



Chap. 8 자기력, 자성체, 인덕턴스

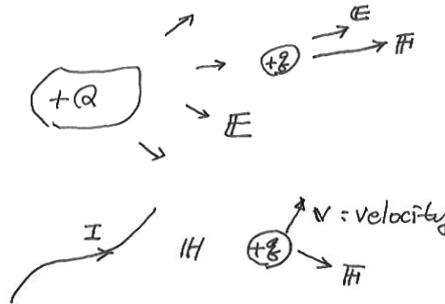
8.1 운동하는 전하에 작용하는 힘

- (전계) \vec{E} Field 내의 Force :

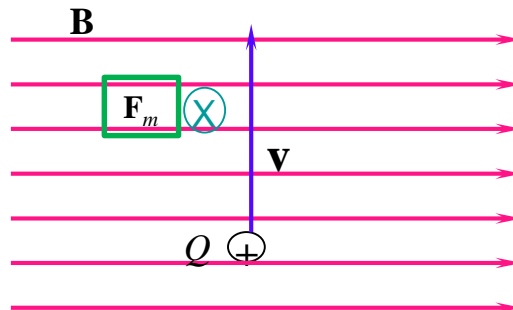
$$\vec{F} = q\vec{E}$$

- (자계) \vec{H} Field 내의 Force :

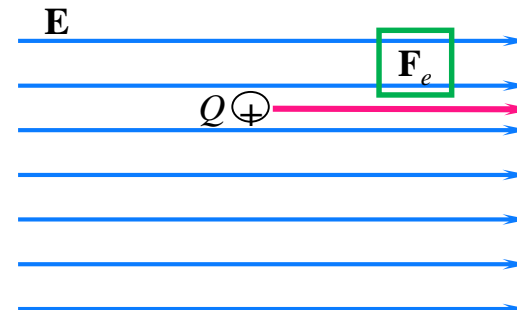
$$\vec{F} = q\vec{v} \times \vec{B}$$



- (i) $\vec{v} = 0 : \vec{F} = 0$
- (ii) $|\vec{F}| = QvB \sin \theta, |\vec{F}| \propto |\vec{v}|$
- (iii) 힘의 방향 ?



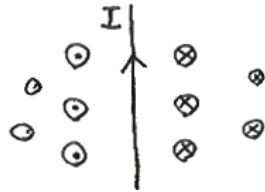
$$\mathbf{F}_m = Q (\mathbf{v} \times \mathbf{B})$$



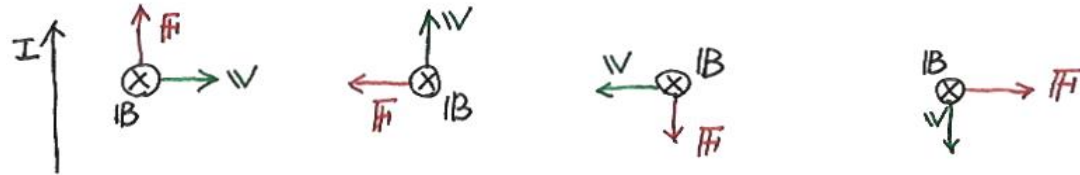
$$\mathbf{F}_e = QE$$

(Ex) :

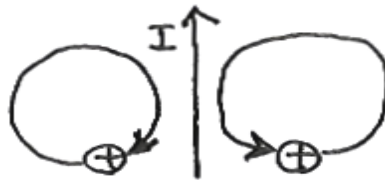
Field :



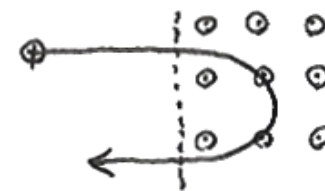
Force :



Motion :

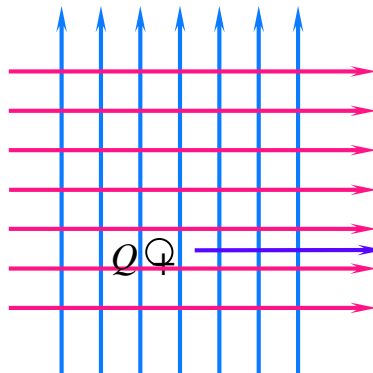


<Magnetic Mirror>



➤ Lorentz force :

B



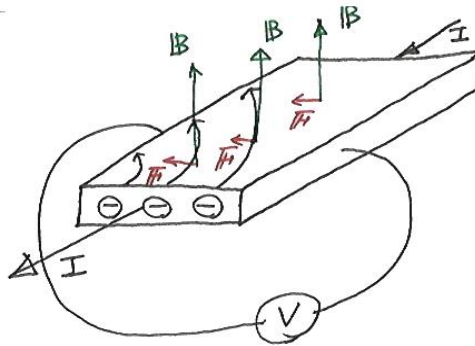
$\vec{E} \text{ \& } \vec{B}$

$$\vec{F} = q(\vec{E} + \vec{v} \times \vec{B})$$

→ Magnetron, Cyclotron, CRT Brown Tube 내의 전자의 운동경로

MHD 발전기, Plasma,

• Hall Effect와 자계의 측정 :

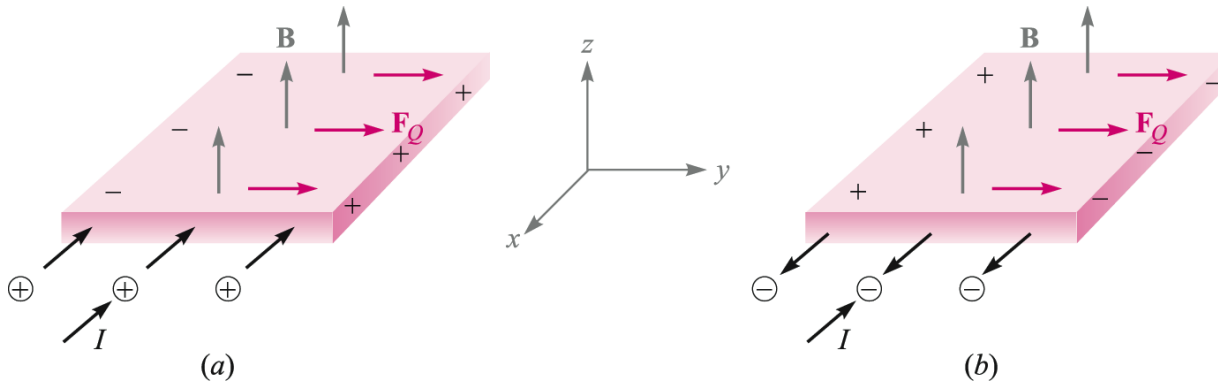


$$d\vec{F} = dQ\vec{v} \times \vec{B} = \rho d\vec{v} \times \vec{B} = \rho \vec{v} \times \vec{B} dv = \vec{J} \times \vec{B} dv$$

$$\therefore \boxed{\vec{F} = \vec{J} \times \vec{B}}$$

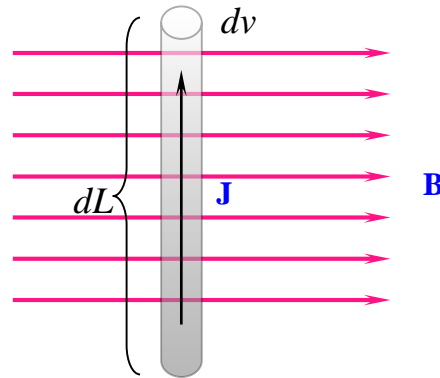
Hall Element : InSb
Hall Probe
Gauss Meter

$$\therefore \begin{cases} \vec{J} = \rho \vec{v} & : \text{대류전류밀도} \\ dQ = \rho dv & : \text{체적전하밀도} \\ dv & : \text{미소체적소} \end{cases}$$



8.2 미소전류에 작용하는 힘

$$\boxed{\vec{F} = q\vec{v} \times \vec{B}} \quad \begin{array}{l} Q \rightarrow dQ \\ F \rightarrow dF \end{array} \quad dF = dQ\vec{v} \times \vec{B}$$



$$d\mathbf{F} = dQ \mathbf{v} \times \mathbf{B} \quad dQ = \rho_v dv$$

$$d\mathbf{F} = \rho_v dv \mathbf{v} \times \mathbf{B} \quad \boxed{\mathbf{J} = \rho_v \mathbf{v}}$$

$$\boxed{d\mathbf{F} = \mathbf{J} \times \mathbf{B} dv}$$

• Current & Force :

$$\boxed{d\mathbf{F} = \mathbf{J} \times \mathbf{B} dv} \quad \text{volume current density (3-D)}$$

$$\boxed{d\mathbf{F} = \mathbf{K} \times \mathbf{B} dS} \quad \text{surface current density (2-D)}$$

$$\boxed{d\mathbf{F} = I d\mathbf{L} \times \mathbf{B}} \quad \text{filament current of length } dL \text{ (1-D)}$$

$$\mathbf{F} = \int_{\text{vol}} \mathbf{J} \times \mathbf{B} dv$$

$$\mathbf{F} = \int_S \mathbf{K} \times \mathbf{B} dS$$

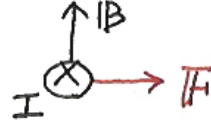
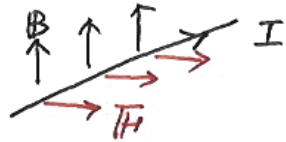
$$\boxed{\mathbf{F} = I\mathbf{L} \times \mathbf{B}}$$

$$\vec{J}dv = \vec{K}d\vec{S} = I d\vec{L}$$

$$d\vec{F} = \vec{J} \times \vec{B} dv (3D) = \vec{K} \times \vec{B} d\vec{S} (2D) = I d\vec{L} \times \vec{B} (1D)$$

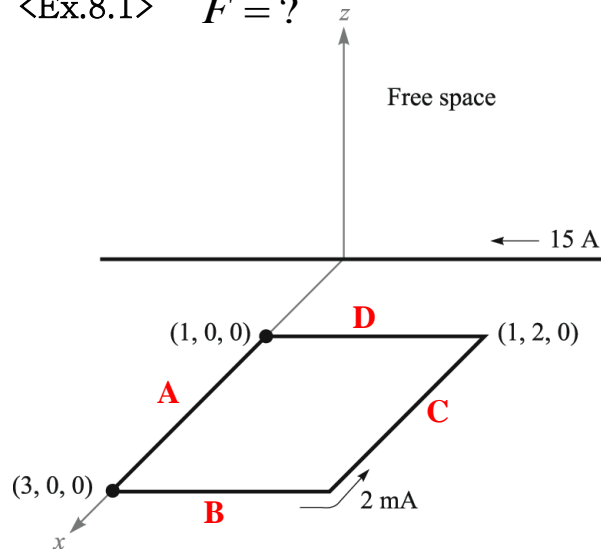
$$\rightarrow \vec{F} = \int_v \vec{J} \times \vec{B} dv = \int_S \vec{K} \times \vec{B} d\vec{S} = \oint I d\vec{L} \times \vec{B} = -I \oint \vec{B} \times d\vec{L}$$

➤ IF : B가 균일하고 I가 직선전류일 경우



$$\vec{F} = I\vec{L} \times \vec{B} = BIL \sin \theta$$

<Ex.8.1> $\vec{F} = ?$



segment 별 force
A, C → Zero
D > B

$$\mathbf{H} = \frac{I}{2\pi x} \mathbf{a}_z = \frac{15}{2\pi x} \text{ A/m}$$

$$\mathbf{B} = \mu_0 \mathbf{H} = 4\pi \times 10^{-7} \mathbf{H} = \frac{3 \times 10^{-6}}{x} \mathbf{a}_z \text{ T}$$

$$\mathbf{F} = -I \oint \mathbf{B} \times d\mathbf{L}$$

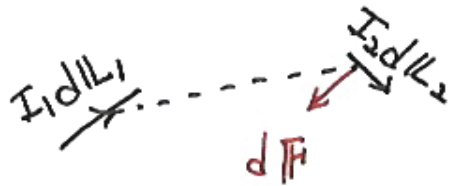
$$\mathbf{F} = -2 \times 10^{-3} \times 3 \times 10^{-6} \left[\underbrace{\int_{x=1}^3 \frac{\mathbf{a}_z}{x} \times dx \mathbf{a}_x}_{\mathbf{A}} + \underbrace{\int_{y=0}^2 \frac{\mathbf{a}_z}{3} \times dy \mathbf{a}_y}_{\mathbf{B}} + \underbrace{\int_{x=3}^1 \frac{\mathbf{a}_z}{x} \times dx \mathbf{a}_x}_{\mathbf{C}} + \underbrace{\int_{y=2}^0 \frac{\mathbf{a}_z}{1} \times dy \mathbf{a}_y}_{\mathbf{D}} \right]$$

$$= -6 \times 10^{-9} \left[\ln x \Big|_1^3 \mathbf{a}_y + \frac{1}{3} y \Big|_0^2 (-\mathbf{a}_x) + \ln x \Big|_3^1 \mathbf{a}_y + y \Big|_2^0 (-\mathbf{a}_x) \right]$$

$$= -6 \times 10^{-9} \left[(\ln 3) \mathbf{a}_y - \frac{2}{3} \mathbf{a}_x + \left(\ln \frac{1}{3} \right) \mathbf{a}_y + 2 \mathbf{a}_x \right]$$

$$= \underline{-8 \mathbf{a}_x \text{ nN}}$$

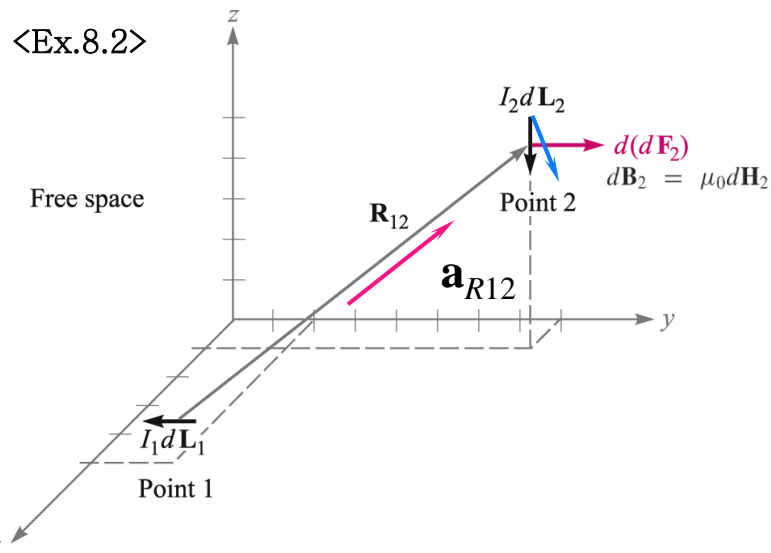
8.3 미소전류소 사이에 작용하는 힘



$$d\mathbf{H}_2 = \frac{I_1 d\mathbf{L}_1 \times \mathbf{a}_{R12}}{4\pi R_{12}^2} \quad d\mathbf{B}_2 = \mu_0 d\mathbf{H}_2$$

$$d(d\mathbf{F}_2) = I_2 d\mathbf{L}_2 \times d\mathbf{B}_2$$

$$d(d\mathbf{F}_2) = \mu_0 \frac{I_1 I_2}{4\pi R_{12}^2} d\mathbf{L}_2 \times (d\mathbf{L}_1 \times \mathbf{a}_{R12})$$



Given: $I_1 d\mathbf{L}_1 = -3\mathbf{a}_y \text{ A} \cdot \text{m}$ at $P_1(5, 2, 1)$

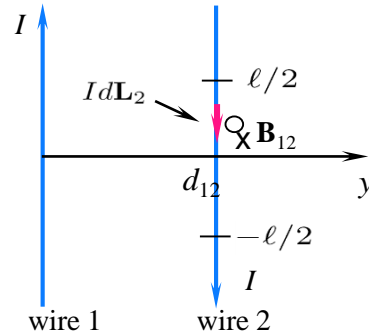
$I_2 d\mathbf{L}_2 = -4\mathbf{a}_z \text{ A} \cdot \text{m}$ at $P_2(1, 8, 5)$

Then $\mathbf{R}_{12} = -4\mathbf{a}_x + 6\mathbf{a}_y + 4\mathbf{a}_z$

$$\begin{aligned} d(d\mathbf{F}_2) &= \frac{4\pi 10^{-7}}{4\pi} \frac{(-4\mathbf{a}_z) \times [(-3\mathbf{a}_y) \times (-4\mathbf{a}_x + 6\mathbf{a}_y + 4\mathbf{a}_z)]}{(16 + 36 + 16)^{1.5}} \\ &= 8.56\mathbf{a}_y \text{ nN} \end{aligned}$$

➤ Force between two line current

- Easy Way : z



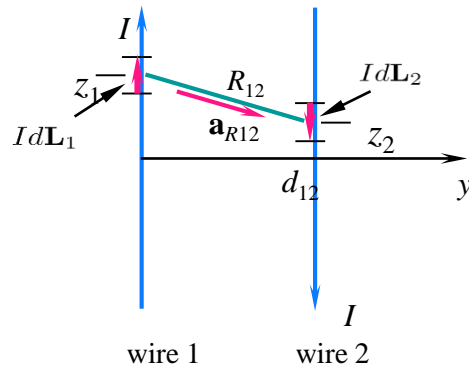
$$\mathbf{B}_{12} = -\frac{\mu_0 I}{2\pi d_{12}} \mathbf{a}_x \quad Id\mathbf{L}_2 = -I dz_2 \mathbf{a}_z$$

$$\mathbf{B}_{12} = -\frac{\mu_0 I}{2\pi d_{12}} \mathbf{a}_x \quad Id\mathbf{L}_2 = -I dz_2 \mathbf{a}_z$$

$$d\mathbf{F}_2 = Id\mathbf{L}_2 \times \mathbf{B}_{12} = -I dz_2 \mathbf{a}_z \times \left(-\frac{\mu_0 I}{2\pi d_{12}} \mathbf{a}_x \right) = \frac{\mu_0 I^2 dz_2}{2\pi d_{12}} \mathbf{a}_y$$

$$\mathbf{F}_2 = \int_{-\ell/2}^{\ell/2} Id\mathbf{L}_2 \times \mathbf{B}_{12} = \boxed{\frac{\mu_0 I^2 \ell}{2\pi d_{12}} \mathbf{a}_y}$$

- Hard Way : z



$$Id\mathbf{L}_1 = I dz_1 \mathbf{a}_z \quad Id\mathbf{L}_2 = -I dz_2 \mathbf{a}_z$$

$$R_{12} = \sqrt{(z_2 - z_1)^2 + d_{12}^2} \quad \mathbf{a}_{R12} = \frac{d_{12} \mathbf{a}_y + (z_2 - z_1) \mathbf{a}_z}{\sqrt{(z_2 - z_1)^2 + d_{12}^2}}$$

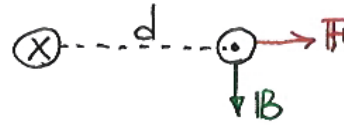
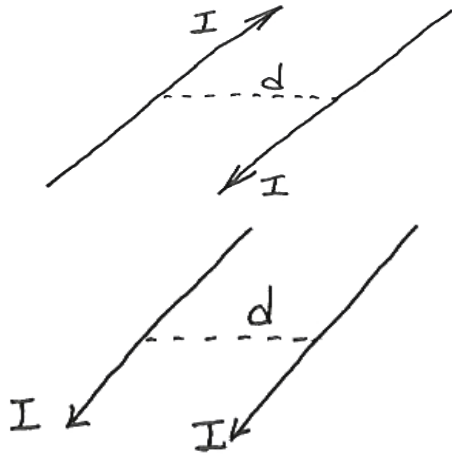
$$\mathbf{F}_2 = \mu_0 \frac{I^2}{4\pi} \int_{-\ell/2}^{\ell/2} \left[\int_{-\infty}^{\infty} \frac{d_{12} \mathbf{a}_y + (z_2 - z_1) \mathbf{a}_z}{[(z_2 - z_1)^2 + d_{12}^2]^{3/2}} \times dz_1 \mathbf{a}_z \right] \times (-dz_2 \mathbf{a}_z)$$

$$\mathbf{F}_2 = \mu_0 \frac{I^2 d_{12}}{4\pi} \mathbf{a}_y \int_{-\ell/2}^{\ell/2} \int_{-\infty}^{\infty} \frac{dz_1 dz_2}{[(z_2 - z_1)^2 + d_{12}^2]^{3/2}}$$

$$\int_{-\infty}^{\infty} \frac{dz_1}{[(z_2 - z_1)^2 + d_{12}^2]^{3/2}} = \frac{z_1 - z_2}{d_{12}^2 [(z_2 - z_1)^2 + d_{12}^2]^{1/2}} \Big|_{z_1=-\infty}^{z_1=\infty} = \frac{2}{d_{12}^2}$$

$$\mathbf{F}_2 = \mu_0 \frac{I^2 d_{12}}{4\pi} \mathbf{a}_y \int_{-\ell/2}^{\ell/2} \frac{2}{d_{12}^2} dz_2 = \boxed{\frac{\mu_0 I^2 \ell}{2\pi d_{12}} \mathbf{a}_y}$$

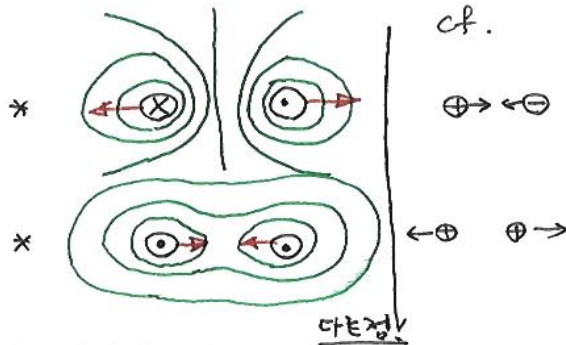
(Ex) 긴 선전류에 작용하는 힘



$$\vec{H} = \frac{I}{2\pi d}$$

$$\vec{B} = \frac{\mu_0 I}{2\pi d}$$

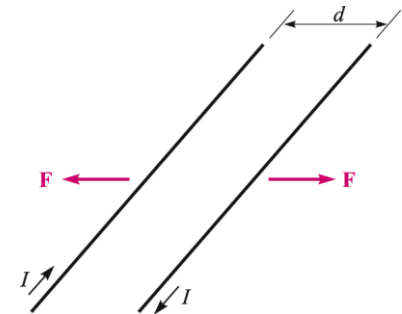
$$\vec{F} = BIL \sin \theta = \frac{\mu_0 I}{2\pi d} \cdot I \cdot L$$



$$d(d\mathbf{F}_2) = \mu_0 \frac{I_1 I_2}{4\pi R_{12}^2} d\mathbf{L}_2 \times (d\mathbf{L}_1 \times \mathbf{a}_{R12})$$

$$\begin{aligned} \mathbf{F}_2 &= \mu_0 \frac{I_1 I_2}{4\pi} \oint [d\mathbf{L}_2 \times \oint \frac{d\mathbf{L}_1 \times \mathbf{a}_{R12}}{R_{12}^2}] \\ &= \mu_0 \frac{I_1 I_2}{4\pi} \oint \left[\oint \frac{\mathbf{a}_{R12} \times d\mathbf{L}_1}{R_{12}^2} \right] \times d\mathbf{L}_2 \end{aligned}$$

$$F = \frac{\mu_0 I_1 I_2}{2\pi d}$$



8.4 폐회로에 작용하는 힘과 회전력

• 균일자기장 내의 힘

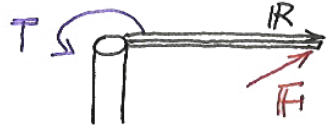


$$\begin{aligned}\vec{F} &= -I \oint \vec{B} \times d\vec{L} = -I \vec{B} \times \oint d\vec{L} \\ &= 0 \quad (\because \nabla \cdot \vec{J} = 0, \int \vec{J} \cdot d\vec{S} = 0), \quad \underline{\underline{\vec{F} = 0}}\end{aligned}$$

→ force는 Zero, 회전력만 작용

✓ Torque, Moment (회전력, 힘의 능률)

$$\vec{T} = \vec{R} \times \vec{F}$$

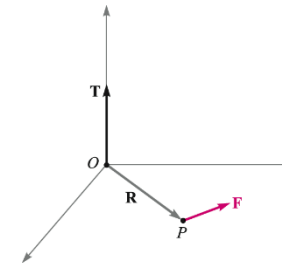


\vec{T} 의 방향은 ? :

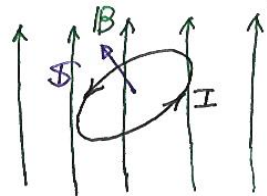


\vec{T} 의 크기는 ? :

$$|\vec{T}| \propto \vec{R}, \vec{F}, \sin \theta$$



• 균일자기장 내의 회전력



\vec{S} 의 크기, 방향 정의

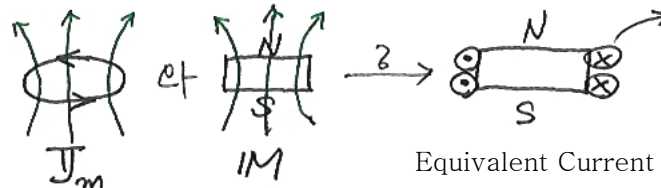
$$d\vec{T} = I d\vec{S} \times \vec{B}$$

$$\vec{T} = I \vec{S} \times \vec{B}$$

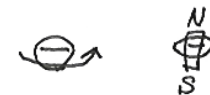
\vec{T} 의 크기 : $\vec{S} \uparrow : \vec{T} \uparrow, \vec{B} \uparrow, \vec{I} \uparrow : \vec{T} \uparrow$

\vec{T} 의 방향 : $\vec{S} \parallel \vec{B} : \vec{T} = 0 \quad \vec{S} \perp \vec{B} : \vec{T} \rightarrow \text{Max} \rightarrow \vec{S} \parallel \vec{B}$ 되도록 작용

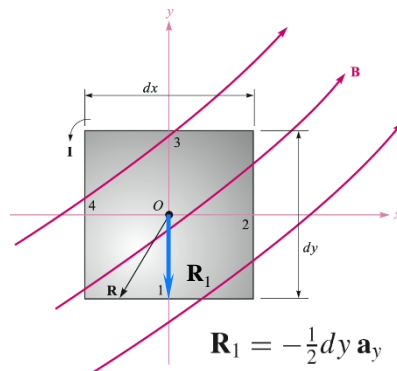
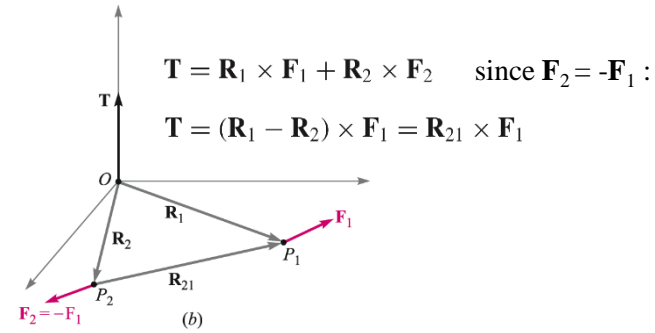
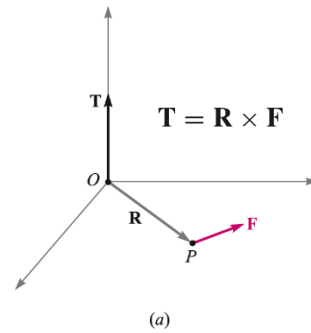
✓ Loop Current & Magnet



$$\text{Equivalent Current : } \vec{J}_m = \nabla \times \vec{M}$$



• Torque in a Loop Current

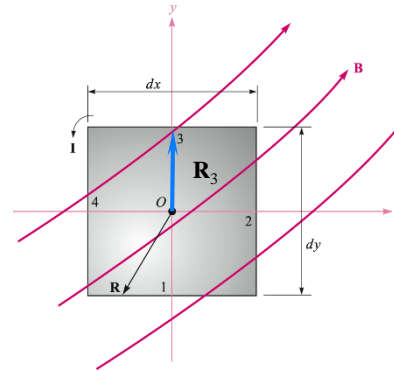


$$d\mathbf{F}_1 = I dx \mathbf{a}_x \times \mathbf{B}_0 = I dx (B_{0y} \mathbf{a}_z - B_{0z} \mathbf{a}_y)$$

$$d\mathbf{T}_1 = \mathbf{R}_1 \times d\mathbf{F}_1$$

$$= -\frac{1}{2} dy \mathbf{a}_y \times I dx (B_{0y} \mathbf{a}_z - B_{0z} \mathbf{a}_y)$$

$$= -\frac{1}{2} dx dy I B_{0y} \mathbf{a}_x$$



$$d\mathbf{T}_3 = \mathbf{R}_3 \times d\mathbf{F}_3 = \frac{1}{2} dy \mathbf{a}_y \times (-I dx \mathbf{a}_x \times \mathbf{B}_0)$$

$$= -\frac{1}{2} dx dy I B_{0y} \mathbf{a}_x = d\mathbf{T}_1 \quad (!)$$

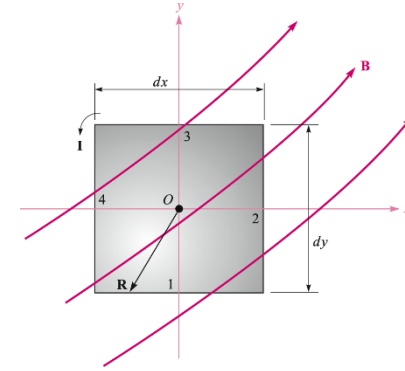
$$d\mathbf{T}_1 + d\mathbf{T}_3 = -dx dy I B_{0y} \mathbf{a}_x$$

$$d\mathbf{T}_2 + d\mathbf{T}_4 = dx dy I B_{0x} \mathbf{a}_y$$

$$d\mathbf{T} = I dx dy (B_{0x} \mathbf{a}_y - B_{0y} \mathbf{a}_x)$$

$$d\mathbf{T} = I dx dy (\mathbf{a}_z \times \mathbf{B}_0) \quad d\mathbf{S} = dx dy \mathbf{a}_z$$

$$d\mathbf{T} = I d\mathbf{S} \times \mathbf{B}$$



$$d\mathbf{T} = I d\mathbf{S} \times \mathbf{B}$$

$$d\mathbf{m} = I d\mathbf{S}$$

$$d\mathbf{T} = d\mathbf{m} \times \mathbf{B}$$

$$\mathbf{T} = I \mathbf{S} \times \mathbf{B} = \mathbf{m} \times \mathbf{B}$$

➤ Dipole Moment (쌍극자 모멘트)

(전계) 전기 쌍극자 모멘트:

$$\vec{P}$$

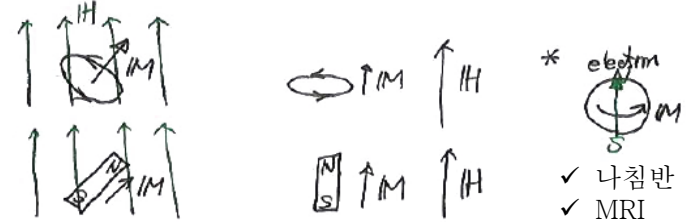
$$d\vec{T} = d\vec{P} \times \vec{E} \quad (* d\vec{P} = dQd\vec{r})$$



(자계) 자기 쌍극자 모멘트:

$$\vec{m}$$

$$d\vec{T} = d\vec{m} \times \vec{B} \quad (* d\vec{m} = Id\vec{S})$$

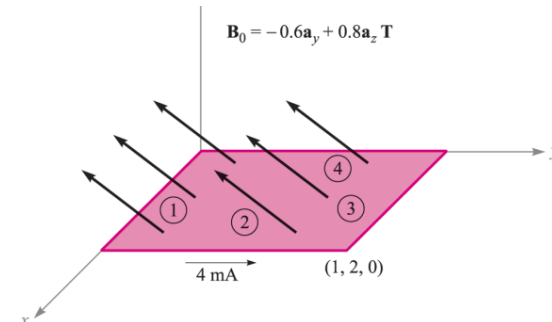


• 균일 자계내에서의 자기 쌍극자 모멘트

$$\vec{T} = I\vec{S} \times \vec{B} = \vec{m} \times \vec{B}$$

< Ex 8.3 > 정방형 Loop Current의 Force, Torque 계산

$$\vec{T} = 4 \times 10^{-3} [(1)(2)\vec{a}_z] \times (-0.6\vec{a}_y + 0.8\vec{a}_z) = 4.8\vec{a}_x \text{ mN} \cdot \text{m}$$



< Ex 8.4 Torque 계산

8.5 자성체의 성질

• 자성체, 매질, 분자, 원자, 전자

• 자성체

반 자성체(Dia Magnetism), Cu

상 자성체(Para Magnetism), Al

강 자성체(Ferro Magnetism), Fe

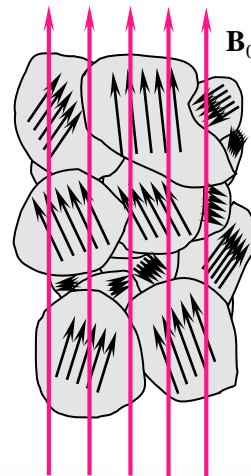
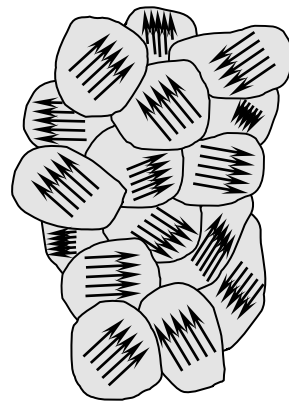
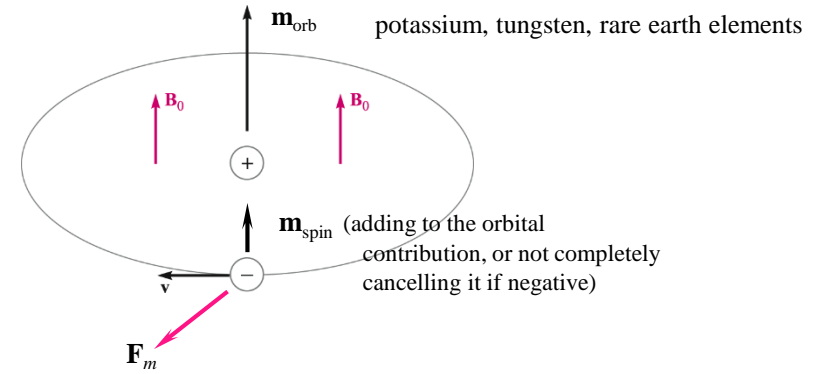
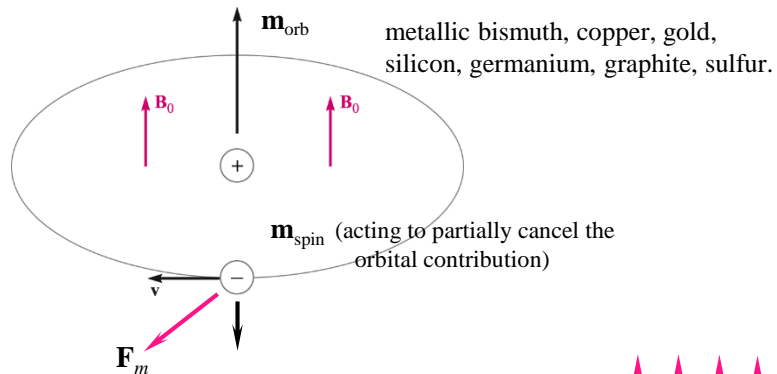
연 자성체(Soft) : Fe

경 자성체(Hard) : 영구자석

역강 자성체(Anti Ferro Magnetism)

페리 자성체(Ferri Ferro Magnetism)

초상 자성체(Super Para Magnetism)

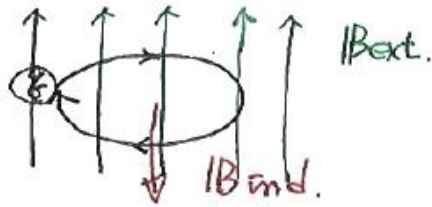


iron, nickel, cobalt
(room temperature),
gadolinium, dysprosium
(low temperature).

※ $\left\langle \begin{array}{l} \text{전자의 공전} \rightarrow \text{반 자성체 성질} \\ \text{전자의 자전} \rightarrow \text{상 자성체 성질} \end{array} \right\rangle$
모든 물질에는 두 가지 다 공존함
어느 것이 큰가에 따라 결정

(1) 반 자성체 (Dia-Magnetic Material)

- 자계 내에서 운동하는 전하 : Lenz Force : $\vec{F} = q\vec{v} \times \vec{B}$



q 의 회전 운동 \rightarrow Current $\rightarrow \vec{B}_{ind}$ 발생
 \vec{B}_{ind} 의 방향 : $-\vec{B}_{ext}$ 방향

$$\vec{B}_{total} = \vec{B}_{ext} + \vec{B}_{ind} < \vec{B}_{ext} \quad \text{즉 매질로 인해 자계가 줄어드는 효과}$$

* 외부자계는 전자의 공전을 방해한다.

* 모든 물체는 전자의 공전운동이 있으므로 반자성적 성질이 있다.

[비스무스 : 0.99999986, 수소, 헬륨, 탄소, 황산]
[구리, 금, 은, 실리콘, 게르마늄]

(2) 상 자성체 (Para-Magnetic Material)

- 전자의 자전 :



하나의 자석



$$\begin{cases} W = -\vec{m} \cdot \vec{B} = -mB \cos \theta \\ \vec{T} = \vec{m} \times \vec{B} = mB \sin \theta \end{cases}$$

$$\begin{cases} \theta = 0^\circ \text{ 때 : } // \rightarrow W \text{ 최소, } \vec{T} = \mathbf{0} \text{ (stable)} \\ \theta = 90^\circ \text{ 때 : } \perp \rightarrow W \text{ 최대, } \vec{T} \text{ 최대} \end{cases}$$

$\rightarrow \theta = 0^\circ$ 로, 즉 외부자계방향으로 정렬

\rightarrow 외부자계를 증대시키는 결과

$$\vec{B}_{total} = \vec{B}_{ext} + \vec{B}_{ind} > \vec{B}_{ext}$$

모멘트 정렬로 인하여 자계가 커진다. $\mu > 1$

원자 내의 전자의 자전운동은 외부자계의 영향으로 정렬되어 자계의 크기를 증가 시킨다.

(3) 강 자성체 (Ferro-Magnetic Material)

- 철은 왜 자석에 달라 붙을 까? Al은? Cu 는? ($\mu_r > 1000$!!!, Why ?)
- 1906년 Pierre Weiss 의 분자장 이론: 가설. Heisenberg 양자역학 → Exchange Energy로 분자장 이론을 설명
 - ① 자발자화(Spontaneous Magnetization). (영구히 자화) ?
 - ② 자구(Magnetic Domain). 존재. (서로반발) ?
- Bitter. 자구 관측. 자구 : Ferrite : 0.8 ~ 1 μm
 Sm-Co : 2 μm
 NdFeB : 0.5 μm
 - ※ 자석의 역사
 전자석/영구자석
 말굽자석/페라이트자석/희토류자석-AlNiCo, Sm-Co, NdFeB
 →(일본 Smitomo, 미국 Quench)
- 강자성체의
 - 자기포화 (Magnetic Saturation)
 - 히스테리시스 (Magnetic Hysteresis)
- 연자성체 (Soft) / 경자성체(Hard)
- Curie 온도 : Fe(769°), Co(1127°), Ni(358°)
 실온에의 강자성체 - Fe, Co, Ni only

(4) 역 반 강 자성체 (Anti Ferro-Magnetic Material) MnO, $\uparrow\downarrow\uparrow\downarrow$

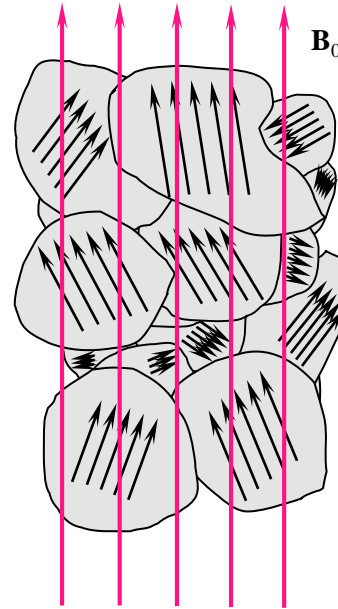
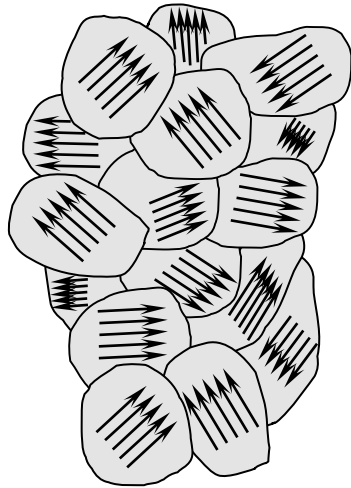
(5) 페라이트 (Ferrite) $\uparrow\downarrow\uparrow\downarrow$ 자철광(Fe_2O_3 , Fe_3O_4), 니켈페라이트, 니켈아연 페라이트

Ceramic Magnet, Ferros spinels = Ferrite, σ 小, μ 大 고주파기기에 사용

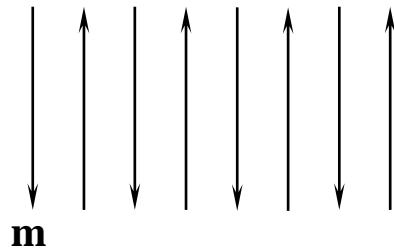
(6) 초상자성체 (Super para-Magnetic Material) 자기테이프



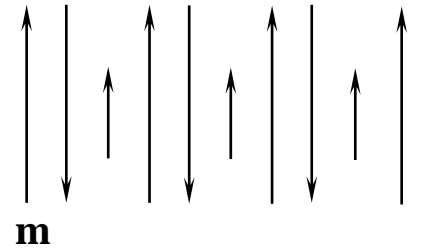
✓ Ferro-Magnetic Material



✓ Anti Ferro-Magnetic Material , MnO



✓ Ferrite , Fe_2O_3 , Fe_3O_4



➤ Magnetic Material Summary

| Classification | Magnetic Moments | B Values | Comments |
|-------------------|---|---|---|
| Diamagnetic | $\mathbf{m}_{\text{orb}} + \mathbf{m}_{\text{spin}} = 0$ | $B_{\text{int}} < B_{\text{appl}}$ | $B_{\text{int}} \doteq B_{\text{appl}}$ |
| Paramagnetic | $\mathbf{m}_{\text{orb}} + \mathbf{m}_{\text{spin}} = \text{small}$ | $B_{\text{int}} > B_{\text{appl}}$ | $B_{\text{int}} \doteq B_{\text{appl}}$ |
| Ferromagnetic | $ \mathbf{m}_{\text{spin}} \gg \mathbf{m}_{\text{orb}} $ | $B_{\text{int}} \gg B_{\text{appl}}$ | Domains |
| Antiferromagnetic | $ \mathbf{m}_{\text{spin}} \gg \mathbf{m}_{\text{orb}} $ | $B_{\text{int}} \doteq B_{\text{appl}}$ | Adjacent moments oppose |
| Ferrimagnetic | $ \mathbf{m}_{\text{spin}} \gg \mathbf{m}_{\text{orb}} $ | $B_{\text{int}} > B_{\text{appl}}$ | Unequal adjacent moments oppose; low σ |
| Superparamagnetic | $ \mathbf{m}_{\text{spin}} \gg \mathbf{m}_{\text{orb}} $ | $B_{\text{int}} > B_{\text{appl}}$ | Nonmagnetic matrix; recording tapes |

8.6 자화 및 투자율

- 자화 \vec{M} (magnetization)

$$\vec{m} = I_b d\vec{S}, \quad \text{속박전류}$$

$$\vec{m}_{\text{total}} = \sum_{i=1}^{n\Delta v} \vec{m}_i$$

자화(또는 자화의 세기) = 단위 체적당 자기쌍극자 모멘트

$$\vec{M} = \lim_{\Delta v \rightarrow 0} \frac{1}{\Delta v} \sum_{i=1}^{n\Delta v} \vec{m}_i$$

$$\vec{M} = n\vec{m} = nI_b d\vec{S}$$

- 속박 전류 밀도: \vec{J}_b

$$I_b = \oint \vec{J}_b \cdot d\vec{S} = \oint \vec{M} \cdot d\vec{L}$$

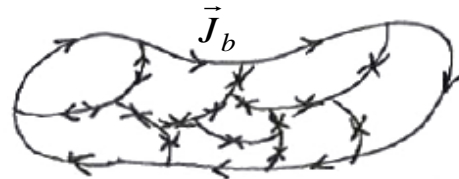
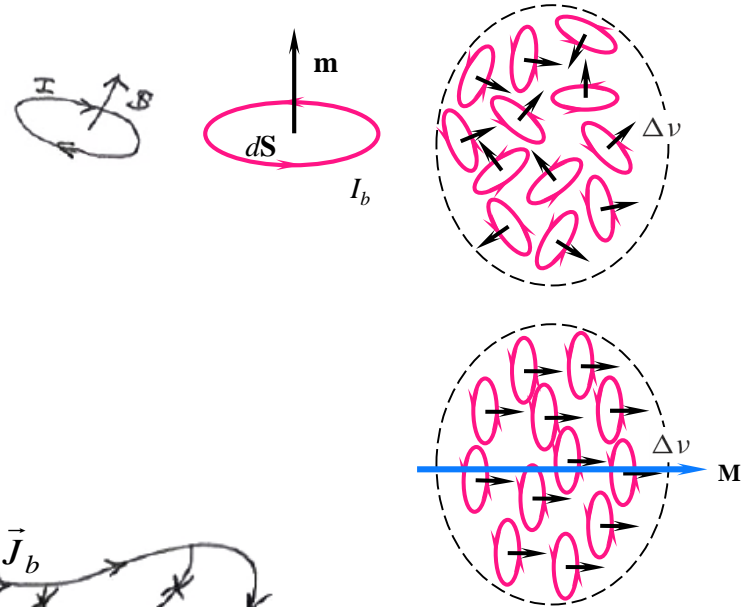
$$\oint \vec{M} \cdot d\vec{L} = \oint_s \vec{J}_b \cdot d\vec{S}$$

$$\oint \nabla \times \vec{M} \cdot d\vec{S} = \oint_s \vec{J}_b \cdot d\vec{S}$$

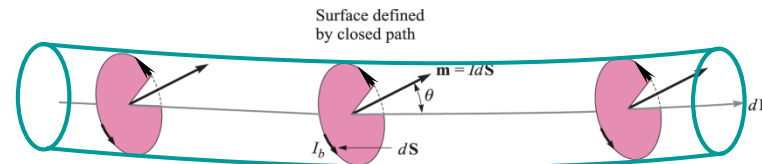
$$\therefore \nabla \times \vec{M} = \vec{J}_b$$

$$\vec{M} \quad \vec{J}_b \quad I_B = \oint \vec{M} \cdot d\vec{L}$$

$$I = \oint \vec{H} \cdot d\vec{L}$$



가운데는 서로 상쇄, 경계만 남음



• $\vec{B}, \vec{M}, \vec{H}$

자유공간에서 : $\nabla \times \vec{H}_T = \vec{J}_T = \vec{J}_s + \vec{J}_b$

$$\vec{J}_b = \nabla \times \vec{M}$$

$$\vec{H}_T = \frac{1}{\mu_0} \vec{B}_T \quad \vec{B}_T = \mu_0 \vec{H}_T$$

$$\therefore \nabla \times \frac{1}{\mu_0} \vec{B}_T = \vec{J}_s + \nabla \times \vec{M}$$

$$\nabla \times \left(\frac{\vec{B}_T}{\mu_0} - \vec{M} \right) = \vec{J}_s$$

$$\nabla \times \vec{H}_s = \vec{J}_s$$

$$\vec{H}_s = \frac{\vec{B}_T}{\mu_0} - \vec{M} \quad \therefore \boxed{\vec{B}_T = \mu_0 (\vec{H}_s + \vec{M})}$$

$$\boxed{\vec{D} = \epsilon_0 \vec{E} + \vec{P}}$$



$$\vec{J}_s \rightarrow \vec{H}_s$$

$$\vec{H}_T = \vec{H}_s + f(\vec{M})$$

$$\left\{ \begin{array}{l} \nabla \times \vec{H}_s = \vec{J}_s \\ \nabla \times \vec{H}_T = \vec{J}_s + \nabla \times \vec{M} \end{array} \right.$$

$$\left\{ \begin{array}{l} \vec{B}_T = \mu_0 (\vec{H}_s + \vec{M}) \\ \vec{H}_T = \vec{H}_s + \vec{M} \end{array} \right.$$

Conduction Current: $I = \int_s \mathbf{J} \cdot d\mathbf{S}$

Bound Current: $I_B = \int_s \mathbf{J}_B \cdot d\mathbf{S}$

Total Current(= $I + I_B$) : $I_T = \int_s \mathbf{J}_T \cdot d\mathbf{S}$

- 자화율 (Magnetic Susceptibility) : χ_m

$$\boxed{\vec{M} = \chi_m \vec{H}_s} \quad \chi_m = \frac{\vec{M}}{\vec{H}_s} \quad \vec{M} // \vec{H}_s \quad ? \quad (\text{등방성 / 이방성})$$

- 투자율 (Magnetic Permeability) : μ

$$\boxed{\vec{B}_T = \mu \vec{H}_s} \quad \vec{B} = \mu_0 (\vec{H}_s + \vec{M}) = \mu_0 (\vec{H}_s + \chi_m \vec{H}_s) = \mu_0 (1 + \chi_m) \vec{H}_s = \mu_0 \mu_r \vec{H}_s$$

$$\mu = \mu_0 \mu_r \quad \mu_r = 1 + \chi_m$$

(Ex 8.5) Given a ferrite material that we shall specify to be operating in a linear mode with $B = 0.05$ T, let us assume $\mu_r = 50$, and calculate values for χ_m , M , and H .

Because $\mu_r = 1 + \chi_m$, we have $\chi_m = \mu_r - 1 = 49$

Now: $B = \mu_r \mu_0 H$ so that.... $H = \frac{0.05}{50 \times 4\pi \times 10^{-7}} = 796$ A/m

The magnetization is $\chi_m H$, or 39000 A/m

- Anisotropic Media : Permeability tensor

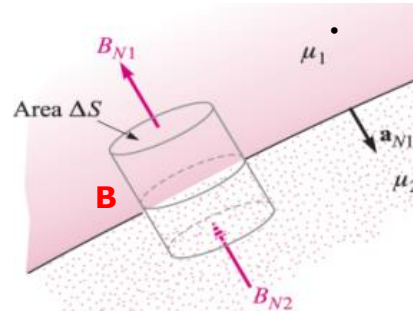
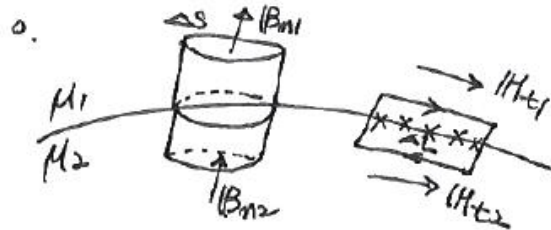
$$B_x = \mu_{xx} H_x + \mu_{xy} H_y + \mu_{xz} H_z$$

$$\mathbf{B} = \bar{\bar{\mu}} \mathbf{H} \quad B_y = \mu_{yx} H_x + \mu_{yy} H_y + \mu_{yz} H_z$$

$$B_z = \mu_{zx} H_x + \mu_{zy} H_y + \mu_{zz} H_z$$

- Sum
- | | | | |
|----------|-----------------|------------------|--|
| Vacuum : | $\mu_r = 1$, | $\chi_m = 0$, | $\vec{M} = 0$ |
| Dia : | $\mu_r < 1$, | $\chi_m < 0$, | $\vec{M} < 0$, ($\chi_m : -0.00005 \sim 0$) |
| Para : | $\mu_r > 1$, | $\chi_m > 0$, | $\vec{M} > 0$, ($\chi_m : -0.0001 \sim 0.01$) |
| Ferro : | $\mu_r \gg 1$, | $\chi_m \gg 0$, | $\vec{M} \gg 0$, ($\chi_m : 100 \sim 100만$) |

8.7 자계 경계조건



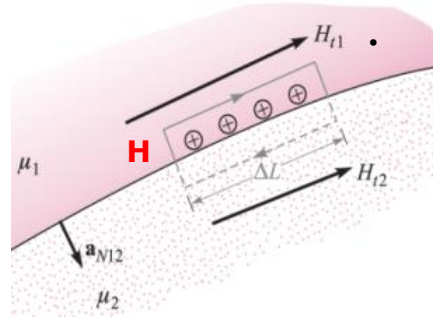
$$\oint \vec{B} \cdot d\vec{S} = 0$$

$$\vec{B}_{n1} \cdot \Delta S - \vec{B}_{n2} \cdot \Delta S = 0$$

$$\mu_1 \vec{H}_{n1} = \mu_2 \vec{H}_{n2}$$

$$\vec{B}_{n1} = \vec{B}_{n2}$$

$$\vec{H}_{n2} = \frac{\mu_1}{\mu_2} \vec{H}_{n1}$$



$$\oint \vec{H} \cdot d\vec{L} = I$$

(부도체: $k=0$)

$$\vec{H}_{t1} \cdot \Delta L - \vec{H}_{t2} \cdot \Delta L = k \cdot \Delta L$$

$$\vec{H}_{t1} - \vec{H}_{t2} = k$$

$$\vec{H}_{t1} = \vec{H}_{t2}$$

$$\vec{B}_{t1} / \mu_1 - \vec{B}_{t2} / \mu_2 = k$$

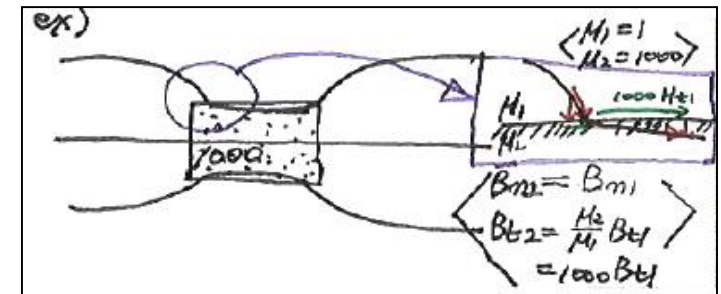
$$\vec{B}_{t2} = \frac{\mu_2}{\mu_1} \vec{B}_{t1}$$

➤ Sum

$$\left[\begin{array}{l} \vec{B}_{n1} = \vec{B}_{n2} \\ \vec{H}_{n2} = \frac{\mu_1}{\mu_2} \vec{H}_{n1} \end{array} \right. \quad \left. \begin{array}{l} \vec{B}_{t2} = \frac{\mu_1}{\mu_2} \vec{B}_{t1} \\ \vec{H}_{t1} = \vec{H}_{t2} \end{array} \right]$$

$$\vec{B} = \mu_0 (\vec{H} + \vec{M})$$

$$\vec{B} = \mu \vec{H} \quad (?)$$



8.8 자기회로

- ✓ 전기회로 : 전압, 전기저항, 전류
자기회로 : 기자력, 자기저항, 자속(자속밀도)

< Electricity >

- Electro-Motive Force(emf) :

$$\mathbf{E} = -\nabla V \quad V_{AB} = \int_A^B \mathbf{E} \cdot d\mathbf{L}$$

- Electric Current :

$$\mathbf{J} = \sigma \mathbf{E} \quad I = \int_S \mathbf{J} \cdot d\mathbf{S}$$

- Electric Resistance :

$$V = IR \quad R = \frac{d}{\sigma S}$$

- Electric Circuit :

$$\oint \mathbf{E} \cdot d\mathbf{L} = 0$$

< Magnetism >

- Magneto-Motive Force(mmf) :

$$\mathbf{H} = -\nabla V_m \quad V_{mAB} = \int_A^B \mathbf{H} \cdot d\mathbf{L}$$

- Magnetic Flux (Density) :

$$\mathbf{B} = \mu \mathbf{H} \quad \Phi = \int_S \mathbf{B} \cdot d\mathbf{S}$$

- Magnetic Reluctance :

$$V_m = \Phi \Re$$

$$\Re = \frac{d}{\mu S}$$

- Magnetic Circuit :

$$\oint \mathbf{H} \cdot d\mathbf{L} = I_{\text{total}}$$

$$\oint \mathbf{H} \cdot d\mathbf{L} = NI$$

전기회로

$$\vec{E} = -\nabla V$$

$$V_{AB} = \int_A^B \vec{E} \cdot d\vec{L}$$

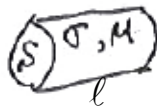
$$\vec{J} = \sigma \vec{E}, \sigma : \text{도전율}$$

$$I = \int_A \vec{J} \cdot d\vec{S}$$

$$V = IR$$

$$R = \frac{V}{I}$$

$$= \frac{\ell}{\sigma S}$$



$$\sigma [S/m] =$$

$$6.17 \times 10^7, \text{ 은}$$

$$5.8 \times 10^7, \text{ 동}$$

$$4.1 \times 10^7, \text{ 금}$$

$$3.8 \times 10^7, \text{ Al}$$

$$1.03 \times 10^7, \text{ 철}$$

$$6.17 \times 10^{-10}, \text{ 도자기}$$

$$2 \times 10^{-13}, \text{ 다이아몬드}$$

$$\oint \vec{E} \cdot d\vec{L} = 0$$

자기회로

$$\vec{H} = -\nabla V_m \quad V_m = \text{기자력(Magnetic Motive Force, mmf) [AT]}$$

$$V_{mAB} = \int_A^B \vec{H} \cdot d\vec{L}$$

$$\vec{B} = \mu \vec{H}, \mu : \text{투자율}$$

$$\Phi = \int_S \vec{B} \cdot d\vec{S}$$

$$V_m = \Phi R_m$$

$$R_m = \frac{V_m}{\Phi}$$

$$R_m = \text{Reluctance [AT/Wb]}$$

$$= \frac{\ell}{\mu S}$$

$$P = \frac{1}{R_m} = \text{Permeance}$$

$$\mu [H/m] =$$

$$\text{Fe : } 1000 \sim 4000$$

$$\text{철분 : } 100$$

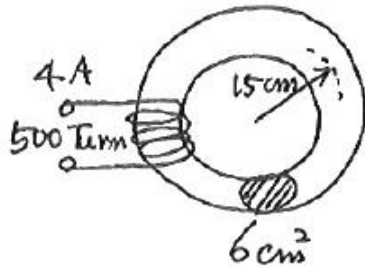
$$\text{Supermalloy : } 10\text{만}$$

→ 자기누설, 비선형 자기회로

$$\oint \vec{H} \cdot d\vec{L} = NI$$

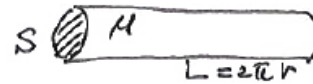
$$\oint \vec{H} \cdot d\vec{L} = NI$$

< Ex. 본문 > 공심 토로이드(Air-Core Toroid)



① 기자력 : $V_m = N \cdot I = 500 \times 4 = 2000 \text{ [A} \cdot \text{T]}$

② 자기저항 :



$$R_m = \frac{\ell}{\mu S} = \frac{2\pi \times 0.15}{4\pi \times 10^{-7} \times 6 \times 10^{-4}} = 1.25 \times 10^9 \text{ [A} \cdot \text{T / Wb]}$$

③ $\left\{ \begin{array}{l} \text{자속 : } \Phi = \frac{V_m}{R_m} = \frac{2000}{1.25 \times 10^9} = 1.6 \times 10^{-6} \text{ [Wb]} \\ \text{자속밀도 : } B = \frac{\Phi}{S} = 2.67 \times 10^{-3} \text{ [Wb / m}^2 = \text{T]} = 26.7 \text{ [G]} \end{array} \right.$

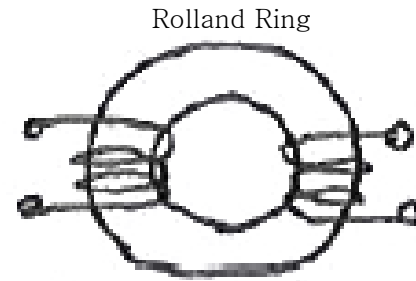
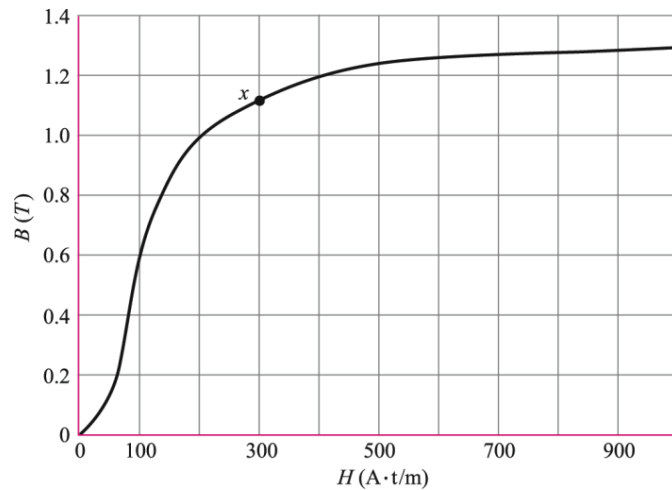
③ $H = \frac{B}{\mu} = \underline{\underline{2120 \text{ [AT / m]}}}$

✓ Ampere 주회법칙 $H_\phi = \frac{NI}{2\pi r} = \underline{\underline{2120 \text{ [AT / m]}}}$

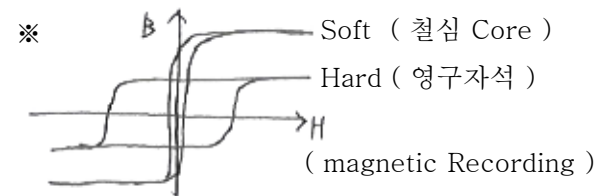
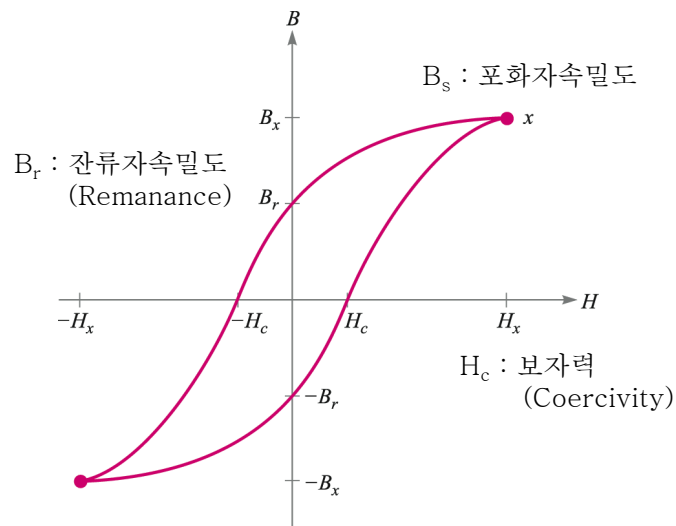
$$\begin{aligned} \int \vec{H} \cdot d\vec{L} &= NI \\ H_\phi \cdot 2\pi r &= NI \end{aligned}$$

◎ 자기포화현상 (Magnetic Saturation)

< B-H Curve >



◎ 자기히스테리시스현상 (Magnetic Hysteresis)

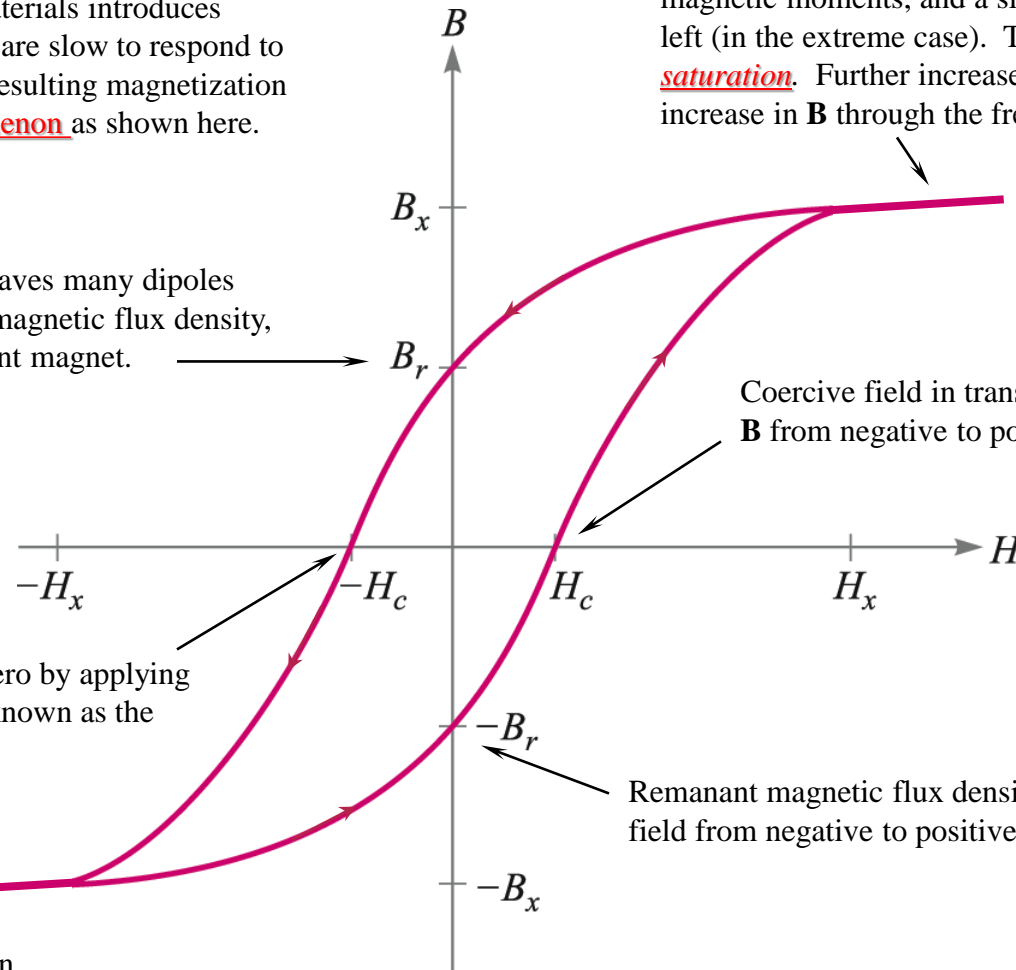


Magnetic Hysteresis

Domain wall shifting in ferromagnetic materials introduces semi-permanent magnetization states that are slow to respond to changes in applied magnetic fields. The resulting magnetization curve demonstrates the **hysteresis phenomenon** as shown here.

Decreasing the applied **H** field to zero leaves many dipoles still aligned, and we have the **remanent** magnetic flux density, B_r . The material has become a permanent magnet.

Increasing **H** to high positive values lines up all magnetic moments, and a single domain is left (in the extreme case). The core is thus in **saturation**. Further increase in **H** leads to an increase in **B** through the free space permeability



Coercive field in transitioning **B** from negative to positive values

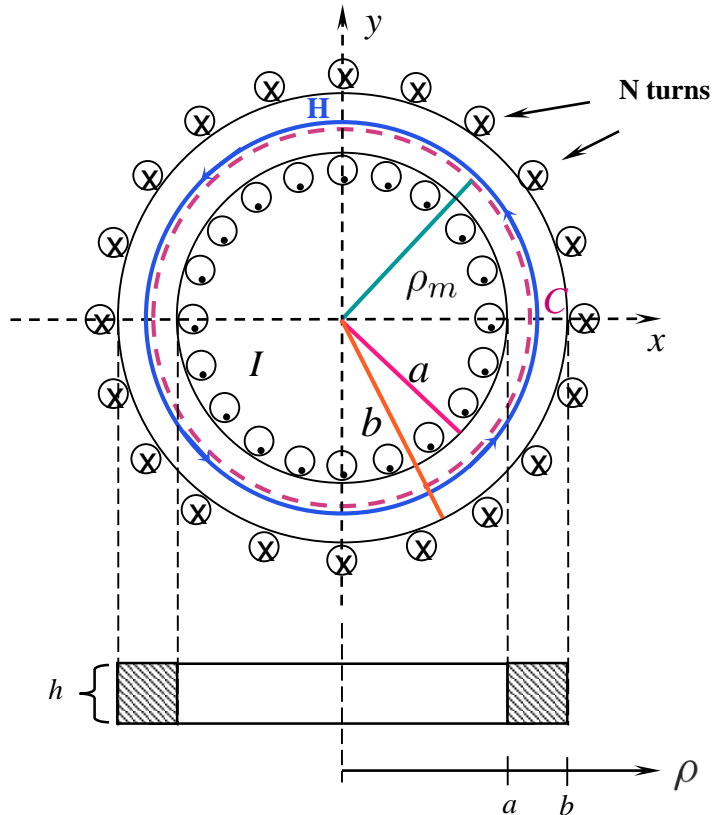
Remanant magnetic flux density, for *increasing* **H** field from negative to positive values

The remanant flux density is reduced to zero by applying an opposing magnetic field strength, $-H_c$ known as the **coercive field (or coercive force)**.

Increasing **H** to high negative values again leads to saturation

$$\oint \vec{H} \cdot d\vec{L} = NI$$

• Application of Reluctance: Toroidal Coil



$$(1) \quad H : \quad \Re = \frac{d}{\mu S} \approx \frac{2\pi\rho_m}{\mu(b-a)h}$$

$$\Phi = \frac{V_m}{\Re} = \frac{NI\mu(b-a)h}{2\pi\rho_m}$$

$$H = \frac{B}{\mu} = \frac{\Phi}{\mu S} = \frac{NI}{2\pi\rho_m}$$

$$\oint_C \vec{H} \cdot d\vec{L} = 2\pi\rho_m H_\phi = I_{encl} = NI$$

$$H_\phi = \frac{NI}{2\pi\rho_m} \text{ A/m}$$

$$(2) \quad \Phi : \quad \vec{B} = B_\phi \vec{a}_\phi = \frac{NI}{2\pi\rho} \vec{a}_\phi$$

$$\Phi = \int \int \vec{B} \cdot d\vec{S} = \int_0^h \int_a^b \frac{\mu NI}{2\pi\rho} d\rho dz = \frac{\mu NIh}{2\pi} \ln\left(\frac{b}{a}\right)$$

$$\left(\because \ln\left(\frac{b}{a}\right) = 2 \left[\left(\frac{b/a-1}{b/a+1}\right) + \frac{1}{3} \left(\frac{b/a-1}{b/a+1}\right)^3 + \frac{1}{5} \left(\frac{b/a-1}{b/a+1}\right)^5 + \dots \right] \right)$$

$$= \frac{\mu NIh}{2\pi} 2 \left[\left(\frac{b/a-1}{b/a+1}\right) + \frac{1}{3} \left(\frac{b/a-1}{b/a+1}\right)^3 + \frac{1}{5} \left(\frac{b/a-1}{b/a+1}\right)^5 + \dots \right]$$

0.33
Uniform field approximation

1.2×10^{-2}
 8.2×10^{-4}
Correction terms

$$\Phi = \frac{\mu NI(b-a)h}{2\pi\rho_m} \quad \rho_m = \frac{1}{2}(b+a)$$

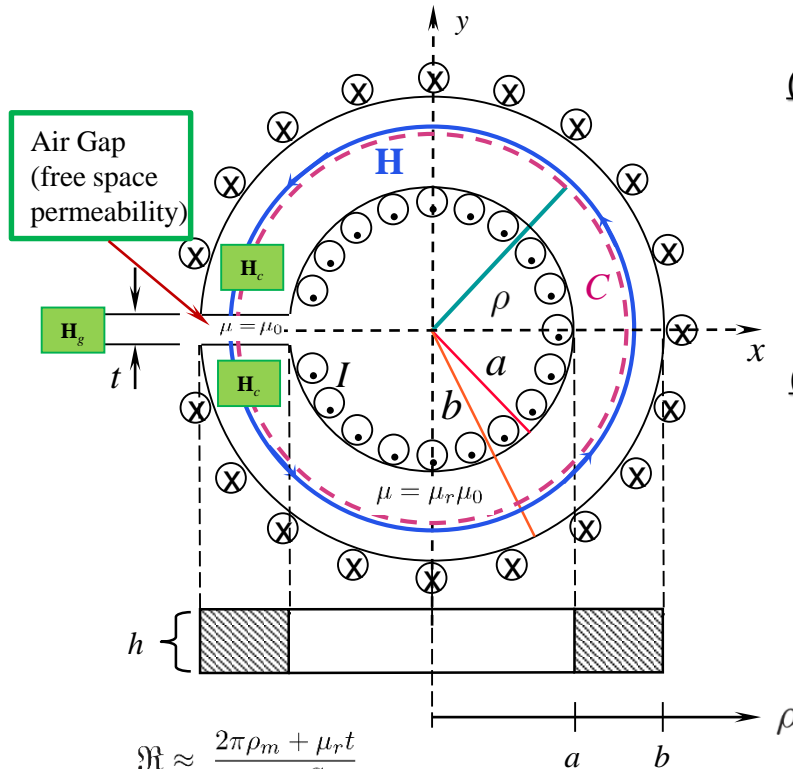
$$\Phi = \frac{\mu NIh}{2\pi} \left[\frac{2(b-a)}{(b+a)} \right] = \frac{\mu NIh}{2\pi} \left[\frac{2(b/a-1)}{(b/a+1)} \right]$$

$$= \frac{\mu NIh}{2\pi} \left[\frac{2(b/a-1)}{(b/a+1)} \right]$$

error $\approx 4\%$

$$\oint \vec{H} \cdot d\vec{L} = NI$$

Application of Reluctance: Toroidal Coil with a Gap



$$\mathfrak{R} \approx \frac{2\pi\rho_m + \mu_r t}{\mu_r \mu_0 S}$$

$$B = \frac{NI}{S} \approx \left[\frac{\mu_r \mu_0}{2\pi\rho_m + \mu_r t} \right] NI$$

$$\text{given } NI \approx \left[\frac{2\pi\rho_m}{\mu_r \mu_0} + \frac{t}{\mu_0} \right] \text{unknown } B$$

$$H_g = \frac{B}{\mu_0}$$

must satisfy Ampere's Circuital Law: $NI \approx 2\pi\rho_m H_c + t H_g$

If not, try again with a corrected value for B, over as many iterations as needed.

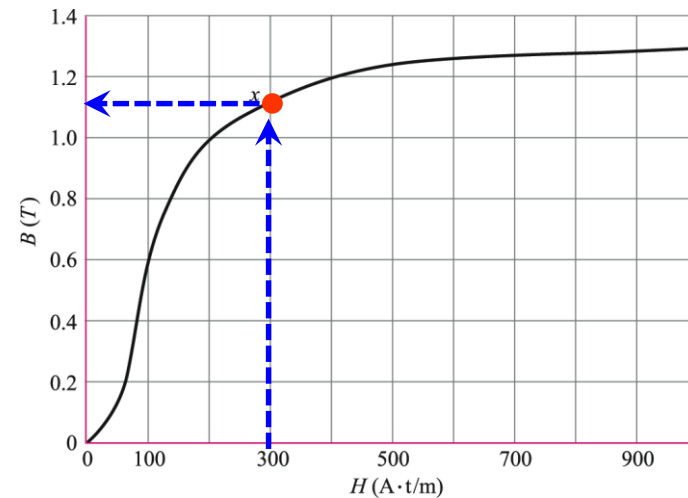
$$(1) \ H : \mathfrak{R} = \frac{2\pi\rho_m - t}{\mu S} + \frac{t}{\mu_0 S} = \frac{2\pi\rho_m + (\mu_r - 1)t}{\mu_r \mu_0 S}$$

$$\approx \frac{2\pi\rho_m + \mu_r t}{\mu_r \mu_0 S} \quad \mu_r \gg 1$$

$$B_c = B_g = B = \frac{NI}{\mathfrak{R} S} \approx \left[\frac{\mu_r \mu_0}{2\pi\rho_m + \mu_r t} \right] NI$$

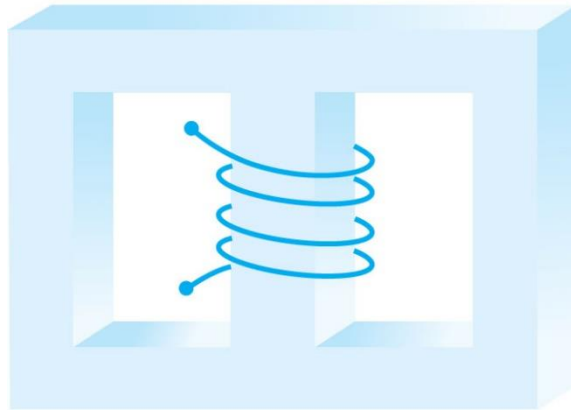
$$(2) \ \Phi : \text{Core} : H_c = \frac{B}{\mu_r \mu_0} = \frac{NI}{2\pi\rho_m + \mu_r t}$$

$$\text{Gap} : H_g = \frac{B}{\mu_0} = \frac{\mu_r NI}{2\pi\rho_m + \mu_r t} = \mu_r H_c$$

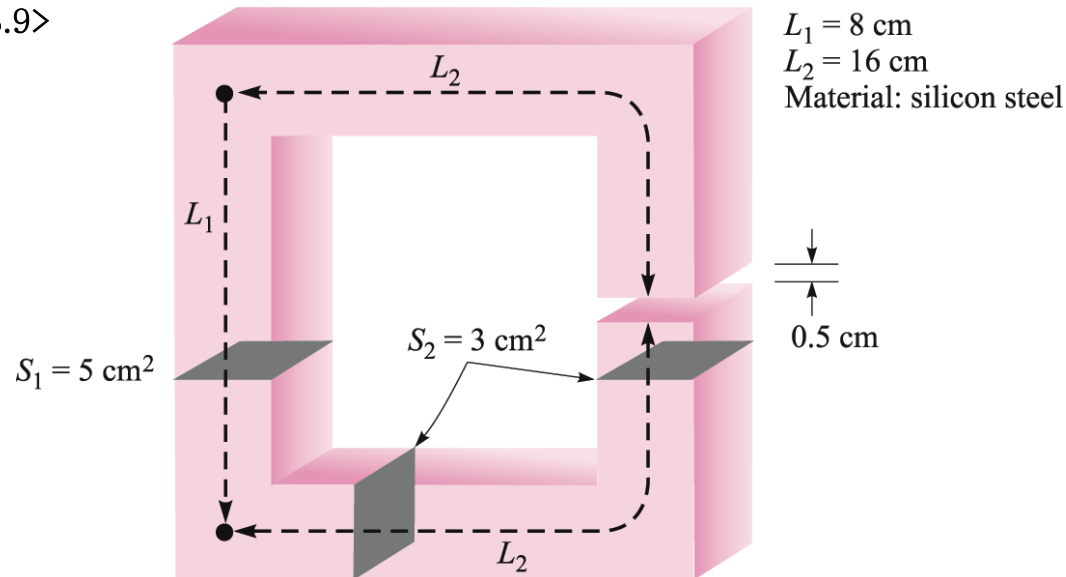


$$\oint \vec{H} \cdot d\vec{L} = NI$$

Copyright © The McGraw-Hill Companies, Inc.
Permission required for reproduction or display.



< 응용 8.9 >



8.9 자성체에서의 포텐셜 에너지와 힘

$$\begin{aligned} \bullet \left\{ \begin{array}{l} \text{전계 : } W_E = \frac{1}{2} \int_V \vec{D} \cdot \vec{E} dv \\ \text{자계 : } W_H = \frac{1}{2} \int_V \vec{B} \cdot \vec{H} dv = \frac{1}{2} \int_V \mu H^2 dv = \frac{1}{2} \int_V \frac{B^2}{\mu} dv \end{array} \right. \end{aligned}$$

$$dW_H = \vec{F} \cdot d\vec{L} = \frac{1}{2} \frac{B^2}{\mu} \cdot dL \cdot S$$

$$\therefore F = \frac{B^2}{2\mu_0} \cdot S$$

$$\text{Pressure : } P = \frac{B^2}{2\mu_0}$$

$$\text{Force : } F = P \cdot S$$

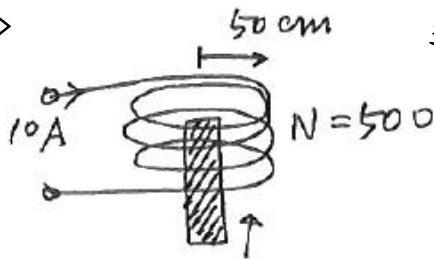
$$\text{Energy : } W = \int F \cdot d\ell$$

• Virtual Work :



* 비선형에서는 ?

< Ex. >



$$\text{코일 중심에서 } H = 5 \times 10^3, (= \frac{NI}{2a})$$

$$B = \mu_0 H = 63G$$

$$P = \frac{B^2}{2\mu_0} = 15.7 N/m^2 \cong 1.57 kg/m^2$$

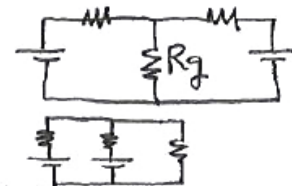
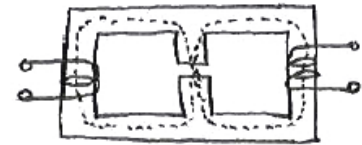
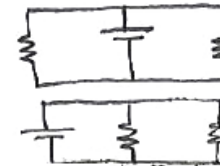
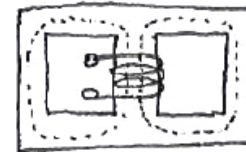
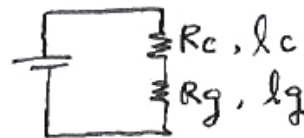
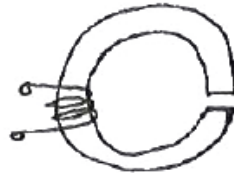
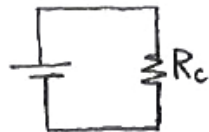
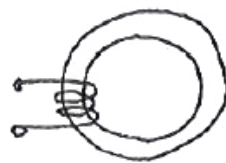
$$F = P \times S = 1.57 kg/m^2 \times \pi(0.5)^2 \cong 1.23 kg$$

$$\oint \vec{H} \cdot d\vec{L} = NI$$

◎ $V_m = N \cdot I = R \cdot \Phi = H \cdot L$

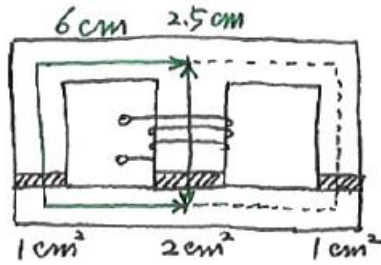
$\left\langle \begin{array}{l} \text{선형 : } N \cdot I = R \cdot \Phi \\ \text{비선형 : } N \cdot I = H \cdot L \end{array} \right\rangle$

◎ 자기회로 종류



$$\oint \vec{H} \cdot d\vec{L} = NI$$

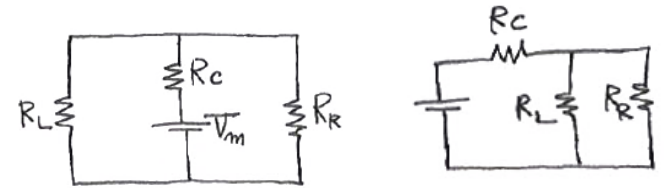
<Ex>



$$I = 8 \text{ mA}$$

$$\mu = 0.006 \text{ [H / m]}$$

$$N = 1500$$

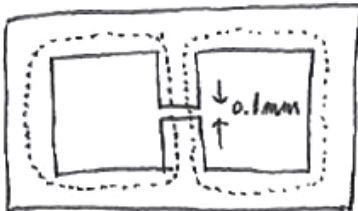


$$\left\{ \begin{array}{l} R_L = \frac{\ell_L}{\mu S_L} = 10 \times 10^4 \\ R_C = \frac{\ell_C}{\mu S_C} = 2.1 \times 10^4 \end{array} \right.$$

$$: R_T = R_C + \frac{R_L}{2} = 7.1 \times 10^4 \quad V_m = N \cdot I = 12$$

$$\left\{ \begin{array}{l} \Phi_C = \frac{V_m}{R_T} = 1.69 \times 10^{-4} \quad B_C = \frac{\Phi_C}{S_C} = 0.845 \text{ [T]} \\ \Phi_L = \Phi_R = \frac{\Phi_C}{2} = 0.845 \times 10^{-4} \quad B_L = B_R = \frac{\Phi_L}{S_L} = 0.55 \text{ [T]} \end{array} \right.$$

<Ex> 윗 예제 중심 Core 에 공극 0.1mm 가 있을 경우 같은 자속을 내기 위해 흘려야 하는 전류 값은?



$$R_g = \frac{\ell_g}{\mu_0 S_g} = 38.78 \times 10^4$$

$$\therefore R'_T = R_T + R_g = 7.1 \times 10^4 + 38.78 \times 10^4 = 46.9 \times 10^4$$

$$\Phi = 1.69 \times 10^{-4} \text{ 를 내어야 하므로}$$

$$V_m = N \cdot I = R'_T \Phi = 46.9 \times 10^4 \times 1.69 \times 10^{-4} = 79.26 \text{ [AT]}$$

$$\therefore I = \frac{V_m}{N} = \frac{79.26}{1500} = \underline{\underline{52.84 \text{ [mA]}}} \quad * \text{ gap } 0.1\text{mm} \text{ 때문에 전류는 6.6배 증가}$$

$$\oint \vec{H} \cdot d\vec{L} = NI$$

< Ex. > Find M A Toroid having an iron core of square section (Fig.) and permeability is wound with N(closed space) turns of wire carrying a current I.
Find the magnitude of the magnetization M everywhere inside the iron. (Wisconsin)

$$\oint \vec{H} \cdot d\vec{L} = NI$$

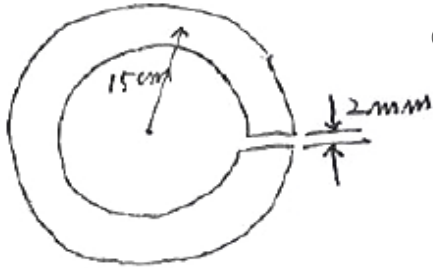
< 자료 >

< Ex. > A cylindrical soft iron rod of length L and diameter d is bent into a circular shape of radius R leaving a gap where the two ends of the rod almost meet. The gap spacing S is constant over the face of the ends of the rod. Assume $S \ll d$, $d \ll R$, N turns of wire are wrapped tightly around the iron rod and a current I is passed through the wire. The relative permeability of the iron is μ_r . Neglecting fringing, What is the magnetic field B in the gap?

(MIT)

$$\oint \vec{H} \cdot d\vec{L} = NI$$

< Ex. 본문 > 비선형 + 공극문제. Core에서 1 [T] 를 유지하기 위해 흘려야 할 전류 값을 구하시오.

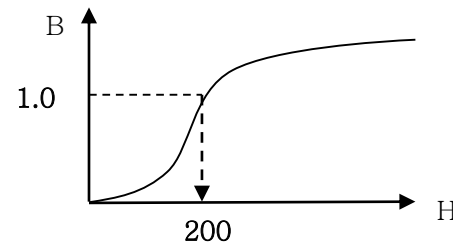


① 공극에서 : $R_a = \frac{\ell_a}{\mu S} = 2.65 \times 10^6 [AT / Wb]$

$$\Phi = B \cdot S = 1 \times 6 \times 10^{-4} = 6 \times 10^{-4} [Wb]$$

$$V_{m,a} = \Phi \cdot R_a = \underline{1590 [AT]}$$

② 철심에서 : $B_s = 1 [T] \xrightarrow{\text{B-H Curve}} H_s = 200 [At/m]$



$$\ell_s = 0.3\pi$$

$$V_{m,s} = H_s \cdot R_s = \underline{188 [AT]}$$

$$\therefore V_{m,Total} = V_{m,a} + V_{m,s} = 1778 [AT]$$

$$= NI$$

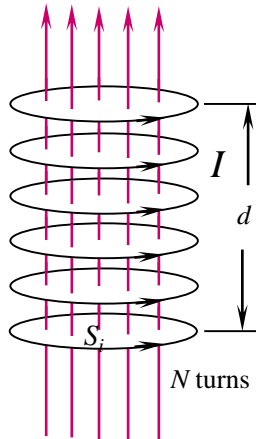
$$\therefore I = \frac{V_m}{N} = \frac{1778}{500} = \underline{3.56 [A]}$$

✓ Leakage, Fringing : $\frac{\mu_{iron}}{\mu_{air}} = 4000$ $\frac{\sigma_{iron}}{\sigma_{air}} = 10^{15}$

8.10 자기인덕턴스 및 상호 인덕턴스

• **Flux Linkage :** $\Phi_i = \int_{S_i} \mathbf{B}_i \cdot d\mathbf{S}_i$ Flux, Weber [Wb]

$$\lambda = \sum_{i=1}^N \Phi_i \quad \text{Flux linkage, Weber-turns [Wb-t]} \quad \lambda = N\Phi = N \int_S \mathbf{B} \cdot d\mathbf{S}$$



$$\Phi_i = \int_{S_i} \mathbf{B}_i \cdot d\mathbf{S}_i \quad B = \mu n I = \frac{\mu N I}{d}$$

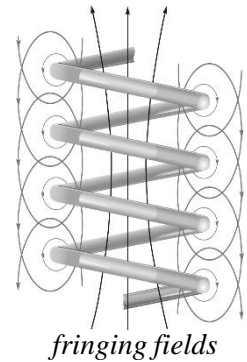
$$\lambda = \sum_{i=1}^N \Phi_i = N\Phi = N \int_S \mathbf{B} \cdot d\mathbf{S} = NBS = \frac{\mu N^2 IS}{d}$$

$$\lambda = \frac{\mu N^2 IS}{d}$$

$$L \equiv \frac{\lambda}{I} = N^2 \frac{\mu S}{d}$$

The units of inductance : Wb-t/A = Henry [H].

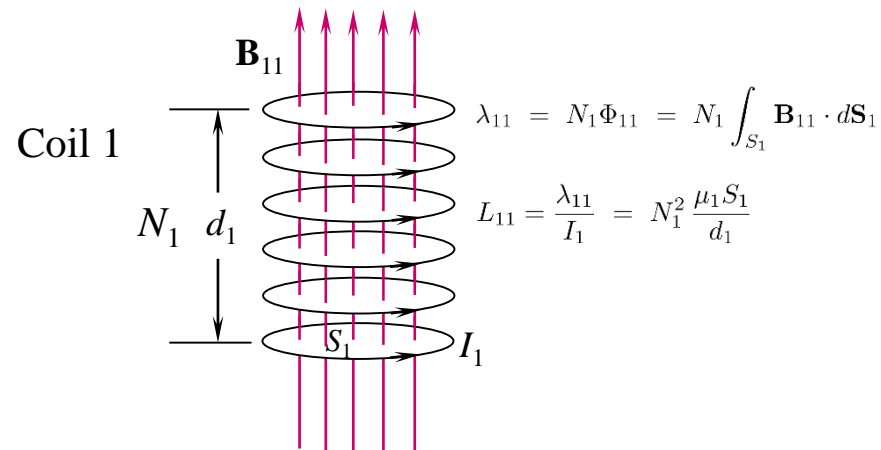
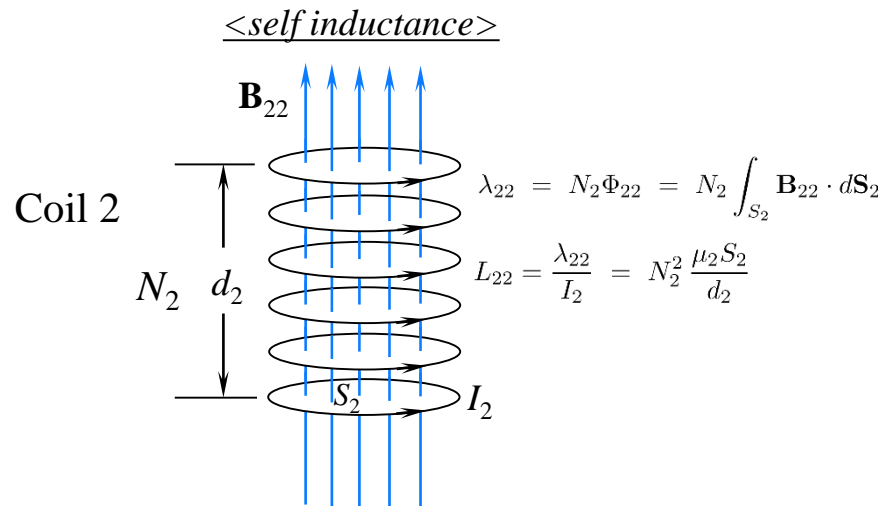
$$C = \frac{\epsilon S}{d}$$



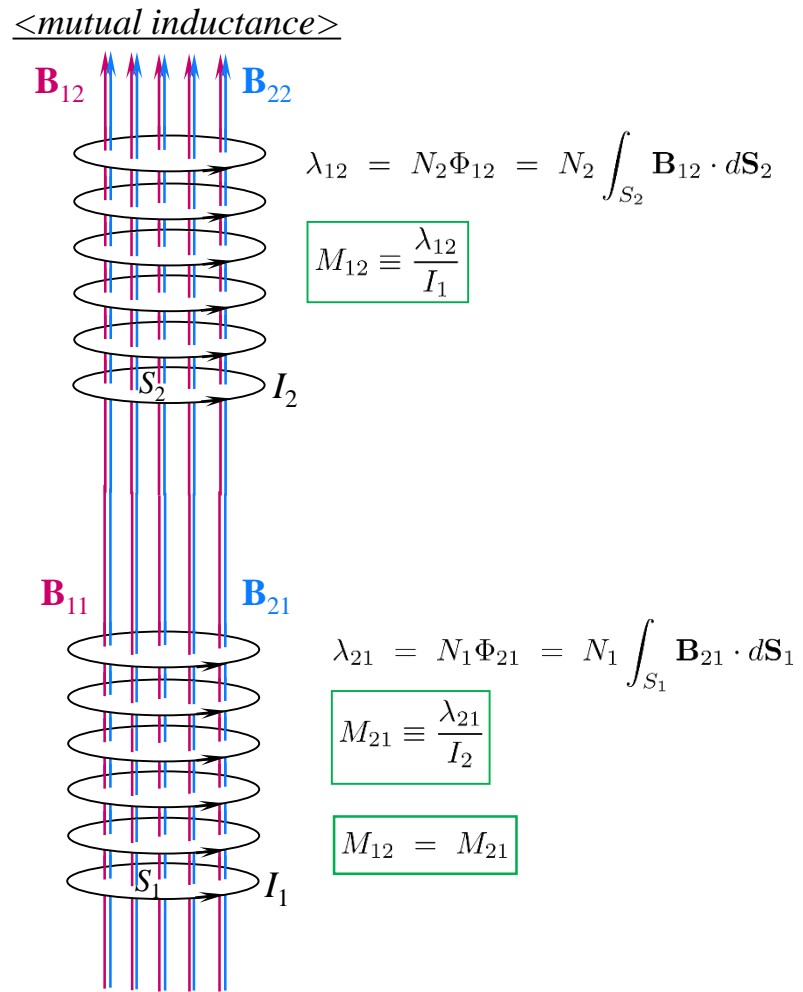
| | | | |
|----------------------|----------------------|--|-------------------------------------|
| 인덕턴스 L : (전류 → 자속) | $L = \frac{\Phi}{I}$ | | [Henry, $H \equiv \frac{Wb}{A}$] |
| 정전용량 C : (전하 → 전압) | $C = \frac{Q}{V}$ | | [Farad, $F \equiv \frac{C}{V}$] |
| 저항 R : (전압 → 전류) | $R = \frac{V}{I}$ | | [Ohm, $\Omega \equiv \frac{V}{A}$] |

!!

◎ 상호 인덕턴스(Mutual Inductance)

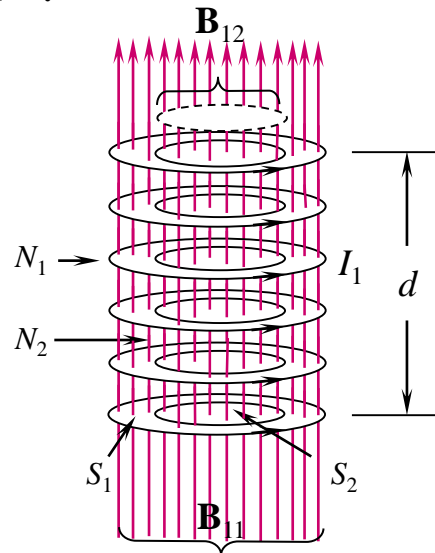


\mathbf{B}_{ij} arising from coil i evaluated within coil j



Red : generated by Coil 1,
Blue : generated by Coil 2

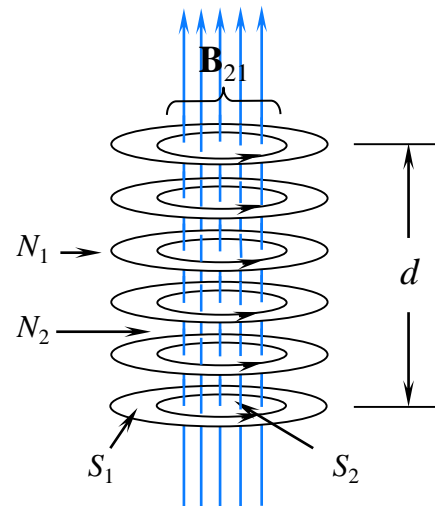
<Ex> Concentric Solenoid :



$$\mathbf{B}_{12} = \frac{\mu N_1 I_1}{d} \mathbf{a}_z$$

$$\lambda_{12} = N_2 \Phi_{12} = N_2 \frac{\mu N_1 I_1}{d} S_2$$

$$M_{12} = \frac{\lambda_{12}}{I_1} = N_1 N_2 \frac{\mu S_2}{d}$$



$$\mathbf{B}_{21} = \frac{\mu N_2 I_2}{d} \mathbf{a}_z$$

$$\lambda_{21} = N_1 \Phi_{21} = N_1 \frac{\mu N_2 I_2}{d} S_1$$

$$M_{21} = \frac{\lambda_{21}}{I_2} = N_1 N_2 \frac{\mu S_1}{d} = M_{12}$$

$$M_{12} = M_{21}$$

Energy and Energy Density in the Magnetic Field

Energy in the electric field within volume v :

$$W_E = \int_v \frac{1}{2} \mathbf{D} \cdot \mathbf{E} dv \quad \text{J}$$

Energy in the magnetic field within volume v :

$$W_M = \int_v \frac{1}{2} \mathbf{B} \cdot \mathbf{H} dv \quad \text{J}$$

Energy density in the electric field :

$$w_e = \frac{1}{2} \mathbf{D} \cdot \mathbf{E} = \frac{1}{2} \epsilon E^2 \quad \text{J/m}^3$$

Energy density in the magnetic field :

$$w_m = \frac{1}{2} \mathbf{B} \cdot \mathbf{H} = \frac{1}{2} \mu H^2 \quad \text{J/m}^3$$

valid for isotropic media

- ✓ restricted to *linear* media (in which permittivity and permeability are constant with field strength).
- ✓ Deriving the magnetic energy relation is very complicated, so we will not do it here.

◎ 에너지와 인덕턴스

• 전계 : $W_C = \frac{1}{2} CV^2$

자계 : $W_H = \frac{1}{2} LI^2$

•
$$L = \frac{2W_H}{I^2} = \frac{1}{I^2} \int_V \vec{B} \cdot \vec{H} dv = \frac{1}{I^2} \int_V \vec{H} \cdot (\nabla \times \vec{A}) dv = \frac{1}{I^2} \left[\int_V \nabla \cdot (\vec{A} \times \vec{H}) dv + \int_V \vec{A} \cdot (\nabla \times \vec{H}) dv \right]$$

$$= \frac{1}{I^2} \left[\oint_s (\vec{A} \times \vec{H}) \cdot d\vec{s} + \int_V \vec{A} \cdot \vec{J} dv \right] \quad \left(\because \nabla \cdot (\vec{A} \times \vec{H}) \equiv \vec{H} \cdot (\nabla \times \vec{A}) - \vec{A} \cdot (\nabla \times \vec{H}) \right)$$

발산정리

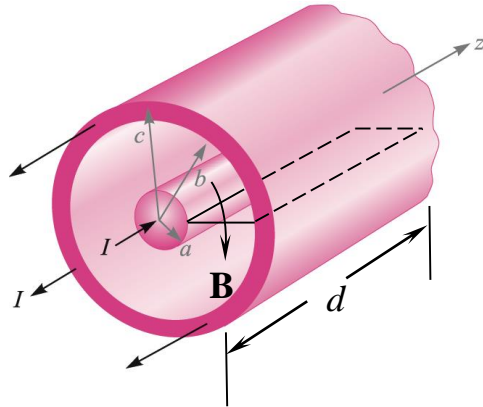
$$\therefore L = \frac{1}{I^2} \int_V \vec{A} \cdot \vec{J} dv$$

(i)
$$L = \frac{1}{I^2} \int_V \vec{A} \cdot \vec{J} dv = \frac{1}{I^2} \int_V \left(\int_V \frac{\mu \vec{J}}{4\pi R} dv \right) \cdot \vec{J} dv = \frac{1}{I^2} \oint \left(\oint \frac{\mu I d\vec{L}}{4\pi R} \right) \cdot I d\vec{L}$$

$$= \frac{\mu}{4\pi} \oint \oint \frac{d\vec{L}}{R} \cdot d\vec{L} : L \text{ 은 기하학적 구조와 재료의 함수}$$

(ii)
$$L = \frac{1}{I^2} \int_V \vec{A} \cdot \vec{J} dv = \frac{1}{I} \oint \vec{A} \cdot d\vec{L} = \frac{1}{I} \int_S (\nabla \times \vec{A}) \cdot d\vec{S} = \frac{1}{I} \int_S \vec{B} \cdot d\vec{S} = \frac{\Phi}{I}$$

<Ex> 동축 케이블



$$H_{\phi} = \frac{I}{2\pi\rho} \quad (a < \rho < b) \quad \mathbf{B} = \mu_0 \mathbf{H} = \frac{\mu_0 I}{2\pi\rho} \mathbf{a}_{\phi}$$

$$\lambda = \Phi = \int_S \mathbf{B} \cdot d\mathbf{S} = \int_0^d \int_a^b \frac{\mu_0 I}{2\pi\rho} \mathbf{a}_{\phi} \cdot d\rho dz \mathbf{a}_{\phi} = \frac{\mu_0 I d}{2\pi} \ln \frac{b}{a}$$

$$L = \frac{\Phi}{I} = \frac{\mu_0 \ell}{2\pi} \ln \frac{b}{a} \quad : [\text{H}]$$

$$L / \ell = \frac{\mu_0}{2\pi} \ln \frac{b}{a} \quad : [\text{H/m}]$$

<Ex> 토로이드

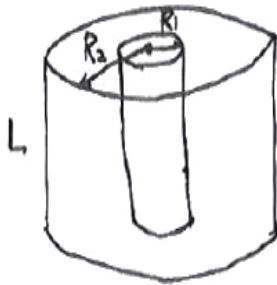


$$B_{\phi} = \frac{\mu_0 N I}{2\pi r}$$

$$\Phi = B \cdot S = \frac{\mu_0 N I S}{2\pi r_0}$$

$$L = \frac{N \Phi}{I} = \frac{\mu_0 N^2 S}{2\pi r_0}$$

< Ex. 8.9 > 동축 솔레노이드



$$\bullet \quad n_1 = \frac{N}{L}, \quad \vec{H}_1 = \begin{cases} n_1 I_1 \hat{a}_z & (0 < r < R_1) \\ 0 & (r > R_1) \end{cases}$$

$$\vec{H}_2 = \begin{cases} n_2 I_2 \hat{a}_z & (0 < r < R_2) \\ 0 & (r > R_2) \end{cases}$$

$$\bullet \quad \left\langle \begin{array}{ll} \Phi_{12} = \mu_0 n_1 I_1 \pi R_1^2 & \Phi_{21} = \mu_0 n_2 I_2 \pi R_1^2 \\ M_{12} = \mu_0 n_1 n_2 \pi R_1^2 & M_{21} = \mu_0 n_1 n_2 \pi R_1^2 = M_{12} \end{array} \right\rangle$$

$$\begin{array}{l} \text{(ex) } R_1 = 2 \text{ cm : } n_1 = 50 \text{ T/cm} \\ \quad \quad R_2 = 3 \text{ cm : } n_2 = 80 \text{ T/cm} \end{array} \rightarrow \begin{cases} L_1 = 39.4 \text{ mH/m} \\ L_2 = 277.0 \text{ mH/m} \\ M_{12} = 63.0 \text{ mH/m} = M_{21} \end{cases}$$

◎ 자기 인덕턴스(Self Inductance)



$$\underline{\underline{L = \frac{N\Phi}{I} :}}$$

I 에 의하여 발생하는 자속의 양

◎ 상호 인덕턴스(Mutual Inductance)



$$\underline{\underline{M_{12} = \frac{N_2 \Phi_{12}}{I_1} :}}$$

I_1 에 의하여 발생하는 자속 중
Coil 2 에 쇄교되는 자속의 양

$$M_{12} = \frac{1}{I_1 I_2} \int_v (\vec{B} \cdot \vec{H}) dv = \frac{1}{I_1 I_2} \int_v (\mu \vec{H} \cdot \vec{H}) dv = M_{21}$$

$$\therefore M_{12} = M_{21}$$