

```
[a4paper, 11pt]article [margin=3cm]geometry []fontenc [utf8]inputenc [italian]babel geometry a4paper,  
top=2cm, bottom=3cm, left=1.5cm, right=1.5cm, heightrounded, bindingoffset=5mm amsmath amssymb  
gensymb graphicx psfrag,amsmath,amsfonts,verbatim xcolor color,soul fancyhdr indentfirst graphicx newlf  
font amssymb amsmath latexsym amsthm subcaption psfrag footnote graphics color hyperref tikz  
snakes positioning shapes,arrows  
block = [draw, fill=white, rectangle, minimum height=3em, minimum width=6em] sum = [draw,  
fill=white, circle, node distance=1cm] input = [coordinate] output = [coordinate] pinstyle = [pin edge=to-  
,thin,black]  
CAT Linea Guida Report  
.... . . . Nome del Progetto ...  
-1in  
Autore, ...  
document  
-0.5cm  
Il progetto riguarda il controllo di . . . , la cui dinamica viene descritta dalle seguenti equazioni differenziali  
subequationseq:system align . . . ,
```