

# CS181 Practice Questions: Linear Regression, Continued

## 1. Posterior Weight Distribution Using Bayes' Rule for Linear Gaussian Systems

**Some background:** In section (2.3.3), Bishop derives the following facts about linear Gaussian systems: assuming we have a marginal distribution on  $\mathbf{x}$  and a conditional distribution on  $\mathbf{y}$  given by

$$p(\mathbf{x}) = \mathcal{N}(\mathbf{x} | \boldsymbol{\mu}, \boldsymbol{\Lambda}^{-1}) \quad (2.113)$$

$$p(\mathbf{y} | \mathbf{x}) = \mathcal{N}(\mathbf{y} | \mathbf{A}\mathbf{x} + \mathbf{b}, \mathbf{L}^{-1}) \quad (2.114)$$

then

$$p(\mathbf{x} | \mathbf{y}) = \mathcal{N}(\mathbf{x} | \boldsymbol{\Sigma}(\mathbf{A}^\top \mathbf{L}(\mathbf{y} - \mathbf{b}) + \boldsymbol{\Lambda}\boldsymbol{\mu}), \boldsymbol{\Sigma}) \quad (2.116)$$

where

$$\boldsymbol{\Sigma} = (\boldsymbol{\Lambda} + \mathbf{A}^\top \mathbf{L} \mathbf{A})^{-1}. \quad (2.117)$$

Now, we know from (3.10) in Bishop that the regression likelihood can be written as

$$p(\mathbf{t} | \mathbf{w}) = \prod_{n=1}^N \mathcal{N}(t_n | \mathbf{w}^\top \boldsymbol{\phi}(\mathbf{x}_n), \beta^{-1}),$$

where  $\beta = \frac{1}{\sigma^2}$ . If the prior distribution on  $\mathbf{w}$  is given by  $p(\mathbf{w}) = \mathcal{N}(\mathbf{w} | \mathbf{m}_0, \mathbf{S}_0)$ , derive that the posterior distribution  $p(\mathbf{w} | \mathbf{t})$  is given by

$$p(\mathbf{w} | \mathbf{t}) = \mathcal{N}(\mathbf{w} | \mathbf{m}_N, \mathbf{S}_N)$$

where

$$\mathbf{m}_N = \mathbf{S}_N(\mathbf{S}_0^{-1}\mathbf{m}_0 + \beta\boldsymbol{\Phi}^\top \mathbf{t})$$

$$\mathbf{S}_N^{-1} = \mathbf{S}_0^{-1} + \beta\boldsymbol{\Phi}^\top \boldsymbol{\Phi}$$

in the following way:

- Write down the likelihood in the form of a multivariate Gaussian.
- Explain what we need to substitute for  $\mathbf{x}, \mathbf{y}, \boldsymbol{\mu}, \boldsymbol{\Lambda}, \mathbf{A}, \mathbf{b}, \mathbf{L}$  (respectively) in equations (2.113)-(2.117) to derive the posterior.

- (a) The likelihood can be written  $p(\mathbf{t} | \mathbf{w}) = \mathcal{N}(\mathbf{t} | \boldsymbol{\Phi}\mathbf{w}, \beta^{-1}\mathbf{I})$ .

(b) Substituting  $x = w, y = t, \mu = m_0, \Lambda = S_0^{-1}, A = \Phi, b = 0, L = \beta I$ , then using (2.117) we first get that  $\Sigma = S_N = (S_0^{-1} + \beta \Phi^T \Phi)^{-1}$ , and plugging into (2.116) we get that  $m_N = S_N(\beta \Phi^T I(t - 0) + S_0^{-1} m_0) = S_N(S_0^{-1} m_0 + \beta \Phi^T t)$ .

## 2. Posterior Weight Distribution By Completing the Square (Bishop 3.7)

We know from (3.10) in Bishop that the regression likelihood can be written as

$$p(\mathbf{t} | \mathbf{w}) = \prod_{n=1}^N \mathcal{N}(t_n | \mathbf{w}^\top \phi(\mathbf{x}_n), \beta^{-1}) \\ \propto \exp \left( -\frac{\beta}{2} (\mathbf{t} - \Phi \mathbf{w})^\top (\mathbf{t} - \Phi \mathbf{w}) \right),$$

where  $\beta = \frac{1}{\sigma^2}$  and in the second line above we have ignored the Gaussian normalizing constants. By completing the square, show that with a prior distribution on  $\mathbf{w}$  given by  $p(\mathbf{w}) = \mathcal{N}(\mathbf{w} | \mathbf{m}_0, \mathbf{S}_0)$ , the posterior distribution  $p(\mathbf{w} | \mathbf{t})$  is given by

$$p(\mathbf{w} | \mathbf{t}) = \mathcal{N}(\mathbf{w} | \mathbf{m}_N, \mathbf{S}_N)$$

where

$$\mathbf{m}_N = \mathbf{S}_N (\mathbf{S}_0^{-1} \mathbf{m}_0 + \beta \Phi^\top \mathbf{t}) \\ \mathbf{S}_N^{-1} = \mathbf{S}_0^{-1} + \beta \Phi^\top \Phi$$

Multiplying the likelihood and prior, we get

$$p(\mathbf{w} | \mathbf{t}) \propto p(\mathbf{t} | \mathbf{w}) p(\mathbf{w})$$

$$\propto \exp \left( -\frac{\beta}{2} (\mathbf{t} - \Phi \mathbf{w})^\top (\mathbf{t} - \Phi \mathbf{w}) \right) \exp \left( -\frac{1}{2} (\mathbf{w} - \mathbf{m}_0)^\top \mathbf{S}_0^{-1} (\mathbf{w} - \mathbf{m}_0) \right) \quad (1)$$

$$= \exp \left( -\frac{1}{2} \mathbf{w}^\top (\mathbf{S}_0^{-1} + \beta \Phi^\top \Phi) \mathbf{w} - \beta \mathbf{t}^\top \Phi \mathbf{w} - \beta \mathbf{w}^\top \Phi^\top \mathbf{t} + \beta \mathbf{t}^\top \mathbf{t} - \mathbf{m}_0^\top \mathbf{S}_0^{-1} \mathbf{w} \right. \\ \left. - \mathbf{w}^\top \mathbf{S}_0^{-1} \mathbf{m}_0 + \mathbf{m}_0^\top \mathbf{S}_0^{-1} \mathbf{m}_0 \right) \quad (2)$$

$$= \exp \left( -\frac{1}{2} \mathbf{w}^\top (\mathbf{S}_0^{-1} + \beta \Phi^\top \Phi) \mathbf{w} - (\mathbf{S}_0^{-1} \mathbf{m}_0 + \beta \Phi^\top \mathbf{t})^\top \mathbf{w} - \mathbf{w}^\top (\mathbf{S}_0^{-1} \mathbf{m}_0 + \beta \Phi^\top \mathbf{t}) \right. \\ \left. + \beta \mathbf{t}^\top \mathbf{t} + \mathbf{m}_0^\top \mathbf{S}_0^{-1} \mathbf{m}_0 \right) \quad (3)$$

$$= \exp \left( -\frac{1}{2} (\mathbf{w} - \mathbf{m}_N)^\top \mathbf{S}_N^{-1} (\mathbf{w} - \mathbf{m}_N) \right) \exp \left( -\frac{1}{2} (\beta \mathbf{t}^\top \mathbf{t} + \mathbf{m}_0^\top \mathbf{S}_0^{-1} \mathbf{m}_0 - \mathbf{m}_N^\top \mathbf{S}_N^{-1} \mathbf{m}_N) \right), \quad (4)$$

where the first exponential in (4) has the form of the desired (unnormalized) Gaussian, and the second exponential in (4) doesn't involve  $\mathbf{w}$ , and so can be absorbed into the Gaussian's normalization constant.

To derive (4) from (3), note that plugging in the definitions of  $\mathbf{m}_N$  and  $\mathbf{S}_N^{-1}$  into the first exponential in (4) and multiplying through gives us all the terms in (3) involving  $\mathbf{w}$ , except with an additional  $\mathbf{m}_N^\top \mathbf{S}_N^{-1} \mathbf{m}_N$  term. We subtract this off in the second exponential, and also collect there the other terms not involving  $\mathbf{w}$ , which are absorbed into the normalization.

### 3. Predictive Distribution

Bishop notes in section (3.2.2) that if our prior distribution on  $\boldsymbol{w}$  is

$$p(\boldsymbol{w}) = \mathcal{N}(\boldsymbol{w} \mid \mathbf{0}, \alpha^{-1} \boldsymbol{I}),$$

and if we assume again that our likelihood involves an inverse variance parameter  $\beta$ , then the predictive distribution of  $t$  for a new datapoint  $\boldsymbol{x}$  is given by

$$p(t \mid \boldsymbol{t}, \alpha, \beta) = \int p(t \mid \boldsymbol{w}, \beta) p(\boldsymbol{w} \mid \boldsymbol{t}, \alpha, \beta) d\boldsymbol{w} \quad (3.57)$$

Does the equation in (3.57) make any independence assumptions about the variables involved? If so, which?

Yes, it assumes that  $t$  is independent of  $\boldsymbol{t}$  (and  $\alpha$ ) given  $\boldsymbol{w}$ . This can be seen, for instance, by writing out  $p(t, \boldsymbol{w} \mid \boldsymbol{t}, \alpha, \beta)$  and using the chain rule of probability.

#### 4. Deriving Lasso Regularization with Lagrange Multipliers

Show that minimization of the unregularized sum-of-squares error function given by

$$E_D(\mathbf{w}) = \frac{1}{2} \sum_{n=1}^N (t_n - \mathbf{w}^\top \phi(\mathbf{x}_n))^2,$$

subject to the constraint

$$\sum_{j=1}^M |w_j| \leq \eta,$$

is equivalent to minimizing the regularized error function

$$\frac{1}{2} \sum_{n=1}^N (t_n - \mathbf{w}^\top \phi(\mathbf{x}_n))^2 + \frac{\lambda}{2} \sum_{j=1}^M |w_j|$$

Rewrite the constraint as

$$\sum_{j=1}^M |w_j| - \eta \leq 0$$

We get the Lagrangian function

$$L(\mathbf{w}, \lambda) = \frac{1}{2} \sum_{n=1}^N (t_n - \mathbf{w}^\top \phi(\mathbf{x}_n))^2 + \frac{\lambda}{2} \sum_{j=1}^M (|w_j| - \eta)$$

where we introduce the factor of 1/2 in front of the second term for convenience. We see immediately that the above function is equal to the regularized error function plus the terms of  $\eta$  which do not depend on  $\mathbf{w}$ . Therefore, minimizing the Lagrangian with respect to  $\mathbf{w}$  will give the same  $\mathbf{w}^*$  as minimizing the regularized error function.

## 5. Connection between Priors and Regularization

Consider the Bayesian linear regression model given in Bishop 3.3.1. The prior is given by

$$p(\mathbf{w}|\alpha) = \mathcal{N}(\mathbf{w}|\mathbf{0}, \alpha^{-1}\mathbf{I}),$$

where  $\alpha$  is the precision parameter that controls the variance of the Gaussian prior. The likelihood can be written as

$$p(\mathbf{t}|\mathbf{w}) = \prod_{n=1}^N \mathcal{N}(t_n | \mathbf{w}^\top \phi(\mathbf{x}_n), \beta^{-1}),$$

Using the fact that the posterior is the product of the prior and the likelihood, show that maximizing the log posterior (i.e.  $\ln p(\mathbf{w}|\mathbf{t}) = \ln p(\mathbf{w}|\alpha) + \ln p(\mathbf{t}|\mathbf{w})$ ) is equivalent to minimizing the regularized error term given by  $E_D(\mathbf{w}) + \lambda E_W(\mathbf{w})$  with

$$E_D(\mathbf{w}) = \frac{1}{2} \sum_{n=1}^N (t_n - \mathbf{w}^\top \phi(\mathbf{x}_n))^2$$
$$E_W(\mathbf{w}) = \frac{\lambda}{2} \mathbf{w}^\top \mathbf{w}$$

Do this by writing  $\ln p(\mathbf{w}|\mathbf{t})$  as a function of  $E_D(\mathbf{w})$  and  $E_W(\mathbf{w})$ , dropping constant terms if necessary.

Conclude that maximizing this posterior is equivalent to minimizing the regularized error term given by  $E_D(\mathbf{w}) + \lambda E_W(\mathbf{w})$ .

(Hint: take  $\lambda = \alpha/\beta$ )

Expanding the posterior gives

$$\begin{aligned} p(\mathbf{w}|\mathbf{t}) &= p(\mathbf{w}|\alpha) p(\mathbf{t}|\mathbf{w}) \implies \\ \ln p(\mathbf{w}|\mathbf{t}) &= \ln p(\mathbf{w}|\alpha) + \ln p(\mathbf{t}|\mathbf{w}) \\ &= \sum_{n=1}^N \ln \mathcal{N}(t_n | \mathbf{w}^\top \phi(\mathbf{x}_n), \beta^{-1}) + \ln \mathcal{N}(\mathbf{w} | \mathbf{0}, \alpha^{-1}\mathbf{I}) \\ &= \sum_{n=1}^N -\frac{\beta}{2} (t_n - \mathbf{w}^\top \phi(\mathbf{x}_n))^2 + \text{const} - \frac{1}{2} \alpha \mathbf{w}^\top \mathbf{w} + \text{const} \\ &= -\beta E_D(\mathbf{w}) - \alpha E_W(\mathbf{w}) \end{aligned}$$

Taking  $\lambda = \alpha/\beta$ , note that minimizing this function is equivalent to maximizing its negative, and that multiplying by a constant positive factor ( $1/\beta$ ) has no effect on the extrema, and we have the result.

## 6. Bayesian Updates in Linear Regression, Bishop 3.8

Suppose we have the standard Bayesian linear regression model and we have already observed  $N$  data points, so the posterior distribution is the same as the one derived in problem 2,

$$p(\mathbf{w} | \mathbf{t}) = \mathcal{N}(\mathbf{w} | \mathbf{m}_N, \mathbf{S}_N)$$

where

$$\begin{aligned}\mathbf{m}_N &= \mathbf{S}_N(\mathbf{S}_0^{-1}\mathbf{m}_0 + \beta\mathbf{\Phi}^T\mathbf{t}) \\ \mathbf{S}_N^{-1} &= \mathbf{S}_0^{-1} + \beta\mathbf{\Phi}^T\mathbf{\Phi}\end{aligned}$$

Suppose we observe a new data point  $(x_{N+1}, t_{N+1})$ . Show that the resulting posterior distribution is of the same form with  $\mathbf{m}_{N+1}$  and  $\mathbf{S}_{N+1}$ .

We proceed by completing the square, as in problem 2.

The prior is of the form

$$p(\mathbf{w}) = \mathcal{N}(\mathbf{w} | \mathbf{m}_N, \mathbf{S}_N),$$

and the likelihood is given by

$$p(t_{N+1} | x_{N+1}, \mathbf{w}) = (\beta/2\pi)^{1/2} \exp\left(-\beta/2(t_{N+1} - \mathbf{w}^T\phi_{N+1})^2\right)$$

where  $\phi_{N+1} = \phi(x_{N+1})$ . Then the posterior is

$$p(\mathbf{w} | \mathbf{t}) \propto \exp\left(-\frac{1}{2}(\mathbf{w} - \mathbf{m}_N)^T \mathbf{S}_N^{-1}(\mathbf{w} - \mathbf{m}_N) - \frac{1}{2}\beta(t_{N+1} - \mathbf{w}^T\phi_{N+1})^2\right)$$

Completing the square in the exponential just as we did in problem 2, we get

$$\begin{aligned} & (\mathbf{w} - \mathbf{m}_N)^T \mathbf{S}_N^{-1}(\mathbf{w} - \mathbf{m}_N) + \beta(t_{N+1} - \mathbf{w}^T\phi_{N+1})^2 \\ &= \mathbf{w}^T \mathbf{S}_N^{-1} \mathbf{w} - 2\mathbf{w}^T \mathbf{S}_N^{-1} \mathbf{m}_N + \beta \mathbf{w}^T \phi_{N+1}^T \phi_{N+1} \mathbf{w} - 2\beta \mathbf{w}^T \phi_{N+1} t_{N+1} + \text{const} \\ &= \mathbf{w}^T (\mathbf{S}_N^{-1} + \beta \phi_{N+1} \phi_{N+1}^T) \mathbf{w} - 2\mathbf{w}^T (\mathbf{S}_N^{-1} \mathbf{m}_N + \beta \phi_{N+1} t_{N+1}) + \text{const} \end{aligned}$$

Plugging this back in to the expression for the posterior we get

$$p(\mathbf{w} | \mathbf{t}) = \mathcal{N}(\mathbf{w} | \mathbf{m}_{N+1}, \mathbf{S}_{N+1})$$

where

$$\begin{aligned}\mathbf{m}_{N+1} &= \mathbf{S}_{N+1}(\mathbf{S}_N^{-1}\mathbf{m}_N + \beta\phi_{N+1}t_{N+1}) \\ \mathbf{S}_{N+1}^{-1} &= \mathbf{S}_N^{-1} + \beta\phi_{N+1}\phi_{N+1}^T\end{aligned}$$