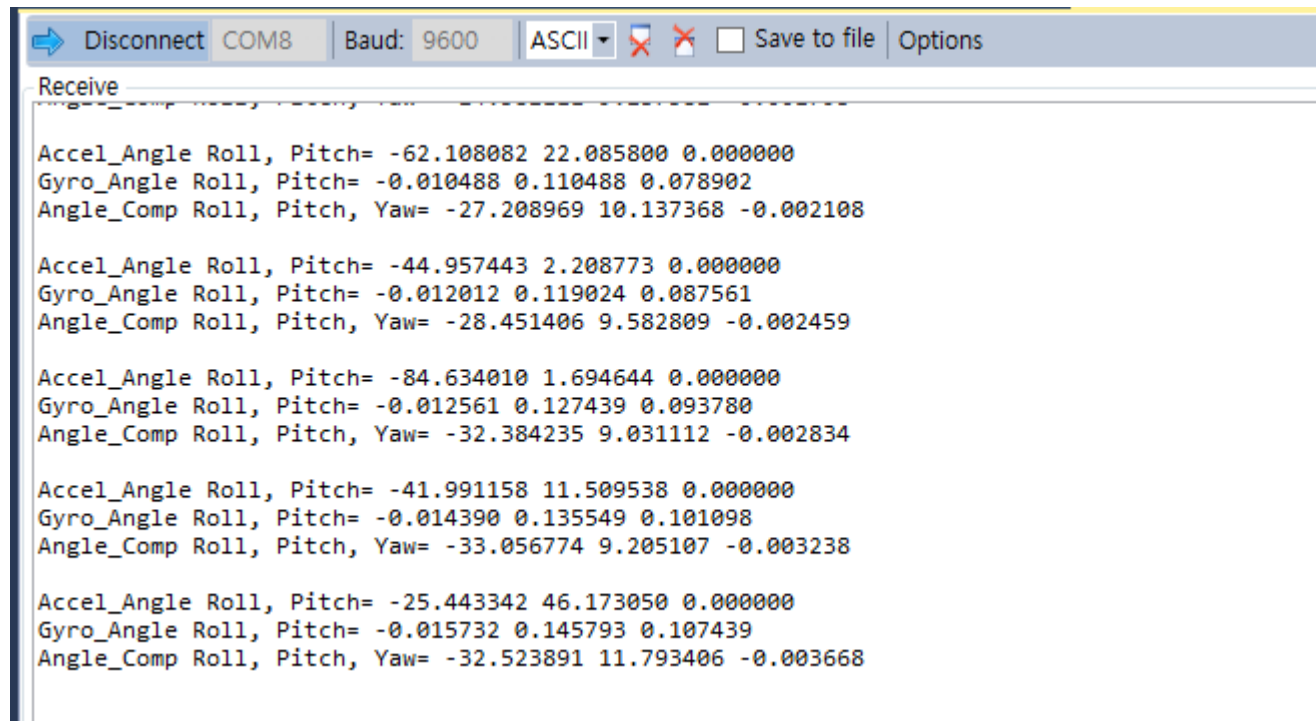


2021/02/03 MPU6050 Test Result



The screenshot shows a serial terminal window with a toolbar at the top containing buttons for 'Disconnect', 'COM8', 'Baud: 9600', 'ASCII', and 'Save to file', along with an 'Options' menu. The main text area displays five sets of sensor data, each consisting of three lines: 'Accel_Angle Roll, Pitch= ...', 'Gyro_Angle Roll, Pitch= ...', and 'Angle_Comp Roll, Pitch, Yaw= ...'. The data values vary across the five sets, representing different orientations or movements of the sensor.

```
Accel_Angle Roll, Pitch= -62.108082 22.085800 0.000000
Gyro_Angle Roll, Pitch= -0.010488 0.110488 0.078902
Angle_Comp Roll, Pitch, Yaw= -27.208969 10.137368 -0.002108

Accel_Angle Roll, Pitch= -44.957443 2.208773 0.000000
Gyro_Angle Roll, Pitch= -0.012012 0.119024 0.087561
Angle_Comp Roll, Pitch, Yaw= -28.451406 9.582809 -0.002459

Accel_Angle Roll, Pitch= -84.634010 1.694644 0.000000
Gyro_Angle Roll, Pitch= -0.012561 0.127439 0.093780
Angle_Comp Roll, Pitch, Yaw= -32.384235 9.031112 -0.002834

Accel_Angle Roll, Pitch= -41.991158 11.509538 0.000000
Gyro_Angle Roll, Pitch= -0.014390 0.135549 0.101098
Angle_Comp Roll, Pitch, Yaw= -33.056774 9.205107 -0.003238

Accel_Angle Roll, Pitch= -25.443342 46.173050 0.000000
Gyro_Angle Roll, Pitch= -0.015732 0.145793 0.107439
Angle_Comp Roll, Pitch, Yaw= -32.523891 11.793406 -0.003668
```