

```

[a4paper, 11pt]article [margin=3cm]geometry []fontenc [utf8]inputenc [italian]babel geometry a4paper,
top=2cm, bottom=3cm, left=1.5cm, right=1.5cm, heightrounded, bindingoffset=5mm amsmath amssymb
gensymb graphicx psfrag,amsmath,amsfonts,verbatim xcolor color,soul fancyhdr indentfirst graphicx newl-
font amssymb amsmath latexsym amsthm subcaption psfrag footnote graphics color hyperref tikz
snakes positioning shapes,arrows
block = [draw, fill=white, rectangle, minimum height=3em, minimum width=6em] sum = [draw,
fill=white, circle, node distance=1cm] input = [coordinate] output = [coordinate] pinstyle = [pin edge=to-
,thin,black]
CAT Linea Guida Report
... ... Nome del Progetto ...
-1in
Autore, ...
document
-0.5cm
Il progetto riguarda il controllo di ..., la cui dinamica viene descritta dalle seguenti equazioni differenziali
subequationseq:system align ...,

```