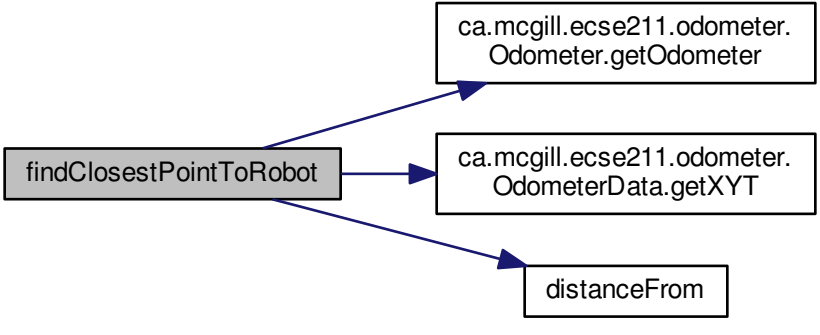
findClosestPointToRobot
ca.mcgill.ecse211.odometer.
Odometer.getOdometer
ca.mcgill.ecse211.odometer.
OdometerData.getXYT
distanceFrom