

## Quiz 2: Control Systems Eng. 2019/05/14

Student Number: [       ] Name: **Solution**

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1. (20 points = 2×10 pts )

(1)

- Forward path gain:  $T_1 = G_1G_2$ ,  $T_2 = G_1G_3$

- Loop gain: (1)  $G_1H_1$  (2)  $-G_1G_2H_2$  (3)  $-G_1G_3H_2$

- Nontouching loops taken two at a time: 0

$$\Delta_1 = 1$$

$$\Delta_2 = 1$$

$$\frac{Y}{R} = \frac{T_1\Delta_1 + T_2\Delta_2}{\Delta} = \frac{G_1G_2 + G_1G_3}{1 - G_1H_1 + G_1G_2H_2 + G_1G_3H_2}$$

(2)

$$\begin{aligned} \dot{x}_1 &= -x_1 + x_2 \\ \dot{x}_2 &= -x_1 + 2u \end{aligned} \rightarrow \begin{pmatrix} \dot{x}_1 \\ \dot{x}_2 \end{pmatrix} = \begin{pmatrix} -1 & 1 \\ -1 & 0 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} + \begin{pmatrix} 0 \\ 2 \end{pmatrix} u$$

$$y = 0.5x_1 + 0.5\dot{x}_1 = 0.5x_1 + 0.5(-x_1 + x_2) = 0x_1 + 0.5x_2 \rightarrow y = (0 \quad 0.5) \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

$$\Rightarrow A = \begin{pmatrix} -1 & 1 \\ -1 & 0 \end{pmatrix}, B = \begin{pmatrix} 0 \\ 2 \end{pmatrix}, C = (0 \quad 0.5), D = 0$$

2. (20 points = 2×10 pts )

(1)

$$R = \frac{1}{s}, E = R - Y$$

$$Y = \frac{2}{s+2} \left[ R + (R - Y) \frac{3}{s} \right] = \frac{2}{s+2} \left[ \left( 1 + \frac{3}{s} \right) R - Y \left( \frac{3}{s} \right) \right]$$

$$Y + \frac{6}{s(s+2)} Y = \frac{2}{s+2} \left( 1 + \frac{3}{s} \right) R$$

$$\frac{s(s+2)+6}{s(s+2)} Y = \frac{2(s+3)}{s(s+2)} R$$

$$\frac{Y(s)}{R(s)} = \frac{2(s+3)}{s(s+2)} \cdot \frac{s(s+2)}{s^2+2s+6} = \frac{2(s+3)}{s^2+2s+6}$$

(2)

$$Y(s) = \frac{2(s+3)}{s^2 + 2s + 6} R(s)$$

$$E(s) = R(s) - Y(s) = R(s) - \frac{2(s+3)}{s^2 + 2s + 6} R(s) = R(s) \left[ 1 - \frac{2(s+3)}{s^2 + 2s + 6} \right]$$

$$= R(s) \left( \frac{s^2 + 2s + 6 - 2s - 6}{s^2 + 2s + 6} \right) = R(s) \left( \frac{s^2}{s^2 + 2s + 6} \right)$$

$$e_{ss} = \lim_{s \rightarrow 0} sE(s) = \lim_{s \rightarrow 0} s \frac{1}{s} \left( \frac{s^2}{s^2 + 2s + 6} \right) = \lim_{s \rightarrow 0} \left( \frac{s^2}{s^2 + 2s + 6} \right) = 0$$

3. (20 points)

$$T(s) = \frac{Y(s)}{R(s)} = \frac{G(s)}{1 + G(s)} = \frac{\frac{K}{s(s^2 + s + 1)(s + 4)}}{1 + \frac{K}{s(s^2 + s + 1)(s + 4)}} = \frac{K}{s(s^2 + s + 1)(s + 4) + K}$$

The characteristic equation is:

$$Q(s) = s(s^2 + s + 1)(s + 4) + K = s^4 + 5s^3 + 5s^2 + 4s + K$$

$s^4$	1	5	K	$b_1 = -\frac{1}{5} \begin{vmatrix} 1 & 5 \\ 5 & 4 \end{vmatrix} = \frac{21}{5}, \quad b_2 = -\frac{1}{5} \begin{vmatrix} 1 & K \\ 5 & 0 \end{vmatrix} = K$
$s^3$	5	4	0	
$s^2$	$\frac{21}{5}$	K		
$s^1$	$\frac{5}{21} \left( \frac{84}{5} - 5K \right)$			
$s^0$	K			

Stable condition:  $\frac{5}{21} \left( \frac{84}{5} - 5K \right) > 0$  and  $K > 0$

$$5K < \frac{84}{5} \rightarrow K < \frac{84}{25} \text{ and } K > 0$$

$$\therefore 0 < K < \frac{84}{25}$$

4. (20 points)

$$1 + G(s) = 1 + \frac{K(1+s)}{s(1+Ts)(1+2s)} = 0, \quad s(1+Ts)(1+2s) + Ks + K = 0, \quad 2Ts^3 + (2+T)s^2 + (K+1)s + K = 0$$

$$\begin{array}{ccc} s^3 & 2T & K+1 \\ s^2 & (2+T) & K \\ s^1 & \frac{(K+1)(2+T)-2KT}{(2+T)} & 0 \\ s^0 & K & \end{array}$$

$$\begin{array}{l} b_1 = -\frac{1}{(2+T)} \begin{vmatrix} 2T & K+1 \\ (2+T) & K \end{vmatrix} = \frac{(K+1)(2+T)-2KT}{(2+T)} \\ b_2 = -\frac{1}{(2+T)} \begin{vmatrix} 2T & 0 \\ (2+T) & 0 \end{vmatrix} = 0 \\ c_1 = -\frac{1}{b_1} \begin{vmatrix} (2+T) & K \\ b_1 & 0 \end{vmatrix} = \frac{1}{b_1} (Kb_1) = K, \quad c_2 = 0 \end{array}$$

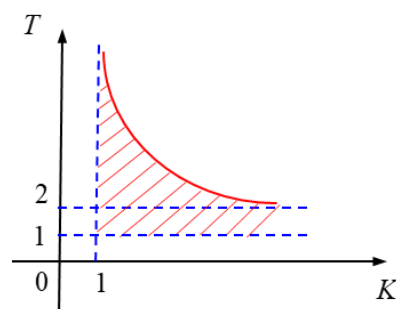
$$2T > 0, \quad (2+T) > 0 \rightarrow \text{From conditions: } T > 1, K > 1$$

$$\frac{(K+1)(2+T)-2KT}{(2+T)} > 0$$

$$2K + 2 + T - KT > 0, \quad 2(K+1) - T(K-1) > 0$$

$$T(K-1) < 2(K+1)$$

$$T < \frac{2(K+1)}{(K-1)} = 2 + \frac{4}{(K-1)} \rightarrow T > 1, K > 1$$



5. (20 points)

(i) Find  $E(s)$

$$Y = G(R - HY) = GR - GHY \rightarrow Y(1 + GH) = GR \rightarrow Y = \frac{G}{1 + GH} R$$

$$E = R - \frac{HG}{1 + GH} R = \frac{R(1 + GH) - HGR}{1 + GH} = \frac{R}{1 + GH} \quad \text{with } R(s) = \frac{1}{s}$$

$$E(s) = \left(\frac{1}{s}\right) \cdot \frac{1}{1 + GH} = \left(\frac{1}{s}\right) \cdot \frac{1}{1 + \left(\frac{s+1}{s^2+5s+\alpha}\right)\left(\frac{1}{s+4}\right)} = \left(\frac{1}{s}\right) \cdot \frac{(s^2+5s+\alpha)(s+4)}{(s^2+5s+\alpha)(s+4) + (s+1)}$$

(ii) The steady-state error:

$$\lim_{t \rightarrow \infty} e(t) = \lim_{s \rightarrow 0} sE(s)$$

$$= \lim_{s \rightarrow 0} \frac{(s^2+5s+\alpha)(s+4)}{(s^2+5s+\alpha)(s+4) + (s+1)}$$

$$= \frac{(\alpha)(4)}{(\alpha)(4) + (1)} = \frac{4\alpha}{4\alpha + 1} = 0$$

$$\therefore \alpha = 0$$

OR

$$\lim_{t \rightarrow \infty} e(t) = \lim_{s \rightarrow 0} sE(s)$$

$$= \lim_{s \rightarrow 0} \frac{1}{1 + \left(\frac{s+1}{s^2+5s+\alpha}\right)\left(\frac{1}{s+4}\right)} = \frac{1}{1 + \left(\frac{1}{\alpha}\right)\left(\frac{1}{4}\right)}$$

$$= \frac{4\alpha}{4\alpha + 1} = 0$$

$$\therefore \alpha = 0$$