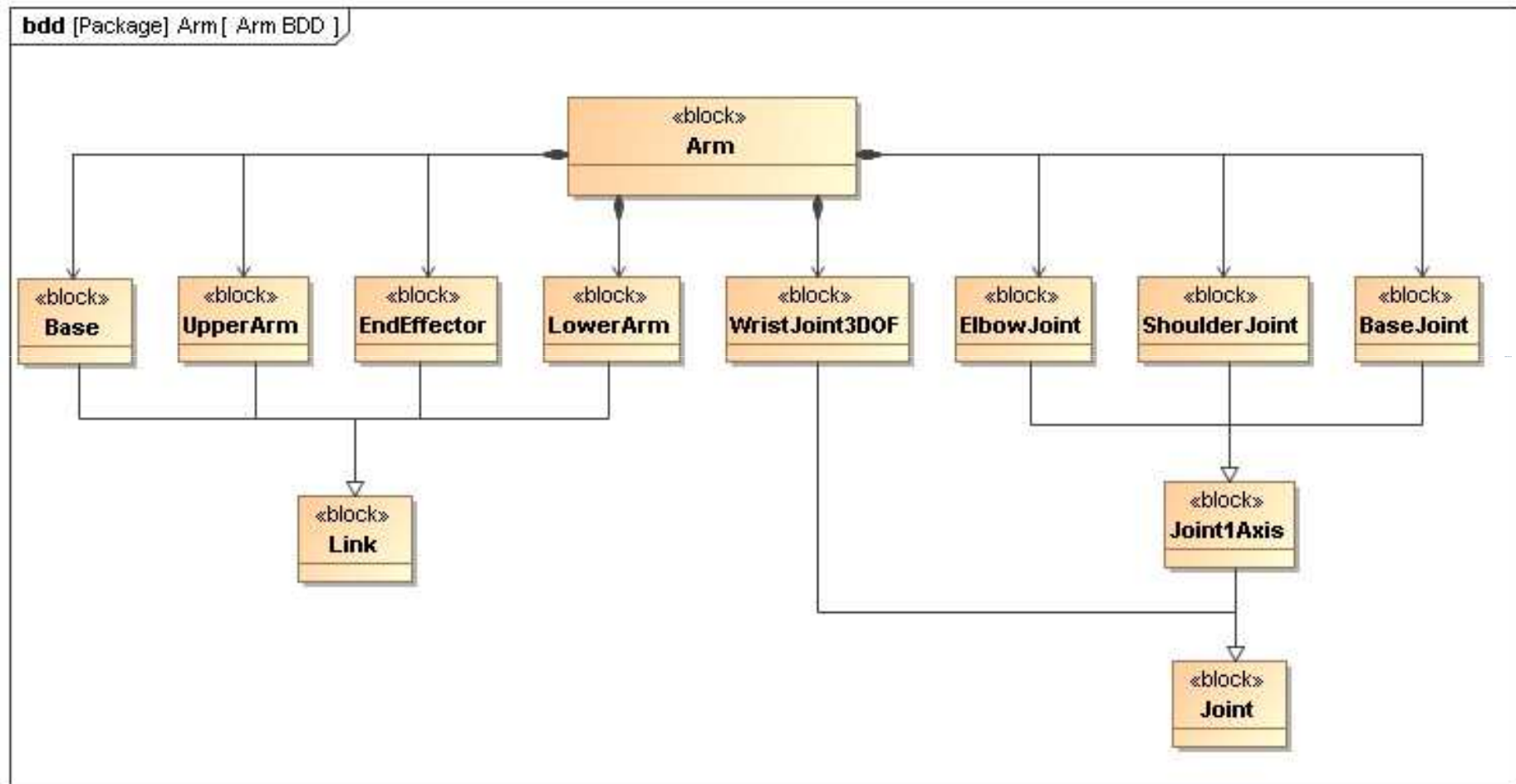


# SysML-Modelica Robot Example:

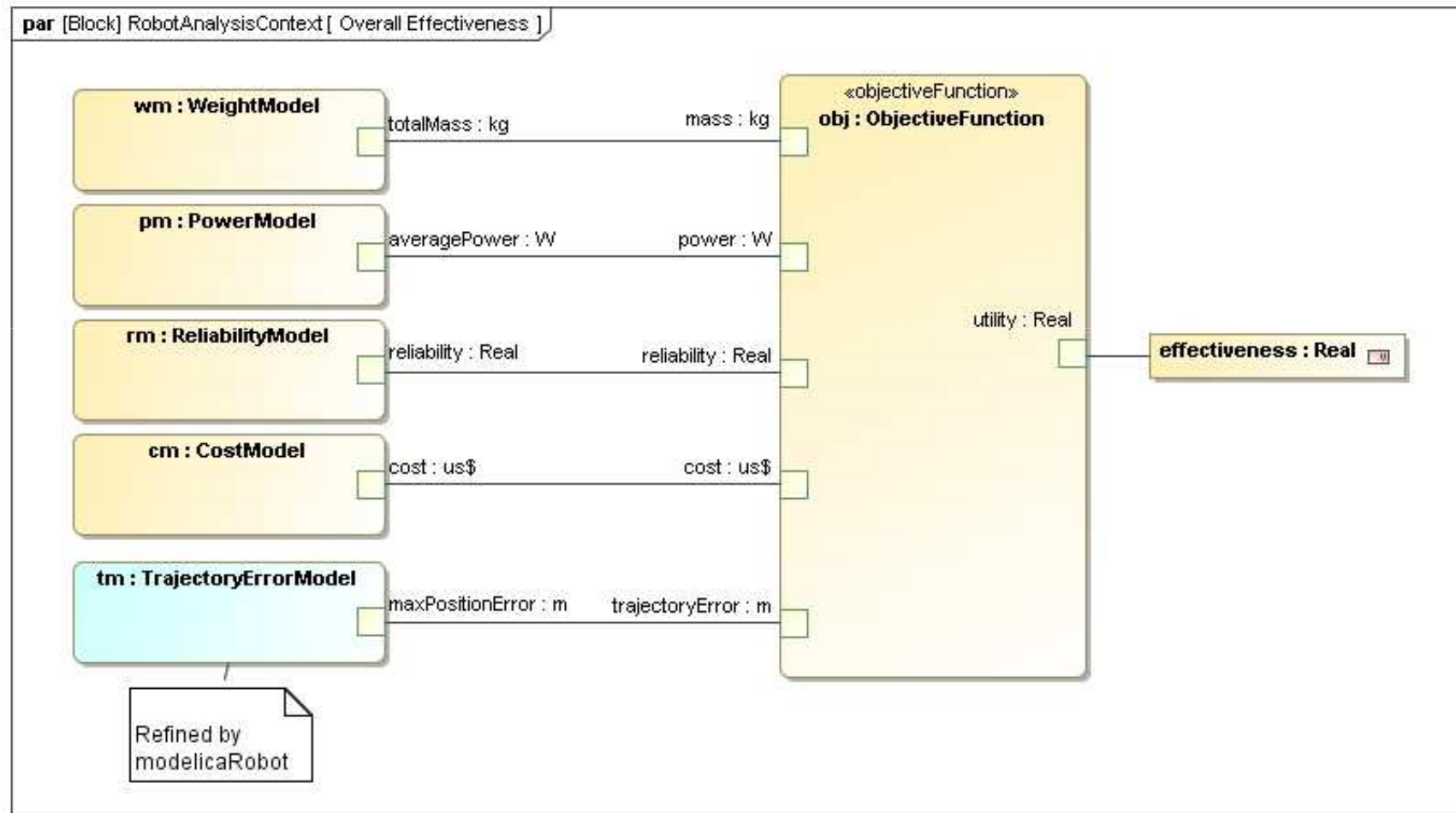
## Robot BDD & IBD



# SysML-Modelica Robot Example: Robot Arm BDD

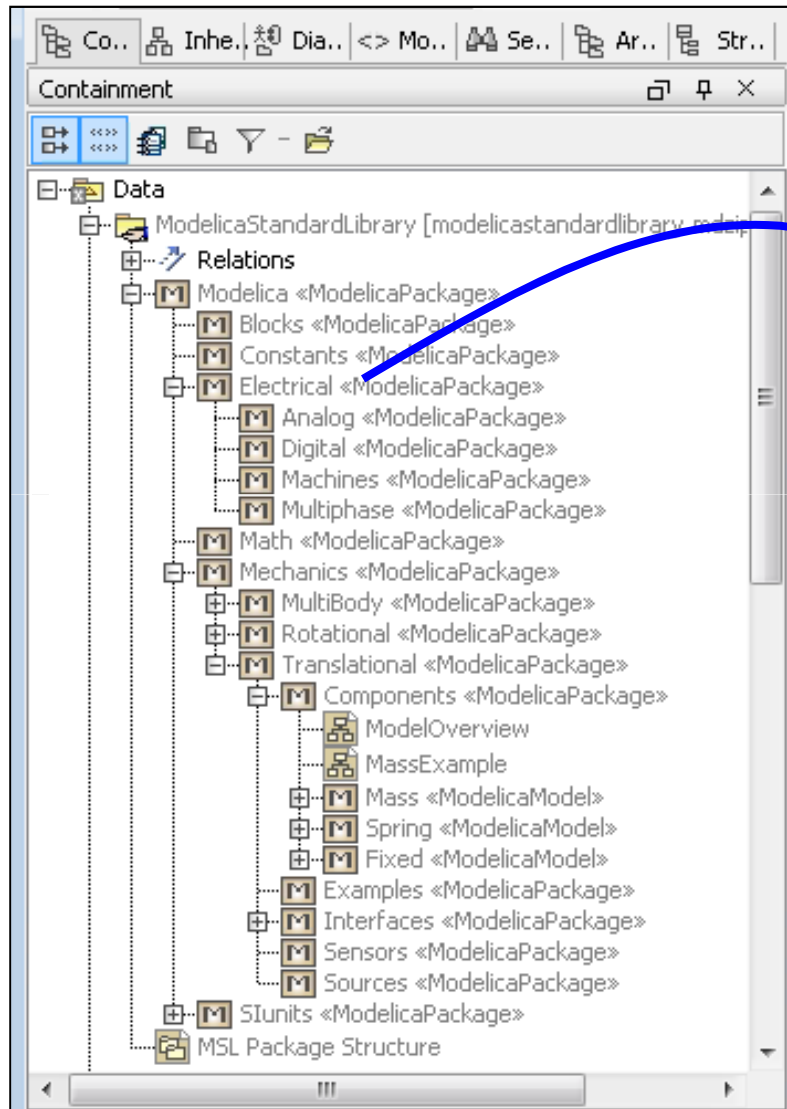


# SysML-Modelica Robot Example: Analysis and Trade Study

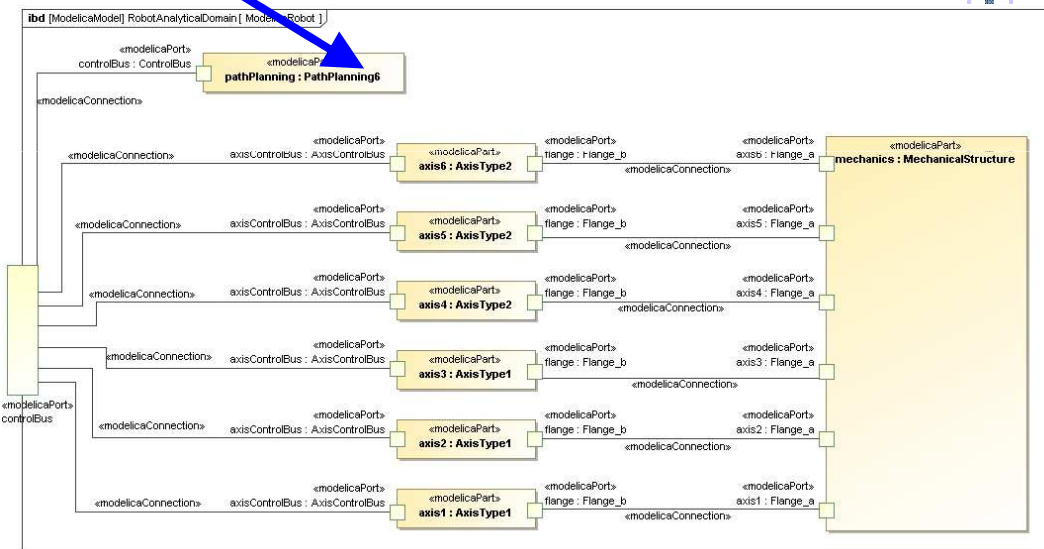


**Analysis models depend on descriptive models**

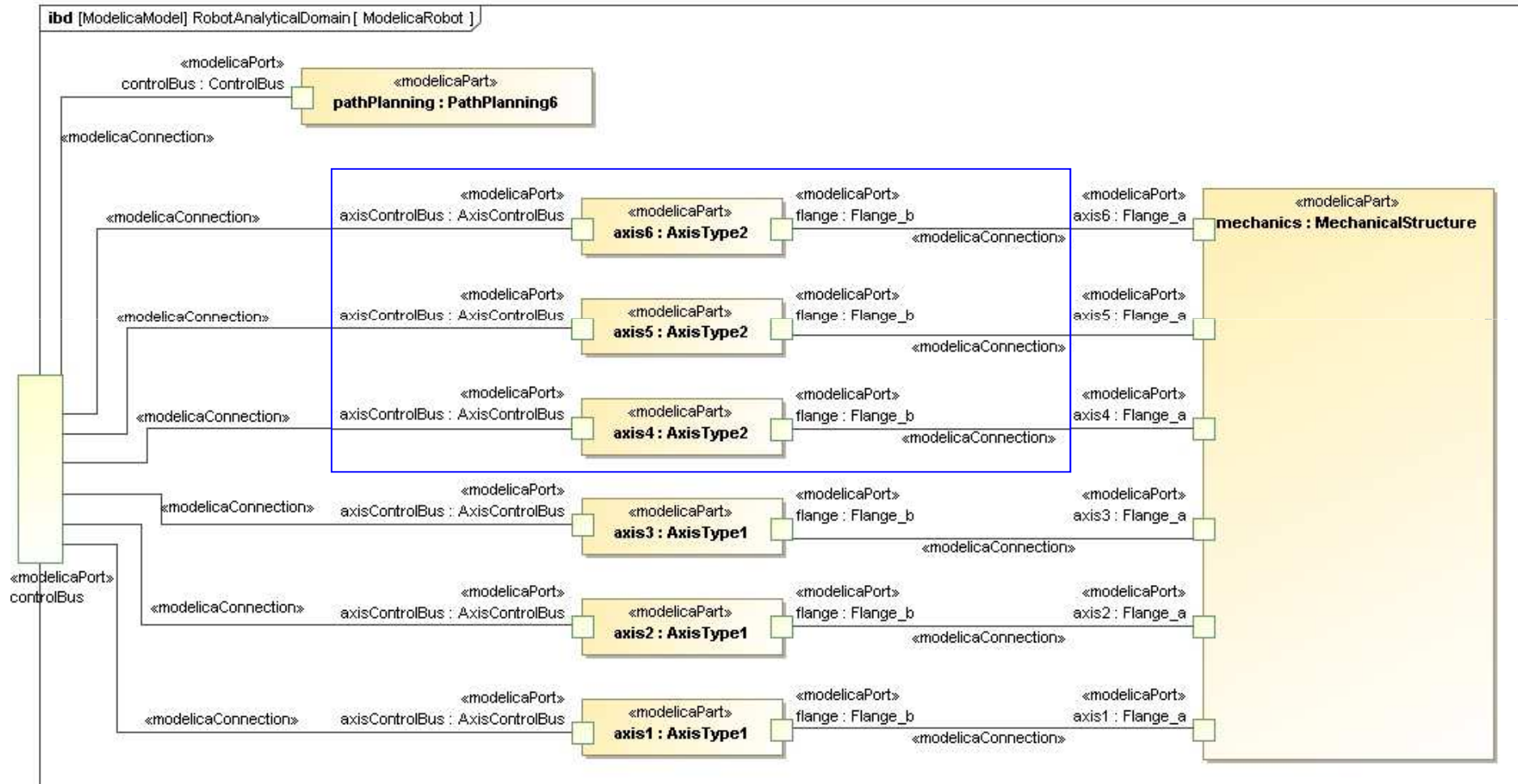
# SysML4Modelica Analytical Model: Compose Model from Standard Library



Drag and drop into  
IBD «ModelicaModel»

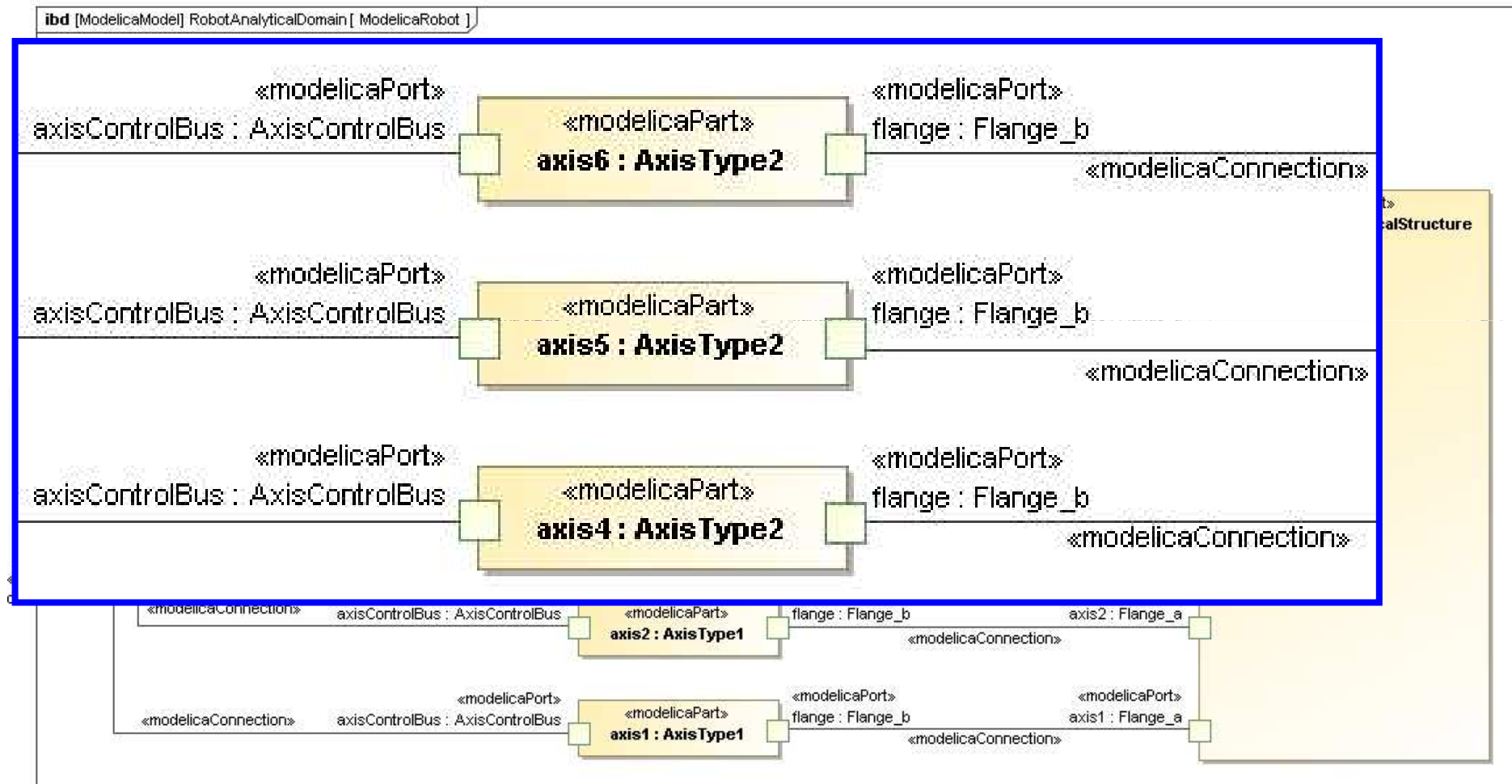


# SysML4Modelica Analytical Model: Detailed IBD

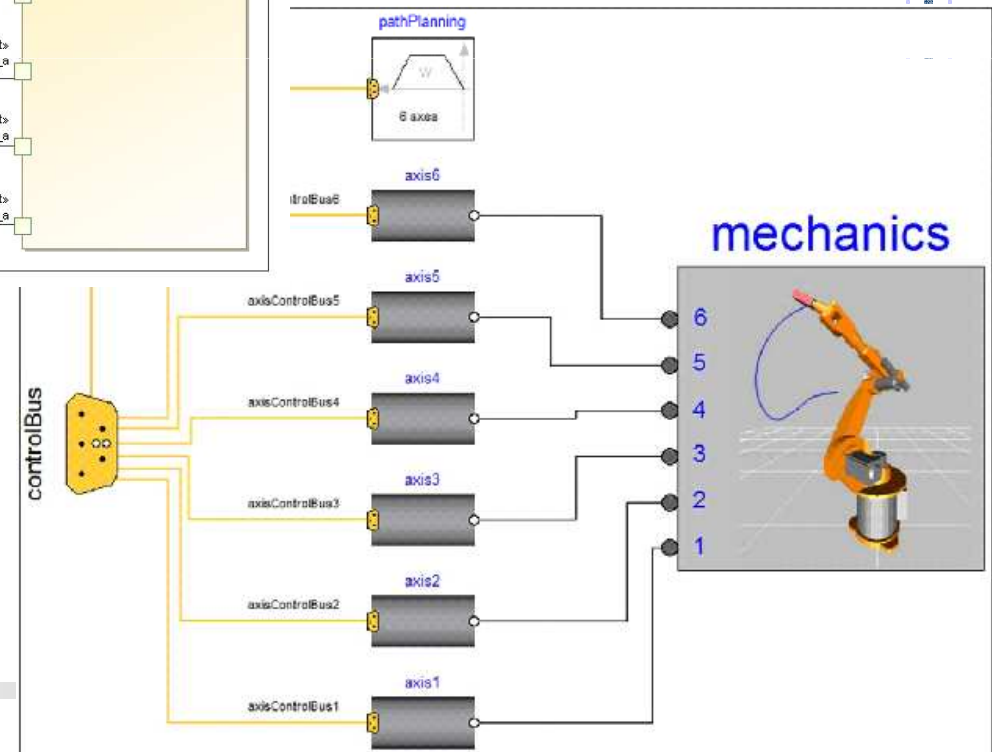
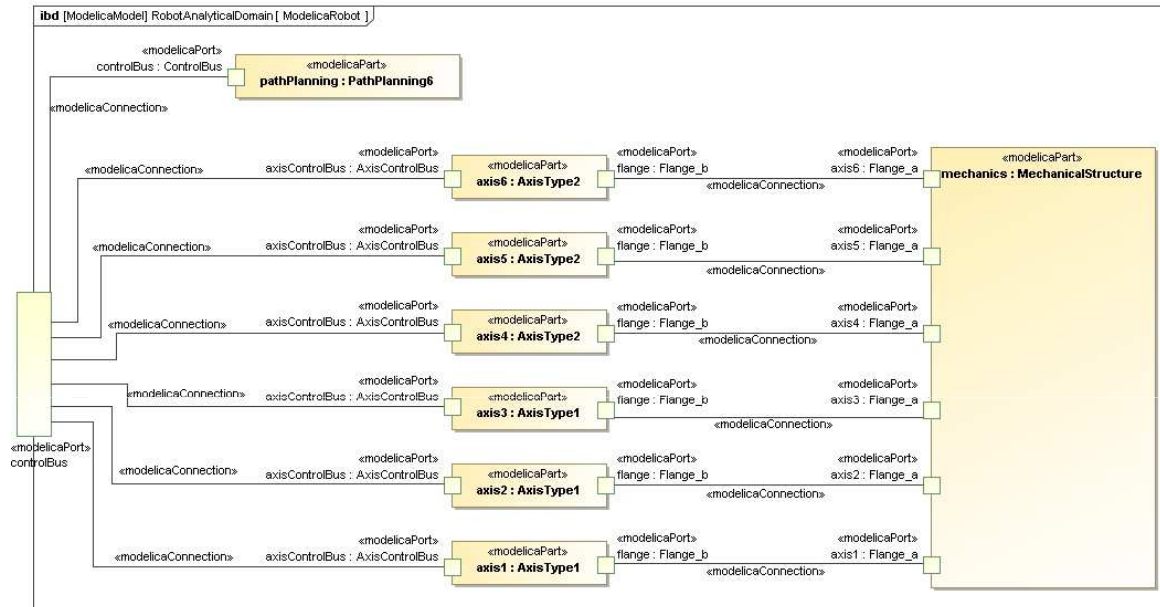




# SysML4Modelica Analytical Model: Detailed IBD

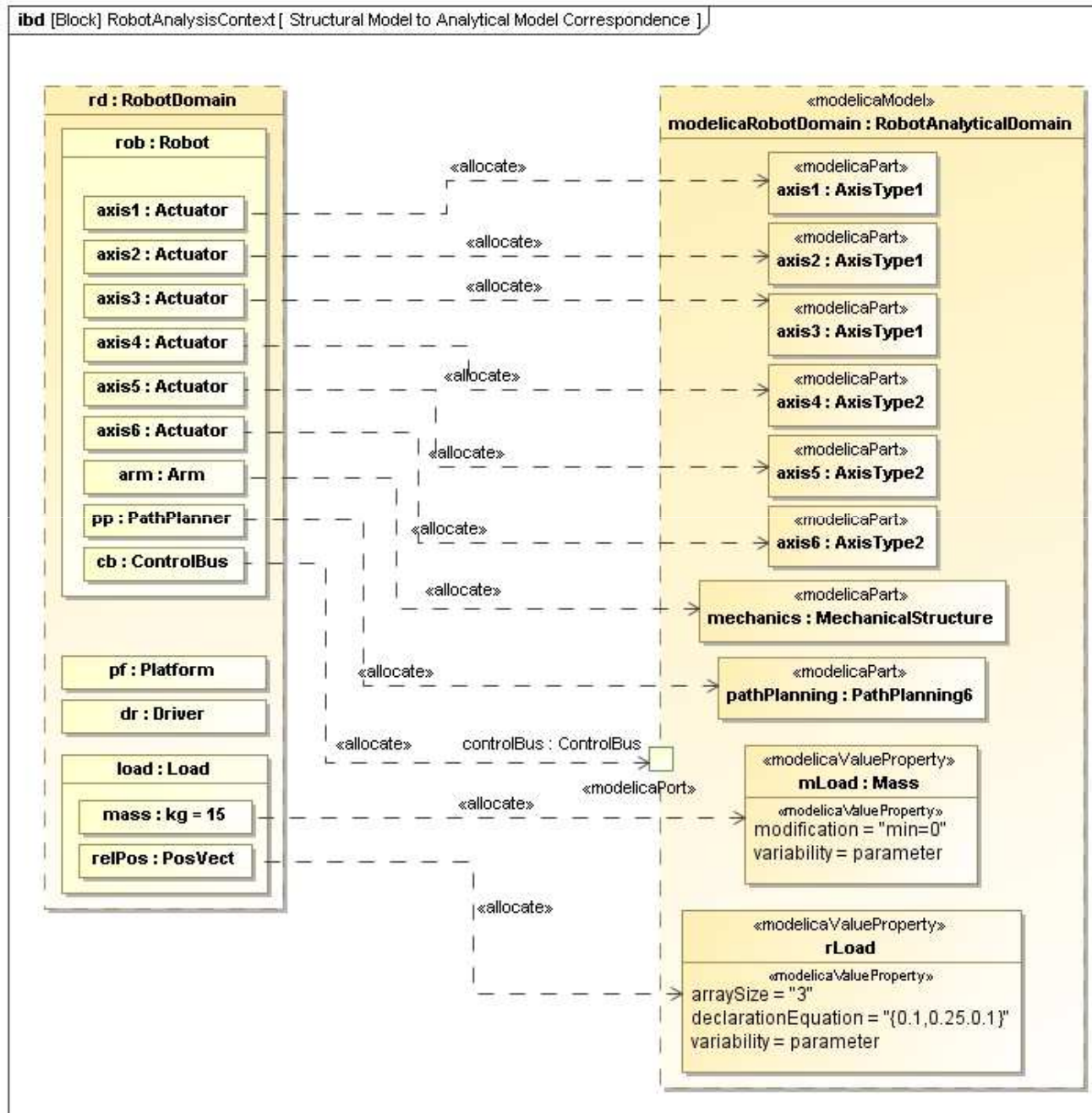


# SysML4Modelica Analytical Model: Relation to Modelica Native Model

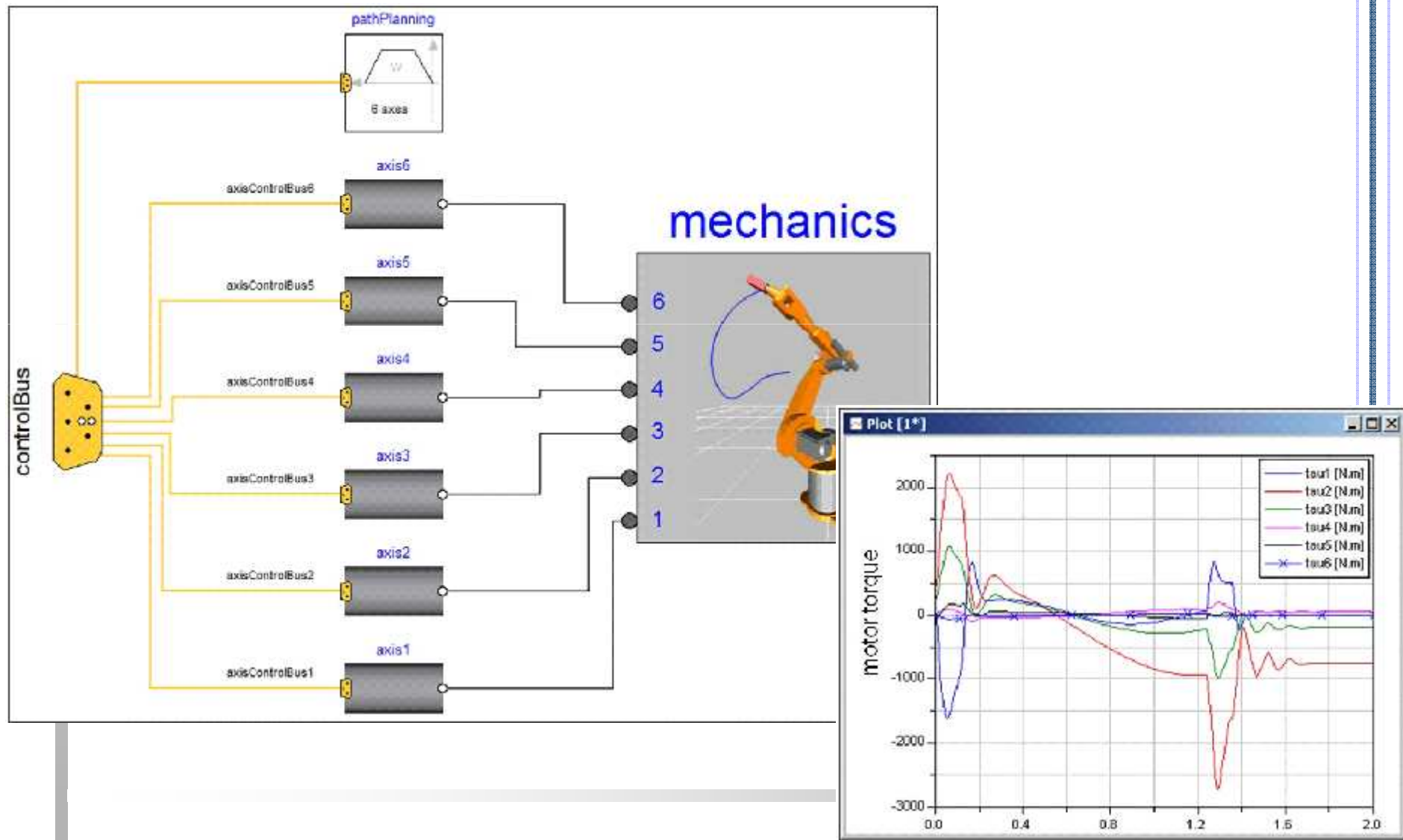




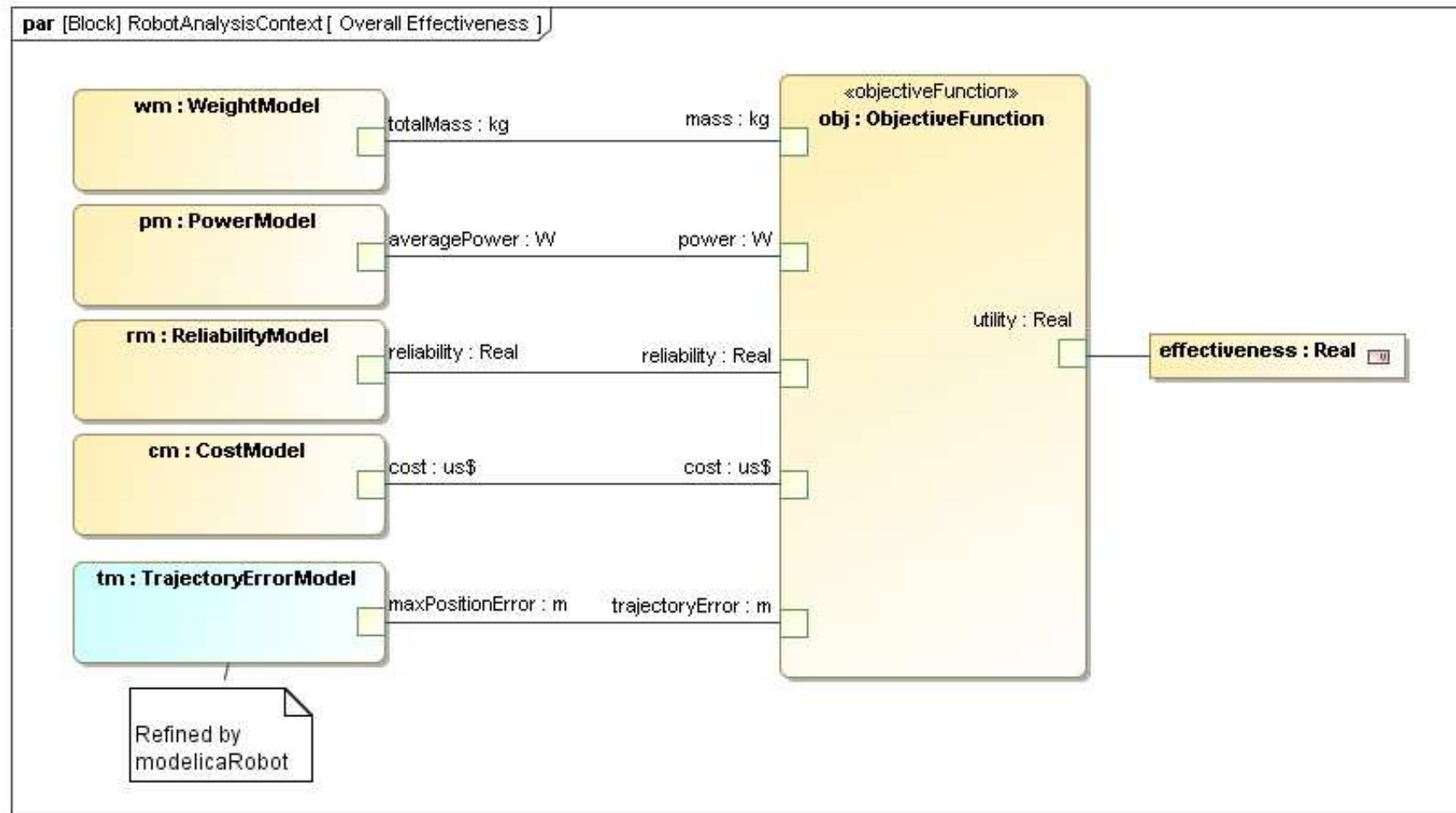
# SysML4Modelica Analytical Model: Allocation



# SysML-Modelica Robot Example: Modelica model with simulation results



# SysML-Modelica Robot Example: Analysis and Trade Study



**Analysis results are incorporated in Trade Study**

# Presentation Overview

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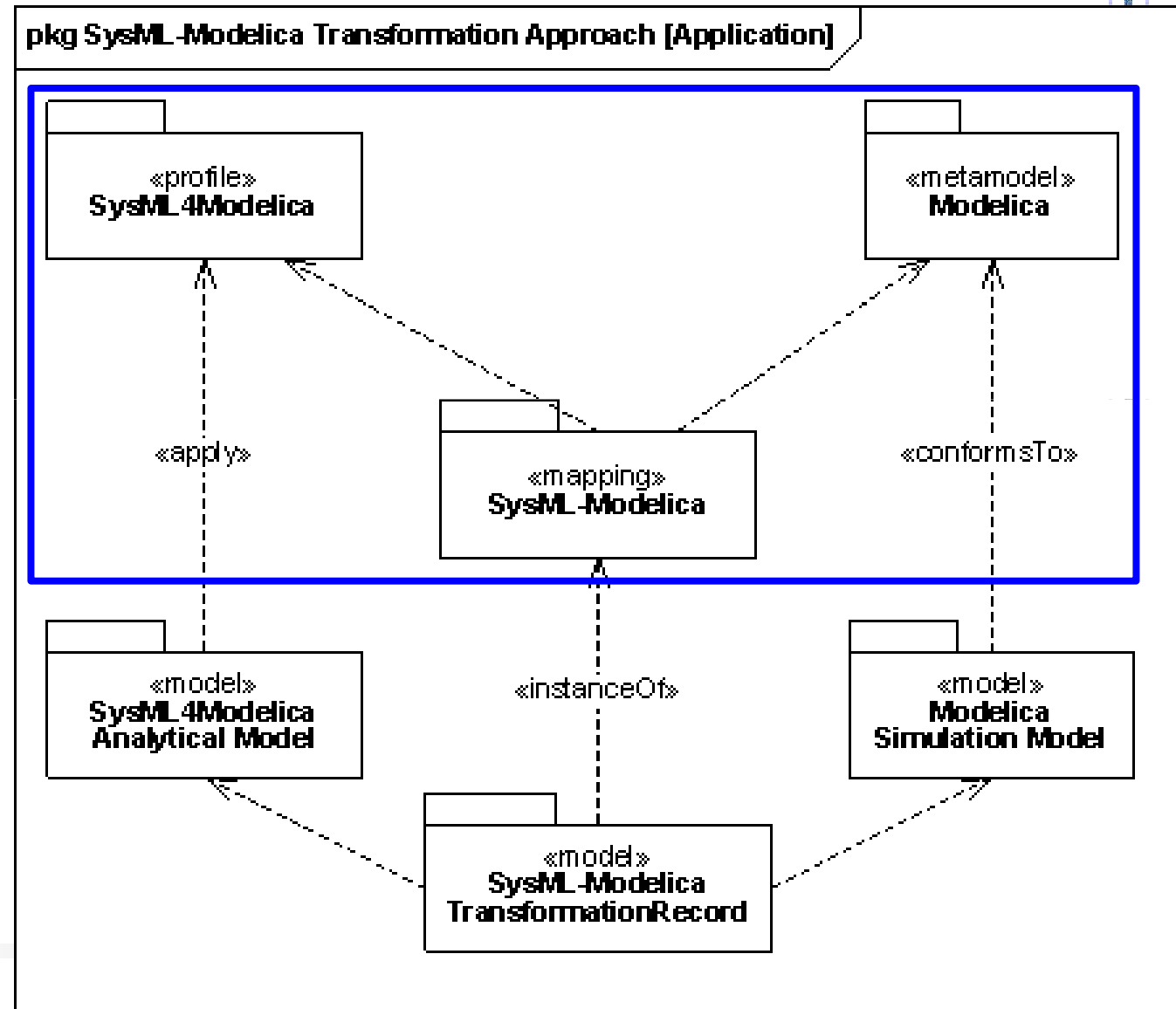


## SysML-Modelica Transformation Specification

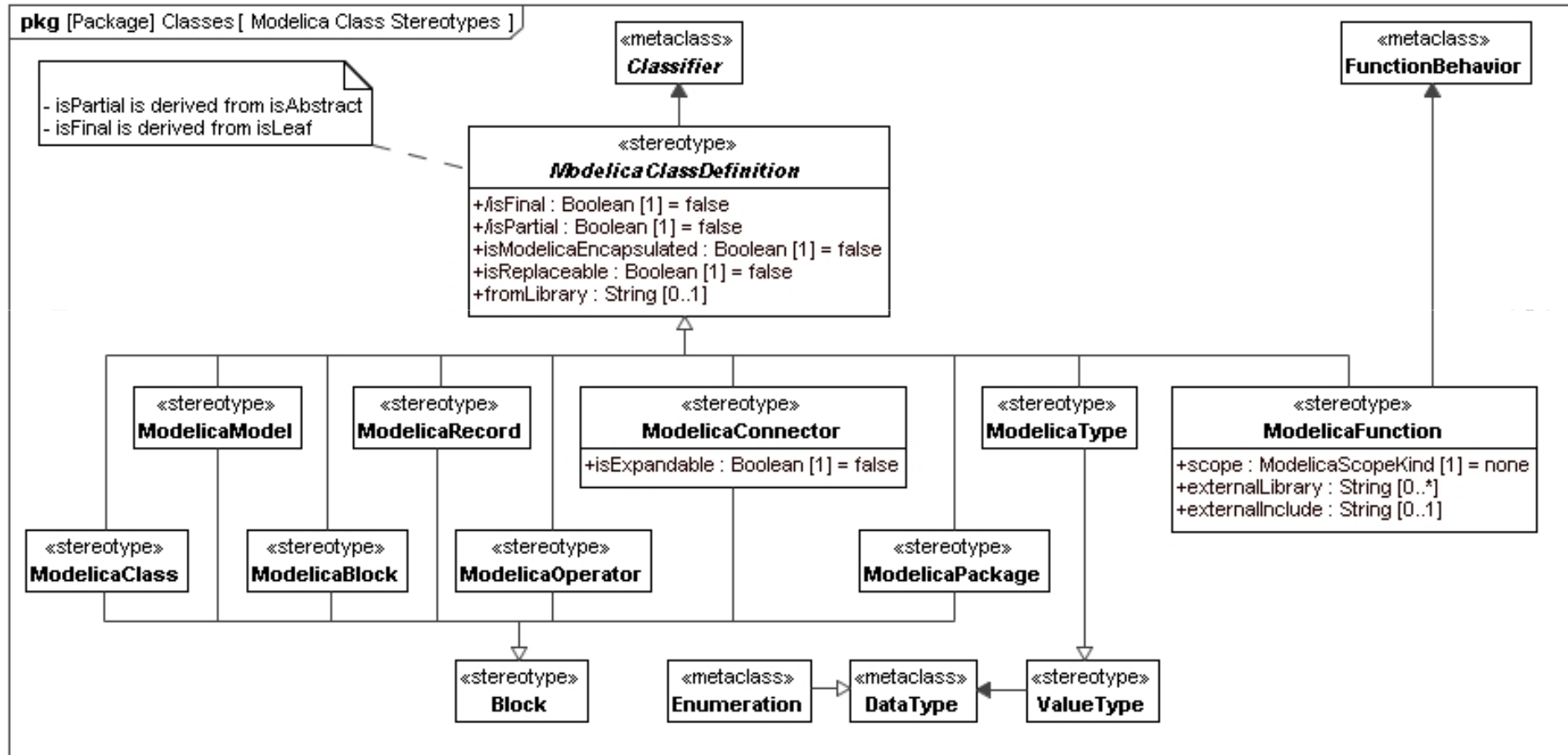
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# SysML-Modelica Transformation Specification

SysML-  
Modelica  
Transformation  
follows the  
principles  
of Model-  
Driven  
Architecture  
(MDA)



# SysML4Modelica Profile

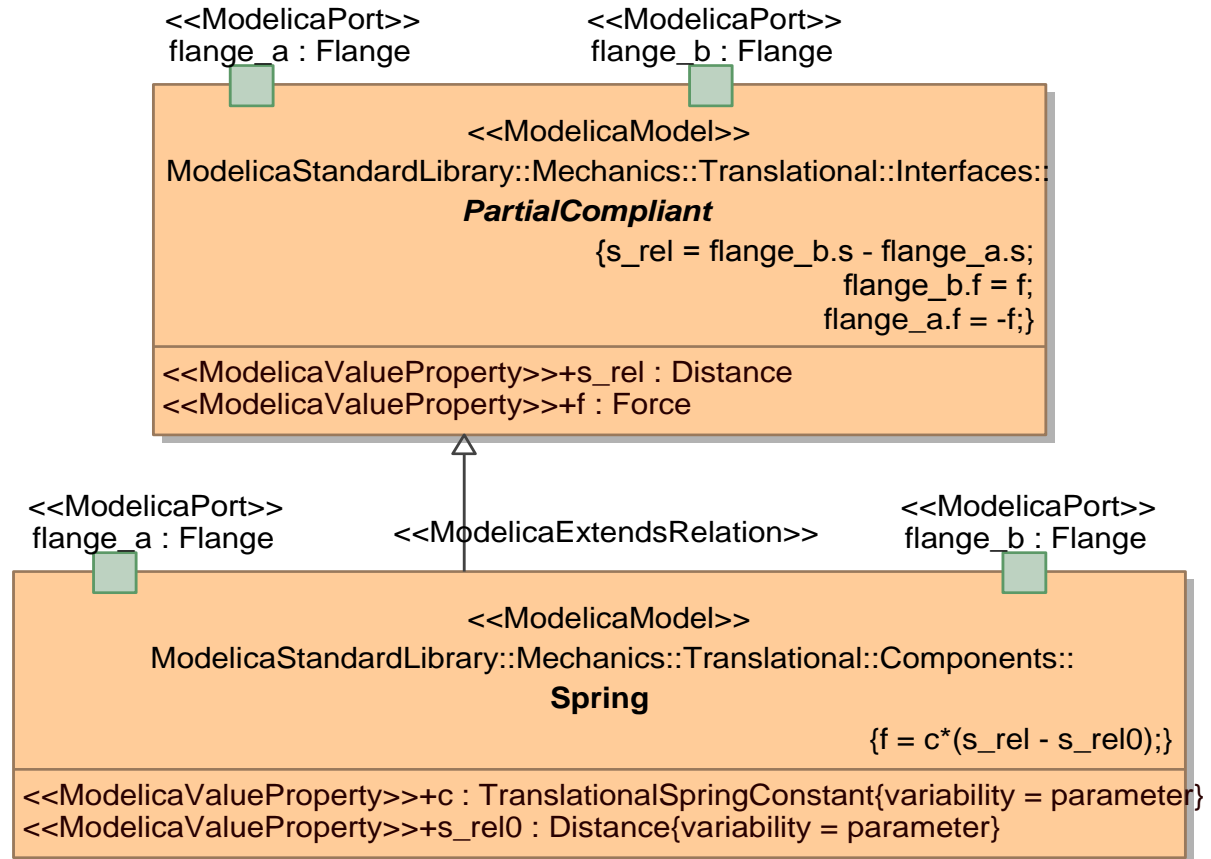


SysML4Modelica

Formal  
mapping

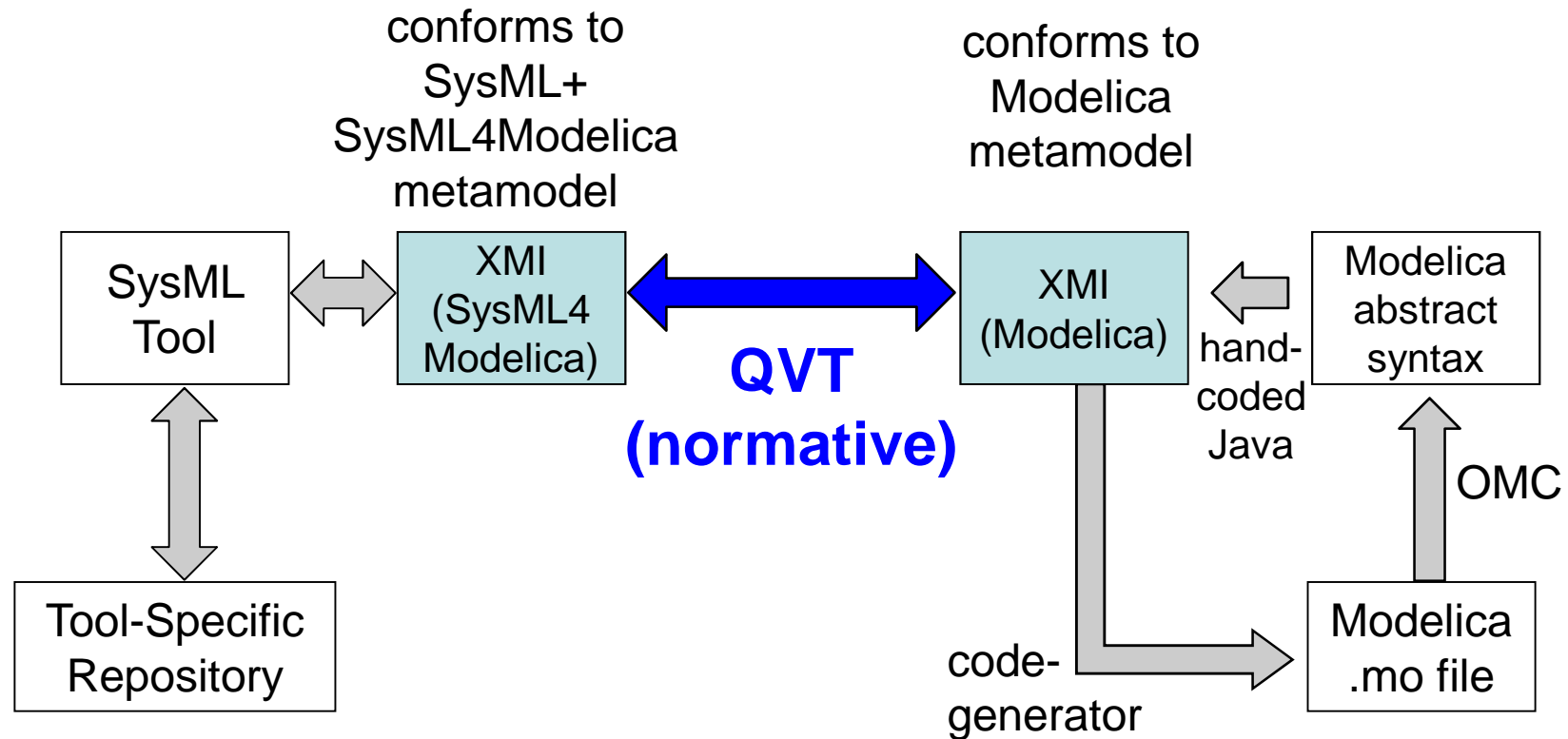
Modelica

bdd [Package] Components[  ModelOverview ]



```
model Spring "Linear 1D translational spring"
  extends Translational.Interfaces.PartialCompliant;
  parameter SI.TranslationalSpringConstant c(final min=0, start = 1)
    "spring constant ";
  parameter SI.Distance s_rel0=0 "unstretched spring length";
equation
  f = c*(s_rel - s_rel0);
end Spring;
```

# Reference implementation: Based on OMG QVT



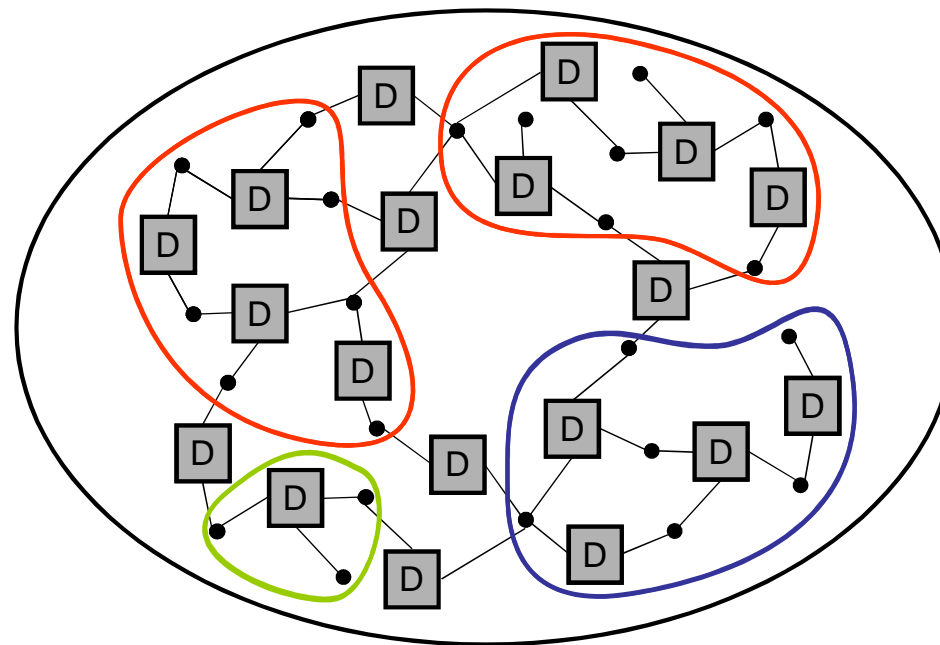
QVT = Query / View / Transformation



# Transformations in Systems Modeling

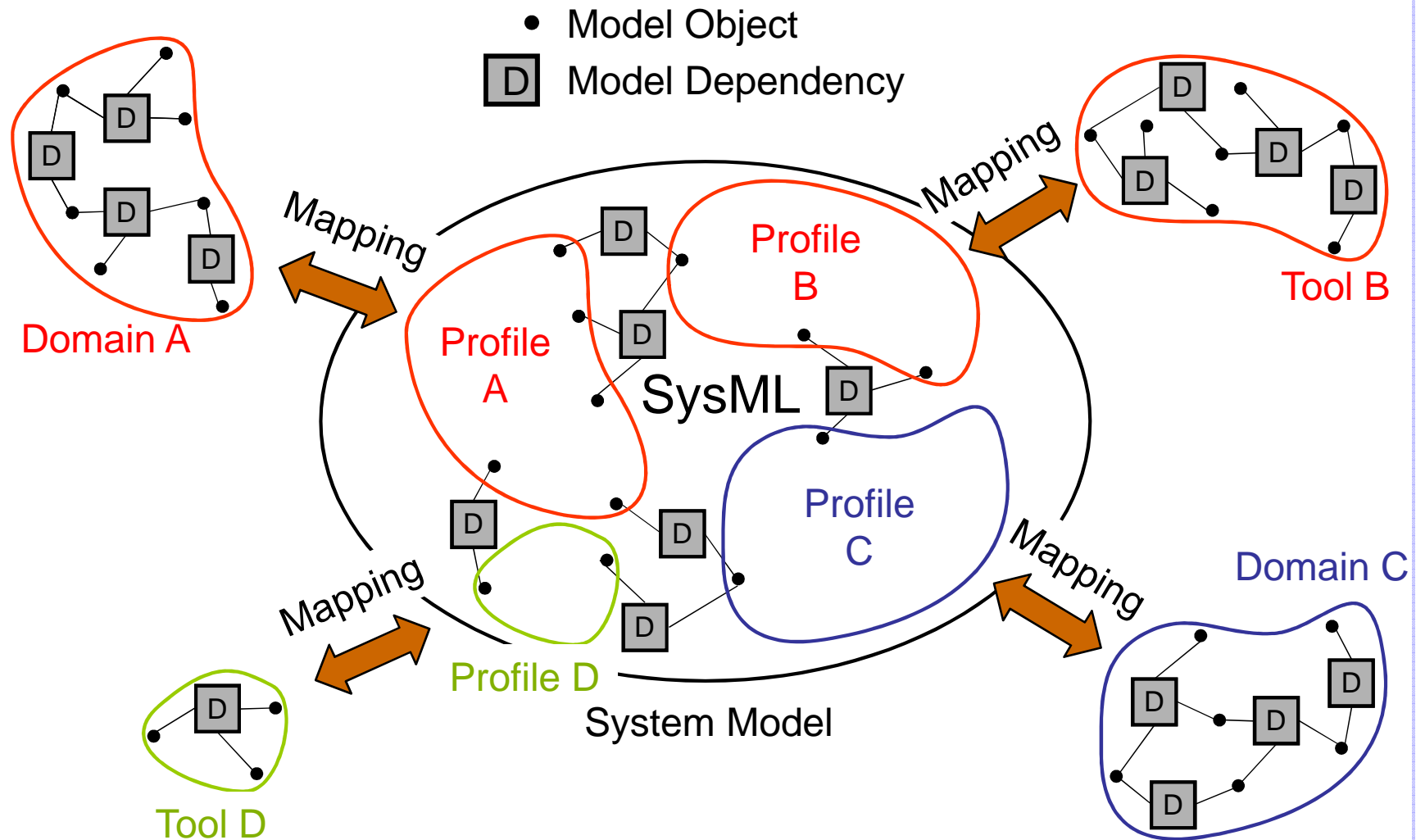
- Model Object

 Model Dependency

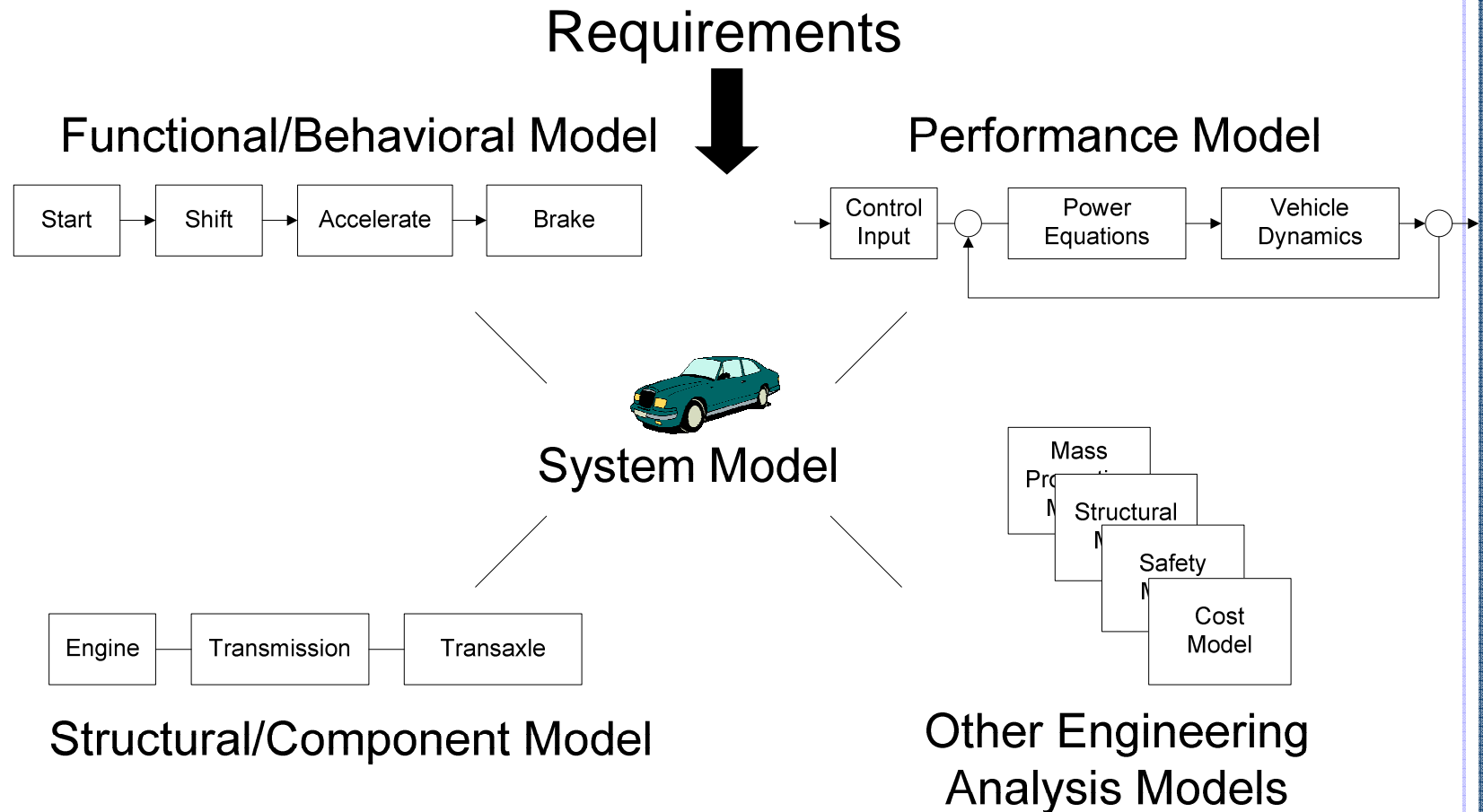


System Model

# Transformations in Systems Modeling



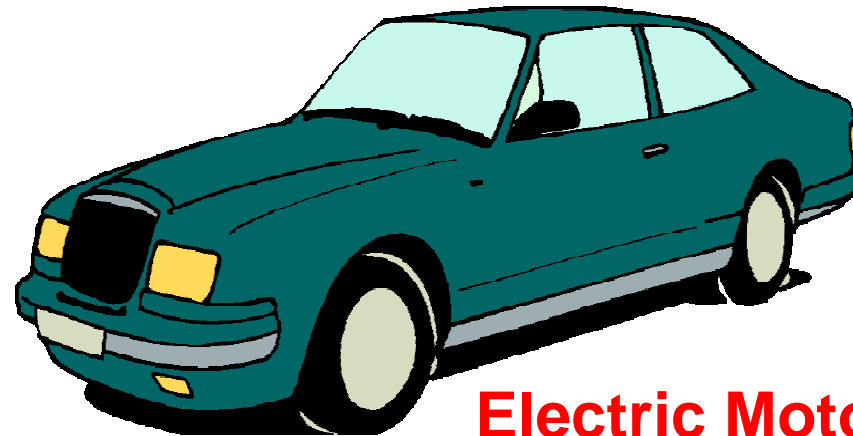
# Model Reuse in MBSE



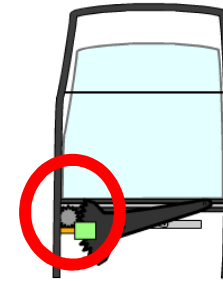
**Creating Models is Expensive and Time-Consuming**

# Reusable Models in MBSE

- Physical components are reused
- Portions of the systems model repeat
- Patterns for instantiating these portions



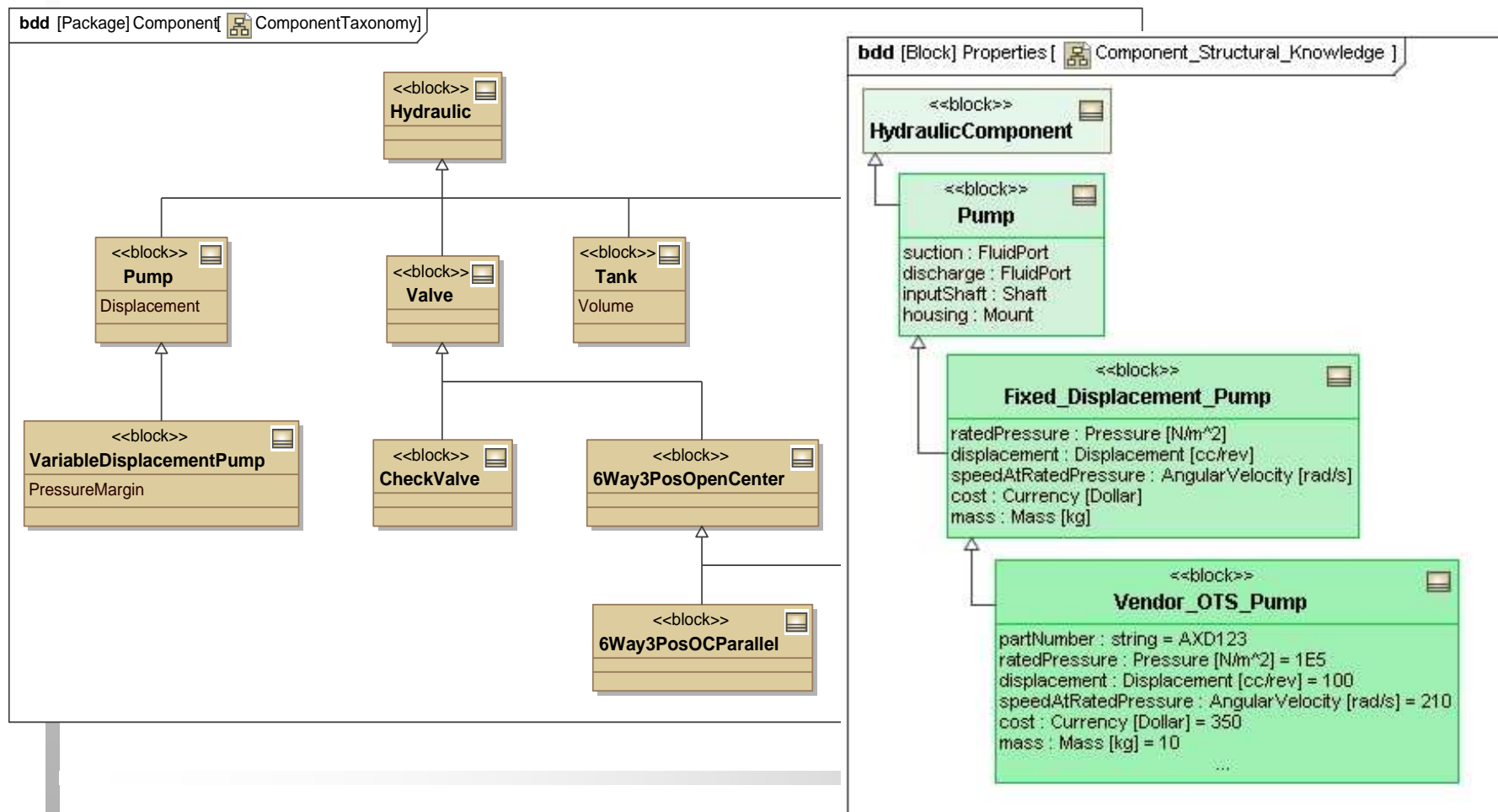
**Electric Motors**



- Component models → Domain specific model libraries
- Application of pattern = model transformations

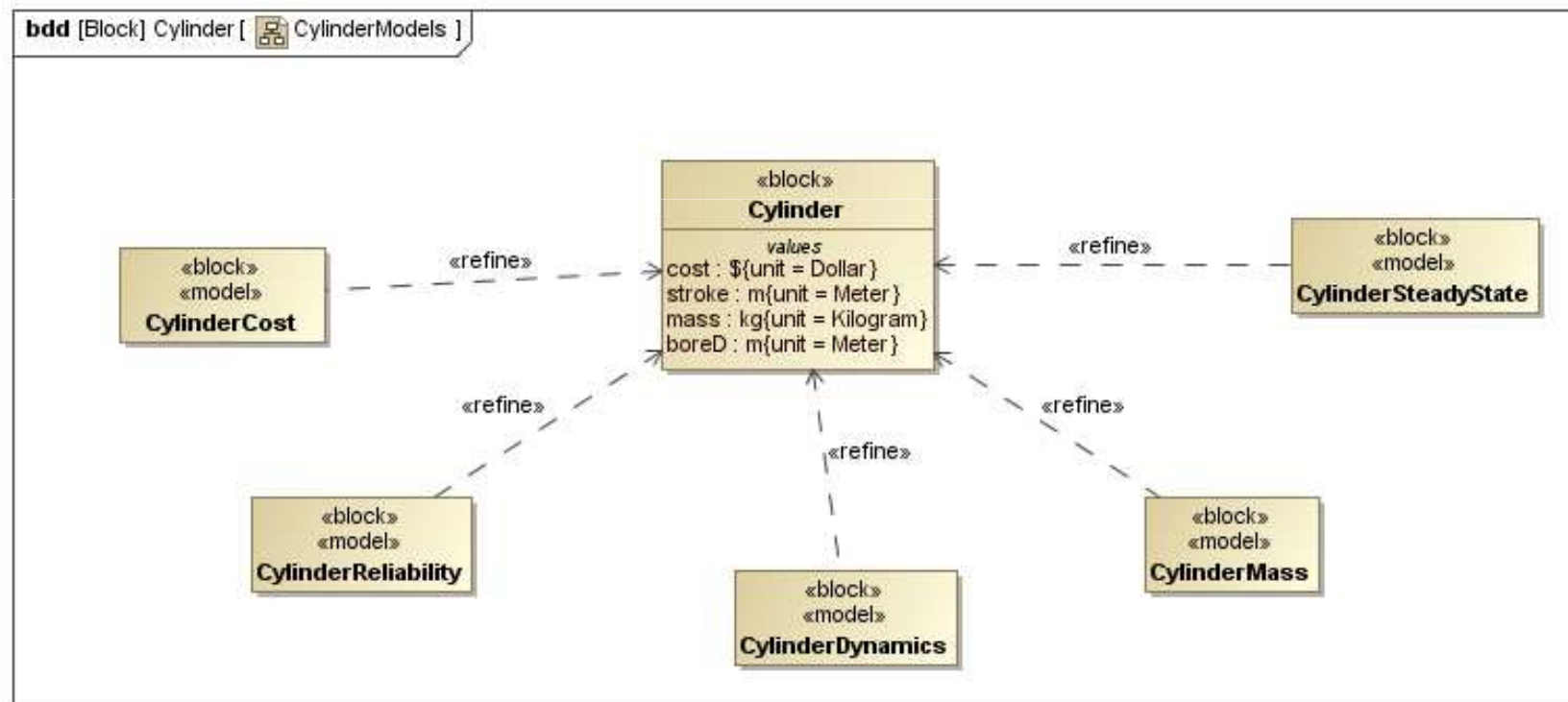
# Model Library of Hydraulic Components

- Needs to be carefully designed and managed
- Encodes domain knowledge



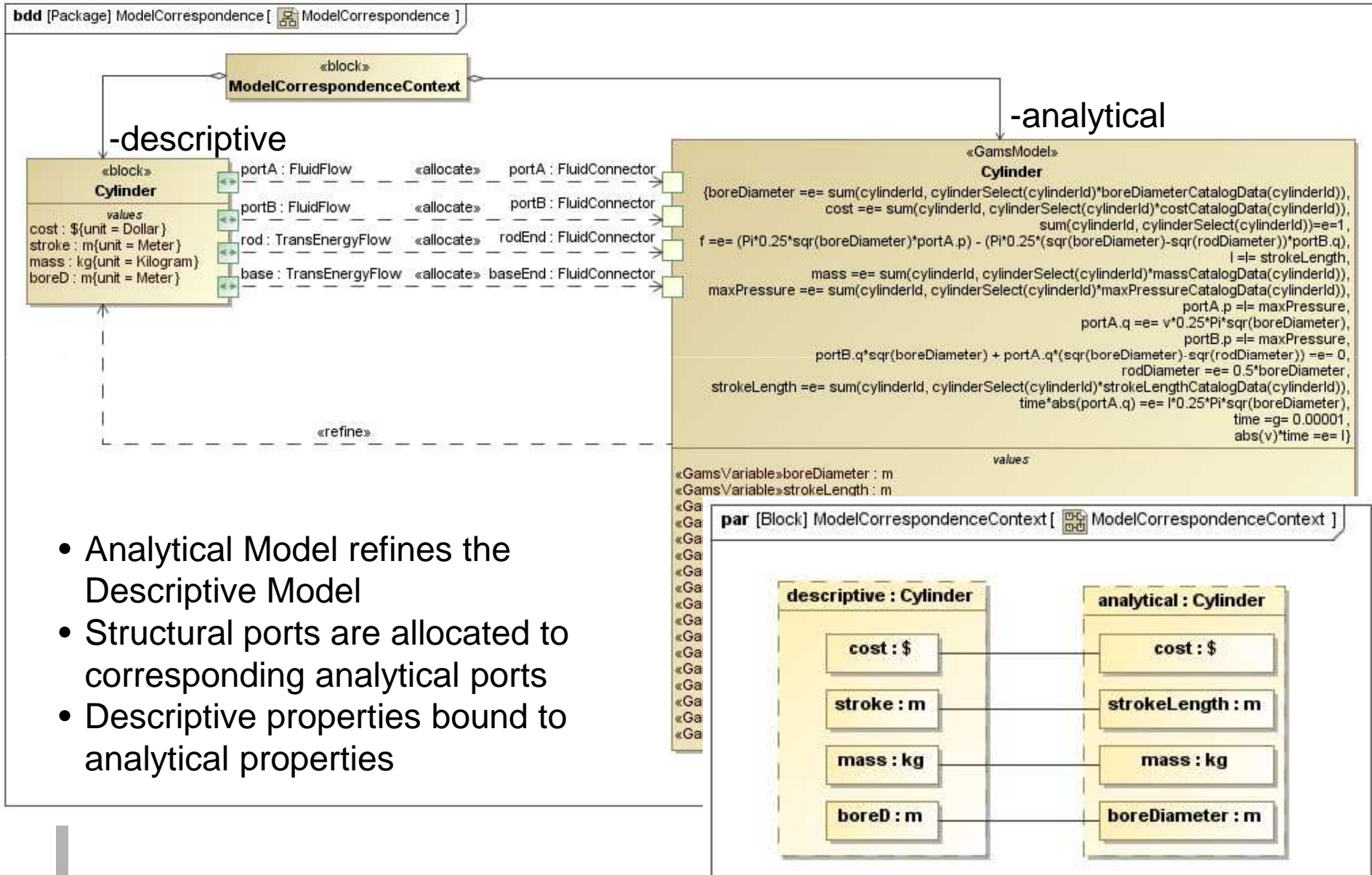
# Other Perspectives of Cylinder are Reusable

- When cylinder is used, other corresponding models are often used also
- Capture the reuse pattern

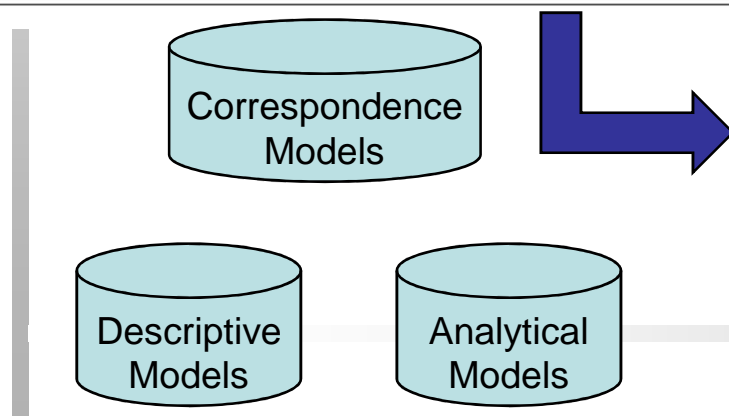
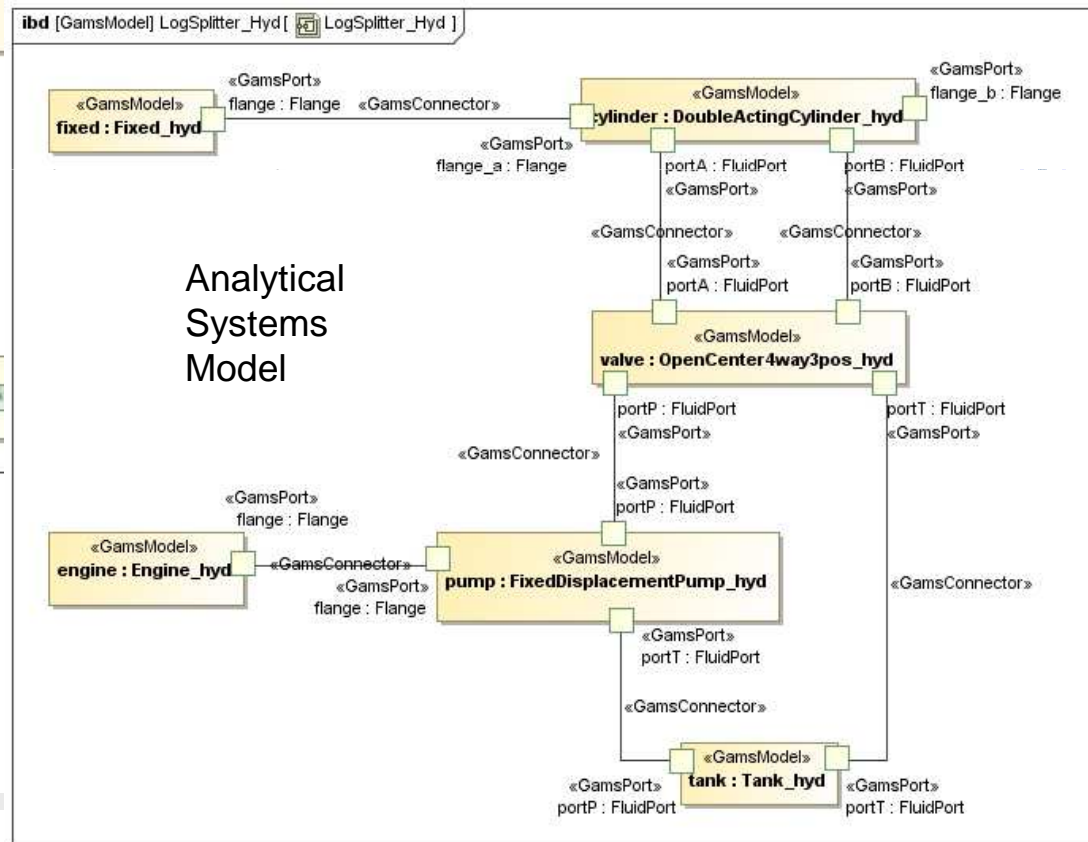
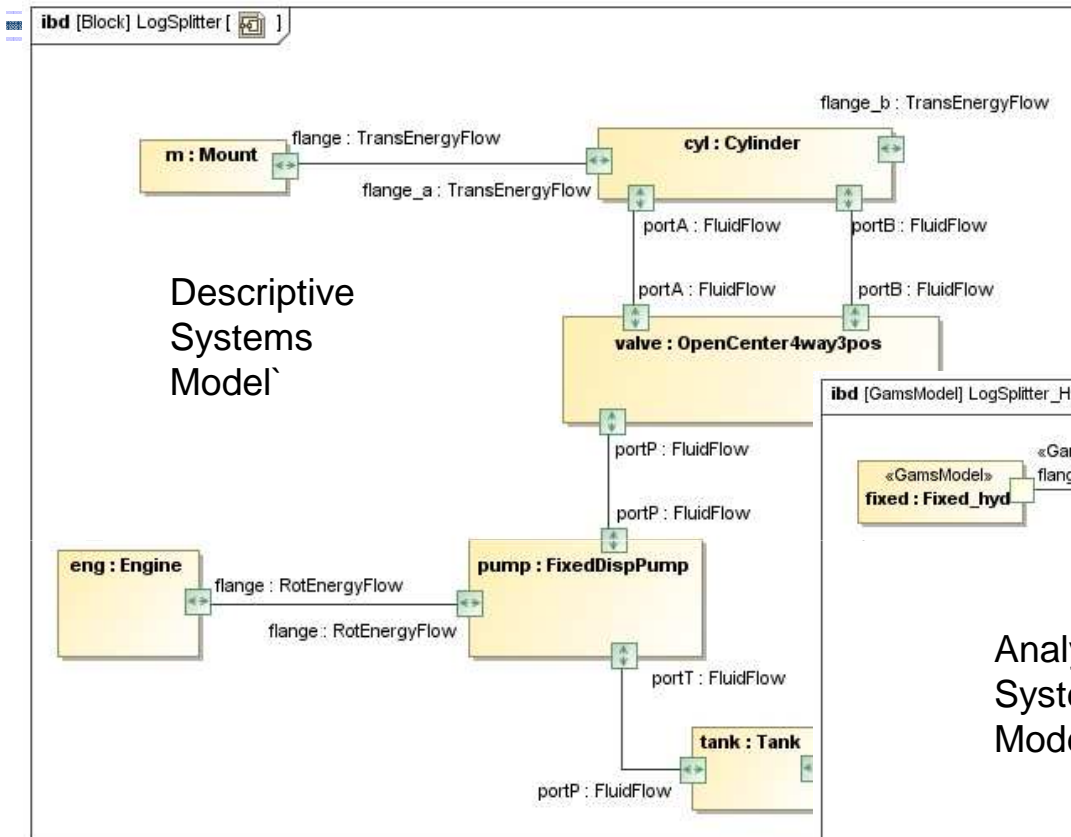




# Correspondence Patterns

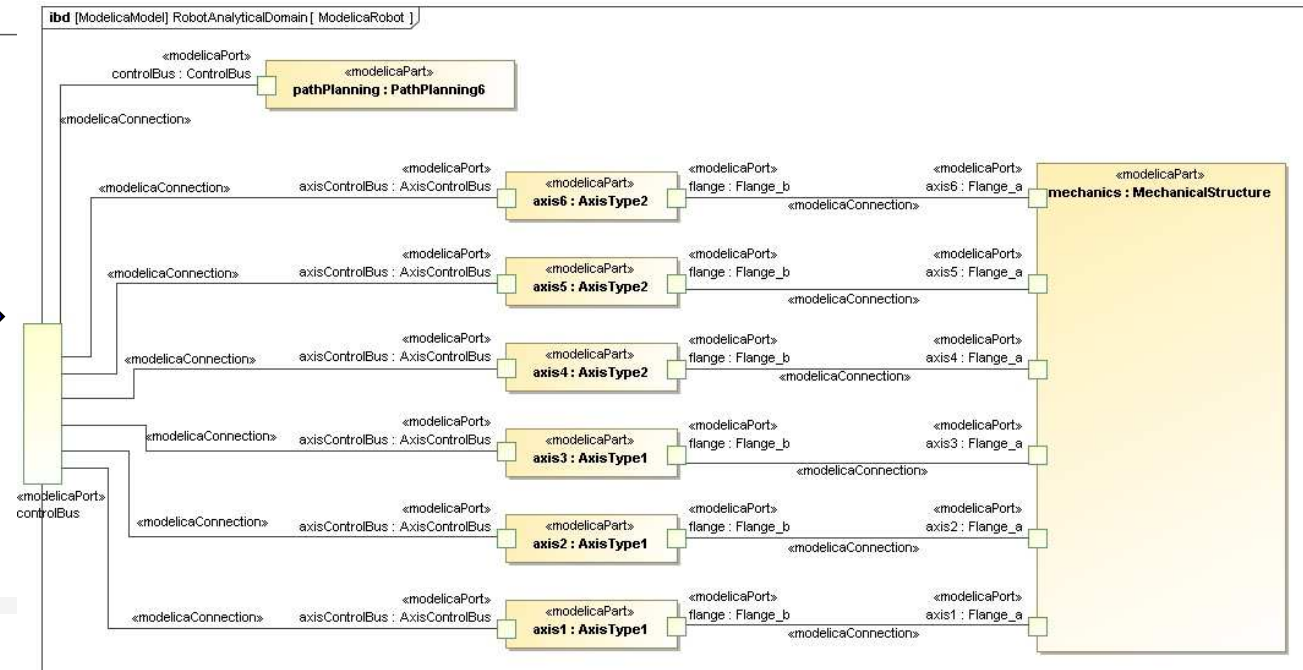
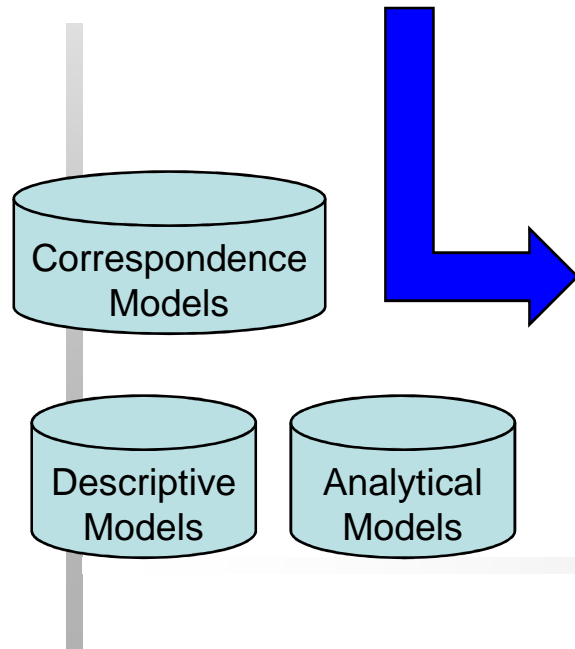
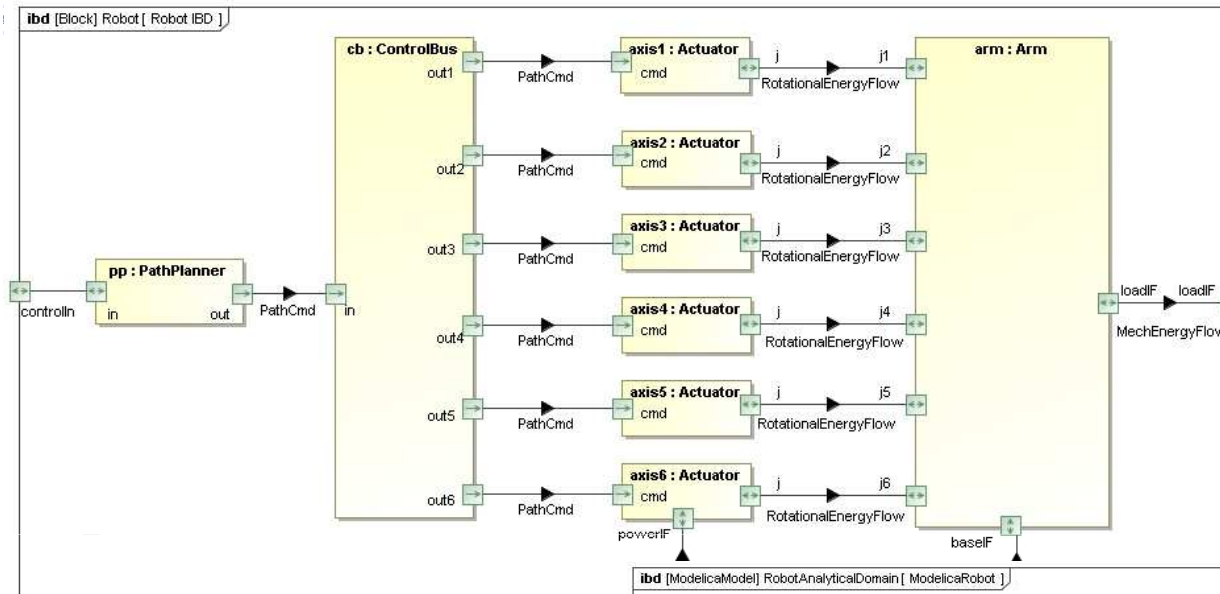


# Model Composition using Model Transformations





# Descriptive to Analytical Transformation



# Summary

➤ Objective:

- Leverage the strengths of both SysML and Modelica by integrating them to create a more expressive and formal MBSE language.

Descriptive Modeling in SysML

+

Formal Equation-Based Modeling for  
Analyses and Trade Studies in Modelica

<http://doc.omg.org/syseng/2010-6-8>

# Acknowledgements

## Working Group Members

- Yves Bernard (EADS)
- Roger Burkhart (Deere & Co)
- Wuzhu Chen (Univ. Braunschweig)
- Hans-Peter De Koning (ESA)
- Sandy Friedenthal (Lockheed Martin)
- Peter Fritzson (Linköping University)
- Nerijus Jankevicius (No Magic)
- Alek Kerzhner (Georgia Tech)
- Andreas Korff (Atego)
- Chris Paredis (Georgia Tech)
- Axel Reichwein (Georgia Tech)
- Nicolas Rouquette (JPL)
- Wladimir Schamai (EADS)

## Students / post-docs

- Kevin Davies
- Sebastian Herzig
- Alek Kerzhner
- Ben Lee
- Roxanne Moore
- Marc Pare
- Axel Reichwein
- Wladimir Schamai

## Sponsors

- Deere & Co
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- National Science Foundation