

Generalizing to Arbitrary Gates

- Delay has two components: d = f + p
- f: effort delay = gh (a.k.a. stage effort)
 - Again has two components
- g: logical effort
 - Measures relative ability of gate to deliver current
 - g = 1 for inverter
- h: electrical effort = C_{out} / C_{in}
 - Ratio of output to input capacitance
 - Sometimes called fanout
- p: parasitic delay
 - Represents delay of gate driving no load
 - Set by internal parasitic capacitance

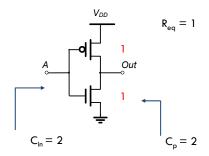
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Inverter Delay



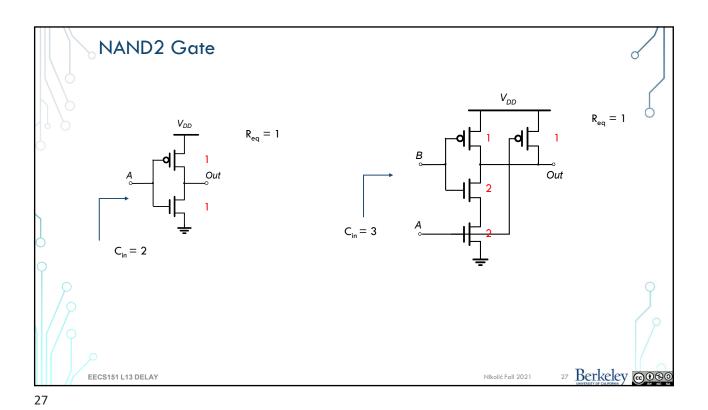
- Parasitic p is the ratio of intrinsic capacitance to an inverter
 - p(inverter) =
- Logical Effort g is the ratio of input capacitance to an inverter
 - g(inverter) =
- Electrical Effort h is the ratio of the load capacitance to the input capacitance
 - h(inverter) =
- Delay = p + f = p + g * h = 1 + f

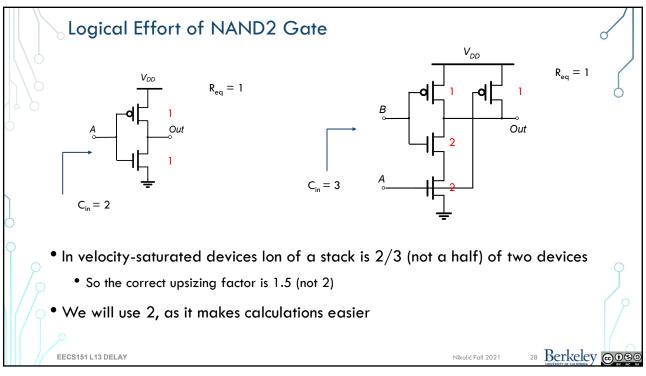
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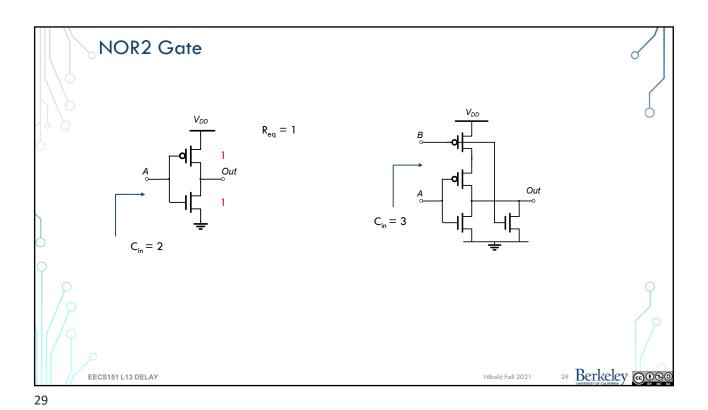
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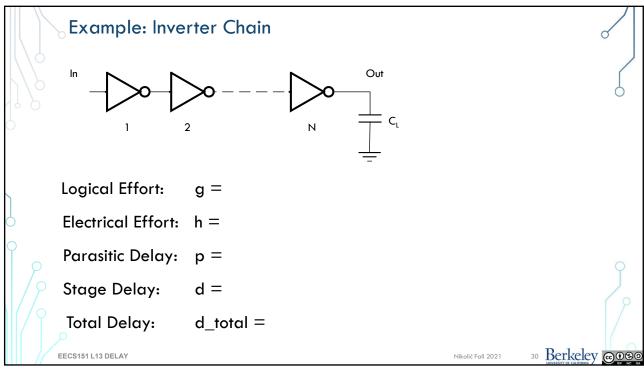
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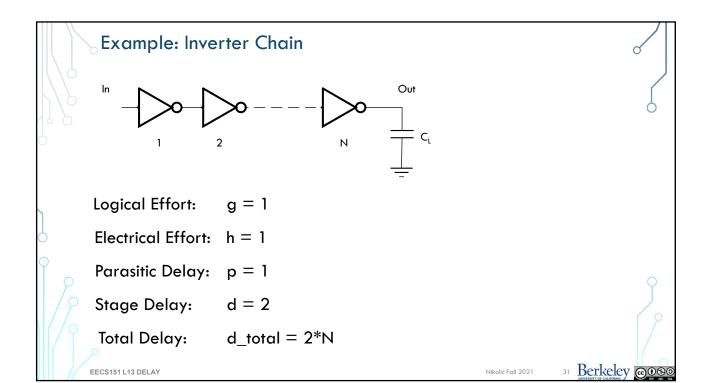
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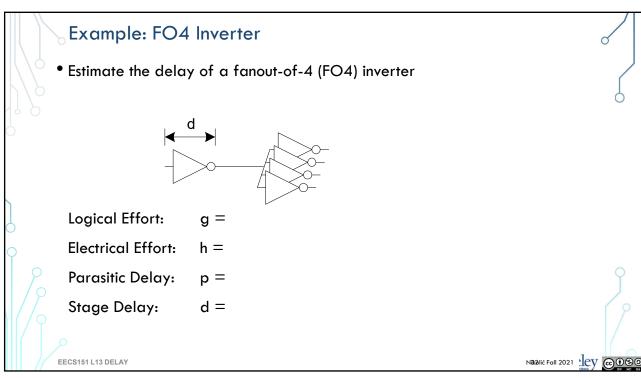






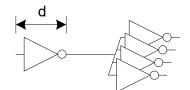






Example: FO4 Inverter

• Estimate the delay of a fanout-of-4 (FO4) inverter



Logical Effort: g = 1

Electrical Effort: h = 4

Parasitic Delay: p = 1

Stage Delay: d = 5

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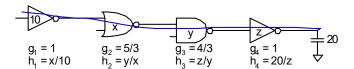
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Multi-stage Logic Networks

- Logical effort generalizes to multistage networks
- Path Logical Effort $G = \prod g_i$
- Path Electrical Effort $H = \frac{C_{\text{out-path}}}{C_{\text{in-path}}}$
- Path Effort

$$F = \prod f_i = \prod g_i h_i$$



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Branching Effect

$$b = \frac{C_{\text{on path}} + C_{\text{off path}}}{C_{\text{on path}}} \qquad B = \prod b_i$$

$$G = 1$$

$$H = 90 / 5 = 18$$

$$GH = 18$$

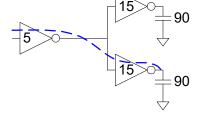
$$h_1 = (15 + 15) / 5 = 6$$

$$h_2 = 90 / 15 = 6$$

$$\mathsf{B} = 2$$

$$F = g_1g_2h_1h_2 = 36 = BGH$$

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Designing Fast Circuits

$$D = \sum d_i = D_F + P$$

• Delay is smallest when each stage bears same effort

$$\hat{f} = g_i h_i = F^{\frac{1}{N}}$$

 ${}^{\bullet}$ Thus minimum delay of N stage path is

$$D = NF^{\frac{1}{N}} + P$$

- This is a key result of logical effort
 - Find fastest possible delay
 - Doesn't require calculating gate sizes

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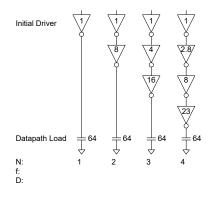
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Example: Best Number of Stages

- How many stages should a path use?
 - Minimizing number of stages is not always fastest
- Example: drive 64-bit datapath with unit inverter

$$D = NF^{1/N} + P$$
$$= N(64)^{1/N} + N$$



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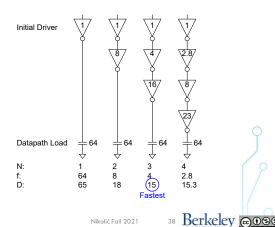
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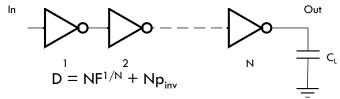
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Best Stage Effort

- How many stages should a path use?
 - To drive given capacitance



- Define best stage effort
- Neglecting parasitics (p_{inv} = 0%, $\overline{w}e^{F_{ind}^{\frac{1}{N}}}$ ρ = e = 2.718
- For $p_{inv} = 1$, solve numerically for $\rho = 3.59$
- Choose 4 less stages, less energy

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Logical Efforts Method

1) Compute path effort

- F = GBH
- 2) Estimate best number of stages
- $N = \log_4 F$
- 3) Sketch path with N stages
- $D = NF^{\frac{1}{N}} + P$

4) Estimate least delay

- $\hat{f} = F^{\frac{1}{N}}$
- 5) Determine best stage effort
- $C_{in_i} = \frac{g_i C_{out_i}}{\hat{f}}$

6) Find gate sizes

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Summary

- Delay is a linear function of R and C
- Delay optimization is critical to improve the frequency of the circuit.
- The dimensions of a transistor affect its capacitance and resistance.
- We use RC delay model to describe the delay of a circuit.
- Two delay components:
 - Parasitic delay (p)
 - Effort delay (F)
 - Logical effort (g): intrinsic complexity of the gate
 - Electrical effort (h): load capacitance dependent

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