제3장 ARMA 모형

3.2 MA모형

3.2.1 MA(1)모형

$$Z_t = a_t - \theta_1 a_{t-1}$$

■ 자기공분산함수

$$\begin{split} Z_t &= a_t - \theta_1 a_{t-1} \\ Var(Z_t) &= Var(a_t - \theta_1 a_{t-1}) = Var(a_t) + \theta_1^2 Var(a_{t-1}) - 2\theta_1 Cov(a_t, \ a_{t-1}) \\ \gamma(0) &= \sigma_a^2 + \theta_1^2 \sigma_a^2 = \left(1 + \theta_1^2\right) \sigma_a^2 \\ Z_t &= a_t - \theta_1 a_{t-1} \\ Z_t Z_{t-1} &= a_t Z_{t-1} - \theta_1 a_{t-1} Z_{t-1} \\ E(Z_t Z_{t-1}) &= E(a_t Z_{t-1}) - \theta_1 E(a_{t-1} Z_{t-1}) = -\theta_1 E\left(a_{t-1}^2\right) = -\theta_1 \sigma_a^2 \\ \gamma(1) &= -\theta_1 \sigma_a^2 \\ Z_t &= a_t - \theta_1 a_{t-1} \\ Z_t Z_{t-k} &= a_t Z_{t-k} - \theta_1 a_{t-1} Z_{t-k} \\ E(Z_t Z_{t-k}) &= E(a_t Z_{t-k}) - \theta_1 E(a_{t-1} Z_{t-k}) \\ \gamma(k) &= 0, \ k \geq 2 \end{split}$$

• 정상성 조건

$$\gamma(0) = (1 + \theta_1^2)\sigma_a^2 < \infty \quad \rightarrow \quad \theta_1^2 < \infty$$

• 가역성(invertibility) 조건

$$\begin{split} Z_t &= a_t - \theta_1 a_{t-1} & \rightarrow & Z_t = a_t - \theta_1 B a_t = (1 - \theta_1 B) a_t = \Theta(B) a_t \\ & \Rightarrow & (1 - \theta_1 B)^{-1} Z_t = a_t \quad \mbox{$\stackrel{>}{\sim}$} \ \ & \\ & (1 + \theta_1 B + \theta_1^2 B^2 + \, \cdots \,) Z_t = a_t \quad \mbox{$\stackrel{>}{\sim}$} \ \ \ \\ & Z_t = - \sum_{i=1}^\infty \theta_1^i Z_{t-i} + a_t \end{split}$$

 \therefore 이런 식으로 표현되려면 θ_1 은 $-1 < \theta_1 < 1$ 조건을 만족해야 한다.

* MA(1)모형의 ACF

$$\rho(1) = \frac{\gamma(1)}{\gamma(0)} = \frac{-\theta_1 \sigma_a^2}{(1 + \theta_1^2) \sigma_a^2} = \frac{-\theta_1}{1 + \theta_1^2}$$
$$\rho(k) = \frac{\gamma(k)}{\gamma(0)} = 0, \ k \ge 2$$

- MA(1)모형의 ACF: 시차 1에서 절단되는 형태
- MA(1)모형의 PACF

[정리 2.3]을 사용

$$\begin{split} P(1) &= \rho(1) = \frac{\gamma(1)}{\gamma(0)} = \frac{-\theta_1 \sigma_a^2}{\left(1 + \theta_1^2\right) \sigma_a^2} = \frac{-\theta_1}{1 + \theta_1^2} \\ P(2) &= \frac{\rho(2) - \rho^2(1)}{1 - \rho^2(1)} = \frac{-\left(\frac{-\theta_1}{1 + \theta_1^2}\right)^2}{1 - \left(\frac{-\theta_1}{1 + \theta_1^2}\right)^2} = \frac{-\theta_1^2}{1 + \theta_1^2 + \theta_1^4} \\ &= \frac{-\theta_1^2(1 - \theta_1^2)}{(1 + \theta_1^2 + \theta_1^4)(1 - \theta_1^2)} = \frac{-\theta_1^2(1 - \theta_1^2)}{1 - \theta_1^{2(3)}} \\ P(k) &= \frac{-\theta_1^k(1 - \theta_1^2)}{1 - \theta_1^{2(k+1)}}, \ k = 1, \ 2, \ \cdots \end{split}$$

• MA(1)모형의 PACF: 시차 k가 증가할 때 0으로 점차 감소

3.2.2 MA(2)모형

$$\begin{split} Z_t &= a_t - \theta_1 a_{t-1} - \theta_2 a_{t-2} \\ Z_t &= a_t - \theta_1 B a_t - \theta_2 B^2 a_t = (1 - \theta_1 B - \theta_2 B^2) a_t = \Theta_2(B) a_t \end{split}$$

■ 자기공분산함수

$$\begin{split} Z_t &= a_t - \theta_1 a_{t-1} - \theta_2 a_{t-2} \\ Var(Z_t) &= Var(a_t - \theta_1 a_{t-1} - \theta_2 a_{t-2}) = Var(a_t) + \theta_1^2 Var(a_{t-1}) + \theta_2^2 Var(a_{t-2}) \\ &= (1 + \theta_1^2 + \theta_2^2) Var(a_t) = (1 + \theta_1^2 + \theta_2^2) \sigma_a^2 \\ \gamma(0) &= (1 + \theta_1^2 + \theta_2^2) \sigma_a^2 \end{split}$$

$$\begin{split} Z_t &= a_t - \theta_1 a_{t-1} - \theta_2 a_{t-2} \\ E(Z_t Z_{t-1}) &= E \big[\big(a_t - \theta_1 a_{t-1} - \theta_2 a_{t-2} \big) \big(a_{t-1} - \theta_1 a_{t-2} - \theta_2 a_{t-3} \big) \big] \\ &= E \Big(- \theta_1 a_{t-1}^2 + \theta_1 \theta_2 a_{t-2}^2 \Big) = - \theta_1 E \Big(a_{t-1}^2 \Big) + \theta_1 \theta_2 E \Big(a_{t-2}^2 \Big) = \Big(- \theta_1 + \theta_1 \theta_2 \Big) \sigma_a^2 \\ \gamma(1) &= \Big(- \theta_1 + \theta_1 \theta_2 \Big) \sigma_a^2 \\ Z_t &= a_t - \theta_1 a_{t-1} - \theta_2 a_{t-2} \\ E(Z_t Z_{t-2}) &= E \big[\big(a_t - \theta_1 a_{t-1} - \theta_2 a_{t-2} \big) \big(a_{t-2} - \theta_1 a_{t-3} - \theta_2 a_{t-4} \big) \big] \\ &= E \Big(- \theta_2 a_{t-2}^2 \Big) = - \theta_2 E \Big(a_{t-2}^2 \Big) = - \theta_2 \sigma_a^2 \\ Z_t &= a_t - \theta_1 a_{t-1} - \theta_2 a_{t-2} \\ E(Z_t Z_{t-k}) &= E \big[\big(a_t - \theta_1 a_{t-1} - \theta_2 a_{t-2} \big) \big(a_{t-k} - \theta_1 a_{t-k-1} - \theta_2 a_{t-k-2} \big) \big] \\ &= 0, \quad k \geq 3 \\ \gamma(k) &= 0, \quad k \geq 3 \end{split}$$

• 정상성 조건

$$\gamma(0) = (1 + \theta_1^2 + \theta_2^2)\sigma_a^2 < \infty \quad \rightarrow \quad \theta_1^2 + \theta_2^2 < \infty$$

• 가역성(invertibility) 조건

 $:\Theta_{2}(z)=1-\theta_{1}z-\theta_{2}z^{2}=0$ 의 두 근의 크기가 모두 1보다 커야 한다.

→ AR(2)모형의 정상성 조건과 대응된다.

$$-1 < \theta_2 < 1, \ \theta_2 + \theta_1 < 1, \ \theta_2 - \theta_1 < 1$$
 (3.40)

* MA(2)모형의 ACF

$$\rho(1) = \frac{\gamma(1)}{\gamma(0)} = \frac{(-\theta_1 + \theta_1 \theta_2)\sigma_a^2}{(1 + \theta_1^2 + \theta_2^2)\sigma_a^2} = \frac{-\theta_1 + \theta_1 \theta_2}{1 + \theta_1^2 + \theta_2^2}$$

$$\rho(2) = \frac{\gamma(2)}{\gamma(0)} = \frac{-\theta_2 \sigma_a^2}{(1 + \theta_1^2 + \theta_2^2)\sigma_a^2} = \frac{-\theta_2}{1 + \theta_1^2 + \theta_2^2}$$

$$\rho(k) = \frac{\gamma(k)}{\gamma(0)} = 0, \ k \ge 3$$

• MA(2)모형의 ACF: 시차 2에서 절단되는 형태

■ MA(2)모형의 PACF

[정리 2.3]을 사용

$$P(1) = \rho(1) = \frac{\gamma(1)}{\gamma(0)} = \frac{(-\theta_1 + \theta_1 \theta_2)\sigma_a^2}{(1 + \theta_1^2 + \theta_2^2)\sigma_a^2} = \frac{-\theta_1 + \theta_1 \theta_2}{1 + \theta_1^2 + \theta_2^2}$$

$$P(2) = \frac{\rho(2) - \rho^2(1)}{1 - \rho^2(1)}$$

$$P(3) = \frac{\rho^3(1) - 2\rho(1)\rho(2) + \rho(1)\rho^2(2)}{1 - 2\rho^2(1) + 2\rho^2(1)\rho(2) - \rho^2(2)}$$

. . .

• MA(2)모형의 PACF: 시차 k가 증가할 때 0으로 점차 감소

3.2.3 MA(q)모형

$$\begin{split} Z_t &= a_t - \theta_1 a_{t-1} - \theta_2 a_{t-2} - \ \cdots \ - \theta_q a_{t-q} \\ Z_t &= a_t - \theta_1 B a_t - \theta_2 B^2 a_t - \ \cdots \ - \theta_q B^q a_t \\ &= (1 - \theta_1 B - \theta_2 B^2 - \ \cdots \ - \theta_q B^q) a_t \\ &= \Theta_q(B) a_t \\ &= \Theta_q(B) A_t \\ & \Rightarrow \partial_q(B) = 1 - \theta_1 B - \theta_2 B^2 - \ \cdots \ - \theta_q B^q \\ & \Rightarrow \partial_q(B) = 1 - \theta_1 B - \theta_2 B^2 - \ \cdots \ - \theta_q B^q \\ & \Rightarrow \partial_q(B) = 1 - \theta_1 B - \theta_2 B^2 - \ \cdots \ - \theta_q B^q \\ & \Rightarrow \partial_q(B) = 1 - \theta_1 B - \theta_2 B^2 - \ \cdots \ - \theta_q B^q \\ & \Rightarrow \partial_q(B) = 1 - \theta_1 B - \theta_2 B^2 - \ \cdots \ - \theta_q B^q \\ & \Rightarrow \partial_q(B) = 1 - \theta_1 B - \theta_2 B^2 - \ \cdots \ - \theta_q B^q \\ & \Rightarrow \partial_q(B) = 1 - \theta_1 B - \theta_2 B^2 - \ \cdots \ - \theta_q B^q \\ & \Rightarrow \partial_q(B) = 1 - \theta_1 B - \theta_2 B^2 - \ \cdots \ - \theta_q B^q \\ & \Rightarrow \partial_q(B) = 1 - \theta_1 B - \theta_2 B^2 - \ \cdots \ - \theta_q B^q \\ & \Rightarrow \partial_q(B) = 1 - \theta_1 B - \theta_2 B^2 - \ \cdots \ - \theta_q B^q \\ & \Rightarrow \partial_q(B) = 1 - \theta_1 B - \theta_2 B^2 - \ \cdots \ - \theta_q B^q \\ & \Rightarrow \partial_q(B) = 1 - \theta_1 B - \theta_2 B^2 - \ \cdots \ - \theta_q B^q \\ & \Rightarrow \partial_q(B) = 1 - \theta_1 B - \theta_2 B^2 - \ \cdots \ - \theta_q B^q \\ & \Rightarrow \partial_q(B) = 1 - \theta_1 B - \theta_2 B^2 - \ \cdots \ - \theta_q B^q \\ & \Rightarrow \partial_q(B) = 1 - \theta_1 B - \theta_2 B^2 - \ \cdots \ - \theta_q B^q \\ & \Rightarrow \partial_q(B) = 1 - \theta_1 B - \theta_2 B^2 - \ \cdots \ - \theta_q B^q \\ & \Rightarrow \partial_q(B) = 1 - \theta_1 B - \theta_2 B^2 - \ \cdots \ - \theta_q B^q \\ & \Rightarrow \partial_q(B) = 1 - \theta_1 B - \theta_2 B^2 - \ \cdots \ - \theta_q B^q \\ & \Rightarrow \partial_q(B) = 1 - \theta_1 B - \theta_2 B^2 - \ \cdots \ - \theta_q B^q \\ & \Rightarrow \partial_q(B) = 1 - \theta_1 B - \theta_2 B^2 - \ \cdots \ - \theta_q B^q \\ & \Rightarrow \partial_q(B) = 1 - \theta_1 B - \theta_2 B^2 - \ \cdots \ - \theta_q B^q \\ & \Rightarrow \partial_q(B) = 1 - \theta_1 B - \theta_2 B^2 - \ \cdots \ - \theta_q B^q \\ & \Rightarrow \partial_q(B) = 1 - \theta_1 B - \theta_2 B^2 - \ \cdots \ - \theta_q B^q \\ & \Rightarrow \partial_q(B) = 1 - \theta_1 B - \theta_2 B^2 - \ \cdots \ - \theta_q B^q \\ & \Rightarrow \partial_q(B) = 1 - \theta_1 B - \theta_2 B^2 - \ \cdots \ - \theta_q B^q \\ & \Rightarrow \partial_q(B) = 1 - \theta_1 B - \theta_2 B^2 - \ \cdots \ - \theta_q B^q \\ & \Rightarrow \partial_q(B) = 1 - \theta_1 B - \theta_2 B^2 - \ \cdots \ - \theta_q B^q \\ & \Rightarrow \partial_q(B) = 1 - \theta_1 B - \theta_2 B^2 - \ \cdots \ - \theta_q B^q \\ & \Rightarrow \partial_q(B) = 1 - \theta_1 B - \theta_2 B^q - \ \cdots \ - \theta_q B^q \\ & \Rightarrow \partial_q(B) = 1 - \theta_1 B - \theta_2 B^q - \ \cdots \ - \theta_q B^q \\ & \Rightarrow \partial_q(B) = 1 - \theta_1 B - \theta_2 B^q - \ \cdots \ - \theta_q B^q \\ & \Rightarrow \partial_q(B) = 1 - \theta_1 B - \theta_2 B^q - \ \cdots \ - \theta_q B^q \\ & \Rightarrow \partial_q(B) = 1 - \theta_1 B - \theta_2 B^q - \ \cdots \ - \theta_q B^q$$

■ 자기공분산함수

$$\begin{split} Z_t &= a_t - \theta_1 a_{t-1} - \theta_2 a_{t-2} - \cdots - \theta_q a_{t-q} \\ Var(Z_t) &= Var(a_t - \theta_1 a_{t-1} - \theta_2 a_{t-2} - \cdots - \theta_q a_{t-q}) \\ &= Var(a_t) + \theta_1^2 Var(a_{t-1}) + \theta_2^2 Var(a_{t-2}) + \cdots + \theta_q^2 Var(a_{t-q}) \\ &= (1 + \theta_1^2 + \theta_2^2 + \cdots + \theta_q^2) Var(a_t) = (1 + \theta_1^2 + \theta_2^2 + \cdots + \theta_q^2) \sigma_a^2 \\ \gamma(0) &= (1 + \theta_1^2 + \theta_2^2 + \cdots + \theta_q^2) \sigma_a^2 \\ Z_t &= a_t - \theta_1 a_{t-1} - \theta_2 a_{t-2} - \cdots - \theta_q a_{t-q} \\ E(Z_t Z_{t-1}) \\ &= E[\left(a_t - \theta_1 a_{t-1} - \theta_2 a_{t-2} - \cdots - \theta_q a_{t-q}\right) \left(a_{t-1} - \theta_1 a_{t-2} - \theta_2 a_{t-3} - \cdots - \theta_q a_{t-q-1}\right)] \\ &= \left(-\theta_1 + \theta_2 \theta_1 + \theta_3 \theta_2 + \cdots + \theta_q \theta_{q-1}\right) \sigma_a^2 \\ \gamma(1) &= \left(-\theta_1 + \theta_2 \theta_1 + \theta_3 \theta_2 + \cdots + \theta_q \theta_{q-1}\right) \sigma_a^2 \\ Z_t &= a_t - \theta_1 a_{t-1} - \theta_2 a_{t-2} - \cdots - \theta_q a_{t-q} \\ E(Z_t Z_{t-k}) \\ &= E[\left(a_t - \theta_1 a_{t-1} - \theta_2 a_{t-2} - \cdots - \theta_q a_{t-q} + \theta_q a_{t-k-q}\right)] \\ &= \left(-\theta_k + \theta_{k+1} \theta_1 + \theta_{k+2} \theta_2 + \cdots + \theta_q \theta_{q-k}\right) \sigma_a^2, \quad (k = 1, 2, \cdots, q) \\ \gamma(k) &= 0, \quad k \geq q + 1 \end{split}$$

• 정상성 조건

$$\gamma(0) = (1 + \theta_1^2 + \theta_2^2 + \cdots + \theta_q^2)\sigma_a^2 < \infty \quad \rightarrow \quad \sum_{i=1}^q \theta_i^2 < \infty$$

• 가역성(invertibility) 조건

:
$$\Theta_q(z)=1-\theta_1z-\theta_2z^2-$$
 ··· $-\theta_qz^q=0$ 의 q 개 근 각각의 크기가 1보다 커야 한다.

* MA(q)모형의 ACF

$$\rho(k) = \begin{cases} \frac{-\theta_k + \theta_{k+1}\theta_1 + \ldots + \theta_q\theta_{q-k}}{1 + \theta_1^2 + \ldots + \theta_q^2}, & k = 1, 2, \cdots, q \\ 0, & k \ge q+1 \end{cases}$$
 (3,49)

• MA(q)모형의 ACF: 시차 q 직후 절단되는 패턴

■ MA(q)모형의 PACF

[정리 2.3]을 사용

$$\begin{split} P(1) &= \rho(1) = \frac{\gamma(1)}{\gamma(0)} = \frac{(-\theta_1 + \theta_1 \theta_2) \sigma_a^2}{\left(1 + \theta_1^2 + \theta_2^2\right) \sigma_a^2} = \frac{-\theta_1 + \theta_1 \theta_2}{1 + \theta_1^2 + \theta_2^2} \\ P(2) &= \frac{\rho(2) - \rho^2(1)}{1 - \rho^2(1)} \\ P(3) &= \frac{\rho^3(1) - 2\rho(1)\rho(2) + \rho(1)\rho^2(2)}{1 - 2\rho^2(1) + 2\rho^2(1)\rho(2) - \rho^2(2)} \end{split}$$

. . .

• MA(q)모형의 PACF: 시차 k가 증가할 때 0으로 점차 감소