

ca.mcgill.ecse211.project.  
Navigation.turnTo

```
graph LR; A[ca.mcgill.ecse211.project.Navigation.turnTo] --> B[ca.mcgill.ecse211.sensors.SensorData.getA]; A --> C[ca.mcgill.ecse211.odometer.OdometerData.getXYT];
```

The diagram illustrates a method call. A gray box on the left represents the caller, `ca.mcgill.ecse211.project.Navigation.turnTo`. Two blue arrows originate from its right side. The top arrow points to a white box representing the first callee, `ca.mcgill.ecse211.sensors.SensorData.getA`. The bottom arrow points to another white box representing the second callee, `ca.mcgill.ecse211.odometer.OdometerData.getXYT`.

ca.mcgill.ecse211.sensors.  
SensorData.getA

ca.mcgill.ecse211.odometer.  
OdometerData.getXYT