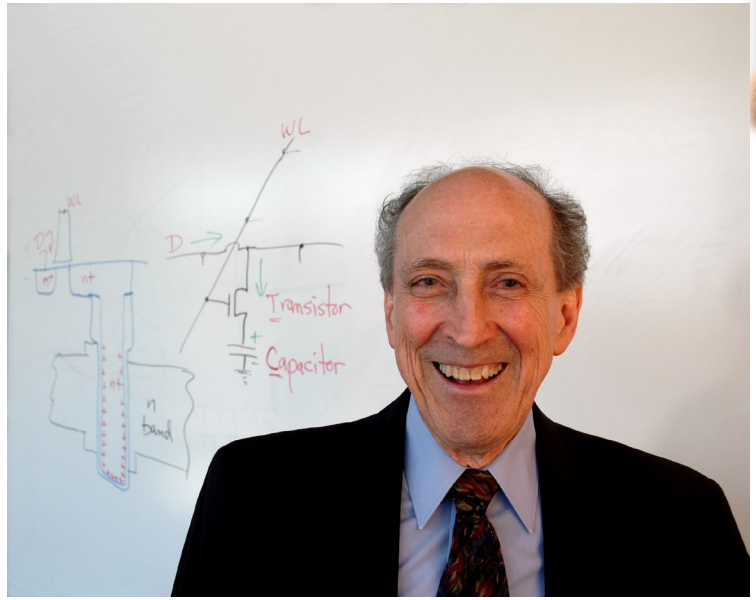
# EECS151 : Introduction to Digital Design and ICs

## Lecture 25 – Memories

Bora Nikolić

### Robert Dennard

- Invented DRAM in 1968 at IBM
- Formulate Dennard's scaling: Maintain constant power density with improved frequency/performance
- The end of Dennard's scaling leads to the inability to further increase clock frequencies and multicore processors as an alternative way to improve system performance



# Review

- Memory decoding is done hierarchically
  - Wire-limited in large arrays
  - Design by using the method of logical effort
- Larger memories can be built out of smaller blocks

# Caches

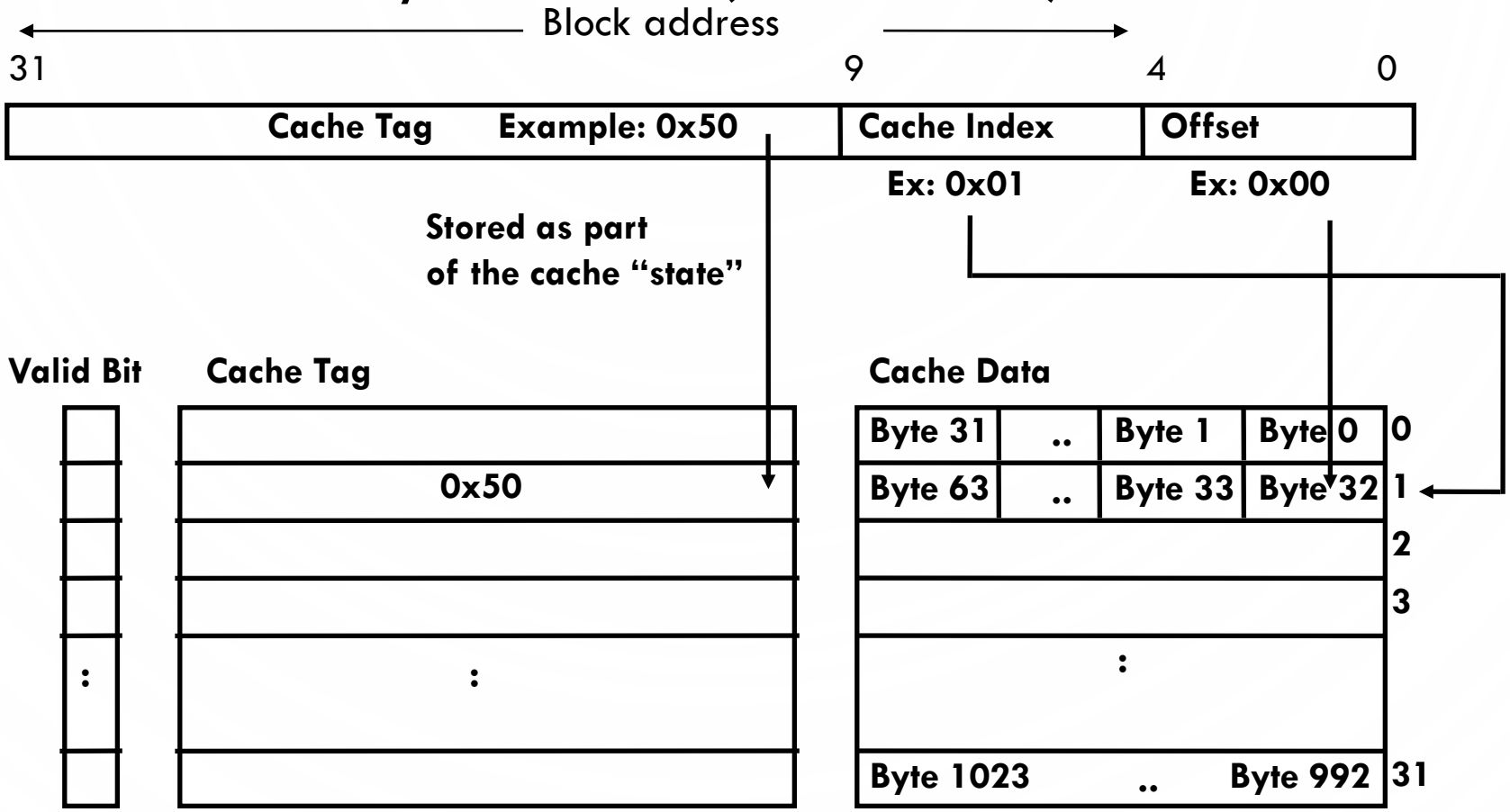
# Caches (Review from 61C)

- **Two Different Types of Locality:**
  - **Temporal locality (Locality in time): If an item is referenced, it tends to be referenced again soon.**
  - **Spatial locality (Locality in space): If an item is referenced, items whose addresses are close by tend to be referenced soon.**
- **By taking advantage of the principle of locality:**
  - **Present the user with as much memory as is available in the cheapest technology.**
  - **Provide access at the speed offered by the fastest technology.**
- **DRAM is slow but cheap and dense:**
  - **Good choice for presenting the user with a BIG memory system**
- **SRAM is fast but expensive and not as dense:**
  - **Good choice for providing the user FAST access time.**

# Example: 1 KB Direct Mapped Cache with 32-B Blocks

**For a $2^N$-byte cache:**

- **The uppermost (32 - N) bits are always the Cache Tag**
- **The lowest M bits are the byte-select offset (Block Size = $2^M$)**

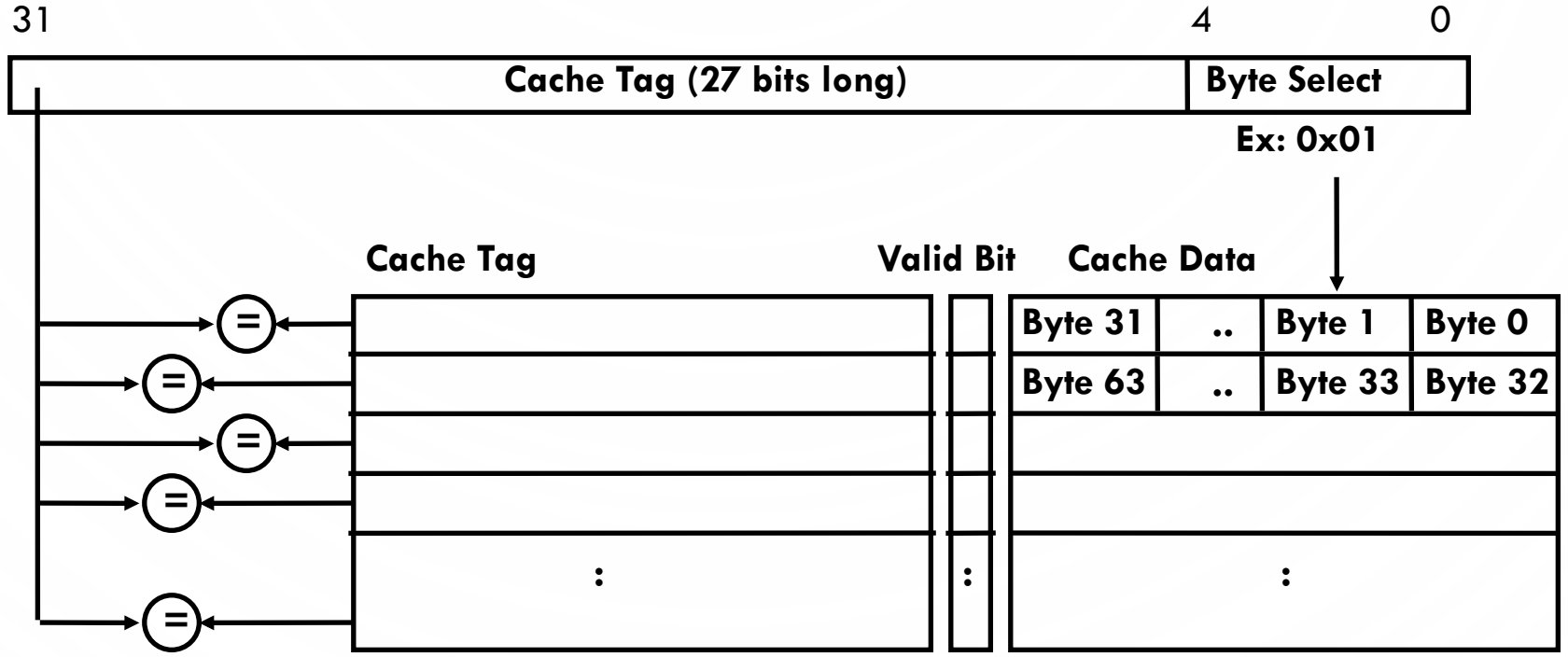


# Fully Associative Cache

## Fully Associative Cache

- Ignore cache Index for now
- Compare the Cache Tags of  all cache entries in parallel (expensive…)
- Example: Block Size = 32 B blocks, we need N 27-bit comparators

By definition: Conflict Miss = 0 for a fully associative cache



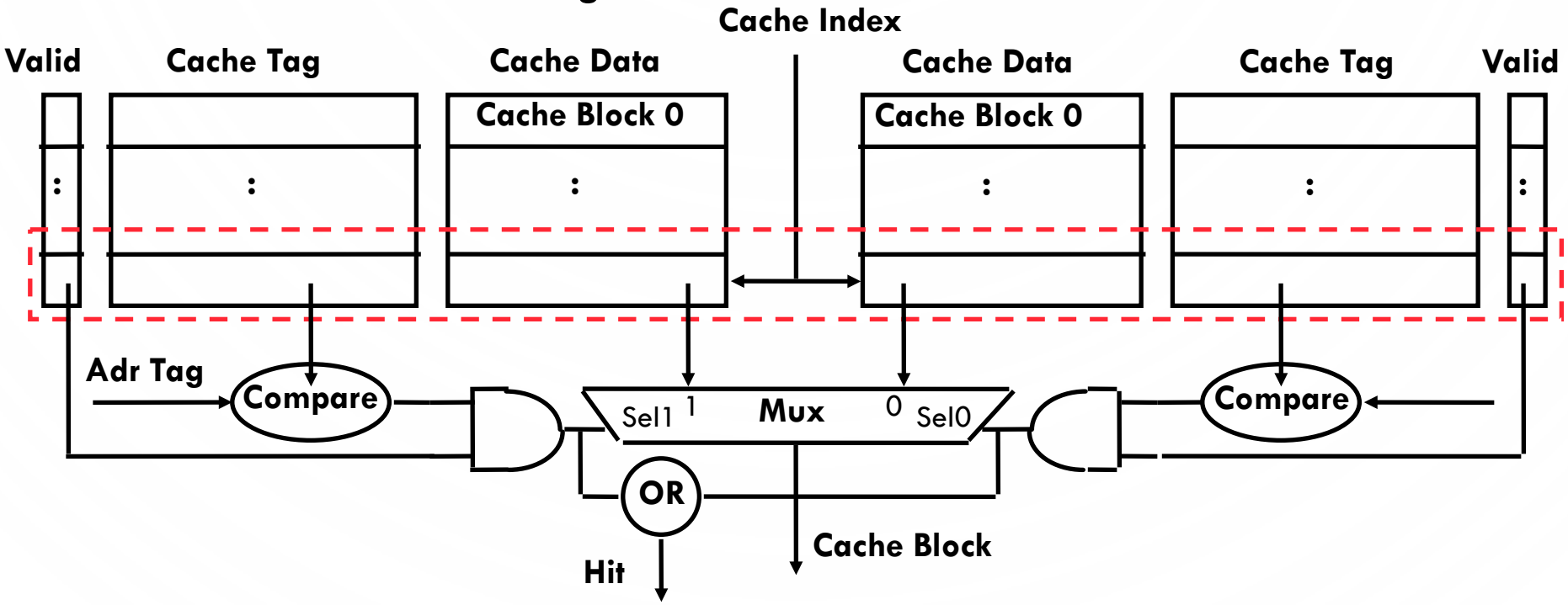
# Set Associative Cache

**N-way set associative: N entries for each Cache Index**

- N direct mapped caches operate in parallel

Example: Two-way set associative cache

- Cache Index selects a "set" from the cache
- The two tags in the set are compared to the input in parallel
- Data is selected based on the tag result



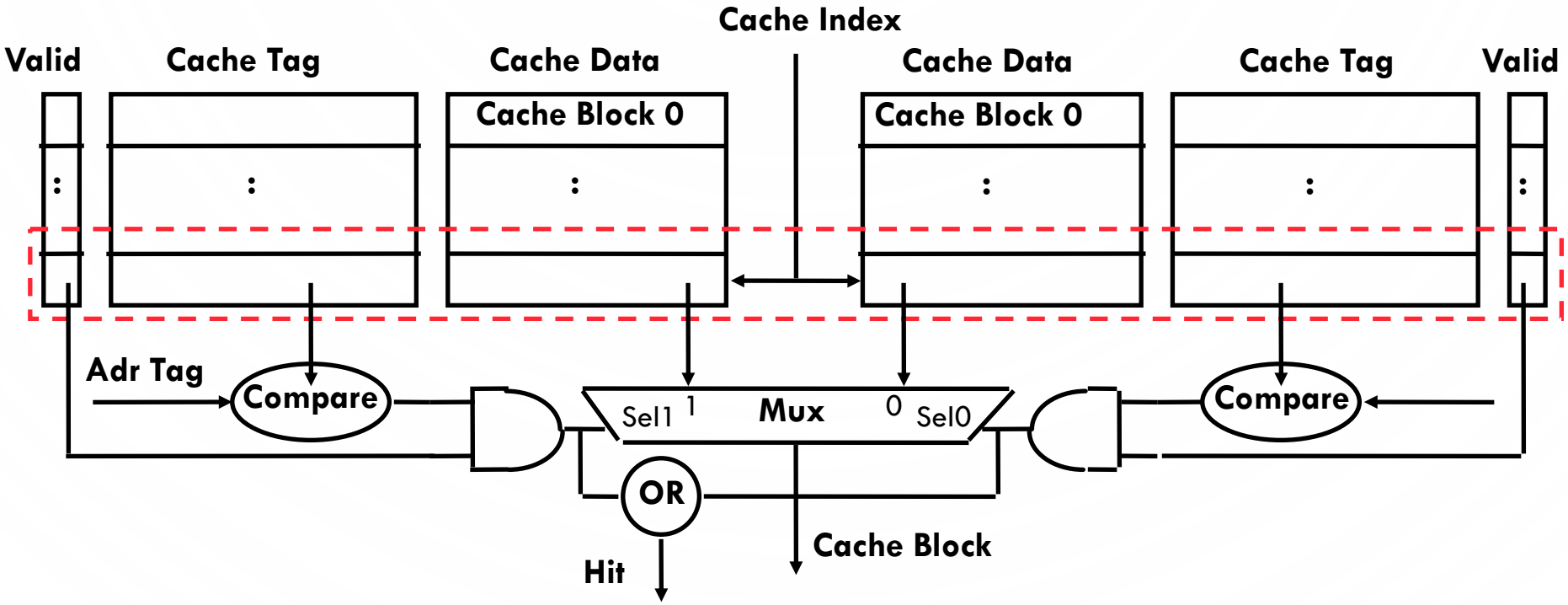
# Disadvantage of Set Associative Cache

**N-way Set Associative Cache versus Direct Mapped Cache:**

- **N comparators vs. 1**
- **Extra MUX delay for the data**
- **Data comes AFTER Hit/Miss decision and set selection**

**In a direct mapped cache, Cache Block is available BEFORE Hit/Miss:**

- **Possible to assume a hit and continue. Recover later if miss.**



# Block Replacement Policy

- Direct-Mapped Cache
  - index completely specifies position which position a block can go in on a miss
- N-Way Set Assoc
  - index specifies a set, but block can occupy any position within the set on a miss
- Fully Associative
  - block can be written into any position
- Question: if we have the choice, where should we write an incoming block?
  - If there's a valid bit off, write new block into first invalid.
  - If all are valid, pick a replacement policy
    - rule for which block gets "cached out" on a miss.

# Block Replacement Policy: LRU

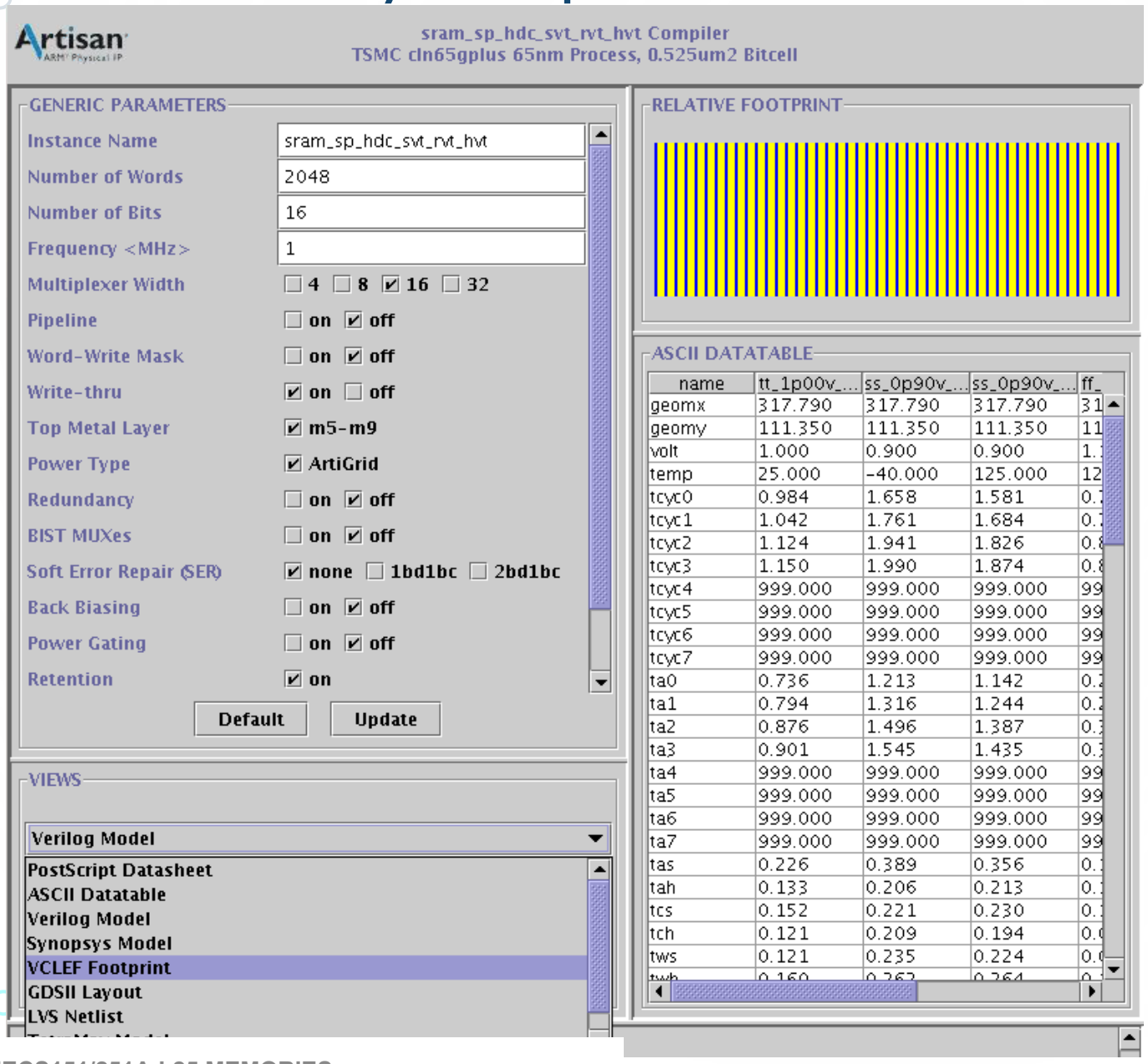
- LRU (Least Recently Used)
  - Idea: cache out block which has been accessed (read or write) least recently
  - Pro: temporal locality ➔ recent past use implies likely future use: in fact, this is a very effective policy
  - Con: with 2-way set assoc, easy to keep track (one LRU bit); with 4-way or greater, requires more complicated hardware and more time to keep track of this

# Administrivia

- Homework 10 posted on Friday, due 11/22
  - No homework during Thanksgiving
- Project checkpoints #2/#3 this week
- Next week:
  - Class lab and discussion on Monday
  - No classes/labs/discussions Tu and We

# ASIC Memories

# ASIC Memory Compilers




- Memory compiler produces front-end views (similar to standard cells, but really large ones)

# FPGA Memories

# Verilog RAM Specification

```
//
// Single-Port RAM with Asynchronous Read
//
module ramBlock (clk, we, a, di, do);
    input  clk;
    input  we;            // write enable
    input  [19:0] a;       // address
    input  [7:0] di;     // data in
    output [7:0] do;     // data out
    reg    [7:0] ram [1048575:0];  // 8x1Meg
    always @(posedge clk) begin    // Sync write
        if (we)
            ram[a] <= di;
    assign do = ram[a];            // Async read
endmodule
```

What do the synthesis tools do with this?

# Verilog Synthesis Notes (FPGAs)

- Block RAMS and LUT RAMS all exist as primitive library elements. However, it is much more convenient to **use inference**.
- Depending on how you write your Verilog, you will get either a collection of block RAMs, a collection of LUT RAMs, or a collection of flip-flops.
- The synthesizer uses size, and read style (sync versus async) to determine the best primitive type to use.
- It is possible to force mapping to a particular primitive by using synthesis directives. Ex: (* ram_style = "distributed" *) reg myReg;
- The synthesizer has limited capabilities (eg., it can combine primitives for more depth and width, but is limited on porting options). Be careful, as you might not get what you want.
- See **User Guide** for examples.
- CORE generator memory block has an extensive set of parameters for explicitly instantiated RAM blocks.

# Inferring RAMs in Verilog (FPGA)

```
// 64X1 RAM implementation using distributed RAM

module ram64X1 (clk, we, d, addr, q);
input clk, we, d;
input [5:0] addr;
output q;

    reg [63:0] temp;
    always @ (posedge clk)
          if(we)
            temp[addr] <= d;
    assign q = temp[addr];

    endmodule
```

Verilog reg array used with "always @ (posedge ... infers memory array.

Asynchronous (combinatorial) read infers LUT RAM

# Dual-read-port LUT RAM (FPGA)

```
//
// Multiple-Port RAM Descriptions
//
module v_rams_17 (clk, we, wa, ra1, ra2, di, do1, do2);
    input  clk;
    input  we;
    input  [5:0] wa;
    input  [5:0] ra1;
    input  [5:0] ra2;
    input  [15:0] di;
    output [15:0] do1;
    output [15:0] do2;
    reg    [15:0] ram [63:0];
    always @(posedge clk)
    begin
        if (we)
            ram[wa] <= di;
    end
    assign do1 = ram[ra1];
    assign do2 = ram[ra2];
endmodule
```

Multiple reference to same array.

# Block RAM Inference (FPGA)

```
//
// Single-Port RAM with Synchronous Read
//
module v_rams_07 (clk, we, a, di, do);
    input  clk;
    input  we;
    input  [5:0] a;
    input  [15:0] di;
    output [15:0] do;
    reg    [15:0] ram [63:0];
    reg    [5:0] read_a;
    always @(posedge clk) begin
        if (we)
            ram[a] <= di;
        read_a <= a;
    end
    assign do = ram[read_a];
endmodule
```

Synchronous read (registered read address) infers Block RAM

# FPGA Block RAM initialization (FPGA)

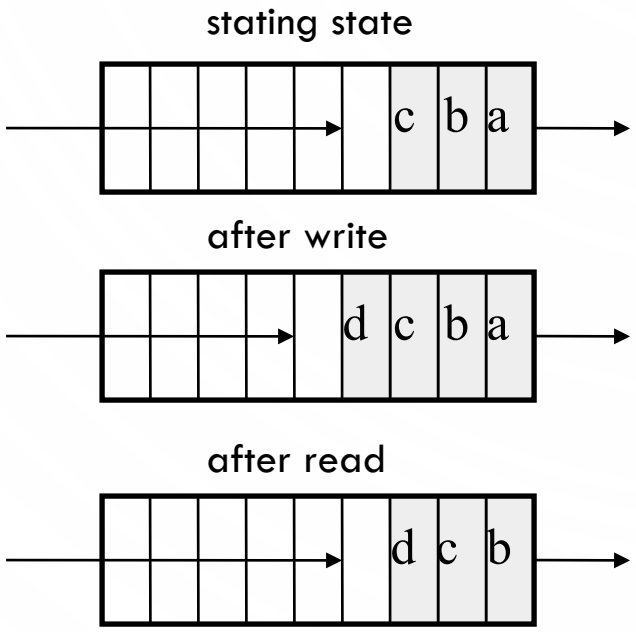
```
module RAMB4_S4 (data_out, ADDR, data_in, CLK, WE);
    output[3:0] data_out;
    input [2:0] ADDR;
    input [3:0] data_in;
    input CLK, WE;
    reg [3:0] mem [7:0];
    reg [3:0] read_addr;

    initial
      begin
        $readmemb("data.dat", mem);
      end

    always@(posedge CLK)
      read_addr <= ADDR;

    assign data_out = mem[read_addr];

    always @(posedge CLK)
      if (WE) mem[ADDR] = data_in;

    endmodule
```

"data.dat" contains initial RAM contents, it gets put into the bitfile and loaded at configuration time.
(Remake bits to change contents)

# FIFOs

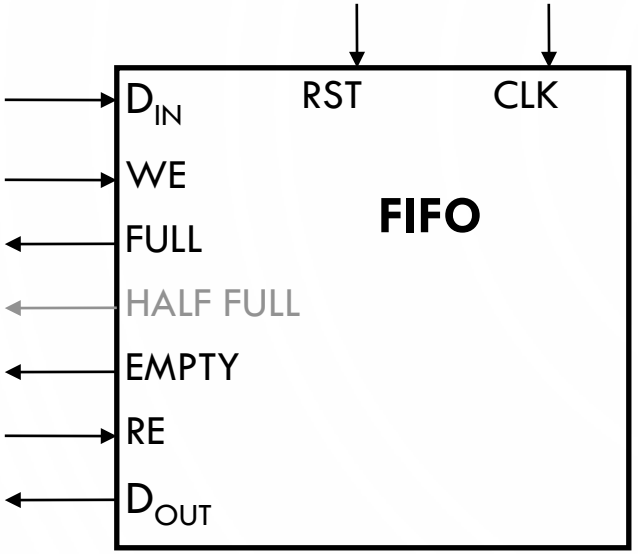
# First-in-first-out (FIFO) Memory

- Used to implement *queues*.
- These find common use in processor and communication circuits.
- Generally, used to "decouple" actions of producer and consumer:



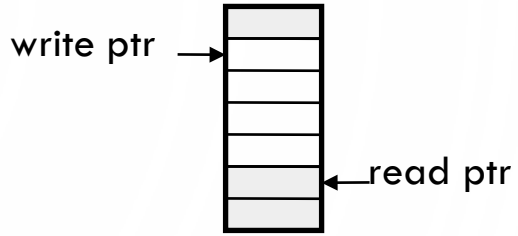

- Producer can perform many writes without consumer performing any reads (or vice versa). However, because of finite buffer size, on average, need equal number of reads and writes.
- Typical uses:
  - interfacing I/O devices. Example network interface. Data bursts from network, then processor bursts to memory buffer (or reads one word at a time from interface). Operations not synchronized.
  - Example: Audio output. Processor produces output samples in bursts (during process swap-in time). Audio DAC clocks it out at constant sample rate.

# FIFO Interfaces

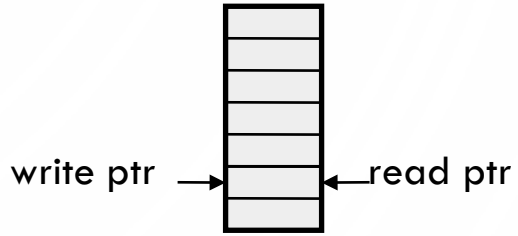



- After write or read operation, FULL and EMPTY indicate status of buffer.
- Used by external logic to control own reading from or writing to the buffer.
- FIFO resets to EMPTY state.
- HALF FULL (or other indicator of partial fullness) is optional.

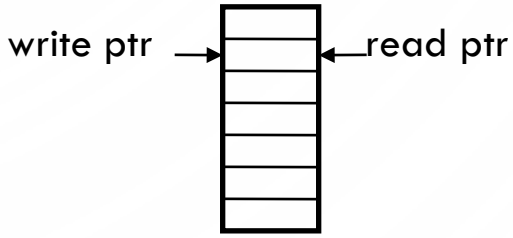
- Address pointers are used internally to keep next write position and next read position into a dual-port memory.




- If pointers equal after write ⇒ FULL:



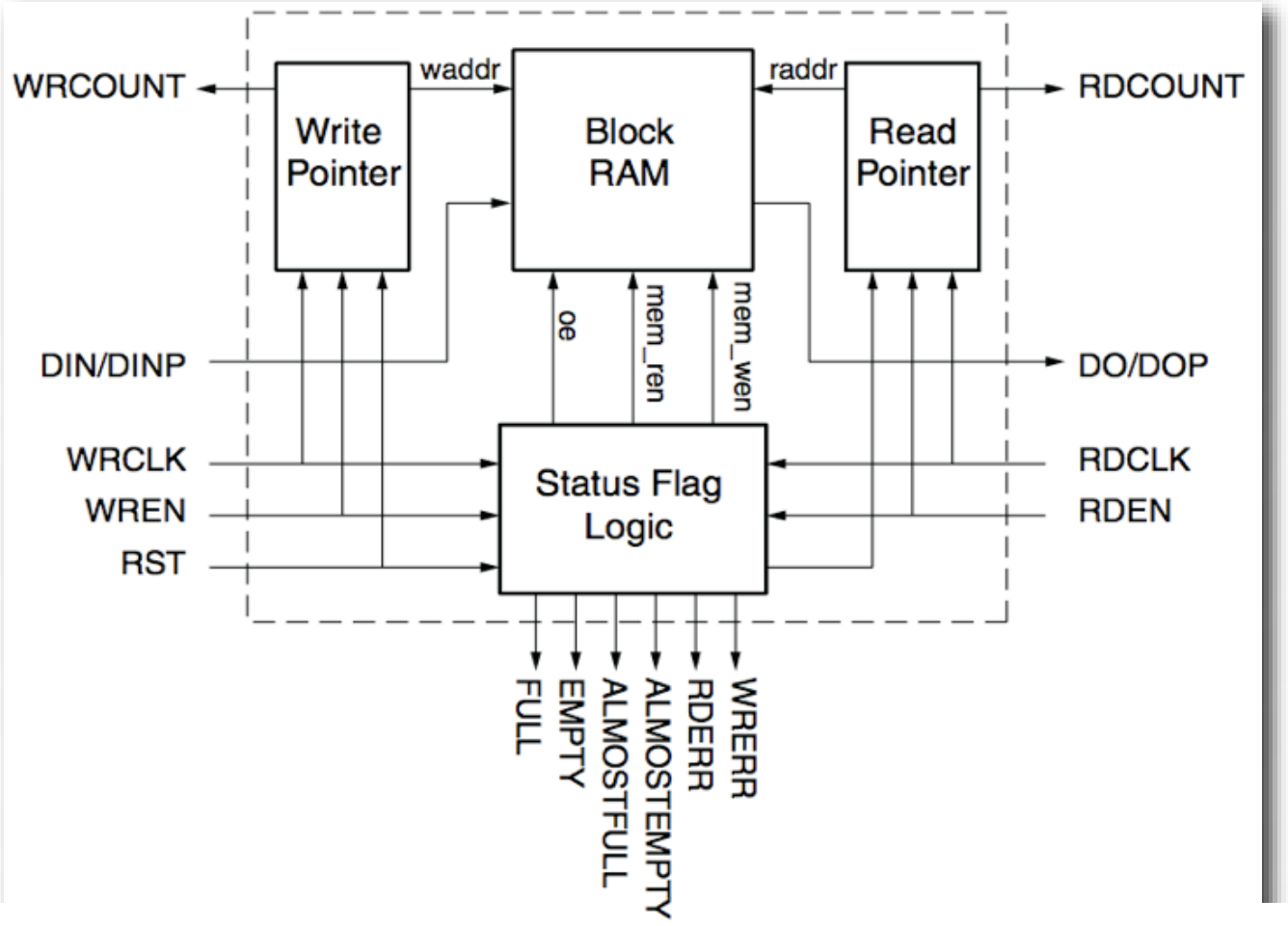

- If pointers equal after read ⇒ EMPTY:




Note: Pointer incrementing is done "mod size-of-buffer"

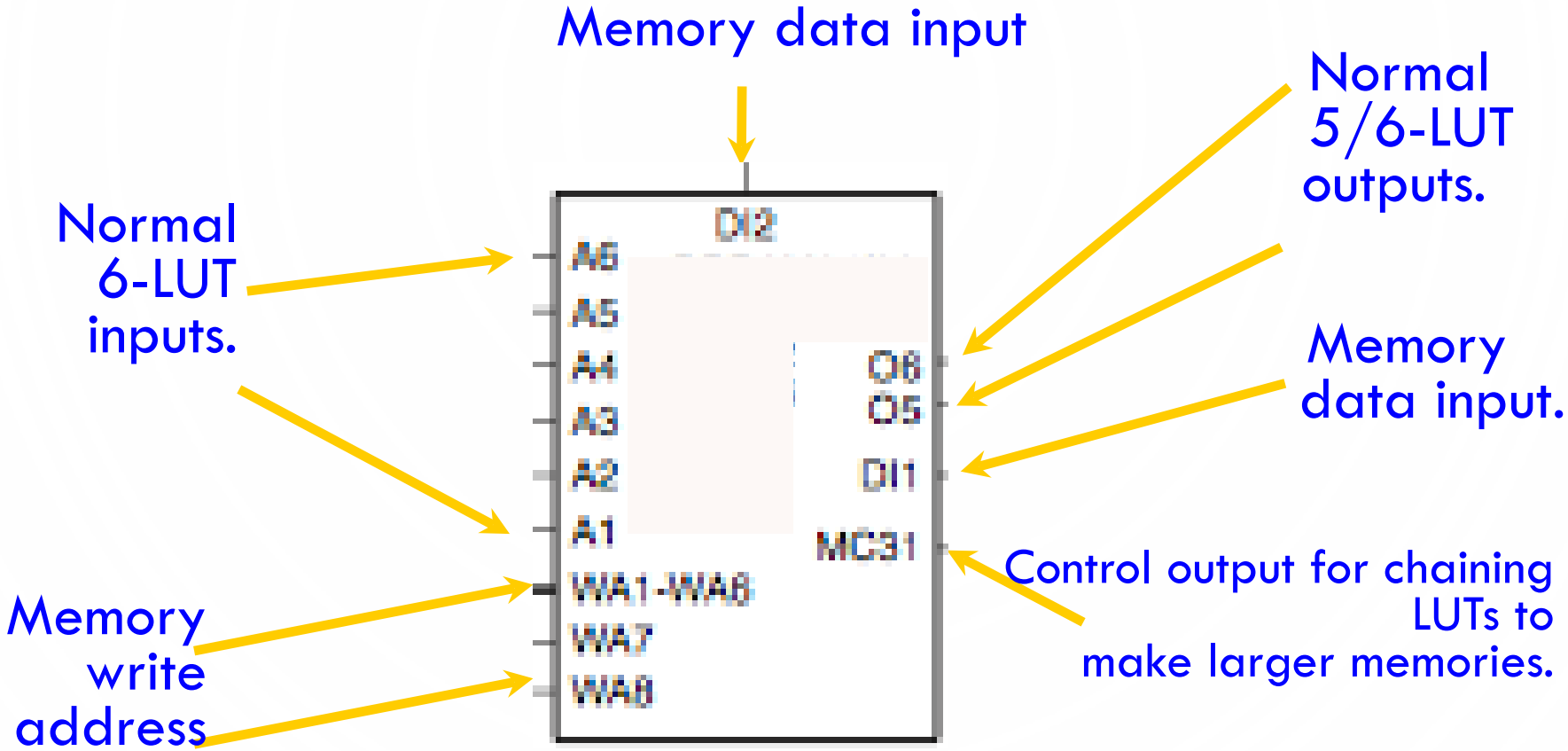
# Xilinx Virtex5 FIFOs

- Virtex5 BlockRAMS include dedicated circuits for FIFOs.
- Details in User Guide (ug190).
- Takes advantage of separate dual ports and independent ports clocks.



# FPGA Memory Blocks

# A SLICEM 6-LUT ...

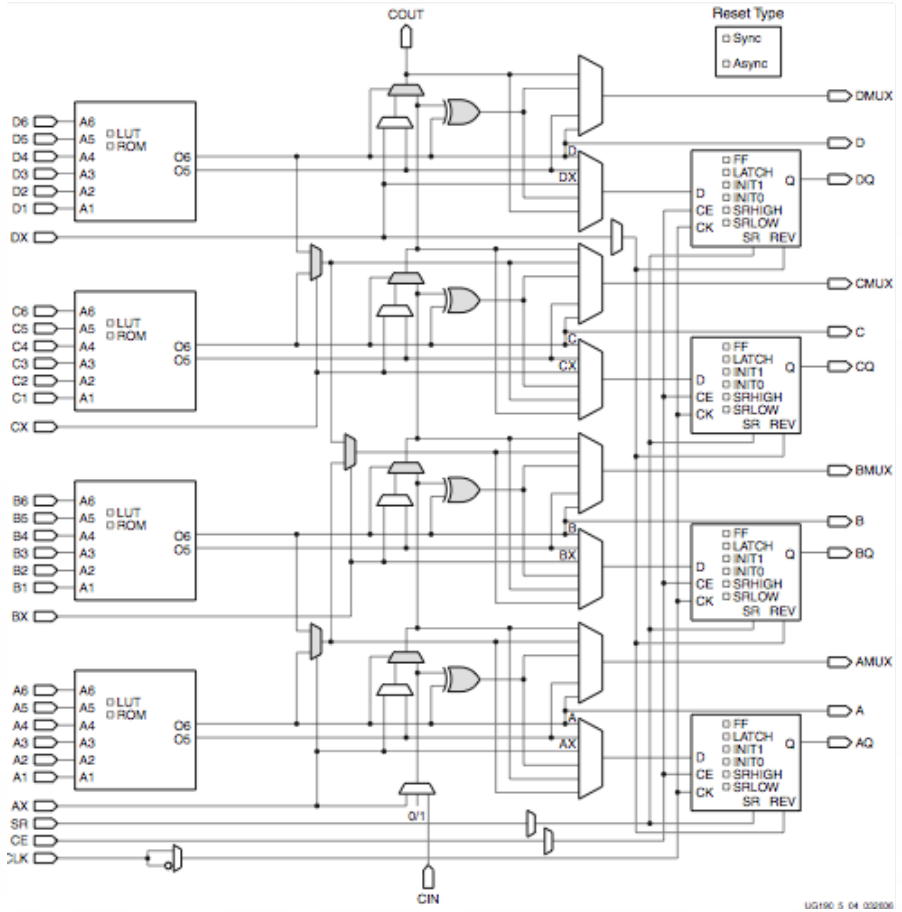



Synchronous write / asychronous read

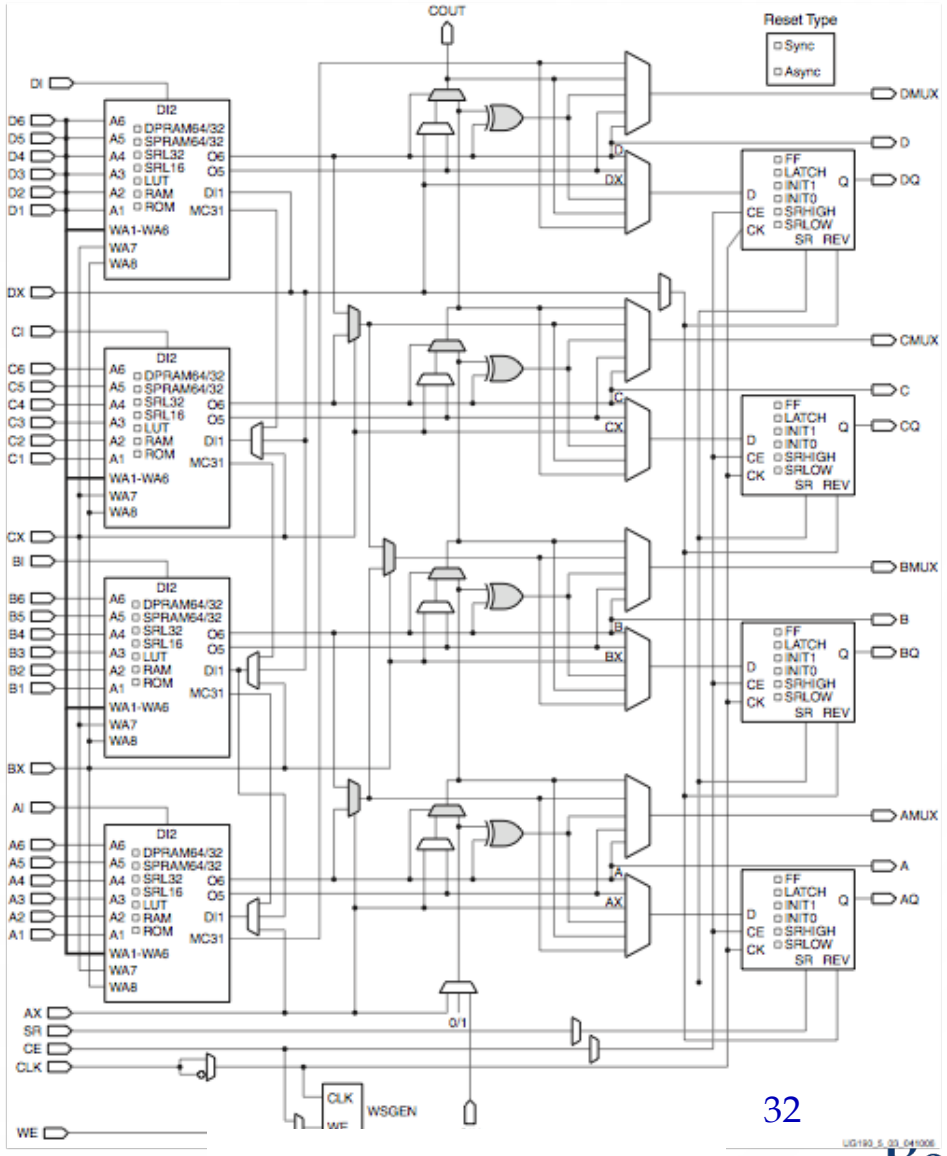
A 1.1 Mb distributed RAM can be made if all SLICEMs of an LX110T are used as RAM.

# SLICEL vs SLICEM ...

## SLICEL




## SLICEM




SLICEM adds memory features to LUTs, + muxes.

# Example Distributed RAM (LUT RAM)

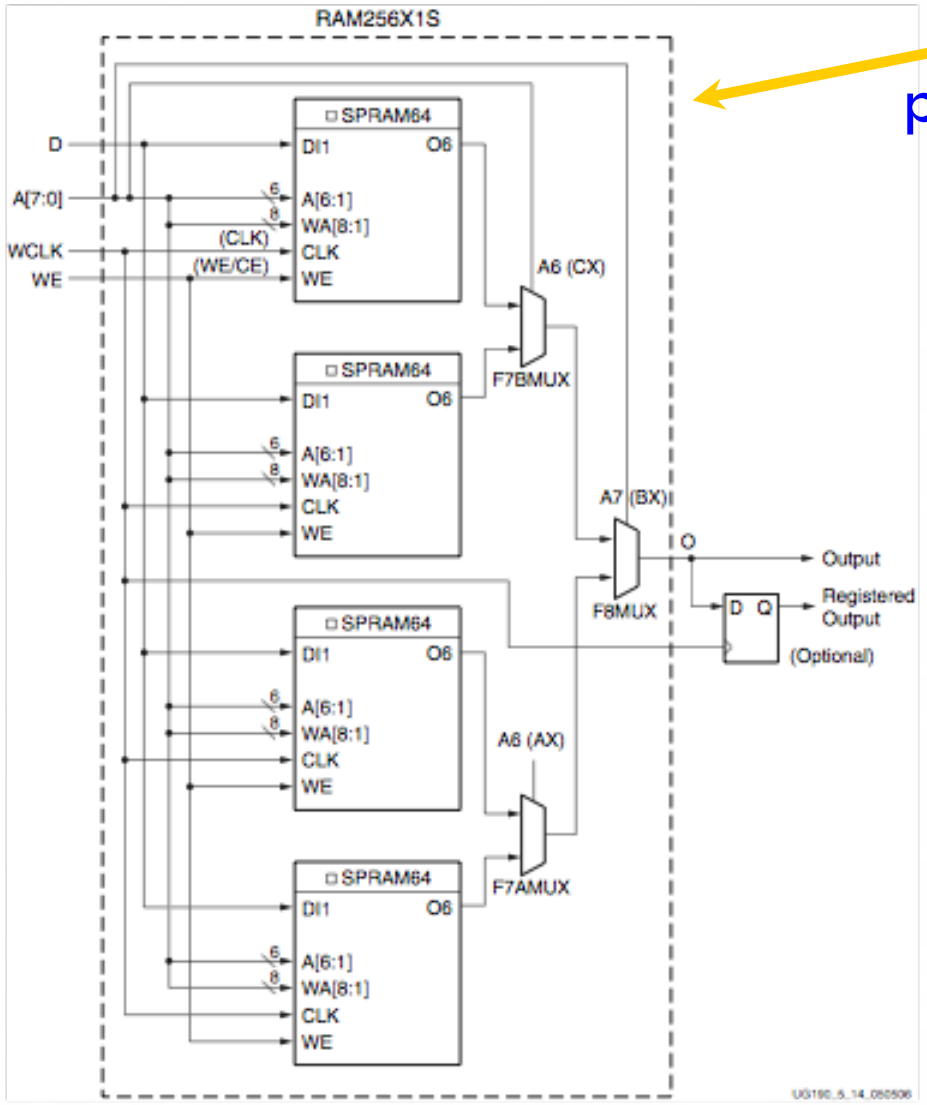
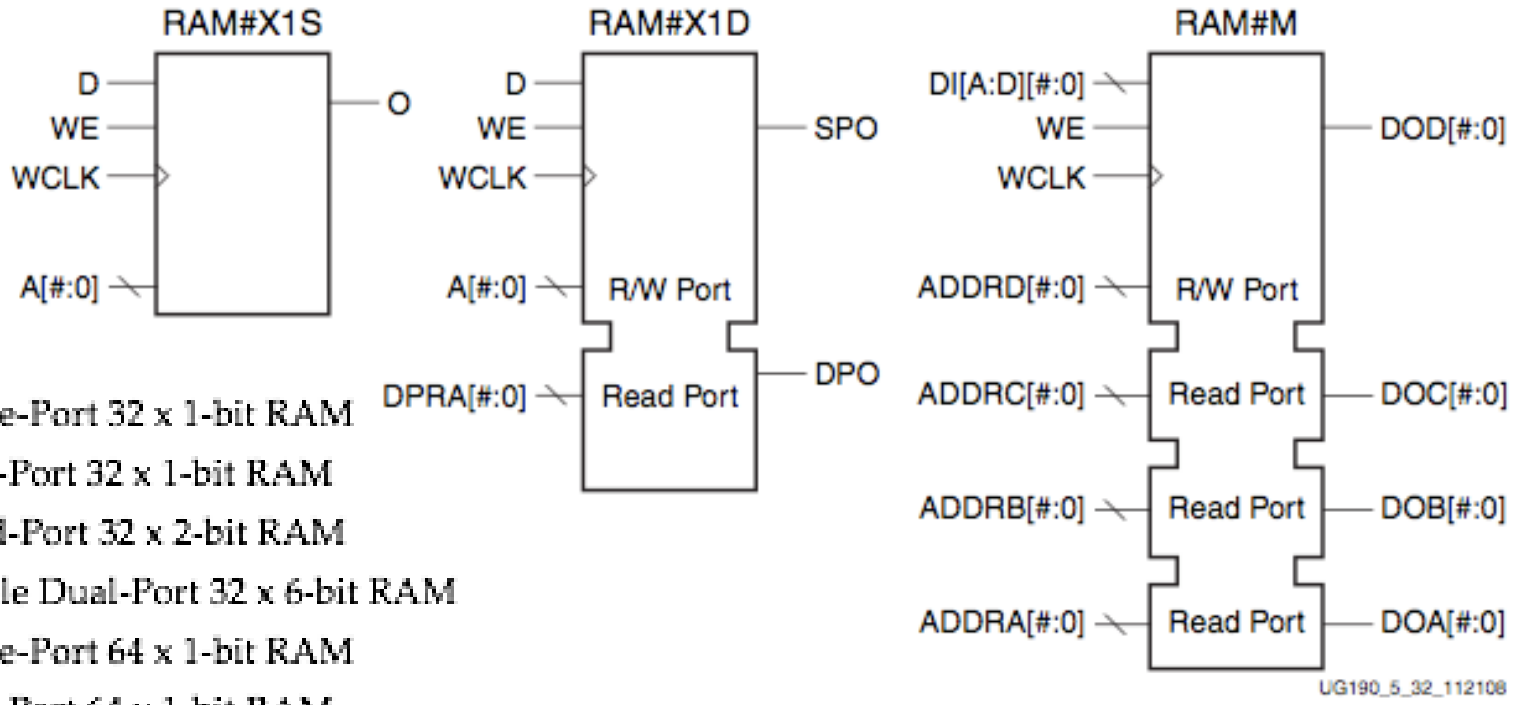



*Figure 5-14:* **Distributed RAM (RAM256X1S)**

Example configuration: Single-port 256b x 1, registered output.

# Distributed RAM Primitives

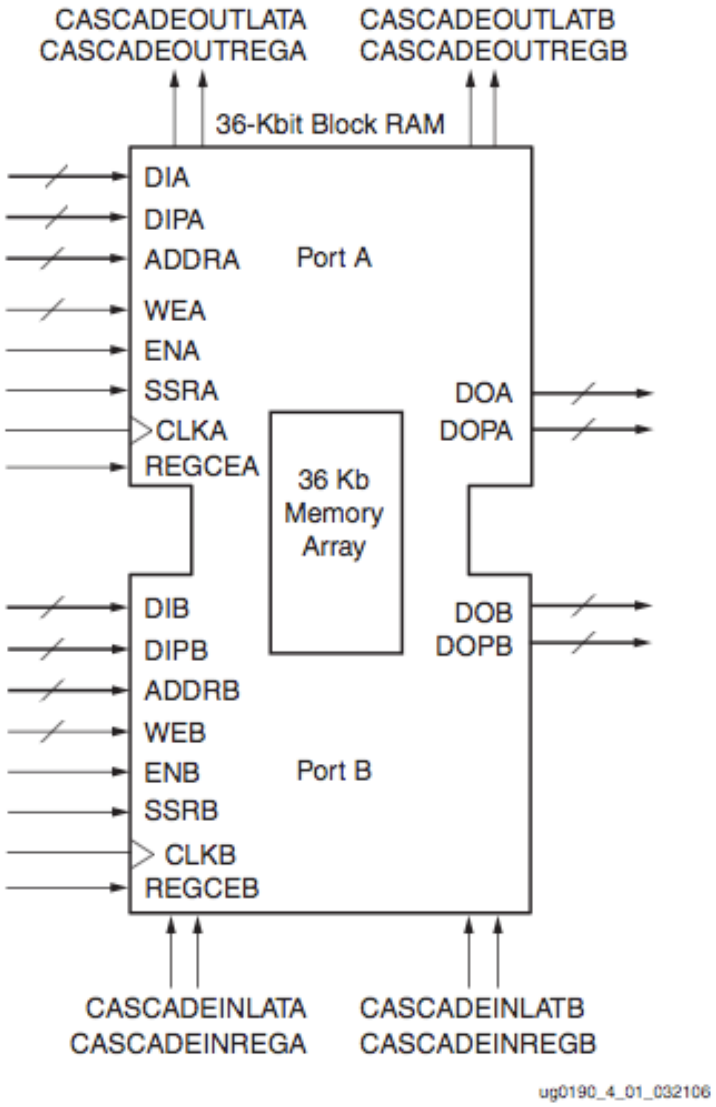



- Single-Port 32 x 1-bit RAM
- Dual-Port 32 x 1-bit RAM
- Quad-Port 32 x 2-bit RAM
- Simple Dual-Port 32 x 6-bit RAM
- Single-Port 64 x 1-bit RAM
- Dual-Port 64 x 1-bit RAM
- Quad-Port 64 x 1-bit RAM
- Simple Dual-Port 64 x 3-bit RAM
- Single-Port 128 x 1-bit RAM
- Dual-Port 128 x 1-bit RAM
- Single-Port 256 x 1-bit RAM

All are built from a single slice or less.

Remember, though, that the SLICEM LUT is naturally only 1 read and 1 write port.

# Block RAM Overview




- 36K bits of data total, can be configured as:
  - 2 independent 18Kb RAMs, or one 36Kb RAM.
- Each 36Kb block RAM can be configured as:
  - 64Kx1 (when cascaded with an adjacent 36Kb block RAM), 32Kx1, 16Kx2, 8Kx4, 4Kx9, 2Kx18, or 1Kx36 memory.
- Each 18Kb block RAM can be configured as:
  - 16Kx1, 8Kx2, 4Kx4, 2Kx9, or 1Kx18 memory.
- Write and Read are synchronous operations.
- The two ports are symmetrical and totally independent (can have different clocks), sharing only the stored data.
- Each port can be configured in one of the available widths, independent of the other port. The read port width can be different from the write port width for each port.
- The memory content can be initialized or cleared by the configuration bitstream.

# UltraRAM Blocks

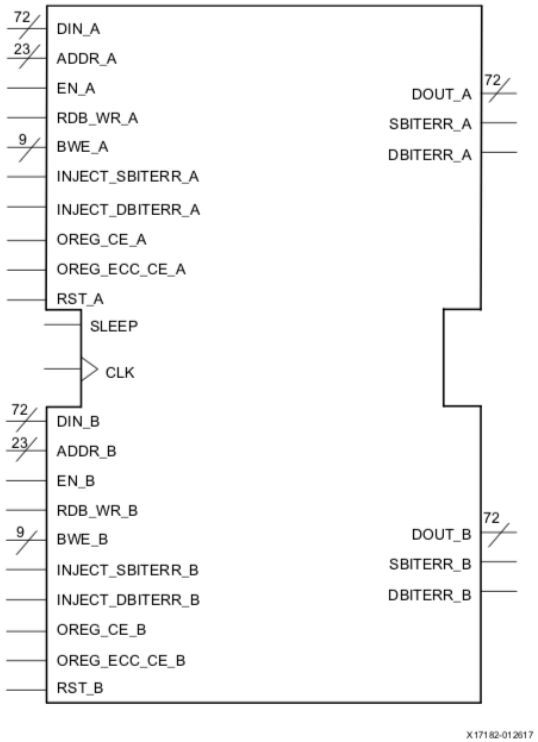


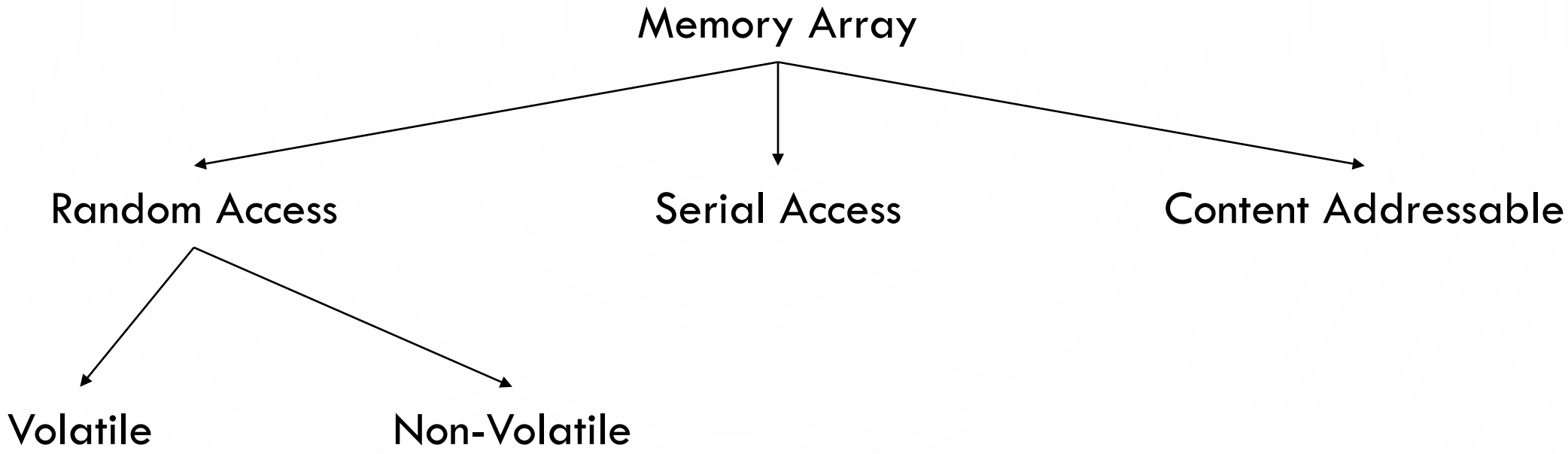

*Figure 2-1:* **UltraRAM URAM288_BASE Primitive**

*Table 2-1:* **Block RAM and UltraRAM Comparison**

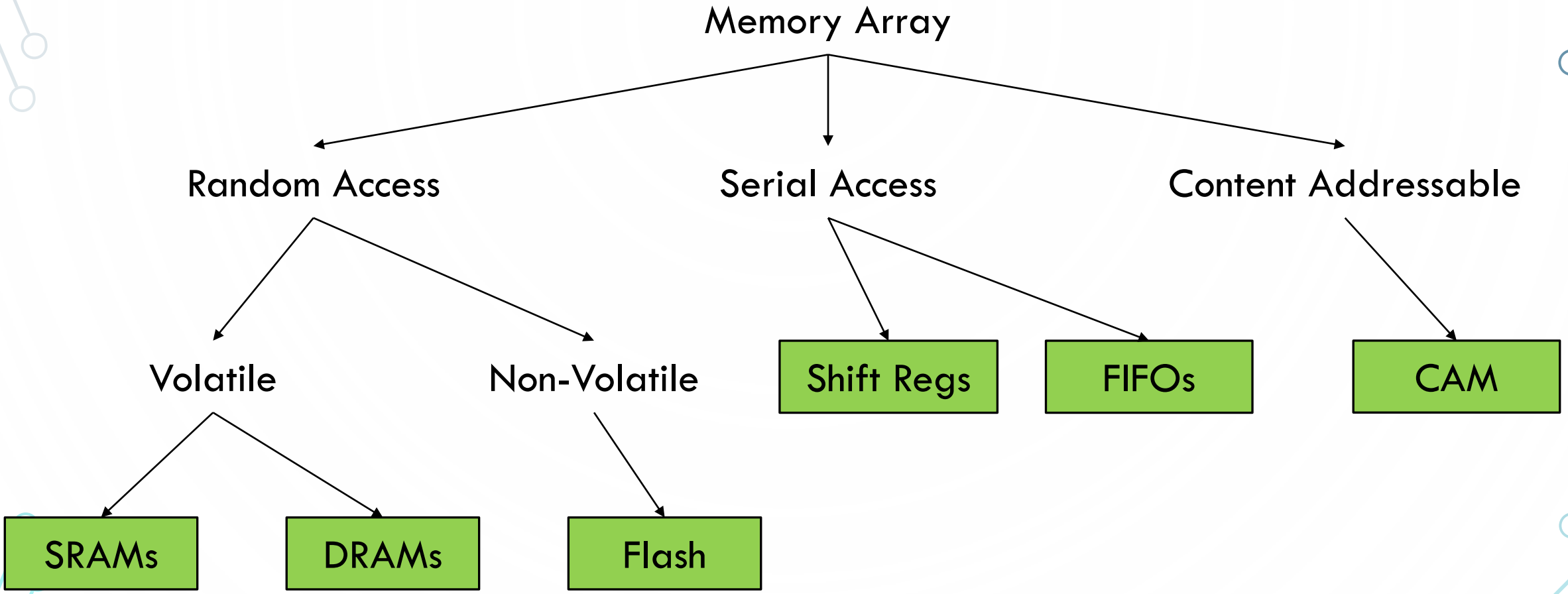
| Feature | Block RAM | UltraRAM |
|---|---|---|
| Clocking | Two clocks | Single clock |
| Built-in FIFO | Yes | No |
| Data width | Configurable (1, 2, 4, 9, 18, 36, 72) | Fixed (72-bits) |
| Modes | SDP and TDP | Two ports, each can independently read or write (a superset of SDP) |
| ECC | 64-bit SECDED<br>Supported in 64-bit SDP only (one ECC decoder for port A and one ECC encoder for port B) | 64-bit SECDED<br>One set of complete ECC logic for each port to enable independent ECC operations (ECC encoder and decoder for both ports) |
| Cascade | • Cascade output only (input cascade implemented via logic resources)<br>• Cascade within a single clock region | • Cascade both input and output (with global address decoding)<br>• Cascade across clock regions in a column<br>• Cascade across several columns with minimal logic resources |
| Power savings | One mode via manual signal assertion | One mode via manual signal assertion |

# DRAM

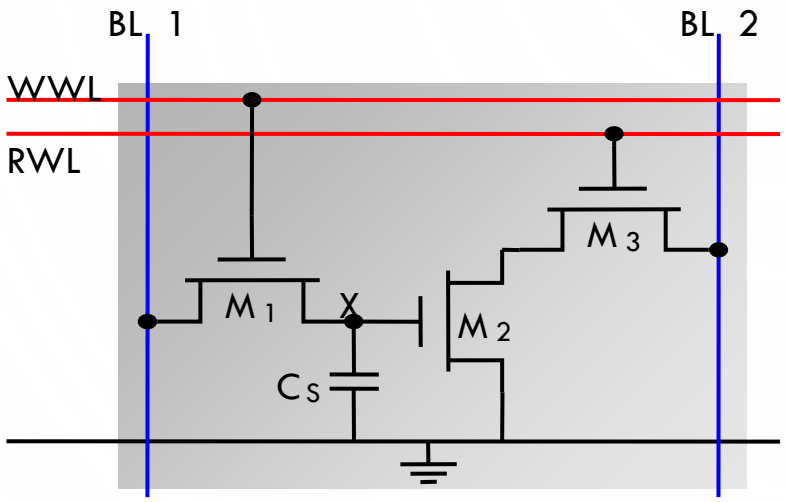
# Memory Overview

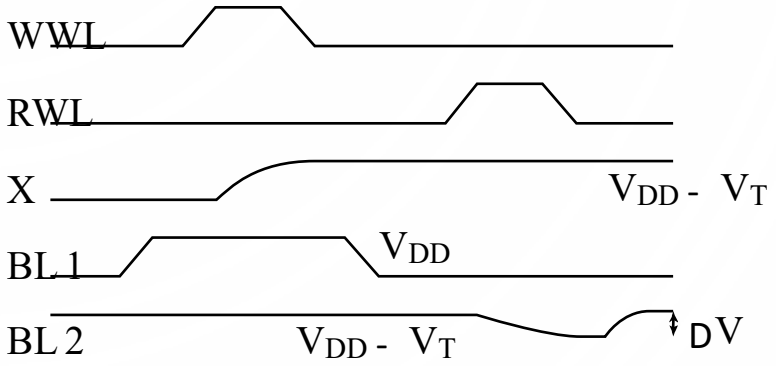


# Memory Overview



# 3-Transistor DRAM Cell

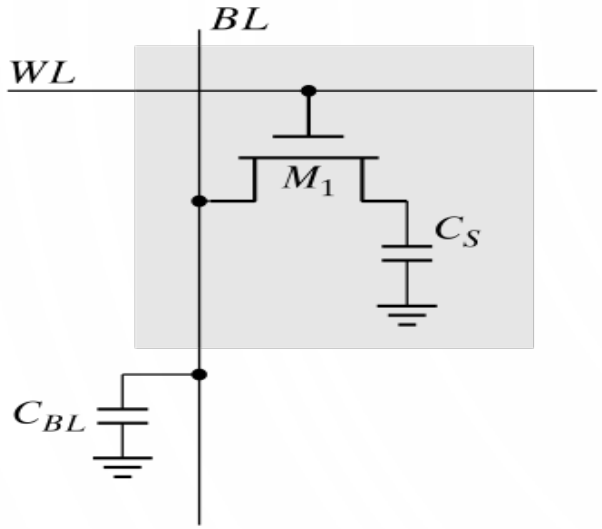


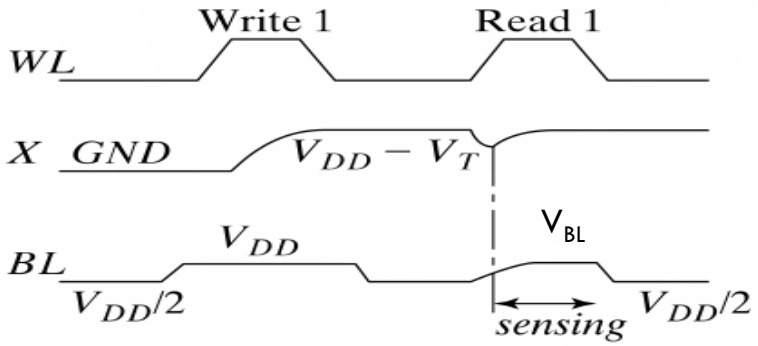




No constraints on device ratios
Reads are non-destructive
Value stored at node X when writing a "1" = $V_{WWL} - V_{Th}$

Can work with a logic IC process

# 1-Transistor DRAM Cell

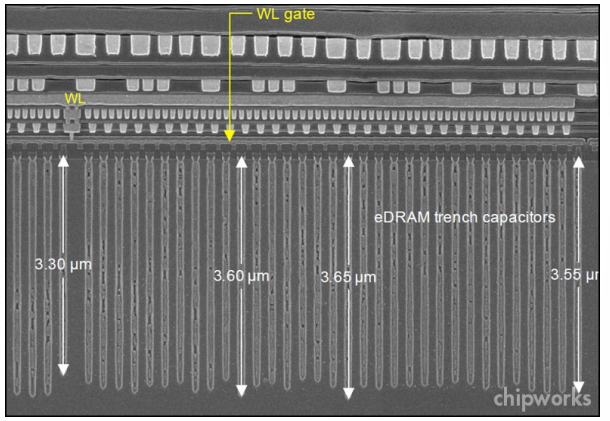


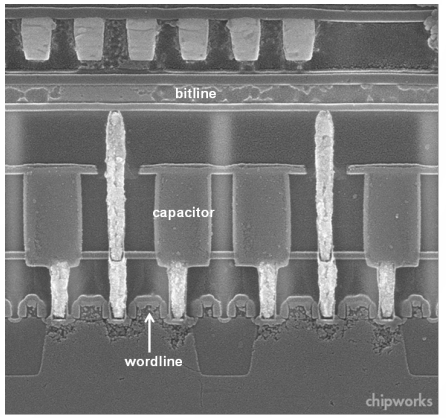

$V_{BIT}$= 0 or ($V_{DD} - V_T$)

Write: $C_S$ is charged or discharged by asserting WL and BL.
Read: Charge redistribution takes places between bit line and storage capacitance

$C_S << C_{BL}$ Voltage swing is small; typically hundreds of mV.




IBM Power 7+




XBOX GPU (TSMC)

Chipworks

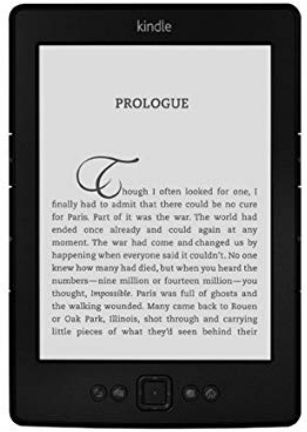
- To get sufficient $C_s$, special IC process is used
- Cell reading is destructive, therefore read operation always is followed by a write-back
- Cell looses charge (leaks away in ms - highly temperature dependent), therefore cells occasionally need to be “refreshed” - read/write cycle

# Flash

# Flash Memory

- Non-volatile memory

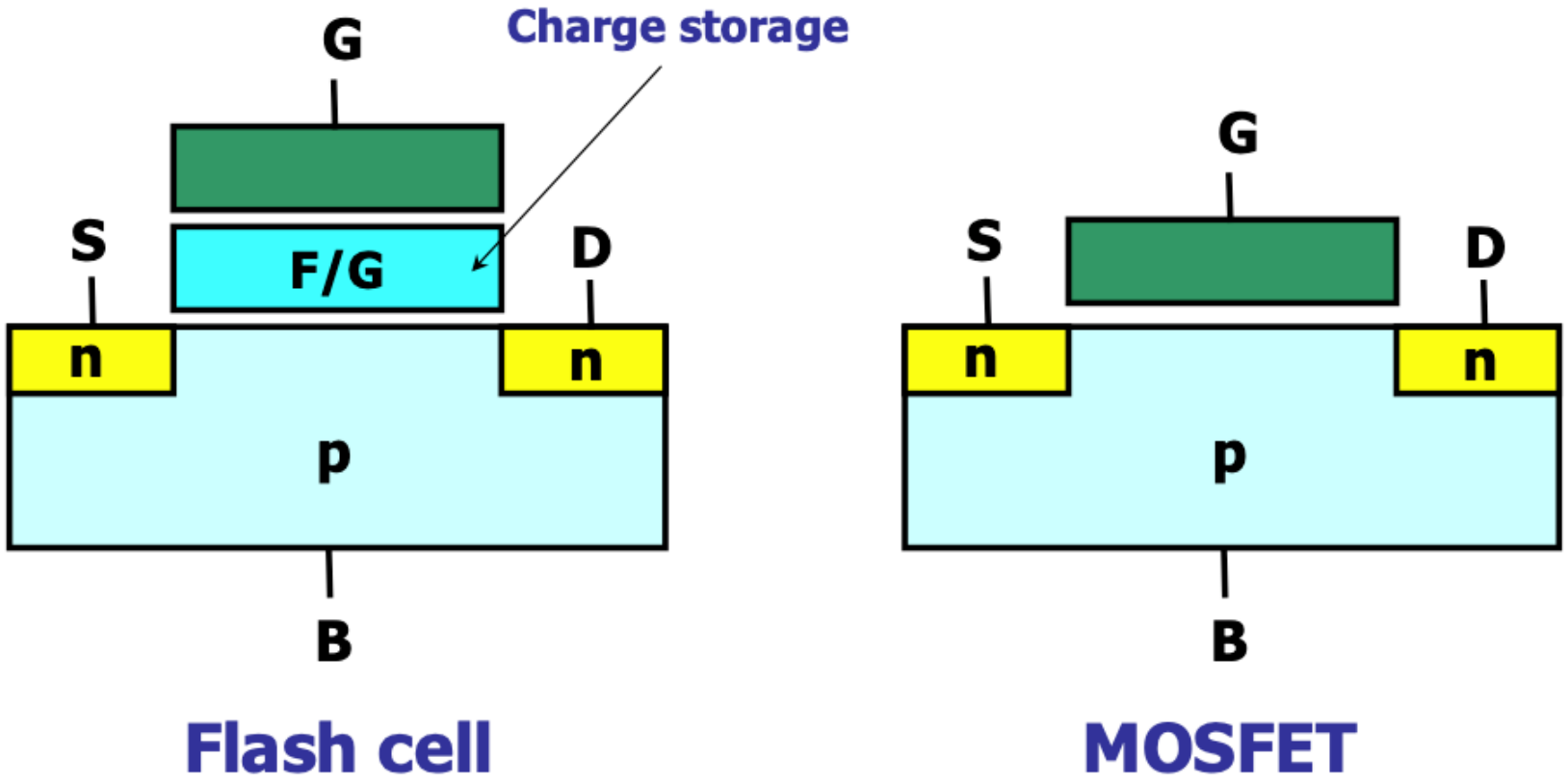




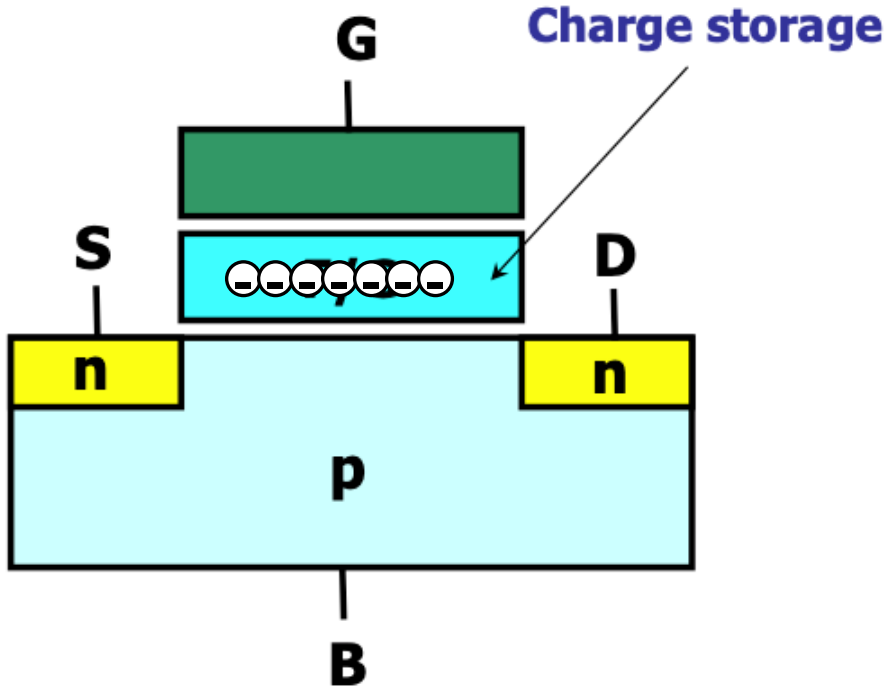


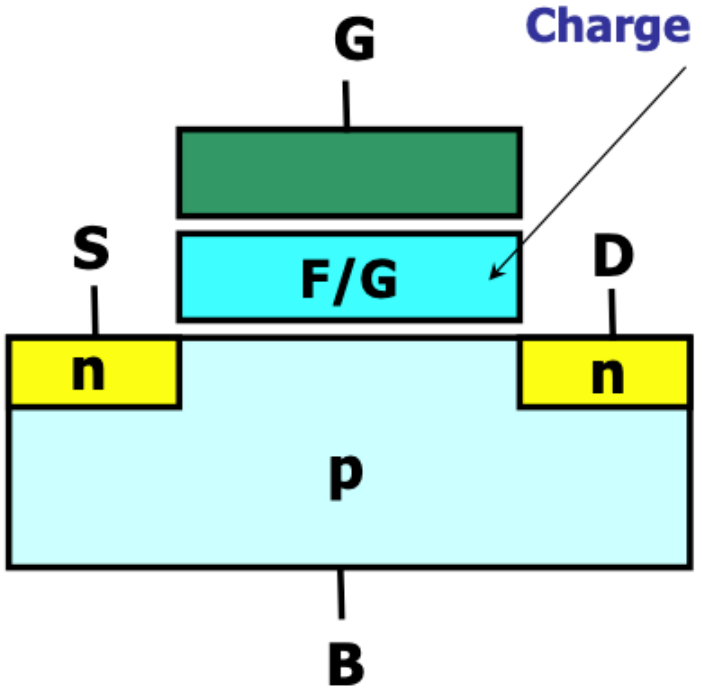
# Key concept: Floating Gate

- Floating Gate: A charge storage layer -> memorize information
- A "Programmable-Threshold" Transistor



# Single-Level Cell: 0 and 1 in Flash

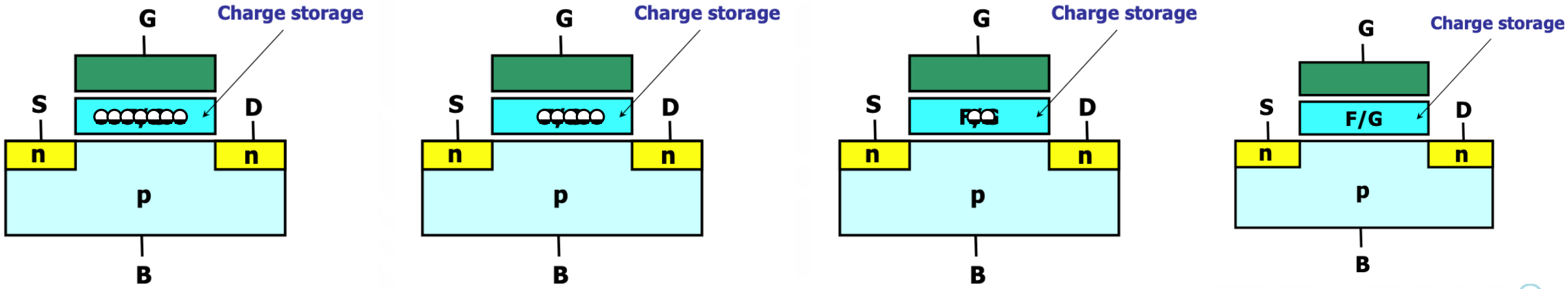



- Storing 0
- Negative charge in floating gate

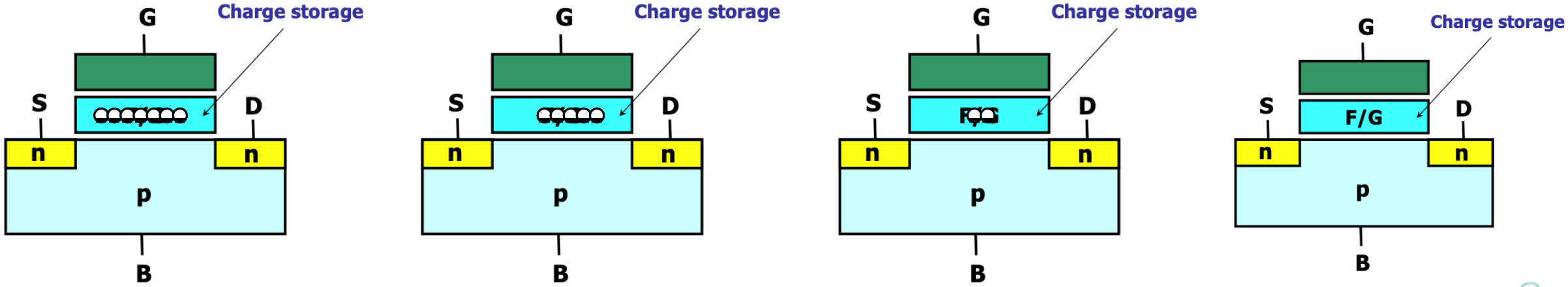
- Storing 1
- No charge in floating gate

# Multi-Level Cell



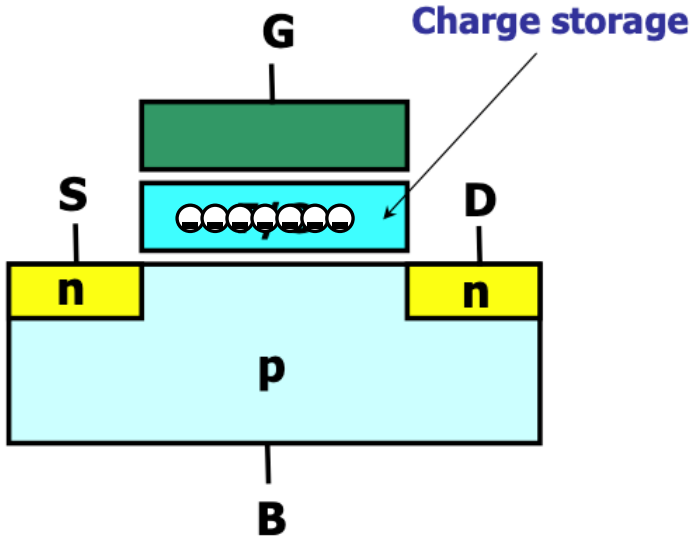
# Multi-Level Cell

- Higher density
- Errors more likely

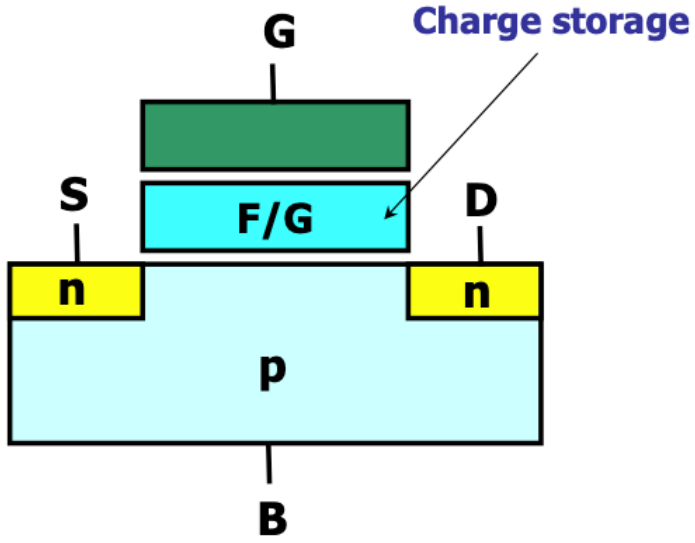


# Read a Flash cell

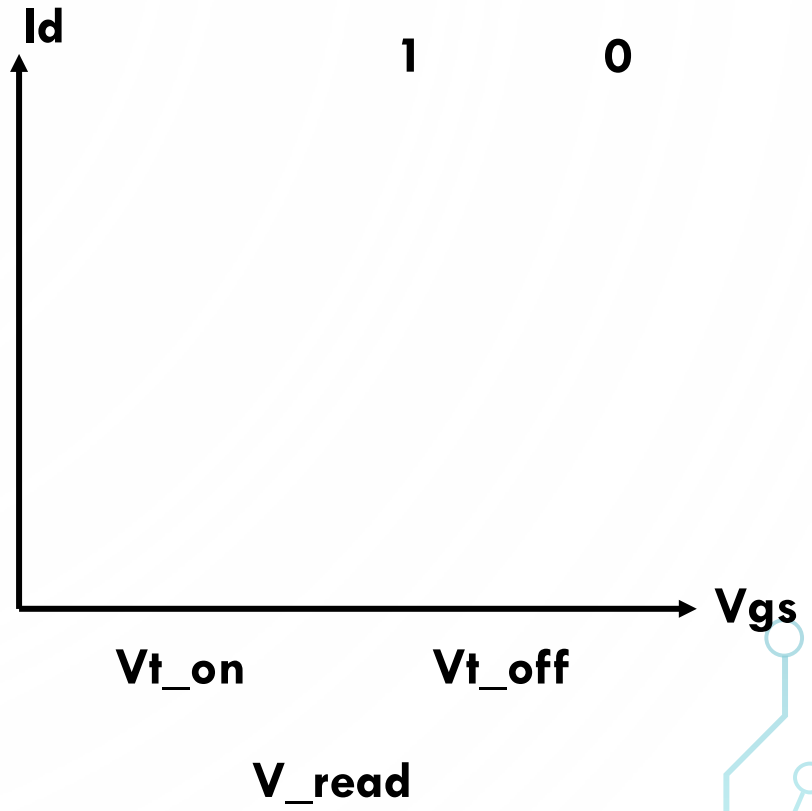
- Floating gate change the threshold voltage of a cell
- Read the cell value by sensing the current




Storing 0
OFF State

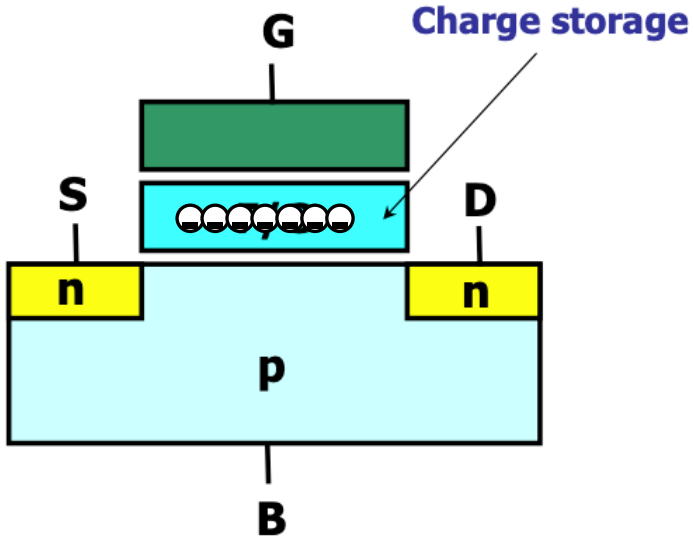



Storing 1
ON State

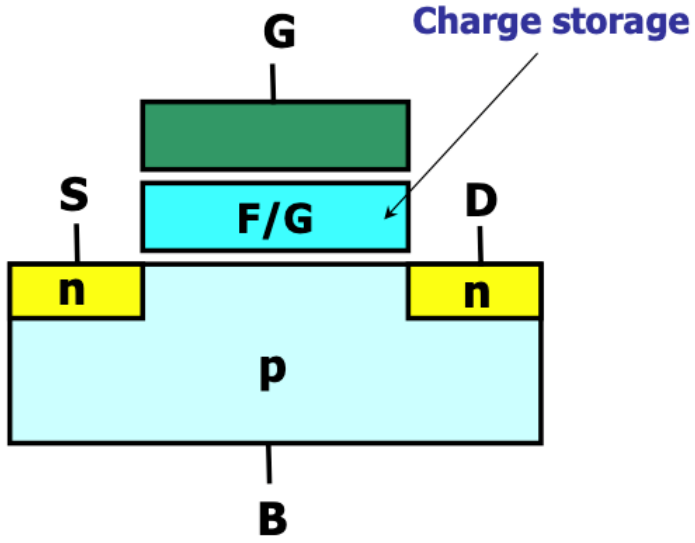


# Read a Flash cell

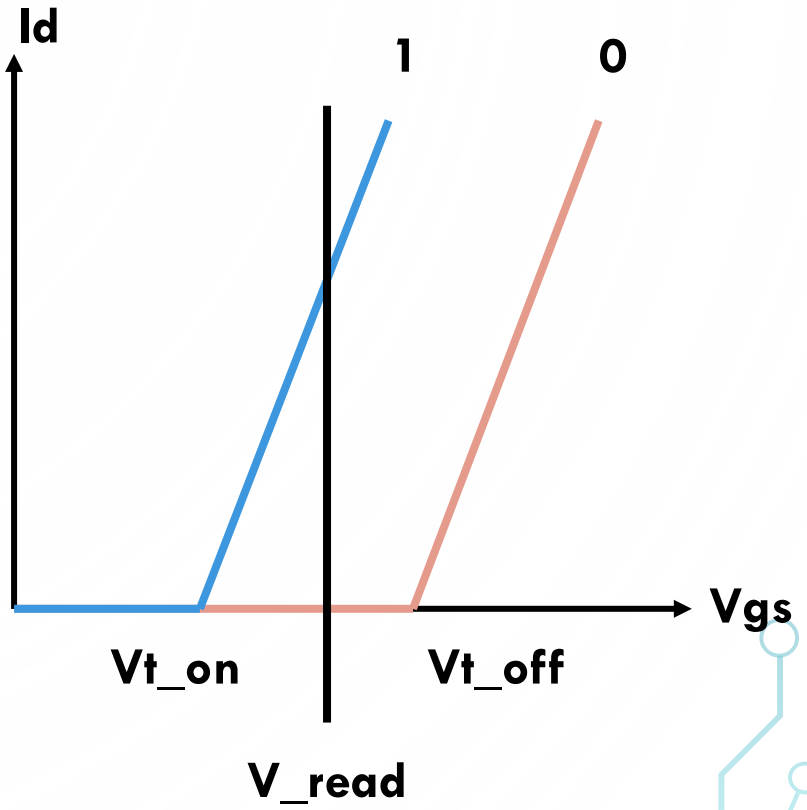
- Floating gate changes the threshold voltage of a cell
- Read the cell value by sensing the current




Storing 0
OFF State

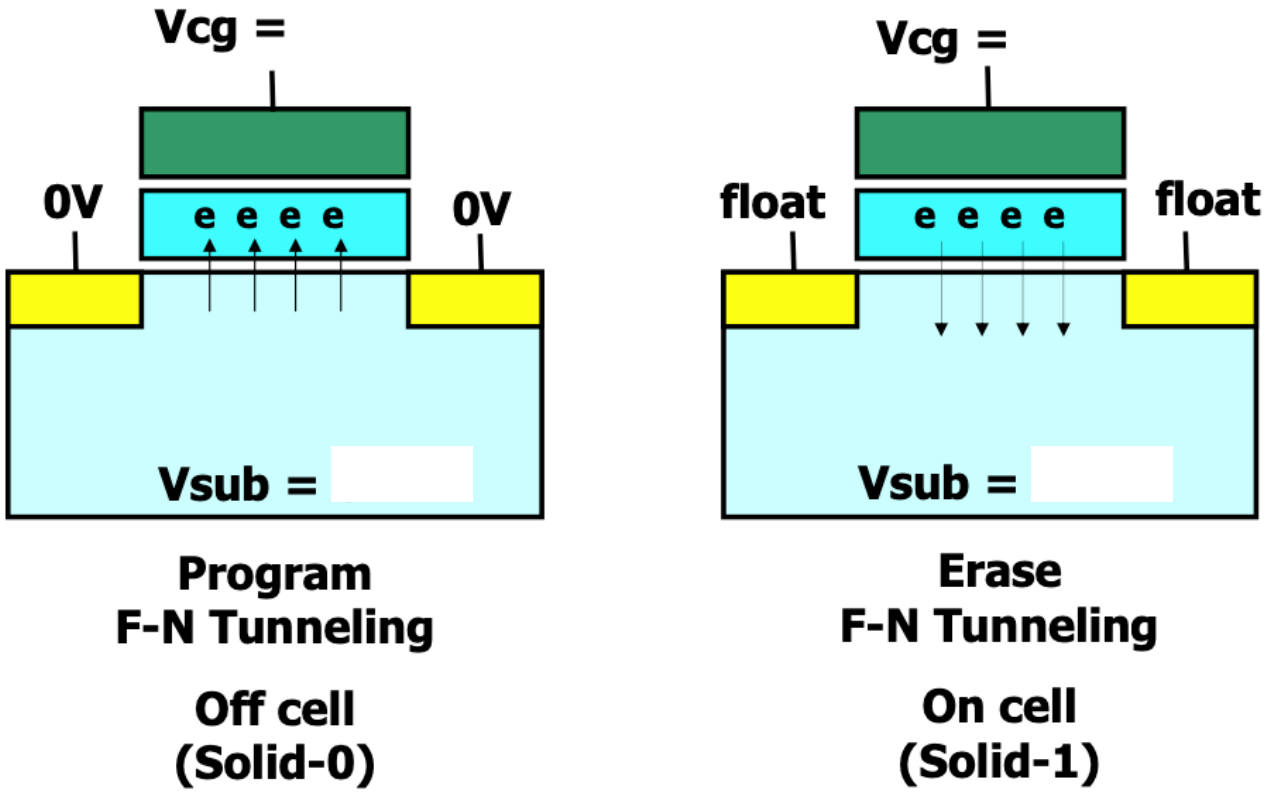


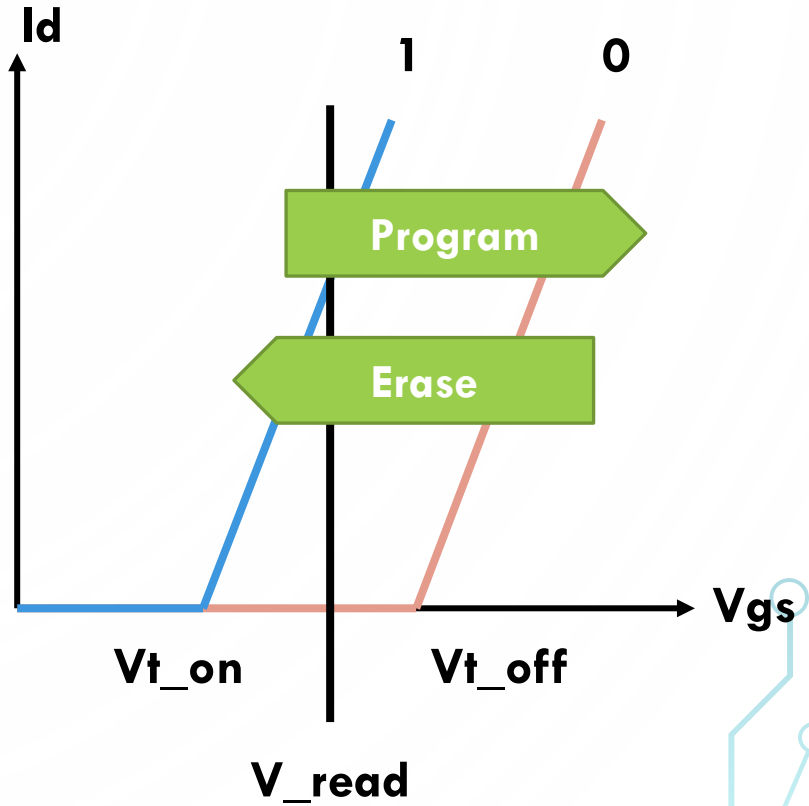

Storing 1
ON State



# Write a Flash cell

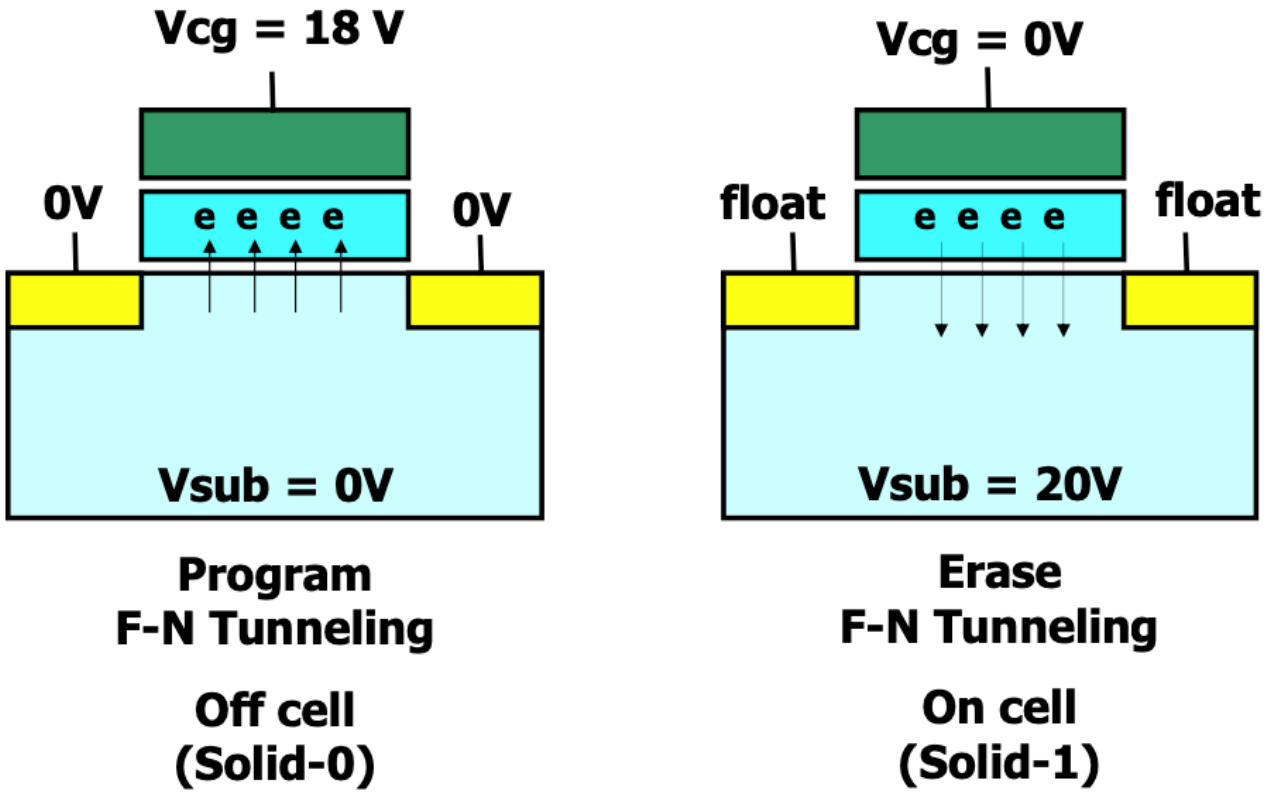
- Write 0: program; Write 1: erase
- Must be erased (store 1) before reprogrammed.
- Endurance: ~100K erase-program cycles

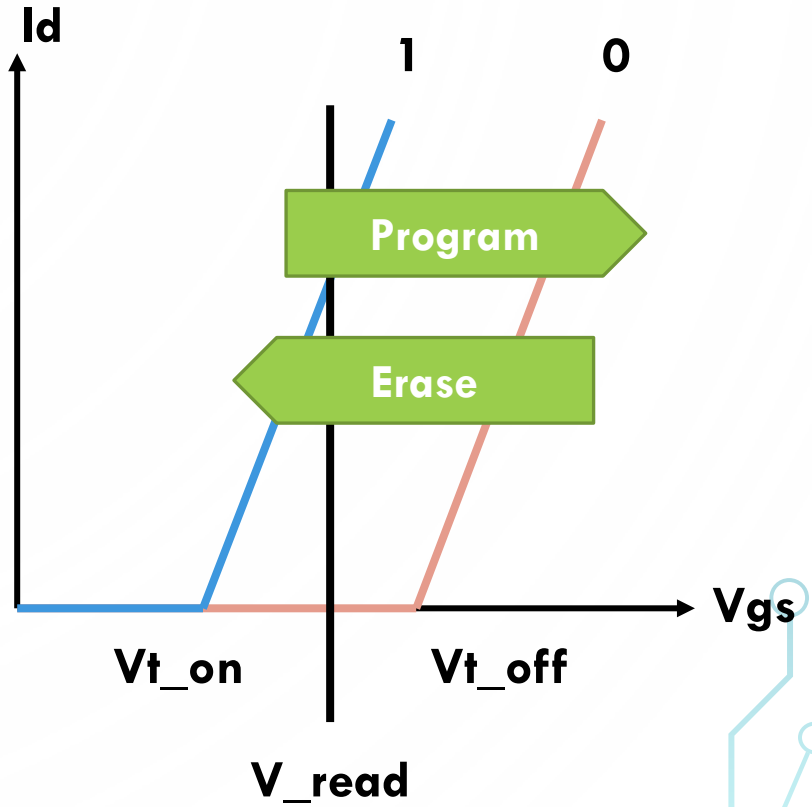


# Write a Flash cell

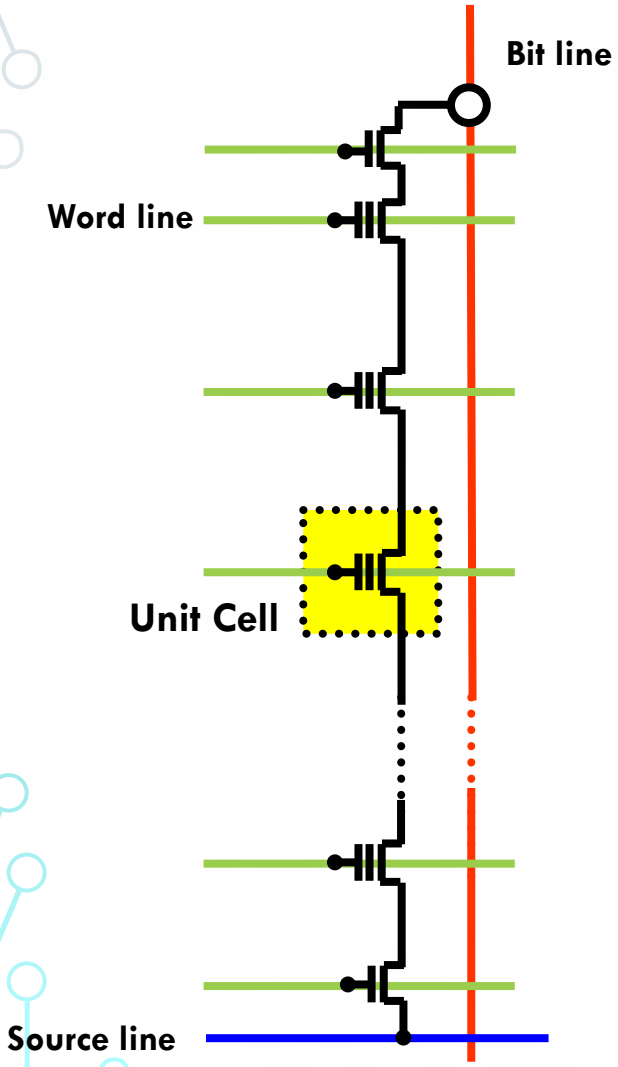
- Write 0: program; Write 1: erase
- Must be erased (store 1) before reprogrammed.
- Endurance: ~100K erase-program cycles

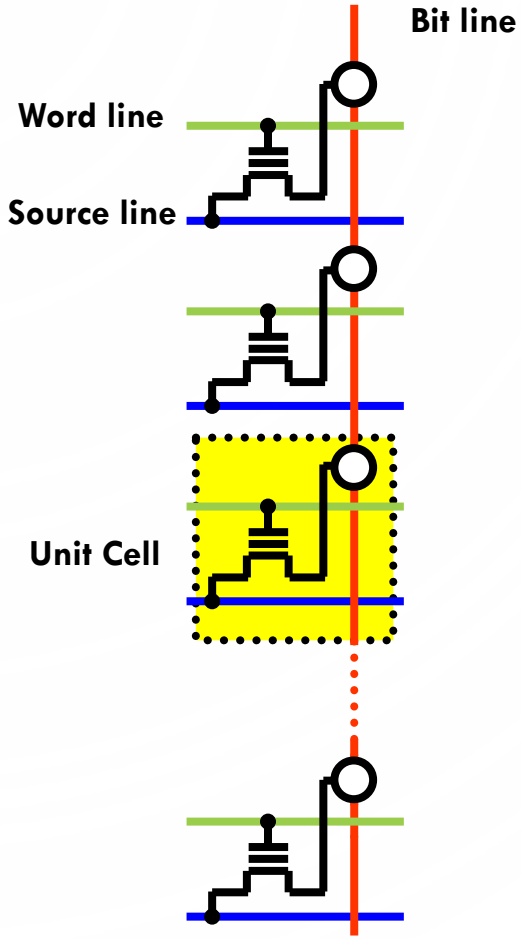


# Flash Organization

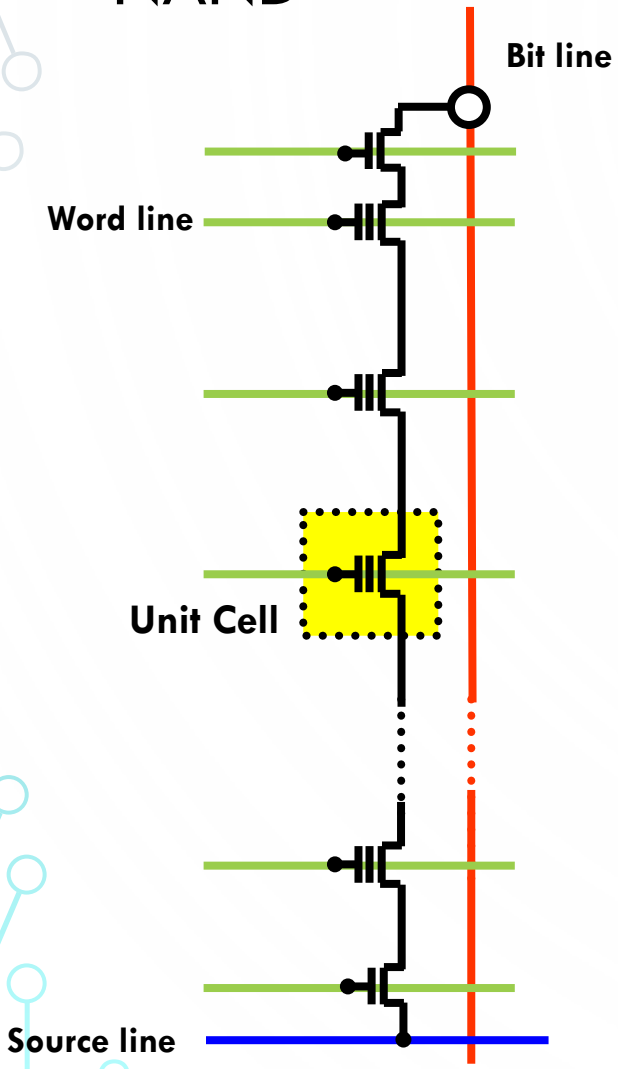
# NAND vs NOR Flash



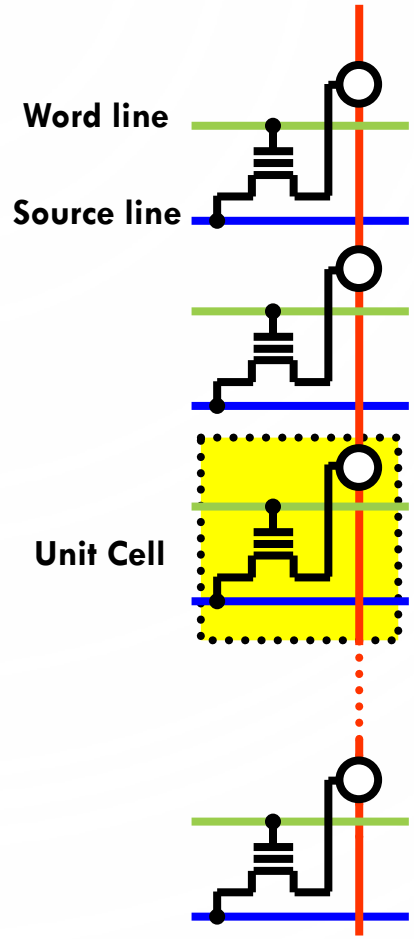
# NAND vs NOR Flash

- NAND



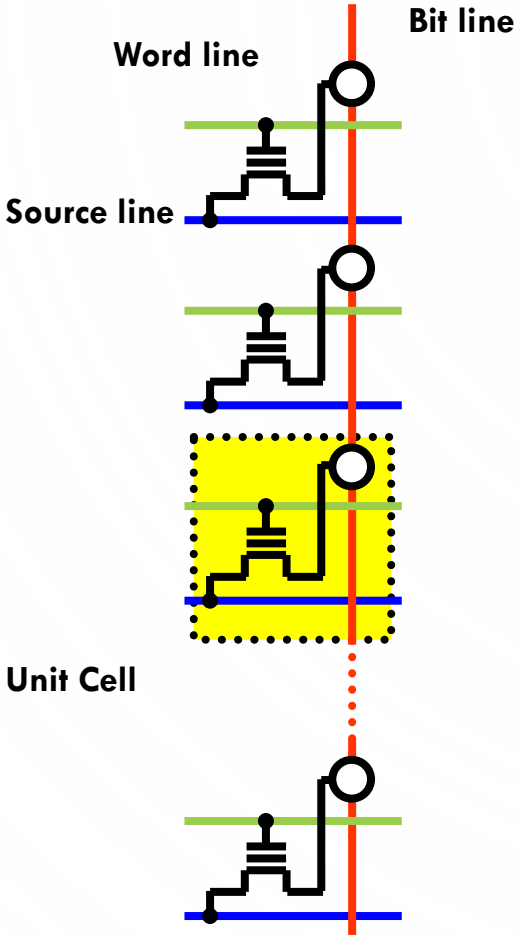

**NAND:**
- High Density
- Used for data storage
  - USB drives
  - Memory cards
  - SSD

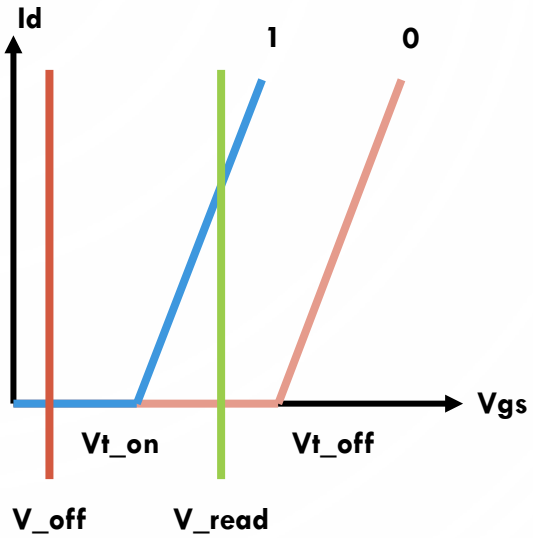
- NOR



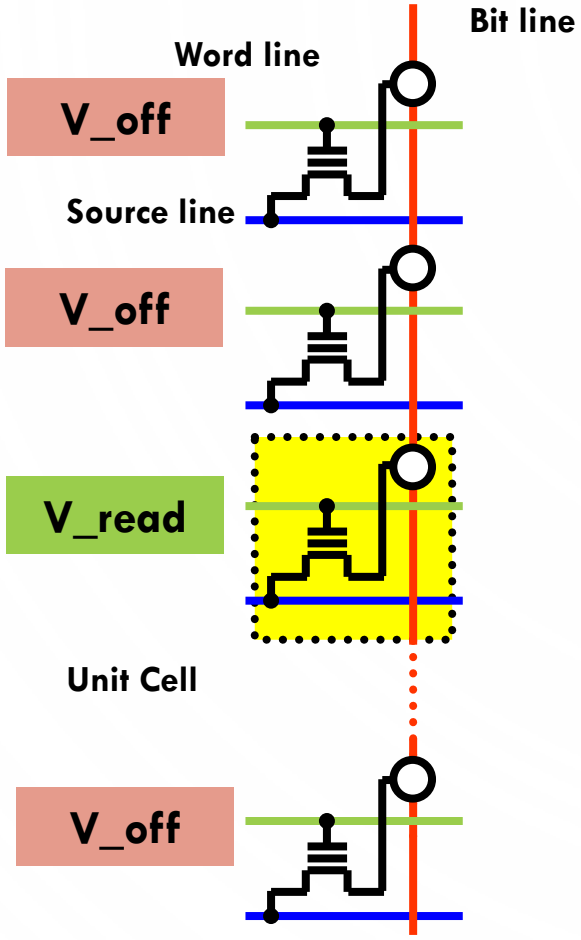

**NOR:**
- Lower Latency
- Used for code storage
  - Embedded systems

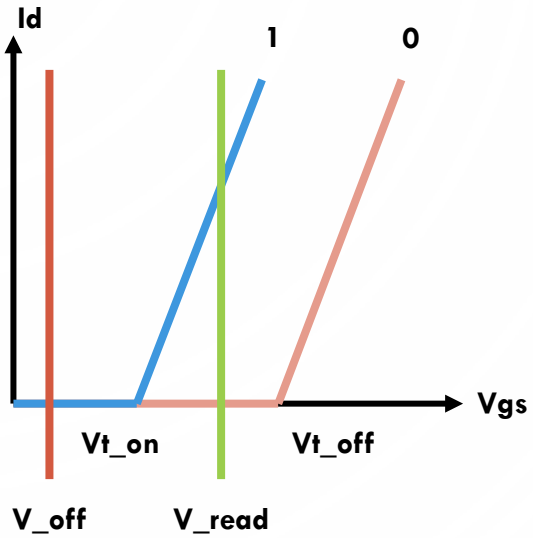
# NOR Flash Read



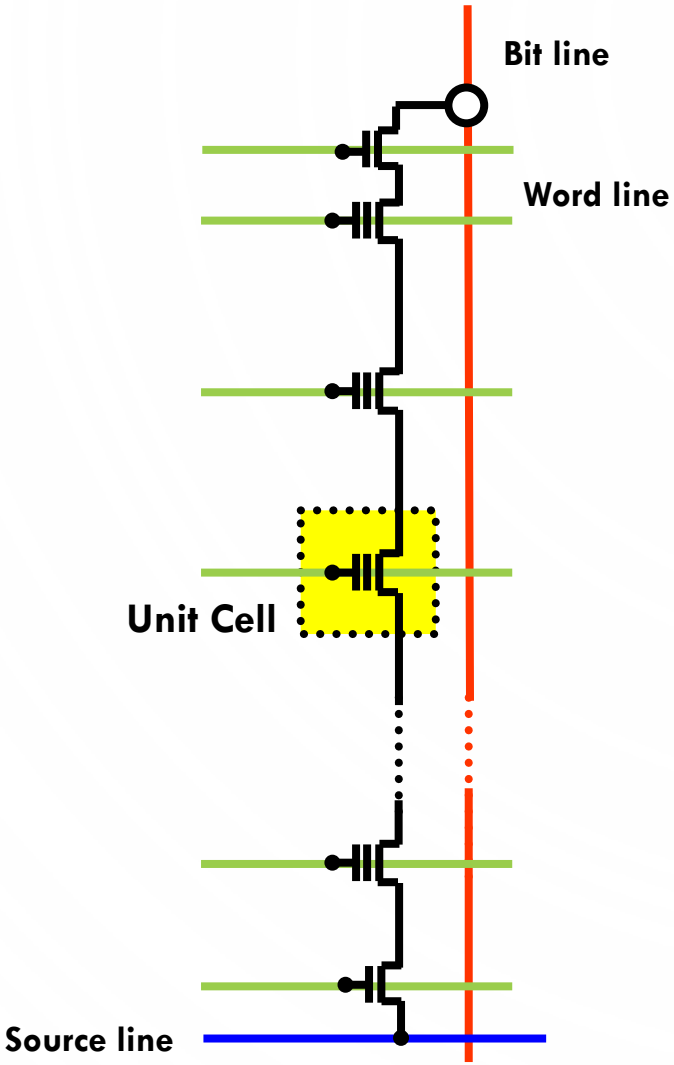



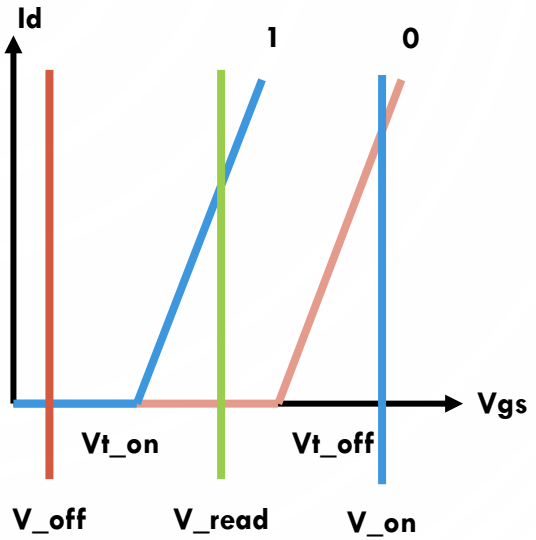
# NOR Flash Read



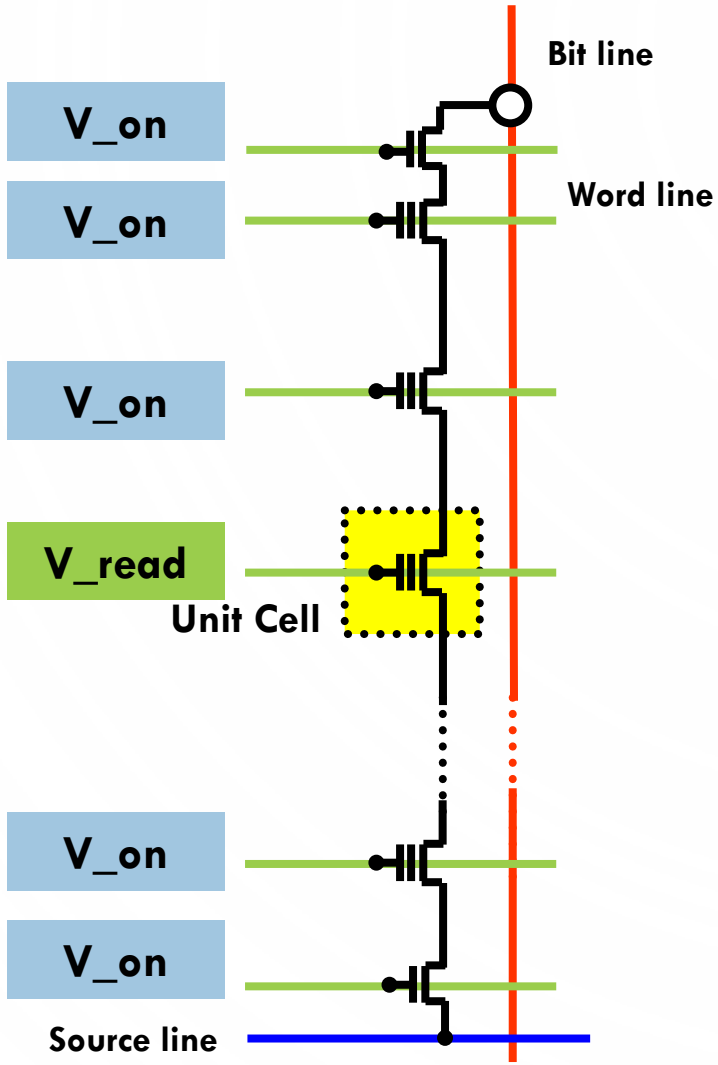



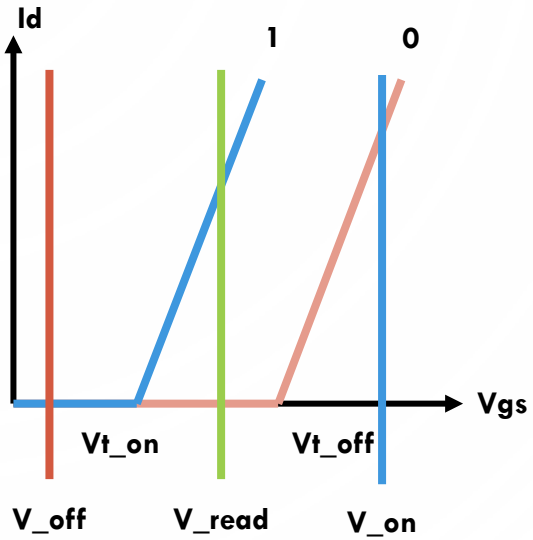
# NAND Flash Read



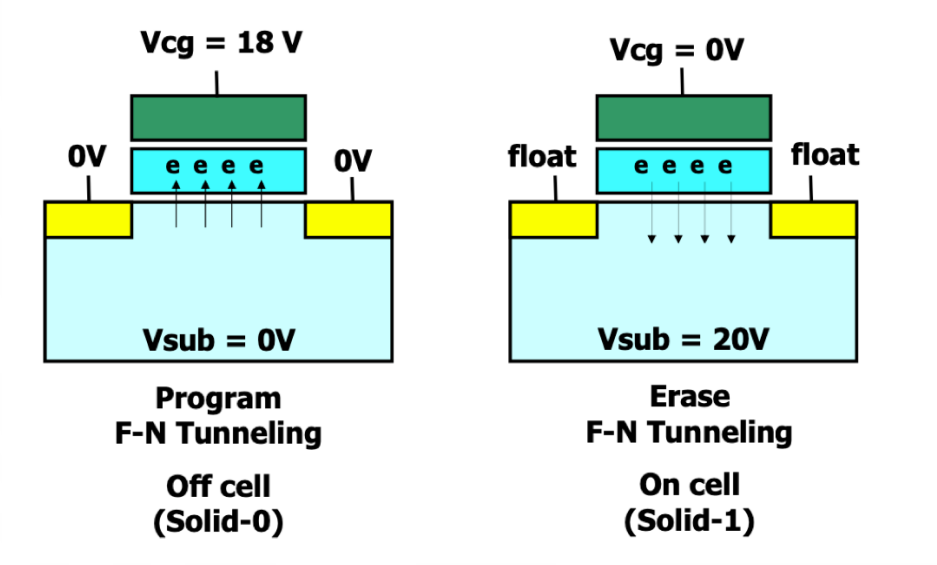
# NAND Flash Read

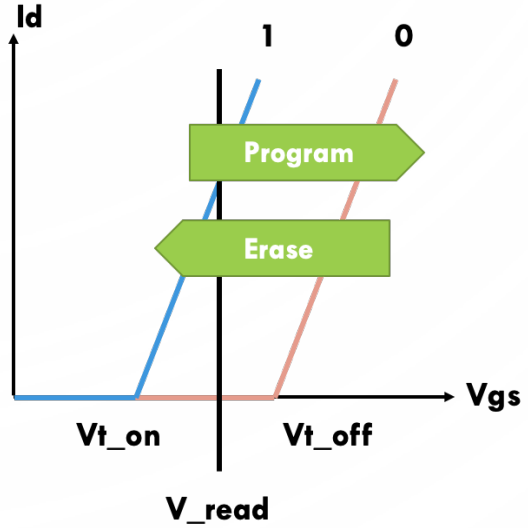


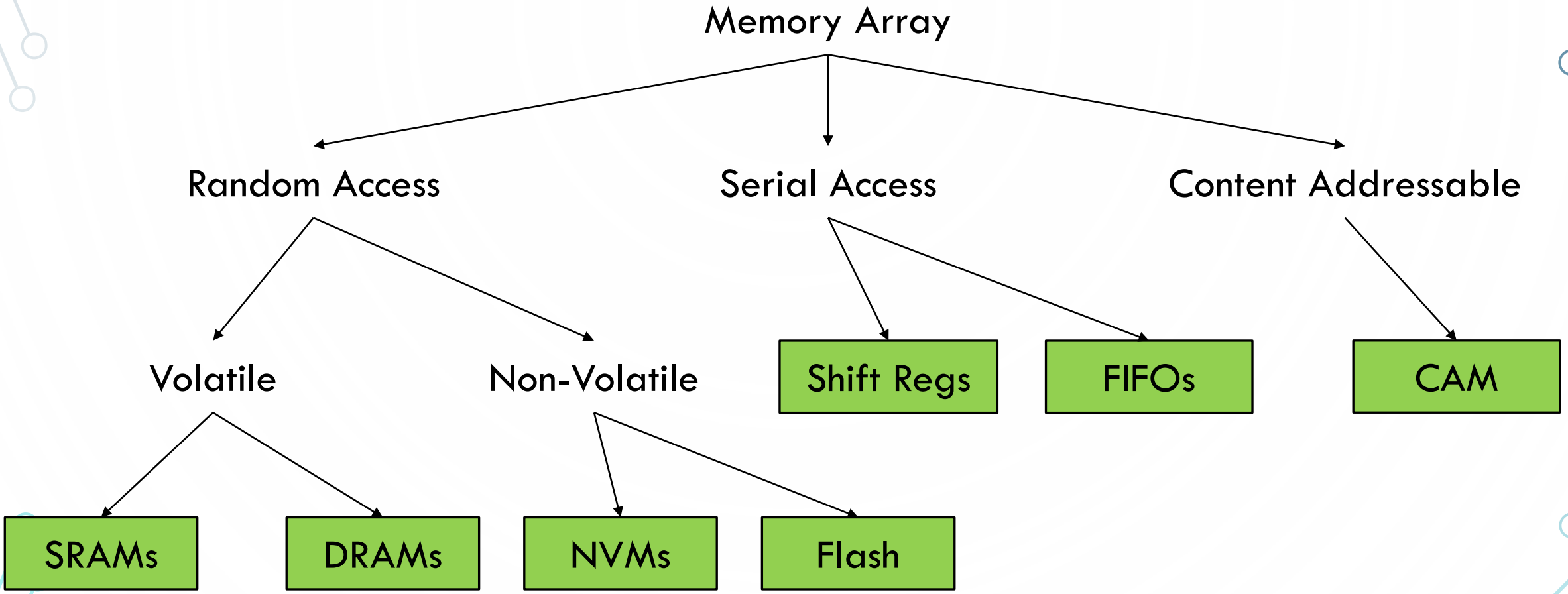
# Flash Write

- Step 1: Erasing.
  - Erase all the FG transistors to set them to 1
  - Apply a negative voltage to the gate -> Electrons flow from the floating gate to the substrate.
- Step 2: Programming
  - Reprogram the appropriate FG transistors to set them to 0
  - Apply a high voltage to the gate -> Electrons are tunneled onto the floating gate.



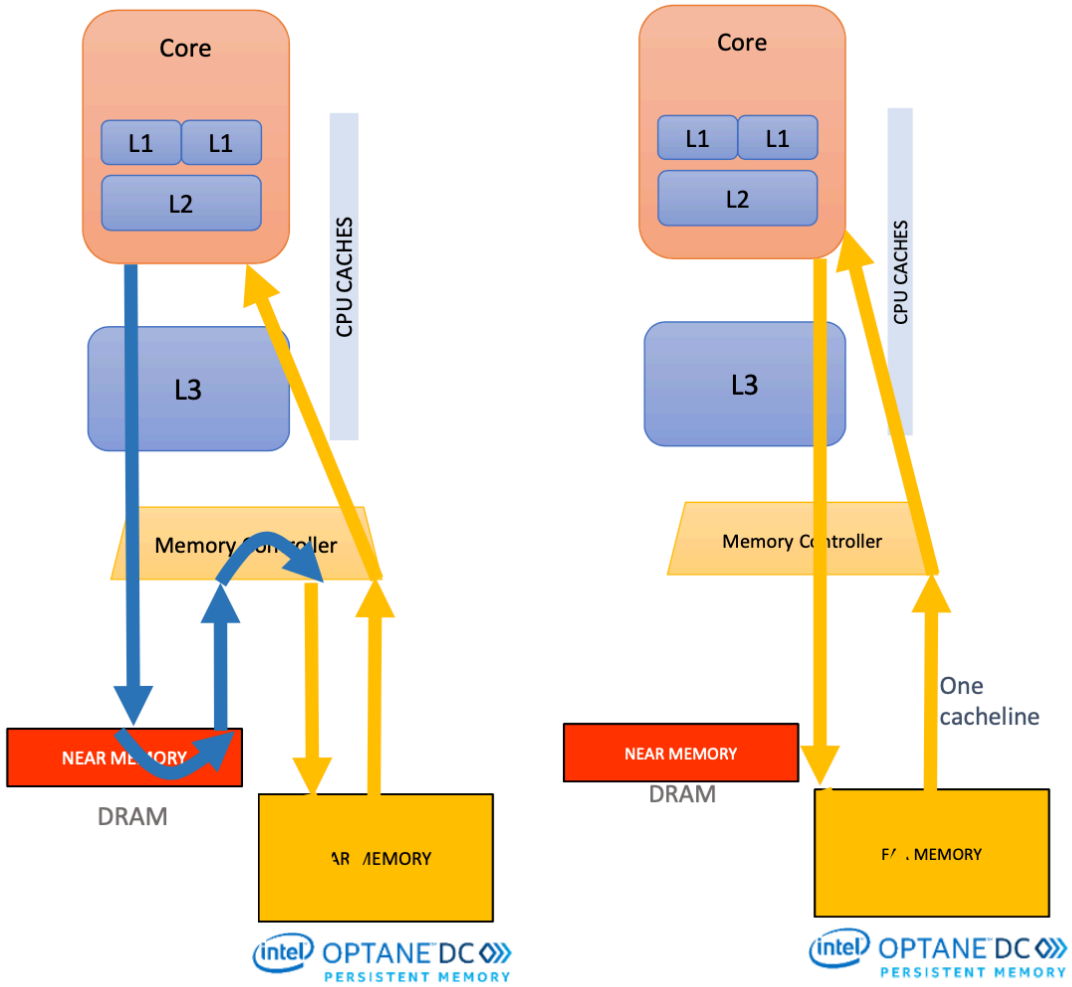
# Memory Overview



# Other Memories

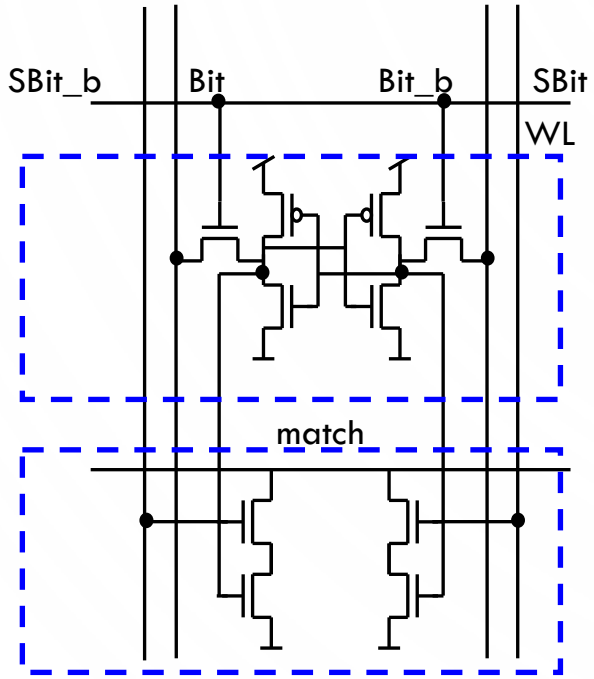
# Non-Volatile Main Memory

- Intel Optane DC Persistent Memory
- Non-Volatile
- Storage based on resistance:
  - High resistivity : 0
  - Low Resistivity: 1
- High capacity:
  - 128, 256, 512 GB
- Modes:
  - Memory Mode
  - App-directed Mode



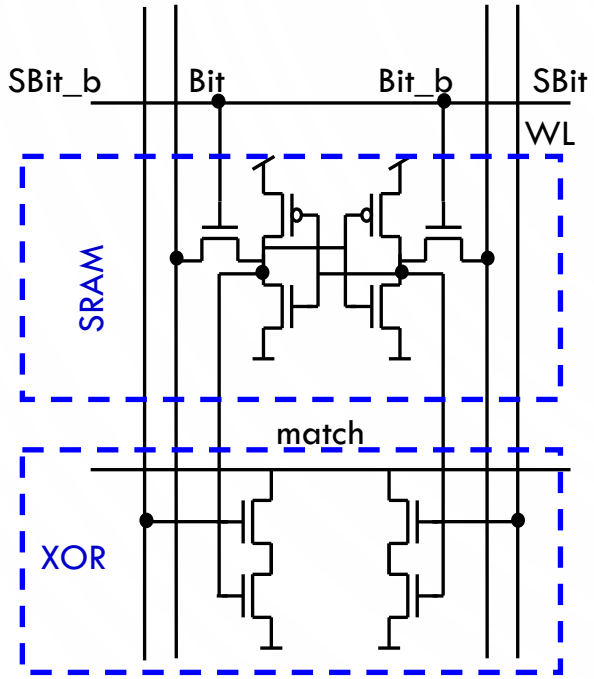
# Content Addressable Memory

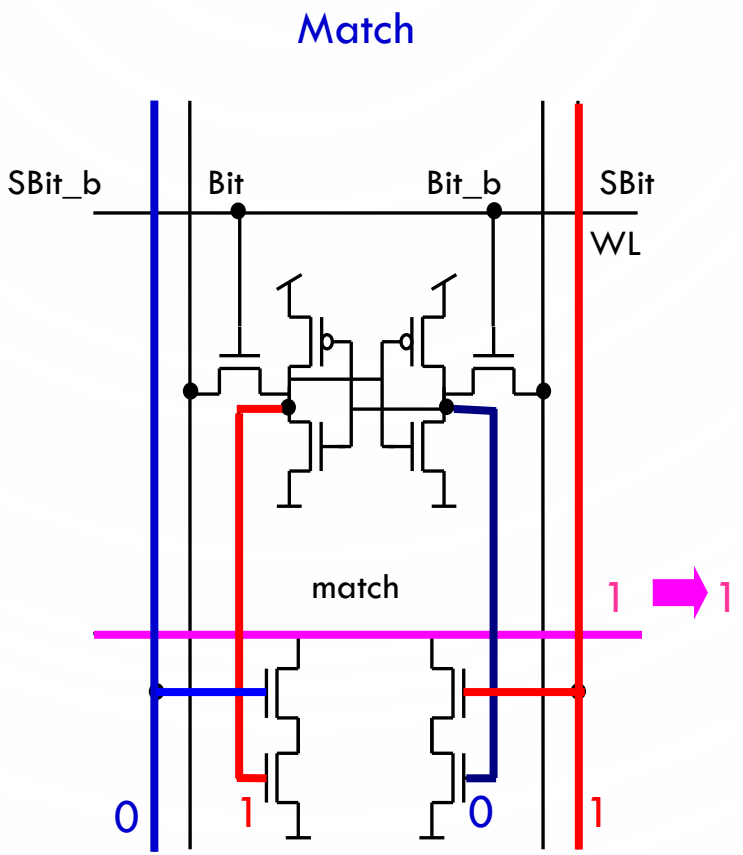
- Commonly used in translation lookaside buffers (TLBs).
- Matching asserts a matchline output for each world that contains a specified key

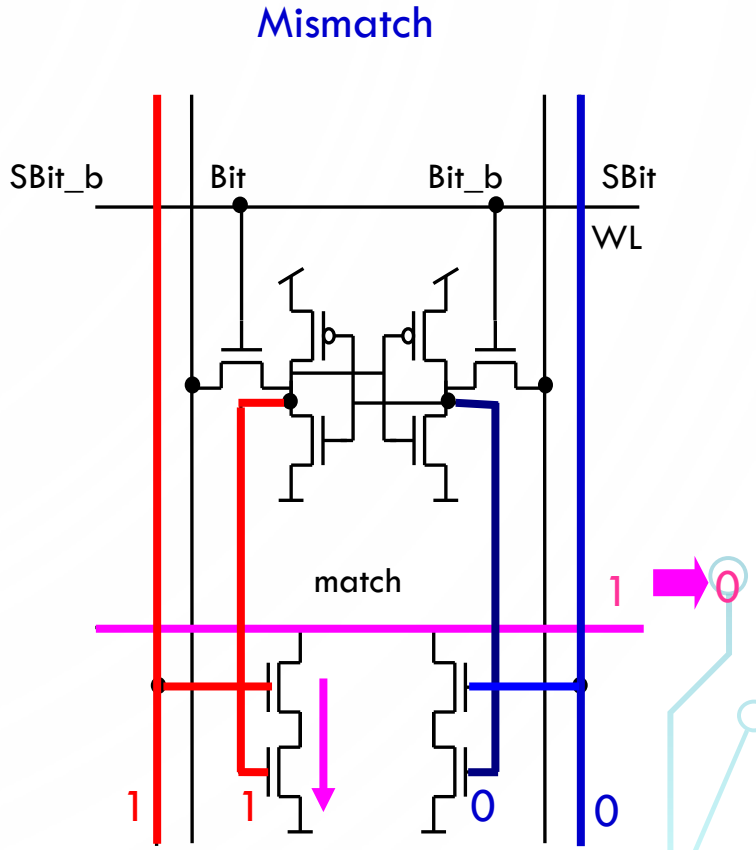


# Content Addressable Memory

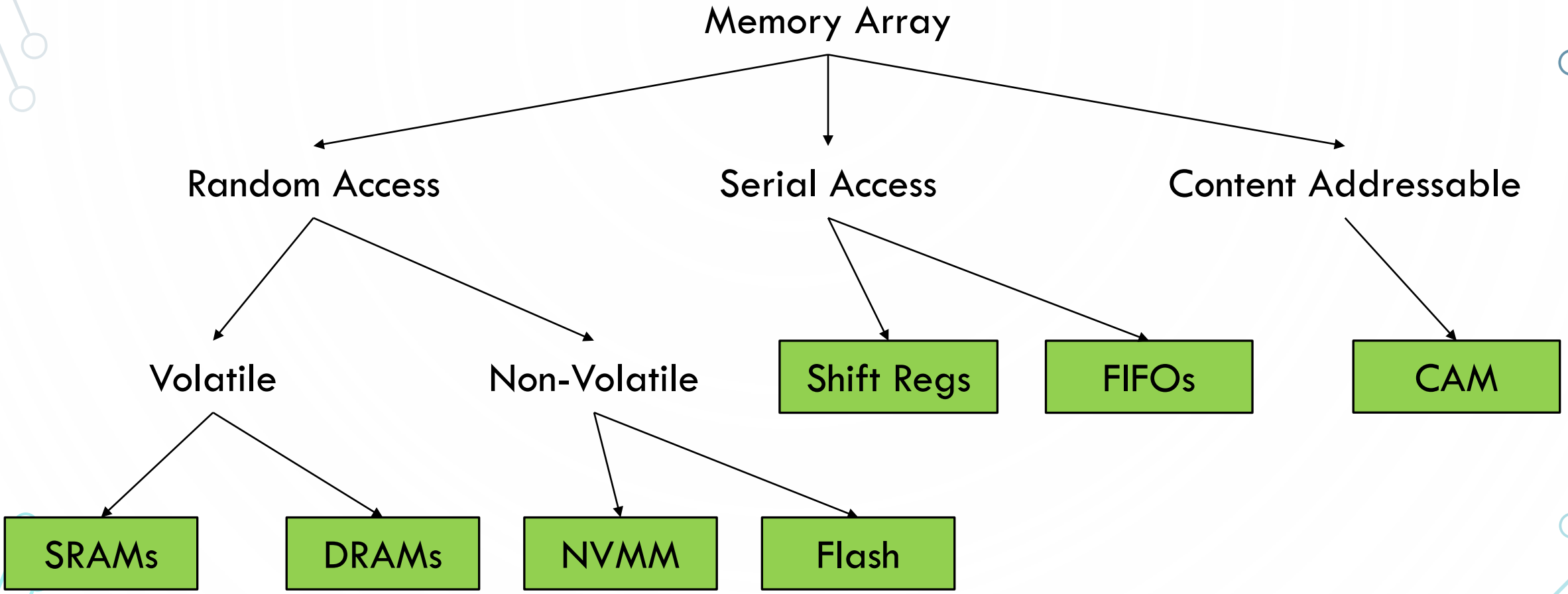
- Commonly used in translation lookaside buffers (TLBs).
- Matching asserts a matchline output for each word that contains a specified key



# Memory Overview



# Summary

- Multiple cache levels make memory appear both fast and big
- Direct mapped and set-associative cache
- Memory compilers generate SRAM blocks
- Several options for memory on FPGAs: Distributed, BlockRAM, UltraRAM
- Many more bits stored in DRAM and Flash
- Flash
  - Single-level vs multi-level
  - Read and Write Flash Cell
  - NAND vs NOR