CS181 Practice Questions: Neural Networks and Decision Trees

1. Multiclass Classification Error Function (Bishop 5.5)

Consider a K-class supervised classification scenario with training data $\{x_n, t_n\}_{n=1}^N$, where the t_n are 1-hot binary vectors, with $t_{nk}=1$ iff x_n 's true class is k. Assume we model this problem using a neural network with K output-units, where the interpretation of the k'th output unit, denoted $y_k(x_n, w)$, is $y_k(x_n, w) = p(t_{nk}=1 \mid x_n)$. Show that maximizing the (conditional) likelihood of such a model is equivalent to minimizing the cross-entropy loss function given by

$$E(\mathbf{w}) = -\sum_{n=1}^{N} \sum_{k=1}^{K} t_{nk} \ln y_k(x, \mathbf{w})$$
 (Bishop 5.24)

2. Activation Gradients (Bishop 5.6)

Consider a single-output network solving a binary classification problem, and trained with the following cross-entropy error function

$$E(w) = -\sum_{n=1}^{N} [t_n \ln y(x_n, w) + (1 - t_n) \ln(1 - y(x_n, w))],$$
 (Compare Bishop 5.21)

where $y(x_n, w) = \sigma(a_n) = \frac{1}{1 + \exp(-a_n)}$ for an activation a_n . Show that the derivative of the error function above wrt a particular a_n satisfies

$$\frac{\partial E}{\partial a_n} = y(x_n, w) - t_n$$
 (Compare Bishop 5.18)

3. Positive Definiteness of Hessian (Bishop 5.10)

Consider a hessian matrix $oldsymbol{H} \in \mathbb{R}^D$ with eigenvector equation

$$Hu_d = \lambda_d u_d$$
, (Bishop 5.33)

where the eigenvectors u_d form an orthonormal basis of \mathbb{R}^D . As Bishop points out, since any vector $v \in \mathbb{R}^D$ can be written as

$$v = \sum_{d=1}^{D} c_d \mathbf{u}_d, \qquad \text{(Bishop 5.38)}$$

the orthonormality of the eigenvectors implies that

$$\boldsymbol{v}^{\mathsf{T}}\boldsymbol{H}\boldsymbol{v} = \sum_{d=1}^{D} c_d^2 \lambda_d.$$
 (Bishop 5.39)

- (a) As a first step, show how to derive (Bishop 5.39) from Bishop (5.38).
- (b) Now, recall that a matrix is positive definite if $v^T H v > 0$ for all nonzero v. Show that H is positive definite if and only if all of its eigenvalues are positive.

4. Approximate Hessian (Bishop 5.2)

The outer product approximation to the Hessian matrix for a neural network using a sum-of-squares error function is given by

$$H = \sum_{n=1}^{N} b_n b_n^{\mathsf{T}}$$
 $b_n = \nabla y_n = \nabla a_n$

This is the approximation to the Hessian matrix of $E = \frac{1}{2} \sum_{n=1}^{N} (y_n - t_n)^2$. Derive an expression for an approximation to the Hessian for the case of multiple outputs. Consider the multivariate generalization of the energy function:

$$E = \frac{1}{2} \sum_{n=1}^{N} (\boldsymbol{y}_n - \boldsymbol{t}_n)^{\mathsf{T}} (\boldsymbol{y}_n - \boldsymbol{t}_n)$$

5. Likelihood Function of Conditional (Bishop 5.2)

Show that maximizing the likelihood function under the conditional distribution given by

$$p(t|x, w) = \mathcal{N}(t|y(x, w), \beta^{-1}I)$$

for a multioutput neural network is equivalent to minimizing the sum of squares error function given by

$$E(w) = \frac{1}{2} \sum_{n=1}^{N} ||y(x_n, w) - t_n||^2$$

6. Degrees of Freedom of the Hessian (Bishop 5.13)

Determine that the number of independent elements (degrees of freedom) in the quadratic error function, given by the Taylor Expansion of the error function around the point \hat{w}

$$E(\boldsymbol{w}) = E(\hat{\boldsymbol{w}}) + (\boldsymbol{w} - \hat{\boldsymbol{w}})^{\mathsf{T}} \boldsymbol{b} + \frac{1}{2} (\boldsymbol{w} - \hat{\boldsymbol{w}})^{\mathsf{T}} \boldsymbol{H} (\boldsymbol{w} - \hat{\boldsymbol{w}})$$

is given by $\frac{W(W+3)}{2}$. Hint: What properties of the Hessian matrix restrict its number of independent elements?

7. Information Theory

Calculate the Shannon entropy of a fair coin, and the Shannon entropy of an unfair coin that comes up heads 80% of the time.

8. Choosing Attributes (Dublin University)

ID	Age	Income	Student	Credit	Buys
1	< 31	high	no	bad	no
2	< 31	high	no	good	no
3	31 - 40	high	no	bad	yes
4	> 40	med	no	bad	yes
5	> 40	low	yes	bad	yes
6	> 40	low	yes	good	no
7	31 - 40	low	yes	good	yes
8	< 31	med	no	bad	no
9	< 31	low	yes	good	yes
10	> 40	med	yes	bad	yes
11	< 31	med	yes	good	yes
12	31 - 40	med	no	good	yes
13	31 - 40	high	yes	bad	yes
14	> 40	med	no	good	no

A dataset collected in an electronics shop showing details of customers and whether or not they responded to a special offer to buy a new laptop is shown in the table above. We plan to use this dataset to build a decision tree to predict which customers will respond to future special offers. We are trying to decide on the root node of our decision tree with ID3. We are given that the information gain of the feature *Age* at the root node of the tree is 0.247. A colleague has suggested that *Student* would be a better feature to consider for the root node. Show that this is not the case.

9. More On Choosing Attributes (Dublin University)

In the above example, yet another colleague suggested that the ID attribute would be another good variable to consider at the root node. Would you agree with this suggestion? This should not require computation.

10. Classification Trees (Elements of Statistical Learning)

Consider a data set on which you were training a classification tree that contained elements from two classes, call them C_1 , C_2 . Now, suppose that we have 200 training points $\{x_i\}_{i=1}^{200}$, with 100 belonging to the first class and 100 belonging to the second class. Let the node (a,b) contains a elements of C_1 and b elements of C_2 . Now, suppose we produce two potential classification trees, T_1 , T_2 , where T_1 created a split that created nodes (75,25) and (25,75), while T_2 contained a split that created nodes (50,100), (50,0). Explain why T_2 is a preferable decision tree even though it causes the same misclassification error.

11. Entropy Intuition (Dublin University)

In problem 1 you calculated the Shannon entropy of a biased coin that comes up head 80% of the time. First, calculate the Shannon entropy of a fair coin and give an explanation for why the entropy of the biased coin is less than the entropy of the fair coin,

12. Decision Tree Recursion (Dublin University)

Suppose we are given a decision tree and we generate a dataset from the decision tree. We then train a new decision tree on this dataset, generate data from the new tree, and repeat this process. As the size of the training set approaches infinity, will we eventually return the original tree using the above recursive process? Note that we only care about "logical" equivalence (i.e., a decision tree that will produce the same outputs for a given input but may have a different structure).