

Burkhard Heer · Alfred Maußner

Dynamic General Equilibrium Modeling

Computational Methods and Applications

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Contents

Part I Representative Agent Models

1	Basic Models	3
1.1	Introduction	3
1.2	The Deterministic Finite Horizon Ramsey Model	4
1.2.1	The Ramsey Problem	4
1.2.2	The Karush-Kuhn-Tucker Theorem	7
1.3	The Deterministic Infinite Horizon Ramsey Model	9
1.3.1	Recursive Utility	10
1.3.2	Euler Equations	11
1.3.3	Dynamic Programming	13
1.3.4	The Saddle Path	17
1.3.5	Models with Analytical Solution	21
1.4	The Stochastic Ramsey Model	25
1.4.1	Stochastic Output	25
1.4.2	Stochastic Euler Equations	27
1.4.3	Stochastic Dynamic Programming	28
1.5	Labor Supply, Growth, and the Decentralized Economy	31
1.5.1	Substitution of Leisure	31
1.5.2	Growth and Restrictions on Technology and Preferences	32
1.5.3	Parameterizations of Utility and Important Elasticities	39
1.5.4	The Decentralized Economy	44
1.6	Model Calibration and Evaluation	47
1.6.1	The Benchmark Business Cycle Model	47
1.6.2	Calibration	51

1.6.3	Model Evaluation	56
1.7	Numerical Solution Methods	63
1.7.1	Overview	63
1.7.2	Accuracy of Solutions	66
	Appendices	68
A.1	Solution to Example 1.3.1	68
A.2	Restrictions on Technology and Preferences	70
	Problems	75
2	Perturbation Methods: Framework and Tools	79
2.1	Introduction	79
2.2	Order of Approximation	80
2.3	Tools	81
2.3.1	A Brief List	81
2.3.2	Application to the Deterministic Ramsey Model ...	82
2.4	The Stochastic Linear-Quadratic Model	88
2.4.1	The Model	89
2.4.2	Policy Functions	89
2.4.3	Certainty Equivalence	91
2.5	A Canonical DSGE Model	92
2.5.1	Example	92
2.5.2	Generalization	93
2.6	More Tools and First Results	96
2.6.1	Computer Algebra versus Paper and Pencil	96
2.6.2	Derivatives of Composite Functions and Tensor Notation	98
2.6.3	Derivatives of Composite Functions and Matrix Chain Rules	103
2.6.4	Computation of Partial Derivatives	106
	Appendices	111
A.3	Solution of the Stochastic LQ Problem	111
A.4	Third-Order Effects	113
	Problems	115
3	Perturbation Methods: Solutions	119
3.1	Introduction	119
3.2	First-Order Solution	120
3.2.1	First-Order Policy Functions	120
3.2.2	BA Model	120
3.2.3	System Reduction	123

3.2.4	Digression: Solving Separately for the Deterministic and Stochastic Components	126
3.3	Second-Order Solution	131
3.3.1	Second-Order Policy Functions	131
3.3.2	Coefficients of the State Variables	132
3.3.3	Coefficients of the Perturbation Parameter	135
3.4	Third-Order Solution	139
3.4.1	Third-Order Policy Functions	139
3.4.2	Coefficients of the State Variables	139
3.4.3	Coefficients of the State-Dependent Uncertainty...	142
3.4.4	Coefficients of the Perturbation Parameter	143
3.5	Implementation	144
	Appendices	146
A.5	Coefficients of the State-Dependent Uncertainty...	146
A.6	Coefficients of the Perturbation Parameter	152
4	Perturbation Methods: Model Evaluation and Applications ..	155
4.1	Introduction	155
4.2	Second Moments	155
4.2.1	Analytic Second Moments: Time Domain	156
4.2.2	Digression: Unconditional Means	158
4.2.3	Analytical Second Moments: Frequency Domain ..	159
4.2.4	Second Moments: Monte-Carlo Approach	165
4.3	Impulse Responses	174
4.4	The Benchmark Business Cycle Model	176
4.5	Time-to-Build Model	181
4.6	A New Keynesian Model	186
4.6.1	The Monopolistically Competitive Economy	187
4.6.2	Price Staggering	199
4.6.3	Wage Staggering	202
4.6.4	Nominal Frictions and Interest Rate Shocks	204
4.6.5	Habits and Adjustment Costs	206
	Appendices	217
A.7	Derivation of the Demand Function	217
A.8	Price Phillips Curve	219
A.9	Wage Phillips Curve	223
	Problems	225

5	Weighted Residuals Methods	231
5.1	Introduction	231
5.2	Analytical Framework	232
5.2.1	Motivation	232
5.2.2	Residual, Test, and Weight Function	236
5.2.3	Common Test Functions	239
5.2.4	Spectral and Finite Element Functions	241
5.2.5	Illustration	241
5.2.6	General Procedure	243
5.3	Implementation	244
5.3.1	State Space	244
5.3.2	Basis Functions	246
5.3.3	Residual Function	248
5.3.4	Projection and Solution	251
5.3.5	Accuracy	255
5.4	The Deterministic Growth Model	256
5.5	The Benchmark Business Cycle Model	260
5.6	The Benchmark Search and Matching Model	264
5.6.1	Motivation	264
5.6.2	The Model	265
5.6.3	Galerkin Solution	270
5.6.4	Results	272
5.7	Disaster Risk Models	275
5.7.1	Motivation	275
5.7.2	The Benchmark Business Cycle Model with Disaster Risk	276
5.7.3	Generalized Expected Utility	285
5.7.4	Adjustment Costs of Capital	291
5.7.5	Variable Disaster Size and Conditional Disaster Probability	294
5.7.6	The Full Model	299
	Problems	305
6	Simulation-Based Methods	311
6.1	Introduction	311
6.2	Extended Path Method	312
6.2.1	Motivation	312
6.2.2	The General Algorithm	319
6.2.3	Application: The Benchmark Business Cycle Model	321
6.2.4	Application: The Model of a Small Open Economy	323

6.2.5	Conclusion	335
6.3	Simulation and Function Approximation	336
6.3.1	Motivation	336
6.3.2	The General Algorithm	341
6.3.3	Application: The Benchmark Business Cycle Model	345
6.3.4	Application: The Limited Participation Model of Money	349
6.3.5	Conclusion	360
	Problems	362
7	Discrete State Space Value Function Iteration	369
7.1	Introduction	369
7.2	Solution of Deterministic Models	371
7.3	Solution of Stochastic Models	383
7.3.1	Framework	383
7.3.2	Approximations of Conditional Expectations	383
7.3.3	Basic Algorithm	385
7.3.4	Initialization	386
7.3.5	Interpolation	387
7.3.6	Acceleration	388
7.3.7	Value Function Iteration and Linear Programming	391
7.3.8	Evaluation	393
7.4	Further Applications	397
7.4.1	Nonnegative Investment	398
7.4.2	The Benchmark Model	401
	Problems	405

Part II Heterogenous Agent Models

8	Computation of Stationary Distributions	413
8.1	Introduction	413
8.2	Easy Aggregation and Gorman Preferences	415
8.2.1	A Numerical Example	415
8.2.2	Gorman Preferences	425
8.3	A Simple Heterogeneous Agent Model with Aggregate Certainty	429
8.4	The Stationary Equilibrium of a Heterogeneous Agent Economy	436
8.4.1	Discretization of the Distribution Function	442
8.4.2	Discretization of the Density Function	449

8.4.3	Monte-Carlo Simulation	451
8.4.4	Function Approximation	453
8.5	The Risk-Free Rate	456
8.5.1	The Exchange Economy	457
8.5.2	Computation	459
8.5.3	Results	462
8.6	Heterogeneous Productivity and Income Distribution	463
8.6.1	Empirical Facts on the Income and Wealth Distribution and Income Dynamics	464
8.6.2	The Model	470
8.6.3	Computation	477
8.6.4	Results	479
	Problems	481
9	Dynamics of the Distribution Function	485
9.1	Introduction	485
9.2	Motivation	486
9.3	Transition Dynamics	489
9.3.1	Partial Information	490
9.3.2	Guessing a Finite Time Path for the Factor Prices ..	500
9.4	Aggregate Uncertainty: The Krusell-Smith Algorithm	505
9.4.1	The Economy	505
9.4.2	Computation	508
9.4.3	Calibration and Numerical Results	513
9.5	Applications	517
9.5.1	Costs of Business Cycles with Indivisibilities and Liquidity Constraints	518
9.5.2	Income Distribution and the Business Cycle	526
	Problems	541
10	Overlapping Generations Models with Perfect Foresight	543
10.1	Introduction	543
10.2	The Steady State in OLG Models	545
10.2.1	An Elementary Model	545
10.2.2	Computational Methods	550
10.2.3	Direct Computation	552
10.2.4	Computation of the Policy Functions	556
10.3	The Laffer Curve	561
10.4	The Transition Path	579
10.4.1	A Stylized 6-Period OLG Model	580

10.4.2	Computation of the Transition Path	581
10.5	The Demographic Transition	589
10.5.1	The Model	590
10.5.2	Calibration	597
10.5.3	Computation	598
10.5.4	Results	609
10.6	Conclusion	614
	Appendices	618
A.10	Derivation of Aggregate Bequests in (10.29)	618
	Problems	620
11	OLG Models with Uncertainty	627
11.1	Introduction	627
11.2	Overlapping Generations Models with Individual Uncertainty	628
11.2.1	The Model	630
11.2.2	Computation of the Stationary Equilibrium	642
11.2.3	Multi-Dimensional Individual State Space	663
11.3	Overlapping Generations with Aggregate Uncertainty	672
11.3.1	Perturbation Methods	674
11.3.2	The OLG Model with Quarterly Periods	675
11.3.3	Business Cycle Dynamics of Aggregates and Inequality	685
11.3.4	The Krusell-Smith Algorithm and Overlapping Generations	693
	Appendices	715
A.11	Derivation of the Stationary Dynamic Program of the Household	715
A.12	First-Order Conditions of the Stationary Dynamic Program (11.13)	718
A.13	Derivation of the Parameters of the AR(1)-Process with Annual Periods	720
	Problems	721

Part III Numerical Methods

12	Linear Algebra	727
12.1	Introduction	727
12.2	Complex Numbers	727
12.3	Vectors	729

12.4	Norms	729
12.5	Linear Independence	730
12.6	Matrices	730
12.7	Linear and Quadratic Forms	735
12.8	Eigenvalues and Eigenvectors	737
12.9	Matrix Factorization	738
12.9.1	Jordan Factorization	738
12.9.2	Schur Factorization	740
12.9.3	QZ Factorization	740
12.9.4	LU and Cholesky Factorization	741
12.9.5	QR Factorization	742
12.9.6	Singular Value Decomposition	743
13	Function Approximation	747
13.1	Introduction	747
13.2	Function Spaces	748
13.3	Taylor's Theorem	749
13.4	Implicit Function Theorem	752
13.5	Lagrange Interpolation	753
13.5.1	Polynomials and the Weierstrass Approximation Theorem	753
13.5.2	Lagrange Interpolating Polynomial	754
13.5.3	Drawbacks	756
13.6	Spline Interpolation	758
13.6.1	Linear Splines	759
13.6.2	Cubic Splines	760
13.7	Orthogonal Polynomials	762
13.7.1	Orthogonality in Euclidean Space	762
13.7.2	Orthogonality in Function Spaces	763
13.7.3	Orthogonal Interpolation	765
13.7.4	Families of Orthogonal Polynomials	766
13.8	Chebyshev Polynomials	766
13.8.1	Definition	766
13.8.2	Zeros and Extrema	769
13.8.3	Orthogonality	770
13.8.4	Chebyshev Regression	771
13.8.5	Chebyshev Evaluation	774
13.8.6	Examples	775
13.9	Multivariate Extensions	777
13.9.1	Tensor Product and Complete Polynomials	777

13.9.2	Multidimensional Splines.....	779
13.9.3	Multidimensional Chebyshev Regression.....	781
13.9.4	The Smolyak Polynomial	783
13.9.5	Neural Networks.....	788
14	Differentiation and Integration	791
14.1	Introduction	791
14.2	Differentiation	792
14.2.1	First-Order Derivatives	792
14.2.2	Second-Order Derivatives	796
14.3	Numerical Integration	798
14.3.1	Newton-Cotes Formulas	798
14.3.2	Gaussian Formulas	799
14.3.3	Monomial Integration Formula	801
14.4	Approximation of Expectations.....	803
14.4.1	Expectation of a Function of Gaussian Random Variables	803
14.4.2	Gauss-Hermite Integration	804
14.4.3	Monomial Rules for Expectations	806
15	Nonlinear Equations and Optimization.....	811
15.1	Introduction	811
15.2	Stopping Criteria for Iterative Algorithms	812
15.3	Nonlinear Equations	815
15.3.1	Single Equations	815
15.3.2	Multiple Equations.....	818
15.4	Numerical Optimization	829
15.4.1	Golden Section Search	829
15.4.2	Gauss-Newton Method	831
15.4.3	Quasi-Newton	835
15.4.4	Genetic Search Algorithms	838
16	Difference Equations and Stochastic Processes	847
16.1	Introduction	847
16.2	Difference Equations	848
16.2.1	Linear Difference Equations	848
16.2.2	Nonlinear Difference Equations	851
16.2.3	Boundary Value Problems and Shooting	854
16.3	Stochastic Processes.....	856
16.3.1	Univariate Processes	856

16.3.2 Trends	858
16.3.3 Multivariate Processes	858
16.4 Markov Processes	859
16.4.1 The First-Order Autoregressive Process	859
16.4.2 Markov Chains	860
16.5 Linear Filters	866
16.5.1 Definitions	866
16.5.2 The HP-Filter	867
Bibliography	870

List of Figures

1.1	Boundedness of the Capital Stock.....	12
1.2	Phase Diagram of the Infinite-Horizon Ramsey Model	18
1.3	No Path Leaves the Region A_2	19
1.4	Convergence of the Capital Stock in the Infinite-Horizon Ramsey Model	21
1.5	Stationary Distribution of the Capital Stock in the Stochastic Infinite-Horizon Ramsey Model.....	30
1.6	Risk Aversion	40
1.7	Impulse Responses in the Benchmark Model.....	57
1.8	Impulse Responses from an Estimated VAR	58
1.9	Productivity Shock in the Benchmark Business Cycle Model .	62
2.1	Eigenvalues of J	84
2.2	Approximate Time Path of the Capital Stock in the Deterministic Growth Model	86
2.3	Policy Function for Consumption in the Deterministic Growth Model	88
4.1	Third-Order Approximate Policy Function for Capital	167
4.2	Impulse Responses in the Time-to-Build Model	185
4.3	Structure of the NK Model	188
4.4	Impulse Responses in the Monopolistically Competitive Economy	198
4.5	Interest Rate Shock and Nominal Rigidities.....	205
4.6	Interest Rate Shock and Real Frictions	211
4.7	TFP Shock in the NK Model	213
4.8	Government Spending Shock in the NK Model.....	214

5.1	Approximations of e^{-t}	242
5.2	Ergodic Set of the Benchmark Business Cycle Model from a Second-Order Solution.....	246
5.3	Euler Equation Residuals: Deterministic Growth Model.....	260
5.4	Policy Function for the Value of Employment	273
5.5	Distribution of Unemployment in the Search and Matching Model	273
5.6	Simulated Time Path of Unemployment	274
6.1	Example Solutions of the Finite-Horizon Ramsey Model	314
6.2	Approximate Time Paths of the Capital Stock in the Deterministic Growth Model	316
6.3	Simulated Time Path of the Stochastic Growth Model.....	318
6.4	Ergodic Set of the Benchmark Business Cycle Model from the Extended Path Simulation	324
6.5	Impulse Responses to a Productivity Shock in the Small Open Economy Model	332
6.6	Impulse Responses to a World Interest Rate Shock in the Small Open Economy Model	333
6.7	Impulse Response to a Money Supply Shock in the Limited Participation Model.....	358
7.1	VI versus LP.....	398
7.2	Policy Function for Consumption in the Stochastic Growth Model with Nonnegative Investment	401
8.1	Dynamics of Aggregate Capital Stock K_t	420
8.2	Dynamics of the Gini Coefficient of Wealth	423
8.3	Dynamics of the Gini Coefficient of Market Income	424
8.4	Savings Function	441
8.5	Convergence of the Distribution Mean	447
8.6	Convergence of the Capital Stock	448
8.7	Invariant Density Function of Wealth	449
8.8	Invariant Density Function, Employed Worker	451
8.9	Next-Period Assets of the Employed Worker	460
8.10	Next-Period Assets of the Unemployed Worker.....	460
8.11	Savings in the Exchange Economy	461
8.12	Stationary Distribution Function	462
8.13	Lorenz Curve of US Earnings, Income, and Wealth in 1992 ..	465
9.1	Value Function of the Employed Worker.....	496

9.2	Savings of the Workers.....	496
9.3	Dynamics of the Density Function over Time	497
9.4	Convergence of the Aggregate Capital Stock.....	498
9.5	The Dynamics of the Density Function	504
9.6	Goodness of Fit for Stationary Density	504
9.7	Distribution Function in Period $T = 3,000$	515
9.8	Prediction Errors without Updating	516
9.9	Time Path of the Aggregate Capital Stock	517
9.10	Consumption Functions in the Storage Economy.....	521
9.11	Savings Functions in the Storage Economy	521
9.12	Invariant Density Functions in the Storage Economy	523
9.13	Consumption in the Economy with Intermediation	523
9.14	Savings Functions in the Economy with Intermediation	524
9.15	Invariant Density Functions in the Economy with Intermediation Technology.....	524
9.16	Lorenz Curve of Income.....	538
9.17	Lorenz Curve of Wealth	540
10.1	Wealth-Age Profile in the Standard OLG Model	554
10.2	Labor-Supply-Age Profile in the Standard OLG Model	555
10.3	Survival Probabilities ϕ^s in Benchmark Equilibrium	569
10.4	Productivity-Age Profile \bar{y}^s	570
10.5	Wealth-Age Profile Approximation	573
10.6	Wealth-Age Profile with Age-Dependent Productivities	575
10.7	Labor-Supply-Age Profile in the Economy with Age-Dependent Productivities	575
10.8	Consumption-Age Profile in the Economy with Age-Dependent Productivities	576
10.9	Laffer Curves.....	576
10.10	Wealth-Age and Labor-Supply-Age Profiles in the New and in the Old Steady State.....	583
10.11	Wealth-Age and Labor-Age Profiles in the Old Steady State and for the Household Born in Period $t = -2$	585
10.12	Transition from the Old to the New Steady State.....	586
10.13	Survival Probabilities in the Years 2014 and 2100.....	591
10.14	US Population Growth Rate 1950-2100 (annual %)	591
10.15	Stationary Age Distribution, Initial and Final Steady State ...	600
10.16	Decline of the Labor Force Share during the Transition	600
10.17	Increase in the Old-Age Dependency Ratio During the Transition.....	602

10.18	Convergence of Transition Path \tilde{K}	607
10.19	Individual Wealth $\tilde{a}_t^{s,j}$ in the Initial and Final Steady State ...	610
10.20	Individual Labor Supply $l_t^{s,j}$, Initial and Final Steady State	611
10.21	Convergence of Capital per Working Hour, $\tilde{K}_t = K_t/(A_t L_t)$, and Aggregate Labor \tilde{L}_t	612
10.22	Convergence of Factor Prices w_t and r_t	613
10.23	Convergence of Government Variables \tilde{tr}_t and τ_t^p	613
11.1	Measure μ^s of the s -Year-Old Cohort	645
11.2	Labor Supply of the Low- and High-Skilled Workers with Idiosyncratic Productivity θ_4	650
11.3	Wealth-Age Profile in the Stochastic OLG Model	656
11.4	Consumption-Age Profile in the Stochastic OLG Model	657
11.5	Labor-Supply-Age Profile in the Stochastic OLG Model	658
11.6	Lorenz Curve of US and Model Earnings	659
11.7	Lorenz Curve of US and Model Wealth	659
11.8	Policy Functions as a Function of Wealth	668
11.9	Policy Functions as a Function of Accumulated Average Earnings	669
11.10	Cumulative Distribution Functions	671
11.11	Steady-State Age Profiles of Capital, Consumption, and Working Hours in the OLG Model of Example 11.3.1	683
11.12	Impulse Responses to a Technology Shock in the OLG Model of Example 11.3.1	686
11.13	Impulse Responses to a Government Demand Shock in the OLG Model of Example 11.3.1	687
11.14	Nonstochastic Steady-State Distribution of \tilde{k} (case 1)	703
11.15	Nonstochastic Steady-State Age Profiles	710
11.16	Simulation Results	711
12.1	Gaussian Plane	728
13.1	Linear Interpolation	755
13.2	Polynomial Approximation of the Runge Function on an Equally Spaced Grid	757
13.3	Polynomial Approximation of the Runge Function on Chebyshev Zeros	757
13.4	Monomials on $[0,1,2]$	758
13.5	Spline Interpolation	759
13.6	Spline Interpolation of the Runge Function	762

13.7	Orthogonal Vectors	762
13.8	Orthogonal Projection in Euclidean Space	763
13.9	Chebyshev Polynomials T_1 through T_5	768
13.10	Weight Function of the Chebyshev Polynomials.	770
13.11	Approximation of the Runge Function with Chebyshev Polynomials	776
13.12	Approximation of a Kinked Function with Chebyshev Polynomials	777
13.13	Rectangular Grid	779
13.14	Tensor and Smolyak Grid	785
13.15	Neural Networks	788
15.1	Bisection Method	816
15.2	Modified Newton-Raphson Method	817
15.3	Secant Method	818
15.4	Gauss-Seidel Iterations	820
15.5	Dogleg Step	827
15.6	Golden Section Search	830
15.7	Stochastic Universal Sampling	841
16.1	Topological Conjugacy	853
16.2	Local Stable and Unstable Manifolds	854

List of Tables

1.1	Calibration of the Benchmark Business Cycle Model	56
1.2	Business Cycles Statistics from the Benchmark Model	61
2.1	Code List for Equation (2.40)	108
2.2	Computation of Derivatives of Example 1.6.1	110
4.1	Euler Equation Residuals: Benchmark Business Cycle Model	178
4.2	Second Moments: German Data	179
4.3	Second Moments: Benchmark Business Cycle Model	180
4.4	Second Moments: Time-to-Build Model	186
4.5	Calibration of the NK Model	196
4.6	Second Moments: NK Model	215
5.1	Weighted Residuals Solution of the Deterministic Growth Model	259
5.2	Euler Equation Residuals of the Galerkin Solution of the Benchmark Business Cycle Model	263
5.3	Second Moments from the Benchmark Business Cycle Model: Perturbation versus Galerkin Solution	264
5.4	Calibration of the Search and Matching Model	270
5.5	Data on Global Real Returns	276
5.6	Calibration of the Benchmark Model with Disaster Risk	278
5.7	Annualized Real Returns in the Benchmark Model	284
5.8	Annualized Real Returns with GEU	290
5.9	Annualized Real Returns with GEU and Adjustment Costs of Capital	294
5.10	Model Calibration with Variable Disaster Size	297
5.11	Annualized Real Returns with Variable Disaster Size	298

5.12	Baseline Calibration of the Full Disaster Risk Model	302
5.13	Annualized Real Returns in the Full Disaster Risk Model . . .	303
6.1	Second Moments from the Benchmark Business Cycle Model: Extended Path Solution	324
6.2	Second Moments from the Small Open Economy Model . . .	335
6.3	Successful generalized stochastic simulation (GSS) Solutions of the Stochastic Growth Model	341
6.4	GSS Solutions of the Benchmark Business Cycle Model . . .	348
6.5	Second Moments from the Benchmark Business Cycle Model: GSS Solutions	349
6.6	Calibration of the Limited Participation Model	355
6.7	Second Moments from the Limited Participation Model . . .	359
7.1	Value Function Iteration in the Deterministic Growth Model: Runtime	380
7.2	Value Function Iteration in the Deterministic Growth Model: Accuracy	382
7.3	Value Function Iteration in the Stochastic Growth Model: Runtime	394
7.4	Value Function Iteration in the Stochastic Growth Model: Accuracy	396
7.5	VI Solution of the Benchmark Business Cycle Model	404
8.1	Statistics for the Computation of the Invariant Distribution	452
8.2	Credit Limit and Interest Rate	463
8.3	Results of Tax Reform Policies	479
9.1	Calibration of Employment Rates	532
9.2	Correlation of Income Shares and Output	539
10.1	Computation of the Steady State of the OLG Model	558
10.2	Calibration of the Large-Scale OLG Model	571
10.3	Computation of Laffer Curves: Runtime	574
10.4	Computation of the Transition Path: Runtime	588
11.1	Calibration of OLG Model with Idiosyncratic Uncertainty ..	639
11.2	Comparison of Runtime and Accuracy	644
11.3	Comparison of Runtime	672
11.4	Second Moments of the OLG Model of Example 11.3.1 . . .	689
11.5	Comparison of Second Moments Across Studies	691

11.6 Calibration of the OLG Model with Individual and Aggregate Uncertainty	697
11.7 Runtime: Krusell-Smith Algorithm and OLG Models	704
11.8 Cyclical Behavior of the Income Distribution	713
13.1 Tabulated Values of the Sine and Cosine Function	767
16.1 Iterative Computation of the Ergodic Distribution	862
16.2 Simulation of a Markov Chain	863

Acronyms

AD	automatic differentiation.....	106
AI	Artificial Intelligence	vii
AR(1)	first-order autoregressive	52
AR(2)	second-order autoregressive.....	473
CAS	computer algebra system	97
CES	constant elasticity of substitution	23
CPU	central processing unit	63
CRRA	constant relative risk aversion	43
DARE	discrete algebraic Riccati equation.....	90
DGE	dynamic general equilibrium.....	vi
DSGE	dynamic stochastic general equilibrium.....	xi
etc	and so forth.....	13
FOC	first-order conditions	4
FT	Fourier transform	160
GA	genetic algorithm	838
GDP	gross domestic product.....	54
GEU	generalized expected utility	276
GSS	generalized stochastic simulation.....	xxxii
HP	Hodrick-Prescott	59
IES	intertemporal elasticity of substitution	41
iid	independently and identically distributed.....	89
IRF	impulse response function	174
KKT	Karush-Kuhn-Tucker	7
LAPACK	linear algebra package	135
lhs	left-hand side	9
LP	linear programming.....	391
LQ	linear-quadratic	88

NIPA	national product and income accounts.....	54
NK	New Keynesian	187
OLG	overlapping generations.....	vii
OLS	ordinary least squares.....	498
PEA	parameterized expectations approach	234
rhs	right-hand side	9
SD	symbolic differentiation	106
s.t.	subject to	7
TAS	time-additive separable	10
TFP	total factor productivity	48
VAR(1)	first-order vector autoregressive	94
VI	value function iteration.....	x
wrt	with respect to	237

List of Symbols

\mathbb{Z}	set of all integers
\mathbb{R}	real line
\mathbb{R}_+	non-negative real numbers, i.e., $x \in \mathbb{R}$ and $x \geq 0$
\mathbb{R}_{++}	positive real numbers, i.e., $x \in \mathbb{R}$ and $x > 0$
\mathbb{R}^n	Euclidean n -space
\mathbb{C}^n	complex n -space
C^n	class of functions having n continuous derivatives
f' or $f^{(1)}$	first derivative of a single valued function of a single argument
f'' or $f^{(2)}$	second derivative of a single valued function of a single argument
$f^{(n)}$	n th order derivative of a single valued function of a single argument
f_i or $D_i f$ or f_{x_i}	first partial derivative of a single valued function with respect to its i th argument
f_{ij} or $D_i D_j f$ or $f_{x_i x_j}$	second partial derivative of a single valued function with respect to argument i and j (in this order)
$A = (a_{ij})$	n by m matrix A with typical element a_{ij}
$A^{-1} = (a^{ij})$	the inverse of matrix A with typical element a^{ij}
A', A^T	the transpose of the matrix $A = (a_{ij})$ with elements $A' = (a_{ji})$
$J(\bar{\mathbf{x}})$	the Jacobian matrix of the vector valued function $\mathbf{f}(\bar{\mathbf{x}})$ at the point $\bar{\mathbf{x}}$
$H(\bar{\mathbf{x}})$	the Hesse matrix of the single valued function $f(\bar{\mathbf{x}})$ at the point $\bar{\mathbf{x}}$

$\nabla f(\mathbf{x})$	the gradient of f at \mathbf{x} , that is, the row vector of partial derivatives $\partial f(\mathbf{x})/\partial x_i$
$\ \mathbf{x}\ _2$	the Euclidian norm (length) of the vector $\mathbf{x} \in \mathbb{R}^n$, which is given by $\sqrt{x_1^2 + x_2^2 + \cdots + x_n^2}$
$\text{tr}A$	the trace of the square matrix A , i.e., the sum of its diagonal elements
$\det A$	the determinant of the square matrix A
$\epsilon \sim N(\mu, \sigma^2)$	the random variable ϵ is normally distributed with mean μ and variance σ^2
\forall	for all
\exists	exists
$!$	factorial, i.e., $n! = 1 \times 2 \times \cdots \times n$.
$\binom{n}{k}$	binomial coefficient
$x = \underset{x}{\operatorname{argmin}} f(x)$	the value x that minimizes the function $f(x)$.

List of Programs

Fortran

BM_EPf90	323
BM_VI.f90	403
DGM_VI.f90	379
Differentiation.f90	
CDHesse	797
CDJac	796
IVDenEf90	451
Optimization.f90	
GaussNewton	834
GSearch1	845
GSearch2	845
GSS	831
SGM_NNI_VI.f90	400
SGM_VI.f90	390, 396, 405
SOE_EPf90	334

GAUSS

AK280_perturb.g	678, 680, 684, 690
AK60_direct.g	553
AK60_proj.g	560
AK60_value.g	557
AK70_prog_pen.g	664, 666, 722
AK70_stoch_inc.g	644, 652
AK70_stock_inc.g	643
BM_pert.g	56
CoRRAM_1.src	

SolveModel	144
CoRRAM_2.src	
HPFilter	869
Impulse1	175
Impulse2	175
CoRRAM_3.src	
Bisec	815
CDHesse	797
CDJac	796
costs_cycles.g	520
Demo_trans.g	591, 598, 605, 609
DGM_VI.g	379
DGM_WRM.g	257
dynamics_income_distrib.g	531, 532, 534
Function.src	
Cheb_coef	773
Cheb_eval	775
CSpline2_coef	781
CSpline2_eval	781
CSpline_coef	257, 761
CSpline_eval	257, 761
Find	760
LSpline_coef	760
LSpline_eval	760
GetPar.g	54
Gorman.g	419
IVDenFg	450, 503
equivc	442, 863
IVDisFg	444
IVdisFg	443
IVExpFg	455
IVMonteCarlo.g	452
Krusell_Smith_algo.g	514
Laffer.g	569, 573, 574, 621
Laffer_p.g	574, 578
NLEQ.src	
Fixp1	821
FixvMN1	821
FixvMN2	821
MNRStep	826

OLG6_trans.g	582, 585, 587, 588
OLG_Krusell_Smith.g	698, 708
Ramsey1.g	85
Ramsey2.g	314
Ramsey3.g	315
Ramsey4.g	318
Risk_free_rate.g	459
SGM_NNI_VI.g	400
SGM_VI.g	390, 405
GSS	440, 831
Markov_AR1_R	866
Markov_AR1_T	865
SGM_VI_MT.g	395
SOE.g	331
SVar.g	59
Tax_reform.g	477
transition_guess.g	503
transition_part.g	493–495, 503

Julia

AK60_value.jl	558
AK70_prog_pen.jl	664
AK70_stock_inc.jl	643

MATLAB[®]

BM_CGC.m	262
BM_CGT.m	262
BM_CGT_Eqs.m	262
BM_EPm	323
BM_GSS.m	347
BM_GSS_NN.m	347
BM_pert.m	56, 176
CDHesse.m	797
CDHesseRE.m	797
CDJac.m	796
ChebBase.m	787
Cubic.m	145
Der_BM.m	109
DGM.m	87
DGM_VI.m	379

DR_V1.m	280
DR_V2.m	289
DR_V3.m	293
DR_V4.m	297
DR_V5.m	297
DR_V6.m	302
DRV1_Eqs_Smolyak.m	282
DRV2_Eqs_Smolyak.m	293
DRV_V3.m	308
Example_Valder.m	109
GetPar.m	54, 178
GH_NW.m	806
GH_quad.m	806
GSearch1.m	340, 845
Impulse1.m	175
Impulse2.m	175, 308
Laffer.m	569, 573, 574, 621
Laffer_p.m	574, 578
Linear.m	145
LP_GSS_LR.m	356
Mon_quad.m	809
NK_Model.m	197
Num_Stab_Approx.m	345
Quadratic.m	145
Ramsey2.m	314
Ramsey3.m	315
Search_CGT.m	272, 275, 306
Search_CGT_Eqs.m	272
SGM_GSS.m	340
SGM_LPm	397
SGM_VI.m	390, 405
SOE_EPm	334
SolveModel.m	144
SVar.m	59
TTB.m	184
Python	
AK60_value.py	557
AK70_prog_pen.py	664, 667
AK70_stock_inc.py	643

IVDenF.py 450

OLG_Krusell_Smith.py698, 708

transition_part.py493