산업인공지능학과

## 조도조절 센서 프로그래밍

지능형 IoT네트워크 2020254003 원형일 ○ LED 밝기 제어(LED.py) - Python

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         Load
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motor.py * ×
     import RPi.GPI0 as GPI0
     import time
    pin = 25
  6 GPIO.setmode(GPIO.BCM)
    GPIO.setup(pin, GPIO.OUT)
     pwm=GPIO.PWM(pin, 50)
 10
    pwm.start(10) #0 ~ 100
 11
 12
    time.sleep(1)
 13
     pwm.stop()
    GPIO.cleanup()
```

○ 조도센서(출력값저하, PR.py) - Python

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materialy* III alsoy III
    import spidev, time
    def analog read(channel):
       r = spi.xfer2([1, (0x86+channel)<<6, 0])
        adc_out = ((r[1]60x03) < cl) + r[2]
        return add out
III spi = spidev.SpiDev()
    sp1.apen(0,9)
    spl.wax speed ht = 1000000
while True:
        adc = analog read(1)
        voltage = adc*3.3/1023
        print("ADC = %s(%d) Voltage = %.3fV" % (hex(adc), adc, voltage))
        time_sleep(0.5)
231
ADC = 8x148(328) Voltage = 1.958V
 ADC = 0 \times 140(333)
                   Voltage = 1.674V
 ADC = 0x14s(330) Voltage = 1.065V
 ADC = 8x141(321)
                   Voltage = 1.035V
ASC = 0x134(308)
                   voltage = 0.994V
ADC = 8x12e(382) Voltage = 8.974V
 ADC = 0x12f(303) Voltage = 0.977V
```