

Homework 2

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Problem 1)

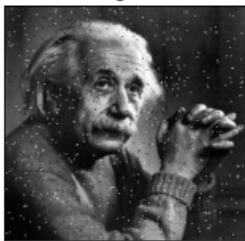
```
def smoothingFilter(img):
    img = cv2.cvtColor(img, cv2.COLOR_BGR2GRAY) #Must convert to grayscale in order to do operations
    kernel = np.ones((5,5),np.float32)/25 #creates 5x5 kernel
    kernelShape = kernel.shape #tuple of kernel dimensions
    imageShape = img.shape #tuple of image dimensions

    #Zero padding below to add 2 units around the border of the image
    paddedDimensions = (imageShape[0]+kernelShape[0]-1,imageShape[1]+kernelShape[1]-1)
    paddedImage = np.zeros(paddedDimensions)
    for i in range(imageShape[0]):
        for j in range(imageShape[1]):
            paddedImage[i+int((kernelShape[0]-1)/2), j+int((kernelShape[1]-1)/2)] = img[i,j]

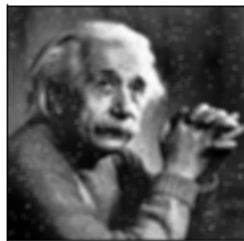
    #running the Filter
    for i in range(imageShape[0]): #Create moving window
        for j in range(imageShape[1]):
            window = paddedImage[i:i+kernelShape[0],j:j+kernelShape[1]] #window matrix gathers values from image
            smoothValue = np.sum(window*kernel)
            img[i,j] = smoothValue #window gets multiplied against the kernel and the sum of the matrix replaces
    return img
```

```
img1 = cv2.imread('imgnoise1.jpg')
smooth1 = smoothingFilter(img1)
plt.subplot(121),plt.imshow(img1,cmap='Greys_r'),plt.title('Original')
plt.xticks([], plt.yticks([]))
plt.subplot(122),plt.imshow(smooth1,cmap='Greys_r'),plt.title('Filtered?')
plt.xticks([], plt.yticks([]))
plt.show()
```

Original

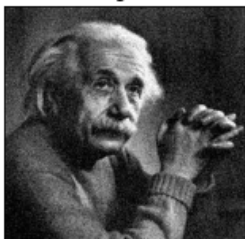


Filtered?

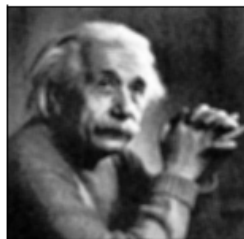


```
img2 = cv2.imread('imgnoise2.jpg')
smooth2 = smoothingFilter(img2)
plt.subplot(121),plt.imshow(img2,cmap='Greys_r'),plt.title('Original')
plt.xticks([], plt.yticks([]))
plt.subplot(122),plt.imshow(smooth2,cmap='Greys_r'),plt.title('Filtered?')
plt.xticks([], plt.yticks([]))
plt.show()
```

Original

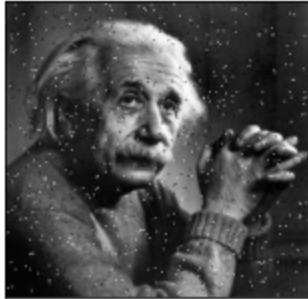


Filtered?

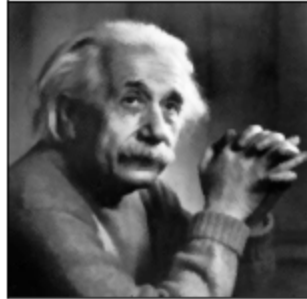


```
img1 = cv2.imread('imgnoise1.jpg')
smooth1 = centerWeightedFilter(img1)
plt.subplot(121),plt.imshow(img1,cmap='Greys_r'),plt.title('Original')
plt.xticks([]), plt.yticks([])
plt.subplot(122),plt.imshow(smooth1,cmap='Greys_r'),plt.title('Filtered?')
plt.xticks([]), plt.yticks([])
plt.show()
```

Original

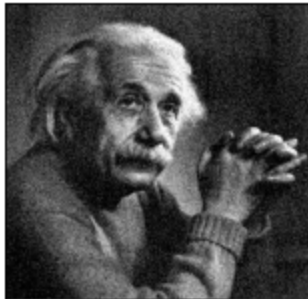


Filtered?

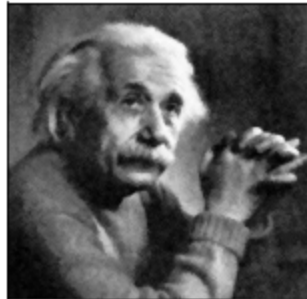


```
img2 = cv2.imread('imgnoise2.jpg')
smooth2 = centerWeightedFilter(img2)
plt.subplot(121),plt.imshow(img2,cmap='Greys_r'),plt.title('Original')
plt.xticks([]), plt.yticks([])
plt.subplot(122),plt.imshow(smooth2,cmap='Greys_r'),plt.title('Filtered?')
plt.xticks([]), plt.yticks([])
plt.show()
```

Original



Filtered?



Problem 2,4 &5

Eleg 4001

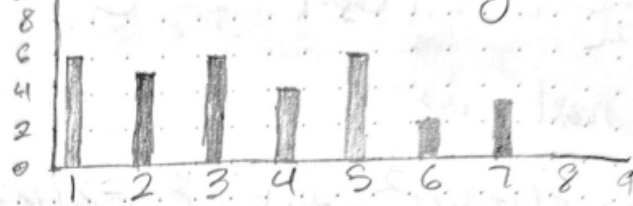
Homework 2

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Problem 2

$$I = \begin{bmatrix} 1 & 3 & 4 & 2 & 2 & 5 \\ 1 & 1 & 7 & 5 & 1 & 2 \\ 6 & 5 & 0 & 5 & 2 & 4 \\ 3 & 5 & 1 & 0 & 4 & 3 \\ 1 & 3 & 2 & 3 & 2 & 3 \\ 0 & 6 & 7 & 7 & 4 & 5 \end{bmatrix}$$

a) Determine the Histogram



b) Determine the Cumulative distribution

$$Pr(r_k) = \frac{n_k}{MN}$$

$$MN = 36$$

use table on slide 14

c) Find point transform $T[I]$

$$S_0 = T(r_0) = 7 \cdot Pr(r_0) = 7 \cdot \left(\frac{6}{36} \right) = 1.1667$$

$$S_1 = 7 \cdot \left(\frac{5}{36} \right) = 0.9722$$

$$S_2 = 1.65 \quad S_4 = 64 \quad S_6 = 24$$

$$S_3 = 128 \quad S_5 = 48 \quad S_7 = 16$$

d) Transformed image

198	228	64	165	165	48
198	198	16	48	108	165
24	48	133	48	165	64
128	48	48	133	64	128
198	128	165	128	165	128
133	24	16	16	64	48

e) Histogram



Eleg 4054

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Problem 4

Prove

$$g\left(\frac{t}{T}\right) \xrightarrow{F} T G(uf)$$

Definition

$$F\{g(ct)\} = \int_{-\infty}^{\infty} g(ct) e^{-i2\pi f t} dt \quad \begin{matrix} u=ct \\ du=c dt \end{matrix}$$

$$F\{g(ct)\} = \int_{-\infty}^{\infty} \frac{g(u)}{c} e^{-i2\pi f \frac{u}{c}} du$$

if $c > 0$

$$F\{g(ct)\} = \boxed{\frac{G\left(\frac{f}{c}\right)}{|c|}}$$

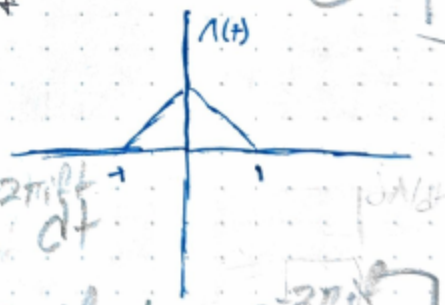
if $c < 0$

$$\begin{aligned} F\{g(ct)\} &= \int_{-\infty}^{\infty} \frac{g(u)}{c} e^{-i2\pi f \frac{u}{c}} du \\ &= - \int_{\infty}^{-\infty} \frac{g(u)}{c} e^{-i2\pi f \frac{u}{c}} du \\ &= \frac{G\left(\frac{f}{c}\right)}{-c} = \boxed{\frac{G\left(\frac{f}{c}\right)}{|c|}} \end{aligned}$$

Problem 5

Find Fourier transform of

$$\Lambda(t) = \begin{cases} 1-t, & \text{if } |t| \leq 1 \\ 0 & \text{otherwise} \end{cases}$$



$$\begin{aligned} &= \int_{-1}^0 (1+t) e^{-i2\pi f t} dt + \int_0^1 (1-t) e^{-i2\pi f t} dt \\ &= \left[\frac{1+i2\pi f t}{4\pi^2 f^2} - \frac{e^{-i2\pi f t}}{4\pi^2 f^2} \right] - \left[\frac{2\pi i f t - 1}{4\pi^2 f^2} + \frac{e^{-i2\pi f t}}{4\pi^2 f^2} \right] \\ &= \frac{e^{-i2\pi f t} (e^{2\pi i f} - 1)^2}{4\pi^2 f^2} = - \frac{e^{-i2\pi f t} (e^{i\pi f} \{e^{i\pi f} - e^{-i\pi f}\})^2}{4\pi^2 f^2} \\ &= \frac{e^{-i2\pi f t} e^{2\pi i f} (2i)^2 \sin^2(\pi f)}{4\pi^2 f^2} = \frac{(\sin(\pi f))^2}{\pi^2 f^2} = \boxed{\text{sinc}^2 f} \end{aligned}$$

Question 3

```
def edgeDetectSobel(img):
    #better version of Sobel Filter from Chapter 2 slide 64
    kernel = np.array([[ -3,0,3],
                       [-10,0,10],
                       [ -3,0,3]])/32

    edgeX = np.zeros_like(img) #create arrays for edge data
    edgeY = np.zeros_like(img)
    kernelShape = kernel.shape #tuple of kernel dimensions
    imageShape = img.shape #tuple of image dimensions

    #Zero padding below to add 2 units around the border of the image
    paddedDimensions = (imageShape[0]+kernelShape[0]-1,imageShape[1]+kernelShape[1]-1)
    paddedImage = np.zeros(paddedDimensions)
    for i in range(imageShape[0]):
        for j in range(imageShape[1]):
            paddedImage[i+int((kernelShape[0]-1)/2), j+int((kernelShape[1]-1)/2)] = img[i,j]

    #running the Filter
    for i in range(imageShape[0]): #Create moving window
        for j in range(imageShape[1]):
            window = paddedImage[i:i+kernelShape[0],j:j+kernelShape[1]] #window matrix gathers values from image
            edgeX[i,j] = np.sum(window*kernel)#window gets multiplied against the kernel
            edgeY[i,j] = np.sum(window*np.flip(kernel.T,axis=0))

    gradient = np.sqrt(np.square(edgeX) + np.square(edgeY))
    gradient *= 255.0 / gradient.max() #using Gradient equation from Chapter 2 Slide 60

    return edgeX, edgeY, gradient
```



```
test1, test2, test3 = edgeDetectSobel(img_blur)
plt.subplot(121),plt.imshow(test1,cmap='Greys_r'),plt.title('LINES x')
plt.xticks([], plt.yticks([]))
plt.subplot(122),plt.imshow(test2,cmap='Greys_r'),plt.title('LINES y')
plt.xticks([], plt.yticks([]))
plt.show()
```

LINES x



LINES y



```
plt.subplot(121),plt.imshow(img_blur,cmap='Greys_r'),plt.title('Original')
plt.xticks([], plt.yticks([]))
plt.subplot(122),plt.imshow(test3,cmap='Greys_r'),plt.title('gradient')
plt.xticks([], plt.yticks([]))
plt.show()
```

Original



gradient

