SRM INSTITUTE OF SCIENCE & TECHNOLOGY

Kattankulathur, Kancheepuram 603203, Tamil Nadu, India

25. B. Tech in Electronics and Communication Engineering (with specialization in Instrumentation Engineering)

25. (a) Mission of the Department

Mission Stmt - 1	Build an educational process that is well suited to local needs as well as satisfies the national and international
Wild Stort Ottric - 1	accreditation requirements
Mission Stmt - 2	Attract the qualified professionals and retain them by building an environment that foster work freedom and
IVIISSION SUNC - Z	empowerment.
Mission Stmt - 3	With the right talent pool, create knowledge and disseminate, get involved in collaborative research with reputed institutes,
IVIISSIUTI SUTIL - 3	and produce competent graduands.

25. (b) Program Educational Objectives (PEO)

The Program Educational Objectives for the Electronics and Communication Engineering (with specialization in Instrumentation Engineering) program describe accomplishments that graduates are expected to attain within five years after graduation. Graduates within 5 years of graduation will / should demonstrate:

9	The state of the s
PEO – 1	Expertise using their mathematical and scientific knowledge to solve emerging real-world problems, design and create novel products and solutions related to Electronics and Instrumentation System Design that are technically sound, economically feasible
	and socially acceptable.
PEO – 2	Broad knowledge to establish themselves as creative practicing professionals, locally and globally, in fields such as design,
	research, testing and manufacturing of Electronics and Instrumentation Systems.
PEO – 3	Communication skills (in both written and oral forms) and critical reasoning skills in bridging the divide between advanced
FLO-3	technology and end users in the practice of Instrumentation Engineering.
PEO – 4	Sustained learning and adapting to a constantly changing field through graduate work, professional development, self-study and
PEU - 4	collaborative activities.
PEO – 5	Leadership and initiative to ethically advance professional and organizational goals, facilitate the achievements of others, and
PEU - 3	obtain substantive results.
PEO – 6	Ability to work productively as individuals and in groups (teamwork) of diverse cultural and multidisciplinary backgrounds.

25. (c) Mission of the Department to Program Educational Objectives (PEO) Mapping

	Mission Stmt 1	Mission Stmt 2	Mission Stmt 3
PEO - 1	L	M	Н
PEO - 2	Н	L	Н
PEO - 3	L	L	M
PEO - 4	M	L	M
PEO - 5	L	Н	Н
PEO - 6	Н	Н	Н

H-High Correlation, M-Medium Correlation, L-Low Correlation

25. (d) Mapping Program Educational Objectives (PEO) to Program Learning Outcomes (PLO)

						Prog	gram Leai	rning Out	comes (P	LO)					
					Gra	duate At	tributes (0	GA)					Prog Out	cific (SO)	
	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
PEO - 1	Н		Н			Н	M	Н			Н		Н		Н
PEO - 2		Н	M	Н	M									Н	M
PEO - 3					L			М		Н			L	L	M
PEO - 4												Н	М		
PEO - 5						L			М						M
PEO - 6						М			Н						M

H – High Correlation, M – Medium Correlation, L – Low Correlation

Program Specific Outcomes (PSO)

Graduates of baccalaureate degree program in ECE with Specialization in Instrumentation Engineering must demonstrate the ability to

- PSO 1 Apply concepts of automatic control, including measurement, feedback and feedforward regulation for the operation of continuous and discrete systems.
- PSO 2 Understand and utilize programmable logic controllers (PLC), distributed control systems (DCS) and supervisory control systems for control of manufacturing and processing systems.
- PSO 3 Utilize modern and effective management skills for performing investigation, analysis, and synthesis in the implementation of automatic control systems.

25. (e) Program Structure for B.Tech in Electronics and Communication Engineering (with specialization in Instrumentation Engineering)

	Humanities & Social Sciences including Management Courses (H)				
Course	Course	Hou	ırs/ V	/eek	
Code	Title	L	Τ	Р	С
18LEH101J	English	2	0	2	3
18LEH102J	Chinese				
18LEH103J	French				
18LEH104J	German	2	0	2	3
18LEH105J	Japanese				
18LEH106J	Korean				
18PDH101L	General Aptitude	0	0	2	1
18PDH102T	Management Principles for Engineers	2	0	0	2
18PDH103J	Social Engineering	1	0	2	2
18PDH201L	Employability Skills & Practices	0	0	2	1
	Total Learning Credits				12

	2. Basic Science Courses (B)				
Course	Course		lour Nee		
Code	Title	L	Τ	Р	С
18PYB101J	Physics: Electromagnetic Theory, Quantum Mechanics, Waves and Optics	3	1	2	5
18CYB101J		3	1	2	5
18MAB101T	Calculus and Linear Algebra	3	1	0	4
18MAB102T	Advanced Calculus and Complex Analysis	3	1	0	4
18MAB201T	Transforms and Boundary Value Problems	3	1	0	4
18MAB203T	Probability and Stochastic Process	3	1	0	4
18MAB302T	Discrete Mathematics for Engineers	3	1	0	4
18BTB101T	Biology	2	0	0	2
	Total Learning Credits				32

	3. Engineering Science Courses (S)				
Course	Course		lours Neel		
Code	Title	L	Τ	Р	С
18MES101L	Engineering Graphics and Design	1	0	4	3
18EES101J	Basic Electrical and Electronics Engineering	3	1	2	5
18MES103L	Civil and Mechanical Engineering Workshop	1	0	4	3
18CSS101J	Programming for Problem Solving	3	0	4	5
18ECS201T	Control Systems	3	0	0	3
	Total Learning Credits				19

	4. Professional Core Courses I				
Course	Course		lours Neel		
Code	Title	L	Τ	А	С
18ECC102J	Electronic Devices	3	0	2	4
18ECC103J	Digital Electronic Principles	3	0	2	4
18ECC104T	Signals and Systems	3	1	0	4
18ECC105T	Electromagnetics and Transmission Lines	3	0	0	3
18ECC201J	Analog Electronic Circuits	3	0	2	4
18ECC202J	Linear Integrated Circuits	3	0	2	4
18ECC203J	Microprocessor, Microcontroller and Interfacing Techniques	3	0	2	4
18ECC204J	Digital Signal Processing	3	0	2	4
18ECC205J	Analog and Digital Communication	3	0	2	4
18ECC206J	VLSI Design	3	0	2	4
18ECC301T	Wireless Communications	3	1	0	4
18ECC302J	Microwave & Optical Communications	3	0	2	4
18ECC303J	Computer Communication Networks	3	0	2	4
18ECC350T	Comprehension	0	1	0	1
	Total Learning Credits				52

	5. Professional Elective Courses (E)				
Course	Course	Hou	rs/ W	/eek	
Code	Title	L	Т	Р	С
	Professional Elective – 1	3	0	0	3
	Professional Elective – 2	თ	0	0	3
	Professional Elective – 3	3	0	0	3
	Professional Elective – 4	3	0	0	3
	Professional Elective – 5	3	0	0	3
	Professional Elective – 6	3	0	0	3
	Total Learning Credits				18

	6. Open Elective Courses (O)					
Course	Course	Hou	rs/ W	/eek		
Code	Title	L	Т	Р	С	
	Open Elective – 1	3	0	0	3	
	Open Elective – 2	3	0	0	3	
	Open Elective – 3	3	0	0	3	
	Open Elective – 4	3	0	0	3	
Total Learning Credits						

	7. Project Work, Seminar, Internship In Industry / Higher Technical Institutions (P)											
Course	Course		lours Neel									
Code	Title	L	T	Р	С							
18ECP101L	Massive Open Online Course- I											
18ECP102L	Industrial Training - I	0	0	2	1							
18ECP103L	Seminar – I											
18ECP104L	Massive Open Online Course- II											
18ECP105L	Industrial Training - II	0	0	2	1							
18ECP106L	Seminar – II											
18ECP107L	Minor Project	0	0	6	3							
18ECP108L	Internship (4-6 weeks)											
18ECP109L	Project	0	0	20	10							
18ECP110L	Semester Internship											
Total Learning Credits												

	8. Mandatory Courses (M)							
Course	Course Course Hours/ Week							
Code	Title	L	Τ	Р	С			
18PDM101L	Professional Skills & Practices	0	0	2	0			
18PDM201L	Competencies in Social Skills	0	0	2	0			
18PDM202L	Critical & Creative Thinking Skills	0	0	2	0			
18PDM301L	Analytical & Logical Thinking Skills	0	0	2	0			
18LEM101T	Constitution of India	1	0	0	0			
18LEM104J	Value Education	1	0	1	0			
18GNM101L	Physical & Mental Health using Yoga	0	0	2	0			
18GNM102L	NCC / NSS / NSO	0	0	2	0			
18LEM109T	Indian Traditional Knowledge	1	0	0	0			
18LEM110L	Indian Art Form	0	0	2	0			
18CYM101T	Environmental Science	1	0	0	0			
	Total Learning Credits	•			0			

	List of Professional Elective Courses (E)				
Course	Course	Hou	rs/ W	/eek	
Code	Title	L	Τ	Р	С
18ECE180J	Transducer Engineering	2	0	2	3
18ECE181T	Measurements and Instrumentation	3	0	0	3
18ECE182T	Automotive Instrumentation Systems	3	0	0	3
18ECE183T	Safety Instrumented System	3	0	0	3
18ECE280T	Industrial Instrumentation	3	0	0	3
18ECE281J	Process Dynamics and Control	2	0	2	3
18ECE282T	Modern Control System	3	0	0	3
18ECE283J			0	2	3
18ECE284J	Graphical System Design in Virtual Instrumentation	2	0	2	3
18ECE380T	Instrumentation and Control in Process Industries	3	0	0	3
18ECE381T	Distributed Control System and SCADA	3	0	0	3
18ECE382T	Building Automation	3	0	0	3
18ECE383J	Instrumentation System Design	2	0	2	3
18ECE384T	Factory Instrumentation Networks	3	0	0	3
18ECE385T	IoT in Process Instrumentation and Automation	3	0	0	3
18ECE386T	MEMS-based Microsystems Analysis and Design	3	0	0	3
18ECE387T	Microsensors and Smart Devices	3	0	0	3

	List of Open Elective Courses (O)				
	Any 4 Courses				
Course	Course	Hou	rs/ W	eek	
Code	Title	L	Т	Р	С
18ECO101T	Short-Range Wireless Communication	3	0	0	3
	Electronic Circuits & Systems	2	0	2	3
18ECO103T	Modern Wireless Communication Systems	3	0	0	3
18ECO104J	Audio and Speech Signal Processing	2	0	2	3
18ECO105T	Underwater Acoustics	3	0	0	3
18ECO106J	PCB Design and Manufacturing	2	0	2	3
18ECO107T	Fiber Optics and Optoelectronics	თ	0	0	3
18ECO108J	Embedded System Design using Arduino	2	0	2	3
18ECO109J	Embedded System Design using Raspberry Pi	2	0	2	3
18ECO110J	3D Printing Hardware and Software	2	0	2	3
18ECO131J	Virtual Instrumentation	2	0	2	3
18ECO132T	Analytical Instrumentation	3	0	0	3
18ECO133T	Logic and Distributed Control System	3	0	0	3
18ECO134T	Sensors and Transducers	3	0	0	3
18ECO135T	Fundamentals of MEMS	3	0	0	3
18ECO121T	Basics of Biomedical Engineering	3	0	0	3
18ECO122T	Hospital Information Systems	3	0	0	3
18ECO123T	Biomedical Imaging	3	0	0	3
18ECO124T	Human Assist Devices	3	0	0	3
18ECO125T	Quality Control for Biomedical Devices	3	0	0	3
18ECO126T	Sports Biomechanics	3	0	0	3

25. (f) Program Articulation for B.Tech in Electronics and Communication Engineering (with specialization in

Course Code						Progr Grad					mes	(PLO)			
						Grad	uate	Δttrik	nutae							
								~ · · · · · ·	Jules	•				PS0		
	Course Name	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	ndividual & Team Work	Communication	Project Mgt. & Finance	ife Long Learning	Automatic Control	Control of manufacturing and	Effective Management Skills
18EES101J	Basic Electrical and Electronics Engineering	Н	М	Н	M	L	-	-	-	-	-	-	-	٠.	-	Н
18MES103L (Civil and Mechanical Engineering Workshop	М	-	-	Н	Н	-		-	-	Н		L	М	L	-
	Control Systems	Н	Н	-	-	-	-	-	-	-	-	-	-	Н	-	-
18ECC102J	Electronic Devices	Н	-	-	-	Н	-	-	L	Н	М	-	М	L	L	-
18ECC103J [Digital Electronic Principles	Н	М	Н	-	Н	-	-	-	Н	-	-	-	М	-	L
	Signals and Systems	Н	Н	М	М	М	-	-	-	-	-	-	-	L	-	L
	Electromagnetics and Transmission Lines	М	Н	-	-		-	-	-	-	-	-	L		-	М
	Analog Electronic Circuits	L	М	Н	-	М	-	-	-	М	-	-	М	Н	L	
	Linear Integrated Circuits	Н	М	Н	-	М	_	-	_	М	-	-	_	Н	L	Н
	Microprocessor, Microcontroller and Interfacing Techniques	М	М	М	-	Н	_	-	_	-	Н	-	Н	L	-	М
	Digital Signal Processing	Н	М	Н	-	-	-	-	-	-	-		-	М	-	Н
	Analog and Digital Communication	М	Н	Н	М	Н	-	-	-	Н	Н	-	М	Н	М	Н
	VLSI Design	Н	М	М	-	Н	_	_	-	Н	М	L	M	11	-	М
-	Wireless Communication	Н	Н	Н	Н	M	-	-	-	-	M	-	M	M	-	Н
		_		Н	М		-			-		-		M	-	
-	Microwave & Optical Communications	Н	Н			-		-	-		-		-			М
	Computer Communication Networks	-	-	M	-	L	L	М	-	-	-	-	М	-	-	H
18ECD1011 /	Comprehension	Н	Н	М	L	L	L	L	L	L	L	L	L	М	М	М
18ECP104L	Massive Open Online Course-I/II	-	-	-	-	-	М	L	-	-	Н	-	Н	-	М	-
18ECP105L	Industrial Training-I/II	Н	М	М	М	М	L	М	Н	Н	М	Н	М	L	L	L
18ECP106L	Seminar-I/II	-	М	М	Н	-	М	Н	-	-	Н	-	М	-	-	-
18ECP 108L	Minor Project / Internship (4-6 weeks)	Н	Н	Н	Н	М	М	Н	М	М	М	М	L	М	М	М
TOECPTIOL	Project / Semester Internship	Н	Н	Н	Н	Н	Н	Н	Н	Н	Н	Н	Н	Н	Н	Н
	Transducer Engineering	Н	М	М	М	-	-	-	-	Н	-	-	-	М	М	Н
	Measurements and Instrumentation	Н	М	М	L	-	-	-	-	-	-	-	-	L	L	-
	Automotive Instrumentation Systems	Н	М	М	L	М	М	М		-	-	-	M	Н	М	-
	Safety Instrumented System	M	L	L	-	-	Н	М	Н	-	-	-	-	-	-	-
	Industrial Instrumentation	Н	М	М	L	-	-	-	-	-	-	-	-	L	L	-
	Process Dynamics and Control	Н	Н	Н	М	М	-	-	-	Н	-	-	-	Н	Н	Н
	Modern Control System	Н	Н	Н	М	Н	-	-	-	-	-	-	Н	Н	М	
18ECE283J F	Programmable Logic Controller	Н	Н	Н	М	Η	-		-	Н			Н	Н	Н	Н
18ECE284J	Graphical System Design in Virtual Instrumentation	-	-	-	-		-		-	-			-	-	-	-
18ECE380T	Instrumentation and Control in Process Industries	Н	L	М	-	-	-	М	-	-	-	-	-	Н	Н	-
18ECE381T [Distributed Control System and SCADA	Н	М	М	-	Η	-	1	-	-	1	1	Н	Н	Н	-
18ECE382T F	Building Automation	Н	L	М	_	Н	Н	Н		_	-	_	-	Н	Н	Н
18ECE383J	Instrumentation System Design	Н	Η	Н	Н	М	•	-		Н	-	-	-	L	М	L-
18ECE384T F	Factory Instrumentation Networks	Н	L	L	Н	1	М	1	М	-	-	1	-	М	М	М
18ECE385T	IoT in Process Instrumentation and Automation	Н	L	М	Н	М	-	-	-	-	-	-	Н	Н	М	Н
18ECE386T	MEMS-based Microsystems Analysis and Design	Н	Н	Н	Н	Н	-	-	Н	Н	-	-	Н	М	-	Н
1 1	Microsensors and Smart Devices	Н	Н	М	Н	М	Н	-	-	Н	-	-	Н	Н	-	Н

H – High Correlation, M – Medium Correlation, L – Low Correlation, PSO – Program Specific Outcomes (PSO)

25. (g) Implementation Plan for B. Tech in Electronics and Communication Engineering (with specialization in Instrumentation Engineering)

	Code Course Title Hours/ Week L T P C	2 3 n 3 1 1 1 1 0	T 0 1 1 0 0 0 0	P 2 0 2 4 2 2 0 0	5 3 4 5 5 5 1 0		
Code	Code	2 3 n 3 1 1 1 1 0	T 0 1 1 0 0 0 0	P 2 0 2 4 2 2 0 0	3 4 5 3 5 1 0		
	18LEH102J-	3 n 3 n 3 n 3 n 3 n 3 n 3 n 3 n 3 n 3 n	0 1 1 0 1 0 0	2 0 2 4 2 2 0	4 5 3 5 1 0		
	18LEH106J Japanese / Korean 2	3 n 3 n 3 n 3 n 3 n 3 n 3 n 3 n 3 n 3 n	1 1 0 1 0 0	0 2 4 2 2 0	5 3 5 1 0		
	18CYB101J Chemistry 3 1 2 5 18CSS101J Programming for Problem Solving 3 0 4 5 18MES103L Civil and Mechanical Engineering Workshop 1 0 4 3 18EES101L Engineering Graphics and Design 18EES101J Basic Electrical and Electronics Engineering 18EEM101T Constitution of India 18EM101T Constitution of India 18EM101T Physical and Mental Health using Yoga Total Learning Control Engineering 18EES101J Basic Electrical and Electronics 18EE	1 1 1 0 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	0 1 0 0	4 2 2 0	3 5 1 0		
	18CSS101J	1 1g 3 0 1	0 1 0 0	4 2 2 0	3 5 1 0		
IBBESTION Semester - III	18MES103L Civil and Mechanical Engineering Workshop 1 0 4 3 18EES101J Basic Electrical and Electronics Engineering 18PDM101L Professional Skills and Practices 0 0 2 0 18PDM101L Value Education 1 0 1 0 1 0 18GNM102L NCC / NSS / NSO 0 0 2 0 0 0 2 0 0 0	0 1 0	0 0	2 2 0	5 1 0		
	18PDM101L Professional Skills and Practices 0 0 2 0 18LEM102J Value Education 1 0 1 0 1 0 18GNM102L NCC / NSS / NSO 0 0 0 2 0 18EM101T Constitution of India 18GNM101L Physical and Mental Health using Yoga Total Learning Credits 20 Total Learning Credits Semester - III Code Course Title Hours/ Week L T P C Code Code Course Title 18MAB201T Transforms and Boundary Value Problems 3 1 0 4 18MAB203T Probability and Stochastic Process 18ECS201T Control Systems 3 0 0 3 18BTB10TT Biology	0 1 0	0	0	1		
	18LEM102J Value Education	1 0	Hours/ Week		0		
	18GNM102L NCC / NSS / NSO	0	Hours/ Week L T P 3 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0				
Semester - III	Total Learning Credits 20 Total Learning Credits 20		Hours/ Week T P 3 0 0 2 3 0 0 2 3 0 0 0 0 0 0 0 0 0				
Semester - III	Semester - III	redits					
Code	Code Course Title Hours/ Week L T P C C Code Course Title 18MAB201T Transforms and Boundary Value Problems 3 1 0 4 18MAB203T Probability and Stochastic Process 18ECS201T Control Systems 3 0 0 3 18BTB101T Biology				21		
Code	Code Course Title Hours/ Week L T P C C Code Course Title 18MAB201T Transforms and Boundary Value Problems 3 1 0 4 4 18MAB203T Probability and Stochastic Process 18ECS201T Control Systems 3 0 0 3 18BTB101T Biology						
Code	Code Course little L T P C Code Code Course little 18MAB201T Transforms and Boundary Value Problems 3 1 0 4 18MAB203T Probability and Stochastic Process 18ECS201T Control Systems 3 0 0 3 18BTB101T Biology						
18MB2017 Transforms and Boundary Value Problems 3 1 0 4 18ECS2017 Control Systems 3 0 0 3 18BBTB1017 Biology 2 0 0 2 18BCC103J Digital Electronic Principles 3 0 2 4 18ECC2013J Digital Electronic Principles 3 0 2 4 18ECC2014 Signals and Systems 3 1 0 4 18ECC2015 Electronic pretices and Transmission Lines 3 0 0 2 18ECC2015 Electronic pretices and Transmission Lines 3 0 0 2 18ECC2015 Electronic pretices and Transmission Lines 3 0 0 2 18ECC2015 Electronic pretices and Transmission Lines 3 0 0 2 18ECC2017 Electronic pretices and Transmission Lines 3 0 0 2 18ECC2017 Electronic pretices and Transmission Lines 3 0 0 2 18ECC2014 Electronic pretices and Transmission Lines 3 0 0 2 18ECC2014 Electronic pretices and Transmission Lines 3 0 0 2 18ECC2014 Electronic pretices and Transmission Lines 3 0 0 2 18ECC2014 Electronic pretices and Transmission Lines 3 0 0 2 18ECC2014 Electronic pretices and Transmission Lines 3 0 0 2 18ECC2014 Electronic pretices and Transmission Lines 3 0 0 2 18ECC2014 Electronic pretices and Transmission Lines 3 0 0 2 18ECC2014 Electronic pretices and Transmission Lines 3 0 0 2 18ECC2014 Electronic pretices and Transmission Lines 3 0 0 2 18ECC2014 Electronic pretices and Transmission Lines 3 0 0 2 18ECC2014 Electronic pretices and Transmission Lines 3 0 0 2 18ECC2014 Electronic pretices and Transmission Lines 3 0 0 2 18ECC2014 Electronic pretices and Transmission Lines 3 0 0 2 18ECC2014 Electronic pretices 3 0 0 2 18ECC2014 Electronic pretices 3 0 0 2 18ECC2014 Electronic pretices 4 1 1 1 1 1 1 1 1 1	18MAB201T Transforms and Boundary Value Problems 3 1 0 4 18MAB203T Probability and Stochastic Process 18ECS201T Control Systems 3 0 0 3 18BTB101T Biology				С		
	18ECS201T Control Systems 3 0 0 3 18BTB101T Biology			_			
SECC102J Electronic Devices					4		
BECC103J Digital Electronic Principles 3 0 2 4	10000101 51 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1				2		
RECC104T Signals and Systems 3 1 0 4					4		
					4		
18PDH103J Social Engineering 1							
18PDM201L Competencies in Social Skills 0 0 2 0							
Semester - V Code							
Semester - V Semester - V	3 - 1 - 1 - 1 - 1 - 1 - 1 - 1 - 1 - 1 -		U				
Semester - V Code Course Title Hours/Week L T P C	J	euits					
Code Course little L T P C	Haura/Week	Hou	urs/ V	Veek			
18ECC203J	Code Course little L T P C Code Course little	L	Т	Р	C		
Techniques	10, 10, 10, 10, 10, 10, 10, 10, 10, 10,				_		
18ECC204J Digital Signal Processing 3 0 2 4 18ECC205J Analog and Digital Communication 3 0 2 4 2 4 4 8ECC205J Analog and Digital Communication 3 0 2 4 4 9 Professional Elective – 2 3 0 0 3 3 8 18 18 18 18 18					4		
18ECC205J Analog and Digital Communication 3 0 2 4 Professional Elective - 2 3 0 0 3 Professional Elective - 2 3 0 0 3 Professional Elective - 2 3 0 0 3 Professional Elective - 3				-	1		
Professional Elective - 2	18ECC205.1 Analog and Digital Communication 3 0 2 4				3		
Semester - VII Seme					3		
18ECP101L/ 18ECP102L/ 18ECP103L 18ECP105L 18				_	3		
Training-I Seminar-I	18ECP101L/ Marries One Online Course I / Industrial 18ECP104L/ Marries One Online Course I / Industrial						
18PDM301L Analytical and Logical Thinking Skills 0 0 2 0 18LEM110L Indian Art Form 0 0 2 0 18LEM110L Indian Art Form Total Learning Credits 10 0 0 2 0 18LEM109T Indian Traditional Knowledge 1 0 0 0 0 0 0 0 0 0	10ECP102L/ Training L/ Seminar I	0	0	2	1		
18LEM110L Indian Art Form	18FCP1031						
Total Learning Credits 23 Total Learning Credits 2		0			1		
Semester - VII Code Course Title Hours/ Week L T P C	18PDM301L Analytical and Logical Thinking Skills 0 0 2 0 18PDH201L Employability Skills and Practices	1	0	0	0		
Code Course Title Hours/ Week L C Code Course Title Hours/ Week L C 18ECC301T Wireless Communications 3 1 0 4 4 18ECP109L/18ECP10L Professional Elective-5 3 0 0 3 3 18ECP109L/18ECP110L Project / Semester Internship 0 0 0 20 10 0 0 20 10 10 0 0 20 20 10 10 0 0 20 20 10 10 0 0 20 20 20 20 10 0 0 20 20 20 20 10 0 0 20 20 20 20 10 0 0 20 20 20 20 10 0 20 20 20 20 20 10 0 20 20 20 20 20 10 0 20 20 20 20 20 10 0 20 20 20 20 20 10 0 20 20 20 20 20 20 10 0 20 20 20 20 20 20 10 0 20 20 20 20 20 20 10 0 20 20 20 20 20 20 10 20 20 20 20 20 20 20 10 20 20 20 20 20 20 20 <td>18PDM301L Analytical and Logical Thinking Skills 0 0 2 0 18PDH201L Employability Skills and Practices 18LEM110L Indian Art Form 0 0 2 0 18LEM109T Indian Traditional Knowledge</td> <td>redits</td> <td></td> <td></td> <td>24</td>	18PDM301L Analytical and Logical Thinking Skills 0 0 2 0 18PDH201L Employability Skills and Practices 18LEM110L Indian Art Form 0 0 2 0 18LEM109T Indian Traditional Knowledge	redits			24		
Code Course Title Hours/ Week L C Code Course Title Hours/ Week L C 18ECC301T Wireless Communications 3 1 0 4 4 18ECP109L/18ECP10L Professional Elective-5 3 0 0 3 3 18ECP109L/18ECP110L Project / Semester Internship 0 0 0 20 10 0 0 20 10 10 0 0 20 20 10 10 0 0 20 20 10 10 0 0 20 20 20 20 10 0 0 20 20 20 20 10 0 0 20 20 20 20 10 0 0 20 20 20 20 10 0 20 20 20 20 20 10 0 20 20 20 20 20 10 0 20 20 20 20 20 10 0 20 20 20 20 20 10 0 20 20 20 20 20 20 10 0 20 20 20 20 20 20 10 0 20 20 20 20 20 20 10 0 20 20 20 20 20 20 10 20 20 20 20 20 20 20 10 20 20 20 20 20 20 20 <td>18PDM301L Analytical and Logical Thinking Skills 0 0 2 0 18LEM110L Indian Art Form 0 0 2 0 18LEM10DL Indian Art Form 0 0 0 0</td> <td></td> <td></td> <td></td> <td></td>	18PDM301L Analytical and Logical Thinking Skills 0 0 2 0 18LEM110L Indian Art Form 0 0 2 0 18LEM10DL Indian Art Form 0 0 0 0						
Code Course little L T P C	18PDM301L Analytical and Logical Thinking Skills 0 0 2 0 18PDH201L Employability Skills and Practices 18LEM101L Indian Art Form 0 0 0 2 0 18LEM109T Indian Traditional Knowledge Total Learning Credits 23						
Professional Elective-5 3 0 0 3	18PDM301L Analytical and Logical Thinking Skills 0 0 2 0 18PDH201L Employability Skills and Practices 18LEM109T Indian Traditional Knowledge Total Learning Credits 23 Semester - VII				_		
Professional Elective-6	18PDM301L Analytical and Logical Thinking Skills 0 0 2 0 18PDM201L Employability Skills and Practices 18LEM110L Indian Art Form	-			С		
Professional Elective-6	18PDM301L Analytical and Logical Thinking Skills 0 0 2 0 18PDM201L Employability Skills and Practices 18LEM109T Indian Traditional Knowledge Total Learning Credits Total Le	L	T	Р			
18ECP107L / 18ECP108L Minor Project / Internship (4-6 weeks) 0 0 6 3	18PDM301L Analytical and Logical Thinking Skills 0 0 2 0 18LEM110L Indian Art Form 0 0 0 2 0 Total Learning Credits Semester - VII Code Course Title Hours/ Week L T P C L T P C Code Code Course Title 18ECC301T Wireless Communications 3 1 0 4 Professional Elective-5 3 0 0 3	L	T	Р	C 10		
18ECP108L Milnor Project / Internsnip (4-6 weeks)	18PDM301L Analytical and Logical Thinking Skills 0 0 2 0 18LEM110L Indian Art Form 0 0 0 2 0 Total Learning Credits 18PDH201L Employability Skills and Practices Total Learning C Semester - VII Code Course Title L T P C 18ECC301T Wireless Communications 3 1 0 4 Professional Elective-5 3 0 0 3 Professional Elective-6 18ECP109L 18ECP110L Project / Semester Internship	L	T	Р			
	18PDM301L Analytical and Logical Thinking Skills 0 0 2 0 18PDM201L Employability Skills and Practices 18LEM110L Indian Art Form 0 0 0 2 0 18PDM201L Employability Skills and Practices 18LEM109T Indian Traditional Knowledge Total Learning Companies To	L	T	Р			
	18PDM301L Analytical and Logical Thinking Skills 0 0 2 0 18PDM301L Indian Art Form 0 0 0 2 0 18LEM110L Indian Art Form Total Learning Credits 23 18PDH201L Employability Skills and Practices 18LEM109T Indian Traditional Knowledge Total Learning Companies Total Learning Com	L	T	Р			

B. Tech in Electronics and Communication Engineering

(with Specialization in Instrumentation Engineering)

2018 Regulations

Engineering Science Courses (S)

Department of Electronics and Communication Engineering SRM Institute of Science and Technology SRM Nagar, Kattankulathur – 603203, Kancheepuram District, Tamilnadu

Course Code	18ECS201T	Course Name	(CONTROL S	SYSTEMS	Course Category	Professional Core	3	T 0	P 0	3
Pre-requisi Courses	**	18MAB102	Co-requisite Courses		18ECC104T	Progressive Courses	Nil				
Course Offer	ring Department	E	Electronics and Communication Eng.	ineering	Data Book / Codes/Standards		Nil				

Course Learning Rationale (CLR): The purpose of learning this course is to:	L	.earni	ing				Pı	rogra	m Le	arnir	ng Ou	ıtcom	es (F	PLO)			
CLR-1: Learn about mathematical modeling techniques of mechanical and electrical systems	1	2	3	1	2	3 .	4	5	6	7	8	9	10	11	12	13	14 15
CLR-2: Impart knowledge about the transient and steady state error and analysis										_							स स
CLR-3: Identify and analyze stability of a system in time domain using root locus technique						- -	5			<u></u>							earc
CLR-4: Know about different frequency domain analytical techniques	(Bloom)	(%)	(%)	ge		Ħ	sea			inal		Work		8			Management & Research
CLR-5: Acquire the knowledge of a controller for specific applications	m m m	Proficiency	nent	<u>₩</u>		Development	꽃	g		Sustainability		>		Finan	g	onal	<u>ω</u> ∞
CLR-6: Impart knowledge on controller tuning methods	hinking	fice	Attainme	9	naiysis	<u>e</u> .	esign,	SO .	₽	∞ర		Team	5	ĕ	Leaming	SSi	Project N as Analyze
	E	F.	I Att	Ē.		و آ		00	<u>.</u>	Jeut		∞ర	icati	Mgt.	Lee	Profe	
Course Learning Outcomes (CLO): At the end of this course, learners will be able to:	Level of	Expected	Expected	Engineering Knowledge		Design &	Analysis,	Modern	Society 8	Environme	Ethics	Individual	Communication	Project N	Life Long	PSO-1: F Achieven	PSO – 2: Technicu PSO – 3:
CLO-1: Determine Transfer function of a system by mathematical modeling, block diagram reduction and signal flow graphs	1,2	80	80	Н	Н	-	-	-	-	-	-	-	-	-	-	Н	
CLO-2: Identify the standard test inputs, time domain specifications and calculate steady state error	1,2	85	80	Н	Н	-	-	-	-	-	-	-	-	-	-	Н	
CLO-3: Plot a root locus curve and analyze the system stability using Routh array	2,3	90	85	Н	Н	-	-	-	-	-	-	-	-	-	-	Н	
CLO-4: Analyze the frequency domain specifications from bode and polar plots	2,3	90	85	Н	Н	-	-	-	-	-	-	-	-	-	-	Н	
CLO-5: Design a closed loop control system for specific application	1,2,3	3 80	80	Ч	Ч	-	-	-	-	-	-	-	-	-	-	Н	- -
CLO-6: Identification of controller parameters and tuning	1,2,3		85	Н	Н	-	-	-	-	-	-	-	-	-	-	Н	

	ration nour)	9	9	9	9	9
	SLO-1	Open and closed loop control system	Standard test signals and their expression	Poles and zeros of a system	Frequency domain analysis	Controllers-Significance and Need
S-1	SLO-2	Feedback and Feed forward control systems	Type number and order of a system	Pole zero plot and concept of s plane	Frequency domain specifications	Stability of closed loop systems
S-2	SLO-1	Transfer function of a system and basis of Laplace transforms	Transfer function of First order system for Step and ramp signal	Proper, Strictly Proper and Improper systems	Frequency domain plots, minimum and non minimum phase systems	SISO and MIMO control systems
0-2	SLO-2	Need for mathematical modeling	Transfer function of First order system Impulse and parabolic signal	Characteristic equation	Correlation between time and frequency domain	Types of controllers-ON-OFF,P,I,D
S-3	SLO-1	Representation of mechanical translational	General transfer function of second order system	Concept of stability from pole zero location	Bode plot approach and stability analysis	Composite Controller-PI,PD and PID
	SLO-2	determination of transfer function	sentation of mechanical translational system location location	Rules for sketching bode plot	Controller parameters and tuning methods	
S-4		Representation of mechanical rotational systems	Step response of critically damped second order system	Necessary and sufficient Condition for stability		Design Specification, controller
0-4	SLO-2	and determination of transfer function	Step response of under damped second order system	Significance of Routh Hurwitz Technique	about plot of typical systems	configurations- ON-OFF controller
٥.	SLU-I	Conversions of Mechanical system to Electrical system	Step response of over damped second order system	Computation of Routh array	Dada alat afti missal avatama	Design Specification, controller
S-5	SLO-2	f-V and f-I electrical analogies	Step response of undamped second order		configurations-PID controller	

S-6	SLO-1	Block diagram reduction rules and methodology	Time domain specifications and their significance	Routh array of Unstable systems	Polar plot and significance	Design of speed control system for DC motor
	SLO-2		Numerical solution	Routh array of Unstable systems	Nyquist stability criterion	IIIOLOI
S-7	SLO-1	Evaluation of transfer function using block diagram			Sketching of polar plot on polar graphs	Design of control system for Twin Rotor Multi input Multi output System(TRMS)
3-1	SLO-2	reduction	Static and dynamic Error coefficients Rules fo			with one degree of freedom
S-8	SLO-1	Signal flow graphs and evaluation of transfer	Static error constants and evaluation of	Root locus plot of typical systems	Polar plot of typical systems	Case study 1
3-0	SLO-2	function	steady state error	Root locus plot of typical systems	roiai piot di typicai systems	Case study 1
S-9	SLO-1	Block diagram to signal flow conversion	Dynamic error constants and evaluation of	Root locus plot of typical systems	Polar plot of typical systems	Case study 2
3-9	SLO-2	DIOUN diagram to Signal 110W CONVERSION	steady state error	noot locus plot of typical systems	roiai piot oi typicai systems	Case study 2

		3. Gopal.M, "Control System Principles and Design", 2 nd Edition, TMH, 2002
Resources	2. Benjamin C Kuo, "Automatic Control System", 9th edition, John Wiley & Sons, 2010	4. Sivanandam and Deepa, "Control system Engineering using MATLAB", 2 nd edition, Vikas publishers, 2007

Learning As:	sessment					
	Bloom's		Continuous Learnir	ng Assessment (50% weightage)		Final Examination (50% weightage)
	Level of Thinking	CLA – 1 (10%)	CLA – 2 (15%)	CLA – 3 (15%)	CLA – 4 (10%)	
Level 1	Remember Understand	40%	30%	30%	30%	30%
Level 2	Apply Analyze	40%	40%	40%	40%	40%
Level 3	Evaluate Create	20%	30%	30%	30%	30%
	Total	100 %	100 %	100 %	100 %	100 %

[#] CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, kumaranuj.anii@gmail.com	1. Dr. Meenakshi, Professor of ECE, CEG, Anna University, meena68@annauniv.edu	Dr. T. Deepa, SRMIST
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	Mrs. R. Bakhya Lakshmi, SRMIST

B. Tech in Electronics and Communication Engineering

(with Specialization in Instrumentation Engineering)

2018 Regulations

Professional Core Courses (C)

Department of Electronics and Communication Engineering SRM Institute of Science and Technology SRM Nagar, Kattankulathur – 603203, Kancheepuram District, Tamilnadu

Course	195001021	Course	ELECTRONIC DEVICES	Course		Professional Core	L	Т	Р	С
Code	10ECC 1023	Name	ELECTRONIC DEVICES	Category	C	Professional Core	3	0	2	4

Pre-requisite Courses	18EES101J		o-requisite Courses	Nil		Progressive Courses	18ECC201J, 18ECC202J, 18ECE203T, 18ECE303T, 18ECE321T, 18ECE322T
Course Offering	Department	Electronics and Communicati	tion Engineeri	ng	Data Book / Codes/Standards	Nil	

Course L	earning Rationale (CLR):	The purpose of learning this course is to:	L	earniı	ng		
CLR-1:	Provide a basis for underst	anding semiconductor material, how a pn junction is formed and its principle of operation	1	2	3		
CLR-2:	Explain the importance of diode in electronic circuits by presenting appropriate diode applications						
CLR-3:	J						
CLR-4:	Describe the basic structure	e, operation and characteristics of BJT, and discuss its use as a switch and an amplifier.	=	_			
CLR-5:	Describe the basic structure	e, operation and characteristics of MOSFET, and discuss its use as a switch and an amplifier.	(Bloom)	(%)/	t (%)		
CLR-6:		ols such as PSPICE to carry out design experiments and gain experience with instruments	<u>e</u>) Suc	neu		
CLK-0:	and methods used by techi	nicians and electronic engineers	hinking	oficiency	ttainment		

Course L	earning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thi	Expected P	Expected A
CLO-1:	Explain the operation, chara	cteristics, parameters and specifications of semiconductor diodes and special diodes	1	60	70
CLO-2:	CLO-2: Illustrate important applications of semiconductor diodes and special diodes.			60	70
CLO-3:	Review bipolar transistor co. and switching.	nstruction, operation, characteristics and parameters, as well as its application in amplification	1	60	70
CLO-4:	Review field-effect transistor amplification and switching.	r construction, operation, characteristics and parameters, as well as its application in	1	60	70
CLO-5: Construct a circuit, then ma		ke functional measurements to understand the operating characteristics of the device / circuit.	3	70	75
CLO-6:	Solve specific design proble	m, which after completion will be verified using modern engineering tools such as PSPICE.	2	70	75

				Prog	ram L	_earn	ing O	utco	mes (PLO)				
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO-1: Professional Achievement	PSO – 2: Project Management Techniques	PSO – 3: Analyze & Research
Н	-	-	-	-	-	-	-	-	-	-	М	-	-	-
-	-	-	-	-	-	-	-	-	-	-	М	-	-	-
Н	1	1	1	1	-	1	-	1	-	1	М	-	-	-
Н	-	-	-	-	-	-	-	-	-	-	М	-	L	-
-	-	-	-	Н	-	-	-	-	-	-	-	L	L	-
-	-	-	-	Η	-	-	L	Н	М	-	М	-	-	-

Du	ration	Semiconductor Diodes	Diode Circuits	Special Diodes	Bipolar Junction Transistors	MOS Field-Effect Transistors
(h	our)	15	15	15	15	15
S-1	SLO-1	Basic semiconductor theory: Intrinsic & extrinsic semiconductors	HWR operation, Efficiency and ripple factor	Backward diode	Physical structure	Physical structure
3-1	SLO-2	Current flow in semiconductors	Problem solving	Varactor diode	Device operation of BJT	Device operation of E-MOSFET & D- MOSFET
S-2	SLO-1	PN junction theory: Equilibrium PN junction	Center-Tapped Transformer FWR operation, Efficiency and ripple factor	Step recovery diode	Current-Voltage characteristics of CE BJT configuration	I-V characteristics of E-MOSFET
3-2	SLO-2	Forward biased PN junction	Problem solving	Point-contact diode	Current-Voltage characteristics of CE BJT configuration	Problem solving
S-3	SLO-1	Reverse biased PN junction		Metal-semiconductor junction: Structure, Energy band diagram	Current-Voltage characteristics of CB BJT configuration	Derive drain current
3-3	SLO-2	Relation between Current and Voltage	Problem colvina	Forward & Reverse Characteristics of Schottky Diode	Current-Voltage characteristics of CB BJT configuration	Problem solving
S 4-5	SLO-1 SLO-2	Lab 1: PN Junction Diode Characteristics	Lab 4: Diode clipping and clamping circuits	Lab 7: Series and Shunt Regulators	Lab 10: BJT and MOSFET Switching Circuits	Lab 13: Repeat Experiments
S-6	SLO-1	Calculate depletion width	Filters: Inductor & Capacitor Filters	Tunnel Diode	Current-Voltage characteristics of CC BJT configuration	Derive transconductance
3-0	SLO-2	Calculate barrier potential	Problem solving	Tunnel Diode	Current-Voltage characteristics of CC BJT configuration	Problem solving
S-7	SLO-1	Derive diode current equation	Filters: LC & CLC Filters	Gunn Diode	BJT as an amplifier	CMOS FET

	01.0.0	Desire die de comment escritica	Decklere extrine	Own Diede	BJT as a switch	MOOFFT
		Derive diode current equation	Problem solving	Gunn Diode	BJT as a switch	MOSFET as an amplifier
S-8	SLO-1	Effect of Capacitance in PN junction: Transition Capacitance	Diode Clippers	IMPATT Diode	BJT circuit models – h-parameter	MOSFET as a switch
	SLO-2	Diffusion Capacitance	Problem solving	IMPATT Diode	BJT circuit models – hybrid-π parameter	Problem solving
S 9-10	SLO-1 SLO-2	Lab 2: Zener diode characteristics	Lab 5: BJT Characteristics	Lab 8: MOSFET Characteristics	Lab 11: Photoconductive Cell, LED, and Solar Cell Characteristics	Lab-14: Model Examination
S-11	SLO-1	Energy band structure of PN Junction Diode	Diode Clampers	PIN Diode	BJT biasing circuits and stability analysis: Base bias and emitter bias	Biasing Circuits for MOSFET: Gate Bias
3-11	SLO-2	Ideal diode and its current-voltage characteristics	Problem solving	PIN Photodiode	Problem solving	Problem Solving
S-12	SLO-1	Terminal characteristics & parameters	Voltage Multipliers	Avalanche photodiode	Voltage-divider bias	Self-bias
3-12		Diode modeling	Zener diode: Characteristics, breakdown mechanisms	Laser diode	Problem solving	Problem Solving
S-13	SLO-1	DC load line and analysis	Zener resistances and temperature effects Zener diode as voltage regulator	Problem solving	Collector-feedback bias	Voltage-divider bias
0-10	SLO-2	Problem solving	Problem solving	Problem solving	Problem solving	Problem Solving
S 14-15	SLO-1 SLO-2	Lab 3: Diode rectifier circuits	Lab 6: BJT Biasing Circuits	Lab 9: MOSFET Biasing Circuits	Lab 12: Simulation experiments using PSPICE	Lab 15: End-Semester Practical Examination

	1.	David A. Bell, Electronic Devices and Circuits, 5 th ed., Oxford University Press, 2015	5.	Robert L. Boylestad, Louis Nashelsky, Electronic Devices and Circuit Theory, 11th ed., Pearson Education, 2013
Learning	2.	Donald Neamen, Electronic Circuits: Analysis and Design, 3rd ed., McGraw-Hill Education, 2011	6.	Muhammad Rashid, Microelectronic Circuits: Analysis & Design, 2 nd ed., Cengage Learning, 2010
Resources	3.	Adel S. Sedra, Kenneth C. Smith, Microelectronic Circuits: Theory and Applications, OUP, 2014	7.	Muhammed H Rashid, Introduction to Pspice using OrCAD for circuits and electronics, 3 rd ed., Pearson, 2004
	4.	Thomas L. Floyd, Electronic Devices", 9th ed., Pearson Education, 2013	8.	Laboratory Manual, Department of ECE, SRM University

Learning Asse	Learning Assessment													
	Bloom's			Conti	nuous Learning Ass	essment (50% weig	htage)			Final Evamination	n (E0% woightage)			
	Level of Thinking	CLA -	1 (10%)	CLA – 2 (15%)		CLA -	3 (15%)	CLA – 4	(10%)#	Final Examination (50% weightage)				
	Level of Thirtking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice			
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%			
Level I	Understand	2070 2070		1370	1070	1070	1070	1070	1370	1070	1070			
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%			
Level 2	Analyze	2070	2070	2070	2070	2070	2070	2070	2070	2070	2070			
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%			
Level 3	Create	10%	10%	13%	13%	15%	13%	13%	13%	13%	15%			
	Total		100 %		100 %		100 %) %		=			

[#]CLA - 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, kumaranuj.anii@gmail.com	1. Dr. Meenakshi, Professor of ECE, CEG, Anna University, meena68@annauniv.edu	1. Mr. Manikandan AVM, SRMIST
2. Mr. Hariharasudhan – Johnson Controls, Pune, hariharasudhan.v@ici.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	2. Dr. Diwakar R Marur, SRMIST

Course		Course	DICITAL ELECTRONIC PRINCIPLES	Course	_	Professional Core	L	Т	Р	С
Code	10ECC 1033	Name	DIGITAL ELECTRONIC PRINCIPLES	Category	C	Professional Core	3	0	2	4

Pre-requisite Courses	18EES101J	Co-requisite Courses	Nil	Progressive Courses	18ECC203J, 18ECC206J, 18ECE206J
Course Offering Department	Electronics and Comm	unication Engineer	ng Data Book / Codes/Standards	Nil	

Course L	Learning Rationale (CLR): The purpose of learning this course is to:	L	earni	ng						Program Learning Outcomes (PLO)									
CLR-1:	Understand binary codes, digital arithmetic operations and able to simplify Boolean logic expressions	1	2	3	-	1	2	3	4	5	6	7	8	9	10	11	1:		
CLR-2:	Describe how basic TTL and CMOS gates operate at the component level																		
CLR-3:	Able to design simple combinational logics using basic gates and MSI circuits																		
CLR-4:	Familiarize with basic sequential logic components: flip-flops, registers, counters and their usage, and able to design and analyze sequential logic circuits and Finite State Machines.	<u>=</u>							earch			bility							
CLR-5:	Know how to implement logic circuits using PLDs.	(moo	(%)	%		ge		Ħ				aina		Work		nce			
CLR-6:	Use modern engineering tools such as PSPICE / Logisim to carry out design experiments and gain experience with instruments and methods used by technicians and electronic engineers	nking (Bloo	roficiency	ttainment		Knowlec	Analysis	relopment	Design, Re	Usage	Culture	& Sustainability		Team W	uo	& Finan	ruina		
		Th:	Expected Pro	Att		ing	Ana	Dev		8		ent		∞ŏ	icati	Mgt.	9		
Course L	purse Learning Outcomes (CLO): At the end of this course, learners will be able to:					Engineering Knowledge	Problem	Design &	Analysis,	Modem 7	Society &	Environment	Ethics	Individual	Communication	Project M	ouo I eji		
CLO-1:	CLO-1: Simplify Boolean expressions; carry out arithmetic operations with binary numbers; apply parity method for error detection and correction.					Н	-	-	•	-	-	-	-	1	-	-			
CI O 2 .	Explain the operational characteristics / properties of digital ICs; implement gates as well as other types of IC devices using					ш													

		Le	Ĥ	ш
CLO-1 :	Simplify Boolean expressions; carry out arithmetic operations with binary numbers; apply parity method for error detection and correction.	1	90	75
CLO-2:	Explain the operational characteristics / properties of digital ICs; implement gates as well as other types of IC devices using two major IC technologies, TTL and CMOS.	1	80	70
CLO-3:	Identify eight basic types of fixed-function combinational logic functions and demonstrate how the devices / circuits can be used in building complete digital systems such as computers.	2,3	90	75
CLO-4:	Analyze and design Mealy and Moore models of sequential circuits using several types of flip-flops.	2,3	90	75
CLO-5:	Implement multiple output combinational logic circuits using PLDs; Explain the operation of a CPLD and FPGA.	2	80	75
CLO-6:	Solve specific design problem, which after completion will be verified using modern engineering tools such as PSPICE / Logisim	2	90	75

1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modem Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO-1: Professional Achievement	PSO – 2: Project Management	PSO – 3: Analyze & Research
Н	-	-	-	-	-	-	-	-	-	-	-	-	-	-
Н	-	-	-	-	-	-	-	-	-	-	-	-	-	-
1	М	Н	-	Н	-	1	-	-	-	1	-	1	-	-
-	М	Н	1	Н	1	1	1	1	-	1	1	1	-	-
	М	Н	-	L	-	-	-	-	-	-	-	-	-	-
-	М	Н	-	Н	-	-	-	Н	-	-	-	М	-	L

	ration	Binary Codes, Digital Arithmetic and Simplification of Boolean Functions	Logic Families	Combinational Systems	Sequential Systems	Memory and Programmable Logic
(1	nour)	15	15	15	15	15
S-1	SLO-1	Binary Codes, Digital Arithmetic and Simplification of Boolean Functions	Introduction	Binary arithmetic units	Flip-flop and Latch: SR latch,	RAM Memory decoding
0-1	SLO-2	Error detecting codes	TTL Logic Family	Adder	JK flip-flop, T flip-flop, D flip-flop	ROM
S-2	SLO-1	Error correcting code	ror correcting code Totem-pole TTL		Master-slave RS flip-flop	Programmable Logic Devices (PLDs): Basic concepts
0-2	SLO-2	Hamming Code	open-collector and tristate TTL	Design of Full adder	Master-slave JK flip-flop	PROM
S-3	SLO-1	Arithmetic number representation	Schottkey TTL, standard TTL characteristics	Subtractor	Registers & Counters	PROM as PLD
0-3	SLO-2	Binary arithmetic	Metal Oxide Semiconductor logic families	Design subtractor using logic gates	Shift registers (SISO, SIPO, PISO, PIPO)	Programmable Array Logic (PAL)
S 4-5	SLO-1 SLO-2	LAB 1: Study of logic gates	LAB 4: Design and implement encoder and decoder using logic gates		LAB 10: Design and implement Synchronous Counters	LAB 13: Construct combinational circuit using Logisim
S-6	SLO-1	Hexadecimal arithmetic	N-MOS	n-bit parallel adder & subtractor	Universal shift register	Programmable Array Logic (PAL)

	SLO-2	Hexadecimal arithmetic	P-MOS	look ahead carry generator	Counters: Asynchronous/Ripple counters	Programmable Logic Array (PLA)
0.7	SLO-1	BCD arithmetic simplification	CMOS logic circuits	Decoder	Synchronous counters, Modulus-n Counter	Programmable Logic Array (PLA)
S-7	SLO-2	Minimization of Boolean Functions: Algebraic simplification	Characteristics of MOS logic	Encoder	Ring counter, Johnson counter	Design combinational circuits using PLD's
S-8	SLO-1	Problems on Algebraic simplification	Compare MOS logic circuits(CMOS) with TTL digital circuit	Multiplexer	Up-Down counter	Design combinational circuits using PLD's
3-0	SLO-2	Karnaugh map simplification	Electrical characteristics	Demultiplexer	Mealy and Moore model	Design combinational circuits using PLD's
S 9-10	SLO-1 SLO-2	LAB 2: Design and implement Adder and Subtractor using logic gates	LAB 5: Design and implement Multiplexer and Demultiplexer using logic gates	LAB 8: Verify characteristic table of flip- flops	LAB 11: Construct and verify shift registers	LAB 14: Model Practical Examination
S-11	SLO-1	Problems on Karnaugh map simplification	Fan-out	Code converters		Design of combinational circuits using PLD's
3-11	SLO-2	Problems on Karnaugh map simplification	Propagation Delay	Magnitude comparators	Synchronous (Clocked) sequential circuits	Design sequential circuits using PLD's
0.40	SLO-1	Quine McCluskey	Power dissipation	Magnitude comparators	Synchronous (Clocked) sequential circuits	Design sequential circuits using PLD's
S-12	SLO-2	Tabulation method	Noise margin	Parity generators (Odd parity)	Analyze and design synchronous sequential circuits	Design sequential circuits using PLD's
6.42	SLO-1	Problems on Quine McCluskey or Tabulation method.	Supply voltage levels	Parity generators (Even parity)	State reduction	Design sequential circuits using PLD's
S-13	SLO-2	Exercise problems using Tabulation method		Implementation of combinational logic by standard IC's.	State assignment	Design sequential circuits using PLD's
S 14-15	SLO-1 SLO-2	Lab 3: Design and Implement 2-bit Magnitude Comparator using logic gates	LAB-6: Design and implement code converters using logic gates	LAB 9: Construct and verify 4-bit ripple counter, Mod-10/Mod-12 ripple counters	Lab 12: Construct mini project work	LAB 15: University Practical Exam

Learning	
Resources	

- Morris Mano M, Michael D. Ciletti, Digital Design with an Introduction to the Verilog HDL, 5th ed., Pearson Education, 2014
- 2. Charles H Roth (Jr), Larry L. Kinney, Fundamentals of Logic Design, 5th ed., Cengage Learning India Edition, 2010
- Thomas L. Floyd, Digital Fundamentals, 10th ed., Pearson Education, 2013

- Ronald J. Tocci, Digital System Principles and Applications, 10th ed., Pearson Education, 2009
 Donald P Leach, Albert Paul Malvino, Goutam Saha, Digital Principles and Applications, 6th ed., Tata-Mcgraw Hill, 2008
- 6. LAB MANUAL, Department of ECE, SRM University

Learning Asses	sment										
	Bloom's			Conti	nuous Learning Ass	essment (50% weig	htage)			Final Evamination	n (50% weightage)
	Level of Thinking	CLA –	1 (10%)	CLA –	2 (15%)	CLA -	3 (15%)	CLA – 4	(10%)#	FIIIai Examination	1 (50 % weightage)
	Level of Thirtking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
r. Level 1	Remember Understand	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
Level 2	Apply Analyze	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
Level 3	Evaluate Create	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Total	10	0 %	100) %	10	0 %	100) %		-

[#] CLA - 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
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1. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, kumaranuj.anii@gmail.com	1. Dr. Meenakshi, Professor of ECE, CEG, Anna University, meena68@annauniv.edu	1. Mr. Viswanathan B, SRMIST
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	

Course	10ECC104T Course	CICNAL C AND CVCTEMO	Course	Professional Cara	L	Т	Р	С
Code	Name	SIGNALS AND STSTEMS	Category	Professional Core	3	1	0	4

Pre-requisite Courses	Nil	Co-requisite Courses	18MAB201T	Progressive Courses	18ECC204J, 18ECS201T, 18ECE240T, 18ECE241J
Course Offering Department	Electronics and Co	mmunication Engineerin	g Data Book / Codes/Standards		Nil

Course Onering Department Electronics and Communication Engineering Data Book / Codes/Standards									IVII									
Course Learning Rationale (CLR): The purpose of learning this course is to:	L	earni		4	1	1	4	-	ram L	_earni	<u> </u>	utcon	nes (F	PLO)	10	12		15
CLR-1: Know about requirements of signal and system analysis in communication.	1	2	3	1		3	4	5	ь	1	8	9	10	11	12	13	14	15
CLR-2: Understand the analysis of Periodic and Aperiodic Continuous time Signals using Fourier series and transforms																ent		
CLR-3: Educate about Continuous time system through Laplace transform and Convolution integral										>						Ven	ent	듄
CLR-4: Understand the characterization of the Discrete time signals and system through DTFT, Convolution sum	=	<u></u>	_				많			Eg						Achie	le le	Research
CLR-5: Understand the concept of Z-Transform for the analysis of DT system	9	(%)/	t (%)	ge		i i	ses			stainability		Work		8			Manager	Re
CLR-6: Develop expertise in time-domain and frequency domain approaches to the analysis of continuous and discrete systems and also the ability to apply modern computation software tool for the analysis of electrical engineering problems	hinking (Bloom)	Proficiency	Attainment	Engineering Knowledge	Analysis	Development	Design, Re	Tool Usage	Culture	ent & Su		& Team	ication	Mgt. & Finance	Learning	Professional	Project Ma es	Analyze &
Course Learning Outcomes (CLO): At the end of this course, learners will be able to:	Level of	Expected	Expected	Engineer	Problem	Design &	Analysis,	Modern T	Society 8	Environme	Ethics	Individual	Communication	Project M	Life Long		PSO – 2: Techniou	PSO - 3:
CLO-1: Understand the various classifications of Signals and Systems	1	65	60	Н	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-2: Analyze Periodic and Aperiodic Continuous time Signals using Fourier series and Fourier Transform	2	65	60	-	Н	-	-		-	-	-	-	-	-	-	-	-	-
CLO-3: Analyze and characterize the Continuous time system through Laplace transform and Convolution integral.	2	65	60	-	Н	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-4: Analyze and characterize the Discrete time signals and system through DTFT, Convolution sum	2	65	60	-	Н	М	-	-	-	-	-	-	-	-	-	-	-	-
CLO-5: Analyze and characterize the Discrete time system using Z transform	2	65	60	-	Н	М	-	-	-	-			-	-	-	-	-	L
CLO-6: Apply the mathematical techniques used for continuous-time signal and discrete-time signal and system analysis	2	65	60	-	Н	-	М	М	-	-	-	-	-	-	-	L	-	-

	ration	Classification of Signals and Systems	Analysis of Continuous Time Signals	Analysis of LTI CT System	Analysis of DT Signals and Systems	Analysis of LTI DT System using Z-Transform
,,	iouij	12	12	12	12	12
S-1	SLO-1	Introduction to signals and systems	Introduction to Fourier series	System modeling	Representation of sequences	Z transform – introduction
3-1	SLO-2	Requirements of signal and system analysis in communication	Representation of Continuous time Periodic signals	Description of differential equations	Discrete frequency spectrum and range	Region of convergence of finite duration sequences
S-2	SLO-1	Continuous time signals (CT signals)	Fourier series: Trigonometric representation		Discrete Time Fourier Transform (DTFT) – Existence	Properties of ROC
3-2	SLO-2	Discrete time signals (DT signals)	Fourier series: Trigonometric representation	Differential equation: Zero initial conditions	DTFT of standard signals	Properties of ROC
S-3	SLO-1	Representation of signals: Step, Ramp, Pulse, Impulse	Fourier series: Cosine representation	Differential equation: Zero state response	Properties of DTFT	Properties of Z transform
3-3	SLO-2	Representation of signals: Sinusoidal, Exponential	Fourier series: Cosine representation	Differential equation: Zero Input response	Properties of DTFT	Properties of Z transform
S-4	SLO-1	Basic operation on the signals	Symmetry conditions	Total Response	Inverse DTFT	Unilateral z transforms
3-4	SLO-2	Problems on signal operations	Properties of Continuous time Fourier series	Step response	Practice on IDTFT	Properties of z transform
S-5	SLO-1	Classification of CT and DT signals: Periodic & Aperiodic signals.	Practice problems on Fourier series	Impulse response	Impulse response of a system with DTFT	Bilateral Z transforms

	SLO-2	Classification of CT and DT signals: Deterministic & Random signals.	Practice problems on Fourier series		Frequency response of a system with DTFT	Properties of z transform
S-6	SLO-1	Energy signal	Gibb's Phenomenon	Convolution integral	Practice problems	Relation between DTFT and Z transform
3-0	SLO-2	Power signal	Parseval's relation for power signals	Properties of convolution	Practice problems	Practice problems
S-7	SLO-1	Even & Odd signals	Power density spectrum,	Practice Problems	Solution of linear constant coefficient difference equations	condition for causality in Z domain
0-1	SLO-2	Even & Odd signals	Frequency spectrum.	Practice Problems	Initial conditions	condition for stability in Z domain
S-8	SLO-1	CT systems and DT systems		Signal and system analysis with Laplace transform	Solution of difference equations	Inverse Z transform
3-0	SLO-2	Classification of systems: Static & Dynamic	Representation of Continuous time signals	Convergence of Laplace Transform	Zero input response	Power series expansion
S-9	SLO-1	Superposition theorem	Properties of Continuous time Fourier transform	Properties of Laplace transform	Solution of difference equations with Zero state response	Inverse Z transform with Partial fraction
3-3	SLO-2	Linear & Nonlinear system	Properties of Continuous time Fourier transform	Properties of Laplace transform	Total response	Inverse Z transform with Partial fraction
S-10	SLO-1	Time-variant & Time-invariant system	Parseval's relation for energy signals	Inverse Laplace transform	Evaluation of Impulse response	Residue method
3-10	SLO-2	Time-invariant system	Energy density spectrum	Problems	Evaluation of Step response	Convolution method
S-11	SLO-1	Causal system	, ,	Analysis and characterization of LTI system using Laplace transform	Convolution Properties	Analysis and characterization of DT system using Z-transform
3-11	SLO-2	Noncausal system		Analysis and characterization of LTI system using Laplace transform	Convolution Sum	Analysis and characterization of DT system using Z-transform
S-12	SLO-1	Stable & Unstable,LTI System	Practice problems on Fourier Transform	Practice problems on Laplace transform	Circular convolution	Practice problems on LTI-DT systems in Z transform
3-12	SLO-2	Unstable, LTI System	Practice problems on Fourier Transform	Practice problems on Laplace transform	Frequency response	Practice problems on LTI-DT systems in Z transform

	1.	Alan V Oppenheim, Ronald W. Schafer Signals & Systems, 2nd ed., Pearson Education, 2015	5.	Johr
Learning	2.	P.Ramakrishna Rao, Shankar Prakriya, Signals & Systems, 2 nd ed., McGraw Hill Education, 2015		Pear
Resources	3.	Simon Haykin, Barry Van Veen, Signals and Systems, 2nd ed., John Wiley & Sons Inc., 2007	6.	Soft
	4	Lathi R.P. Linear Systems & Signals 2nd ed. Oxford Press 2009		tooll

- . John G. Proakis, Manolakis, Digital Signal Processing, Principles, Algorithms and Applications, 4th ed., Pearson Education, 2007.
- Software: Matlab Student Version Release 2011a, Mathworks, Inc. The Matlab Student Version and toolboxes may be purchased through the Mathworks website at http://www.mathworks.com/

Learning Ass	essment											
	Bloom's		Continuous Learning Assessment (50% weightage)									
	Level of Thinking	CLA -	CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		l (10%)#	Final Examination (50% weightage		
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-	
	Understand			****				00 ,1		*****		
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-	
Level 3	Evaluate	20 %	_	30 %	_	30 %	_	30 %		30%		
revel 2	Create	20 /0	-	JU /0	-	JU /0	-	JU /0	-	3070	-	
	Total	10	0 %	10	0 %	10	0 %	100	0 %	10	0 %	

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2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	2. Dr. D. Malathi, SRMIST
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Course	18ECC105T	Course	ELECTROMACNETICS AND TRANSMISSION LINES	Course	_	Drofossianal Cara	L	Т	Р	С	
Code	10ECC1051	Name	ELECTROMAGNETICS AND TRANSMISSION LINES	Category	C	Professional Core	3	0	0	3	

Pre-requisite Courses		18PYB101J	Co-requisite Courses	Nil	Progressive Courses	18ECC301T
Course Offering Department		Electronics and Co	mmunication Engineering	Data Book / Codes/Standards		Clark's Table, IS : 456-2000

Course Learning Rationale (CLR): The purpose of learning this course is to:					ram L	Learning Outcomes (PLO)														
CLR-1:	CLR-1: Gain knowledge on the basic concepts and insights of Electric field 1								4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Gain knowledge on the basic concepts and insights of Magnetic field and Emphasize the significance of Maxwell's equations.				•													ənt		
CLR-3:	Interpret the wave propagation in guided waveguide.											,						Achievement	Ħ	등
CLR-4:	Acquire the fundamental knowledge on Transmission Line Theory.	(-	_	_					arch			pii i						je.	Management	Research
CLR-5:	Acquire the knowledge on transmission line parameter calculation and impedance matching concepts.	000	%)	t (%)		dge		tie	sea			aina		Work		8			ınag	
CLR-6:	Acquire knowledge on theoretical concepts and analysis techniques to find solutions for problems related to electromagnetic wave propagation and Transmission line Theory.	Thinking (Bloom)	Proficiency (%)	Attainment		Knowle	Analysis	Development	Design, Re	Usage	Culture	& Sustainability		Team M	on	& Finance	Learning	Professional	Project Ma es	Analyze &
		Thin	Pro			ing	Ana		Des	loo	& Cu	nent		~	icati		Lee	Profe	Pro Pro	. Ans
Course L	earning Outcomes (CLO): At the end of this course, learners will be able to:	Level of	Expected	Expected		Engineering Knowledge	Problem	Design &	Analysis,	Modem -	Society 8	Environment	Ethics	Individual &	Communication	Project Mgt.	Life Long		PSO – 2: Technique	PSO – 3:
CLO-1:	Apply the concepts and knowledge to solve problems related to electric field.	2	60	60	ĺ	М	Н	-	-	-	-	-	-	-	-	-	-	-	-	L
CLO-2:	Analyze the concepts of Magnetic field and Maxwell's equations in the real world application.	2	60	60	ĺ	Н	М	-	-	-	-	-	-	-	-	-	-	-	-	L
CLO-3:	Translate the phenomenon of guided wave propagation and its mode of propagation.	1	60	60	ĺ	Н	М	-	-	-	-	-	-	-	-	-	-	-	-	L
CLO-4:	Describe the importance of transmission line theory applicable to low frequency transmission lines.	1	60	60	ĺ	М	Н	-	-	-	-	-	-	-	-	-	-	-	-	L
CLO-5:	Solve transmission line parameter and impedance matching through analytical and graphical methods.	2	60	60	ĺ	М	Н	-	-	-	-	-	-	-	-	-	-	-	-	М
CLO-6:	Demonstrate how electromagnetic wayse are generated using Maywell's equations and how Transmission lines are used to					М	Н	-		-	1		-	-	-	-	L	-	-	Н

	ration	Electrostatics	Magnetostatics and Maxwells Equations	Electromagnetic Waves and Waveguides	Transmission Line Theory	Transmission Line Calculator and Impedance Matching
(1	nour)	9	9	9	9	9
S-1	SLO-1	Introduction	Energy density in electrostatic field	Introduction	Transmission line parameters	Introduction
3-1	SLO-2	Rectangular co-ordinate	Problem discussion.	Waves in general	Transmission line parameters	Smith chart Introduction
S-2	SLO-1	Cylindrical & Spherical Co-ordinate	Biot savart law-Magnetic field intensity due to Infinite line charge	Plane wave in lossless dielectric	Transmission line equivalent circuit	Reflection coefficient, Standing wave ratio Input impedance calculation in smith chart
0-2	SLO-2	Review of vector calculus	H- due finite and semi finite line charge	Plane wave in free space	Explanation	Practice problems.
S-3	SLO-1	Coulomb's Law and field intensity	Ampere's circuital law& application: Infinite line current	Plane wave in good conductor	Transmission line equation derivation	Single stub matching Introduction
3-3	SLO-2	Problem based on coulomb's law		Problems based on plane waves in lossless, free space and good conductor	Problem discussion.	Procedure for single stub matching
S-4	SLO-1	Electric field due to continuous charge distribution Concept	Infinitely long coaxial Transmission line	Rectangular waveguide	Transmission line characteristics: lossless line	Problems solving in smith chart
3-4	SLO-2	Derivation of E due Infinite Line charge	Problem based on ACL.	Rectangular waveguide-Problems	Distortionless line.	Problems solving in smith chart

S-5	SLO-1	Electric field due to sheet charge	Magnetic flux density	Transverse Electric (TE) mode	Input impedance derivation	Impedance matching using Quarter wave transformer
3-3	SLO-2	Problem based on sheet charge	Problem based on magnetic field and flux.	Transverse Electric (TE) mode-problems	Problems for input impedance calculation.	Problems.
S-6	SLO-1	Electric field due to volume charge	Maxwell's equation for static field	Transverse Electric (TE) mode	Standing wave ratio	Single stub tuner
3-0	SLO-2	Electric flux density	Faraday's law	Transverse Electric (TE) mode-Problems	Calculation of standing wave ratio.	Problem discussion
S-7	SLO-1	Gauss law application-point charge	Transformer EMF	Wave propagation in guide	Reflection coefficient	Slotted Line (Impedance Measurement)
3-1	SLO-2	Electric flux due infinite line charge	Motional EMF	Problem discussion	Problem discussion.	Problem discussion
S-8	SLO-1	Electric flux due sheet charge	Displacement current.	Power Transmission	Shorted line, open circuited line	Transmission Lines as circuit Elements
3-0	SLO-2	Electric flux due coaxial cable	Maxwell's equation in time varying field	Calculation of Pavg and Ptotal	Matched line	Problem discussion
	SLO-1	Relation between E&V	Time varying potential concepts	Power attenuation	Power calculations	Additional smith chart problem solving.
S-9	SLO-2	Electric dipole and flux lines	Time varying potential derivation.	Calculation of αTE and αTE	Problem discussion.	Additional smith chart problem solving.

Learning Resources	2. G. S. N.	v N. O. Sadiku., S. V. Kulkarni, Elements of Electromagnetics, 6 th ed., Oxford University Press, 2015 Raju, Electromagnetic Field Theory and Transmission Lines, Pearson Education, 2006 aneni Narayana Rao, Principles of Engineering Electromagnetics, 6 th ed., Pearson Education, 2016	4.	William H. Hayt,Jr., John A.Buck., Engineering Electromagnetics, 8th ed., Tata McGraw-Hill 2012 John D.Ryder, Networks, Lines and Fields, PHI, 2009
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Learning Ass	sessment										
	Bloom's				Final Examination (50% weightage)						
	Level of Thinking	CLA –	1 (10%)	CLA –	2 (15%)	CLA –	3 (15%)	CLA – 4	(10%)#	FIIIai Examination	i (50% weightage)
	Level of Thirtking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Evaluate Create	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Total	10	0 %	100	0 %	10	0 %	100	0 %	10	0 %

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2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in									

Course Code	18ECC201J	Course Name	ANALOG E	ELECTRONIC CIRCUITS	Course Category	С	Professional Core	L 3	T 0	P 2	C 4
Pre-requis	ite	18FCC1021	Co-requisite	18FCC202 I	Progre	ssive	Nil				

Pre-requisite	18ECC102J	Co-requisite	18ECC202J	Progressive	Nil
Courses	10200 1023	Courses	102002023	Courses	IVII
Course Offering Department	Electronics and Comm	unication Engineer	ing Data Book / Codes/Standards	Nil	

Course Learning Rationa	le (CLR):	The purpose of learning this course is to:	l	_earn	ing					Prog	ram L	.earni	ing O	utcor	nes (l	PLO)				
CLR-1: Understand the	operation	and design of BJT amplifier circuits for a given specification	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2: Understand the	operation	and design of MOSFET amplifier circuits for a given specification																		
CLR-3 : Understand the to determine th		negative feedback on amplifier circuits, and analyze the different RC and LC oscillator circuits of oscillation																ement	t	당
CLR-4: Understand the	operation	and design of various types of power amplifier circuits.	1 _						된			oiiity						je.	eue	earc
CLR-5 : Understand hor current sources		transistor characteristics are used in the IC design and to be able to design BJT and MOSFE	Thinking (Bloom)	Proficiency (%)	Attainment (%)	vledge		Development	Resea	ge		Sustainability		Work ا		Finance	б	Professional Achievem	Management	& Resear
CLR-6: Gain hands-on	experience	to put theoretical concepts learned in the course to practice.	ing	ficie	iğ.	Śno	ysis	elo	ign,	Usage	Culture	S S		Team	5	ĕ	Learning	SSiC	Project as	Analyze
			Thir	Pro	Atta	ing	Analysis		Design,	Tool	& Cul				icati		Lea	Profe	Pro Ies	
Course Learning Outcon	es (CLO):	At the end of this course, learners will be able to:	Level of	Expected	Expected /	Engineering Knowledge	Problem	Design &	Analysis,	Modern ⁷	Society &	Environment	Ethics	Individual &	Communication	Project Mgt.	Life Long		PSO – 2: Technio	PSO – 3:
		r amplifier circuits to meet certain specifications, and to Analyze the frequency response of o account various circuit capacitors, to determine the bandwidth of the circuit.	2,3	3 70		L	М	Н	-	-	-	-	-	-	-	-	-	-	-	-
		ET amplifier circuits to meet certain specifications, and to Analyze the frequency response of o account various circuit capacitors, to determine the bandwidth of the circuit.	2,3	3 70	70	L	М	Н	-	-	-		-	-	-	-	-	-	-	-
CLO-3: Understand the circuits to meet		stics and principles of feedback amplifier circuits and oscillator circuits to analyze and design actifications.	2,3	3 70	70	L	М	Н	-	•	-		-	-	-	-	-	-	-	-
CLO-4: Analyze three p		sses of power amplifiers, and determine the maximum possible conversion efficiency of each	2,3	3 70	70	L	М	Н	-	-	-		-	-	-	-	-	-	-	-
CLO-5: Design the bas	c circuit bu	ilding blocks that are used in the design of IC amplifiers, namely current mirrors and sources	2,3	3 70	70	L	М	Н	-	1	-	-	-	-	-	-	-	-	-	-

Analyze and design analog electronic circuits using discrete components, and take measurement of various analog circuits to compare experimental results in the laboratory with theoretical analysis.

Durat	a.a. /la.aa\	BJT Amplifiers	FET Amplifiers	Feedback amplifies & Oscillators	Oscillators & Power Amplifiers	IC Biasing & Amplifiers with Active Load
Durat	on (hour)	15	15	15	15	15
S-1	SLO-1	Overview of DC analysis of BJT circuits	Overview of FET DC circuit analysis	Basic feedback concepts, general feedback structure	Crystal Oscillators	BJT current sources: Cascode current source, Widlar current source
		Overview of BJT models	Problem solving	Properties of negative feedback	Problem solving	Multi-transistor current source Problem solving
S-2	SLO-1	AC load line analysis	Graphical analysis, load lines, and small- signal models	Feedback Topologies: Voltage-Series & Current-Series feedback connections	Negative-resistance oscillator	FET current sources: 2-transistor MOSFET current source
3-2	SLO-2	Problem solving	Problem solving	Problem solving	Problem solving	Problem solving
S-3	SLO-1	AC analysis of Common-Emitter BJT amplifier config. using hybrid-π model	AC analysis of Common-Source MOSFET amplifier configuration	Feedback Topologies: Voltage-Shunt & Current-Shunt feedback connections	Power Amplifiers: Definitions and amplifier types	FET current sources: Cascode current mirror and Wilson current mirror
3-3	SLO-2	Problem solving	Problem solving	Problem solving	Q point placement	Problem solving
S 4-5	SLO-1 SLO-2	Lab 1: Learning to design amplifier and oscillator circuits	Lab 4: Design & analyze differential amplifier with resistive load	Lab 7: Design and analyze RC oscillators	Lab 10: BJT & FET Current Sources	Lab 13: Design and analyze differential amplifier with active load
S-6	SLO-1	AC analysis of Common-Base BJT amplifier configuration using hybrid-π model	AC analysis of Common-Gate MOSFET amplifier configuration	Practical Feedback Amplifier Circuits	Maximum dissipation hyperbola	Analysis of CE BJT amplifier circuit with active load

3 90 80

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CLO-6:

	SLO-2	Problem solving	Problem solving	Problem solving	Heat sink	Problem solving
S-7	SLO-1	AC analysis of Common-Collector BJT amplifier config. using hybrid-π model	AC analysis of Common-Drain MOSFET amplifier configuration		Class A amplifier	Analysis of CS FET amplifier circuit with active load
3-1	SLO-2	Problem solving	Problem solving	Types of Oscillators	Problem solving	Problem solving
S-8	SLO-1	Multi-stage amplifier configurations: CE - CE, CE - CC amplifiers	BiFET amplifier configuration	Audio Frequency Oscillators: RC Phase- Shift Oscillator	Class B and Class AB push-pull amplifiers	DC and small-signal analysis of basic BJT differential pairs
3-0	SLO-2	Problem solving	Problem solving	Problem solving	Problem solving	Problem solving
S 9-10	SLO-1 SLO-2	Lab 2: Design and analyze BJT amplifier configurations	Lab 5: Design and analyze negative feedback amplifier configurations	Lab 8: Design and analyze LC oscillators	Lab 11: Design and analyze BJT CE amplifier with active load	Lab 14: Model Practical Examination
S-11	SLO-1	Multi-stage amplifier configurations: CE - CB, and CC - CC amplifiers	Low Frequency response analysis of a basic FET CS amplifier	Audio Frequency Oscillators: Wein Bridge Oscillator	Class C amplifiers	DC and small-signal analysis of basic FET differential pairs
3-11	SLO-2	Problem solving	Problem Solving	Problem Solving	Problem solving	Problem solving
S-12	SLO-1	Low Frequency response analysis of a basic BJT CE amplifier	High Frequency response analysis of a basic FET CS amplifier	Radio Frequency Oscillators: Hartley Oscillator	Class D and Class E amplifiers	Analysis of BJT differential amplifier with active load
3-12	SLO-2	Problem Solving	Problem Solving	Problem solving	Amplifier distortions	Problem solving
S-13	SLO-1	High Frequency response analysis of a basic BJT CE amplifier	Design problems in MOSFET amplifier configurations	Radio Frequency Oscillators: Colpitts & Clapp Oscillators	IC Biasing & Amplifiers with Active Load: BJT current sources: 2- & 3-transistor current sources	Analysis of FET differential amplifier with active load
	SLO-2	Problem Solving	Operational voltage levels	Problem solving	Problem solving	Problem solving
S 14-15	SLO-1 SLO-2	Lab 3: Design and analyze multistage amplifier configurations	Lab 6: Design and analyze MOSFET amplifier configurations	Lab 9: Classes of power amplifier (efficiency calculation)	Lab 12: Design and analyze FET CS amplifier with active load	Lab 15: End Semester Practical Examination

Learning
Resources

- David A. Bell, Electronic Devices and Circuits, 5th ed., Oxford University Press, 2015
 Donald Neamen, Electronic Circuits: Analysis and Design, 3rd ed., McGraw-Hill Education, 2011
 Muhammad Rashid, Microelectronic Circuits: Analysis & Design, 2nd ed., Cengage Learning, 2010
 Adel S. Sedra, Kenneth C. Smith, Microelectronic Circuits: Theory and Applications, OUP, 2014
- 5. Robert L. Boylestad, Louis Nashelsky, Electronic Devices and Circuit Theory, 11th ed., Pearson Education, 2013
- 6. Albert P. Malvino, David J. Bates, Electronic Principles, 8th ed., Tata McGraw Hill, 2015

Learning Ass	sessment												
	Bloom's			Conti	nuous Learning Ass	essment (50% weig	htage)			Final Evamination	o (E00/ woightogo)		
	Level of Thinking	CLA -	1 (10%)	CLA –	2 (15%)	CLA -	3 (15%)	CLA – 4	(10%)#	FIIIai Examinatio	n (50% weightage)		
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice		
r. Level 1	Remember Understand	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%		
Level 2	Apply Analyze	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%		
Level 3	Evaluate Create	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%		
	Total	10	0 %	100	0 %	10	0 %	100) %	-			

[#] CLA - 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, kumaranuj.anii@gmail.com	1. Dr. Meenakshi, Professor of ECE, CEG, Anna University, meena68@annauniv.edu	1. Mr. Manikandan AVM, SRMIST
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	2. Dr. M. Sangeetha, SRMIST

Course Code	18ECC202J	Course Name	LINEAR INTEGRATED	O CIRCUITS	Course Category	С	Professional Core	3	0	2	4
Pre-requis	ite		Co-requisite		Progre	ssive					

Pre-requisite Courses	18ECC102J	Co-requisite Courses	18ECC201J	Progressive Courses	Nil
Course Offering Department	Electronics and Comm	unication Engineeri	ng Data Book / Codes/Standards	Nil	

Course L	earning Rationale (CLR): The purpose of learning this course is to:	Learning							Prog	ram L	earn	ing O	utcon	nes (F	PLO)				
CLR-1:	Study the basic principles, configurations and practical limitations of op-amp	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Understand the various linear and non-linear applications of op-amp																ent		
CLR-3:	Understand the operation and analysis of op-amp oscillators, single chip oscillators and frequency generators										,						Achievement	Ħ	당
CLR-4:	Identify the active filter types, filter response characteristics, filter parameters and IC voltage regulators.		_					된			bilit						hie.	eme	Research
CLR-5:	Gain knowledge on data converter terminology, its performance parameters, and various circuit arrangements for A/D and D/A conversions.	(Bloom)	ncy (%)	ent (%)	/ledge		Development	Resea	e d		Sustainability		Work 1		Finance	D		Management	∞ర
CLR-6:	Gain hands-on experience to put theoretical concepts learned in the course to practice.	hinking	Proficiency	Attainment	\ou	Analysis	/elop	Design,	Usage	Culture	∞		Team	E 0	& Fir	Learning	Professional	Project es	Analyze
		틸	d Pro	d Att	ring	Ana	& De	, De	<u> </u>	& Cu	nent		య	icati	Mgt.	g Le			
Course L	earning Outcomes (CLO): At the end of this course, learners will be able to:	Level of	Expected	Expected	Engineering Knowledge	Problem	Design 8	Analysis,	Modern	Society	Environment	Ethics	Individual	Communication	Project I	Life Long	7	PSO – 2 Technio	PSO - 3
CLO-1:	Infer the DC and AC characteristics of operational amplifiers and its effect on output and their compensation techniques	3	80	70	Н	М	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-2:	Elucidate and design the linear and non-linear applications of an opamp and special application ICs	3	85	75	-	М	Н	-	-	-		-	-	-	-	-	-	-	-
CLO-3:	Explain and compare the working of multivibrators using special application IC 555 and general purpose opamp	3	75	70	-	М	Н	-	-	-	-	-	-	-	-	-	-	-	-
CLO-4:	Classify and comprehend the working principle of data converters and active filters	3	85	80	-	М	Н	-	-	-	-	-	-	-	-	-	-	-	-
CLO-5:	Illustrate the function of application specific ICs such as Voltage regulators, PLL and its application in communication	3	85	75	-	М	Н	-	-	-	-	-	-	-	-	-	М	-	Н
CLO-6:	.0-6: Analyze and design electronic circuits and systems using linear ICs, and take measurement of various analog circuits to compare experimental results in the laboratory with theoretical analysis			75	-	М	Н	-	М	-	1	-	М	-	-	-	Н	L	-

Durat	on (hour)	15	15	15	15	15
S-1	SLO-1	Op-amp symbol, terminals, packages	Basic op-amp circuits: Inverting & Non- inverting voltage amplifiers	Waveform Generators: Sine-wave Generators - Design	Filters: Comparison between Passive and Active Networks	Digital to Analog Conversion: DAC Specifications
0-1	SLO-2	Op-amp-Specifications	Voltage follower	Implementation & Solving problems	Active Network Design	Solving problems
	SLO-1	Block diagram Representation of op-amp	Summing, scaling & averaging amplifiers,	Square Wave generators- Design	Filter Approximations	Weighted Resistor DAC
S-2	SLO-2	Ideal op-amp & practical op-amp - Open loop & closed loop configurations	AC amplifiers	Implementation & Solving problems	Design of LPF & Solving problems	Solving problems
S-3	SLO-1	DC performance characteristics of op-amp	Linear Applications: Instrumentation Amplifiers	Triangle wave generators	Design of HPF & Solving problems	R-2R Ladder DAC
3-3	SLO-2	Solving Problems	Instrumentation Amplifiers, Solving Problems	Saw-tooth Wave generators.	Design of BPF& Solving problems	Solving problems
S 4-5	SLO-1 SLO-2	Lab-1:Basic op-amp circuits	Lab 4: Comparators	Lab 7: Waveform generators: using op- amp & 555 Timer	Lab 10: Design of LPF, HPF, BPF and Band Reject Filters	Lab 13: Flash Type ADC
S-6	SLO-1	AC performance characteristics of op-amp	V-to-I Converters	IC 555 Timer: Circuit schematic	Design of Band Reject Filters	Inverted R-2R Ladder DAC
3-0	SLO-2	Solving Problems	I-to-V converters	Operation and its applications	Solving problems	Monolithic DAC
S-7	SLO-1	Frequency response	Differentiators	IC 555 Timer: Monostable operation	State Variable Filters – All Pass Filters,	Analog to Digital conversion: ADC specifications
3-1	SLO-2	Frequency response	Integrators	Applications & Solving problems	Solving problems	Solving problems

S-8	SLO-1	Frequency compensation	Non-linear Applications: Precision Rectifiers	IC 555 Timer: Astable operation	Switched Capacitor Filters.	Ramp Type ADC
3-0	SLO-2	Frequency compensation	Wave Shaping Circuits (Clipper and Clampers)	Applications & Solving problems	Solving problems	Solving problems
S 9-10	SLO-1 SLO-2	Lab 2: Integrators and Differentiators	Lab 5: Wave shaping circuits	Lab 8: Waveform generators: using op- amp & 555 Timer	Lab 11: IC Voltage regulators	Lab 14: Simulation experiments using EDA tools
S-11	SLO-1	Basic op-amp internal schematic	Log and Antilog Amplifiers,	PLL: Operation of the Basic PLL	Voltage Regulators: Basics of Voltage Regulator	Successive Approximation ADC
3-11	SLO-2	operations of blocks	Analog voltage multiplier circuit and its applications,	Closed loop analysis of PLL	Specifications and characteristic parameters	Solving problems
S-12	SLO-1	Basic op-amp internal schematic	Operational Trans-Conductance Amplifier (OTA)	Voltage Controlled Oscillator	Linear Voltage Regulators using Op-amp,	Dual Slope ADC
3-12	SLO-2	operations of blocks	Comparators : operation	Solving problems	IC Regulators (78xx, 79xx, LM 317, LM 337, 723),	Flash Type ADC,
S-13	SLO-1	Review of data sheet of an op-amp.	Comparators applications	PLL applications	Switching Regulators -operation	Solving problems on Flash Type ADC,
3-13	SLO-2	Solving Problems	Sample and Hold circuit.	Solving problems	Types	Monolithic ADC
S 14-15	SLO-1 SLO-2	Lab 3: Rectifiers	Lab 6: Waveform generators: using op- amp & 555 Timer	Lab 9: Design of LPF, HPF, BPF and Band Reject Filters	Lab 12: R-2R ladder DAC	Lab 15: Simulation experiments using EDA tools

Learning Resources

- 1. Ramakant A. Gayakwad, Op-Amps and Linear Integrated Circuits, 4th ed., Prentice Hall, 2000
- 2. David A. Bell, Operational Amplifiers and Linear ICs, 3rd ed., OUP, 2013
- Roy Choudhury, Shail Jain, Linear Integrated Circuits, 4th ed., New Age International Publishers, 2014
 Robert F. Coughlin, Frederick F. Driscoll, Operational-Amplifiers and Linear Integrated Circuits, 6th ed., Prentice Hall, 2001
- 5. Sergio Franco, Design with operational amplifier and analog integrated circuits, McGraw Hill, 1997
- 6. LABORATORY MANUAL, Department of ECE, SRM University
- 7. David A Bell, Laboratory Manual for Operational Amplifiers & Linear ICs, 2nd ed., D.A. Bell, 2001
- 8. David La Lond, Experiments in Principles of Electronic Devices and Circuits, Delmar Publishers, 1993
- 9. Muhammed H Rashid, Introduction to PSpice using OrCAD for circuits and electronics, 3rd ed., Pearson,
- 10. L. K. Maheshwari, M. M. S. Anand, Laboratory Experiments and PSPICE Simulations in Analog Electronics, PHI, 2006

Learning Assess	sment												
	Bloom's			Conti	nuous Learning Ass	essment (50% weig	htage)			Final Evamination	n (50% weightage)		
	Level of Thinking	CLA –	1 (10%)	CLA – 2	2 (15%)	CLA –	3 (15%)	CLA – 4	(10%)#	FIIIai Examinatio	i (50 % weightage)		
	Level of Thirking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice		
Level 1	Remember Understand	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%		
Level 2	Apply Analyze	20%	20% 20% 20% 20% 20%		20%	20%	20%	20%					
Level 3 Evaluate Create		10%	10%	15%	15%	15%	15%	15%	15%	15%	15%		
	Total	10	0 %	100	0 %	100	0 %	100) %	-			

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Course Code	18ECC203J	Course Name		Microprocessor, Microprocessor	cocontroller and Interfacing Techniques	_	ourse tegory	,	С	Professional Core						L 3	T 0	P 2	C 4					
Pre-req Cours		18ECC103	3J	Co-requisite Courses	Nil		gress ourse		e 18ECE204J, 18ECE205J															
Course O	ffering Department	Elec	tronics and Com	munication Engineer	ing Data Book / Codes/Standards										Nil									
	earning Rationale (ng this course is to:		L	earnir									earniı								
CLR-1:	Understand basic a					1	2	3		1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	peripheral chips	ents with the p	rogramming and	i interfacing of microp	processors and microcontrollers with memory and																		sent	
CLR-3:	programming in ass	embly			rices and perform input/output device																	ent	Techniques	
CLR-4:	target microprocess	or			and also run them by downloading them to the	<u> </u>	(9	<u> </u>					arch			pility						Achievement	Project Management	Research
CLR-5:	parallel and serial p	orts	•	••	, and as well the properties and interfacing of the	Thinking (Bloom)	Proficiency (%)	Attainment (%)		egbəlw	s	pment	Design, Research	age	Φ	Sustainability		m Work		inance	Вu	Professional Ac	t Manaç	∞ŏ
CLR-6:	Provide strong foun	dation for desi	gning real world	applications using m	icroprocessors and microcontrollers.	nking	rofici	ttainr		J Kno	alysi	evelc	esign	Tool Usage	Culture			Теа	ation	⊗. ⊡	Learning	fessi	ojeci	Analyze
Course L	earning Outcomes	CLO): At the	e end of this cour	rse, learners will be a	ble to:	Level of Thi	Expected P	Expected A		Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Do	Modern Too	Society & C	Environment &	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Le	PSO-1: Pro	PSO – 2: Pi	PSO – 3: A
CLO-1:	Apply a basic conce	pt of digital fu	ndamentals to M	icroprocessor based	personal computer system	1	60	70		1	Н	-	-	L	-	-	-	-	-	-		-	-	-
CLO-2:				oprocessor. / microco		2	60	70		М	-	-	-		-	-	-	-	-	-	М	-	-	-
CLO-3:					odes of the target microprocessor / microcontrolle	. 3	60	70		-	М	Н	-	Н	-	-	-	-	-	-		-	-	L
CLO-4:	Distinguish and ana	lyze the prope	rties of Micropro	cessors & Microconti	rollers.	1	60	70		-	Μ	-	-		-	-	-	-	-	-	Н	-	-	-
CLO-5:	Illustrate their practi					3	60	70		-	М	М	-	Н	-	-	-	-	Н	-		-	-	Н
CLO-6:	Design, interface ar	d program me	mory chips and	various peripheral ch	with microprocessor / microcontroller 3 60 70					-	-	Μ	-	Н	-	-	-	-		-	Н	L	-	Μ

		Learning Unit / Module 1: Intel 8086 – Architecture, Signals and Features	Learning Unit / Module 2: Programming with Intel 8086	Learning Unit / Module 3: 8086 Interfacing with Memory and Programmable Devices	Learning Unit / Module 4: Intel 8051 – Architecture and Programming	Learning Unit / Module 5: Interfacing of 8051
Duratio	n (hour)	15	15	15	15	15
S-1	SLO-1	Introduction: History of computers, Block diagram of a microcomputer	Addressing modes of 8086	Semiconductor memory interfacing	Introduction: Differences between microprocessor and microcontroller	8051 parallel ports, and
3-1	SLO-2	Intel 80x86 evolutions		Dynamic RAM interfacing	Intel's family of 8-bit microcontrollers, and feature of 8051 microcontroller	its programming
S-2	SLO-1	Features of 8086 microprocessor	Instruction Set of 8086: Data Transfer Instructions	Programmable Peripheral Interface 8255	Architecture of 8051	8051 timers, and
3-2	SLO-2	Register organization of 8086	Example programs	Interfacing 8255 with 8086 and programming		its programming
S-3	SLO-1	Architecture of 8086	Data Conversion Instructions, Arithmetic Instructions	Interfacing ADC with 8086 and programming	Signal descriptions of 8051	8051 interrupts, and
S-3	SLO-2		Example programs	Interfacing DAC with 8086 and programming		its programming
	SLO-1	Lab-1: (a) Learning to Program with				
S-4,5	SLO-2	8086 processor kit; Learning the hardware features of the 8086 processor kit	Lab-4: General Purpose Programming in 8086	Lab-7: Interfacing DAC / ADC with 8086 / 8051	Lab-10: Programming timer / counter in 8086 / 8051	Lab-13: Simulation of 8051 using Keil Software
S-6	SLO-1	Instruction queue and pipelining	Logical instructions and Processor control instructions	Stepper Motor interfacing	Register set of 8051	8051 serial port, and
	SLO-2	Segmentation of memory used with 8086	Example programs		Operational features of 8051	its programming

0.7	SLO-1	Methods of generating physical address in 8086	String instructions	Programmable Interval Timer 8254	Memory and I/O addressing by 8051	Interfacing program memory with 8086
S-7	SLO-2	Pin signals of 8086: Common signals	Example programs	Interfacing 8254 with 8086 and programming	Interrupts and Stack of 8051	Interfacing data memory with 8086
S-8	SLO-1	Minimum mode signals	Branch Instructions	Programmable Interrupt Controller 8259	Addressing modes of 8051	Interfacing input devices: push-button / matrix keypad
3-0	SLO-2	Maximum mode signals	Example programs	Interfacing 8259 with 8086 and programming		Example programs
S-9,10		Lab-2: General Purpose Programing in 8086	Lab-5: Simulation of 8086 using MASM Software / 8086 Emulator	Lab-8: Interfacing DC motor / stepper motor / servo motor with 8086 / 8051	Lab-11: Programming interrupts in 8086 / 8051	Lab-14: Model Practical Exam
S-11	SLO-1	Minimum mode 8086 system, and	Assembly Language Programming of 8086	Programmable Keyboard / Display Controller 8279	8051 Instruction Set: Arithmetic and Logical Instructions	Interfacing display devices: LED / 7- segment / LCD displays
3-11	SLO-2	Timings	Assembly Language Programming of 8086	Interfacing 8279 with 8086 and programming	Example Programs	Example programs
S-12	SLO-1	Maximum mode 8086 system, and	Stack structure, and	Programmable Communication Interface 8251 USART	Data Transfer Instructions	Interfacing DAC
3-12	SLO-2	Timings	related programming	Interfacing 8251 with 8086 and programming	Example Programs	Interfacing ADC
S-13		Intel 8088 Microprocessor: Pins signals and Architecture	Interrupt structure, and	DMA Controller 8257 Boolean Variable Instructions and Brand Instructions		Interfacing DC motor / stepper motor / servo motor
0-10	SLO-2	Differences between 8086 & 8088 microprocessors	related programming	Interfacing 8257 with 8086 and programming	Example Programs	Example programs
S-14,15			Lab-6: Interfacing 8255 with 8086 / Lab-9: General Purpose Programming in 8051		Lab-10: Programming serial communication in 8086 / 8051	Lab-15: End-Semester Exam

	1.	K. M. Bhurchandi and A. K. Ray, "Advanced Microprocessors and Peripherals-with ARM and	4.	Kenneth.J.Ayala, "8051 Microcontroller Architecture, Programming and Applications", 3rd edition, Thomson,
		an Introduction to Microcontrollers and Interfacing ", Tata McGraw Hill, 3rd edition 2015		2007
Learning	2.	Muhammad Ali Mazidi and Janice GillispieMazidi, "The 8051 - Microcontroller and	5.	Subrataghoshal " 8051 Microcontroller Internals Instructions , Programming And Interfacing", 2nd edition
Resources		Embedded systems", 7th Edition, Pearson Education, 2011.		Pearson 2010
	3.	Doughlas.V.Hall, "Microprocessor and Interfacing: Programming and Hardware", 3rd	6.	Yu-cheng Liu, Glenn A. Gibson, "Microcomputer systems: The 8086/8088 family-Architecture, programming and
		edition, McGraw Hill, 2015		design",2nd edition, Prentice Hall of India,2007

Learning Assess	Learning Assessment													
	Diagras's			Conti	nuous Learning Ass	essment (50% weig	htage)			Final Evamination	n (50% weightage)			
	Bloom's Level of Thinking	CLA –	1 (10%)	CLA –	2 (15%)	CLA –	3 (15%)	CLA – 4	(10%)#	FIIIai Examination	i (50% weightage)			
	Level of Triiriking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice			
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%			
Level I	Understand	2070	2070	1070	1370	1370	1070	1070	1070	1070	1070			
Level 2	Apply	20%	20%	20% 20%		20%	20%	20%	20%	20%	20%			
LGVGI Z	Analyze	2070	2070	2070	2070	2070	2070	2070	2070	2070	2070			
Level 3	Evaluate	10%	10%	15%	15%	15%	15% 15% 15%		15% 15%		15%	15%	15%	
Level 3	Create 10% 10% 13% 13% 13% 13%										1370			
	Total 100 % 100 % 100 % 100 %													

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Course Code	18ECC204J	Course Name	DIGITA	AL SIGNAL PROCESSING	Course Category	С	Professional Core	3	T 0	P 2	4
Pre-requis Courses		18ECC104T	Co-requisite Courses	Nil	Progressiv Courses	е	18ECE243J, 18ECE244J, 18ECE245T				
Course Offe	ring Department	Electronics a	and Communication Enginee	ring Data Book / Codes/Standards		•	Nil				
	ning Rationale (CL		of learning this course is to:		Learning		Program Learning Outcomes (PLC		140	144	

Course L	earning Rationale (CLR): The purpose of learning this course is to:	L	earnii	ng					Pro	gram	Learr	ning C	Jutco	mes (PLO)				
	Understand the operations involved in digital conversion of analog signals.	1	2	3		1 :	2	3 4	5	6	7	8	9	10	11	12	13 1	14	15
	Realize a digital filter in direct, cascade and parallel forms. Perform efficient computation of DFT using radix 2 FFT										Α.						/ement	<u>=</u>	را ج
CLR-3:	Design digital FIR filter using windowing technique and frequency sampling methods.	=	<u></u>	_				5			Sustainability				.		Achiev	wanagement	Research
CLR-4:	Design IIR filters using both direct method and method involving conversion of analog filter to digital filter	00	(%) /	t (%)		age l	-	Research			aj.		Work		8		A P	20	Re
CLR-5:	Understand sampling rate conversion and apply it for applications like QMF, sub band coding.	(Blo	Proficiency	Attainment		ă K	·n			, ,	ust		>		Finance	و و			e S
CLR-6:	Utilize the techniques for digital conversions, filter designs and multi rate signal processing to solve real time problems	ki Ši	jej Sej	ai I		§ .	- S	Design	, I su	Culture	∞ర		Team	lo O	⊗ E			a E	Analyze
		Thinking		d Att		Ē.	Analysis		8	S Cu	ent			icat	Mgt.		Profe:	- Proje	
Course L	earning Outcomes (CLO): At the end of this course, learners will be able to:	Level of	Expected	Expected			_ '	Design & Analysis	Modern 7	Society 8	Environment	Ethics	Individual &	Communication	ect	e e	PSO-1: I	- hi	PSO - 3:
CLO-1:	Determine the knowledge of sampling and quantization and understand the errors that arise due to quantization.	1	80	70		1	-	- -	-	-	-	-	-	-	- 1	-	-	-	-
CLO-2:	Understand the concept of DFT and its efficient computation by using FFT algorithm.	1	75	70		- 1	И	- -	-	-	-	-	-	-	- T	-	-	-	
CLO-3:	Design FIR filters using several methods	3	75	70		- 1	И	1 -	-	-	-	-	-	-	- 1	-	-	-	Н
CLO-4:	Design IIR filters using several methods	3	75	70		-	- 1	H -	-	-	-	-	-	-	- 1	-	-	-	Н
CLO-5:	Discuss the basics of multirate DSP and its applications.	1	70	70		- 1	И	- -	-	-	-	-	-	-	- 1	-	-	-	-
CLO-6:	CLO-6: Apply the concepts of digital filter designs and multi rate signal processing for real time signals					- 1	И	- -	-	-	-	-	-	-	- 1	-	М	-	-

		Learning Unit / Module 1: Signals and Waveforms	Learning Unit / Module 2: Frequency Transformations	Learning Unit / Module 3: FIR Filters	Learning Unit / Module 4: IIR Filters	Learning Unit / Module 5: Multirate signal Processing
Duratio	on (hour)	15	15	15	15	15
	SLO-1	Basic Elements of DSP	Realization of digital filters Direct form of realization	Design of Linear Phase FIR filters General consideration	Design of digital IIR filters Comparison of FIR and IIR filters	Introduction to Multirate signal processing
S-1	SLO-2	Advantages and applications of DSP	Cascade form of realization	Causality and its implication Characteristics of practical frequency selective filters	Analog IIR filter design	Decimation
	SLO-1	Continuous Time vs Discrete time signals	Parallel form of realization	Frequency response of symmetric FIR filter	Properties of Butterworth filters	Interpolation
S-2	SLO-2	Continuous valued vs discrete valued signals	Introduction to DFT	N is odd	Properties of chebyshev filters Comparison of Butterworth and chebyshev filters	Spectrum of interpolated signal
S-3	SLO-1	Concepts of frequency in analog signals	Computation of DFT	Frequency response of symmetric FIR filter	Analog IIR filter design	Sampling rate conversion by a rational factor I/D
S-3	SLO-2	Continuous and discrete time sinusoidal signals	Properties of DFT Periodicity, linearity and symmetry properties	N is even	Design of low pass Butterworth filter	Anti-aliasing and anti-imaging filters
S-4	SLO-1	Lab 1 :Generation of basic signals	Lab 7: Linear convolution	Lab 13: Design of digital FIR Low Pass and High Pass filter using rectangular	Lab 19: Design of analog Butterworth	Lab 25: Interpolation
0.	SLO-2			window	filter	
S-5	SLO-1	Lab 2: Unit step, ramp and impulse	Lab 8: Circular convolution	Lab14: Design of digital FIR Band Pass and Band Stop filter using rectangular		Lab 26: Effect of interpolation in
0-0	SLO-2	Lab 2. Offic Step, ramp and impulse	Lab o. Gircular convolution	window	filter	frequency domain
S-6	SLO-1	Sampling of analog signals Sampling theorem	Circular convolution	Frequency response of antisymmetric FIR filter	Analog IIR filter design	Polyphase structure of decimator Polyphase decimation using z transform

	SLO-2	Aliasing Quantization of continuous amplitude signals	Matrix method and concentric circle method	N is odd and N is even	Design of low pass Chebyshev filter	Polyphase structure of interpolator Polyphase interpolation using z transform
	SLO-1	Analog to digital conversion Sample and hold,	Efficient Computation of the DFT	Design of FIR filters Fourier series method	Design of digital filters Impulse invariance method	Advantages of multirate DSP
S-7	SLO-2	Quantization and coding	Divide and Conquer Approach to Computation of the DFT Using FFT	Need for filter design using window Comparison of various windowing techniques	Design of digital filters Bilinear transformation	Applications of multirate DSP
S-8	SLO-1	Oversampling A/D converters	N Point DFT Decimation-in-Time FFT Radix-2 FFT Algorithm	Filter Design using windowing technique	Design of digital filters Impulse invariance method	Practical Applications of multirate DSP
3-0	SLO-2	Digital to analog conversion Sample and hold	N Point DFT Decimation-in-Frequency FFT	Rectangular window	Design of digital filters Bilinear transformation	interfacing of digital systems with different sampling rates
S-9	SLO-1 SLO-2	Lab 3: Generation of waveforms	Lab9: Autocorrelation and cross correlation	Lab 15: Design of digital FIR Low Pass and High Pass filter using Hanning and Hamming window	Lab 21: Design of digital Butterworth filter using impulse invariance method	Lab 27: Decimation
S-10	SLO-1 SLO-2	Lab 4: Continuous and discrete time	Lab10: Spectrum analysis using DFT	Lab 16: Design of digital FIR Band Pass and Band Stop filter using Hanning and Hamming window	Lab 22: Design of digital Butterworth filter using bilinear transformation	Lab 28: Effect of decimation in frequency domain
S-11	SLO-1	Oversampling D/A converters	Radix-2 FFT Algorithm Implementation of FFT Using DIT	Filter Design using windowing technique Hanning window	Design of digital Chebyshev filters	Practical Applications of multirate DSP Sub band coding of speech signals
3-11	SLO-2	Quantization noise	Implementation of FFT Using DIF	Filter Design using windowing technique Hamming window	Impulse invariance method	Filter banks Analysis filter bank
S-12	SLO-1	Errors due to truncation	IDFT	Filter Design using windowing technique	Design of digital Chebyshev filters	Synthesis filter bank
3-12	SLO-2	Probability of error	Using DIT FFT	Blackmann window	Bilinear transformation	Subband coding filterbank
S-13	SLO-1	Errors due to rounding	IDFT	Design of FIR filters	Frequency transformation in analog domain	Quadrature Mirror Filter
3-13	SLO-2	Probability of error	Using DIF FFT	Frequency sampling method	Frequency transformation in digital domain	Alias free filter bank
S-14	SLO-1	Lab 5: Study of sampling theorem	Lab 11: Efficient computation of DFT	Lab 17: Design of digital FIR Low Pass, High Pass, Band pass and band stop	Lab 23: Design of digital Chebyshev	Lab 29: Design of anti-aliasing filter
0 1 1	SLO-2	Zaz er etady er eampling tricerem	using FFT	filter using Blackmann window	filter using impulse invariance method	Zuo zo: Zooigii oi aiia aiiaoiiig iiitoi
S-15	SLO-1	Lab 6: Aliasing effects	Lab12: Computation of IDFT	Lab 18: Design of digital FIR filter	Lab 24: Design of digital Chebyshev	Lab 30: Design of anti-imaging filter
3 10	SLO-2			using frequency sampling method	filter using bilinear transformation	

Learning Resources 1. John G. Proakis, Dimitris G. Manolakis, "Digital Signal Processing, Principles, Algorithms and Applications", Pearson Education, 4th edition, 2014 2. Alan V. Oppenheim, Ronald W. Schafer, "Discrete-Time Signal Processing", Pearson Education, 1st edition, 2015	 Sanjit Mitra, "Digital Signal Processing –A Computer Based Approach", McGraw Hill, India, 4th Edition, 2013. Fredric J. Harris, "Multirate Signal Processing for Communication Systems", 1st edition, Pearson Education, 2007
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Learning As	sessment											
	Bloom's			Conti	nuous Learning Ass	essment (50% weig	htage)			Final Evamination	n (E0% woightage)	
	Level of Thinking	CLA – 1 (10%)		CLA –	CLA – 2 (15%)		CLA – 3 (15%)		l (10%)#	Final Examination (50% weightage)		
	Level of Thirking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	
Level 1	Remember Understand	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%	
Level 2	Apply Analyze	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%	
Level 3	Evaluate Create	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%	
	Total	10	100 %		100 %		100 %		100 %		100 %	

[#] CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, kumaranuj.anii@gmail.com	1. Dr. Meenakshi, Professor of ECE, CEG, Anna University, meena68@annauniv.edu	Dr. M.S. Vasanthi,,SRMIST
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	

Course	105000051	Course	ANALOG AND DIGITAL COMMUNICATION	Course	_	Professional Core	L	Т	Р	С
Code	10ECC2033	Name	ANALOG AND DIGITAL COMMUNICATION	Category	C	Fiolessional Core	3	0	2	4

Pre-requisite Courses	MAB203T	Co-requisite Courses	Nil	Progressive Courses	18ECC301T, 18ECC302J, 18ECE221T & 18ECE223T
Course Offering Department	ECE		Data Book / Codes/Standards	Nil	

Course L	earning Rationale (CLR): The purpose of learning this course is to:	L	earnii	ng				
CLR-1:	Introduce and Understand the need for modulation, various Amplitude modulators/demodulators, frequency modulators and demodulators	1	2	3				
CLR-2:	Comprehend the radio transmitters and receivers using the modulators and demodulators and to analyze the noise performance	<u></u>						
CLR-3:	To introduce basics of Digital modulation and detection techniques	(Bloom)	(%)	(%)				
CLR-4:	To analyze the pass band data transmission techniques in terms of probability of error	ĕ	Proficiency	Attainment				
CLR-5:	To introduce basics of spread spectrum techniques and information theory concepts	Thinking	ici ei	E.				
CLR-6:	: Gain hands-on experience to put theoretical concepts learned in the course to practice.							
-		≟	Expected F	Expected A				
Course L	urse Learning Outcomes (CLO): At the end of this course, learners will be able to:							
CLO-1:	Understand the concepts of analog modulation and demodulation techniques	2	80	70				
CLO-2:	Learn the function of radio transmitters and receivers and familiarize with noise performance of various receivers	2	85	75				
CLO-3:	Understand various digital modulation schemes and matched filter receiver	2	75	70				
CLO-4:	Understand and analyze various digital pass band data transmission schemes	2	85	80				
CLO-5:	Understand and analyze various digital pass band data transmission schemes Understanding data transmission using spread spectrum and error coding techniques							
CLO-6:	Analyze the operation of analog and digital communication systems and take measurement of various communication systems to compare experimental results in the laboratory with theoretical analysis	2	85	75				

				Prog	ram l	_earn	ing O	utco	mes (PLO)				
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO-1: Professional Achievement	PSO – 2: Project Management Techniques	PSO – 3: Analyze & Research
М	-	-	-	-	-	-	-	-	Н	-	-	Н	-	-
-	М	Н	-	-	-	-	-	-	-	-	-	Н	-	-
М	-	-	-	-	-	-	-	-	-	-	-	-	М	Н
-	-	1	М	1		1		1			-	-	М	-
-	Н	-	-	-	1	-	1	-	1	1	-	Μ	-	Н
-	-	Н	-	Н	-	-	-	Н	-	-	М	-	М	Н

		Analog Modulation	Radio Transmitters and Receivers	Digital Modulation System and Baseband Detection	Passband Data Transmission	Spread Spectrum Techniques and Information theory Concepts	
	ration nour)	15	15	15	15	15	
S-1	SLO-1	Modulation, Need for Modulation,	AM transmitter : Low Level,	Pulse modulation systems, Overview of PAM,PWM,PPM	Overview of ASK, FSK, PSK	Spread spectrum Communications, Frequency Hopping Spread Spectrum (FHSS)	
3-1	SLO-2	Amplitude Modulation, Types of Amplitude Modulation	AM transmitter : High Level Transmitter	Pulse modulation systems, Overview of PAM,PWM,PPM	Overview of ASK, FSK, PSK	Spread spectrum Communications, Frequency Hopping Spread Spectrum (FHSS)	
S-2	SLO-1	Double sideband Full carrier	FM transmitter: Direct Method	Pulse modulation systems, Sampling and quantization	Generation, Signal Space Diagram and detection of FSK	Direct Sequence Spread Spectrum (DSSS)	
3-2	SLO-2	Double sideband Full carrier	FM transmitter: Direct Method	Pulse modulation systems, Sampling and quantization	Generation, Signal Space Diagram and detection of FSK	Direct Sequence Spread Spectrum (DSSS)	
	SLO-1	Double sideband Suppressed carrier	FM transmitter: Indirect Method	PCM systems	Probability of Error for FSK	Direct Sequence Spread Spectrum (DSSS)	
S-3	SLO-2	Single sideband Suppressed carrier, VSB	FM transmitter: Indirect Method	Bandwidth of PCM, PCM TDM signal multiplexing, Limitations of PCM system	Probability of Error for FSK	Code Division Multiple Access of DSSS	
S	SLO-1	Lab-1: AM modulator and Demodulator	Lab-4: Pre emphasis and De-emphasis	II ah-7: I)P('M and its I)emodulation	Lab-10: QPSK Modulation and	Lab-13: Mini Project	
4-5	SLO-2	Lab-1. Am modulator and Demodulator	במט-א. ו וכ פוווףוומסוס מווע טפיכוווףוומסוס	Lab-1. Di Viii and its Demodulation	Demodulation	Lau-13. Willi Froject	

S-6	SLO-1	Generation of AM waves: Linear method- Collector modulator	Classification of radio receiver, Functions and Characteristics of radio receiver	Data formatting	Generation, Detection, Signal Space Diagram of PSK	Code Division Multiple Access of DSSS	
3-0	SLO-2	Generation of AM waves: Linear method- Collector modulator	Tuned Radio Frequency receiver	Data formatting	Generation, Detection, Signal Space Diagram of PSK	OFDM Communication	
. 7	SLO-1	Non-linear Modulation-Balanced Modulator	Super-heterodyne receiver- AM	Differential PCM (DPCM)	Probability of Error for PSK	OFDM Communication	
S-7	SLO-2	Non-linear Modulation-Balanced Modulator	Super-heterodyne receiver- AM	Differential PCM (DPCM)	Probability of Error for PSK	OFDM Communication	
S-8	SLO-1	Demodulation of AM waves : Linear diode detector	Super-heterodyne receiver- FM	Delta modulation (DM)	Generation, signal space diagram and detection of QPSK	Measures of Information	
3-0	SLO-2	Demodulation of AM waves : Linear diode detector	Super-heterodyne receiver- FM	Delta modulation (DM), Noise in DM	Generation, signal space diagram and detection of QPSK	Measures of Information	
s	SLO-1	Lab-2: DSB-SC modulator and	Lab-5: PAM,PPM,PWM modulation and	Lab 0. DM and to Damadulation	Lab-11: DPSK Modulation and	Lab-14: Model Practical Exam	
9-10	SLO-2 demodulator		demodulation	Lad-8: DIM and its Demodulation	Demodulation	Lau-14. Mouti Flatilidi Exdiii	
S-11	SLO-1	Frequency modulation, Types of FM	Sources of Noise	Demodulation and detection process	Probability of Error for QPSK	Source encoding, Shannon's Channel capacity theorem	
3-11	SLO-2	Narrow Band FM, Wide Band FM, Phase modulation	Sources of Noise	Demodulation and detection process	Probability of Error for QPSK	Shannon's Channel capacity theorem	
S-12	SLO-1	Generation of Narrowband FM		Maximum likelihood receiver structure, Matched filter receiver	Generation, signal space diagram and detection of π/4 QPSK	Linear block codes	
3-12	SLO-2	Generation of Narrowband FM	INDISA IN AM IENVAIDNA DATACTION	Maximum likelihood receiver structure, Matched filter receiver	Generation, signal space diagram and detection of π/4 QPSK	Linear block codes	
S-13	SI ()-1	Demodulation of FM : Foster seely discriminator		Probability error of the Matched filter, Inter symbol interference, Eye pattern	Generation, signal space diagram and detection of QAM	Cyclic codes	
3-13	SLO-2	Demodulation of FM : Foster seely discriminator	Threshold effect, Pre-emphasis and De- emphasis	Probability error of the Matched filter, Inter symbol interference, Eye pattern	Generation, signal space diagram and detection of QAM	Cyclic codes	
s	SLO-1	Lab-3: FM Modulator and Demodulator	Lab-6: Pulse Code Modulation and Lab-9: PSK Modulation and		Lab-12: BER performance analysis of	of Laboration in Provided Francisco	
14-15	l ah-3· FN	Lad-3: Fin modulator and Demodulator	Demodulation	Demodulation	various Modulation Schemes	Lab-15: University Practical Exam	

Learning Resources 1. Simon Haykin and Michael Moher, "Communication Systems," 5th edition, John Wiley & Sons, 2013 2. Singh. R. P & Sapre. S. D, "Communication Systems: Analog & Digital," 3rd edition, McGrawHill Education, Seventh Reprint, 2016. 3. Simon Haykin, "Communication Systems", John Wiley & Sons, 4th Edition, 20008. 4. Bernard Sklar, "Digital Communication, Fundamentals and Application", Pearson Education Asia 2nd Edition, 2001	B.F. Latili, Modern Digital and Ariatog Communication System, Oxford University Press, 3rd Edition, 2003. Shu Lin, Daniel Costello, "Error control coding – Fundamentals and Applications", Prentice Hall, Upper Saddle Piver, N.I. 2nd Edition, 2004.
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Learning Ass	sessment										
	Bloom's			Conti	nuous Learning Ass	essment (50% weig	htage)			Final Examination	n (EOO/ waightaga)
	Level of Thinking	CLA - 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#		Final Examination (50% weightage)	
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
Level 2	Apply Analyze	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
Level 3	Evaluate Create	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Total	100 %		100 %		100 %		100 %		-	

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Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, kumaranuj.anii@gmail.com	1. Dr. Meenakshi, Professor of ECE, CEG, Anna University, meena68@annauniv.edu	Mrs. S. Vasanthadev Suryakala, SRMIST
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	

Course Code	18ECC206J	Course Name			VLSI Design	Course Category		Professional Core	3	T 0	P 2	C 4
Pre-requisite Courses		18ECC103J		Co-requisite Courses	Nil	Progressiv Courses	'e	18ECE301J				
Course Offe	ring Department	Electro	nics and Comn	nunication Enginee	ring Data Book / Codes/Standards		•	Nil				
Course Lear	ning Rationale (CL	R): The pur	pose of learnin	g this course is to:	Learning	ı	Program Learning Outcomes (PLC	0)				

Cours	186	CC103J	Courses	Nil		ourse							18	ECE30)1J						
Course Of	ffering Department	Electronics and Com	munication Engineering	Data Book / Codes/Standards									Nil								j
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	earning Rationale (CLR):				Ļ	<u>earni</u>	_	<u> </u>				Progr	ram Le		Outco		(PLO)				4
CLR-1:	Use Verilog HDL as a design	gn-entry language for F.	PGA in electronic design	automation of digital circuits	1	2	3		1 2	2 3	4	5	6	7 8	3 9	10	11	12	13	14 15	
CLR-2:	Design, construct and simu	ılate VLSI adders and n	nultipliers.																		
CLR-3:	Understand MOSFET oper	ation																	ent		
CLR-4:	Implement a given logic fur	nction using appropriate	logic styles for improved	performance										>					vement	ਰੂ ਜ਼	
ULK-D:	Understand the basic procerules.	esses in IC fabrication,	steps in the fabrication of	MOS ICs, and as well the layout design	(Bloom)	(%)/	t (%)		ge	in the	search			ustainability	Work		9		Achie	anagem Reseal	
CLR-6:	Use modern engineering to with the design and analysis			out design experiments and gain experience	hinking (Bl	oficiency	Attainment		Knowlec	Development	esign, Re	Usage	Culture	& Susta	Team W	uo	& Finance	arning	ssion	ect M yze 8	
Course Le	earning Outcomes (CLO):	At the end of this cou	rse, learners will be able	to:	evel of Thinl	Expected Pro	cted,		Engineering Knowledge	Design & Develo	^nalysis, Des	Modern Tool	Society & Cu	Environment	ual &	Communication	ct Mgt.	Long Lea	1-1	O – 2: Proje shnidues O – 3: Anal	
01.0.4	D : !: ! !!!		1151 () ()	· · · · · ·			Expe				Ā		တိ	Ē Ē	<u> </u>		Proje	Life	8 8	Z A R	-
	Design and implement digit			, ,	3	85	75	-	- 1	H H	-	Н	-	- -		-	-	-	-		1
CLO-2:	Design general VLSI system	m components, adder c	ells and multipliers to add	dress the design of datapath subsystem.	3	85	75		- I	1 H	-	Н	-			-	-	-	-		
CLO-3:	Examine the characteristics	s of MOS transistors			2	80	70		H I	1 -	-	-	-	- -	- -	-	-	-	-	- -	
CLO-4:	Analyze CMOS inverter an	d other complex logic g	ates designed using diffe	rent logic styles	2	80	70		- 1	L	-	-	-		- -	-	-	-	-		1
CLO-5:	Explain how the transistors	are built, and understa	nd the physical implemer	ntation of circuits.	2	80	70		- 1	_ L	-	-	-		-	-	-	-	-	- -	1
CLO-6:	Use HSPICE computer and	alysis program and Veri	log HDL for simulation an	nd analysis of MOS circuits and building blocks	3	85	75		- 1	<i>I</i> М	-	Н	-		- H	М	L	М	-	- M]

Duratio	n (hour)	Learning Unit / Module 1: Introduction to Verilog HDL & Coding	Learning Unit / Module 2: Subsystem Design	Learning Unit / Module 3: MOS Transistor	Learning Unit / Module 4: CMOS Inverter and Circuit Design Styles	Learning Unit / Module 5:
		15	15	15	15	15
	SLO-1	Introduction to HDL & Verilog HDL	General VLSI System Components: Multiplexers	Generic overview of the MOS device: MOS transistor symbols	CMOS Inverter Characteristics: Operation and properties of static CMOS inverter	Properties of basic materials used in microelectronics: Silicon, Silicon dioxide
S-1	SLO-2	Introduction to Verilog HDL, modules and ports	Decoders	MOS structure demonstrating (a) accumulation, (b) depletion, and (c) inversion; nMOS transistor demonstrating cutoff, linear, and saturation regions of operation	VTC of static CMOS inverter	Polysilicon and Silicon Nitride
S-2	SLO-1	Lexical Conventions: White Space and Comments, Operators	Comparators	MOS Transistor under Static Conditions: The threshold voltage	DC Inverter Calculations	Basic Processes in Integrated-Circuit Fabrication: Wafer Formation, Photolithography, Well and Channel Formation
	SLO-2	Numbers, Strings, Identifiers, System Names, and Keywords	priority encoder	Resistive operation	Symmetrical Inverter	Silicon Dioxide (SiO ₂), Isolation, Gate Oxide
S-3	SLO-1	Verilog Data Types: Nets, Register Variables, Constants	shift and rotate operations	Saturation region	Inverter switching characteristics	Gate and Source/Drain Formations, Contacts and Metallization, Passivation, Metrology
3-3	SLO-2	Referencing Arrays of Nets or Regs	Adders: Standard adder cells	Current-voltage characteristics	Output capacitance	Some Recurring Process Steps: Diffusion and Ion Implantation, Deposition, Etching, Planarization
S-4, 5	SLO-1	Lab-0: Verilog Operators:		Lab-6: Realization of VLSI multipliers - I		

SLO-2	Arithmetic Operators, Bitwise Operators, Reduction Operators, Logical Operators, Relational Operators, Shift Operators, Conditional Operator, Concatenation Operator, Expressions and Operands, Operator Precedence	Lab-3: Design using FSM and ASM charts		Lab-9: Design and Analysis of CMOS Inverter using HSPICE	Lab-12: Design and Analysis of 4-input Dynamic NAND gate using HSPICE
SLO-1		Ripple Carry Adder (RCA)	Dynamic behavior: MOSFET Capacitances, viz., MOS structure capacitances	Secondary Parasitic Effects: Leakage Currents, Parasitic Resistances	Simplified CMOS Process flow
SLO-2	sequential circuits	Carry Look-Ahead Adder (CLA)	Channel capacitance and Junction (or, depletion) capacitances	Inverter layout	
SLO-1	Compilation and simulation of Verilog code	Carry Select Adder (CSL)	Parasitic Resistances, viz., Drain and Source Resistance, Contact Resistance		Layout design rules: Well rules, transistor rules
SLO-2	Test bench	Carry Save Adder (CSA)	Non-ideal I-V effects: Mobility Degradation, Velocity Saturation		Contact rules, metal rules, via rules and other rules
SLO-1	Dataflow modelling	Carry Skip Adder (CSK)	Channel Length Modulation, Threshold Voltage Effects	CMOS Circuit Design Styles: Static CMOS logic styles	Gate Layouts
SLO-2	Realization of Combinational and sequential circuits	Carry Bypass Adder (CBA)	Leakage, Temperature Dependence, Geometry Dependence, Subthreshold Current	CMOS circuits, pseudo-nMOS, tristate circuits, clocked CMOS circuits	Stick diagrams
SLO-1 SLO-2	Lab-1: Realization of combinational and sequential circuits using gate-level and dataflow modeling	Lab-4: Realization of VLSI adders - I	Lab-7: Realization of VLSI multipliers - II	Lab-10: (a) Design and Analysis of complex CMOS gate using HSPICE (b) Design and Analysis of Pseudo-NMOS gates using HSPICE	Lab-13: Model Practical Examination
SLO-1	Behavioral modelling	Multipliers: Overview of multiplication (unsigned multiplication, shift/add multiplication algorithms, multiplication of signed numbers, types of multiplier architectures)	Short-channel MOSFETS: Hot carriers, Lightly-Doped Drain (LDD)	Differential Cascade Voltage Switch Logic (DCVSL), Pass Transistor Logic (PTL)	CMOS Process Enhancements: Transistors (Multiple Threshold Voltages and Oxide Thicknesses, Silicon-on- Insulator, High-k Gate Dielectrics, Higher
SLO-2	Realization of Combinational and sequential circuits	Braun multiplier	MOSFET scaling	Dynamic CMOS logic styles: Basic dynamic logic	Mobility, Plastic Transistors,)
SLO-1	Switch-level modelling	Baugh-Wooley multiplier	Short-channel effects: Negative Bias Temperature Instability (NBTI), oxide breakdown	Signal integrity issues in dynamic design	Interconnects
SLO-2	Realization of MoS circuits	Wallace Tree multiplier	Drain-Induced Barrier Lowering (DIBL), Gate-Induced Drain Leakage (GIDL), Gate Tunnel Current	Signal integrity issues in dynamic design	Circuit elements
SLO-1	Design using FSM	Booth multiplier	Tutorials	Domino Logic Circuits: Differential Domino logic, multiple-output domino	Beyond conventional CMOS
SLO-2	Realization of sequential circuits	Booth multiplier	Tutorials	Compound domino, NORA, TSPC	Tutorials
SLO-1	Lab-2: (a) Realization of digital circuits using behavioral modeling (b) Realization of MOS circuits using witch local median	Lab-5: Realization of VLSI adders - II	Lab-8: Realization of RAM & ROM	Lab-11: (a) Design and Analysis of AND/NAND gate in DCVSL using SPICE (b) Design and Analysis of Pass- Transistor gates and CPL gates using	Lab-14: End-Semester Practical Examination
	SLO-1 SLO-2 SLO-1 SLO-2 SLO-1 SLO-2 SLO-1 SLO-2 SLO-1 SLO-2 SLO-1 SLO-2 SLO-1	SLO-2 Reduction Operators, Logical Operators, Relational Operators, Shift Operators, Conditional Operator, Concatenation Operator, Expressions and Operands, Operator Precedence SLO-1 Verilog modelling: Gate-level modelling Realization of Combinational and sequential circuits SLO-1 SLO-2 Realization of Combinational and sequential circuits SLO-1 SLO-2 Realization of Combinational and sequential circuits SLO-1 SLO-1 Lab-1: Realization of combinational and sequential circuits using gate-level and dataflow modelling SLO-2 Realization of Combinational and sequential circuits using gate-level and dataflow modeling SLO-1 SLO-1 Switch-level modelling SLO-2 Realization of MoS circuits SLO-1 Design using FSM SLO-2 Realization of sequential circuits using behavioral modeling	Reduction Operators, Logical Operators, Relational Operators, Conditional Operators, Conditional Operator, Concatenation Operator, Expressions and Operands, Operator Precedence SLO-1 Verilog modelling: Gate-level modelling SLO-2 Realization of Combinational and sequential circuits SLO-1 Dataflow modelling SLO-2 Test bench SLO-1 Dataflow modelling SLO-2 Realization of Combinational and sequential circuits SLO-1 Lab-1: Realization of combinational and sequential circuits using gate-level and dataflow modeling SLO-1 Behavioral modelling SLO-2 Realization of Combinational and sequential circuits SLO-1 Behavioral modelling SLO-2 Realization of Combinational and sequential circuits SLO-1 Behavioral modelling SLO-2 Realization of Combinational and sequential circuits SLO-1 Switch-level modelling SLO-2 Realization of MoS circuits SLO-1 Design using FSM Booth multiplier SLO-2 Realization of sequential circuits using behavioral modeling SLO-2 (a) Realization of digital circuits using behavioral modeling SLO-3 (b) Realization of VLSI adders - II Lab-2: (a) Realization of digital circuits using behavioral modeling SLO-2 (b) Realization of MOS circuits using	Reduction Operators, Logical Operators, Relational Operators, Shift Operators, Shift Operators, Concatenation Operator, Concatenation Operator, Expressions and Operands, Operator Precedence SLO-1 Verilog modelling: Gate-level modelling SLO-2 Realization of Combinational and sequential circuits SLO-1 Compilation and simulation of Verilog code SLO-2 Test bench Carry Save Adder (CSL) Carry Save Adder (CSA) Parasitic Resistances, viz., Drain and Source Resistance, Contact Resistance SLO-1 Dataflow modelling Carry Save Adder (CSA) Mon-ideal I-V effects: Mobility Degradation, Velocity Saturation SLO-1 Dataflow modelling Carry Skip Adder (CSK) Channel Leapadion, Velocity Saturation SLO-1 Dataflow modelling Carry Skip Adder (CSA) Carry Suppass Adder (CBA) SLO-2 Realization of Combinational and sequential circuits using gate-level and dataflow modelling SLO-1 Behavioral modelling Multipliers: Overview of multiplication algorithms, multiplication of signed numbers, types of multiplier architectures) SLO-2 Realization of Combinational and sequential circuits SLO-2 Realization of Scircuits Wallace Tree multiplier Tutorials SLO-2 Realization of sequential circuits using behavioral modelling Booth multiplier Tutorials Lab-2: (a) Realization of digital circuits using behavioral modelling Booth multiplier Tutorials Lab-3: Realization of Scircuits using Scott Industry Science Tutorials SLO-2 (a) Realization of digital circuits using behavioral modeling Lab-5: Realization of VLSI adders - Il Lab-5: Realization of VLSI adders - Il Lab-8: Realization of RAM & ROM	Reduction Operators, Logical Operators, Sufficient Operators, Conditional Operators, Conditional Operator, Concatenation Operator, Concatenation Operator, Expressions and Operators, Conditional Operator, Concatenation Operator, Expressions and Operators, Operator Precedence SLO-1 Verilog modelling: Gate-level modelling Realization of Combinational and sequential circuits SLO-2 Realization of Combinational and sequential circuits SLO-2 Tost bench Carry Select Adder (CSL) Carry Save Adder (CSA) Degradation, Velocity Saturation Carry Save Adder (CSA) Degradation, Velocity Saturation Carry Save Adder (CSK) Stock Saturation Carry Save Adder (CSK) Carry Save Adder (CSK) Stock Saturation Carry Save Adder (CSK) Carry Save Adder (CSK) Stock Saturation Carry Save Adder (CSK) Carry Save Adder (CSK) Stock Saturation Carry Save Adder (CSK) Stock Saturation Carry Save Adder (CSK) Stock Saturation Carry Save Adder (CSK) Carry Save Adder (CSK) Stock Saturation Carry Save Adder (CSK) Carry Save Adder (CSK) Carry Save Adder (CSK) Stock Saturation Carry Save Adder (CSK) Carry S

	9.	Jan Rabaey, Anantha Chandrakasan, B Nikolic, "Digital Integrated Circuits: A Design	12.R. Jacob Baker, "CMOS Circuit Design, Layout, and Simulation", Wiley, (3/e), 2010.	
Loorning		Perspective". Second Edition, Feb 2003, Prentice Hall of India.	13. John P. Uyemura, "CMOS Logic Circuit Design", Kluwer, 2001.	
Learning Resources	10.	Weste, Harris, "CMOS VLSI Design: A Circuits and Systems Perspective", 4th edition, Addision-	14. S. Palnitkar , Verilog HDL – A Guide to Digital Design and Synthesis, Pearson , 2003	
Resources		Wesley, 2011.	15. Paul. R. Gray, Robert G. Meyer, "Analysis and Design of Analog Integrated Circuits", Wiley, (4/e), 2001.	
	11.	Wayne Wolf, "Modern VLSI Design: IP-based Design", 4th edition, PHI, 2009.	16. M.D. Ciletti , Modeling, Synthesis and Rapid Prototyping with the Verilog HDL, Prentice Hall, 1999	

	Bloom's			Conti	nuous Learning Ass	essment (50% weig	htage)		Final Examination (50% weightage)		
		CLA -	- 1 (10%) CLA - 2		2 (15%)	CLA –	CLA – 3 (15%)		l (10%)#	Final Examination	i (50% weightage)
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
Level 2	Apply Analyze	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
Level 3	Evaluate Create	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Total	10	0 %	10	0 %	10	0 %	100	0 %	10	0 %

[#] CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, kumaranuj.anii@gmail.com	1. Dr. Meenakshi, Professor of ECE, CEG, Anna University, meena68@annauniv.edu	1. Mr. Manikandan AVM, SRMIST
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	2. Dr. J. Manjula, SRMIST

Course	18ECC301T C	Course	Wireless Communication	Course	^	Professional Core	L	Т	Р	С
Code	N	Name	Wileless Communication	Category		Piolessional Cole	3	1	0	4

Pre-requisite Courses	18ECC205J, 18ECC105T	Co-requisite Courses	Nil	Progressive Courses	18ECE220T
Course Offering	Department Electronics and C	ommunication Engineering	Data Book / Codes/Standards		Nil

Course L	earning Rationale (CLR):	The purpose of learning this course is to:	L	earniı	ng
CLR-1:	Understand the elements of	Wireless Communication and mobile communications	1	2	3
CLR-2:	Understand the Mobile Rad	lio Wave Propagation - Large Scale Fading	<u></u>	~)
CLR-3:	Analyze how to apply Mobi	le Radio Wave Propagation - Small Scale Fading	(Bloom)	(%)	(%)
CLR-4:	Study the Capacity and Dive	ersity concepts in wireless communications	- I iii	S _O	ent
CLR-5:	Acquire the knowledge of W	/ireless System and Standards	Thinking	Proficiency	Attainment
CLR-6:	Understand and design vari	ous wireless systems	ij	Jo.	ıttai
			₽		- 1
Course L	earning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of	Expected	Expected
CLO-1:	Acquire the knowledge of W	rireless communication and basic cellular concepts	2	75	60
CLO-2:	Understand` the essential R	adio wave propagation and mobile channel models	2	75	60
CLO-3:	Familiarize about Various p	erformance analysis of mobile communication system.	2	75	60
CLO-4:	Attain the knowledge of Div	ersity and capacity concepts	2	75	60
CLO-5:	O-5: Be familiar with the various standards of Mobile Communication Systems 2			75	60
CLO-6:	Explore the various concept	s of wireless communication, its design with respect to fading and link performance	2	75	60

				Prog	ram L	earn	ing O	utco	mes (PLO)				
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO-1: Professional	PSO – 2: Project Management Techniques	
Н	-	-	-	-	-	-	-	-	-	-	М	М	-	L
Н	Н	Н	Н	-	-	-	-	-	-	-	М	М	-	Н
Н	Н	Н	-	-	-	-	-	-	-	-	-	-	-	Н
Н	Н	-	-	-	ı	1	ı	1	1	-	-	-	ı	Н
Н	-	-	-	-		-	1	1	1	-	М	М	1	L
Н	Н	Н	Н	М	-	-	-	-	М	-	М	М	-	Н

Duration		Wireless communication: Mobile communications	Large Scale Fading	Small Scale Fading	Improvement on Link performance	Wireless systems and standards		
(I	nour)	12	12	12	12	12		
S-1	SLO-1	Introduction to wireless communication and mobile radio communication	Introduction to Radio wave Propagation	Introduction Small scale multipath propagation	Introduction to diversity, equalization and	AMPS Voice modulation Process		
3-1	SLO-2	Classification of wireless communications - simplex, half duplex, dull duplex		Impulse response model of multipath channel	capacity	AMPS voice modulation Process		
S-2	SLO-1	Paging and Cordless systems		Impulse response model of multipath channel	Space diversity	GSM system architecture and its interfaces		
3-2	SLO-2	Cellular telephone systems	propagation model - pathloss model	Small scale multipath measurements - Direct Pulse measurement	Scanning diversity	OSW System architecture and its interial		
S-3	SLO-1	Timing diagram - landline to mobile		Small scale multipath measurements - Sliding correlator measurement	Maximal ratio combiner	GSM frame structure		
3-3	SLO-2	Timing diagram - mobile to mobile		Small scale multipath measurements - Swept frequency measurement	Equal gain diversity	GOW Harrie Structure		
S-4	SLO-1	Basic antenna parameters, Far field and near field	Simplified pathloss model	Parameters of mobile multipath channels -	Rake Receiver	GSM speech operations input - output		
3-4	SLO-2	Frequency reuse, sectored and omni- directional antennas	Emperical model - Okumara	Time dispersion and Coherent bandwidth	nake Neceivei	GOM speech operations input - output		
	SLO-1	Channel assignment strategies	Emperical model - Hata model	Parameters of mobile multipath channels -				
S-5	SLO-2	Handoff and its types		Doppler spread and Coherent time	Capacity in AWGN	Forward CDMA process		
S-6	SLO-1	Interference and system capacity	Piecewise linear model - log normal model		Capacity of flat fading channels	Reverse CDMA Process		
0-0	SLO-2	The residue and System capacity	in lose miser moder - log normal moder	selective fading		IVEACISE OFINIVILIOCESS		

S-7	SLO-1	Taxabian and Condo of Comics	Shadowing	Types of fading: Flat and Frequency	Carrelines and its mode	Multicarrier modulation	
5-1	SLO-2	Trunking and Grade of Service	Combined pathloss and shadowing	selective fading	Equalizer and its mode	Multicarrier modulation	
S-8	SLO-1	Cell splitting	Outage Probabilty	Types of fading: Fast and Slow fading	Adaptive equalizer block diagram	OFDM Transmitter Block diagram	
0-0	SLO-2		Cutage 1 Tobability	Types of fading. I ast and Glow fading	Adaptive equalizer block diagram	Of DW Transmitter block diagram	
S-9	SLO-1	Sectoring	Cell Coverage Area	Types of fading: Fast and Slow fading	Types of Equalizers , elementary level only	OFDM Receiver Block diagram	
3-9	SLO-2	Sectoring	Cell Coverage Area	Types of faultig. I ask and Slow faultig	Types of Equalizers - elementary level only		
S-10	SLO-1	Microcell zone concepts	Solving problems – Brewster angle	Ricean distribution	Introduction to MIMO antennas	Importance of Cyclic Prefix	
3-10	SLO-2		Solving problems – Brewster angle	Ricean distribution	introduction to whive antennas	importance of Cyclic Frenx	
S-11	SLO-1	Umbrella cells	Solving problems –empirical model	Rayleigh distribution	Introduction to MIMO antennas	Case study - Modern antennas	
3-11	SLO-2	Unibrella cells	Solving problems –empincal model	, 0		,	
S-12	SLO-1	Salving Droblems	Solving problems – friis transmission	Salving problems Depoler effect	Case study :Recent trends in Diversity and MIMO antennas	Case study Modern entennes	
3-12	SLO-2	Solving Problems	formula	Solving problems – Doppler effect	MIMO antennas	Case study - Modern antennas	

		1.	Rappaport.T.S., "Wireless Communications: Principles and Practice", 2 nd Edition, Pearson, 2011.	ı
Learni	rnina	2.	John D Kraus, Ronald J Marhefka, Ahmed S Khan "Antenna and Wave Propagation", 4th Edition, Tata	ı
	ources		McGraw Hill, 2010	ı
Res	ources	3.	Constantine Balanis. A, "Antenna Theory: Analysis and Design", 3rd Edition, John Wiley, 2012.	ı
		4	Andreas F Molisch "Wireless Communications" Wiley 2nd Edition-2005 Reprint-2014	ı

- Andrea Goldsmith, "Wireless Communications", Cambridge University Press, Aug 2005
 Schiller, "Mobile Communications", Pearson Education Asia Ltd., Reprint 2012
 Lee W.C.Y., "Mobile Communications Engineering: Theory and Applications", McGraw Hill, New York, 2nd Edition, 1998

Learning As	arning Assessment											
	Bloom's			Conti	nuous Learning Ass	essment (50% weig	htage)			Final Evamination	o (50% woightage)	
	Level of Thinking	CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#		Final Examination (50% weightage)		
	Level of Thirking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	
Level 1	Remember	40 %		30 %		30 %		30 %		30%		
Level I	Understand	40 %	-	30 70		30 %	-	30 %		30 /0	-	
Level 2	Apply	40 %	_	40 %	_	40 %	_	40 %	_	40%	_	
Level 2	Analyze	40 /0	_	40 /0	_	40 70	_	40 70	_	4070	_	
Level 3	Evaluate	20 %		30 %		30 %		30 %		30%		
Level 3	Create	20 %	-	30 %	-	30 %	-	30 %	-	30%	-	
	Total	100 %		100 %		100 %		100 %				

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Course	18ECC3021 Course	Microwave & Optical Communications	Course	C	Professional Core	L	Т	Р	С	
Code	Name	wildowave & Optical Communications	Category	C	Fibressional Core	3	0	2	4	

Pre-requisite Courses	18ECC	205.1	-requisite Courses	Nil	Progressive Courses	18ECE226T & 18ECE323T
Course Offering I	Department	Electronics and Communication Engineering		Data Book / Codes/Standards	Nil	

Course L	earning Rationale (CLR):	The purpose of learning this course is to:	L	earniı	ng			
CLR-1:	Identify Microwave active de	evices and Microwave generators	1	2	3			
CLR-2:	Analyze Microwave passive	devices						
CLR-3:	Explore Microwave Measure	ements) E	(%)	%)			
CLR-4:	Analyze Optical Fibers Option Measurements	cal Sources, Amplifier and Transmitter Optical Detectors , Receiver and Performance	Level of Thinking (Bloom)	Proficiency	Attainment			
CLR-5:	Explore Optical Communication System Design and Concepts							
CLR-6:	Analyze Microwave and optical components							
			el o	Expected	Expected			
Course L	earning Outcomes (CLO):	At the end of this course, learners will be able to:	Lev	Exp	찞			
CLO-1:	Acquire knowledge on the th	neory of microwave transmission, microwave generators and associated components.	2	80	70			
CLO-2:	Analyse microwave passive	devices and components.	2	80	70			
CLO-3:	Understand microwave measurements and associated techniques with equipment							
CLO-4:	Familiarize with the fundamentals of light transmission through fiber							
CLO-5:	Design a basic optical communication system.							
CLO-6:	Understand the working principle of microwave components , Microwave measurements, optical sources, detector and fibers							

				Prog	ram l	earn	ing O	utco	mes (PLO)				
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO-1: Professional	PSO – 2: Project Management Techniques	PSO – 3: Analyze & Research
Н	-	-	L	-	-	-	-	-	-	-	-	-	-	L
Н	М	Н	Н	-	-	-	-	-	-	-	-	L	-	М
Н	М	Н	М	-	-	-	-	-	-	-	-	М	-	Н
Н	Н	-	М	-	-	-	-	-	-	-	-	L	-	L
Н	Н	-	Н	-	-	-	-	-	-	-	-	М	-	М
Н	Н	Н	Н	-	-	1	1	1	-	-	-	М	1	Н

Du	ration						
(h	our)	15	15	15	15	15	
S-1	SLO-1	Introduction to microwaves and optical	High frequency parameters: S parameters	Importance matching	Florente of Outled fiber communication	Point-to-Point link –Analog system design	
3-1	SLO-2	communications	and S matrix analysis for N-port microwave device	impedance matching.	Elements of Optical fiber communication	considerations and design steps	
	SLO-1	History of Microwave Engineering,			Functional block diagram of a Transmitter	Point-to-Point link – Digital system design	
S-2	SLO-2	Microwave transmission and Applications; Maxwell Equations	Directional coupler	IVSVVR and Impedance measurement	and receiver module	considerations and design steps	
	SLO-1	Microwave Tubes			Optical fiber structure, Light Propagation in		
S-3	SLO-2	Klystron amplifier	E and H plane Tee	Measurement of Power	Optical fibers: Ray theory , Total Internal reflection, Skew rays	Digital Link Design: Link power budget	
	SLO-1		Lab- 4 Gain and radiation pattern of		Lab- 10 Measurement of Numerical	Lab- 13 Design of basic Optical	
S-4-5	SLO-2	Lab- 1 Characteristics of Reflex Klystron	Horn antenna	Lab- 7 Practice session	Aperture, propagation and bending losses of optical fiber	Communication system using computational tool	
S-6	SLO-1	Reflex Klystron oscillators	Magic Tee	Measurement of Frequency and Q factor	Optical Sources: Light source materials,	Rise time budget	
3-0	SLO-2	Therex Mystron oscillators	iwagic 166	ineasurement of Trequency and Q factor	LED Structures	Trase time budget	
S-7	SLO-1	Magnetron oscillators	Microwave Circulators, Isolators	Insertion loss measurements	LED Characteristics	Overview of Analog links: Radio over Fiber;	
3-1	SLO-2	iviagnetion oscillators	iviiciowave circulators, isolators	inscrion ioss measurements	LLD Glialaciciistics	Overview of Arialog IIIIKS. Radio over Fiber,	
S-8	SLO-1	Microwave Bipolar Transistors	Attenuators and Phase Shifters	Attenuation measurements	Semiconductor Laser Diode, Laser	Key link parameters	
3-0	SLO-2	Field effect transistor	Alteridators and mase Smilers	Auguation measurements	Characteristics	ney link parameters	

S-9- 10	61.0.3	Lab- 2 Study of power distribution in Directional coupler, E plane, H plane and Magic Tee	Microstrin natch antenna and narallel	Lab- 8 DC characteristics of LED and Laser diode	Lab- 11 Analysis of Analog optical link	Lab- 14 Practice Session
S-11	SLO-1	IMPATT, TRAPATT and Tunnel diode	Destangular Wayaguidaa	Measurement of Scattering parameters	Optical Detectors: PIN and APD photo	Multichannel System: Need for multiplexing
3-11	SLO-2	TIMPATT, TRAPATT and Tunner Gode	Rectangular Waveguides	Measurement of Scattering parameters	detector	Operational principles of WDM, DWDM
S-12	SLO-1	Gunn diode	Rectangular Waveguides	Manager amount of Coattoring parameters	Responsivity and efficiency of APD	WDM Components: Coupler/Splitter, Fabry
3-12	SLO-2	Guilli diode	Rectangular waveguides	Measurement of Scattering parameters	Responsivity and eniciency of APD	Perot Filter
0.40	SLO-1	Owner Orallistics made		Functioning details of Vector Network		WDM Components: Optical MEMS
S-13	SLO-2	Gunn Oscillation modes		Analyzer; Signal Analyzer; Spectrum analyzers	reiner altentiation and dispersion	switches
S-14-	SLO-1	Lab- 3 Impedance measurement by	Lab- 6 Design of RF Filters and	Lab- 9 DC characteristics of PIN and		Lab- 15 Study experiment - Gunn Diode
15				APD photo-diode	, , , , ,	(Microwave) and Optical WDMA (Optical)

		1.	David M. Pozar, "Microwave Engineering", 4th Edition, John Wiley & Sons, 2012.
		2.	David M. Pozar, "Microwave & RF Design of Wireless Systems", John Wiley & Sons, 2001.
		3.	Samuel Y. Liao, "Microwave Devices and Circuits", 3rd Edition, Pearson Education, 2013.
		4.	Robert. E. Collin, "Foundations for Microwave Engineering", 2nd edition, Wiley, Reprint 2014.
	earning	5.	Annapurna Das, Sisir K. Das, "Microwave Engineering", 3rd Ed., McGraw Hill, 2015.
K	esources	6.	I. Hunter, "Theory and design of microwave filters", The Institution of Engineering &Technology,
			2001.
		7.	Keiser G, "Optical Fiber Communication Systems", 5th Edition, 6th Reprint, McGraw Hill
			Education (India), 2015.

- Vivekanand Mishra, Sunita P. Ugale, "Fiber Optic Communication: Systems and Components", Wiley-India, 1st edition. 2013
- Djafar.K. Mynbaev and Lowell and Scheiner, "Fiber Optic Communication Technology", Pearson Education Asia, 9th impression, 2013
- John M. Senior, "Optical fiber Communications: Principles and Practice", Pearson Education, 3rd Edition, 2009
- 11. R.P. Khare, "Fiber Optics and Optoelectronics", Oxford University Press, 2007.
- 12. Rajiv Ramaswami, Kumar N. Sivaranjan, Galen H.Sasaki "Optical Networks A practical perspective", 3nd edition, 2013

Learning Assessment											
	Bloom's	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
	Level of Thinking	CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#		Final Examination (50% weightage)	
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
Level 2	Apply Analyze	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
Level 3	Evaluate Create	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Total	otal 100 %		100 %		100 %		100 %		100 %	

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Course	18ECC303J	Course		Comput	er Communication Networks		Cou	ırse		,			_	Profess	sional	Coro					L	Т	Р	С
Code	10ECC3033	Name		Comput	er Communication Networks		Cate	gory	'	C Professional Core 3 0							2	4						
Pre-requi	site	18CSS101J	,	Co-requisite	Nil		Prog	ressi	ive							8ECE	2207							
Course	s	186331013		Courses	INII		Co	urses	s						1	BECE	3201							
Course Off	ering Department	Ele	ectronics and Co	ommunication Eng	ineering Data Book / Codes/Standard	is			Nil															
Course Lea	rning Rationale (CL	R): The pu	rpose of learning	g this course is to:			Lea	arnin	ıg					Prog	ram L	earni	ng Oı	utcom	nes (F	PLO)				
CLR-1: /	ntroduce the basic co	ncepts in the	field of compute	r networks.			1	2	3	ſ	1	2 3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Inderstand the function	onal aspects o	of OSI model arc	hitecture.			(-	0))							У							ent	당
CLR-3:	Acquire knowledge of	the Network	Layer protocols				l oc	(%)	(%)				뒫			pilit							eu	Research
CLR-4: /	Analyze the various is:	sues and cha	llenges of Trans	port Layer.			g (Bloom) lency (%) ment (%) nent Aesearch e e e e ance ance ala						ınag											
CLR-5: /	amiliarize the various	Application I	Layer Protocols.				king (Bloom fficiency (%) ainment (%) sis lopment n, Research sage re re am Work n ing sional ct Manageme						₩ W	∞ ∞										
CLR-6:	Itilize the networking	concepts to a	nalyze the perfo	rmance of Routing	protocols.		Thinking (Blc I Proficiency Attainment Attainment Besign, Resea bol Usage Culture and & Sustainal ant & Sustainal atton t. & Finance earning ofessional ant						Project Management s	Analyze										

CLR-6: Office the networking concepts to analyze the performance of Routing protocols.	f Thin	ed Pro	ed Att	ee mig iv	تِّ ا	, Desig	Tool U	& Cultu	nent &		al & Te	nicatio	Mgt. &	ng Leari	Profes ment	: Proje	3: Analy
Course Learning Outcomes (CLO): At the end of this course, learners will be able to:	Level o	Expected	Expecte	Problem	Design 6	Analysis	Modern	Society	Environ	Ethics	Individual	Communic	Project I	Life Lon	PSO-1: Achieve	PSO – 2 Technia	PS0 - 3
CLO-1: Express the basic services and concepts related to internetworking.	1	60	65	-	-	-	-	-	Н	-	-	-	-	М	-	-	-
CLO-2: Explain the basic OSI model architecture and its lower layer functions.	1	60	65		М	-	-	-	L	-	-	- 1	-	-	-	-	Н
CLO-3: Illustrate the various Network Layer concepts, mechanisms and protocols.	2	65	65	-	Н	-	-	L	М	-	- 1	- 1	-	-	-	-	-
CLO-4: Describe the services and techniques of Transport Layer.	1	60	65	-	-	-	-	-	М	-	-	- 1	-	-	-	-	Н
CLO-5: Discuss the various services and protocols in Application Layer.	1	60	65	-	М	-	-	-	-	-	- 1	-	-	-	-	-	Н
CLO-6: Analyze the various Networking concepts and Routing protocols.	2	60	65	-	-	-	L	-	-	-	-	- 1	-	М	-	-	Н
				•		•											

	ration nour)	DATA COMMUNICATION & NETWORKING BASICS	OSI LOWER LAYERS	NETWORK LAYER	TRANSPORT LAYER	APPLICATION LAYER
		15	15	15	15	15
S-1	SLO-1	Introduction to Data Communication and Networking	Network models	Introduction to Network Layer	Introduction to Transport Layer	Introduction to Application Layer
3-1	SLO-2	Data transfer modes-Serial and Parallel transmission	OSI layer architecture	Need for Internetworking	TCP/IP Model	Application Layer Paradigms
S-2	SLO-1	Protocols & Standards	Data Link Layer-Introduction	Addressing-Classful	User Datagram Protocol(UDP)	Client Server Interaction
5-2	SLO-2	Layered Architecture	Link Layer Addressing	Addressing-Classful	User Datagram Protocol(UDP)	Client Server Interaction
	SLO-1	Principles of Layering & Description	Error Detection	Addressing-Classless	Transmission Control Protocol(TCP)	SIP
S-3	SLO-2	Brief description of concepts in OSI & TCP/IP model	Error Detection	Addressing-Classless	Transmission Control Protocol(TCP)	SIP
	SLO-1	Lab 1: To build and configure a simple	.			Lab 13: Create a Socket (TCP&UDP)
S 4-5	SLO-2	network of four nodes connected with point-to-point links.	Lab 4: To simulate token ring protocol and to study its performance.	Lab 7:To simulate CSMA/CA protocol and to study its performance	Lab 10: Implementation and study of Selective Repeat protocol.	between two computers and enable file transfer between them.
S-6	SLO-1	Switching Types- Circuit- & Packet switching	Error Correction	Network Layer Protocol-IPV4	TCP Services & Features	Compression Techniques
3-0	SLO-2	Switching Types- Message switching, Comparison of switching types	Error Correction	Internet Protocol(IP)-IPV4	TCP Services & Features	Compression Techniques
S-7	SLO-1	LAN, MAN & WAN	Data link control-LLC	Internet Protocol(IP)-IPV6	Congestion Control	Introduction to Cryptography

	SLO-2	LAN, MAN & WAN	Data link control-LLC	Internet Protocol(IP)-IPV6	Congestion Control	Types, Attacks and Services
S-8	SLO-1	Network topologies-Types	Data link control-MAC	Routing Protocols- Distance Vector& Link State	Congestion Control	DES
3-0	SLO-2	Comparison of topologies	Data link control-MAC	Routing Issues-Delivery, Forwarding and Routing	Congestion Control	DES
S	SLO-1	Lab 2: To simulate star and bus network		Lab 8: Implementation and study of	Lab 11: To configure a network using	Lab 14: Implementation of Data
9-10	SLO-2	topologies.	detection and Correction scheme.	stop and wait protocols	Link State Routing protocol .	Encryption and Decryption.
S-11	SLO-1	IEEE standards for LAN-Ethernet	Flow & Error Control Protocol	Routing Information Protocol-RIP	QOS-Quality of Service	RSA
3-11	SLO-2	Types of Ethernet	Flow & Error Control Protocol	Routing Information Protocol-RIP	QOS-Quality of Service	RSA
S-12	SLO-1	Token Bus	ARQ Schemes	Open Shortest Path First-OSPF	Techniques to improve QOS	Email
3-12	SLO-2	Token Ring	ARQ Schemes	Open Shortest Path First-OSPF	Techniques to improve QOS	FTP
S-13	SLO-1	FDDI	HDLC	Border Gateway Protocol-BGP	Techniques to improve QOS	HTTP
3-13	SLO-2	FDDI	HDLC	Border Gateway Protocol-BGP	Techniques to improve QOS	SNMP
S	SLO-1	Lab 3: To simulate token bus protocol	Lab 6:To simulate CSMA/CD protocol	Lab 9: Implementation and study of Go	Lab 12: To configure a network using	
14-15	SLO-2	and to study its performance.	and to study its performance	back N protocol.	Distance Vector Routing protocol.	Lab 15: Mini Project

Learning	•		Behrouz A.Fehrouzan, "Data communication & Networking", Mc-Graw Hill, 5 th Edition Reprint, 2014
Resourc	es	2.	Andrew S.Tanenbaum, "Computer Networks", Pearson Education India, 5th Edition, 2013.

- William Stallings, "Data & Computer Communication", Pearson Education India, 10th Edition, 2014.
 James F. Kurose, Keith W. Ross, "Computer Networking: A Top–Down Approach Featuring the Internet", Pearson Education,6th Edition, 2013.
 "Lab Manual", Department of ECE, SRM Institute of Science and Technology

Learning Ass	sessment										
	Bloom's			Conti	nuous Learning Ass	essment (50% weig	htage)			Final Evamination	n (50% weightage)
	Level of Thinking	CLA –	1 (10%)	CLA –	2 (15%)	CLA –	3 (15%)	CLA – 4	(10%)#	Filiai Examinatio	ii (50 % weigiilage)
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
Level I	Understand	2070	2070	1370	1370	1370	1370	1370	1370	1370	1370
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
Level 2	Analyze	2070	2070	2070	2070	2070	2070	2070	2070	2070	2070
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
Level 3	Create	10%	10%	13%	10%	10%	10%	13%	13%	13%	13%
	Total	10	0 %	100	0 %	10	0 %	100) %	10	0 %

[#]CLA - 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, kumaranuj.anii@gmail.com	1. Dr. Meenakshi, Professor of ECE, CEG, Anna University, meena68@annauniv.edu	1. Ms. T. Ramya, SRMIST
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	

Course Code	18ECC350T	Course Name		CON	IPREHENSION		Cou Cate	(.	Professional Core	e L T 0 1	P C 0 1
Pre-requisite	NIL			Co-requisite				D	O NIII		
Courses				Courses	-			· ·	Courses NIL		
Course Offering	Department	Electronics	and Communication	Engineering	Dat	a Book / Codes/Sta	ındards	Nil			
Course Learning	Rationale										
(CLR):	The p	urpose of learning	this course is to:					Learning	Program	Learning Outcomes (PLO)	
CLR-1: Acquire	e skills to solve real wor	ld problems in Ana	alog and Digital Elect	ronics (Discrete & I	C)			1 2 3	1 2 3 4 5	6 7 8 9 10 11 12	2 13 14 15
	e skills to solve real wor									>	
CLR-3: Acquire	e skills to solve real wor	ld problems in Sig	nals & Systems, and	DSP				(F) (Q) (G)	Engineering Knowledge Problem Analysis Design & Development Analysis, Design, Research Modern Tool Usage	Society & Culture Environment & Sustainability Ethics Individual & Team Work Communication Project Mgt. & Finance	
	e skills to solve real wor				SI Design			Level of Thinking (Bloom) Expected Proficiency (%) Expected Attainment (%)	Engineering Knowledge Problem Analysis Design & Development Analysis, Design, Resea Modern Tool Usage	Society & Culture Environment & Sustaina Ethics Individual & Team Work Communication Project Mgt. & Finance	
	e skills to solve real wor							ng (E	owlk sis lopm n, R	Sus Sus	
CLR-6 : Acquir	e skills to solve real wor	id problems in Mic	crowave and Optical	Communications				inkir rofic	Engineering Knowle Problem Analysis Design & Developm Analysis, Design, Rk Modern Tool Usage	Society & Culture Environment & Sus Ethics Individual & Team 1 Communication Project Mgt. & Fina	
Causaa I aassaisaa	Outeeman							ed F	ering & D K D I S, D To	Mgt Mgt	5 - 2 8
Course Learning (CLO):	At the	end of this course	e, learners will be ab	le to:				vel o	gine obler sign alysi	Society Enviror Ethics Individu Commu	PSO - 1 PSO - 2 PSO - 3
` '								E E E	Mo Ber G		
	ce and gain confidence a					ete & IC)		3 85 80	H H H L L	L L L L L L	
	ce and gain confidence a							3 85 80	H H M L L	L L L L L L	M M M
	ce and gain confidence a					11/10/D '		3 85 80	H H M L L		
	ce and gain confidence a							3 85 80	H H M L L		M M M
	ce and gain confidence a ce and gain confidence a							3 85 80 3 85 80	H H H L L H H M L L	<u>L L L L L L L L</u>	M L M
CLO-6: Practic	e and gain confidence a	япа сотретенсе и	soive problems in i	листоwave and Opuc	ai Communicat	ONS		3 80 80	HHHMLLL		IVI IVI IVI
Duration (hour)		3		3			3		3		3
S-1 SLO-1	Tutorial on Analog E	lectronics (Discret	e & IC) Tutorial on	Digital Communica	ation	Tutorial on Micro	rocessors & Interfacin	g Tutorial o	on Transmission Lines	Tutorial on Opt	ical Communication
SLO-2	Problem Solving		Problem Sol			Problem Solving		Problem S		Problem Solving	
	Tutorial on Digital El	lectronics		Signals and Syster			ontrollers & Interfacing		n VLSI Design	Model Test	
SLO-2	Problem Solving		Problem Sol			Problem Solving		Problem S		Model Test	
	Tutorial on Analog C	Communication		Digital Signal Proc		Tutorial on Electr	omagnetics		on Microwave Communic		
SLO-2	Problem Solving		Problem Sol	ving	ı	Problem Solving		Problem S	solving	Final Test	
Learning Resources	1. R.S.Khurmi, J.K.Gu	ıpta, Mechanical E	ngineering: Convent	ional and Objective	Types, S.Chand	1 & Co., 2018	2. R.K.Jain, Convention Publishers, 2014	onal & Objectiv	ve Type Question & Answe	rs on Mechanical Engineeri	ng for Competitions, Khai
Learning Assess	sment										
	Bloom's					Assessment (50%	<u> </u>	1		Final Examination	n (50% weightage)
	Level of Thinking		1 (10%)		2 (15%)		LA – 3 (15%)		CLA – 4 (10%)#		
	o l	Theory	Practice	Theory	Practice	Theory	Practice	Theory	/ Practice	Theory	Practice
Level 1	Remember Understand	-	40%	-	30%	-	30%	-	30%	-	30%
Level 2	Apply Analyze	-	40%	-	40%	-	40%	-	40%	-	40%
			20%	-	30%	-	30%	-	30%	-	30%
Level 3	Evaluate Create	-	1				100 %	1	100 %	1 1/	00 %
	Create Total		00 %		0 %	0 1/ 0/ 1 1/22		<u>.</u>	100 /6	II.	10 /6
# CLA – 4 can be	Create Total e from any combination					l s, Self-Study, MOO	Cs, Certifications, Conf.	Paper etc.,	100 /6	10	70 76
Course Designe	Create Total e from any combination rs			Talks, Mini-Project	s, Case-Studies	•	Cs, Certifications, Conf.	Paper etc.,	100 /6		
# CLA – 4 can be Course Designe Experts from Ind	Create Total e from any combination rs lustry	of these: Assignment	ents, Seminars, Tech	n Talks, Mini-Project	s, Case-Studies	her Technical Insti	Cs, Certifications, Conf.	•		Internal E	
# CLA – 4 can be Course Designe Experts from Ind	Create Total e from any combination rs	of these: Assignment	ents, Seminars, Tech	n Talks, Mini-Project	s, Case-Studies	her Technical Insti	Cs, Certifications, Conf.	•		Internal E	

B. Tech in Electronics and Communication Engineering

(with Specialization in Instrumentation Engineering)

2018 Regulations

Professional Elective Courses (E)

Department of Electronics and Communication Engineering SRM Institute of Science and Technology SRM Nagar, Kattankulathur – 603203, Kancheepuram District, Tamilnadu

Course	19ECE1901 Cours	TRANSPINCED ENGINEEDING	Course	Professional Elective	L T	Р	С
Code	18ECE180J Name	TRANSDUCER ENGINEERING	Category	Professional Elective	2 0	2	3

Pre-requisite Nil	Co-requisite Courses		Progressive Courses	
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil	

Course Learning Rationale (CLR): The purpose of learning this course is to:	L	earni	ng						Progr	ram L	_earn	ing O	utcor	nes (F	PLO)			
CLR-1: Gain knowledge on methods of measurement, & know about various types of errors in instruments	1	2	3	ŀ	1	2	3	4	5	6	7	8	9	10	11	12	13	14 15
CLR-2: Know the behavior of transducers under static and dynamic conditions and to model the transducers				Ī							>-						for ns	ror ent
CLR-3: Acquire knowledge on different types of resistive, inductive and capacitive transducers	=		_					arch			pilit						- 9,	3 🖺
CLR-4: Identify the application of resistive, inductive and capacitive transducer	(Bloom)	y (%)	t (%)		dge		ent	Se			aina		Work		9		control te syste	anagement
CLR-5: Predict correctly the expected performance of various sensor	g(B)	Proficiency	Attainment		× e	S	Development	ı, Re	age	Φ	Sustainability		٦ ٧		Finance	Б	S et c	S E
CLR-6: Locate the different type of sensors used in real life applications and paraphrase their importance	hinking	ofici	tain		출	alysi	velc	esign,	l Us	Culture	∞		Team	igi	∞ŏ	arni	disc	sten ctive
	Ē	- L			ing	Analysis	& De	D	Tool Usage	ರ %	nen		∞ŏ	ical	Mgt.	J Le	Automatic	orillz of svs Effec
Course Learning Outcomes (CLO): At the end of this course, learners will be able to:	Level of	Expected	Expected		Engineering Knowledge	Problem	Design 8	Analysis,	Modern .	Society 8	Environment	Ethics	Individual	Communication	Project ∧	e l	PSO 1: /	rsO-2: r control o PSO-3: I skills
CLO-1: Apply the mathematical knowledge, science and engineering fundamentals to solve problems pertaining to various measurements	2	80	80	-	Н	Н	1	-	-	-	-	-	-	-	-	-	Н	- H
CLO-2: Determine the static and dynamic characteristics of transducer	2	85	80		Н	Н	-	Μ	-	-	-	-	-	-	-	-	Н	- H
CLO-3: Understand the resistive, inductive and capacitive transducers which are used for measuring various parameters	2	75	80	Ī	Н	-	М	М	-	-	-	-	-	-	-	-	Н	- H
CLO-4: Have an adequate knowledge on the various miscellaneous transducers.	2	85	80		Н	Н	-	М	-	-	-	-	-	-	-	-	Н	- H
CLO-5: To demonstrate the various types of basic transducers.	2	85	80		Н	-	Н		-	-		-	Н	М	-	-	Н	- H
CLO-6: Select the right transducer for the given application	2	85	80		Н	1	Н	Н	1	-	-	-	Н	М	-	-	Н	- H

		Learning Unit / Module 1	Learning Unit / Module 2	Learning Unit / Module 3	Learning Unit / Module 4	Learning Unit / Module 5
Duratio	n (hour)	12	12	12	12	12
S-1		General configuration and description of measuring Instruments	Characteristics of instruments : Static characteristics: Accuracy, precision, resolution, sensitivity	Inductive sensor: common types- brief discussion with respect to material, construction and input output variable	Miscellaneous Transducers: Piezoelectric transducer	Smart Transducers: Smart Sensors, Components of Smart Sensors
	SLO-2	Basic methods of measurement	Characteristics of instruments : linearity, span and range, threshold, Hysterisis, Dead Time	Reluctance change type	Hall Effect transducer	General architecture of Smart Sensors
	SLO-1	Functional Elements of Measurement Systems	Dynamic characteristics	Magnetostrictive type	Magneto elastic sensor	Evolution of Smart Sensors
S-2		Definition, principles of sensing and transduction	Resistive Transducers: RTD Materials, Temperature measurement change in physical properties, 3 wire and 4 wire RTD	Mutual inductance change type	Digital transducers	Advantages of Smart Sensors
S-3	SLO-1 SLO-2	Lab1: Identifying the components of	Lab 4: Characteristics of RTD	Lab 7: Characteristics of Thermistor	Lab10: Characteristics of Hall effect	Lab13:Temperature measurement using
S-4	SLO-1 SLO-2	measuring instruments.	Lab 4. Characteristics of TV1D	Lab 1. Characteristics of Thermistor	transducer	LABVIEW and DAQ Hardware
	SLO-1	Units, Standards	Potentiometer Type- Forms, material	Transformer Type	Radiation sensors: Materials	Application area of Smart Sensors
S-5	SLO-2	Unit conversions	Potentiometer Types- resolution, accuracy, sensitivity.	LVDT: Construction, material, output input relationship, I/O curve, discussion.	Radiation sensors: construction, response	MEMS sensor
S-6		Error: Classification of errors, Limiting error and probable error	Strain gauge: Theory, type, materials, design consideration, sensitivity	RVDT : Construction, material	Photo emissive cell types	NEMS sensor

		T	Derivation of acuse factor variation with	Cynobron Microsyn	T	T
	SLO-2	Error analysis- Statistical methods	Derivation of gauge factor, variation with temperature, adhesive, rosettes	Synchros, Microsyn	Photovoltaic cells	Proximity sensors
	01.0.4	-	temperature, aunesive, rosettes			·
S-7	SLO-1					
	SLO-2	Lab2:Determining the transfer function of	Lab 5: Characteristics of strain gauge	Lab 8: Characteristics of LVDT	Lab11: Characteristics of Synchros	Lab14:Displacement measurement
S-8	SLO-1	a first order transducer	Lab o. Onaracteristics or strain gauge	Lab o. Onaractoristics of LVD1	Lab 11. Characteristics of Cynonios	using LABVIEW and DAQ Hardware
3-0	SLO-2					
	SLO-1	Problems in Statistical methods- mean,	Thermistor: Material, shape, ranges and	Capacitive Transducers: Variable	Photodiodes	Fiber optic sensors
	020 /	median mode,variance	accuracy specification	distance-parallel plate type		Tiber opic sensors
S-9		Problems in Statistical methods- standard	Thermocouple:Thermo emf sensor:	Capacitive Transducers: variable area-		
	SLO-2	deviation, probable error of one reading	types, Laws of thermo couple. Reference		Light Dependent Resistor	Biosensors
		lueviation, probable error or one reading	junction compensation	dielectric constant type		
				Capacitive Transducers: calculation of		
	SLO-1	Classification of transducers	Load cell-Principle, construction	sensitivity. Stretched diaphragm type	Geiger counters	Film sensors
S-10						
	SLO-2	Selection of transducers	Hot-wire anemometer	Capacitor Microphone, response	Scintillation detectors	Environmental Monitoring sensors
	3LU-2	Selection of transducers	not-wire ariemometer	characteristics	Schrillation detectors	(Water Quality & Air pollution)
S-11	SLO-1	Lab 2. Ctatistical Eman analysis Mann CD				
3-11	SLO-2	Lab3: Statistical Error analysis- Mean, SD,		Lab 9: Characteristics of capacitive	Lahan Ohamatariatian at LDD	A mini project on MEMS / Nano/ smart/
0.40	SLO-1	variance for an open loop response of	Lab 6: Characteristics of Thermistor	transducer		fiber/ sensor using any software tools
S-12	SLO-2	thermocouple]

	1.	Doeblin, E.O., "Measurement Systems: Applications and Design", 6th Edition, Tata McGraw-Hill	
Learning Resources	2.	Book Co., 2011. Bentley, J. P., "Principles of Measurement Systems", 4th Edition, Addison Wesley Longman Ltd.,	
	3.	UK, 2004. Patranabis, D., "Sensors and Transducers", 2 nd Edition, Prentice Hall India Pvt. Ltd, 2010.	

- Murthy, D.V.S., "Transducers and Instrumentation", Prentice Hall of India Pvt. Ltd., New Delhi, 2010.
 Neubert H.K.P., "Instrument Transducers An Introduction to their Performance and Design", Oxford University Press, Cambridge, 2003.

Learning Ass	sessment											
	Bloom's				Final Evamination	o (50% woightage)						
	Level of Thinking	CLA –	1 (10%)	CLA –	2 (15%)	CLA –	3 (15%)	CLA – 4	l (10%)#	Final Examination (50% weightage)		
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%	
Level I	Understand	2070	2070	1370	1370	1370	1370	1370	1370	1070	1370	
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%	
Level 2	Analyze	2070	2070	2070	2070	2070	2070	2070	2070	2070	2070	
Laval 2	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%	
Level 3	Create	10%	10%	15%	15%	13%	13%	15%	13%	15%	15%	
	Total	10	0 %	100	0 %	10	0 %	100	0 %		-	

[#]CLA - 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. D. Karthikeyan, Controls of Engineering India Pvt Ltd, <u>karthikeyan.d@controlsoftengg.in</u>	1. Dr. J. Prakash, MIT, Chennai, prakaiit@rediffmail.com	1. Mrs. N. Deepa, SRMIST
2. V. Venkateswaran, Instrumentation Consultant, wenkat99@gmail.com	2. Dr. D. Nedumaran, Madras University, dnmaran@gmail.com	2. Dr. A. Vimala Juliet, SRMIST

Course	18ECE181T	Course	MEASUDEMENTS AND INSTRUMENTATION	Course	_	Professional Elective	L	Т	Р	С
Code	10EGE1011	Name	MEASUREMENTS AND INSTRUMENTATION	Category	E	Professional Elective	3	0	0	3

Pre-requisite Nil	Co-requisite Courses		Progressive Courses	
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil	

Course Learning Rationale (CLR): The purpose of learning this course is to:		Lea	arning	g	Program Learning Outcomes (PLO)														
CLR-1: Study the various techniques that are used to measure Current & Voltage		1	2	3	Ī	1	2	3	4	5	6	7	8	9	10	11	12	13 14	4 15
CLR-2: Study the various techniques that are used to measure power & energy		(L	(%	<u></u>														ms for	ent
CLR-3: Design circuits to measure resistance, capacitance & inductance		\approx $^{\circ}$	\sim	(%)		Knowledge		ij						Work		8		S ign o	s management
CLR-4: Study different techniques to measure non-electrical quantities		<u>n</u>	5	jeu		Ş Ş		ä		ge				>		Finance	g i	S S S	ınaç
CLR-5: Study the working of various display devices		E G	icie	<u>⊒</u>		lo N	/sis	ele	esign,	Jsa	en:	∞		Team	<u>_</u>	走	earning	screte PLC	S m s
CLR-6: Study the working of various recorders		l ninking	Proficiency	Attainment		g X	Analysis	Development	Des	Tool Usage	Culture	nt 8			aţic	÷. ∞	ea	mar disc	Stive
		=	교			eri	n A	ంద		T ₀	∞ర	me		<u>a</u>	ij	Mgt.	ong L	\$ % E	f sv Effe
Course Learning Outcomes (CLO): At the end of this course, learners will be able to:		Level of	Expected	Expected		Engineering	Problem	Design	Analysis,	Modern	Society	Environment &	Ethics	Individual &	Communication	Project	Life Lor	continou PSO-2: 1	control o PSO-3: F skills
CLO-1: Understand the techniques to measure current and voltage	2	.3	80	80		Н	-	-	-	-	Ĥ	-	-	-	-	-	Н	Н -	Н
CLO-2: Understand the techniques to measure power and energy	1	2	80	80		Н	-	-	-		Н			-	-	-	Н		· H
CLO-3: Design circuits for measuring resistance, inductance and capacitance	1		80	80		Н	Н	М	Н	М	Н	-	-	-	-	-	Н	Н -	· H
CLO-4: Understand the techniques to measure non electrical quantities	2	3	80	80		Н	Н	М	Н	М	-			Н	-	-	Н		· H
CLO-5: Apply knowledge of measurement and instrumentation in display a devices	3		80	80		Н	-	М	-	Н	ı		-	-	-	-	Н		· H
CLO-6: Apply knowledge of measurement and instrumentation in recording devices	3		80	80		Н	-	М	-	Н	-	-	-	-	-	-	Н		· H

Di	uration	Learning Unit / Module 1	Learning Unit / Module 2	Learning Unit / Module 3	Learning Unit / Module 4	Learning Unit / Module 5
(hour)	9	9	9	9	9
S-1	SLO-1	Introduction to measurements and Instrumentation. Classification of Instruments.	Introduction of power energy measurements		Introduction to measurement of Non- Electric Quantities	Introduction to display devices and recorders
	SLO-2	Galvanometer Introduction and its type.	Measurement of power in A.C. circuits	Classification of resistance types	Non-electric parameters	Digital display methods
S-2	SLO-1	D'Arsonval Galvanometer – construction, working and torque derivation.	Derivation of total power in A.C circuits	Methods of Low resistance measurement – Ammeter Voltmeter, Kelvins Double bridge method, Potentiometer.	Measurement of Pressure	Digital Storage Oscilloscope,
	SLO-2	PMMC – construction, working and torque derivation	Measurement of power in D.C. circuits	Methods of Medium resistance measurement	low and high pressure	Digital Voltmeter
S-3	SLO-1	Vibration galvanometer – construction, working and derivation	Derivation of total power in D.C. circuits	Substitution method & Voltmeter - ammeter method	Measurement of Vibration	Ramp type, integrating, potentiometric
	SLO-2	Introduction to Moving iron instruments	Introduction to Electrodynamic wattmeter	Wheatstone bridge method	Nature & its quantities	Recorders
S-4	SLO-1	Attraction type – construction and working	Electrodynamic wattmeter - Construction, Working and derivation	Methods of High resistance measurement	Measurement of Temperature	Continuous and discrete recorders
0 4	SLO-2	Repulsion type– Construction and working	Errors in Electrodynamic wattmeter	Megger	Thermistor, thermocouple	Strip chart recorder
S-5	SLO-1	Electro dynamometer – working principle	Numerical Problem	Methods of Earth resistance measurements	Measurement of Radiation	X-Y recorder
3- 3	SLO-2	Dynamometer type Instrument- Construction and working	Power measurement in polyphase systems- basics	Introduction and general equations of A.C. Bridges	Pyrometers	UV Recorder
S-6	SLO-1	Induction type Instruments	Three Wattmeter method	Methods of Inductance measurements	Measurement of Flow	Direct recording

	SLO-2	Construction and Working	Two & One Wattmeter method	problems	Ultrasonic flow transducer, electromagnetic flow meter	Audio recorder
C 7	SLO-1	Introduction to ammeter and voltmeter		·	Measurement of Humidity	Advantages and Disadvantages
S-7	SLO-2	Extension of ammeter ranges	Introduction to Single phase induction type energy meter	problems	Using Hygrometers	Video Recorder
S-8	SLO-1	Extension of voltmeter ranges	Single phase induction type energy meter - Construction, working principle	Methods of Mutual inductance	Measurement of Sound	Advantages and Disadvantages
3-0	SLO-2	Calibration of ammeters	Testing of energy meters			Case Study on Plasma, LCD and Led Displays
S-9	SLO-1	Calibration of voltmeter	Phantom loading	Methods of Frequency measurements	Measurement of Level	Case Study on digital voice recorder
3-9	SLO-2	summary	Meter testing circuits	problems	Ultrasonic method, capacitive methods	Summary

	1.	Sawhney, A.K., "A Course in Electrical & Electronic Measurements & Instrumentation", Dhanpat Rai and
		Co., New Delhi, 2015
Learning	2.	Golding. E. W, and Widdis F.C, "Electrical Measurements and Measuring Instruments", 3rdEdition,A.H.
Resources		Wheeler & Company, 2011.
	3.	Copper. W.D and Helfrick A.D, "Modern Electronic Instrumentation and Measurement Technique", 1
		Edition, Pearson Education, India, 2013.

- 4. Bell, A.D., "Electronic Instrumentation and Measurements", 3rd EditionOxford University PressIndia,
- Northrop, R.B., "Introduction to Instrumentation and Measurements", 3rd Edition, CRC Press, 2017.
 Carr, J.J., "Elements of Electronic Instrumentation and Measurement", Pearson Education India, 3rd edition, 2003.

Learning Ass	sessment											
	Bloom's				Final Evamination	n (50% woightage)						
	Level of Thinking	CLA –	1 (10%)	CLA -	2 (15%)	CLA -	3 (15%)	CLA – 4	(10%)#	Final Examination (50% weightage)		
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	
Level 1	Remember Understand	30 %	-	30 %	-	30 %	-	30 %	-	30%	-	
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-	
Level 3	Evaluate Create	30 %	-	30 %	-	30 %	-	30 %	-	30%	-	
	Total	10	0 %	10	0 %	10	0 %	100	0 %	10	0 %	

[#] CLA - 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. D. Karthikeyan, Controlsoft Engineering India Pvt Ltd, <u>karthikeyan.d@controlsoftengg.in</u>	1. Dr. J. Prakash, MIT, Chennai, prakaiit@rediffmail.com	1. Mr. C. Likith Kumar, SRMIST
2. V. Venkateswaran, Instrumentation Consultant, wvenkat99@gmail.com	2. Dr. D. Nedumaran, Madras University, dnmaran@gmail.com	2. Dr. A. Vimala Juliet , SRMIST

Course Code	18ECE182T	Course Name	AUTOMOTIVE INSTRUME	NTATION SYSTEMS	Course Category	Ε	Professional Elective	1 3	T 0	P 0	C 3
Pre-requis Courses Course Offe	INII	Electronic	Co-requisite Courses Nil Courses Stand Communication Engineering	Data Book / Codes/Standards	Progre Cour Nil	- 1	Nil				

Course O	ffering Department	Data Book / Codes/Standards	NII																	
Course L	earning Rationale (CLR):	The purpose of learning this course is to:		L	earni	ng				ı	Progra	am Le	earnir	າg Oເ	utcon	nes (F	PLO)			
CLR-1:	Know about the basics of au	tomotive systems and requirements.		1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13 14	15
CLR-2:	Know about the principles b	ehind various sensors and its application across a v	vehicle.										_						or For	ır
CLR-3:	Know about various electric	al systems pertaining to engine.		-	_					된			<u>=</u>						2 H 2	eme
CLR-4:	Know about different safety	and security systems.		(Bloom)	(%) /	(%)	ge		Ħ	Sea			ustainability		Work		8		ontrol s syste & DC	nag
CLR-5:	Know about different electro	nic systems in the body of the car.		<u>B</u>	ency	Attainment	wed	(0	Development	8	Usage	m	nste				Finance	ning	2 4 7	ma
CLR-6:	Know about the sensors and	d various systems of automotive domain.		ki j	Jicie	ainn	Kno	lysi	Nelo	esign,	ns	Culture	∞ S		Feam	o.	Σ	earnir	matic discre e PLC	tive
				Thinking	F.		ing	Analysis	De		<u>100</u>		ent		∞	icat	Mgt.		s & c	:svs
Course L	earning Outcomes (CLO):	At the end of this course, learners will be able to:		Level of "	Expected	Expected	Engineering Knowledge	Problem	Design &	Analysis,	Modern 7	Society &	Environn	Ethics	Individual	Communication	Project N	Life Long	PSO 1: A continous PSO-2: L	control of PSO-3: E skills
CLO-1:	Understand the automotive	domain and electronic systems in it.		1	80	75	Н	Н	-	-	L	-	-	-	-	-	-	Н	Н -	Н
CLO-2:	Understand the effect of ele	ctromagnetic interference.		1-3	70	60	Н	Н	-	L	-	-	-	-	-	-	-	-	М -	Н
CLO-3:	Identify the sensor and actu	ator technologies involved in a car.		1,2	90	80	Н	Н	М	L	Μ	-	-	-	-	-	-	Н	Н Н	-
CLO-4:	Analyze the various electrical	al systems and electronics involved in it for upgrade	ed operation.	2,3	90	80	Н	Н	М	L	Μ	-	-	-	-	-	-	Н	М -	Н
CLO-5:	LO-5: Update his/her knowledge with new systems on safety, security and body of a car.				80	75	Н	Н	М	L	М	-	-	-	-	-	-	Н	МН	М
CLO-6:	-6: Understand the automotive problems and provide solutions through new system design.				80	70	Н	Н	-	-	L	-	-	-	-	-	-	Н	Н -	Н

Du	ration	Learning Unit / Module 1	Learning Unit / Module 2	Learning Unit / Module 3	Learning Unit / Module 4	Learning Unit / Module 5
(ł	nour)	9	9	9	9	9
	SLO-1	Introduction to Automotive Electronics	Intake Air Temperature (IAT) Sensor	Starting Systems – Requirements	Tire pressure monitoring systems	Power Windows
S-1	SLO-2	Outline to Automotive Sensors	Engine Coolant Oil Temperature Sensor	Starter Motor – selection and working principle	Capacitive based Pressure Sensor	Smart Window Lift Control Module
S-2	SLO-1	Requirements in Automotive Sensor	Exhaust Gas Recirculation Temperature Sensor	Diagnosing Faults – Symptoms	Anti-lock braking system	Central Locking System
3-2	SLO-2	Open and Closed Loop Control Strategies	Exhaust Gas Temperature Sensor	Testing Procedures	Anti-lock braking system	Power Seat
S-3	SLO-1	Shop safety – General safety	Manifold Absolute Pressure (MAP) Sensor	Charging systems – Requirements	Traction Control System	Automatic Wiper systems
3-3	SLO-2	Electrical Safety	High Pressure Fuel Sensor, Engine Oil Pressure Sensor	Components and operation	Adaptive Cruise Control	Electronic Vehicle Immobilizer
S-4	SLO-1	Office Safety	Crankshaft Angular Position Sensor	Diagnosing Faults – Symptoms	Types of Adaptive Cruise Control	Oil Pressure Warning System
3-4	SLO-2	Lifting Procedures	Cam Position Sensor	Testing Procedures	Types of Adaptive Cruise Control	Engine Overheat Warning System
S-5	SLO-1	Electrical wiring, Terminals & Switching	Piston Position Sensor	Ignition systems – Requirements	Parking guide systems	Speed Warning System
3-3	SLO-2	Multiplexed Networking	Throttle Plate Angular Position	Conventional Ignition System	Air Bag System	Door Lock Indicators
S-6	SLO-1	Circuit Diagrams and Symbols	Knock Sensor	Electronic Ignition System	Reversible Seat Belt Pre-tensioner	Gear Neutral Indicator
3-0	SLO-2	Electromagnetic Interference	Oxygen Concentration Sensor	Programmed Ignition System	Electronic Power Steering systems	Anti-Theft Alarm System

6.7	SLO-1	Electromagnetic Compatibility	Mass Air Flow (MAF) Rate Sensor	Distributor less Ignition System	Vehicle Stabilization System	Brake Actuation Warning System
S-7	SLO-2	Use of Diagnostic Equipment	Rain Sensor	Direct Spark Ignition System	II Venicie Staniii 7ation System	Computer Controlled Air Conditioning Systems
S-8	SLO-1	Look Up Tables	Acceleration Sensor	Fuel Injection System – Requirements	Collision Avoidance System	On Board Diagnostics
3-0	SLO-2	Applications	Yaw Rate Sensor	Components and operation	Collision Avoidance System	Roof Control Module
S-9	SLO-1	Case Study I	Chassis Level Sensor	Types of Fuel Injection System	Case Study II	Case study III
3-9	SLO-2	Case Study I	Fuel Level Sensor	Types of Fuel Injection System	Case Study II	Case study III

Learning	1.	Tom Denton, Automotive Electricals / Electronics System and Components, 3rd ed., 2004
Resources	2.	BOSCH, Automotive Electrics, Automotive Electronics: Systems & Components, BOSCH, 4th ed., 2005.

- Jack Erjavec, A Systems Approach to Automotive Technology, Cengage Learning, 2009
 Ronald K.Jurgen, Automotive Electronics Reliability, Vol 2, SAE International, 2010

Learning Ass	sessment														
_	Dia a m²a		Continuous Learning Assessment (50% weightage)												
	Bloom's Level of Thinking	CLA -	1 (10%)	CLA –	2 (15%)	CLA –	3 (15%)	CLA – 4	l (10%)#	Filiai Examination	n (50% weightage)				
	Level of Thirking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice				
Level 1	Remember Understand	30 %	-	30 %	-	30 %	-	30 %	-	30%	-				
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-				
Level 3	Evaluate Create	30 %	-	30 %	-	30 %	-	30 %	-	30%	-				
	Total	10	0 %	100	0 %	10	0 %	10	0 %	10	0 %				

[#]CLA - 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. D. Karthikeyan, Controlsoft Engineering India Pvt Ltd, <u>karthikeyan.d@controlsoftengg.in</u>	1. Dr. J. Prakash, MIT, Chennai, <u>prakaiit@rediffmail.com</u>	1. Mr. Arockia Vijay Joseph, SRMIST
2. V. Venkateswaran, Instrumentation Consultant, wvenkat99@gmail.com	2. Dr. D. Nedumaran, Madras University, dnmaran@gmail.com	Mr. J. Sam Jebakumar SRMIST

Course	18ECE183T	Course	CAEETY INCTUIMENTED CYCTEM	Course	Е	Professional Elective	L	T	Р	С
Code	10EGE1031	Name	SAFETT INSTRUMENTED STSTEM	Category	L	Professional Elective	3	0	0	3

Pre-requisite Courses		Co-requisite Courses	Nil		Progressive Courses	Nil
Course Offering Department	Electronics and Communica	cation Engineeri	ng	Data Book / Codes/Standards	Nil	

Course Learning Rationale (CLR): The purpose of learning this course is to:		L	earnir	ng					Progr	ram L	.earni	ing O	utcon	nes (PLO)			
CLR-1: Know the standard and regulation of SIS design.		1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13 14	15
CLR-2: Know the Corrective and Preventive maintenance of SIS.		(u	(%)	(^					ţ	or so	ent
CLR-3: Know the requirement of field device and the control components.		(Bloom)	\sim	(%):				Research			Sustainability							s management
CLR-4: Know the failure diagnostic technique.		(B)	nc)	ient	ge		ent	ese			aina		Work		8	Catao	S D	mag
CLR-5: Acquire the knowledge on the software development model and Industrial application of SIS.		Thinking	Proficiency	Attainment	Knowledge	S	Development	Ä,	Usage	ø	Sust		<u>د</u>		Finance		2 # (2	ms me
CLR-6: Know the function of safety life cycle and hazard analysis.		ij	Prof	∖tta	호	Analysis	Nelc Nelc	Design,	l Ns	Culture	∞ర		Team	ion	∞ర	earning	disc Ze P	ctive
			pe I		ing	Ä	& De	Ğ,	Tool	Š	nen		∞	ig	Mgt.		8	Effe
Course Learning Outcomes (CLO): At the end of this course, learners will be able to:		Level of	Expected I	Expected	Engineering l	Problem	Design 8	Analysis,	Modern	Society	Environment	Ethics	Individual &	Communication	Project I	Life Long	continou PSO-2:	PSO-3:
CLO-1: Develop, operate and maintain the safety systems.		2,3	80	80	Н	-	Н	-	-	Ĥ	Н	H	-	-	-	Н	Н -	T -
CLO-2: Perform the corrective and preventive maintenance of SIS.		1,2	80	80	Н	-	-	Н	-	Н	-	-	-	-	-	Н	- H	-
CLO-3: Understand the knowledge of field devices and reliability.		1	80	80	-	-	-	-	-	Н	-	-	Н	Н	-	-	Н -	-
CLO-4: Evaluate the failure diagnostic technique.		3	80	80	-	Н	Н	-	-	-	-	-	-	-	-	-	- H	-
CLO-5: Verify the skills of software development model for safety related system.		3	80	80	-	-	Н	-	Н	-	-			-	-	Н		Н
LO-6: Gain knowledge on safety life cycle and function of protective layers.				80	Н	-	Н	-	-	Н	Н	Н	-	-	-	Н	Н -	-

Duratio	n (hour)	9	9	9	9	9
	SLO-1	Industry Guidelines	Introduction to Safety Instrumentation	Importance of field device	Introduction of failure diagnostic mode	Selection of Technology
S-1	SLO-2	Industry Standards and Regulations.	Hazards & risk	Impact of Field Devices on System Performance.	Equipment Failure mode	Relay systems-PLC based system
	SLO-1	Set of Standards.HSE – PES, AIChE – CCPS,	Process Hazards Analysis (PHA)	Percentage Split of System Failures	Fail –Safe, Fail-danger, Annunciation	Safety PLCs
S-2	SLO-2	IEC 61508, ANSI/ISA, OSHA (29 CFR 1910.119 - Process Safety Management of Highly Hazardous Chemicals)	Safety cycle	Issues relating to field devices. Wiring of Field Devices.	Reliability block diagram. Series system, Parallel systems, Fault trees, Fault tree symbols	Safety System Complexity
S-3	SLO-1		Shutdown/Interlock/Instrumented Systems (Safety Instrumented Systems – SIS).	Sensors	Comparison of Reliability block diagram and Fault tree	Communication with others system
	SLO-2	Design Lifecycle	Physical Protection	Switches, Transmitters	Fault tree AND gates ,fault tree OR gates	Software development models for safety related system
	SLO-1	Hazard & Risk Analysis- HAZOP analysis	Mitigation Layers	Sensor Diagnostics	Approximation technique	Rapid prototyping, V model
S-4	SLO-2	Allocation of Safety Functions to Protective Layers	Containment Systems	Smart Transmitters	Common mistakes	Water model, spiral model
S-5	SLO-1	Requirements	Scrubbers and Flares	Final Elements	Markov models	Implementation Procedure
	SLO-2	Develop Safety Specification	Fire and Gas (F&G) Systems	Valve Diagnostics	Markov solution technique	case study- Introduction
S-6	SLO-1	SIS Design & Engineering	Evacuation Procedures.	Smart Valve Positioners	Realistic safety instrumented system modeling	The Safety Lifecycle and Its Importance
3-0	SLO-2	Installation , Commissioning	Diversification	Redundancy	Event tree analysis	Case Description: Furnace/Fired Heater Safety Shutdown System
S-7	SLO-1	Validation	Corrective and Preventive maintenance	Voting Schemes and Redundancy	Failure mode and effect analysis	Safety Instrumented system in PLC

	SLO-2	Operations and Maintenance	Types of corrective and preventive maintenance	Design Requirements for Field Devices		Safety Instrumented system in oil and gas facilities
S-8	SLO-1	Modifications. Decommissioning.		Operator Interface requirement, Communication Interface requirement	Factory Acceptance Test	Nuclear plant safety discussion
	SLO-2	Process Hazard Analysis (PHA)	SIS Requirement for system behavior on detection of a fault	Final Element Design Requirements,	Spurious trip rate	Safety Instrumented system in DCS
S-9		Failure mode, Effects, and criticality analysis(FMECA), Probability of failure on demand(PFD)		Differences between using certified vs. proven-in-use devices	Risk Assessment	Installation, Commissioning and Prestartup Tests
	SLO-2	Examples of usage of standards on specific applications.	SIS Integration: Architectural Issues	Circuit measures to increase the reliability	safety integrity levels (SIL)	Operation and Maintenance Procedures

	1.	Paul Gruhn, Harry Cheddie, Safety Instrumented Systems: Design, Analysis and Justification, 2nd ed.,	3.	Roger L. Brauer, Safety and Health for Engineers, John Wiley Sons, 2006
Learning		International Society of Automation, 2005	4.	B.S. Dhillon, Maintainability, Maintenance and Reliability for Engineers, CRC Press, 2006
Resources	2.	William M.Goble, Harry Cheddie, Safety Instrumented Systems Verifications: Practical Probabilistic	5.	Swapan Basu, "Plant Hazard analysis and Safety Instrumentation systems" Academic Press,
		Calculations, ISA-2005		2016

Learning As	sessment											
	Bloom's		Continuous Learning Assessment (50% weightage)									
	Level of Thinking	CLA -	CLA – 1 (10%)		2 (15%)	CLA –	3 (15%)	CLA – 4	I (10%)#	FIIIai Examination	n (50% weightage)	
	Level of Thirtking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	
Level 1	Remember	30 %		30 %		30 %		30 %		30%		
Level I	Understand	30 %	-	30 %	-	30 %	-	30 %	-	30%	-	
Level 2	Apply	40 %		40 %		40 %		40 %		40%		
Level 2	Analyze	40 /0	-	40 /0	-	40 /0	-	40 /0	-	40 /0	-	
Level 3	Evaluate	30 %		30 %		30 %		30 %		30%		
Level 3	Create	30 %	-	30 %	-	30 %	-	30 %	-	30%	-	
	Total	10	0 %	10	100 %		0 %	10	0 %	100 %		

[#] CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. D. Karthikeyan, Controlsoft Engineering India Pvt Ltd, <u>karthikeyan.d@controlsoftengg.in</u>	1. Dr. J. Prakash, MIT, Chennai, prakaiit@rediffmail.com	1. Mrs. K. Vibha, SRMIST
2. V. Venkateswaran, Instrumentation Consultant, wvenkat99@gmail.com	2. Dr. D. Nedumaran, Madras University, dnmaran@gmail.com	2. Dr. G Joselin Retna Kumar, SRMIST

Course	18ECE280T	Course	INDLICTUAL INICTUIMENTATION	Course	_	Professional Floative	L	Т	Р	С
Code	10EGE2001	Name	INDUSTRIAL INSTRUMENTATION	Category		Professional Elective	3	0	0	3

Pre-requisite Nil	Co-requisite Courses	Nil		Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineer	ing	Data Book / Codes/Standards	Nil	

Course L	earning Rationale (CLR): The purpose of learning this course is to:	L	earni	ng					Progr	am L	earni	ng O	utcor	nes (l	PLO)				
CLR-1:	Acquire familiarity about various industrial instrumentation types, their parameters and different types of measurement techniques.	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Gain knowledge about pressure measurement techniques.							_			₹						for ms	ō.	ent
CLR-3:	Learn about the different techniques of measurement of flow.	(Bloom)	(%) /	t (%)				arch			<u>=</u>						. 01 (3	Je I
CLR-4:	Get exposed to the various techniques of measurement of level.		Proficiency	Attainment	dge		ent	ese			ustainability		Work		92		control	⊃ ×	anag
CLR-5:					Ne Ne	S	md.	œ,	Usage	Φ	Sust		E		Finance	ng	atic o	ے ج	Ĕ
CLR-6:	LR-6: Familiarize the measuring devices used in industrial applications.				Knowledge	Analysis	Development	esign,	ns	Culture	∞		Team	.io	∞ŏ	earning	ᆮᄆ	er Hen	₹
		f Thinking			ing	Ana	, De		T00	ನ %	Jent		∞ŏ	icat	Mgt.		Auto		Ě
Course L	earning Outcomes (CLO): At the end of this course, learners will be able to:	Level of	Expected	Expected	Engineering	Problem	Design &	Analysis,	Modern 7	Society 8	Environment	Ethics	Individual	Communication	Project N	Life Long	PSO 1: A	Control of	PSC-5. r skills
CLO-1:	Understand the need for measurement in industries and the basic measurement techniques.	3	80	75	Н	Н	-	Ĥ	Н	-	-	Н	L	-	Н	Н	М	Н	L
CLO-2:	Elucidate the construction & working of various industrial devices used to measure pressure.	3	80	70	Н	Н	Н	Н	Н	-	-	Н	L	-	Н	Н	Н	Н	L
CLO-3:	Summarize the different methods for flow measurement.	3	75	70	Н	Н	Н	Н	Н	-	-	Н	L	-	Н	Н	Н	Н	L
CLO-4:	O-4: Illustrate the different methods for the measurement of level.			75	Н	Н	Н	Н	Н	-	-	Н	L	-	Н	Н	Н	Н	Н
CLO-5:	: Analyze different techniques to measure temperature.			70	Н	Н	Н	Н	Н	-	-	Н	L	-	Н	Н	Н	Н	Н
CLO-6:	Analyze, formulate and select suitable sensor for the given industrial applications.			70	Н	Н	-	Н	Н	-	-	Н	L	-	Н	Н	Μ	Н	Н

	ration	Force, Acceleration and Speed Measurement	Pressure Measurement	Level Measurement	Flow Measurement	Temperature Measurement
(r	nour)	9	9	9	9	9
S-1	SLO-1	Introduction to industrial symbols and standards	Units of pressure and vacuum	Need for level Measurement	General concepts - Laminar flow, Reynolds's number	Definitions and standards
3-1	SLO-2	Classification of industry	Need for pressure measurement Visual level indicators		Effect of temperature and pressure on flow rate measurement	Primary and secondary fixed points
S-2	SLO-1	Definitions of Process variable	,	Purge method	Calibration of flow meters.	Calibration of thermometer
3-2	SLO-2	Unit conversions	Types- U tube, Inclined Tube and Well type Manometers	Buoyancy method	Head IVDE HOW Measurement -Principle	Different types of filled in system thermometer
S-3	SLO-1	Types of measurement required	TBOURGON TUDE Pressure Gauge Capsule	Resistance, Capacitance and inductive probes	Orifice , Venturi tube	Sources of errors in filled in systems and their compensation
	SLO-2	Detectors, probe analyzers, actuators	Diaphragm gauges, bellows and force balance type sensors	Ultrasonic type	Pitot Tubes, Flow nozzle	Bimetallic thermometers
S-4	SLO-1	Measurement of force	Electronic Pressure / DP transmitters- capacitive type	Laser type	Variable Area Flow meters-Principle	Review of RTD and Thermistors
3-4	SLO-2	Different types of load cells – Magneto- elastic load cell, Strain gauge load cell Piezo - resistive and resonating wire in		Optical fiber, Thermal type	Rotameters	Signal conditioning of industrial RTDs and their characteristics
S-5	SLO-1	Acceleration Measurement	Vacuum pressure Measurements- Mcleod Gauge	Radar, Radiation type	Electrical Type Flow meters-Principle	Three lead and four lead RTDs.

	SLO-2	Strain gauges, Piezoelectric	Pirani gauge	Solid level measurement	Electromagnetic type, Ultrasonic type	Thermocouples – Laws of thermocouple
S-6	SLO-1	Translational and rotational displacement using potentiometers		Boiler drum level measurement :- Differential pressure method	Positive displacement type	Fabrication of industrial thermocouples
3-0	SLO-2	Differential transformers	Knudsen gauge	Hydrastep method	Nutating disc, Reciprocating piston	Commercial circuits for cold junction compensation
S-7	SLO-1		Ionization gauge- cold cathode and hot cathode types	Miscellaneous Measurement,	Mass flow meters - Coriolis type	Pyrometers:Total radiation pyrometers
3-1	SLO-2	Vibrometer	I i nermai condiictivity dalide	Humidity – Dry and wet bulb psychrometers	Thermal, Impeller type	Selective radiation pyrometers
	SL0-1	Speed measurement – Revolution counter	Testing and calibration of pressure gauges	Resistive and capacitive type hygrometers	Weirs, Flumes	Optical pyrometer
S-8	SLO-2	D.C and A.C tachogenerators	Dead weight tester	Moisture measurement in solids- Conductivity sensor-Microwave and IR sensors.	Open channel flow measurement	Two colour radiation pyrometers
	SLO-1			Discussion of device types and models used in practical industrial applications	Discussion of device types and models used in practical industrial applications	Discussion of device types and models used in practical industrial applications
S-9	SLO-2	Discussion of device types and models used in practical industrial applications	Installation Requirements	Installation Requirements	Installation Requirements	Installation Requirements

Learning Resources

- 1. Liptak B.G., "Instrument Engineers Handbook (Measurement)", Chilton book Co., McGraw Hill, publishing Ltd., 19th Revised edition-2011. 2. A.K. Sawhney, "A course in Electrical and Electronic Measurements and instrumentation
- Dhanpatrai co., 19th Revised edition-2011. Reprint 2014
 Patranabis D, "Principles of industrial Instrumentation", Tata McGraw Hill, 3rd Edition, New Delhi, Reprint 2010
- Tony R. Kuphaldt, "Lessons In Industrial Instrumentation ", Version 2.02, 2014 Singh S. K., "Industrial Instrumentation & Control", Tata McGraw Hill, 2ndEdition, Reprint 2007 NPTEL video lectures on "Industrial Instrumentation" by Prof. AlokBarua, IIT Kharagpur

Learning Ass	sessment											
	Bloom's		Continuous Learning Assessment (50% weightage)									
	Level of Thinking	CLA –	CLA – 1 (10%)		2 (15%)	CLA –	3 (15%)	CLA – 4	(10%)#	FIIIai Examination	n (50% weightage)	
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	
Laval 1	Remember	30 %		30 %		30 %		30 %		30%		
Level 1	Understand	30 %	-	30 %	-	30 %	-	30 %	-	30%	-	
Level 2	Apply	40 %		40 %		40 %		40 %		40%		
Level 2	Analyze	40 /0	-	40 /0	-	40 /0	-	40 /0	-	40 /0	-	
Level 3	Evaluate	30 %		30 %		30 %		30 %		30%		
Level 3	Create	30 %	-	30 %	-	30 %	-	30 %	-	30%	-	
	Total 100 % 100 %		0 %	10	0 %	10	0 %	100 %				

[#] CLA - 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. D. Karthikeyan, Controlsoft Engineering India Pvt Ltd, karthikeyan.d@controlsoftengg.in	1. Dr. J. Prakash, MIT, Chennai, prakaiit@rediffmail.com	1. Ms. N. Deepa, SRMIST
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. D. Nedumaran, Madras University, dnmaran@gmail.com	2. Dr. A. Vimala Juliet, SRMIST

Course	195052911	Course	PROCESS DYNAMICS AND CONTROL	Course	_	Professional Floative	L	Т	Р	С
Code	18ECE281J	Name	PROCESS DYNAMICS AND CONTROL	Category		Professional Elective	2	0	2	3

Pre-requisite Nil	Co-requisite Courses	Vil	Progressiv Courses	Nil
Course Offering Department	Electronics and Communication Engineering	ng Data Book	/ Codes/Standards Nil	

Course Learning Rationale (CLR): The purpose of learning this course is to:	L	earni	ng	Program Learning Outcomes (PLO)														
CLR-1: Impart fundamental knowledge on the dynamics and mathematical modeling of various processes	1	2	3	-	1	2	3	4	5	6	7	8	9	10	11	12	13 14	15
CLR-2: Introduce the effect of various control actions and the tuning techniques of controllers.	(L	(9	<u></u>								≥					ţ	or for	ent
CLR-3: Impart knowledge on final control elements	(Bloom)	(%) /	t (%)					먑			pilit							Jem
CLR-4: Get exposed different types of advanced control schemes	<u>@</u>	ncy	en		dge		ent	Research			ain		Work		8	l cutar	& D	nanagement
CLR-5: Explore the computer as controller in digital control system.	Thinking	Proficie	Attainment		wle	S	Development	Æ,	ool Usage	Ф	Sustainability		E		Finance	g g		Si Si
CLR-6: Identify the different type of control schemes used in process industries and paraphrase their importance	ij	Jo	\tta		ᇫ	Analysis	velc	Design,	ns	Culture	∞ర		Team	ion	∞ŏ	earning	Biging.	ctive
	Ē	Ď.	b B		ring	Ans	& De	å	Tool	ತ ಶ	neu			ical	Mgt.		ageili.	Te Te
Course Learning Outcomes (CLO): At the end of this course, learners will be able to:	Level of	Expected	Expected		Engineering Knowledge	Problem	Design 8	Analysis,	Modern .	Society &	Environment	Ethics	Individual &	Communication	Project N	Life Long	continuo PSO-2: U	control o PSO-3: F skills
CLO-1: Analyze and mathematically model the process systems	3	80	75		Н	Н	Μ	Н	Н	-	-	Н	Н	-	Н	Н	M L	L
CLO-2: Select and optimize the tuning of a controller	3	80	70		Н	Н	Н	Н	Н		-	Н	Н	-	Н	Н	H L	L
CLO-3: Demonstrate the working and application of different type of actuators and control valves	3	75	70		Н	Н	Н	Н	Н	-	-	Н	Н	-	Н	Н	н м	L
CLO-4: Understand and analyze the various advanced control schemes	3	80	75		Н	Н	Н	Н	Н		-	Н	Н	-	Н	Н	Н М	Н
CLO-5: Design suitable digital controllers for the process	3	80	70		Н	Н	Н	М	Н	-	-	Н	Н	-	Н	Н	Н Н	Н
CLO-6: Recommend the right choice of control schemes for the application	3	80	70		Н	Н	Μ	Н	Н	-	-	Н	Н	-	Н	Н	м н	Н

	ration	Process Dynamics	Control Action and Tuning of controllers	Final Control Elements	Advanced Control Schemes	Digital Control System
(h	our)	12	12	12	12	12
S-1	SLO-1	Need for process control	Basic control actions	I/P converter	Feedback and Feed-forward control	Introduction to state space ,Basic building blocks of computer control system
0-1	SLO-2	The process control loop	Characteristics of ON- OFF controllers	P/I converter	Application of feed forward control in various processing units	Data loggers
S-2	SLO-1	Need for process modeling	Characteristics of Single speed floating controllers	Pneumatic actuators	Split-range control	Data acquisition systems
3-2	SLO-2	Servo and Regulatory operation	P+I, P+D and P+I+D control modes	Electric actuators	Application of cascade control in various processing units	Supervisory control , SCADA, Direct digital control
S 3-4	SLO-1 SLO-2	Lab1: Identify the components of the process control loop.	Lab 4: Design the on-off, P,PI and PID controller for the Pressure Process	Lab 7: Determine the characteristics of I/P and P/I converter	Lab10: Tune the PID Controller for mathematically described process using ZN method	Lab13:Determine the state model for the mechanical system using MATLAB
S-5	SLO-1	Continuous and batch processes	Practical forms of PID controller	Control Valves	Inferential control	Review of z transforms
3-3	SLO-2	Self-regulation, Degrees of freedom	Auto/manual transfer, Reset windup	Characteristic of Control Valves:- Inherent characteristics	Ratio control	Digital PID , Position and velocity form
S-6	SLO-1	Mathematical model of level, flow processes	Evaluation criteria- Quarter Decay Ratio, IAE, ISE and ITAE	Installed characteristics	Cascade control.	Implementation of digital controllers
3-0	SLO-2	Interacting and non interacting systems	Selection of Time Integral performance Criteria	Modeling of control valves and types	Fuzzy controllers	Design of Deadbeat controller, Dahlin's controller
S 7-8	SLO-1 SLO-2	Lab 2 : Determine the characteristics of interacting system	Lab 5: Design the on-off control, P,Pl and PID controller for the flow Process	Lab 8: Determine the characteristics of Pneumatically Actuated Control Valve	Lab11: Tune the PID Controller for mathematically described process using ZN open loop method	Lab14:Design the Deadbeat algorithm for the given system using MATLAB

	SLO-1	Laws and assumptions governing gas process	Tuning – Process reaction curve method	Valve Positioner and its importance	Adantiva controllars	Multi-loop multivariable control , Introduction
S-9	SLU-Z	Mathematical models of pressure processes	Z-N open loop tuning techniques	Control valve sizing	Model predictive control	Interaction between control loops
S-10	SLO-1	Laws and assumptions governing thermal process	Continuous cycling method	Cavitation and flashing	Smith predictor control scheme	The Relative Gain Array (RGA)
0-10	SLO-2	Mathematical models of thermal processes	Damped oscillation method	Selection criteria	Internal model control (IMC) ,P& I diagram	Decoupling of control loops
s	SLO-1	Lab3: Determine the characteristics of non			Lab12: Compare the responses of simple	Case study: Design of computerized multi
11-12		interacting system	controller for the level Process	r neumatically Actuated Control valve (with		loop controller

Learning
Learning Resources

- 1. Seborg ,D.E., Mellichamp, D.P., Edgar, T.F., and Doyle,F.J., III, "Process Dynamics and Control", John Wiley and Sons, 4thEdition 2016
- 2. Stephanopoulos. G" Chemical Process Control An Introduction to Theory and Practice", Prentice Hall of India,2nd Edition,2015
- 3. Gopal, M., "Digital Control and State Variable Methods", Tata McGraw Hill, 2003

- D.R. Coughanour, 'Process Systems analysis and Control', McGraw-Hill, 3rd Edition, 2013
 Bela.G.Liptak., "Process Control and Optimization", Instrument Engineers' Handbook., volume 2,CRC press and ISA, 2005
- Curtis D. Johnson Process Control Instrumentation Technology, 8th Edition, Pearson, 2006
 NPTEL video lectures on "Chemical Process Control" by Prof. SujitJogwar, IITM.
 P.W. Murrill., "Fundamentals of Process Control Theory", 3rd Edition-ISA Books

Learning Ass	sessment												
	Bloom's			Conti	nuous Learning Ass	essment (50% weig	htage)			Final Examination	n (E00/ weightege)		
	Level of Thinking	CLA –	1 (10%)	CLA – 2 (15%)		CLA –	3 (15%)	CLA – 4	(10%)#	Final Examination (50% weightage)			
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice		
Level 1	Remember Understand	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%		
Lavalo	Apply	200/	200/	200/	200/	200/	200/	200/	200/	200/	200/		
Level 2	Analyze	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%		
Laval 2	Evaluate	100/	400/	450/	450/	450/	450/	450/	450/	450/	150/		
Level 3	Create	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%		
	Total	10	0 %	10	0 %	10	0 %	100	%		=		

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2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. D. Nedumaran, Madras University, dnmaran@gmail.com	2. Mrs. Indirani, SRMIST

Course	18ECE282T	Course	MODERN CONTROL SYSTEM	Course	E	Professional Elective	L	Τ	Р	С
Code	TOLOLZOZI	Name	MODERN CONTROL SYSTEM	Category	1	i iolessional Elective	3	0	0	3

Pre-requisite Courses	18E	CS201T	Co-requisite Courses	Nil		Progressive Courses
Course Offering I	Department	Electronics and Commu	ınication Enginee	ring	Data Book / Codes/Standards	Nil

Course Le	earning Rationale (CLR): The purpose of learning this course is to:	L	.earni	ng					Prog	ram L	earni	ing O	utcor	nes (l	PLO)				
CLR-1:	Know and design various conventional compensators.	1	2	3	3 1 2 3 4 5 6 7 8 9 10 11 12 1					13 ′	14	15							
CLR-2:	LR-2: Know and develop mathematical modeling using state space technique.			~							>-						for for	5	ent
CLR-3:				t (%)				arch			Sustainability						± a .,	3	management
CLR-4:	LR-4: Know the importance of structural properties and to analyze the stability of the system.			Attainment	dge		ent	Se			aju		Work		8		control	a ر	anaç
CLR-5:				. <u>⊑</u>	we a	S	l g	, Re	Usage	Φ	Sust		m V		Finance	gu .	atic o iscret	2 g	E
CLR-6:	CLR-5: Study the state space control methodologies for various systems. CLR-6: Know and design modern control techniques which are linear.				Ā	Analysis	Development	Design,	l ns	Culture	∞ర		Team	ion	∞ర	7	E 70 9	n 4 :	ctive
							8	ical	Mgt.	J Le	Autor Lus&	f SV	He I						
Course Le	earning Outcomes (CLO): At the end of this course, learners will be able to:	Level of	Expected I	Expected	Engineering Knowledge	Problem	Design 8	Analysis,	Modern	Society &	Environment	Ethics	Individual &	Communication	Project N	Lo J	PSO 1: / continuo PSO 2: I	routrol o	PSO-3: I skills
CLO-1:	Design cascade compensators in time domain and design PID controllers in time domain.	3	80	75	Н	Н	Н	-	L	-	-	Н	-	-	-	Н	Н	-	Н
CLO-2:	Understand and develop state space model for different systems	3	80	70	Н	L	Н	-	Н	-	-	Η	-	-	-	-	М	-	Н
CLO-3:	Analyze the controllability and observability of a system and to design controllers and observers.	3	75	70	Н	Н	-	Н	Н		-	Н		-	-	-	М	-	Н
CLO-4:	4: Implement procedure to find the structural properties of any linear system			75	Н	Н		Н	Н	-	-	Н	-		-	-	М	-	Н
CLO-5:	Understand the procedure of applying the control methodology on various linear systems			70	Н	Н	Н	Н	Н	-	-	Н	-	-	-	Н	М	-	Н
CLO-6:	Design and apply linear based modeling and modern control methods for different linear systems.	3	80	70	Н	Н	Н	-	L	1	-	-	-	1	-	Н	Н	-	Н

	ration nour)	Linear Control Design	State Space Analysis	Controllability And Observability	Controller Design For Linear System	Applications
,	,	9	9	9	9	9
	SLO-1	Design specifications	Concept of State variables	Concept of Stability	Pole placement using feedback	State space Modeling of Inverted
S-1	SLO-2	Compensator configuration (series and feedback)-	LL oncent of State space model	Computation of Stability of State space model	Eigen value placement theorem	Pendulum
		Design cascade compensators - lag by using time domain	Relationship between transfer function and State space model	Concept of Controllability	Selection of desired poles	State space Modeling of Ball and Beam
S-2	SLO-2	Design feedback compensators - lag by using time domain	TCODUDITIONS TIME SYSTEMS HSIDO DOVSICAL	Computation of Controllability of State space model	Eigen structure assignment	system
S-3	SLO-1	Design cascade compensators - lead by using time domain	State space representation of linear continuous time systems using phase variables	Concept of Observability	State controller design exercise	State space Modeling of Translational
3-3	SLO-2	Design feedback compensators - lead by using time domain	I CONTINUOUS TIME SYSTEMS USING CANONICAL	Computation of Observability of State space model	State controller design exercise	Mechanical Systems
S-4	SLO-1	Compensator design exercises	Conversion of transfer function to various	Computation of structural properties using	State controller design exercise	State space Modeling of Rotational
3-4	SLO-2	Compensator design exercises	state space representations	Controllability & Observability	State controller design exercise	Mechanical Systems

9 E	3-5 SLO-1	Design cascade compensators – lead-lag by using time domain	Diagonalization	Computation of structural properties using	State controller decign eversion	Modeling exercises for Translational and		
3-3		1	State space representation of discrete time systems	eigen decomposition			igen decomposition State Controller design exercise Rotation	
S-6	SLO-1		Solution of state equations – from	, ,	acement by state Optimal Control – Linear Quadratic Regulation (LQR) State space Modeling of			
	SLO-2	Effect of PID on linear systems	differential equations	Concept of State Observers	Infinite Horizon Regulator			
	SLO-1	Design of PD controller using time domain	Solution of state equations – from Transfer	Control System Design Via Pole	Receding Horizon Regulator			
S-7	SLO-2	PD Controller design exercises		Placement by state feedback	Receding Horizon Regulator - Design Parameters	Modeling exercises for Electrical Systems		
	SLO-1	Design of PI controller using time domain	Concepts of state transition matrix.		Controller Design with Reference Input	State space Modeling of Field controlled		
S-8	SLO-2	PI Controller design exercises	Computation of state transition matrix	Effect of state feedback	Trocking/ Conta Control using State	DC Motor		
6.0	SLO-1	Design of PID controller using time domain	Computation of state transition matrix	State feedback Controller design exercises	State controller with reference input design	State space Modeling of Armature		
3-9	S-9 SLO-2	PID Controller design exercises	Computation of state transition matrix	State reedback Controller design exercises	exercise	controlled DC Motor		

Learning
Resources

- Katsuhiko Ogata, "Modern Control Engineering"-fifth edition, Prentice Hall of India Private Ltd, New Delhi,
- Kirk D.E, "Optimal control theory-an introduction", Dover Publications, 2004.
 Richard .C, Dorf and Robert.H.Bishop, "Modern Control System Engineering", Pearson Education (US), United States, 2010.

- Gopal. M, "Modern Control System theory", New age international(P) ltd, 2012.
 Nagarath, I.J. and Gopal, M., "Control Systems Engineering", New Age InternationalPublishers, 2010.
 NPTEL Video Lecture Notes on "Advanced Linear Continuous Control Systems "by Prof. Yogesh Vijay Hote, IIT Roorkee. https://nptel.ac.in/courses/108107115/

Learning Assess	sment											
	Bloom's			Final Evamination	(E00/ weightegs)							
	Level of Thinking	CLA –	1 (10%)	10%) CLA – 2 (15%)		CLA –	3 (15%)	CLA – 4 (10%)#		Final Examination (50% weightage		
	Level of Thirtking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	
Level 1	Remember Understand	30 %	-	30 %	-	30 %	-	30 %	-	30%	-	
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-	
Level 3	Evaluate Create	30 %	-	30 %	-	30 %	-	30 %	-	30%	-	
	Total	100	0 %	100	0 %	100	0 %	100) %	10	0 %	

[#] CLA - 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

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Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. D. Karthikeyan, Controlsoft Engineering India Pvt Ltd, <u>karthikeyan.d@controlsoftengg.in</u>	1. Dr. J. Prakash, MIT, Chennai, prakaiit@rediffmail.com	1. Mr. Arockia Vijay Joseph, SRMIST
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. D. Nedumaran, Madras University, dnmaran@gmail.com	2. Mr. P. Jekan, SRMIST

Course	18ECE2831 Course	DDOCDAMMADI E I OCIC CONTDOLLED	PROGRAMMABLE LOGIC CONTROLLER Course Category E Professional Elective	Professional Floative	L	Т	Р	С
Code	Name		Category	Fiolessional Elective	2	0	2	3

Pre-requisite Courses	Nil	Co-requisite Courses		Progressive Courses Nil
Course Offering	Department	Electronics and Communication Engineering	ng Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR): The purpose of learning this course is to:	L	earni	ng					Progr	ram L	_earni	ng O	utcor	nes (PLO)			
CLR-1: Study the hardware components of Programmable Logic Controller	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13 1	4 15
CLR-2: Understand the need of programming languages for PLC	~	(0)							у						for for	ent
CLR-3: Explore the ladder logic program for control application	(Bloom)	(%)	(%):				arch			ustainability						# H (c)	em
CLR-4: Identify applications of timers and counters in process automation	<u>B</u>	0	ent	dge		eut	Se			aina		Work		90		control	nag
CLR-5: Locate the malfunctions and troubleshooting various types of errors in Programmable Logic Controller	Thinking	Proficiency	Attainment	wle	တ	Development	, Re	Usage	ω	Sust				Finance	ning	atic o iscreti PLC	SE SE
CLR-6: Provide the knowledge of Commissioning, Maintenance and their importance in industry.	ž	of Jo	∖tta	Knc	Analysis	velc	esign,	US	Culture	∞ర		Team	io	∞ŏ	earni	E P B	sten
				ing	Ans	& De		Lool	ر ال	nent		∞ŏ	icat	Mgt.		Auto Jus& Utiliz	f.svs
Course Learning Outcomes (CLO): At the end of this course, learners will be able to:	Level of	Expected	Expected	Engineering Knowledge	Problem	Design 8	Analysis,	Modern -	Society &	Environn	Ethics	Individual	Communication	Project N	Life Long	PSO 1: A continuo PSO-2: L	control or PSO-3: E skills
CLO-1: Select right I/O modules in PLC for process control	3	80	75	Н	L	-	-	-	-	-	-	L	-	-	Н	H F	I Н
CLO-2: Develop ladder logic program for control application	3	80	70	Н	Н	Н	Н	Н	-	-	Н	Н	М	-	Н	H F	I Н
CLO-3: Use timers and counters in process automation	3	75	70	Н	Н	Н	Н	Н	-	-	Н	Н	М		Н	H F	Н
CLO-4: Interpret data compare instruction in PLC program	3	80	75	Н	Н	Н	Н	Н	-	-	Н	Н	М	-	Н	H F	I Н
CLO-5: Troubleshoot the input and output malfunctions in PLC	3	80	70	Н	Н	-	Н	Н	-	-	-	Н	Н		Н	M F	Н
CLO-6: Select a right PLC for the given application	3	80	70	Н	Н	-	-	-	-	-	Н	Н	-	М	М	H F	Н Н

	ration	PLC Hardware Components	PLC Programming and Wiring	Timers and Counters	Data manipulation and Math instructions	Troubleshooting
(r	nour)	12	12	12	12	12
S-1	SLO-1	Evolution of Programmable logic controllers	PLC programming languages-Ladder Logic	Timer Instructions	Data manipulation	Electrical Noise
0-1	SLO-2	Architecture of a PLC	Function Block Diagram, Instruction List	On-Delay timer instruction	Data transfer operations	Leaky Inputs and Outputs
S-2	SLO-1	Principles of Operation	Instruction Addressing	Off-delay timer instruction	Data compare instructions	Grounding
3-2	SLO-2	PLCs versus Computers	Branch Instructions	Retentive Timer	Data manipulation programs	Voltage Variations and Surges
S 3-4	SLO-1 SLO-2	Lab1: PLC Wiring	Lab 4: Traffic light control system	Lab 7: HMI Programming	Lab10: Lift control	Lab13: Electro pneumatic direction control
S-5	SLO-1	PLC size and application	Electromagnetic Control Relays	Cascading Timers	Numerical Data I/O Interfaces	Program Editing and Commissioning
3-3	SLO-2	Discrete I/O modules	Contactors	Up-Counter	Closed-Loop Control	Preventive Maintenance
S-6	SLO-1	Sinking and sourcing	Manually Operated Switches	One-Shot Instruction	Math Instructions	Troubleshooting
3-0	SLO-2	Analog I/O modules	Mechanically Operated Switches	Down-Counter	Addition Instruction	Processor Module
S 7-8	SLO-1 SLO-2	Lab 2 :Water level control system	Lab 5: Sequential operation of motor	Lab 8: DC motor speed control system	Lab11: Car parking system	Lab14: Stamping machine control

	SLO-1	Special I/O modules	Proximity Sensor, Magnetic Reed Switch	Cascading Counters	Subtraction Instruction	Input Malfunctions	
S-9	SLO-2	I/O Specifications	Light Sensors, Velocity and Position Sensors	Combining Counter and Timer Functions	Multiplication Instruction	Output Malfunctions	
S-10	SLO-1	Human Machine Interfaces (HMIs)	Output Control Devices, Seal-In Circuits, Electrical Interlocking Circuits	High-Speed Counters	Division Instruction	Comparative	
3-10		Alarms, Graphics Library	Converting Relay Schematics into PLC Ladder Programs	Problems	Other Word-Level Math Instructions	study of Industrial PLCs.	
S	SLO-1	Lab 3. Material bandling aveters	Lab C. Dattle fillian anatom	I ab O. Tamanayatawa aa mtuul aa atama	Lab 42: Flam a antival ameters	Lab15: Servo controller	
11-12	SLO-2	Lab3: Material handling system	Lab 6: Bottle filling system	Lab 9: Temperature control system	Lab12: Flow control system	programming	

Learning Resources	 Frank D. Petruzella, "Programmable Logic Controller", Tata McGraw Hill 5th Edition, 2017. Bolton. W, "Programmable Logic Controllers", 6th Edition, Elsevier Newnes, 2016. John W. Webb, Ronald A. Reis, "Programmable Logic Controllers", Principles and Applications, Prentice Hall, 5th Edition, 2011 	 Gary Dunning, "Programmable Logic Controllers", Cengage Learning, 3rdEdition, 2009. John R. Hackworth, "Programmable logic controllers Programming Methods and Applications", Pearson, 1stEdition, 2006 NPTEL Video Lecture Notes on "Industrial Automation and Control "by Prof. S. Mukhapadhyay, IIT Kharagpur
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Learning Ass	sessment											
	Bloom's			Final Evamination	(E00/ weightegs)							
	Level of Thinking	CLA –	CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		(10%)#	Final Examination (50% weightage)		
	Level of Thirtking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	
Level 1	Remember Understand	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%	
Level 2	Apply Analyze	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%	
Level 3	Evaluate Create	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%	
	Total	10	0 %	100) %	10	0 %	100) %		-	

[#] CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. D. Karthikeyan, Controlsoft Engineering India Pvt Ltd, <u>karthikeyan.d@controlsoftengg.in</u>	1. Dr. J. Prakash, MIT, Chennai, prakaiit@rediffmail.com	1. Mr. J. Sam Jebakumar, SRMIST
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. D. Nedumaran, Madras University, dnmaran@gmail.com	2. Dr. G. Joselin Retna Kumar, SRMIST

Course	 Course		Course	_		L	Τ	Р	С
Code	Name	GRAPHICAL SYSTEM DESIGN IN VIRTUAL INSTRUMENTATION	Category	Е	Professional Elective	2	0	2	3

Pre-requisite Courses		Nil Co-requisite Courses	Nil	Progressive Courses	Nil	
Course Offering I	Department	Electronics and Communication Engineer	ering Data Book / Codes/Standards		Nil	

Course Learning Rationale (CLR): The purpose of learning this course is to:	L	earni	ng					Prog	ram L	.earn	ing O	utco	nes (PLO)			
CLR-1: Study the concepts of Virtual instrumentation and to learn the programming concepts in VI.	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13 1	14 15
CLR-2: Study about the various measurement systems and their data acquisition methods in real time.	(-	())							у						for ms for	5 ant
CLR-3: Study about the various Instrument Interfacing concepts.	(Bloom)	(%)	(%):				Research			Sustainability						₩ H //	anagement
CLR-4: Explore various control techniques using VI software	<u>a</u>	5	ent	ge		eut	Sec			aine		Work		8		ontrol e svst	ag s
CLR-5: Explore various remote accessing techniques	hinking	Proficiency	Attainment	Me Me	s	elopment	~ ~	Usage	Φ	nst		S E		Finance		in the contract of the contrac	E E
CLR-6: Get exposed with various analysis tools for Process control applications.				Knowledge	alysis	Ne le	Design,	Usi	ulture	∞		Team	.u	× ×	arning	mat disc	sten Stive
				E I	Ana	Dev		00	& Cu	ent			icat	Mgt.	ω I	uto Is&	f sw
Course Learning Outcomes (CLO): At the end of this course, learners will be able to:	Level of	Expected	Expected	Engineering	Problem	Design &	Analysis,	Modern 7	Society &	Environment	Ethics	Individual &	Communication	Project №	Life Long L	PSO 1: A	control or PSO-3: E
CLO-1: Identify the purpose and need of virtual instrumentation in process control Industries	1,2	80	70	Ч	-	-	-				-	Н	-	-	-	Н	
CLO-2: Measure the parameters using various data acquisition methods.	2,3	85	75	4	Н	-	-	-		-	Н	Н	-	Н	Н	Н	
CLO-3: Implement the available interfacing instruments	2,3	75	70	Ч	Н	Н	Н	Н	-			Н	-	Н	Н	Н	Н -
CLO-4: Implement various control techniques using VI software	2,3	85	80	Ч	Н	Н	Н	Н	1	-	Н	Н	-	Н	Н	Н	Н Н
CLO-5: Apply remote accessing Techniques	2,3	85	75	Ч	Н	Н	Н	Н	-			Н	Н	Н	Н	Н	- H
Develop a system for an engineering application.		80	70	4	Н	Н	Н	Н	-	-	Н	Н	Н	Н	Н	Н	Н Н

Duratio	n (hour)	Programming Concepts in LabVIEW	Measuring Concepts in Virtual Instrumentation	Controlling Concepts in Virtual Instrumentation	Final Control Elements and its implementation	Signal Processing and Applications
	(,	12	12	12	12	12
	SLO-1	Historical perspective, Need of VI, Advantages of VI, Virtual Instruments versus Traditional Instruments	Components of Measuring System, Origin of signals	Introduction to Non continuous controllers in LabVIEW	Final Control Operation	PC based digital storage oscilloscope
S-1 SLO-2		Review of software in Virtual Instrumentation ,Software environment Architecture of VI, Introduction to the block diagram and Front panel Pallets	Transducer, Sensors, Differences between chemical sensors, physical sensors, Biosensors. Selection criteria	Introduction to continuous controllers in LabVIEW	Fundamentals of Mechatronic Actuators	Sensor Technology
	SLO-1	Creating and saving a VI, Front Panel Tool Bar, Block diagram Tool Bar, Palettes	General Conditioning Functions, A/D Control ,D/A Control in VI platform	Design of ON/OFF controller	Position-Controlled Actuators	Oscillators, counters
S-2	SLO-2	Creating sub VI, Creating an ICON, Building a connector pane, Displaying VI'S Placing and Saving Sub VI'S on block diagram Example of full adder circuit using half adder circuit	Introduction to MyRIO ,Applications of MyRIO	P,PI,PID controllers for a mathematically described processes using VI software.	open-loop and closed-loop actuator position control in a hands-on application	Signal and image processing Techniques
	SLO-1	Lab 1: Verification of Arithmetic	Lab 4 :Design a VI to measure angle	Lab 7: To apply on-off controller using	Lah 10: To apply Position Controlled	
S-3,4	SLO-2	Operations & Verification of Half Adder	with my RIO using Y-axis onboard accelerometer	QNET HVAC in virtual instrumentation platform	actuators	Lab 13: To Design of DSO
9 -5	SLO-1	Loops-For Loop,	Introduction to PC Buses	Modeling of level process	Manipulator Importance, Operation of Manipulators	Spectrum Analyzer
S-5 SLO-2	While Loop	Local Buses-ISA, PCI,	Basic control of level process in LabVIEW	Types of Manipulators Selection Criteria,	Waveform Generator	

	SLO-1	Arrays	RS232, RS422	Modeling of Reactor Processes	Controlling techniques on Manipulators	Data visualization from multiple locations
S-6	SLO-2	Clusters, plotting data	RS485	Basic control of Reactor process in LabVIEW	Controlling techniques on Manipulators	Distributed monitoring and control
	SLO-1	Lab O.D. www. to find Addition of First	Lab 5:Ta familiary and October 1 of	Lab 0:0antinana Oantralatana	Lab 44 Ta annia BID ta Cantual	Lab 44 Deal time and the second second
S-7,8		Lab 2:Program to find Addition of First n natural numbers using for loop	Lab 5:To implement Speed Control of DC Motor (QNET)	process using LabVIEW	Lab 11:To apply PID to Control Manipulators	Lab 14:Real time spectrum analysis using LabVIEW
S-9	SLO-1	Charts, Graphs, Formula nodes,	Interface Buses-USB,PXI	Case studies on development of HMI in VI	Remote access using LabVIEW	Vision and Motion Control
3-9	SLO-2	Case and Sequence Structures	VXI,	Case studies on development of HMI in VI	Different types of Protocols	Examples on Integrating Measurement with vision and motion
S-10	SLO-1	Acquiring Data Using Hardware	SCXI	•	Case study on TCP/IP Protocol application	NI Motion control
3-10	SLO-2	DAQ Devices	I DE META	Case studies on development of SCADA in VI	Case studies on web publishing tool	Speed control system
S-11,12		Lab 3:Design a Voltmeter by using AO to generate a signal and AI to acquire		Lab 9:Controlling of Rotary Inverted	Lab 12:Online process control using LabVIEW using TCP/IP and web	Lab 15 :Minor Project
3-11,12		the signal using DAQ	Rotary Inverted Pendulum	Pendulum	publishing	Lab 13 .Willion Project

Г		1. Nadovich, C., "Synthetic Instruments Concepts and Applications", Elsevier, 2005.
		2. Bitter, R., Mohiuddin, T. and Nawrocki, M., "Labview Advanced Programming Techniques",
١,	carning	CRC Press, 2nd Edition, 2007.
	₋earning Resources	3. Gupta, S. and Gupta, J. P., "PC Interfacing for Data Acquisition and Process Control", 2nd
ľ	resources	Edition, Instrument Society of America, 1994
		4. Liptak,"Instrument Engineers Handbook Process Measurement and Analysis", Elsevier,
		2005

- Jamal, R. and Picklik, H., "Labview Applications and Solutions", National Instruments
- Johnson, G., "Labview Graphical programming", McGraw-Hill, Newyork, 1997.
 Wells, L.K. and Travis, J., "Labview for Everyone", Prentice Hall, NewJersey, 1997.
 Buchanan, W., "Computer Busses", CRC Press, 2000.

Learning Asse	essment										
	Bloom'sLevel of			Continu	uous Learning Ass	essment (50% wei	ghtage)			Final Evamination	(E00/ weightege)
	Thinking	CLA –	1 (10%)	CLA –	2 (15%)	CLA –	3 (15%)	CLA –	4 (10%)#	Filial Examination	n (50% weightage)
	illinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand	20 /0	2070	1370	1370	1370	1370	1370	1370	1070	1370
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
Level 2	Analyze	20 /0	2070	2070	2070	2070	2070	2070	2070	2070	2070
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
Level 3	Create	10%	10%	13%	13%	13%	13%	1370	13%	13%	1370
	Total	100	0 %	100) %	100) %	10	0 %	10	0 %

[#] CLA - 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

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2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. D. Nedumaran, Madras University, dnmaran@gmail.com	

Course		Course		Course		L	T	Р	С
Code	18ECE380T	Name	INSTRUMENTATION AND CONTROL IN PROCESS INDUSTRIES	Category	Professional Elective	3	0	0	3

Pre-requisite Courses	Nil		Nil		Progressive Courses Nil
Course Offering	Department	Electronics and Communication Engineer	ring	Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR): The purpose of learning this course is to:		Lea	arnin	g					Prog	ram L	_earn	ing O	utco	mes (PLO)			
CLR-1: Learn various methods involved in the petroleum industries.			2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14 1
LR-2: Import the knowledge of control and measurement used in iron and steel industries.											,						for	to to
CLR-3: Study the various instruments and the role of instrumentation in paper industries.		_	(%)	(%)				arch			Sustainability						~ ნ.	C & DCS for
CLR-4: Learn the measurement and control in thermal industries.					dge		ent	Research			aina		Work		8		control	א ו
CLR-5: Study the industry standards and safety consciousness in process industries.					<u>ĕ</u>	S	Development	, Ré	ool Usage	a)	Sust		×		Finance	g	ice e	ع ۾ ٿ
CLR-6: Import the knowledge of chemical process hazards in industries.	2.	I hinking	Proficiency	Attainment	2	Analysis	velc	Design,	Us	ulture	∞ర		Team	.u	× E	arni	mat disc	ter terr
		=	효	b b	E I	Ans	Ď	De	00	& Cl	hent			g	Mgt.	J Le	왕(JE SV
Course Learning Outcomes (CLO): At the end of this course, learners will be able to:		Level of	Expected	Expected	Engineering Knowledge	Problem	Design &	Analysis,	Modern ⁷	Society &	Environment	Ethics	Individual &	Communication	Project N	Life Long L	PSO 1: A continuo	PSU-Z: L
CLO-1: Understand the basics of petrochemical industries.	3		80	75	Н	-	-	-	-	-	-	-	Н	-	-	Н	Н	-
CLO-2: Apply knowledge in working of various instruments that are used in iron and steel industries.				70	Н	Н	-	-	-	-	-	Н	Н	-	-	Н	Н	- 1
CLO-3: Acquire the knowledge of analyzers and measurement of density, level in paper industries.	3	3	75	70	Н	Н	М	-	-	-	-	Н	Н	-	-	Н	Н	Н
CLO-4: Understand the operation of boiler in thermal industries.	3	3	80	75	Н	Н	Μ	Н	-	-	-	Н	Н	-	-	Н	Н	Н
CLO-5: Understand the process safety in chemical industries.	3	3	80	70	Н	Н	Μ	Н		Н	-	-	Н	-	-	Н	М	М
CLO-6: Apply the knowledge of process hazards in industries.	3	3	80	70	Н	-	-	-	-	Н	-	-		-	-	Н	-	М

	ration	Instrumentation in Petroleum Industry	Measurement and control in Iron and Steel Industry	Instrumentation and control in Paper Industry	Boiler operation and control in Thermal Industry	Industrial Safety Management
(r	iour)	9	9	9	9	9
S-1	SLO-1	Introduction to petroleum	Introduction: Steel Production	Conventional and non-conventional raw materials for paper manufacture	Introduction to power generation	Introduction to process safety
3-1	SLO-2	Petroleum exploration Methods	Basic oxygen furnace	Different pulping processes	Importance of instrumentation & control in power generation	Importance of Safety consciousness in Indian Chemical Industries
S-2	SLO-1	Magnetic Survey	Blast furnace	Continuous and batch digesters	Classification of instruments in power plant	Industry Standards and Regulations.
3-2	SLO-2	Drilling process	Rolling process	Chemical recovery process	Building blocks	Set of Standards. HSE – PES, AIChE – CCPS,
S-3	SLO-1	Rotary Drilling	Hot rolling process	Conversion process	Combined Heat and Power System	Process hazard analysis
3-3	SLO-2	Petroleum production	Cold rolling process	Identification of various process parameters	Control Loops in Boiler	Chemical process hazards
S-4	SLO-1	Petroleum refining and unit operations in refinery	Temperature measurement	pH measurement	Combustion Control,	Material hazards
0-4	SLO-2	Constituents of crude oil	Pressure measurement	Density measurement	Air/fuel ratio control	Energy hazards
S-5	SLO-1	Atmospheric distillation of crude oil	Shape and thickness measurement	Level measurement	Steam flow measurement	Chemical interaction hazards
SLO-2		Vacuum distillation process	Analyzers in iron and steel industry	Special applications for control	Smoke, density measurement	Layers of protection

2.0	SLO-1	Thermal conversion process		Digester blow tank control	Turbine speed and vibration measurement	Types of safeguard
S-6	SLO-2	Control of distillation column	Blast furnace and stove combustion control system	Dryer temperature control.	Use of feed forward and cascade control in process industries	Safety performance measurement tools
S-7	SLO-1	Temperature control.	Casting mold Level Control	Fuel gas oxygen analyzer	Instrumentation and control in reactors	Techniques used to reduce explosion hazards
3-1	SLO-2	Pressure control	Computer Applications	Dissolved oxygen analyzer	Sodium analyzer	Hazard identification techniques
S-8	SLO-1	Level measurement of petroleum		Computer applications: Direct Digital Control	Flue gas analyzer	Fault tree analysis
0-0	SLO-2	Temperature measurement of petroleum	Steel rolling mill Control	Distributed control system in power plant	Fuel composition analyzer	Operation and maintenance
	SLO-1	Case Study: An. Application for Petroleum Refineries.	Case Study on iron and steel manufacturing process.		Case Study: Chandrapura Thermal Power Station	Case Study: Safety in Explosive
S-9	SLO-2	Case Study: Control of an Industrial Distillation Column	Case Study: Analysis of the Production Processes in a Steel Factory	Case Study: Boiler Materials for the Pulp and Paper Industry	ILLASE STUDV'BOILER TUDE TAILURES	Case Study: Chemical splash at process plant.

	1.	Mian.M.A, "Petroleum Engineering Handbook for the Practicing Engineer", Gulf Professional
Learning		Publishing, 2005.
Resources	2.	Liptak, Bela G, "Instrumentation in the Processing Industries", Chilton Publishers, 1973.
	3.	Considine D. M.," Process/Industrial Instruments and control Handbook", McGraw Hill, 6th Edition2019.

- Sam .G.Duke low, "The Control of boilers", instrument Society of America, 1991.
 Paul Gruhn& Harry Cheddie, Safety Instrumented Systems: Design, Analysis and Justification, 2nd Edition, International Society of Automation, 2005.

Learning Asse	essment											
	Bloom's			Final Evamination	o (50% woightage)							
	Level of Thinking	CLA –	CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		1 (10%)#	Final Examination (50% weightage)		
	Level of Thirking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	
Level 1	Remember	30 %	_	30 %	_	30 %	_	30 %	_	30%	_	
LOVOIT	Understand	00 70		00 70		00 70		00 70		0070		
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-	
Level 3	Evaluate	30 %		30 %		30 %		30 %		30%		
LEVEL 3	Create	JU //0	- 30 %		-	JU /0	-	30 /0	-	3070	-	
	Total	10	0 %	10	0 %	10	0 %	10	0 %	10	0 %	

[#]CLA - 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. D. Karthikeyan, Controls of Engineering India Pvt Ltd, <u>karthikeyan.d@controlsoftengg.in</u>	1. Dr. J. Prakash, MIT, Chennai, prakaiit@rediffmail.com	1. Ms. A.Asuntha, SRMIST
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. D. Nedumaran, Madras University, dnmaran@gmail.com	2. Dr. A. Vimala Juliet, SRMIST

Course	18ECE381T	Course	DISTRIBUTED CONTROL SYSTEM AND SCADA	Course	_	Professional Elective	L	T	Р	С
Code	10ECE3011	Name	DISTRIBUTED CONTROL SYSTEM AND SCADA	Category	E	Professional Elective	3	0	0	3

Pre-requisite Courses	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	ing Data Book / Codes/Standards	Nil	

Course Learning Rationale (CLR): The purpose of learning this course is to:		Learr	ing					Progi	ram L	.earni	ng O	utcor	nes (l	PLO)			
CLR-1: Give basic knowledge in SCADA in the field of automation		1 2	3	1	2	3	4	5	6	7	8	9	10	11	12 1	3 14	15
CLR-2: Understand the communication modules used in SCADA	-	<u>(</u>	, (>-					for	ns for	ent
CLR-3: Give basic knowledge in different architectures of DCS		(Bloom)					arch			ij.						SS	em
CLR-4: Explore the local control unit of distributed control system	į	<u>a</u> 6	en'	dge		eut	Research			aj.		Work		ge	ontrol	8 D	management
CLR-5: Impart adequate information in the interfaces used in DCS		I ninking (Bio	Attainment	× e	S	Development	Ä,	Tool Usage	Ф	Sustainability		E		Finance	g 3	C E	Ĕ
CLR-6: Learn the applications of DCS in process industries		ğ ğ	∖tta	χ	Analysis	Ne lc	Design,	Πs	Culture	∞		Team	io	∞ŏ	aming	district dis	ctive
	[= =	þ	ing		& De	, De	8	ರ ಶ	nent			icat	Mgt.	의미워	JHI V	ille.
Course Learning Outcomes (CLO): At the end of this course, learners will be able to:		Expected	Expected	Engineering Knowledge	Problem	Design 8	Analysis,	Modern	Society 8	Environment	Ethics	Individual &	Communication	友	Life Long PSO 1: Au	PSO-2: L	PSO-3: E
CLO-1: Understand the elements of SCADA system		3 80		Н	-	-	-	-	Ĥ	-	-	-	-	-	Η Л	1 H	-
CLO-2: Develop any application based on SCADA along with GUI using SCADA software.		3 80	70	Н	-	-	-	-	Н	-	-	-	-	Н	Н -	· H	-
CLO-3: Understand evolution and architecture of DCS and hierarchical control in DCS		3 75	70	Н	Н	М	Н	М	Н	-	М	М	-	Н	H	H H	Н
CLO-4: Demonstrate interfacing of hardware and software of computer based automation system.		3 80	75	Н	Н	М	Н	М	-	-	М	Н	-	Н	Η Л	1 H	Н
CLO-5: Select and use the most appropriate automation technologies for a given application		3 80	70	Н	-	М	-	Н	-	-	Н	Н	-	Н	Η Л	1 H	Н
CLO-6: Evaluate computer based automation system used in industries ranging from discrete, continuous process to hybrid		3 80	70	Н	-	-	,	-	Н	-	Н	Н	-	Н	Н	Н	Н

	ration nour)	SCADA Elements	Communication	DCS Architecture	Operator interface	DCS Application
		9	9	9	9	9
S-1	SLO-1	SCADA basics introduction	SCADA communication introduction	DCS - basics	DCS operator interfaces- introduction	DCS Application in Power plant
3-1	SLO-2	Elements of SCADA	Communication system components	Evolution of Distributed Control System	Operator Interface Requirements	Automation strategy
S-2	SLO-1	Functionality of SCADA	Structure of a SCADA Communications Protocol	DCS Architecture	Low-level Operator Interface	Distributed system structure
0-2	SLO-2	Process example	Field/RTU communication	Local control unit	Continuous control station	Application functions
S-3	SLO-1	History of SCADA	Analog electronic controllers	I/O module(Analog & Digital)	Manual Loader Station	DCS Application in cement plant
3-3	SLO-2	Development from Telemetry	Communication Topology	Basic elements	Indicator/Logic Station	System architecture
S-4	SLO-1	Key features	RTU/MTU communication	Architectural parameters	Smart annunciators	DCS Application in iron plant
3-4	SLO-2	Real time systems	System components	Types of architecture	High level Operator interface	System architecture
S-5	SLO-1	Analog signals measurement	Communication Protocols	CPU, Memory	Architectural Models	DCS Application in steel plant

	SLO-2	Control techniques	Operator interface	Local control unit languages	Hardware Elements	System architecture
S-6	SLO-1	Discrete signals measurement	Monitoring alarms	Language requirements	Operator displays	DCS Application in Paper and pulp industry
3-0	SLO-2	Control techniques	Status points	Functional blocks	Engineering interface- Introduction	System architecture
S-7	SLO-1	Remote terminal unit	Control interfacing	Problem-oriented languages	System configuration requirements	DCS Application in petroleum-refining
5-/	SLO-2	Analog and Discrete control	Parallel operator interface	High-level languages	Diagnosis of System Problems	industry
	SLO-1	Monitoring signals	SCADA Development for any one typical	Process interfacing issues	Low-level engineering interface	DCS Application in oil and gas processing
S-8	SLO-2	Master terminal unit	application	Security design issues	System configuration	industry.
	SLO-1	Process configuration	Programming for GUI development using	Process input/output design issues	High-level engineering interface	DCS Application in water treatment plant
S-9	SLO-2	Application	SCADA software	Remote I/O and communication modules	System configuration	System architecture

Learning Resources	Stuart Boyer A, "SCADA: Supervisory control and data Acquisition", Fourth Edition, ISA-The Instrumentation, Systems, and Automation Society, 2010 Dobrivojie Poppovik, Vijay P Bhatkar, "Distributed Computer Control Systems in Industrial Automation" CRC Press, 1990	 Michael Lucas, "Distributed Control Systems", Van Nostrand Reinhold Co., 1986 IDC Technologies, "Practical Distributed Control Systems (DCS) for Engineers and Technicians" 2012 Krishna Kant, Computer Based Industrial Control, 2nd Edition, Prentice Hall of India, New Delhi, 2010
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Learning Assess	sment											
	Bloom's				Final Examination	(50% woightage)						
	Level of Thinking	CLA –	CLA - 1 (10%)		CLA – 2 (15%)		3 (15%)	CLA – 4	(10%)#	Final Examination (50% weightage)		
	Level of Thirking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	
Level 1	Remember Understand	30 %	-	30 %	-	30 %	-	30 %	-	30%	-	
Level 2	Apply Analyze	40 %	-	40 %	-	- 40 % -		40 %		40%	-	
Level 3	Evaluate Create	- 10%		-	30 %	-	30 %	-	30%	-		
	Total 100 % 100 %) %	100	0 %	100	0 %	100 %				

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

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Course	18ECE382T	Course	BUILDING AUTOMATION	Course	Е	Professional Floative	L	T	Р	С
Code	10ECE3021	Name	BUILDING AUTOWATION	Category	E	Professional Elective	3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil		Progressive Courses
Course Offering I	Department	Electronics and Communication Engineer	ing	Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR): The purpose of learning this course is to:	L	earni	ng					Progi	ram L	.earni	ing O	utcor	nes (PLO)			
CLR-1: Give basic knowledge in intelligent building and building automation systems				1	2	3	4	5	6	7	8	9	10	11	12 1	13 14	15
LR-2: Gain Knowledge on different sensors and measurement systems in BMS system										Ŋ					for	ns for	ent
CLR-3: Know the basic concepts of HVAC Air handling unit	(Bloom)	(%) /	t (%)				arch			ij							Jem
CLR-4: Understand the basic concepts of HVAC terminal unit	<u>B</u>	ncy	en	ge		ent	Research			ain		Work		8	utuc	& D	s management
CLR-5: Explore the BAS Architecture	Thinking	Proficie	Attainment	₩ Me	S	Development	, R	ool Usage	ø	Sustainability		> E		Finance	g i	. <u>.</u> .	S E
CLR-6: Present an overview of different communication protocols	Ę	ρ	₩	출	Analysis	Nel C	Design,	Ns	Culture	∞ర		Team	io	∞ŏ	Learning	e dis	ctive
	Ĵ	8		ing	Ana	& De	, D		چ ت	nen			ica	Mgt.	J Le	aggilla Saliji	f sv
Course Learning Outcomes (CLO): At the end of this course, learners will be able to:	Level of	Expected	Expected	Engineering Knowledge	Problem	Design 8	Analysis,	Modern	Society &	Environment	Ethics	Individual &	Communication	Project N	Life Long	continuo PSO-2: 1	control o PSO-3: I skills
CLO-1: Understand the need of intelligent buildings and automation systems	3	80	75	Н	-	-	-	-	Н	Н	-	-	-	-	H	н н	Н
CLO-2: Measure the parameters and design of sensors				Н	•	-	•	-	Н	Н	-	-	-	Н	Н	- M	Н
CLO-3: Design different Air handling units	3	75	70	Н	Н	М	Н	М	Н	М	Н	-	-	Н	H	н м	Н
CLO-4: Understand and design terminal units	3	80	75	Н	Н	М	Н	М		М	Н	Н	-	-	Н	- M	Н
CLO-5: Familiarize with the components of BAS architecture	3	80	70	Н		М	1	Н	-	М	Н	1	-	-	Н	- M	Н
: Select the communication protocol for a particular application			70	Н	-	-	-	-	Н	-	Н	-	Н	М	Н	Н -	Н

	ration	Introduction to Building automation systems	Comfort parameters	HVAC Basic Concepts- Air handling unit	Terminal Unit	BAS Architecture
(f	iour)	9	9	9	9	9
S-1	SLO-1	Introduction to intelligent building	Temperature	Concept of Air handling unit	Concept of Variable Air Volume (VAV) system	BAS Hierarchy
0-1	SLO-2	intelligent architecture	Enthalpy, Entropy	components in AHU	different types of VAV	Field level components
S-2	SLO-1	structure	Heat Transfer - Conduction, Convection, Radiation	different types of dampers	Design, working	Direct Digital Control (DDC)
3-2	SLO-2	Facility management vs. intelligent buildings	Working Principle, Characteristics of RTD	Working, configuration,	series fan powered	Supervisory Controller
S-3	SLO-1	Lifecycle of building	Thermistor, Thermocouple	different types of AHU	parallel fan powered	Server, Operator Workstation (OWS)
0-3	SLO-2	Evolution of intelligent buildings	Bimetallic strip	Design and working	pressure dependent	Different communication protocol
S-4	SLO-1	Introduction to BAS	Humidity, Specific Humidity,	Operation of different modes in AHU	supply-exhaust VAV	addressing concepts
3-4	SLO-2	Different systems of BAS	Relative Humidity, Due point, Saturation point	humidification	dual duct VAV	Open Protocols -BACnet, LON
S-5	SLO-1	LO-1 HVAC Working principle of relative humidity dehumidification Design, working, u		Design, working, use of radiation coil	Profibus, Modbus	
3-3	SLO-2	HVAC Applications	mounting for humidity sensors in BAS	static pressure control	chilled beam	M-bus

	SLO-1	Security system	Psychrometric chart	volume matching	CRAC unit, VRV systems	Proprietary Protocols- N2, CBUS		
S-6	SLO-2	Field Devices	Pressure, Static Pressure, Velocity pressure, Absolute Pressure	cooling, heating,	unit heater, Fan coil unit and unit ventilator	Wireless filed devices		
S-7	SLO-1	Fire alarm system	Gauge Pressure, Vacuum Pressure, Differential Pressure, Sealed Pressure	economizer mode	Chilled water system	controllers		
3-1	SLO-2	Types of Detectors	Pressure Sensors		Concept of refrigeration cycle, components used in refrigeration cycle	routers		
S-8	SLO-1	Modules Working of principle of different air flow sensors Working of principle of different water flow sensors		plate heat exchanger	different types of chilled water system	coordinators		
3-0	SLO-2			I hoat rocovory whool	Working and design of different types of boilers	Benefits of a Wireless BAS		
S-9	SLO-1	lighting systems	Measurement of CO2 level	AHU for different applications	Working and design of different types of	Wireless Field Bus		
3-9	SLO-2	ngnung systems	Working principal of BTU meter	ино тог интегент аррисацонs	heat exchanger	Basic Reference Model (BRM)		

Learning Resources	 Smart Buildings by Jim Sinopoli, Butterworth-Heinemann imprint of Elsevier, 2ndEdition., 2010 Intelligent Building Systems by Albert Ting-Pat So, WaiLok Chan, Kluwer Academic publisher, 3rdEdition., 2012. 	 Design of Special Hazards and Fire Alarm Systems by Robert Gagnon, Thomson Delmar Learning; 2nd Edition, 2007.
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Learning Asse	earning Assessment										
	Bloom's			Conti	nuous Learning Ass	essment (50% weig	htage)			Final Evamination	n (50% weightage)
	Level of Thinking	CLA –	1 (10%)	CLA –	2 (15%)	CLA –	3 (15%)	CLA – 4	1 (10%)#	FIIIai Examination	i (50 % weightage)
	Level of Thirtking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %		30 %	_	30 %	_	30 %	_	30%	
Level I	Understand	30 70	-	30 70	-	30 70	-	30 70	-	3070	-
Level 2	Apply	Apply 40 %		40 %	_	40 %	_	40 %	_	40%	_
Level 2	Analyze	70 /0	_	40 /0	_	70 70	_	70 70	_	4070	_
Level 3	Evaluate	30 %		30 %		30 %		30 %		30%	
Level 3	Create	30 /0	_	30 /0	-	30 /0	-	30 /0	-	3070	_
	Total	Total 100 % 100 %		0 %	10	0 %	10	0 %	100 %		

[#] CLA - 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. D. Karthikeyan, Controlsoft Engineering India Pvt Ltd, karthikeyan.d@controlsoftengg.in	1. Dr. J. Prakash, MIT, Chennai, prakaiit@rediffmail.com	1. Dr.G.JoselinRetna Kumar, SRMIST
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. D. Nedumaran, Madras University, dnmaran@gmail.com	2. Mr.J.SamJeba Kumar, SRMIST

Course	18ECE383J	Course	INISTELIMENTATION SYSTEM DESIGN	INSTRUMENTATION SYSTEM DESIGN Course E Professional Elective	Professional Floative	L	Т	Р	С	
Code	10ECE3033	Name	INSTRUMENTATION STSTEM DESIGN	Category	_	Professional Elective	2	0	2	3

Pre-requisite Courses	Nil	Co-requisite Courses		Progressive Courses Nil
Course Offering	Department	Electronics and Communication Engineering	ng Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR): The purpose of learning this course is to:	L	earni	ng					Prog	ram L	Learn	ing O	utcor	nes (l	PLO)			
CLR-1: Impart knowledge on basic signal conditioning circuits.			3	1	2	3	4	5	6	7	8	9	10	11	12	13 ′	14 15
CLR-2: Familiarize students on the requirements of industry.	<u></u>	(9	(>-					1	for ms for	or ent
CLR-3: Obtain adequate knowledge on process parameter optimization.	(Bloom)	(%) /	t (%)				arch			l ≣						on co	3 8
CLR-4: Gain expertise to handle basic instruments in Industry.	<u>B</u>	Proficiency	Attainment	dge		ent	Research			Sustainability		Work		92	ı	ontrol e syst	C & DCS for management
CLR-5: Acquire knowledge of piping diagram in Industry.	ing	icie	inr	we le	S	mdo	, <u>R</u>	age	Φ	gnst		<u>۶</u>		& Finance		atic o	S E
CLR-6: Bridge the gap between industrial requirements and operational constraints.	Thinking	Jo	۱tta	ᇫ	Analysis	Development	Design,	Ns	Culture	∞		Team	io		<i>-</i> - - -	E 70 9	sten Stive
			pe	ing		& De	, De	Tool Usage	ರ *	nen			ical	∕lgt.	J Le	Auto	offiza Effec
Course Learning Outcomes (CLO): At the end of this course, learners will be able to:	Level of	Expected	Expected	Engineering Knowledge	Problem	Design 8	Analysis,	Modern ⁻	Society 8	Environment	Ethics	Individual &	Communication	Project Mgt.	6.	∴ ≝ ⊹	PSO-2: 1 control o PSO-3: 1 skills
CLO-1: Apply mathematical knowledge, science, engineering fundamentals to design circuits pertaining to various process measurements	3	80	75	Н	Н	Н	М	-	-	-	-	-	-	-	М	Н	- -
CLO-2: Design signal conditioning circuits for various process parameters.			70	Н	Н	-	М	Н	-	-	-	Н	-	L	- 1	М	M H
CLO-3: Optimize the performance of process output.			70	Н	-	М	М	М	-	Н	М	-	-	-	-	-	- M
CLO-4: Select optimal sensor for process measurement.	3	80	75	Н	Μ	-	М	-	М	М	-	-	-	-	-	- 1	М -
CLO-5: Choose type of indication circuits for industry.	3	80	70	Н	-	Н	-	-	-	М	-	Н	М	-	-	Н	- L
LO-6: Analyze and select the suitable sensing and transduction unit.			70	Н	Н	1	1		-	-	-	-	-		-	Н	МН

	ration	Review of Signal Conditioning circuits	Design of Level and Pressure Measurement	Design of Flow measurements and Control Valve	Design of Transmitters and final control element	Design of indicators and Logic circuits
(ř	iour)	12	12	12	12	12
	SLO-1	Requirements of Signal Conditioning	Electronic PID controller Design.	Study of Orifice, Venturi and Rotameter.	2 wire and 3 wire transmitter	Alarm circuit design
S-1	SLO-2	Analog, Digital and adaptive filter design	P,I,D modes of operation Solving numerical	Review of design requirements.	Thermocouple based temperature transmitter	Annunciator circuit design
S-2	SLO-1	V/I and I/V Converter design. Design of amplifiers – Pre amplifier	Composite modes – PI, PD and PID.	Design of Orifice.	Design of transmitter	Interlocks
3-2	SLO-2	Instrumentation Amplifier, Bridge and Isolation Amplifier.	Realization using composite modes.	Design of Rotameter.	IL anacitance pased flow transmitter	Overview of Programmable logic controllers
s	SLO-1	Lab1: Design of Active Filters – LPF,	nb1: Design of Active Filters – LPF, Lab 4: Design, Fabrication and Testing		Lab10: Design, Fabrication and Testing	Lab 13: Seguential controller using PLD
3-4	SLO-2	HPF and BPF.	of Analog PID Controller.	Program for sizing Orifice.	of 2-wire Analog Transmitter.	Lab 13: Sequential controller using PLD
S-5	SLO-1	Signal conditioning circuits for temperature measurement. – RTD.	Requirements of Pressure Measurement.	Design constraints.	Level transmitter	Microprocessor based PID controller
3-3	SLO-2	Design of RTD	Bourdon tube, Bellows, Diaphragms	Study of Valve characteristics and valve body	Flapper nozzle amplifier characteristics	Study of recorders
	SLO-1	1 Signal Conditioning for Thermocouple. Factors affecting sensitivity.		Design of Actuator and positioner	Pneumatic actuator	Numerical in alarm circuit
S-6	SLO-2	Design of thermocouple	Adjustment of set point, bias and controller settings	Control Valve sizing	Hydraulic actuator	Real time case study

S	SLO-1	Lab 2 :Design of Instrumentation	Lab 5. Design of V/I and I/V conventor	Lab 8: Development of Software	Lab11: Design of multi channel data	Lab 14: Functional constraints and
7-8	SLO-2	Amplifier.	Lab 5: Design of V/I and I/V converter.	Program for sizing Rotameter.	acquisition system	specification in industry
S-9	Air purge Level Measurement		Design of Control valve factor and plug area.	Criaracieristics of burnes	Operating console and control room panel design.	
3-9	SLO-2			Selection of material for body and trim.	Instruments used in pumping practices	Instrument symbols and signals
	SLO-1	Zero and Span adjustment in Temperature Transmitters.	Capacitive based level Measurement.	Cavitation and flashing in Control valve	Pump operation and maintenance	Mini project on any process application.
S-10		Temperature indicators and selection criteria for temperature sensing instruments.		Characteristics of control valve for typical applications	Selection of pumps	Discussion on project
s	61.0.4	Lab3: Design of regulated power	Lab 6: Design of signal conditioning	Lab 9: Study of control valve	Lab12: Study of P&I diagrams	Lab 15: Process application
11-12	SLO-2		circuits for level measurements.	characteristics	Lab 12: Study of P&I diagrams	Lab 15: Process application

ſ		1.	C.D.Johnson, ""Process Control Instrumentation Technology", 8th Edition, Prentice Hall, 2015.		
	Learning	2.	Bentley, J. P., Principles of Measurement Systems, Pearson Education, 2015.	4.	N.A.Anderson, Instrumentation for Process Measurment and Control, Chilton Company, 2003.
	Resources	3.	Beta G.Liptak, "Instrument Engineers Handbook – Process Control and Optimization". 4th Edition. CRC	5.	R.W.Miller, "Flow measurement engineering Handbook", McGraw hill. New York, 1996.
			Press. 2008.		

Learning Ass	sessment											
	Bloom's		Continuous Learning Assessment (50% weightage)									
	Level of Thinking	CLA –	1 (10%)	CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#		Final Examination (50% weightage)		
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	
Lovel 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%	
Level 1	Understand	20%	20%	13%	13%	10%	10%	13%	10%	10%	13%	
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%	
Level 2	Analyze	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%	
1 1 2	Evaluate	400/	400/	450/	450/	450/	450/	450/	450/	450/	450/	
Level 3	Create	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%	
	Total	10	0 %	100) %	10	0 %	100) %		-	

[#] CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. D. Karthikeyan, Controlsoft Engineering India Pvt Ltd, <u>karthikeyan.d@controlsoftengg.in</u>	1. Dr. J. Prakash, MIT, Chennai, prakaiit@rediffmail.com	1.S.Sharanya SRM IST
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. D. Nedumaran, Madras University, dnmaran@gmail.com	2.Dr.G.Joselin Retna Kumar

Course	19ECE29AT Co	ourse	FACTORY INSTRUMENTATION NETWORKS	Course	_	Professional Flective	L	Т	Р	С
Code		lame	FACTORT INSTRUMENTATION NETWORKS	Category	L	Professional Elective	3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil		Progressive Courses	Nil
Course Offering	Department	Electronics and Communication Engineer	ing	Data Book / Codes/Standards	Nil	

Course Learning Rationale (CLR): The purpose of learning this course is to:		Lear	ning					Prog	ram L	.earni	ing O	utcor	nes (l	PLO)			
CLR-1: Educate on the basic concepts of data networks	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12 1	3 14	15
CLR-2: Introduce the basics of inter-networking and serial communications	2		5 3							y.					for	ns for	ent
CLR-3: Provide details on HART and Field buses	(moold)	(%)					arch			pilit						. <u>a</u> .v	em
CLR-4: Know different techniques on Modbus, PROFIBUS and other communication protocols	Q	<u> </u>	er S	dge		ent	Research			ain		Work		92	ontro	& D	management
CLR-5: Present an overview of industrial Ethernet	Thinking	Proficiency	Attainment	w e	S	Development	چ	Usage	Φ	Sustainability		E		Finance	ning	E E	Z E
CLR-6: Study the working of computer busses and protocols	<u>.</u>	1 2	₹	Α̈́	Analysis	, velc	sign	ns	Culture	∞ర		Team	ion	∞ర	earning	Ф -	ctive
	Ę	3	- R	ing	Ans	& De	, D	Tool	8 C	nen		∞	ica	Mgt.	J Le	agiil S	# E
Course Learning Outcomes (CLO): At the end of this course, learners will be able to:	90 000		Expected	Engineering Knowledge	Problem	Design 8	Analysis, Design,	Modern	Society &	Environment	Ethics	Individual &	Communication	Project N	Life Long L	continuo PSO-2: 1	PSO-3: I
CLO-1: Understand the basic concepts of data networks	3			Н	Н	-	-	М	Ĥ	-	-	-	-	-	Н	-	Н
CLO-2: Analyze the techniques of inter-networking and serial communications	3	8	0 70	Н	-	-	Н	-	Н	-	-	-	-	-	Н	- M	Н
CLO-3: Understand the protocols and layers of HART and field bus	3	7.	5 70	Н	-	Μ	Н	М	Н	-	Н	-	Н	М	НІ	И Н	Н
CLO-4: Analyze the techniques of MODBUS, PROFIBUS and other communication protocol	3	8	75	Н	Н	М	Н	М	1		Н	Н	Н	Н	Н	- H	Н
CLO-5: Utilize the concept of industrial Ethernet	3	8	0 70	Н	-	М	-	Н	1	-	Н	-	Н	Н	Н	Н	Н
CLO-6: Analyze the working of computer busses and protocols	3	8	0 70	Н	-	Μ	-		Н	-	Н	-	Н	-	Н	H	Н

Du	ration	OSI Model	Inter-Networking	HART and Field bus	PROFIBUS and Modbus	Industrial Ethernet
(h	nour)	9		9	9	9
S-1	SLO-1	Introduction to Modern instrumentation	Introduction to RS-232	Introduction to HART and smart instrumentation	Introduction to PROFIBUS	Introduction to Industrial Ethernet
3-1	SLO-2	Introduction to control systems	RS-422 and RS-423	HART protocol	PROFIBUS protocol stack	10 Mbps Ethernet
S-2	SLO-1	Open systems interconnection (OSI) model	Electrical characteristics of RS 232	Physical layer- Analog 4–20 mA	Physical layer (layer 1)	Media systems
3-2	SLO-2	Representation of the OSI model	Examples	Digital frequency shift keying (FSK)	Type A cable	10Base5, 10Base2, 10BaseT
S-3	SLO-1	Protocols	Communications between two nodes	Data link layer	Type B cable	Signaling methods
3-3	SLO-2	Basic structure of an information frame defined by a protocol	Transmission and reception of characters	HART protocol implementation of OSI model layer	Data link layer (layer 2)	Medium access control
S-4	SLO-1	Standards	Simple no-handshaking communications	Application layer- Universal commands	Hybrid medium access control	Frame transmission
3-4	SLO-2	EIA-232 interface standard	Software handshaking	Common practice commands, Device specific commands	Application layer	Frame reception
C E	SLO-1	EIA-485 interface standard	Hardware handshaking	Troubleshooting	Introduction to Modbus	MAC frame format
S-5	SLO-2	Interoperability, Interchangeability	Two-way communications with handshaking	HART cable length calculation	Modbus protocol structure	Differences between IEEE 802.3 and Blue Book Ethernet (V2)

	SLO-1	Mod bus	DTE-DCE connections (PC to modem)	Introduction to foundation field bus	Function codes	IEEE 802.2 LLC
S-6	SLO-2	Data Highway Plus protocol structure Exercises			Read coil or digital output status (function code 01) and Read digital input status (function code 02)	Reducing collisions
S-7	SLO-1	DeviceNet	Introduction to RS-485 (ISO 8482)	Wiring rules	Read holding registers (function code 03) and Reading input registers (function code 04)	Design rules
	SLO-2	Profibus	RS-485 connecting to multiple nodes	Encoding rule, permeable and delimiters	Force single coil (function code 05)	Length of the cable segments
	SLO-1	Introduction to OLE for process control	Line drivers	Data link layer	Preset single register (function code 06)	100 Mbps Ethernet
S-8	SLO-2	Common problems and solutions	Unbalanced digital interface circuit (RS- 423) and balanced digital interface circuit (RS-422)	Data link layer: packet format	Troubleshooting	Media access: full-duplex
S-9	SLO-1 General comments on troubleshooting		RS-232/485 converter	Application layer	Common Problems and Discussion	Auto-negotiation
3-9	SLO-2	Specific Methodology	Exercises	User layer	Modbus Plus protocol overview	Fiber optic cable distances 100BaseFX

Learning Resources	 Steve Mackay, Edwin Wrijut, Deon Reynders, John Park, "Practical Industrial Data Networks Design, Installation and Troubleshooting", Newnes Publication, Elsevier 1st edition, 2004. Ian Verhappen and Augusto Pereira, "Foundation Field bus", 4th Edition, Feb 29, 2012 William Buchanan, "Computer Buses", CRC Press, 2000. 	 Andrew S. Tanenbaum, David J. Wetherall, "Computer Networks", Prentice Hall of India Pvt. Ltd., 5th Edition. 2011. A. Behrouz Forouzan, "Data Communications & Networking", 3rd edition, Tata Mc Graw hill, 2006.
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Learning Asses	ssment											
	Bloom's		Continuous Learning Assessment (50% weightage)									
	Level of Thinking	CLA – 1 (10%)		CLA – 2 (15%)		CLA –	3 (15%)	CLA – 4	ł (10%)#	Final Examination (50% weightage)		
	Level of Thirking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	
Level 1	Remember Understand	30 %	-	30 %	-	30 %	-	30 %	-	30%	-	
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-	
Level 3	Evaluate Create	30 %	-	30 %	-	30 %	-	30 %	-	30%	-	
	Total	100	0 %	100	0 %	10	0 %	10	0 %	10	0 %	

[#] CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. D. Karthikeyan, Controlsoft Engineering India Pvt Ltd, karthikeyan.d@controlsoftengg.in	1. Dr. J. Prakash, MIT, Chennai, prakaiit@rediffmail.com	1. Dr.S.Umamaheswari, SRMIST
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. D. Nedumaran, Madras University, dnmaran@gmail.com	2. Dr. A. Vimala Juliet, SRMIST

Course	18ECE385T Cours	IoT IN PROCESS INSTRUMENTATION AND AUTOMATION	Course _	Professional Elective	L	T	Р	С
Code	Name	101 IN PROCESS INSTRUMENTATION AND AUTOMATION	Category	i Tolessional Elective	3	0	0	3

Pre-requisite Nil	Co-requisite Courses	Vil	Progressiv Courses	Nil
Course Offering Department	Electronics and Communication Engineering	ng Data Book	/ Codes/Standards Nil	

Course Learning Rationale (CLR): The purpose of learning this course is to:			ng					Prog	ram L	.earni	ing O	utcon	nes (I	PLO)			
CLR-1: Impart fundamental knowledge on the concepts of Internet of Things with its Architecture.			3	1	2	3	4	5	6	7	8	9	10	11	12 13	3 14	15
CLR-2: Provide an overview of various techniques that are using Internet of Things in Industry applications.			<u></u>							₹					for	ns for	ent
CLR-3: Understand the working of Internet of Things in Industry with the advanced Industry 4.0 platforms.	(moo	(%) /	t (%)				arch			iliq		_				SS	Jem
CLR-4: Understand the application of Internet of Things in Automation	(B)	Proficiency	eni	95	5	ent	Research			aina		/ork		20	ontrol	e Sv ⊘ S	management
CLR-5: Gain knowledge on the operation of Engineering in IoT Automation with arrowhead framework.			Attainment	oly,		, lac	ج ا	Usage	ө	Sustainability		Team Work		Finance		LC Get	E C
CLR-6: Explore the working of IoT in various real-time industries			∤tta	, K	Signalyeis	Ne Sel	Design, I	l ns	Culture			Tea	ig	∞ŏ	arning matic c	dis P	ctive
	f Thinking	8		2	2	Ğ	ے	Tool	Š	nen		<u>∞</u>	ica	Mgt.	<u> </u>	us& Jtiliz	Elle.
Course Learning Outcomes (CLO): At the end of this course, learners will be able to:	Level of	Expected	Expected	Engineering Knowledge	Droblom	Design & Development	Analysis, I	Modern	Society &	Environment &	Ethics	Individual &	Communication	헗	Life Long PSO 1: Au	PSO-2: 1	PSO-3: I skills
CLO-1: Understand the basic concepts of IoT, Architecture and Its Applications	3	85	80	H	١ .	-	-	-		-	-	-	-	-	Н -	Н	-
CLO-2: Analyze the techniques to apply IoT for Industry		85	75	ŀ	l F	l H	Н	Н	ı		Н	-	-	-	Н -	Н	-
CLO-3: Apply the knowledge of different techniques of IoT in industry with an advanced platform of Industry 4.0		80	80	H	l F	l H	Н	Н	Н	-	-	-	-	-	Н -	Н	Н
CLO-4: Develop the knowledge of IoT in Automation.	3	85	80	H	l F	l H	Н	Н	ı			Н	-	-	Н -	Н	Н
CLO-5: Apply the knowledge of Engineering in IoT Automation System			75	H	-	Н	-	Н		-	Н	-	-	-	H F	I H	Н
CLO-6: Design the IoT based real-time projects			85	H	١ -	Н	Н	Н	Н	Н	Н	Н	Н	Н	H	I H	Н

Du	ıration	IoT – Landscape, System Architectures	ectures Industrial Internet of Things(IIoT) IIoT Platforms		IoT Automation	Engineering of IoT Automation System
(i	hour)	9	9	9	9	9
S-1	SLO-1	Introduction to IoT	Introduction to IIoT	Introduction to IIoT Conceptual diagram	From DCS and SCADA to IoT	Engineering of an Arrowhead domain facility
	SLO-2	Applications and Architectures	IIoT Architecture	Middleware Architecture	Automation System Architectures	Engineering Tool Interoperability
S-2	SLO-1	Wireless Networks, Devices	Communication Methods for IoT Devices	Functions of Middleware Platforms	Automation System Properties	Component based Engineering Method
3-2	SLO-2	Security and Privacy	IoT Reference Model by ITU	IIoT WAN and Protocol	Communication within Automation Systems	Life Cycle Dimensions
S-3	SLO-1	Event-Driven Systems	IoT Business Model by ITU	IIoT Device for M2M	Current Trends in Automation System	Data Model
3-3	SLO-2	IoT System Architectures	Designing Industrial Internet Systems	Securing the Industrial Internet	Automation System Security	Design Guidelines for Component based Engineering
S-4	SLO-1	Protocols Concepts	OSI Table	Security in Manufacturing	Future Automation System Requirements	Safety and Security Engineering of IoT Automation System
	SLO-2	IoT- Oriented Protocols	Web 2.0 Layers	OT Manufacturing Network	Next Generation Automation	Security Analysis
S-5	SLO-1	Data bases & Time Bases	IP Layers vs IIoT Layers	OT vs IT Security Domains	Internet of Things	ETSI and STRIDE method
3-3	SLO-2	IoT Device Design Space	Modern Communication Protocols	Defining Industry 4.0	System of Systems	Safety Analysis
S-6	SLO-1	Cost of Ownership	Wireless Communication Technologies	Characteristics of Industry 4.0	Service Oriented Architecture	FMEA / FMECA Analysis

	SLO-2	Power Consumption	Proximity Network Communication Protocols	Industry 4.0 Design Principles	Local Automation Cloud Concept	Engineering Scenarios
S-7	SLO-1	Cost per Transistor and Chip Size	Access Network Technology	Building Blocks of Industry 4.0	Local Cloud Properties	Efficient Deployment of IoT Sensors
3-7	SLO-2	Duty Cycle and Power Consumption	Ethernet, IP Routing	Industry 4.0 Reference Architecture	Local Cloud Establishment	Network Deployment tool
S-8	SLO-1	Platform Design	TCP/IP	Smart Factories - Introduction	Automation Support	Cost of Wireless Sensor Network
3-0	SLO-2	IoT Network Model	Application Programming Interface	Smart Factory Production line	Latency in Local Clouds	Swift Deployment and Configuration
S-9	SLO-1	Single and Multi – Hub Networks	API – Technical Perspective with Example	Smart Manufacturing	Security in Local Clouds	Deployment Procedure
3-9	SLO-2	Physical Networks	Summary	Real World Smart Factories	System of System Scalability	Replacement of Device

Learning
Resources

- 1. Dimirios Serpanos and Marilyn Wolf, Internet-of-Things (IoT) Systems, Architectures, Algorithms, Methodologies, Springer, 2018.
- Alasdair Gilchrist, Industry 4.0 The Industrial Internet of Things, Apress, 2016.
 "IoT Automation Arrowhead Framework", Jerker Delsing, CRC Press, Taylor & Francis Group, 2017.
- 4. Patel Chintan, Internet of Things Security: Challenges, Advances, and Analytics, Auerbach Publications, 2019.
- 5. Jeschke S Brecher, Song C, Industrial Internet of Things Cyber Manufacturing Systems, Springer,
- 6. Stamatios Manesis, George Nikolakopoulos, Introduction to Industrial Automation, CRC Press, Taylor & Francis Group, 2018.

Learning Asses	earning Assessment											
	Bloom's		Continuous Learning Assessment (50% weightage)									
	Level of Thinking	CLA –	CLA – 1 (10%)		CLA – 2 (15%)		3 (15%)	CLA – 4	(10%)#	FIIIai Examination	n (50% weightage)	
	Level of Thirtking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	
Level 1	Remember	30 %		30 %	_	30 %	_	30 %		30%		
Level I	Understand	30 70	-	30 70	-	30 70	-	30 70	<u>-</u>	3070	-	
Level 2	Apply	40 %	_	40 %	_	40 %	_	40 %	_	40%	_	
Level 2	Analyze	40 /0	_	40 /0	_	40 70	_	40 /0		4070	_	
Level 3	Evaluate	30 %		30 %		30 %		30 %		30%		
Level 3	Create		-	30 70	-		-			3070	-	
	Total	10	0 %	100 %		10	0 %	100) %	100 %		

[#] CLA - 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. D. Karthikeyan, Controlsoft Engineering India Pvt Ltd, karthikeyan.d@controlsoftengg.in	1. Dr. J. Prakash, MIT, Chennai, prakaiit@rediffmail.com	1. Dr. G. Y.RajaaVikhram, SRMIST
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. D. Nedumaran, Madras University, dnmaran@gmail.com	2. Dr. Joselin Retna Kumar, SRMIST

Course	10ECE206T	Course	MEMS DASED MICROSVETEM ANALYSIS AND DESIGN	Course	_	Professional Flective	L	Т	Р	С
Code	18ECE3861	Name	MEMS-BASED MICROSYSTEM ANALYSIS AND DESIGN	Category		FIOIESSIONAL ETECTIVE	3	0	0	3

Pre-requisit Courses	te _{Nil}	Co-requisite Nil		Progressive Courses Nil
Course Offeri	ing Department	Electronics and Communication Engineering	g Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR): The purpose of learning this course is to:		L	earnir	ng						Prog	ram L	_earn	ing O	utco	nes (PLO)			
CLR-1: Study the basics of microfabrication and its techniques			2	3	F	1	2	3	4	5	6	7	8	9	10	11	12	13 14	15
CLR-2: Impart the knowledge ofmechanicalmicrosensors		<u>_</u>	5)	(y.						ns for	ent
CLR-3: Understand the mechanism for various actuators		(Bloom)	(%)/	t (%)					arch			ppilliqu						an co	le l
CLR-4: Know the behavior of fluid at the micro level, working of microfluidic devices and its fabrication techniques			nc)	jeu		dge		ent	Research			aina		Work		92		ontrol e svst & DC	management
CLR-5: Identify the correct interfacing circuits for microsystem			Proficiency	Attainment		wle	S	Development		Usage	Ф	Sustainability		E .		Finance	gu .		S III
CLR-6: Know the working and readout mechanism for microdevices or microsystems			Prof	∖tta		Kno	Analysis	, kelc	Design,	Ns	Culture	∞		Team	ion	∞ర	arning	mat dis	ctive
		f Thinking				ring		& De	å	Tool	ನ ನ	nen		⋖	ical	Mgt.	۳	Auto Liis Liis	f sv
Course Learning Outcomes (CLO): At the end of this course, learners will be able to:		Level of	Expected	Expected		Engineering Knowledge	Problem	Design 8	Analysis,	Modern ⁻	Society 8	Environment	Ethics	Individual	Communication	Project N	Life Long	PSO 1: / continuo PSO-2: 1	control o PSO-3: I skills
CLO-1: Apply the knowledge of micro technology to fabricate micro devices		3	80	80		Н	Н	-	Н	Н	-	-	Н	Н		-	Н	М -	Н
CLO-2: Design a microsensor based on an application with a suitable working principle.		3	80	80		Н	Н	Н	Н	Н	-	1	Н	Н	-		Н	М -	Н
CLO-3: Design, analyse and optimise the microactuator for different applications.		3	80	80		Н	Н	Н	Н	Н	-	-	Н	Н		-	Н	М -	Н
CLO-4: Design a microfluidic device for automobile, medical, electronics and industrial applications		3	80	80		Н	Н	Н	Н	Н	-	1	Н	Н	-		Н	М -	Н
CLO-5: Design an interfacing circuit for reading output from microsystems		3	80	80		Н	Н	Н	Н	Н	-	-	Н	Н	-	-	Н	М -	Н
O-6: Develop a microsystem for a specific application		3	80	80		Н	Н	Н	Н	Н	-	-	Н	Н	-	-	Н	М -	Н

Du	ration	Micromachining Technology	Mechanical Microsensors	Microactuators	Microfluidics	Interface Circuitry and Microsystems
(i	nour)	9	9	9	9	9
0.4	SLO-1	Introduction	Introduction Introduction Intro		Introduction	Introduction
S-1	SLO-2	Bulk Micromachining	Automotive	Actuators: Transducers with Mechanical Output	Properties of Fluids	Microsensor Systems
S-2	SLO-1	Wet Etching	Computers and Peripherals	Transduction Mechanisms	Volumes and Length Scales	Microsensor System Applications - Automotive Sensors
3-2	SLO-2	High-Aspect-Ratio Micromachining	Consumer Products	Scaling Advantages and Issues	Mixtures, Physical Properties	Biomedical Sensors
S-3	SLO-1	Surface Micromachining	Medical and Biological Applications	Electrical Microactuators	Vapour Pressure, Surface Tension	Sensors for Household Appliances, Building Control
3-3	SLO-2	Basic Process Sequence	Inertial Sensors	Electrostatic Forces	Electrical Properties, Optical Properties, Transport Phenomena	Industrial Control
S-4	SLO-1	Deposition , Sputtering and Etching	Accelerometers	Electrostatic Systems	Physics of Microfluidic Systems	Environmental Sensors
3-4	SLO-2	Epi-Micromachining	Yaw-Rate Sensors	Forces in Electrostatic Systems	Navier-Stokes Equations	Interface Circuit Architecture
S-5	SLO-1	SIMPLE, SCREAM	Pressure Sensors	Scaling Properties	Laminar Flow, Dynamic Pressure	Requirements and Specifications
3-3	SLO-2	Black Silicon, MELO	Fundamentals	Electrostatic Microactuator Configurations	Fabrication Technologies	Analog Front-End

S-6	SLO-1	Porous Silicon	TRUIK-MICTOMACDIDED Pressure Sensors	Gap-Closing Electrostatic Microactuators& Examples	Silicon, Plastics,	Voltage Output - Current or Charge Output
3-0	SLO-2	SIMOX		Constant-Gap Electrostatic Microactuators& Examples	Quartz, Glass	Impedance Variation
S-7	SLO-1	Epi-Po1y	Signal Generation	Hybrid Electrostatic Microactuators	Microarrays	A/D Converter
3-1	SLO-2	Release and Stiction			Concept, Fabrication, Particle-Based Microarray Concepts	Types of converters
	SLO-1	IC Compatibility Issues	Linking the Macro World to the Micro World	Piezoelectric Microactuators	Micropumps	Digital Processing and Output Interface
S-8	SLO-2	Compatible Bulk Micromachining	Fabrication	Piezoelectric Energy Density	Microdisplacement Pumps, Charge- Induced Pumping Mechanisms, Other Pumping Mechanisms	Digital Signal Processing
S-9	SLO-1	Compatible Surface Micromachining		Piezoelectric Microactuator Configurations & Design Issues	Microanalytical Chips	Wired Output Interfaces
3-9	SLO-2	Compatible Epi-Micromachining	I Lost and Calibration		Lab-on-a-Chip Systems, Chip-Based Capillary Electrophoresis	Wireless Output Interfaces

Learning	1.	Jan G. Korvink, Oliver Paul, "MEMS: A Practical Guide to Design, Analysis and Applications", William Andrew, Inc. & Springer, 2006	4. 5	<u>Julian W. Gardner</u> , "Micro sensors, MEMS, and Smart Devices", John Wiley & Sons Inc, 2001 John A. Pelesko, "Modeling MEMS and NEMS", CRC Press; 1stedition, 2002
Resources	2.	Chang Liu, "Foundations of MEMS", Pearson; 2 nd edition, 2011	6.	Stephen Beeby, "MEMS Mechanical Sensors", ARTECH HOUSE, INC 2004
	3.	Mohamed Gad-el-Hak, "MEMS: Design and Fabrication", CRC Press; 1st edition, 2005.		

Learning Assessment											
	Bloom's	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
	Level of Thinking	CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)		Final Examination (50% weightage)	
	Level of Thirtking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyse										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

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2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. D. Nedumaran, Madras University, dnmaran@gmail.com	2. Dr. A. Vimala Juliet, SRMIST					

Course	18ECE387T	Course	MICDO SENSODS AND SMADT DEVICES	Course	E	Professional Elective	L	T	Р	С
Code	10ECE3071	Name	WICKO SENSORS AND SWART DEVICES	Category	E	Professional Elective	3	0	0	3

Pre-requisite Courses	Co-requisite Courses	Nil	Progressive Courses	
Course Offering Department	Electronics and Communication Engineering	ing Data Book / Codes/Standards	Nil	

Codise Offering Department Electronics and Communication Engineering Data Book / Codes/Cod	1 411																		
Course Learning Rationale (CLR): The purpose of learning this course is to:		Learning							Progi	ram L	_earn	ing O	utcon	nes (F	PLO)				
CLR-1: To realize the importance of micro sensors and actuators	1	2	3		1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2: To learn the operating principle of various micro sensors											y.								
CLR-3: To analyze the applications of various micro fabrication techniques	Ē	(%)						arch			stainability								
CLR-4: To understand the different packaging techniques	(Bloom)	()	ıt (%)		dge		eut	ese			ain		Work		8				
CLR-5: To appreciate the significance of available MEMS based smart devices	g (B	enc	Attainment		we we	S	Development	Ä,	age	e	Sust				inance	ng			
CLR-6: To recognize recent developments and challenges in MEMS	hinking	rofici	tain		Ā	Analysis	svelc	sign,	l Us	Culture	× ×		Team	ţi	∞	arning			
	_ :=	Δ.			ring	Ana	& D	, De	T00	S CI	nen		<u>∞</u>	jca	Mgt.	g Le			
Course Learning Outcomes (CLO): At the end of this course, learners will be able to:	Level of	Expected	Expected		Engineering Knowledge	Problem	Design 8	Analysis,	Modern	Society &	Environm	Ethics	Individual	Communication	Project №	Life Long	PS0 - 1	PS0 - 2	PSO - 3
CLO-1: Appreciate the importance of sensors and actuators based on MEMS technology	3	80	75		Н	1	-		-	Ĥ	-	-	-	-	-	Н	Н	-	Н
CLO-2: Understand the fabrication and machining techniques of MEMS devices			70		Н	•	-	-	-	Н	-	-	-	-	-	Н	-	-	Н
CLO-3: Familiarize with the concepts of packaging and interfaces in MEMS devices			70		Н	Н	М	Н	М	Н	-	-	-	-	-	Н	Н	-	Н
CLO-4: Appreciate the significance of general micro fabrication processes	3	80	75		Н	Н	М	Н	М	-	-	-	Н	-	-	Н	-	-	Н
CLO-5: Differentiate between the working principle of various micro sensors			70		Н	-	М	-	Н	-	-	-	-	-	-	Н	-	-	Н
CLO-6: Analyze recently developed smart devices employing MEMS technology	3	80	70		Н	-	-	-	-	Н	-	-	-	-	-	Н	Н	-	Н

	ration		_			
(r	our)	9	9	y	9	9
S-1	SLO-1	Introduction to Microelectronics	Micro thermal Sensors-overview	Micro machining techniques	MEMS Packaging	Smart Devices-Overview
3-1	SLO-2	Evolution& History of MEMS	TEG and Thermopiles	Significance and types	Objectives in Packaging	Functionalities
S-2	SLO-1	Overview of Micro system technology	Micro radiation Sensors-overview	Bulk MMC-overview	Flip chip assembly	Features & requirements
3-2	SLO-2	Broad applications of Micro systems	Implementation	Principle and block diagram	Ball grid array	Broad applications
S-3	SLO-1	Miniaturization & Scaling laws	Micro mechanical Sensors-overview	Surface MMC-overview	wire bonding techniques	Airbag deployment
3-3	SLO-2	Micro devices -examples	Vibration sensor -Accelerometer	Principle and block diagram	Types	Tire pressure monitoring
S-4	SLO-1	Types of Micro Sensors	Micro pressure Sensors-overview	LIGA process-overview	surface bonding techniques	GPS-Gyro sensor
3-4	SLO-2	Types of Micro actuators	Parameter measurement	Principle and block diagram	Types	Micro Energy harvesters
S-5	SLO-1	Si and other substrates	Micro humidity Sensors-overview	Photolithography	sealing	Smart home automation
3-3	SLO-2	Special MEMS Materials& properties	Types of Sensing film & measurement	Process Description, implementation	Different types of sealing	MEMS devices in agriculture
S-6	SLO-1	Polymer materials	Micro SAW Sensors-overview	Ion implantation and oxidation	Process design	Blood pressure monitor
3-0	SLO-2	Electro active polymers	Implementation	Process Description, implementation	Block diagram	Heart Parameter monitors

0.7	SLO-1	Shape memory alloys	Micro magnetic Sensors-overview	PVD-CVD	Interferences	RF MEMS technology
S-7	SLO-2	Shape memory polymers	Si gnificance & measurement	Process Description, implementation	Types of interferences	Optical Mirrors
S-8	SLO-1	Piezoelectric materials	Micro bio chemical Sensors-overview	Wet and dry etching	Electronic Interfacing	Micro fluidics
3-0	SLO-2	Ceramic materials	Parameter measurement	Isotrophic and Anisotrophic	Electro mechanical interfacing	LOC module
S-9	SLO-1	Case study-1	Micro optical Sensors-overview	Case study-1	Case study-1	Case study-1
3-9	SLO-2	Case study -2	Types & Implementation	Case study -2	Case study -2	Case study -2

Learning Resources	 Marc Madou, "Fundamentals of Microfabrication" CRC Press Tai Ran Tsu, "MEMS and Microsystems: Design Manufacture", Tata McGraw Hill 	3. Vardhan Gardener,"Micro sensors and smart devices", John Wiley & Sons
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Learning Asses	Learning Assessment												
	Bloom's			Conti	nuous Learning Ass	essment (50% weig	htage)			Final Evamination	n (50% weightage)		
	Level of Thinking	CLA –	1 (10%)	CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#		FIIIai Examination	i (50 % weightage)		
	Level of Thirking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice		
Level 1	Remember	30 %		30 %		30 %	_	30 %		30%			
Level I	Understand	30 /0	-	30 /0	-	30 /0	-	30 //	-	3070	-		
Level 2	Apply	40 %	_	40 %	_	40 %	_	40 %	_	40%	_		
Level 2	Analyze	40 /0	-	40 /0	-	40 /0	-	40 /0	-	4070	-		
Level 3	Evaluate	30 %		30 %	_	30 %		30 %		30%			
Level 3	Create	30 /0	-	30 /0	-	30 /0	-	30 //	-	3070	-		
	Total	100) %	100 %		10	0 %	100	0 %	100 %			

[#] CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. D. Nedumaran, Madras University, dnmaran@gmail.com	2. Mrs. R. Bakiya Lakshmi, SRMIST

B. Tech in Electronics and Communication Engineering

(with Specialization in Instrumentation Engineering)

2018 Regulations

Open Elective Courses (O)

Department of Electronics and Communication Engineering SRM Institute of Science and Technology SRM Nagar, Kattankulathur – 603203, Kancheepuram District, Tamilnadu

Course Code	18ECO101T	Course Name	Short-Range Wireless Communication	Course	0	Open Floative	L	T	Р	С
Course Code	10ECO1011	Course Name	Short-Range wheless communication	Category	0	Open Elective	3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Co.	mmunication Engineering	Data Book / Codes/ Standards		Nil

Course L	earning Rationale (CLR): Understand the concept of Short-range Wireless Communication							
CLR-1:	Overview of different modulation scheme and wireless system							
CLR-2:	To understand the various components used to implement a short-range radio system.							
CLR-3:	Analysis of the various kinds of transmitters and receivers used for Short-range Wireless Communication.							
CLR-4:	To know about regulations and standards of ISM band communications							
CLR-5:	Design and analysis of short-range radio like UWB and Visible light.							

	L	earnin	g	
	1	2	3	
of radio	vel of Thinking (Bloom)	pected Proficiency (%)	pected Attainment (%)	

				Pro	ogram	Learn	ing O	utcom	es (PL	.0)				
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modem Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO-1: Professional Achievement	PSO – 2: Project Management Techniques	PSO – 3: Analyze & Research
L	-	-	-	-	-	-	-	-	-	-	-	-	Н	-
-	-	М	L	-	-	-	-	-	-	-	-	Н	-	-
-	•	Τ	М	-	-	-	ı	ı	-	-	ı	-	Н	1
М	•	•	-	-	-	-	-	-	-	-	1	М	-	•
-	1	L	М	-	-	-	1	1	-	-		-	-	Τ

	The purpose of this course is to introduce practically all aspects of radio	of Think	ed Pro	ed Atta		
Course L	earning Outcomes (CLO): communication including wave propagation, antennas, transmitters, receivers, design principles, telecommunication regulations		Expected	Expected		
CLO-1:	CLO-1: To cover the various forms of signals used for information transmission and modulation, and overall wireless system properties.					
CLO-2:	2	85	75			
CLO-3:	CLO-2: To present various component types that can be used to implement a short-range radio system. CLO-3: To describe the various kinds of transmitters and receivers.					
CLO-4:	2	85	80			
CLO-5:	To covers some of the most important new developments in short-range radio like UWB and Visible light.	2	85	75		

Dum	ation (boun)	Wireless Systems	Baseband Coding basics	RF transceivers	Wireless standards	Optical wireless Technologies
Dura	ation (hour)	9	9	9	9	9
S-1	SLO-1	Introduction to wireless systems	Types of Antennas-Dipole, groundplane, loop	RF Receivers- Introduction	Technical Background to the WPAN Concept - Regulation and Standardization Issues	Fundamentals of UROOF Technologies
	31 U-/	Reasons for the Spread of Wireless Applications	Helical, Patch antennas	RF Source-Frequency control	European Consortium: Overview	Conversion from RF to Optical Domain
S-2	SLO-1		Antenna Characteristics-Impedence, directivity and gain, Effective area	Modulation types	- PAN scenarios in the 151 Magnet project	Conversion from Optical to RF Domain
3-2	SLO-2	Wireless Applications	Polarization, Bandwidth, Antenna factor	Amplifiers		Optical Microwave Mixing Used for UWB Over Systems
S-3	SI O-1		Baseband Data Format and Protocol - Radio Communication Link Diagram	Impedance matching in transmitter and receivers	Frequency Regulation and Standardization Issues - Optional UM4 usage models issued from the IEEE802.15.3c TG	Integrated UROOF Transceiver (IUT)
	SI ()-/	Elements of Wireless Communication Systems-Receiver	Code Hopping	Filtering	Flexible antenna gain, 60 GHz regulation status for wireless transmissions.	Mixed Wireless-wired UROOF Channel, Carrier-to-noise Ratio
S-4	SLO-1	Wireless Local Area Networks (WLAN)-WIFI	Baseband Coding-Digital systems	SAW band pass filter matching	Channel Propagation Characterization and Modeling- 60 GHz Propagation Measurements	Laser and Photodetector Noise Baseline,
	SLO-2	Network Architecture	Wireless Microphone System		Propagation Channel Characterization	Clipping Distortion Implication , Latency
S-5	SLO-1	Bluetooth Transceiver	RF Frequency and Bandwidth-factors	ASH Receiver	Multipath Propagation Modeling	Modelling the Propagation through the Fibre

	SLO-2	Bluetooth Modes	Propagation characteristics	, ,	France Telecom Propagation Channel Models	Analysis of UWB Technologies for UROOF- Comparing UWB Technologies for Radio-over- fibre
S-6	SLO-1	Zigbee Architecture, Frame Structure	Modulation types	, ,	MSK-Based System for LOS Gb/s Communications	MB-OFDM Over Multimode Fibre
3-0	SLO-2	Applications and conflicts	Modulation for digital event communication			All-optical Generation of Ultra-wideband Impulse Radio
S-7	SLO-1	Ultra-wideband Technology-Bit Sequence detection	Continuous Digital Communication	Silner neternavne Receiver- Uneration		Operation Principles and Theoretical Approach
3-1	SLO-2	UWB Block Diagram	Advanced Digital Modulation		System architecture for an OFDM-based system to operate in a NLOS channel.	VLC Link –Transmitter
	SLO-1	Wireless Modules-Japan, UK, USA	Spread Spectrum-DHSS	Direct Conversion Receiver- Operation	System Design Aspects-Channel Plan	The VLC Channel
S-8	SLO-2	Wireless Modules-Austria, Honeywell, Norway	Spread Spectrum-FHSS		60 GHz Channel Characteristics, Baseband Modulation: OFDM versus Single Carrier	Receiver, Modulation
	SLO-1	FCC Regulations-Terms and definitions	RFID-transceiver	Software radio operation	60 GHz Analog Front-End Architectures	Potential Applications
S-9	SLO-2	Nomenclature for defining Emission, modulation and transmission	Design issues for RFID	Repeaters	Multiple Antenna Technologies	Challenges

Learning Resources

- Alan Bensky, "Short-range Wireless Communications-Fundamentals of RF system design and Applications", Elsevier Inc, 2004
- Antti V. Raisanen, Arto Lehto, "Radio engineering for wireless communication and sensor applications", Artech House, 2003
- Rolf Kraemer and Marcos Katz, "Short-range wireless communications emerging technologies and applications", Wiley WWRF series, March 2009
- Shlomi Arnon, John Barry, George Karagiannidis, Robert Schober, Murat Uysal, "Advanced Optical Wireless Communication Systems", Cambridge University Press, 2012

Learning Ass	sessment											
	Bloom's			Conti	nuous Learning Ass	essment (50% weig	htage)			Final Evamination	(E00/ weightegs)	
	Level of Thinking	CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4	(10%)#	Final Examination (50% weightage)		
	Level of Thirking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	
Level 1	Remember Understand	40 %	-	30 %	-	30 %	-	30 %	-	30%	-	
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-	
Level 3	Evaluate Create	20 %	-	30 %	-	30 %	-	30 %	-	30%	-	
	Total 100 % 100 %		10	0 %	100) %	100 %					

[#] CLA - 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, kumaranuj anii@gmail.com	1. Dr. Meenakshi, Professor of ECE, CEG, Anna University, meena68@annauniv.edu	1. Dr. J. Subhashini, SRM IST
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	

		_		Course	_		L	Τ	Р	С
Course Code	18EC0102J	Course Name	Electronic Circuits and Systems	Category	0	Open Elective	2	0	2	3

Pre-requisite Courses	Nil Co-requisite Courses		Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communic	cation Engineering	Data Book / Codes/ Standards		

	Learning Rationale (CLR): The purpose of learning this course is to:	L	.earni	ng					Prog	ram L	.earnii	ng Ou	utcom	es (P	LO)			
CLR-1 :	Provide a basis for understanding semiconductor material, how a pn junction is formed and its principle of operation	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14 15
CLR-2 :	Describe the basic structure, operation and characteristics of transistors BJTs and FETs, and discuss their use as a switch and an amplifier																nent	_
CLR-3:	Learn the basics of op-amp: the principle, operation, characteristics and fundamentally important circuits							υ			₹						ever	ment
CLR-4:	Describe and analyze the basic operation of sinusoidal oscillators and use a 555 Timer in an oscillator application.	(Bloom)	cy (%)	nt (%)	edge		nent	Researc	ø.		Sustainability		Work		Finance		al Achievem	Management
CLR-5 :	Learn the fundamentals of analog and digital communication, networking, radio transmission and mobile telephones	Thinking (F	roficien	Attainment	Knowledge	Analysis	Development	esign, F	Tool Usage	Culture			Team	Sommunication	∞	ong Leaming	Professional	Project Mes
CLR-6:	Encourage the learner to assemble and test real circuits in the laboratory	Ë	P P		Engineering	۸Pu	∞	Ď,	2	∞ŏ	Environment &		a &	nica	Mgt.	g Le	Pro	2: Pragues 3: Ar
		elof	ecte	Expected	inee	Problem,	Design	llysis	Modern	Society	ion	S	Individual	n W	Project		1	1 .5 1
Course I	.earning Outcomes (CLO): At the end of this course, learners will be able to:	Level	Exp	Exp	Eng	Pro	Des	Analy	₩ W	S	Ē	Ethics	Indi	Cor	Pro	Life	PSO.	PSO Tech PSO
CLO-1 :	Understand the operation, characteristics, parameters and specifications of semiconductor diodes and demonstrate its important applications	1	80	70	L	L		-	-	-	-	-	-	-		-	-	- -
CLO-2:	Review the transistor (BJT & FET) construction, operation, characteristics and parameters, as well as its application in amplification and switching.	1	80	70	L	L		-	-	-	-	,	-	-				- -
CLO-3:	Identify different configurations of op-amp analyze the parameters of op-amp and	1	80	70		ı												
	observe the frequency response of operational-amplifier.				L	L	-	-	-	-	-	-	-	•	-		-	
CLO-4:	Understand & demonstrate different applications based on operational-amplifier and special linear ICs	1	80	70	L	L		1	-	-	-	-	-	-	-		-	- -
CLO-5:	derstand the basic concepts and techniques of telecommunication systems and networks		80	70	L	Ĺ		-	-	-	-	-	-	-			-	
CLO-6:	Understand how circuit behavior can be studied with a computer, using a circuit simulation software	2	90	80	-	-	Н	-	Н	-	-	-	-	L	-	M	L	- -

		Learning Unit / Module 1 (12)	Learning Unit / Module 2 (12)	Learning Unit / Module 3 (12)	Learning Unit / Module 4 (12)	Learning Unit / Module 5 (12)
Duratio	n (hour)	Active Discrete Components & Circuits – I	Active Discrete Components & Circuits – II	Linear Integrated Circuits	Oscillators and Timers	Telecommunications
S-1	SLO-1	Conduction in semiconductors	JFETs: Structure & Operation	Introduction to Op-amp	RC Phase-Shift oscillator Operation	Analog & Digital Communication: Stages in telecommunication systems
	SLO-2	Conduction in diodes	Characteristics & Parameters	Basic op-amp and its characteristics	& Design	Carriers and Modulation
S-2	SLO-1	Basic operation of PN junction diode	JFET Biasing (Voltage-Divider Biasing)	op-amp modes	Wein bridge Oscillator operation	Carriers and Modulation
3-2	SLO-2	VI Characteristics of diode	CS-JFET Amplifier operation	parameters	& Design	Pulse Modulation
S-3	SLO-1 SLO-2	Lab-1: VI Characteristics of PN	Lab-4: Design & Analysis of CE BJT	Lab-7: Negative Feedback op-amp	Lab-10: Analysis & Design of RC	
S-4	SLO-1 SLO-2	Junction Diode	Amplifier	circuits	Oscillators	Lab-13: Demonstration of AM & FM
S-5	SLO-1	Applications of diode: HWR & FWR	MOSFETs: Structure	Op-amp circuits: Scale changer, adder, subtractor	LC oscillators operation: Hartley Oscillator	Pulse Modulation
3-3	SLO-2	Clippers & Clampers	Operation	HWR & FWR	Colpitts Oscillator	Digital Transmission, Frequency Division MultiplexingTime Division Multiplexing
S-6	SLO-1	Basic operation of Zener diode and its VI characteristics	Characteristics	Clipper &Clamper	555 Timer IC: Basic Operation	Networks: RS-232, circuit switching

	SLO-2	Zener diode as a voltage regulator	Parameters	Log & Antilog amplifiers	Astable Operation	Message switching, TCP/IP
S-7	SLO-1					
3-1	SLO-2	Lab-2: VI Characteristics of Zener	Lab-5: Design & Analysis of CS-JFET	Lab-8: Op-amp Circuits-I	Lab-11: 555 Timer Operation &	Lab-14: Demonstration of Pulse
S-8	SLO-1	Diode	Amplifier	Lab-o. Op-amp Circuits-i	Applications	Modulation
3-0	SLO-2					
S-9	SLO-1	BJTs: Structure & Operation	MOSFET as an amplifier	Instrumentation amplifier	Monostable Operation	Radio Transmission: Electromagnetic Spectrum, ground waves, sky waves
	SLO-2	Characteristics & Parameters	MOSFET as a switch	Comparator	Applications of 555 Timer	antennas, directional transmissions,
S-10	SLO-1	CE BJT amplifier operation	MOSFET Biasing (Voltage-Divider Biasing)	Comparator applications	Applications of 555 Timer	Transmitters, Receivers
	SLO-2	Differential amplifier operation	CS-MOSFET amplifier operation	Schmitt trigger	Voltage-Controlled Oscillators	Mobile telephones
S-11	SLO-1					
3-11	SLO-2	Lab-3: Applications of PN Junction	Lab-6: Design & Analysis of CS-	Lab-9: Op-amp Circuits-II	Lab-12: VCO Operation	Mini Project / Model Practical
S-12	SLO-1	diode and Zener diode	MOSFET Amplifier	Lab-9. Op-amp Gircuits-II	Lab-12. VCO Operation	Examination
J-12	SLO-2					

Learning	1.	Owen Bishop, "Electronic Circuits and Systems", 4th edition, Elsevier, 2011.	3.	Paul Scherz, "Practical Electronics for Inventors", McGraw-Hill, 2000.
Resources	2.	Harry Kybett, Earl Boysen, "All New Electronics", 3rd edition, Wiley, 2008.		

Learning As	sessment												
	Dia a mai'a			Conti	nuous Learning Ass	essment (50% weig	htage)			Final Examination	n (EOO/ waightaga)		
	Bloom's	$(1\Delta = 1/10\%)$		CLA –	CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#		Final Examination (50% weightage)		
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice		
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%		
Level I	Understand	20%	20%	10%	10%	13%	13%	10%	15%	13%	13%		
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%		
Level 2	Analyze	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%		
1 1 2	Evaluate	400/	400/	450/	450/	450/	450/	450/	450/	450/	450/		
Level 3	Create	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%		
	Total 100 % 100 % 100 %								0 %		-		

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2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	2. Dr. Rajesh Agarwal, SRM IST

Course	18FC∩103T	Course	Modern Wireless Communication System	Course	0	Open Floative	L	T	Р	C
Code	10ECO1031	Name	Modern Wireless Communication System	Category	U	Open Elective	3	0	0	3

Pre-requisite Courses		Nil	Co-requisite Courses		Nil	Progressive Courses	Ni	il
Course Offering I	Department	Electronics and Con	mmunication Engir	neering	Data Book / Codes/Standards		Nil	

Course L	earning Rationale (CLR):	The purpose of learning this course is to:					
CLR-1:	Learn to analyze the transm	ission of various wireless communication systems					
CLR-2:	Understand the fundamentals of various networks in wireless communication						
CLR-3:	Inderstand the techniques involved in personal communication services.						
CLR-4:	ntroduce various wireless systems for 3G and future communication						
CLR-5:	Learn to analyze wireless ne	etworks for short-range communication					
CLR-6:	Understand the Fundamenta	als, Techniques and Networks of Wireless Communication Systems					
CLIN-U.	Understand the Fundament	ns, recriniques and reciworks or wheless communication systems					

Course Lo	earning Rationale (CLR):	The purpose of learning this course is to:	Le	earnii	ng
CLR-1:	Learn to analyze the transm	ission of various wireless communication systems	1	2	3
CLR-2:	Understand the fundamenta	ls of various networks in wireless communication	(-	,	_
CLR-3:	Understand the techniques i	nvolved in personal communication services.	(Bloom)	Proficiency (%)	(%):
CLR-4:	Introduce various wireless s	ystems for 3G and future communication	<u>B</u>	nc)	Attainment
CLR-5:	Learn to analyze wireless ne	etworks for short-range communication	ing	icie	<u>=</u>
CLR-6:	Understand the Fundamenta	als, Techniques and Networks of Wireless Communication Systems	Thinking	Prof	₽
			of∏	ed F	
Course Lo	ourse Learning Outcomes (CLO): At the end of this course, learners will be able to:		Levelo	Expected I	Expected
CLO-1:	Discuss the fundamentals of	transmission in wireless systems	2,3	80	75
CLO-2:	Provide an overview of vario	us approaches to communication networks	2,3	80	85
CLO-3:	Study the numerous differen	t-generation technologies with their individual pros and cons	2,3	85	85
CLO-4 :	0-4: Discuss about the principles of operation of the different access technologies like FDMA, TDMA, SDMA and CDMA and their		2,3	85	80
	pros and cons.				
CLO-5:		pile data services and short-range networks.	2,3	85	80
CLO-6:			2,3	85	80

	Program Learning Outcomes (PLO)													
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO-1: Professional	PSO – 2: Project Management Techniques	PSO – 3: Analyze & Research
-	-	-	Н	-	-	-	-	-	-	-	-	Н		
-	-	-	Н	-	-	-	-	-	-	-	-	-	-	Н
-	-	-	Н	-	-	-	-	-	-	-	-	М	-	Н
-	-	-	Н	-	-	-	-	-	-	-	-	М	-	Н
-	-	-	-	-	-	-	-	-	-	-	-	-	-	Н
-	-	-	-	-	-	-	-	-	-	-	-	Н	-	-

	ration	Transmission Fundamentals	Network Concepts	Personal Communication Services	3G and Beyond	Mobile Data Services and Short- Range Network
(I	nour)	9	9	9	9	9
S-1	SLO-1	Cellphone Generations	Communication Networks	Personal communication Introduction, HSCSD, GPRS, D-AMPS, CDMA One, CDMA Two, Packet Data Systems	3G Introduction	Mobile Data Services Introduction Messaging, wireless web, WAP, site design Short-Range Wireless Networks: Unlicensed spectrum, WLANs, cordless telephony, IrDA, Bluetooth Smart Phones: Future phones, mobile OSs, smart phone applications.
	SLO-2	1G and 2G	LANs	GSM	IMT-2000 Introduction	Data Services
S-2	SL0-1	2.5G	MANs	GSM	IMT-2000	Messaging
3-2	SLO-2	3G	WANs	HSCSD	IMT-2000	Wireless web
S-3	SLO-1	4G Transmission Introduction	Circuit switching	HSCSD	W-CDMA Introduction	WAP
3-3	SLO-2	4G Transmission Fundamentals	Packet switching	GPRS	W-CDMA	Site design
S-4	SLO-1	Time domain concepts	ATM Cellular Networks Introduction	GPRS	CDMA 2000 Introduction	Short-Range Wireless Networks

	SLO-2	Frequency domain concepts	Cells	D-AMPS	EDGE	Unlicensed spectrum
S 5-6	SLO-1 SLO-2	Radio Media	Duplexing	D-AMPS	EDGE	WLANs
S-7	SLO-1	Analog Vs Digital	Multiplexing	CDMA Introduction	Wi-Fi Introduction	Cordless telephony
3-1	SLO-2	Channel capacity	Voice coding	CDMA One	Wi-Fi	IrDA
S-8	SLO-1	Transmission media	Multiple Access Techniques: FDMA	CDMA One	WiMAX Introduction	Bluetooth Smart Phones
3-0	SLO-2	Signaling Schemes	TDMA, SDMA	CDMA Two	WiMAX	Future phones
S-9	SLO-1	Carrier-based signaling,	CDMA	CDMA Two	OFDM	Mobile OSs
3-9	SLO-2	Spread-spectrum signaling	Spectral efficiency	Packet Data Systems	МІМО	Smart phone applications

Learning Resources

- Simon Haykin, David Koilpillai, Michael Moher," Modern Wireless Communication", 1/e, Pearson Education, 2011
- Rappaport T.S, "Wireless Communications: Principles and Practice", 2nd edition, Pearson education.
- Andrea Goldsmith, "Wireless Communications", Cambridge University Press, Aug. 2005.
 Andy Dornan, "The essential guide to wireless communications applications: from cellular systems to Wi-Fi", 2nd Edition, Prentice Hall, 2002
- lan F.Akyildiz, David M. Gutierrez Estevez, and Elias Chavarria Reyes, "The evolution of 4G cellular systems: LTE advanced", Physical communication, Volume 3, No. 4, pp. 217-298, Dec. 2010
- 6. William Stallings, "Wireless Communication & Networking", Pearson Education Asia, 2004
- 7. Andrea .F.Molisch, "Wireless communications", 2nd edition, Wiley Publications.

Learning Asses	ssment											
	Bloom's				Final Examination (50% weightag							
	Level of Thinking	CLA -	1 (10%)	CLA –	2 (15%)	CLA –	3 (15%)	CLA – 4 (10%)#		i iliai Examination (30 % weightage)		
	Level of Thirtking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	
Level 1	Remember	30 %	_	30 %	_	30 %	_	30 %	_	30%	_	
LOVOIT	Understand	00 70		00 70		00 70		00 70		0070		
Level 2	Apply	40 %	_	40 %	_	40 %	_	40 %	_	40%	_	
LCVCI Z	Analyze	40 70		70 70		40 70		40 70		4070		
Level 3	Evaluate	30 %	_	30 %	_	30 %	_	30 %	_	30%	_	
Level 3	evel 3 Evaluate Create		-	30 /0	-	30 /0	_	30 70	-	3070	-	
	Total	10	0 %	100	0 %	10	0 %	100	0 %	10	0 %	

[#] CLA - 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

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2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	

Course Code	18ECO104J	Cauraa Nama	Audia and Chasah Cignal Processing	Course	0	Open Floative	L	T	Р	С
Course Code	10ECO 1043	Course Name	Audio and Speech Signal Processing	Category	0	Open Elective	2	0	2	3

Pre-requisite Courses		Nil	Co-requisite Courses		Nil	Progressive Courses	Nil
Course Offering Department		Electronics and C	ommunication Engine	ering	Data Book / Codes/Standards		Nil

Course Learn	ing Rationale (CLR): The purpose of learning this course is to:	I	earni	ng					Pro	gram	Learni	ing Οι	ıtcom	s (PL	0)				
CLR-1:	CLR-1: To explore about Speech signal processing				1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	To explore about the human auditory system		5	Ħ	Φ								بج					dnes	
CLR-3:	Feature Extraction of Speech signal using Time characteristics		_	ner	edg		nen		ø.				Work		inance		nal	niqu	
CLR-4:	Frequency characteristics of Speech signal	ķ.	roficie	Attainme	ow.	.8	lop	É	sagı	<u>e</u>			am	_	Fina	ing	ssic	act Tech	Ze
CLR-5:	Provide a foundation for developing applications in this field.	Thinking	F	Att	Engineering Knowledge	nalysis	Development	Design,	ool Usage	Culture	nt & ty		<u>-e</u>	ation	∞	earning	rofe	roje nt T	nal
CLR-6:	Understand the concept of speech processing both in time and frequency domain	of T	eg	cted	ing	¥	∞	ر م بی		∞ರ	ment ability		<u>8</u>		Mgt.	ong L	1: P	2: P	3: A
		l - 8	96) GC	in ex	Problem	Design	Analysis, Research	Modem	ociety	iron tain	S	vidu	ommunic	roject		. – C	i g	1 8
Course Learn	ing Outcomes (CLO): At the end of this course, learners will be able to:	Leve	Expe (%)	Exper (%)	Eng	Pro	Des	Ana Res	Мос	Soc	Environme Sustainab	Ethi	Indiv	S	Proj	Life	PS(Ach	PS(Mar	PSO ℜ
CLO-1:	Understand the functioning of the human vocal and auditory systems in terms of signal processing	1	90	68	Н		Н		Н				-	-	-	-	М	Н	
CLO-2:	Analyze the function of feature extraction in speech and audio signal processing using Time Domai Characteristics	2	85	67	Н			Н				M	-	-	-	-	М		Н
CLO-3:	Understand the frequency characteristics of speech signal	2	85	68	Н		Н			M		М	-	-	-	-		Н	Н
CLO-4:	Understand the Digital models for speech signal	1&2	85	65	Н		Н	Н					-	-	-	-	Н	М	
CLO-5:	CLO-5: Understand the elements of music		85	66			Н		I			I	-	-	-	-	Н		Н
CLO-6:	Understand Speech signal processing in time and frequency domain and their models.	1,2,3	85	68	Н		Н			М		Н	-			-		М	М

Duratio	on (hour)	Learning Unit / Module 1 Basic Audio Processing	Learning Unit / Module 2 Human auditory system	Learning Unit / Module 3 Speech Signal Analysis in Time Domain	Learning Unit / Module 4 Speech Signal Analysis in Frequency Domain	Learning Unit / Module 5 Speech and Audio processing applications				
		12	12	12	12	12				
S-1	SLO-1	Introduction to Digital audio	Human auditory system	Speech signal analysis	Short Time Fourier analysis	Introduction to Speech recognition				
3-1	SLO-2	Capturing and converting sound	Human auditory system	Speech signal analysis	Short Time Fourier analysis	Introduction to Speech recognition				
S-2	SLO-1	Sampling of sound wave	simplified model of cochlea	Segmental, sub-segmental levels	Filter bank analysis	Complete system for an isolated word recognition with vector quantization /DTW				
3-2	SLO-2	Handling audio in MATLAB	simplified model of cochlea	Suprasegmental levels	Formant extraction and Pitch extraction	Complete system for an isolated word recognition with vector quantization /DTW				
S-3	SLO-1 SLO-2	Lab 1: Read & write a speech signal, Record a speech signal, playback,	Lab 4: Short-term energy of a speech	Lab 7: Estimation of pitch period using	Lab 10: Phoneme-level segmentation	Lab 13: Compute pitch period and				
S-4	SLO-1 SLO-2	convert into a wave file, plot the speech signal, and spectrogram plot.	signal	simplified inverse filter tracking (SIFT) algorithm	of speech	fundamental frequency for speech signal				
S-5	SLO-1	Normalization	Sound pressure level and loudness	Time domain parameters of speech signal	Homomorphic speech analysis	Complete system for speaker identification, verification				
	SLO-2	Audio processing	Sound pressure level and loudness	Time domain parameters of speech signal	Cepstral analysis of Speech	Introduction to speech enhancement				
S-6	SLO-1	Segmentation	Sound intensity and Decibel sound levels	Methods for extracting the parameters Energy	Formant and Pitch Estimation	Introduction to speech enhancement				
3-0	SLO-2	Analysis of window sizing	Sound intensity and Decibel sound levels		Linear Predictive analysis of speech	Speech enhancement using spectral subtraction method				

S- 7	SLO-1 SLO-2	Lab 2: Convert into a wave file, plot the	Lab 5: Short-time Fourier transform		Lab 11:To study the quantization and	Lab 44 Obas 44 company la salaria			
S-8	SLO-1 SLO-2	speech signal, and spectrogram plot	magnitude spectrum		aliasing effect of speech signal	Lab 14: Short term speech analysis			
S-9	SLO-1	Visualization	Concept of critical band	LZero crossina Rate	Autocorrelation method, Covariance method	Introduction to Text to speech conversion			
5-9		Sound generation	Uniform filter bank , Non- uniform filter bank	Silence Discrimination using ZCR and energy	Solution of LPC equations	Introduction to Musical instrument classification			
S-10	SLO-1	Speech production mechanism, Charistics of speech	Mel scale and bark scale,		Durbin's Recursive algorithm, Application of LPC parameters	Musical Information retrieval.			
3-10	SLO-2	Understanding of speech			Pitch detection using LPC parameters, Formant analysis	Sample Programs			
S-11	SLO-1								
3 -11	SLO-2		Lab 6: (i)Linear prediction magnitude spectrum, (ii) (ii) Estimation of formant	using time-domain nitch synchronous	Lab 12:: Speech signal to symbol	Lab 15: Study of Praat			
S-12	020 .			overlap and add (TD-PSOLA) method	transformation using wavesurfer	Lab 10. Olddy Of Fraat			
J 1.2	SLO-2								

Learning	1.	lan McLaughlin, "Applied Speech and Audio processing, with MATLAB examples", 1st Edition, Cambridge University Press, 2009	3.	Rabiner,B.H.Juang, "Fundamentals of Speech Recognition", 2 nd Edition, Prentice-hall Signal Processing Series, April 1993
Resources	2.	Ben Gold, Nelson Morgan, Dan Ellis, Wiley, "Speech and Audio Signal Processing: Processing and Perception of Speech and Music", 2nd Edition, John Wiley & Sons, 01-Nov-2011.		Ken Pohlmann, "Principles of Digital Audio", 6th Edition, McGraw-Hill, 2007 A.R.Jayan, "Speech and Audio Signal Processing", ISBN: 978-81-203-5256-8, PHI Learning Pvt. Ltd, 2016.

Learning Ass	sessment												
	Bloom'sLevel of			Contin	uous Learning Ass	essment (50% wei	ightage)			Final Evamination	n /EOO/ waishtaga\		
	Thinking	CLA -	1 (10%)	CLA -	2 (15%)	CLA -	3 (15%)	CLA –	4 (10%)#	Final Examination (50% weightage)			
	ininking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice		
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%		
Level 1	Understand	2070	2070	1370	10/0	1070	1570	1570	1370	1370	1370		
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%		
Level 2	Analyze	2070	2070	2070	2070	2070	2070	2070	2070	2070	2070		
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%		
Level 3	Create	10%	10%	1370	1370	1370	1370	13%	13%	13%	13%		
	Total	10	0 %	10	0 %	10	0 %	100 %		10	0 %		

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, kumaranuj.anii@gmail.com	1. Dr. Meenakshi, Professor of ECE, CEG, Anna University, meena68@annauniv.edu	1. Dr. S. Dhanalakshmi, SRMIST
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Course Code	18ECO105T	Course	Undervister Acquetics Course		0 5 "	L	Т	Р	С
Course Code	10ECO1051	Name	Underwater Acoustics Category	0	Open Elective	3	0	0	3

Pre-requisite Courses	Nil Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engi	neering Data Book / Codes/Standards		Nil

Course L	earning Rationale (CLR): The purpose of learning this course is to:	Learning Program Learning Outco								utcor	nes (F	PLO)							
CLR-1:	Understand what is Sound Navigation and Ranging (SONAR) and how it can be used in underwater applications.	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2: Study about Ocean Acoustic Processing and sound wave propagation and analyze sea floor characteristics and ocean sounds.																	ent		
CLR-3: Understand about Underwater reverberation and how types of noises affects the underwater acoustics signal data analysis.								당			Sustainability						_	Management	Research
CLR-4:	Study about Acoustic transducers.	(Bloom)	ency (%)	(%)	ge		Ħ	Resea			ina		Work		9		Ac	nag	Res
CLR-5: Know which transducers can be used for underwater applications.				Jent	Wee .		bme	8	g		uste		N W		Finance	g.	ona	₩	∞ర
CLR-6: Understand the basic theory and signal processing application for underwater communication and navigation.				Attainment	ŝ	lysis	Development	ign	Usage	Culture	∞ర		Team	6	ĕ	Ë	SSi	Project	Analyze
		Thinking	Proficie	A#	g	Analysis		Design,	T00	D,	ent		8	icati		Le	o Lo	Pro es	
Course L	earning Outcomes (CLO): At the end of this course, learners will be able to:	Level of	Expected	Expected	Engineering Knowledge	Problem	Design &	Analysis,	Modern 7	Society &	Environment	Ethics	Individual &	Communication	Project Mgt.	Life Long Learning	PSO-1: F	PSO – 2: Techniou	PSO - 3:
CLO-1:	Acquire in-depth knowledge and analyze on Sound Navigation and Ranging (SONAR) equations and it characteristics.	L1	85	65	М	-	-	-	-	-	-	-	-	-	-	М	L		
CLO-2:	Analyze Ocean Acoustic Processing and sound wave propagation.	L2	85	65	М	Н	Н	Н	Н	-	-	-	-	-	-	L	Н	Н	Н
CLO-3: Acquire knowledge and analyze Underwater reverberation and various types of noises.			85	65	М		Н	Н	Н	-	-	-	-	-	-	L	Н	M	Н
CLO-4:	CLO-4: Acquire knowledge on working of underwater Acoustic transducers.			65	Н	Н	Н	Н	Н	-	-	-	-	-	-	L	Н	Н	Н
CLO-5:	CLO-5: Gain knowledge and apply SONAR concepts for underwater applications.			65	L		Н	Н	-	-	-	-	-	-	-	L	Н	M	Н
CLO-6:				65	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-

Duratio	on (hour)	Learning Unit / Module 1 Sound Navigation and Ranging (SONAR)	Learning Unit / Module 2 Ocean Acoustic Processing and sound wave propagation	Learning Unit / Module 3 Reverberation and Noises	Learning Unit / Module 4 Acoustic Transduction	Learning Unit / Module 5 SONAR Application
		9	9	9	9	9
S-1	SLO-1	Introduction to SONAR equation,	Processing ocean sound-Sampling rules	Reverberation-Scattering, back scattering strength and target strength	Piezoelectric transducer-Introduction	Echo sounder
		Source Intensity, Source Directivity	Spatial sampling and Temporal sampling	Surface and bottom scattering	Piezoelectric transducer-33-Mode longitudinal vibrator	Echo Sounder
	SLO-1	Transmission loss	Filter operations-Finite Fourier transformation	Volume scattering, bottom scattering, reverberation target strength	Piezoelectric transducer-33-Mode longitudinal vibrator	Sub-bottom profiling
S-2	SLO-2	Transmission loss	Filter operations-Time domain view of Band pass filtering. convolution operations, frequency domain	Calculation of reverberation for use in the sonar equation, Volume reverberation level	Electrostrictive transducers	Fishing sonars
S-3	SLO-1	Target Strength	Gated Signals-Dependence of Spectrum on ping carrier periodicity	Reverberation frequency spread and Doppler gain potential-Power spectral density of a CW pulse	Electrostrictive transducers	Side scan terrain mapping sonar
	SLO-2	Reflection Intensity Loss Coefficient	Power spectra of random signal-Signal having random characteristics, Spectral density,	Environmental frequency sampling	Magnetostrictive transducers	Side scan terrain mapping sonar
	SLO-1	Sea-floor Loss,	Radom signal simulations-Intensity spectral density, Spectral smoothing	Frequency spreading due to transmitter and receiver motion	Magnetostrictive transducers	Acoustic positioning and navigation
S-4	SLO-2	Sea-surface Loss	Matched filters and autocorrelation	Frequency spreading due to target, important observation with respect to reverberation	Electostatic Transducers	Acoustic positioning and navigation

	SLO-1		Sounds in the oceans-natural physical sounds and biological sounds	Noise-Ambient noise models	Electostatic Transducers	3D Imaging Processing-data model
S-5	SLO-2	Active and Passive Sonar Equations	Sound propagation in the ocean and underwater acoustic channel-Sound wave and vibration, velocity of sound	Ambient noise-seismic noise, ocean turbulence, shipping noise	Variable Reluctance Transducers	3D Imaging Processing-acquisition of 3D information
S-6	SLO-1		Sound propagation in the ocean and underwater acoustic channel-Sound wave velocity of sound	Wave noise, thermal noise	Variable Reluctance Transducers	3D Imaging Processing-matrix approach and real time systems
5-0	SLO-2		Wave and ray theories of underwater sound fields	Rain noise, temporal variability of ambient noise, depth effects of noise	Moving coil transducers	3D Imaging Processing-Image representation, Acoustic image processing
S-7	SLO-1	Active SONAR target strength	Wave and ray theories of underwater sound fields	Under ice noise	Moving coil transducers	3D Imaging Processing-Segmentation and reconstruction of underwater tubular structures
3-1	SLO-2	Active SONAR- reverberation, detection threshold			Equivalent circuits-Basics Circuit Resonance	3D Imaging Processing-Segmentation and reconstruction of underwater tubular structures
S-8	SLO-1	Active Sonar Sources- Source Level, Cavitation	Sound absorption in sea water and its characteristics	Self-noise-Flow noise	Circuit Q and Bandwidth	Acoustic communication-Cross attributes of the received signal
3-0	SLO-2	Near Field Interactions		Self-noise – Flow noise	Transducers as projectors-principle	Acoustic communication-channel transfer function
S-9	SLO-1	Physics of Shock Waves in Wate, Bubble Pulses	Lower boundary of acoustic channel and its characteristics	Self noise-turbulent noise coherence	Transducers as Hydrophones- principles of operations	Acoustic communication-combating multipath
S-8	SLO-2	Pros and Cons of Explosive Charges, Parametric Acoustic Sources	sound field in shallow water	Self noise-strumming noise	Transducers as Hydrophones- simplified equivalent circuit	Acoustic communication-diversity reception, equalization

	1. Richard P HODGES, "Underwater Acoustics – Analysis, Design and Performance of SONAR",
	Wiley 1 edition2010, ISBN 978-0-470-68875-
Learning	2. Rodney F W Coates, "Underwater Acoustics Systems", Macmillan New Electronics, Wiley, 1stedition
Resources	, 1990, ISBN 978-0-333-42542-8
	3. Robert S H Istepanian and MilicaStojanovic, "Underwater Acoustic Digital Signal Processing and
	Communication Systems", Springer, 2002 edition, ISBN 978-1-4419-4882-3

- 4. Charles H Sherman, John L Butler, "Transducers and Arrays for Underwater Sound", Springer; 2nd edition, 2016, ISBN-10: 0-387-32940-4 ISBN-13: 978-0387-32940-6

 5. Qihu Li, "Digital Sonar Design in underwater acoustics: Principles and applications", Springer, Zhejang University Press, 2012
- 6. Herman Medwin, Clarence S.Clay, "Fundamentals of Acoustical Oceanography", Academic Press,

Learning Assess	sment											
	Dlaam'a				Final Evamination	o (E00/ woightogo)						
	Bloom's Level of Thinking	CLA –	1 (10%)	CLA – 2	2 (15%)	CLA -	3 (15%)	CLA – 4	l (10%)#	Final Examination (50% weightage)		
	Level of Trilliking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	
Level 1	Remember	40 %		30 %		30 %		30 %		30%		
Level I	Understand	40 /0	-	30 /0	-	30 /0	-	30 /0	-	30 /0	_	
Level 2	Apply	40 %		40 %		40 %		40 %		40%		
Level 2	Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-	
Level 3	Evaluate	20.0/		30 %		30 %		30 %		30%		
Level 3	Create	20 %	20 %	30 %	-	30 %	-	30 %	-	30%	-	
	Total	100) %	100	100 %		100 %		100 %		0 %	

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			Course	_		L	T	Р	C
Course Code 18ECO106J	Course Name	PCB Design and Manufacturing	Category	0	Open Elective	2	0	2	3

Pre-requisite Courses	Nil	Co-requisite Courses Nil		Nil
Course Offering Departm	ent Electronics and Communic	ation Engineering	Data Book / Codes/ Standards	

Course Le	arning Rationale (CLR):	The purpose of learning this course is to:	Le	arning	ı	
CLR-1:	Explore the terminologies of	PCB design and Electronic components.	1	2	3	
CLR-2:		ther consideration involved in PCB design	Ē	(%)	(%)	
CLR-3:	Understand the PCB design	consideration for special application circuits	(Bloom)			
CLR-4:	Design a PCB layout using C	CAD tool) g	Proficiency	Attainment	
CLR-5:	Explore various PCB manufa	ncturing techniques	evel of Thinking	īg	ttair	
CLR-6:	CLR-6:					
Course Le	Course Learning Outcomes (CLO): At the end of this course, learners will be able to:					
CLO-1:	CLO-1: Identify the various types of PCB and electronics components packaging					
CLO-2:	Select suitable design and of	onsider appropriate parameters involved in PCB design	1,2	80	70	
CLO-3:	LO-3: Apply the appropriate design rules in designing PCB for special application circuits				70	
CLO-4:	CLO-4: Design and develop a PCB layout using CAD tool				70	
CLO-5:	LO-5: Identify and select the required PCB manufacturing technology				70	
CLO-6:	LO-6:					

				Pro	gram	Learn	ing O	utcom	es (PL	.0)				
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modem Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO-1: Professional Achievement	PSO – 2: Project Management Techniques	PSO – 3: Analyze &
Η			L											
M		L												
М			L											
М			М	Н										
L				Н										

		Learning Unit / Module 1	Learning Unit / Module 2	Learning Unit / Module 3	Learning Unit / Module 4	Learning Unit / Module 5
Duratio	n (hour)	12	12	12	12	12
S-1	SLO-1	Nomenclature of a Printed Circuit Board	PCB Design Considerations - Important Design Elements	Design Rules for Analog Circuits		Image Transfer Techniques- Screen
0-1	SLO-2	Classification of Printed Circuit Boards	PCB Design Considerations - Important Performance Parameters	Design Nules for Analog Officials	,	Printing, Pattern Transferring Techniques
	SLO-1	Manufacturing of basic PCB - Single-and Double-sided Plated Through-holes	PCB Design Considerations - Mechanical Design Considerations			Image Transfer Techniques- Printing Inks, Photo Printing, Laser Direct Imaging (LDI)
S-2	SLO-2	Manufacturing of Multi-layer Boards - Flexible Boards, Challenges in modern PCB Design and Manufacture, PCB Standards	PCB Design Considerations - Mechanical Design Considerations	Design Rules for Digital Circuits	Schematic Capture - Schematic to layout transfer	Copper Clad Laminates - Properties of Laminates, Types of Laminates, Evaluation of Laminates
S-3	Study of electronic components- Passive		Design and analysis of RL and RC time constants.	Schematic and PCB Layout in CAD tool. Regulated power supply design Full		Mini Project - PCB Layout Design of electronic turn ON/OFF timer using
S-4	SLO-1 SLO-2	electronic components	Schematic in CAD tool	wave rectifier circuit design with fixed voltage regulator	pulse counter using PCB design tool.	IC555 using PCB design tool.
S-5	SLO-1	Types, Symbols, Packaging shapes and terminal details of Electronic Components -Resistors, Thermistors Capacitors, Inductors	PCB Design Considerations - Electrical Design Considerations	Design Rules for High Frequency Circuits		Etching Techniques – wet Etching chemicals
	SLO-2	Diodes, Light Emitting Diodes (LED), Photodiode,	PCB Design Considerations - Conductor Patterns, Component Placement Rules		PCB Layout Design - Specifying Parts, Packages and Pin Names, Libraries	Etching Techniques - Mechanical Etching
S-6		Transistors, Field-effect Transistors, Insulated Gate Bipolar Transistor (IGBT), Thyristor	Fabrication and Assembly Considerations	Design Rules for Microwave Circuits	PCB Layout Design - Checking foot prints of the components, Part list, Net list, Making Net list Files	PCB Assembly Process - Through-hole
S-7			Design and analysis of RLC circuits. Schematic in CAD tool	Schematic and PCB Layout in CAD tool.		Mini Project - Manufacture the PCB for electronic turn ON/OFF timer using

S-8		Study of electronic components- active devices, analog and digital integrated circuits (IC)		wave recuirer circuit design with fixed	IPCR Decian of cinale digit nulce	IC555and construct and test the designed circuit.
S-9	OLO-1	Access Memory	Requirements			PCB Assembly Process - Surface Mount, Mixed Technologies
	SLO-2	Read Only Memory	Packaging Density	interconnection directared	Tidding Toxt, TOD Edyout	mixed recimelegies
S-10	SLO-1	Microcontrollers, Surface Mount Devices	Layout Design	Electromagnetic Interference/Compatibility	PCB Layout Design - DRC, Pattern	PCB Assembly Process - Soldering
	SLO-2	Transformer, Relays, Connectors	Layout Design	(EMI/EMC)	Transfer, Layout printing	FOB Assembly Flocess - Soldering
S-11	SLO-1	Study of testing and measuring		Cabamatia and DCD Lavavt in CAD tool		Mini Duniant Manufacture the DCD for
	SLO-2	Instruments: Logic analyzer, spectrum		Schematic and PCB Layout in CAD tool.		Mini Project - Manufacture the PCB for
S-12		analyzer, IC tester (Analog and Digital),	PCB Layout Design - of RL, RC and RLC	Full wave rectifier circuit design with		electronic turn ON/OFF timer using IC555and construct and test the
	SLO-2	LCR meters		fixed voltage regulator	IICSSS using DCB dosign tool	designed circuit.

Learning Resources

- Raghbir Singh Khandpur, "Printed Circuit Boards: Design, Fabrication, and Assembly" McGraw-Hill Electronic Engineering, 2006.
- 2. Charles A. Harpe, "High Performance Printed Circuit Boards", McGraw Hill Professional, 2000.
- Bruce R. Archambeault, James Drewniak, "PCB Design for Real-World EMI Control", Volume 696 of The Springer International Series in Engineering and Computer Science, Springer Science & Business Media, 2013.
- 4. Kraig Mitzner, "Complete PCB Design Using OrCAD Capture and PCB Editor", Newnes/Elsevier, 2009.
- 5. Douglas Brooks "Signal Integrity Issues and Printed Circuit Board Design", Prentice Hall PTR, 2003.
- Mark I. Montrose "Printed Circuit Board Design Techniques for EMC Compliance: A handbook for designers" Wiley, 2 Edition, 2015.
- 7. Esim open source tool: http://esim.fossee.in/
- 8. TINA/Orcad User manual

Learning Asse	earning Assessment											
	Bloom's			Conti	nuous Learning Ass	essment (50% weig	htage)			Final Examination (50% weightage)		
	Level of Thinking	CLA –	1 (10%)	CLA –	2 (15%)	CLA –	3 (15%)	CLA – 4	I (10%)#			
	Level of Thirtking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%	
Level I	Understand	2070	2070	1370	1370	1370	1370	1370	1370	1370	1370	
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%	
Level 2	Analyze	2070	2070	2070	20%	2070	2070	2070	2070	2070	2070	
112	Evaluate	400/	400/	450/	450/	450/	450/	450/	450/	450/	450/	
Level 3	Create	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%	
	Total	10	0 %	100	100 %		100 %		0 %	-		

[#] CLA - 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

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2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	

Code Name Name Category Category	Course	10ECO107T Cours	Fiber Ontice and Ontecleatranics	Course	0	Open Floative	L	Τ	Р	С
	Code	Name	Fiber Optics and Optoelectronics	Category	U	Open Elective	3	0	0	3

Pre-requisite Courses		Nil Co-requisite Courses	Nil	Progressive Courses	Nil	
Course Offering Department		Electronics and Communication Engineer	ring Data Book / Codes/Standards		Nil	

Learning 2 3

Course L	Learning Rationale (CLR): The purpose of learning this course is to:		Le	arniı	ng				
CLR-1:	Analyze the basic laws and theorems of light associated with the optical fiber communication and the classification of		1	2	2				
CLK-I.	optical fibers		'	2	3				
CLR-2:	Address concepts related to transmission characteristics such as attenuation and dispersion.								
CLR-3:	Explore the fundamentals of optoelectronics display devices, Sources and Detectors								
CLR-4:	Gain to information on Optical modulators and amplifiers		(Bloom)	Proficiency	Attainment				
CLR-5:	Illustrate the integration methods available for optoelectronic circuits and devices								
CLR-6:	Utilize the basic optical concepts applied in various engineering problems and identify appropriate solutions								
			Thinking	ted F	ed /				
		-	₽	te	4				

made ato the magnater methods arandor for optioned and actives								
Utilize the basic optical cond	epts applied in various engineering problems and identify appropriate solutions	Ē	of De	∖ttair				
		- ⊢		þ				
Course Learning Outcomes (CLO): At the end of this course, learners will be able to: CLO-1: Review the basic theorems related to fiber optic communication, and attain knowledge of types of optical fibers								
Review the basic theorems related to fiber optic communication, and attain knowledge of types of optical fibers								
Understand the optical signs	al distortion factors in optical fiber communication	2	85	75				
Familiarize the principle and	operation of various display devices, light sources and detectors	2	75	70				
Acquire knowledge of various optoelectronic modulators and amplifiers								
Understand the various optoelectronic integrated circuits								
Acquire fundamental concepts related to optical communication and optoelectronic devices								
	earning Outcomes (CLO): Review the basic theorems of the optical signst Familiarize the principle and Acquire knowledge of various opto	Review the basic theorems related to fiber optic communication, and attain knowledge of types of optical fibers Understand the optical signal distortion factors in optical fiber communication Familiarize the principle and operation of various display devices, light sources and detectors Acquire knowledge of various optoelectronic modulators and amplifiers Understand the various optoelectronic integrated circuits	earning Outcomes (CLO): At the end of this course, learners will be able to: Review the basic theorems related to fiber optic communication, and attain knowledge of types of optical fibers 2 Understand the optical signal distortion factors in optical fiber communication 2 Familiarize the principle and operation of various display devices, light sources and detectors 2 Acquire knowledge of various optoelectronic modulators and amplifiers 2 Understand the various optoelectronic integrated circuits 2	earning Outcomes (CLO): At the end of this course, learners will be able to: Review the basic theorems related to fiber optic communication, and attain knowledge of types of optical fibers 2 80 Understand the optical signal distortion factors in optical fiber communication 2 85 Familiarize the principle and operation of various display devices, light sources and detectors 2 75 Acquire knowledge of various optoelectronic modulators and amplifiers 2 85 Understand the various optoelectronic integrated circuits 2 85				

				Prog	ram L	earn	ing C	utco	mes ((PLO)				
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO-1: Professional	PSO – 2: Project Management Techniques	⊤ PSO – 3: Analyze & Research
Н	Н	-	-	-	-	-	-	-	-	-	-	-		Н
Н	-	М	-	-	-	-	-	-	-	-	-	-	-	М
Н	М	М	-	-	-	-	-	-	-	-	-	-	-	L
Н	-	М	-	-	-	-	-	-	-	-	-	-	-	Н
Н	-	М	L	-	-	-	-	-	-	-	-	-	-	L
Н	М	М	L	-	-	-	-	-	-	-	-	-	-	Н

	ration hour)	Learning Unit / Module 1 Introduction to Optical Fibers	Transmission Characteristics of Ontical I		Learning Unit / Module 4 Optoelectronic Modulators and Switching Devices	Learning Unit / Module 5 Optoelectronic Integrated Circuits
		9	9	9	9	9
	SLO-1	Evolution of fiber optic system	Attenuation – Absorption, Attenuation units	Display devices – Photo luminescence	Analog and Digital Modulation	Optoelectronic integrated circuits - Introduction
S-1	SLO-2	Elements of an optical fiber transmission link	Attenuation – Scattering losses	Cathode luminescence	Electro optic modulators – Electro optic effect – Longitudinal electro optic modulator	Need for Integration - Hybrid and Monolithic Integration
S-2	SLO-1	Elements of an optical fiber transmission link	Attenuation – Bending losses, microbending and macro bending losses	Electro luminescence	Electro optic modulators – Transverse electro optic modulator	Hybrid and Monolithic Integration
3-2	SLO-2	Advantages of fiber optic system	Attenuation - Core cladding losses	Injection luminescence	Acousto optic modulators – Transmission type – Raman Nath modulator	Materials and processing of OEICs
S-3	SLO-1	Characteristics and behavior of light	Signal distortion in optical waveguides	Light source materials	Acousto optic modulators – Reflection type – Bragg modulator	Application of optoelectronic integrated circuits
3-3	SLO-2	Total internal reflection	Types of dispersion-Intramodal and Intermodal dispersion	Surface emitting LEDs	Solving Problems	Slab and Strip Waveguides
	SLO-1	Acceptance angle	Material dispersion	Edge emitting LEDs	Optical switching and logic devices – self- electro-optic-device	Integrated transmitters and receivers – Front end photo receivers
S-4	SLO-2	Numerical aperture, Critical angle		Quantum efficiency and LED power – Internal quantum efficiency derivation	Optical switching and logic devices – Bipolar controller modulator	Integrated transmitters and receivers – photoreceiver noise and bandwidth considerations

S-5	SLO-1	Solving Problems	Waveguide dispersion	Quantum efficiency and LED power – External quantum efficiency and total LED power	Optical switching and logic devices- tunable threshold logic gate – Switching speed and energy.	Integrated transmitters and receivers – PIN-HBT photoreceivers
5-5	SLO-2	Solving Problems	Signal distortion in single mode fibers	Solving Problems	Optical Amplifiers – General applications of	Integrated transmitters and receivers – OEIC transmitters – equivalent circuit for integrated receivers
0.0	SLO-1	Ray optics	Polarization mode dispersion	Semiconductor laser diode	Semiconductor optical amplifiers – Basic configuration	Integrated transmitters and receivers – Complex circuits and arrays
S-6	SLO-2	Types of rays	Polarization mode dispersion, Intermodal dispersion	Modes and threshold condition	Semiconductor optical amplifiers – Optical	Integrated transmitters and receivers - optical control and microwave oscillators
S-7	SLO-1	Optical fiber modes	Intermodal dispersion		Erbium doped fiber amplifiers – energy level diagram and amplification mechanism	Guided wave devices – Waveguide and couplers
3-1	SLO-2	Optical fiber configurations	Solving Problems	PIN Photodiode	Erbium doped fiber amplifiers – EDFA configuration	Guided wave devices – Active guided wave devices
S-8	SLO-1	Single mode fibers	Solving Problems	PIN photodiode - Avalanche Photodiode	Solving Problems	Guided wave devices – Mach Zehnder Interferometers
3-8	SLO-2	Multimode Fibers	Pulse Broadening in Graded Index Waveguides	Avalanche Photodiode	Solving Problems	Active couplers
S-9	SLO-1	Step Index Fibers	Mode Coupling	Noise mechanism in photodetectors	Fiber Raman Amplifiers – Configuration – Forward pumping	Active Couplers
3-9	SLO-2	Graded Index Fibers	Design Optimization of Single Mode Fibers	Solving Problems	Fiber Raman Amplifiers – Backward pumping	Active Couplers

Learning	1.	Gerd Keiser, "Optical Fiber Communications", 5th Edition, McGraw Hill Education (India), 2015.
Resources	2.	Khare R P, "Fiber Optics and Optoelectronics", Oxford University Press, 2014.

- J. Wilson and J. Hawkes, "Optoelectronics An Introduction", Prentice Hall, 1995.
 Pallab Bhattacharya, "Semiconductor Optoelectronic Devices", Prentice Hall of India Pvt. Ltd, 2006.

Learning Asses	sment											
	Bloom's			Conti	nuous Learning Ass	essment (50% weig	htage)			Final Evamination	o (50% woightage)	
	Level of Thinking	(1 // 1/10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#		Final Examination (50% weightage)		
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	
Level 1	Remember	40 %		30 %		30 %		30 %		30%		
Level I	Understand	40 %	-	30 %	-	30 %	-	30 %	-	30%	-	
Level 2	Apply	40 %		40 %		40 %	_	40 %		40%		
Level 2	Analyze	40 /0	-	40 70	-	40 70	-	40 /0	-	4070	-	
Level 3	Evaluate	20 %		30 %		30 %	_	30 %		30%		
Level 3	Create	20 /0	-	30 /0	-	30 /0	-	30 /0	-	30%	_	
	Total	100) %	100	0 %	100 %		100 %		100 %		

[#] CLA - 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, kumaranuj.anii@gmail.com	1. Dr. Meenakshi, Professor of ECE, CEG, Anna University, meena68@annauniv.edu	1. Dr. S. Sathiyan, SRMIST
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@ici.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	

Course	LOCALON Cours		Course	Course			Τ	Р	С
Code	18ECO108J Name	EMBEDDED SYSTEM DESIGN USING ARDUINO	Category	0	Open elective courses	2	0	2	3

Pre-requisite Courses		Co-requisite Courses	Nil		Progressive Courses	Nil
Course Offering Department	ECE			Data Book / Codes/Standards	Nil	

Course Le	ourse Learning Rationale (CLR): The purpose of learning this course is to:							
CLR-1:	Get to know about ARDUINO h	nardware details and environment		1	2	3		
CLR-2:	To understand the core elemen	nts of ARDUINO programming language		Œ	(%)	(%)		
CLR-3:	Create insights to the concepts	of serial communication		(Bloom)	Proficiency (Attainment (
CLR-4:	CLR-4: To use common input and output devices							
CLR-5:	CLR-5: Apply the ARDUINO programming into real time applications							
CLR-6:	CLR-6:							
				evel of Thinking	Expected	Expected		
Course Le	arning Outcomes (CLO):	At the end of this course, learners will be able to:		Fe	Ä	Ä		
CLO-1:	Analyze the programming skill			2	80	70		
CLO-2:	Apply the real time data's into o	digital		2	85	75		
CLO-3:	CLO-3: Interact with almost many devices							
CLO-4:	-	2	85	80				
CLO-5:	Use and modifying the existing	libraries	2	85	75			
CLO-6 ·								

				Pro	gram	Learn	ing Ou	ıtcom	es (PL	.0)				
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modem Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO-1: Professional Achievement	PSO – 2: Project Management Techniques	PSO – 3: Analyze & Research
Н		-	-	-	-	-	-	-	-	-	-	-	Н	Н
Н	Н	Н	Н	Н	-	-	-	Н	-	Н	-	-	Н	Н
Н	-	Н	Н	Н	-	-	-	Н	-	Н	-	Н	Н	-
Н	Н	Н	Н	Н	-	-	-	Н	-	Н	-	Н	Н	-
Н	-	Н	Н	Н	-	-	-	Н	-	Н	-	Н	Н	-

	ation our)	12	12	12	12	12
S-1	SLO-1	Introduction to arduino platform	Introduction To Arduino C	Analog And Serial Communication	IO Programming	Case Studies
3-1	SLO-2	Block diagram	Arduino C Data Types .	Introduction To Analog Communication	Introduction To Timer/Counters	Wireless Communication Using Zigbee
6.0	SLO-1	AT mega 328p architecture	Decision Making in C	Pulse Width Modulation	Introduction To Timer/Counters	Bluetooth
S-2 SLO-2		AT mega 328p architecture	Decision Making in C	RS232	Timer programming	Robotics -Motor And Sensor
S 3-4	SLO-1	Lab 1 Getting Started With Adriano	Lab 4 -Sensor Interfacing For Temperature Monitoring	Lab 7: Actuators – Stepper Motor	Lab10:Interrupt Programming	Lab 13:Mini Project
5 3-4	SLO-2	CCS And AVR Studio 7 Blinking Led	Lab 4 -Sensor Interfacing For Displacement Measurement	Lab 7: Actuators – Stepper Motor	Lab10:Interrupt Programming	Lab 13:Mini Project
S-5	SLO-1	Pin function	Program Loops in C	12C	Timer programming	Security-RFID, Infrared
5-5	SLO-2	Overview of main features-I/O ports	Functions in C	I2C	Timer programming	Security-RFID, Infrared
S-6	SLO-1 SLO-2	Features-timers,interrupts	Introduction to Pointers	I2C	Timer programming	Bio medical application
6.7.6	SLO-1	Lab 2 GPIO LED	Lab 5: PWM BASED SERVO MOTOR INTERFACING	Lab 8: DC MOTOR	Lab11:Watch Dog Timer	Lab14:Model Practical
S 7-8	SLO-2	Switch Based Led Control	Lab 5: PWM Based Servo Motor Interfacing	Lab 8: DC MOTOR	Lab11:Watch Dog Timer	Lab14:Model Practical
S-9	SLO-1	Features-PWM,SERIAL PORT	Using Pointers Effectively	SPI Protocol	Interrupts	Bio medical application

	SLO-2	Features-ADC	Structures, Unions, and Data Storage	Interrupt programming	Bio medical application	
C 40	SLO-1	Introduction to Arduino IDE	Arduino Libraries	Interfacing with sensors	External interrupt	GPS Navigation
S-10	OLO-2			Interfacing with sensors	External interrupt	GPS Navigation
S11-12	SLO-1	Lab 3:DISPLAY INTERFACE-7 SEGMENT	Lab 6:SERIAL COMMUNICATION	Lab 9: Repeat/Revision Of Experiments	Lab 12 : I2C	Lab:15 University Practical
311-12		LCD 16x2 Matrix	Lab 6:Serial Communication	Lab 9: Repeat/Revision Of Experiments	Lab 12: I2C	Lab:15 University Practical

	James M. Fiore, Embedded Controllers Using C and Arduino, ARDUINO open source community, 2018 Jack Purdum ,Beginning C for Arduino , Apress, 2012

Learning Assessment													
	Bloom's		Continuous Learning Assessment (50% weightage)										
	Level of Thinking	ΓΙΔ = 1 /10%		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4	(10%)#	Final Examination (50% weightage)			
	Level of Thirtking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice		
Level 1	Remember Understand	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%		
Level 2	Apply Analyze	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%		
Level 3	Evaluate Create	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%		
	Total	100 % 100 %		0 %	10	0 %	100) %	-				

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2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	

Course	18ECO109J	Course	Embedded S	Embedded System Design using Raspberry Pi		Course Category	0	Open Elective	L	Т	Р	С
Code	102001000	Name	Embodada Oyalam Boolgii dollig Maabbony i i					Open Elective	2	0	2	3
					<u> </u>							
Pre-requisite		Nil	Nil Co-requisite		Nil		е	Nil				
Courses			Courses			Courses		740				
Course Offer	ring Department	Electro	onics and Communication Engi	neering	Data Book / Codes/Standards			Nil				

Course Learning Patients (CLD). The purpose of learning this course is to:				1					Drog	I	Learn	ina O	\taa	<i>(</i>	DI O			
Course Learning Rationale (CLR): The purpose of learning this course is to:	_ _	earn	irig		1				Prog	ram ı	Learn	iing C	Julco	mes (PLU)			
CLR-1: Understanding the programing of python for Raspberry Pi	1	2	3		1	2	3	4	5	6	7	8	9	10	11	12	13	14 15
CLR-2: Applying python programming on GPIO and interfacing motors using Raspberry Pi															, 1		ement	
CLR-3: Applying python programming on GPIO switch and keyboard	7		. _								_				, !		lem/	ਜ਼ ਚ
CLR-4: Create insights to the concepts and programming of motion detection ,GPS programming, light sensor ,gas detection	_ 0	(%)						된			1 1 1 1 1				, !		Achieve	nagement Research
CLR-5: Analyze and understand the working principle and data sheet of temperature sensor, gas sensor ,ADC, ultrasonic	(Bloom)	્રો જે	ent		g		art	sea			Sustainability		Work		ූ පු		Ac	
rangefinder, Acceleration and light sensor	2	Se.	핕		<u>₹</u>		l iid	Ä,	ge		nste		<u>ج</u>		Finance	б	ssional	e ≥ ≥
CLR-6: Utilize the technology of node is ,cloud service and MQTT Protocol for moving sensor data to web	hinking	Proficiency	Attainment		Š	Analysis	& Development	Design,	Usage	Culture	∞ŏ		Team	ou	ĕ	ong Learning	essi	ject
			-		g	Ana	ě	De	Tool	S	ent			icati	Mgt.	Lee	Profe	Projer es Analy
Course Learning Outcomes (CLO): At the end of this course, learners will be able to:	level of		Expected		Engineering Knowledge	Problem,	Design &	Analysis,	Modern T	Society &	Environment	Ethics	Individual &	Communication	Project M	Life Long		PSO – 2: Techniou PSO – 3:
CLO-1: Apply python for Raspberry Pi	2	80	70		Н	Н	-	-	Н	-	-	-	-	-	-	-	Н	
CLO-2: Analyze data sheet and functioning of sensors	2	85	75		Н	Н	Н	Н	Н	-	-	-	-	-		-	-	- H
CLO-3: Apply python programming on GPIO of Raspberry Pi and interfacing of sensor	2	75	70		Н	Н	Н	Н	-	-	-	-	-	-	-	-	Н	
CLO-4: Apply python programming on GPIO of Raspberry Pi to interfacing of actuators	2	85	80		Н	Н	Н	Н	Н	-	-	-	-	-	, - 1	-	Н	
CLO-5: Apply python programming on GPIO of Raspberry Pi to interfacing input and display device	2	85	75		Н	-	Н	Н	-	-	-	-	-	-	-	-	Н	
CLO-6: Apply technology of node is cloud service and MQTT Protocol for IOT application	2	80	70		Н	-	Н	-	Н	-	-	-	-	-	1	-	-	- H

	ration nour)	Learning Unit / Module 1 Basic python programming	Basic python programming Programming interrupts – Motor control, switches and keyboard interface Sensor interface and programming interface programming Temperature sensor and display interface programming				
		12	12	12	12	12	
	SLO-1	Python Basics- Editing Python Programs with IDLE, Variables, displaying Output, Reading User Input, Arithmetic, Creating Strings	Programming with Interrupts	Detecting Movement-PIR sensor	Measuring Temperature Using a Digital Sensor	publish sensor data on web service- building a home security dash board	
S-1	SLO-2	Concatenating (Joining) Strings, Converting Numbers to Strings, Converting Strings to Numbers ,Find the Length of a String, Find the Position of One String Inside Another, Extracting Part of a String, Replacing One String of Characters with Another Inside a String ,Converting a String to Upper- or Lowercase		Data sheet analysis of PIR sensor	Data sheet analysis Digital Temperature Sensor	publish sensor data on web service- building a home security dash board	
	SLO-1	Running Commands Conditionally, Comparing Values, Logical Operators,	Controlling GPIO Outputs Using a Web Interface	Adding GPS to the Raspberry Pi	Measuring Distance-ultrasonic rangefinder	MQTT Protocol	
S-2	SLO-2	Repeating Instructions an Exact Number of Times ,Repeating Instructions Until Some Condition Changes , Breaking Out of a Loop, Defining a Function in Python	Controlling GPIO Outputs Using a Web	Data sheet analysis of GPS	Data sheet analysis ultrasonic rangefinder	MQTT Protocol- installation and setting account ,token creation ,reading sensor data and pushing to thingsboard	

S-3-4	SLO-1	Lab 1: Arithmetic and string	Lab 7: Programming on interrupts	Lab 13: Programming on PIR sensor	Lab 19: Programming on Digital Temperature Sensor	Lab 25: Publish sensor data on web service
3-3-4	SLO-2	Lab 2: Loop	Lab 8: Programming on Web Interface	Lab 14: Programming on GPS	Lab 20: Programming on ultrasonic rangefinder	Lab 26: Publish sensor data on web service
S-5	SLO-1	Creating a List , Accessing Elements of a List, Find the Length of a List , Adding Elements to a List , Removing Elements from a List,	Controlling Servo Motors using PWM	Using Resistive Sensors	Logging to a USB Flash Drive	basic of java scripts –node.js
3-3	SLO-2	Creating a List by Parsing a String, Iterating over a List, Enumerating a List, Sorting a List, Cutting Up a List. Applying a Function to a List	Controlling the Speed of a DC Motor	Measuring Light	Logging to a USB Flash Drive	Modules-HTML module
S-6	SLO-1	Creating a Dictionary ,Accessing a Dictionary, Removing Things from a Dictionary,	Controlling the Direction of a DC Motor	Detecting Methane	Using a Four-Digit LED Display	Modules –file –event
	SLO-2	Iterating over Dictionaries	Using a Unipolar Stepper Motor	Data sheet analysis of gas sensor	Displaying Messages on an I2C LED matrix with data sheet discussion	Modules –file –event
S-7-8		Lab 3: Program on list	Lab 9: Programming on Stepper Motor	Lab 15: Programming on light sensor	Lab 21: Programming on Four-Digit LED Display	Lab 27: Programming on node js HTML module
3-1-0		Lab 4: Program on Dictionary	Lab 10: Programming on DC Motor	Lab 16: Programming on Gas sensor	Lab 22: Programming on I2C LED matrix	Lab 28: Programming on node js file and event module
S-9	SLO-1	Controlling Hardware-Connecting an LED- Controlling the Brightness of an LED		Measuring a Voltage using MCP3008 And data sheet of MCP3008	Displaying Messages on an Alphanumeric LCD	LED blinking using node.js
3-9	SLO-2	a Buzzing Sound	Building a Simple Robot Rover	Using Resistive Sensors with an ADC	Displaying Messages on an Alphanumeric LCD	LED blinking using node.js
S-10	SLO-1	Switching a High-Power DC Device Using a Transistor	Digital Inputs-Connecting a Push Switch- Toggling with a Push Switch-Using a Two- Position Toggle or Slide Switch	Measuring Temperature with an ADC	Cloud service for IOT	building java script client using MQTT broker
	SLO-2	Switching a High Power Doving Heing a Heing a Potony (Quadrature) Encoder on		Measuring Acceleration and data sheet discussion of Acceleration sensor	Cloud service for IOT	building java script client using MQTT broker
S-11,	SLO-1	Lab 5: LED blinking and Brightness control	Lab 11: Programming on Switch	Lab 17: Programming on ADC	Lab 23: Programming on an Alphanumeric LCD	Lab 29: Programming on LED blinking using node.js
S-11, 12		Lab 6: Switching a High-Power DC Device		Lab 18: Programming on Measuring Acceleration	Lab 24: Programming on an Alphanumeric LCD	Lab 30: Building java script client using MQTT broker

Learning	
Resources	

- Simon Monk, "Raspberry Pi Cookbook", O'Reilly Media, Inc, 2014.
 Volker Ziemann, "A Hands-On Course in Sensors Using the Arduino and Raspberry Pi, CRC Press, 2018.
- Colin Dow, "Internet of Thing: Programming Projects Build modern IoT solutions with the Raspberry Pi 3 and Python", packtpub 2018.
 https://thingsboard.io/docs/
 https://www.w3schools.com/nodejs/nodejs_raspberrypi_blinking_led.asp

Learning Assess	Learning Assessment Continuous Learning Assessment (50% weightage) Find Franciscus (50% weightage)												
	Bloom's			Final Examination	(50% woightage)								
	Level of Thinking			CLA – 2 (15%)		CLA – :	3 (15%)	CLA – 4	I (10%)#	Final Examination (50% weightage)			
	Level of Thirking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice		
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%		
Level I	Understand	2070	2070	1370	1370	1370	1370	1370	1370	1370	1370		
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%		
LGVGI Z	Analyze	2070	2070	2070	2070	2070	2070	2070	2070	2070	2070		
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%		
LCAC! 2	Create	1070	1070	1370	1370	1370	1370	1370	1370	1370	1370		
	Total	100 %		0 %	100	0 %	100	0 %	100 %				

[#]CLA - 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

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Course	18ECO110J Course	3D Printing Hardware and Software	Course _	Professional Elective	L	T	Р	С
Code	Name	3D Finiting Hardware and Software	Category	Floressional Liectuve	2	0	2	3

Pre-requisite Courses		Nil	Co-requisite Courses	Nil	Progressive Courses	Nil	
Course Offering I	Department	Electronics and Co	ommunication Engineering	Data Book / Codes/Standards		Nil	

					1															
Course Learning Rationale (CLR):	The purpose of learning this course is to:		Learn	ing	Program Learning Outcomes (PLO)															
CLR-1: Understand the tools available	CLR-1: Understand the tools available for 3D printing							3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2: Familiarize with 3D design	software and hardware																	ement		
CLR-3: Understand the 3D design	criteria and its limitations.	<u> </u>	` (6									>-						Mem .	eut	듄
CLR-4: Learn the contemporary te	chnology available for 3D design and printing	(Bloom)	(%)						arch			iii						Achiev	Je J	Research
CLR-5: Understand various post p	rocessing methods involved in 3D printing technology	<u>B</u>	5	eni		dge		eut	Research			aj.		Work		8		¥	Management	
CLR-6: Develop the skillset on 3D available.	component design and development using contemporary commercial software and hardware	Thinking	Proficiency	Attainment		Knowle	Analysis	Development	Design, Re	Usage	Culture	& Sustainability		Team V	ion	& Finance	Learning	Professional	Project Ma	Analyze &
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Ti	ted	Expected,		Engineering Knowledge	Problem An	Design & De	Analysis, De	Modern Tool	Society & C	Environment	Ethics	Individual &	Communication	Project Mgt.	ong-	÷ 1	-2: Big	PSO – 3: Ar
CLO-1 : Apply the 3D printing tools	for components design	1	80	60		М				М										
CLO-2: Able to optimistically select	the 3D design software and hardware for the given problem	1	80	60		М				Н										
CLO-3: Capability to solve 3D desi	gn components design problems	2	75	60		М			М										М	
CLO-4: Choose the contemporary	technology available for 3D design and printing	3	80	60				М											М	L
CLO-5: Apply various post processing methods involved in 3D printing technology							Н													
CLO-6: Ability to develop the skillset on 3D component design and development using contemporary commercial software and bardware available																М			М	

	ration nour)	Introductions to 3D design tools	Three-dimensional (3D) Modeling	3D Design Fundamentals and Projects		Post Processing - Product Visualization and Print Cleaning
S-1	SLO-1	Introduction to Maya GUI - Object creation workflow, Constructing object primitives to scale and with accuracy	An overview of CAD software packages - Introduction to Fusion 360 - Drawing based workflow, Drawing constraints - Surfacing operations.	The good, the bad, and the ugly of design	History of 3D printing - Overview of 3D Printing technologies	Workflows for printing
S-2		Duplication and arrayed duplication - Grid and point/vertex snapping	Moving Parts and Articulation Hinges - Ball and sockets	Prominent Designers	Selective Laser Sintering (SLS) Direct Metal Laser Sintering (DMLS)	Software and Drivers - Formats for Printing (SLA, OBJ, CAD, etc.)
S 3-4	SLO-2	Understanding NURBS: NURBS Surfaces advantages, Similarities and differences between NURBS and CAD drawings Curve and surface construction	Maya the proper way (NURBS Curves,	Franchises Success stories, Pop culture	Vacuum forming - Resin casting - Injection Molding - Terms and standards for injection molding systems	Post and Export Print Lab setup
S-5	SLO-1 SLO-2		Flexibility and elasticity, Locks, bolts, and fasteners Threading (taps and dies)		Fused Deposition Modeling (FDM) - Stereolithography (SLA)	Cleanup and airtight modeling
S-6	SI ()-1	Best Practices for constructing printable polygon meshes Fundamental Structure - Combining, merging, and sewing up polygon meshes	Interfacing, support, and reinforcement		Laminated Object Manufacturing (LOM) - Electron Beam Melting (EBM)	Loading models and arranging print stage

S 7-8	SLO-2	Combining, merging, and sewing up		design priase Group critiques of in-	Printing Resolutions and Tolerances Materials Properties (Temperature, Flexibility, Strength, Brittleness)	Printing - Removing support material
S-9	SLO-1	Understanding two-manifold vs. non- manifold geometry Exporting geometry - Laying out a simple model on a stage for print	Form and function visualizing the assembly process	Early decision-making criteria Knowing the product Vision and Reality	3D Printing (3DP) – Selective laser melting (SLM)	Special topics – 3D Scanners and its types
S-10	OLO-1	Hollow forms and the importance of reducing volume Cost of size, cost of volume, cost of detail, cost of time State table		land droub childles of in-brodress brolects		Reverse engineering, Concepts and its hardware and software
S 11-12			techniques Molding, sculpting, lathing,		Planning for injection molding - 3D Printing for injection molding	High speed machining

Learning Resources	2.	Hod Lipson, Melba Kurman, Fabricated: The New World of 3D Printing, Wiley, 2013 Matthew Griffin, Design and Modeling for 3D Printing, Maker Media, Inc., 2013. Rob Thompson, Manufacturing Processes for Design Professionals, Thames & Hudson; Reprint edition, 2007. https://web.stanford.edu/class/me137/ SolidWorks Gallery: http://www.3dcontentcentral.com/default.aspx	7. 8. 9.	3D Anatomy Models: http://lifesciencedb.jp/bp3d/?lng=en AutoDesk Fusion360 HomePage: http://fusion360.autodesk.com International Journal of Rapid Manufacturing Academic Journals on 3D Printing International Journal of Rapid Manufacturing
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Learning As	sessment										
	Bloom's			Conti	nuous Learning Ass	essment (50% weig	htage)			Final Evamination	(EOO/ woightogo)
	Level of Thinking	CLA –	1 (10%)	CLA – :	2 (15%)	CLA –	3 (15%)	CLA – 4	l (10%)#	FIIIai Examination	n (50% weightage)
	Level of Thirtking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Lovel 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
Level 1	Understand	20%	20%	13%	10%	10%	15%	13%	10%	10%	10%
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
Level 2	Analyze	2070	2070	2070	2070	2070	2070	2070	2070	2070	2070
Laval 2	Evaluate	400/	100/	150/	450/	450/	150/	150/	15%	450/	150/
Level 3	Create	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Total	10	0 %	100	0 %	10	0 %	100	0 %		-

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Course Code	18ECO121T	Course Name	BASIC BIOI	MEDICAL ENGINEERING	Course Category	0	Open Elective	3	T 0	P 0	C 3
Pre-requis Courses	INII		Co-requisite Courses	Nil	- 3	essive rses	Nil				
Course Offe	ring Department	Electror	nics and Communication Enginee	ering Data Book / Codes/Stand	dards Nil						

Course Le	earning Rationale (CLR): The purpose of learning this course is to:	L	earni.	ng	Program Learning Outcomes (PLO)														
CLR-1:	Analyze the scopes and roles of Biomedical Engineering	1 2 3 1 2 3 4 5 6 7						7	8	9	10	11	12	13	14	15			
CLR-2:	Utilize biomedical instrumentation modules										≥						the		
	Utilize medical imaging principles and its applications	Ē	(%)			_		arch			stainability						gat dicij	elop	200
	Analyze the scope of biomechanics and its applications	(Bloom)		ıt (%)	-	8	eut	ese			ain		Work		Ce	-	₹ ≥	eve	sciplinary alth care
	Utilize biomaterials and its applications) B	enc	mer	1	Sis	l dc	, Re	age	æ	Sust		Ε		inance	g e	လ္ကိုင္မ	∞ <u>,</u>	cipli
CLR-6:	Gain the knowledge about Biomedical Engineering	Thinking	Proficiency	Attainment	2	alys	evelopment	sign	l Ns	ulture	š		Team	ation	∞ ⊥	eaming	E g	ig ig	idisi
		▋∄	P P			Ä	& De	ď	<u>8</u>	رت ح	nen		∞	jca	Mgt.		g J	De De	if if
Course Le	earning Outcomes (CLO): At the end of this course, learners will be able to:	Level of	Expected	Expected		Problem	Design 8	Analysis	Modern	Society	Environme	Ethics	Individual	Communic	Project I	Life Long	PSO-1: I interface	PSO-:2: Medical	PSO-3: I
CLO-1:	Analyze the areas in which biomedical engineers can work	2	85	75		-	-	-	-	-	-	-	-	-	-	L	-	-	L
CLO-2:	Analyze the basic biomedical instrumentation unit	3	85	75	I		-	-	-	-	-	-	-	-	-	-	-	-	L
CLO-3:	Analyze basic medical imaging principles	3	85	75	/	1 -	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-4:	Apply the concepts of biomechanics on human body	3	85	75	1		-	-	-	-	-	-	-	-	-	-	-	-	L
						-	-	-	-	-	-	-	-	-	-	-	-]	-	-
CLO-6:	O-6: Analyze the applications of Biomedical Engineer					1 -	-	-	-	-	-	-	-	-	-	L	-	-	L

Du	ration	Introduction to Biomedical Engineering	Biomedical Instrumentation	Medical Imaging system	Biomechanics	Biomaterials
(I	nour)	9	9	9	9	9
S-1	SLO-1	Evolution of the modern health care system	Introduction: Bioinstrumentation	X-Ray production	Introduction: Principal Areas of Biomechanics	Biomaterials Introduction
3-1	SLO-2	Modern Healthcare system	Basic Bioinstrumentation System	X-Ray Imaging principle	Fundamentals of biomechanics and qualitative analysis	Classification of Biomaterials
	SLO-1	What is Biomedical Engineering	Physiological Systems of the body	Application of X-ray imaging	Kinematics of Human Body Models	Properties of Biomaterials: Mechanical
S-2	SLO-2	Roles played by the Biomedical Engineers	Kinetics of Human Body Models	Properties of Biomaterials: Chemical		
	SLO-1	Types of Biomedical Engineering	Origin of Bioelectric Signals	CT-Imaging Applications	Modelling of Bio systems	Properties of Biomaterials: Biological
S-3	SLO-2	Surgical instruments and medical devices	Origin of Bioelectric Signals	MRI- Introduction	Tissue Biomechanics	Biomedical alloys and its medical applications- titanium
S-4	SLO-1	Biomaterials	Various Electrodes used for picking the biomedical signals	MRI Imaging principles	Modelling in Cellular Biomechanics	Biomedical alloys and its applications- Stainless steel, Cobalt-Chromium alloys
3-4	SLO-2	Biomechanics	Various Electrodes used for picking the biomedical signals	MRI Imaging principles	Fluid mechanics	Introduction to ceramics
S-5	SLO-1	Tissue Engineering			Mechanics of the musculoskeletal system impact	Alumina, Zirconia
3-3	SLO-2	Neural Engineering	ECG system Block diagram and its uses	Ultrasound basics	Mechanics of Blood Vessels	Titanium, Hydroxyapatite
S-6	SLO-1	Telehealth	EEG Introduction	Ultrasound Imaging	Cardiac Biomechanics	Glass ceramics
3-0	SLO-2	Bio signal processing	EEG system Block diagram and its uses	Ultrasound Application	Biomechanics of Chest and Abdomen	Introduction to polymers

6.7	SLO-1	Medical Imaging	EMG Introduction	fMRI Imaging	Cochlear Mechanics	Types of polymers
S-7	SLO-2	Computational modelling	EMG system Block diagram and its uses	fMRI Imaging Application	II DVNAMICS OF HUMAN BOOV MODELS	Biodegradable polymers and its applications
S-8	SLO-1	BioMEMS	Cardiac pacemakers and its uses	PET- Imaging	Gait analysis	Composites and its applications
3-0	SLO-2	Mobile POCT	Cardiac Defibrillators and its uses	PET Imaging Application	Biomechanics in physical education	Wound-Healing process
	SLO-1	Professional Status of Biomedical Engineering	Patient Monitoring System Introduction	SPECT Imaging	Biomechanics in strength and conditioning	Biomaterials for artificial valve, Ear
S-9	SLO-2	Professional Societies	Patient Monitoring System Block diagram and its uses		Biomechanics in sports medicine and rehabilitation	Biomaterials for artificial Skin, Eye

Learning
Learning Resources

- 1. Anthony Y. K. Chan, Biomedical Device Technology: Principles and Design, Charles C Thomas publisher, 2008
- R.S Khandpur, Handbook of Biomedical Instrumentation, 3rd ed., McGraw Hill, 2014
 Joseph J. Carr, John M.Brown, Introduction to Biomedical Equipment Technology, 4th ed., Pearson, 2002
- John Enderle, Joseph Bronzino, Introduction to Biomedical Engineering, Academic Press, 2011 Andrew R Webb, Introduction to Biomedical Imaging, Wiley-IEEE Press, 2003
- Sujata V. Bhat, Biomaterials, 2nd ed., Alpha Science International, 2005

Learning Ass	essment											
_	Bloom's			Conti	nuous Learning Ass	essment (50% weig	htage)			Final Evamination	(E00/ woightage)	
	Level of Thinking	CLA -	1 (10%)	CLA -	CLA – 2 (15%)		3 (15%)	CLA – 4 (10%)#		Final Examination (50% weightage)		
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	
Level 1	Remember Understand	40 %	-	30 %	-	30 %	-	30 %	-	30%	-	
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-	
Level 3	Evaluate Create	20 %	-	30 %	-	30 %	-	30 %	-	30%	-	
	Total	10	0 %	10	0 %	10	0 %	100	0 %	10	0 %	

[#] CLA - 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Sathyanarayanan J, Mindray Medical India Pvt Ltd, <u>sathyanarayananjayagopal@mindray.com</u>	1. Dr. S. Poonguzhali, Anna University, poongs@annauniv.edu	1. Ms. Oinam Robita Chanu, SRMIST
2. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, kumaranuj.anii@gmail.com	2. Dr. Meenakshi, Professor of ECE, CEG, Anna University, meena68@annauniv.edu	2. Dr. D. Kathirvelu, SRMIST
3. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	3. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	

Course	19ECO122T	Course	HOSDITAL INFORMATION SYSTEMS	Course	0	Open Floative	L	Т	F	, С
Code	18ECO1221	Name	HOSE TIAL INFOLVING TO LEMO	Category	J	Open Elective	3	0	0	3

Pre-requisite Nil	Co-requisite Courses	Nil		Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engine	ering	Data Book / Codes/Standards	Nil	

Course Learning Rationale (CLR): The purpose of learning this course is to:		_earn	ing	Program Learning Outcomes (PLO)														
CLR-1: Utilize the planning and organizational activities of Hospitals	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2: Analyze the concepts in clinical and diagnostic services										y						the		
CLR-3: Utilize the policies and procedures about support services and material management] <u>-</u>		_				arch			Sustainability						<u>:</u> at	8	los
CLR-4: Utilize the features in staff and safety management in hospital	(Bloom)	y (%)	t (%)	dge		ent	sse			ains		Work		9		lving Med	eve)ary
CLR-5: Analyze the reporting system and recent advancement in hospital administration	9,8	Proficiency	Attainment	₩ We	S	Development	ı, Re	age	Φ	sust		n V		Finance	Вu	တ္တလ္ခ	∞ □	ultidisciplinary for health care
CLR-6: Apply all the advanced application the field of telemedicine	hinking	ofici	Taj.	출	Analysis	l velc	Design,	l ns	Culture	∞ర		Team	io.	∞ŏ	Learning	blem Fnaa	sign vices	idisc
	j	L L	d At	ring	Añ	& De	, D	Tool Usage	023	nen		<u>∞</u>	jcal	∕lgt.	g Le	P. P.	Des	for T
Course Learning Outcomes (CLO): At the end of this course, learners will be able to:	Level of	Expected	Expected	Engineering Knowledge	Problem	Design 8	Analysis,	Modem	Society	Environment	Ethics	Individual	Communication	Project Mgt.	Life Long	PSO-1: I	PSO-:2: Medical	PSO-3: I
CLO-1: Analyze the role of hospitals and ensure proper healthcare delivery	2	85	75	L	-	-	-	-	М	-	-		-	-	-	L	-	-
CLO-2: Suggest appropriate technologies and services in clinical and diagnostic field	3	85	75	М	-	-	-	-	-	-	-		-	-	-	L	-	-
CLO-3: Analyze the supportive services and the use of proper material management	3	85	75	М	-	-	-	-	-	М	L		-	-	-	М	-	L
CLO-4: Identify objectives of staff management and ensure safety management in hospitals	3	85	75	М	-	-	-	-	-		L	-	-	-	L	L	-	-
CLO-5: Implement the advance technologies and effectively evaluate the healthcare information			75	L	-	-	-	-	М	-	L	L	-	-	-	L	L	L
CLO-6: Implement the various standards in hospital and healthcare services	3	85	75	L	-	-	-	-	М	-	-		-	-	-	L	-	-

	ration	Planning and designing of hospitals	Inpatient and Outpatient services	Material management services	Management services in hospitals	Patient record and advancement in healthcare services
(1	nour)	9	9	9	9	9
S-1	SLO-1	Hospital as a social system	Design and planning of emergency department	Pharmacy services- goals of hospital pharmacy services		Medical record management- Importance of medical record
	SLO-2	Primary health care and hospitals	Health information and counselling	Staff organization and divisions of hospital pharmacy services	Hospital staff skill development	Methods of record keeping
S-2	SLO-1	Hospital planning and design-Guiding principles in planning	Outpatient services –Types and functions of outpatient department	Benefits of formulatory system	Nursing management-Functions of nursing management	Electronic medical record-Benefits and drawbacks
	SLO-2	Regionalization of Hospital service	Physical features of outpatient department	TUINER SERVICES OF HOSDIIAL DHARMACV	Nursing management- organizational structure	Record retention and disposal
S-3	SLO-1	Role of health promotion approach in hospitals	Ward/Indoor services-Components of the ward system		Biomedical waste management- Types and Composition of Biomedical Waste	Office management -skills required by the office staff
	SLO-2	Health promoting hospital system	Design of special units	Communication and physical facilities of ambulance service	Categories of biomedical waste	Functions of office management
S-4	SLO-1	Healthy hospital environment	Operation theatre services-Planning and designing of Operation theatres	Staff transport services	Concept of total quality management	Operations research in hospitals-Phases of operation research
3-4	SLO-2	Components of healthy hospital environment	Types of Operation theatres	Other transport services in hospitals	Types of approaches in quality management	Operations research in hospitals- Tools and techniques of operations research
S-5	SLO-1	Creating manpower services	Policies and procedures of operation theatres	Medicolegal services- Steps for Medicolegal Examination	Quality assessment and management tools	Emerging health insurance – components of health insurance

	SLO-2	Hospital engineering: Key to efficient healthcare services	Assessing operation theatre utilisation	Problems faced by healthcare professionals in medicolegal service	Clinical audit	Emerging health insurance-Types of health insurance
S-6	SLO-1	Designing disabled friendly hospitals- Barriers faced and implications in Persons with disabilities	Clinical laboratory services-Introduction and role of laboratory medicine	Food safety in hospitals-Need of food safety	method	Advantages and common problems of health insurance schemes
	SLO-2	Need for disabled-friendly health services	Testing procedure in clinical laboratory	Sources of food contamination	Pareto analysis	Role of health and hospital administrators in Health insurance
S-7	SLO-1	Barrier-Free Environment to Universal Design	Radio diagnosis and imaging services- Planning and equipments of radiology department	Materials management- Principles of material management	Failure mode and effect analysis	Telemedicine clinic –functions and classification of telemedicine
	SLO-2	Overcoming the barriers	Advancement in radiology service	Concepts of Inventory control	Triggers of quality improvement strategy in a hospital	Challenges for telemedicine
S-8	SLO-1	Energy conservation- Classification	Radiation oncology service-Radiotherapy facilities	Modern techniques for inventory control	, ,	Growth of mobile phones and potential of mobile health
3-0	SLO-2	Types of energy streams in hospitals	Nuclear medicine services-Categorization and nuclear medicine department	Integrated concept for materials management	Prevention of hazards specific to health sector	Mobile health and its applications
S-9	SLO-1	Need for energy conservation	Planning of nuclear medicine department	Purchase and procurement system- Essentials for procurement process	Hospital security-Physical security	Challenges in implementing information and Communication technology in healthcare
	SLO-2	Energy conservation opportunities in hospitals	Ancillary requirements	Purchase system	Organizational chart of security wing	Information and communication technology applications in healthcare

Learning Resources	SonuGoel, Anil Kumar Gupta, Amarjeet Singh, Hospital administration A problem- solvin approach, 1st ed., Elsevier, 2014	 Sakharkar B M, Principles of hospital administration and planning, 2nd ed., Jaypee Brothers Medical Publishers, 2009 Kunders G D, Hospitals: Facilities planning and management, 1st ed., Tata Mcgraw Hill, 2008
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Learning Asses	sment											
	Bloom's			Conti	nuous Learning Ass	essment (50% weig	htage)			Final Evamination	(E00/ waightaga)	
	Level of Thinking	CLA –	1 (10%)	CLA – 2	CLA – 2 (15%)		3 (15%)	CLA – 4	1 (10%)#	Final Examination (50% weightage)		
	Level of Thirtking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	
Level 1	Remember Understand	40 %	-	30 %	-	30 %	-	30 %	-	30%	-	
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-	
Level 3	Evaluate Create	20 %	-	30 %	-	30 %	-	30 %	-	30%	-	
	Total	100	0 %	100) %	100	0 %	10	0 %	10	0 %	

[#] CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

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2. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, kumaranuj.anii@gmail.com	2. Dr. Meenakshi, Professor of ECE, CEG, Anna University, meena68@annauniv.edu	2. Mr. P. Muthu, SRMIST
3. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	3. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	

Course	Course	PIOMEDICAL IMACING	Course	0	Open Floative	L	Т	Р	С	
Code	 Name	BIOMEDICAL IMAGING	Category	U	Open Elective	3	0	0	. 3	

Pre-requisite Nil	C	Co-requisite Courses	Nil		Progressive Courses	Nil
Course Offering Department	Electronics and Communication	cation Engineeri	ng	Data Book / Codes/Standards	Nil	

oouise e	onering Department	Electronics and communication Engineering Data Book (Codes) candidates	1 411																	
	, , ,	The purpose of learning this course is to:		Learn	arning Program Learning Outcomes (PLO)															
CLR-1:	Utilize the working principle	of X-ray imaging	1	2	3		1	2	3	4	5	6	7	8	9	10	11	12 1	13 14	4 15
CLR-2:		d tomographic imaging and the reconstruction techniques															.			등
CLR-3:	Interpret the theory behind	nuclear medicine and utilize the working of imaging modalities in nuclear medicine								_			₹				1	4		ear
CLR-4:	Analyze the physics of ultra	sound and the different imaging modes using ultrasound	í e	(%)						search			iliqe				.	4		. 8
CLR-5:	Utilize the physical principle	e of nuclear magnetic resonance and magnetic resonance image reconstruction	(Bloom)	6)	ıt (%)		dge		ent	ese			ains		Work		<u>8</u>	Ţ.	We We	plinary
CLR-6:	The learner will be to gain k	knowledge in the working principle of imaging modalities using X-ray, computed tomography,	a (B	oficiency	Attainment		we we	S	elopment	, Re	Usage	ө	Sustainability		٦		Finance	g V	3 8 8	
CLK-U.	nuclear medicine, ultrasoun	nd and magnetic resonance imaging.	Thinking	ofici	taj.		Ā	nalysis	evelc	Design,		ulture	∞ŏ		Team	tion	∞ర	arning	ig is	idis
			<u>`</u>	ā	₹		ring	Ans	» De		T00	S S	nent		× ∞	ig.	Mgt.	g Le	- F E E	mult Dev
Course L	earning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of	Expected	Expected		Engineering Knowledge	Problem	Design {	Analysis,	Modern	Society	Environm	Ethics	Individual	Communication	Project I	Life Lon	nterface PSO-:2:	Medical PSO-3:
CLO-1:	Analyze the physics and pri	inciple behind the working of X-ray imaging	2	85	75		М		-	-	-	-	-	-	-	- [-	- 1	М -	-
CLO-2:	Identify the principle behind	I working of tomographic imaging and reconstruction procedures.	3	85	75		М	-	-	-	-	-	-	-	-	-	- 1	- /	М -	-
CLO-3:	Analyze the working princip	ole of nuclear medicine imaging modalities	3	85	75		М		-	-	-	-	-	-	-	- [-	- 1	М -	-
CLO-4:	Identify the physics of ultras	sound and the modes of ultrasound imaging	3	85	75		Μ	-	-	-	-	-	-	-	-	-	- 1	- /	М -	
CLO-5:	CLO-5: Explain the physical principle of magnetic resonance imaging and the instrumental components involved in MR imaging			85	75		М	-	-	-	-	-	-	-	-	-	- 1	- /	М -	
CLO-6:	LO-6: Understand the basic principle and working of medical Imaging systems				75	1 1	М		-	-	-	-	-	-	-	_	- 1	- 1	М -	

Du	ration	X-ray	Computed Tomography	Ultrasound	Magnetic Resonance Imaging	Nuclear medicine
(ł	our)	9	9	9	9	9
S-1	SLO-1	General principles of Imaging with X-rays		Characteristics of sound: Propagation, wavelength, frequency and speed	Principles of NMR Imaging	Radionuclide decay terms and relationship
3-1	SLO-2	X-ray Production –X-ray source	Comparison between tomographic and planar imaging	Pressure, Intensity and dB scale	Free Induction decay	Nuclear transformation
S-2	SLO-1	X-ray tube current, tube output	Basic principle: Technique of producing CT images	Interaction of ultrasound with matter: Acoustic impedance, reflection, refraction	Excitation, Emission	Radionuclide production
0.2	SLO-2	Beam intensity, X-ray Energy Spectrum	Contrast scale	Scattering, Attenuation	Relaxation times-T1 & T2	Radiopharmaceuticals
S-3	SLO-1	Coherent and Compton scattering	System components: first generation, second generation, third generation,	Transducers: Piezoelectric materials, resonance transducers	Spin echo technique	Radiation detection and measurement: types of detectors, Gas-filled detectors
0-3	SLO-2	Photoelectric effect	Fourth, fifth and spiral/helical CT	Damping block, matching layer, Resolution	Spin echo contrast weighting	Scintillation detectors
S-4	SLO-1	Linear and Mass attenuation coefficient of X-rays in tissue	X-ray source, types of detectors	Transducer arrays	T1 weighted image	Semiconductor detectors
3-4	SLO-2	Instrumentation for Planar X-ray Imaging: Collimators	Gantry and slip ring technology, Collimation and filtration	Multi-element linear array scanners	T2 weighted image	Pulse height spectroscopy
0.5	SLO-1	Antiscatter grids Intensifying screens	Processing system	Multi-linear and phased array	Gradient recalled sequence	Non-imaging detector applications
S-5	SLO-2	X-ray films	Iterative reconstruction, back projection reconstruction	I Generation and detection of Hitrasoling	Proton density weighted images, pulse sequence for fast imaging	Counting statistics
S-6	SLO-1	Instrumentation for computed and digital radiography	Filtered back projection	Basic pulse echo apparatus: A-scan	Slice selection gradient	Nuclear imaging

	SLO-2	X-ray Image characteristics: Signal to Noise ratio	Helical /Spiral CT: Helical pitch	B-Mode	Frequency encode gradient	Anger scintillation camera
S-7	SLO-1	Spatial resolution, Contrast to Noise ratio	Basic reconstruction approaches	M-mode	Phase encode dradieni	Basic principle :Emission computed tomography
3-1	SLO-2	X-ray contrast agents, X-ray angiography	Slice sensitivity profile	Echocardiograph	ZD SDIN ECNO DATA ACQUISITION	Single photon emission computed tomography
S-8	SLO-1	X-ray Fluoroscopy	Multislice CT		Basic NMR components: Main magnet, RF transmitter/receiver	Positron emission tomography
3-0	SLO-2	X-ray mammography	Detector configuration	Intravascular imaging		Imaging techniques and scanner instrumentation
S-9	SLO-1	Dual energy Imaging		Artefacts: Refraction, shadowing and enhancement	fMRI : Basic principle	Dual modality: PET/CT
3-9	SLO-2	Abdominal X-ray scans	Methods for dose reduction	Reverberation	BOLD concept, MR spectroscopy	Working and applications

Learning Resources	R.S.Khandpur, Handbook of Biomedical instrumentation, 3 rd ed., Tata McGraw Hill, 2014	Jerrold T. Bushberg, John M. Boone, The essential physics of medical imaging, 3 rd ed., Lippincott Williams & Wilkins, 2011
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Learning Asses	sment												
	Ploom's	Bloom's Continuous Learning Assessment (50% weightage)											
	Level of Thinking	CLA –	1 (10%)	CLA – 2 (15%)		CLA –	3 (15%)	CLA – 4	I (10%)#	FIIIai Examination	n (50% weightage)		
	Level of Thirtking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice		
Level 1	Remember	40 %		30 %		30 %	_	30 %		30%			
Level I	Understand	40 /0	-	30 /0	-	30 /0	-	30 //	-	3070	-		
Level 2	Apply	40 %		40 %		40 %		40 %		40%			
Level 2	Analyze	40 /0	-	40 /0	-	40 /0	-	40 /0	-	4070	-		
Level 3	Evaluate	20 %		30 %	_	30 %	_	30 %		30%			
LEVEL 3	Create	20 70	_	30 /0	_	30 /0	_	30 /0	_	3070	-		
	Total	100) %	100	0 %	100	0 %	100	0 %	10	0 %		

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2. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, kumaranuj.anii@gmail.com	2. Dr. Meenakshi, Professor of ECE, CEG, Anna University, meena68@annauniv.edu	2. Dr. U. Snekhalatha, SRMIST
3. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	3. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	

Course	18ECO124T	Course	HIIMANI ASSIST DEVICES	Course	0	Open Floative	L	Т	Р	С	1
Code	10ECO1241	Name	HOWAN ASSIST DEVICES	Category	0	Open Elective	3	0	0	3	

Pre-requisite Nil	Co-requisite Courses	Nil	Progressive Nil	
Course Offering Department	Electronics and Communication Engineering	ring Data Book / Codes/Standards	Nil	

Course Learning Rationale (CLR): The purpose of learning this course is to:	Learning Program Learning Outcomes (PLO)																		
CLR-1: Utilize the latest technology and device used for assisting human disability	1	2	3		1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2: Analyze various devices used for mobility											^						the		
CLR-3: Utilize the various assist device used for hearing	=		_					arch			Sustainability						<u>:</u> at	do	solu
CLR-4: Utilize the various assist device used for vision	(Bloom)	y (%)	t (%)		dge		ent	Se			aine		Work		9		Solving & Med	evel	nary Sare
CLR-5: Utilize the various assist device used in orthopaedic	9 (B	Proficiency	Attainment		Me.	S	mdo	, Re	age	Φ	snst		<u>د</u>		Finance	В		& □	ildi H
CLR-6: Analyze the working principles of cardiac assist devices and Artificial kidney	hinking	ofici	tain		출	Analysis	yelc	Design,	l Us	Culture	×		Team	ig.	∞ŏ	arni	roblem of Enga	sign vices	idisc
	Ę	P P	d At		ring	Ä	& Development	9	Tool Usage	ంగ	nen		<u>∞</u>	ical	∕lgt.	g Fe	Prof	Des	mult for
Course Learning Outcomes (CLO): At the end of this course, learners will be able to:	Level of	Expected	Expected		Engineering Knowledge	Problem	Design 8	Analysis,	Modem	Society	Environment &	Ethics	Individual &	Communication	Project Mgt.	Life Long Learning	PSO-1: I	PSO-:2: Medical	PSO-3: multidisciplinary research for health care s
CLO-1: Comprehend the assistive technology (AT) used for mobility	2	85	75		М	-	-	-	-	-	-	-	-	-	-	-	М	-	-
CLO-2: Analyze the Assist technology used for hearing	3	85	75		М	-	-	-	-	-	-	-	-	-	-	-	-	L	
CLO-3: Evaluate the Assist technology used for sensory impairment of vision	3	85	75		-	-	-	-	-	-	-	-	-	-	-	-	-	L	-
CLO-4: Evaluate the assist device used in orthopedic	3	85	75		М	-	-	-	-	-	-	-	-	-	-	-	М	L	-
CLO-5: Analyze the latest use of assist technology in health care			75		М	-	-	-	-	-	-	-	-	-	-	-	М	-	-
CLO-6: Design the prosthetic heart valves and pacemaker	3	85	75		М	-	-	-	-	-	-	-	-	-	-	-	М	-	-

	ration nour)	0	9	0	q	0
٧.	,	9	9	y	9	9
S-1	SL0-1	Basic assessment and evaluation for mobility	Basic ear anatomy, Mechanism of hearing	Anatomy of eye	Anatomy of upper & lower extremities -	Basic Anatomy and physiology of heart.
3-1	SLO-2	Basic assessment and evaluation for mobility	Common tests audiograms	Categories of visual impairment	Classification of amputation types	Cardiac assist devices
S-2	SLO-1	Manual wheelchairs	Air conduction, Bone conduction	Intraocular Devices	Prosthesis prescription	Intra-Aortic Balloon Pump (IABP),
3-2	SLO-2	Electric power wheelchairs	Masking techniques,	Extraocular Devices	Hand and arm replacement	Prosthetic heart valves
S-3	SLO-1	Power assisted wheelchairs	SISI		Different types of models, externally powered limb prosthesis	Evaluation of prosthetic valve
3-3	SLO-2	Wheel chair standards & tests -	Hearing aids principles		Different types of models, externally powered limb prosthesis	Heart pacemaker
C 4	SLO-1	Wheel chair transportation	Drawbacks in the conventional unit	Voice Control Sound Control.	Foot orthosis	CABG
S-4	SLO-2	Control systems, navigation in virtual space by wheelchairs	DSP based hearing aids	Sensor Technology Adapted for the Vision Impaired	Pediatric orthoses	Extracorporeal support
S-5	SLO-1	Wheel chair seating and pressure ulcers.	Cochlear Implants	Libraille	Wrist-hand orthosis	Vascular prosthesis
3-3	SLO-2	EOG based voice controlled wheelchair	Internal Hearing Aid	GRAB	feedback in orthotic system	Vascular prosthesis
S-6	SLO-1	BCI based wheelchair	External Hearing Aid	mathematical Braille	Components of upper limb prosthesis	Artificial heart

	SLO-2	Fuzzy logic expert system for automatic tuning of myoelectric prostheses	Permanent Hearing Restoration	Blind mobility aids	Components of lower limb prosthesis	Intermittent positive pressure breathing (IPPB) type assistance for lungs
S-7	SLO-1	Intelligent prosthesis	Non-Permanent Hearing Restoration	Reading writing & graphics access,	Lower extremity- and upper extremity- orthoses	Dialysis for kidneys
3-1	SLO-2	Intelligent prosthesis	Touch Tactile Haptic Technology	Orientation & navigation Aids	Lower extremity- and upper extremity- orthoses	Artificial Kidney
S-8	SLO-1	Future trends in assistive technology	Sound Coding Translation	Wearable Assistive Devices for the Blind	functional electrical stimulation	Haemodialysis
3-0	SLO-2	virtual reality based training system for disabled children	Acoustic Transducers Hearing Quality	Wearable tactile display for the fingertip.	Sensory assist devices	Membrane dialysis
S-9	SLO-1	Information technology, telecommunications,	Electric Electronic Stimulation	Cortical implants	Sensory assist devices	Portable dialysis monitoring and functional parameter
3-9	SLO-2	new media in assisting healthcare	Hearing Enhancement	Retinal implants	Slints – materials used	Latest use of assistive technology for chronic heart diseases and healthcare

	1.	Levine S.N. Advances in Bio-medical engineering and Medical physics, 1st ed., Vol. I, II, IV, Interuniversity	6.	Albert M.Cook, Webster J.G, Therapeutic Medical Devices, Prentice Hall Inc., 1982
		publications, 1968.	7.	Gerr .M. Craddock Assistive Technology-Shaping the future, 1st ed., IOS Press, 2003
Learning	2.	Marion. A. Hersh, Michael A. Johnson, Assistive Technology for visually impaired and blind, 1st ed., Springer	8.	Brownsell, Simon, et al., A systematic review of lifestyle monitoring technologies, Journal of
Resources		Science & Business Media, 2010		telemedicine and telecare 17.4 (2011): 185-189
Resources	3.	Kopff W.J, Artificial Organs, 1 st ed., John Wiley and Sons, 1976	9.	Yadin David, Wolf W. von Maltzahn, Michael R. Neuman, Joseph.D, Bronzino, Clinical
	4.	Daniel Goldstein, Mehmet Oz, Cardiac assist Devices, Wiley, 2000		Engineering, 1st ed., CRC Press, 2010
	5.	Kenneth J. Turner, Advances in Home Care Technologies: Results of the match Project, 1st ed., Springer, 2011	10.	Pascal Verdonck, Advances in Biomedical Engineering, 1st ed., Elsevier, 2009

Learning Ass	sessment											
	Bloom's			Final Examination	n (50% woightage)							
	Level of Thinking	CLA –	1 (10%)	CLA –	2 (15%)	CLA –	3 (15%)	CLA – 4	l (10%)#	Filiai Examinatio	inal Examination (50% weightage)	
	Level of Thirtking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	
Level 1	Remember	40 %		30 %		30 %		30 %		30%		
Level I	Understand	40 %	-	30 %	-	30 %	-	30 %	-	30%	-	
Level 2	Apply	40 %	_	40 %	_	40 %	_	40 %	_	40%	_	
Level 2	Analyze	40 /0	_	40 70	_	70 70	_	40 70		7070		
Level 3	Evaluate	20 %		30 %		30 %	_	30 %		30%		
revel 2	Create	20 /0	-	30 //	_	30 70	-	30 /0	_	30%	_	
	Total	10	0 %	10	0 %	10	0 %	100	0 %	10	00 %	

[#] CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Sathyanarayanan J, Mindray Medical India Pvt Ltd, <u>sathyanarayananjayagopal@mindray.com</u>	1. Dr. S. Poonguzhali, Anna University, poongs@annauniv.edu	1. Mrs. Lakshmi Prabha, SRMIST
2. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, kumaranuj.anii@gmail.com	2. Dr. Meenakshi, Professor of ECE, CEG, Anna University, meena68@annauniv.edu	2. Dr. U. Snekhalatha, SRMIST
3. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	3. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	

Course	18ECO125T Cours	OLIALITY CONTROL FOR RIOMEDICAL DEVICES	Course	Open Flortive	L	Т	Р	С
Code	Name	QUALITY CONTROL FOR BIOWEDICAL DEVICES	Category	Open Elective	3	0	0	3

Pre-requisite Nil	Co-requisite Courses	Nil		Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engine	ering	Data Book / Codes/Standards	Nil	

Course Learning Rationale (CLR): The purpose of learning this course is to:					Program Learning Outcomes (PLO)															
CLR-1: Utilize Quality, Quality control measures essential for an organization	1	1	2	3		1 2	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2: Utilize the quality management principles and good management practices												,						at the		
CLR-3: Utilize the various quality control tools	-	-	<u> </u>	<u> </u>					Research			Sustainability							velop	. 5
CLR-4: Utilize the various quality management tools	Bloom (Bloom)	<u> </u>	y (%)	ıt (%)		a Sn		ent	ese			aina		Work		90		lving Med	eve	isciplinary ealth care
CLR-5: Analyze the various standards applicable to healthcare globally and nationally	(B)	g (R	Proficiency	Attainment	-	1	,	& Development	Ç.	Usage	go.	Sust		Α.		Finance	В	လ္တ	∞	ile f
CLR-6: Implement the global standards in healthcare	Thing the state of	Ž.	ofici	ain	:	Ž 3	niaiyəiə	Ne Ne	Design,	ns	Culture	∞ర		Team	io	∞ŏ	Learning	E E	sign ices	
		≣	프			5	Ě	۵	۾	Tool	ತ ಶ	nen			Sa	Mgt.	J Le	Proble of E	Dev	3: multidi:
Course Learning Outcomes (CLO): At the end of this course, learners will be able to:	evel of	Level of	Expected	Expected		Eligineeling Miowiedge		Design 8	Analysis,	Modern	Society &	Environment	Ethics	Individual &	Communication	Project N	Life Long	PSO-1: Finterface	PSO-:2: Medical	PSO-3: r
CLO-1: Analyze the underlying concepts of quality and quality control concepts of an organization	2	2	85	75		-		-	-	-	-	-	-	-	-	-	L	-	-	L
CLO-2: Evaluate the various quality management principles and good management practices	3	3	85	75		-		-	-	-	-	-	-	-	-	-	-	-	-	L
CLO-3: Evaluate various tools of quality control	3	3	85	75	1	1		-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-4: Analyze the various quality management tools	3	3	85	75		-		-	-	-	-	1	-	1	-	1	-	-	-	L
CLO-5: Analyze the various standards applicable to healthcare globally and nationally	3		85	75		-		-	-	-	-	-	-	1	-		-	-	-	-
CLO-6: Analyze the outcomes of implementing global standards	3	3	85	75		1	. [- T	-	-	-	-	-	-	-	-	L	-	-	L

Du	ration	Introduction to quality	TQM principles	Statistical process control	TQM tools	Quality systems
(ł	our)	9	9	9	9	9
S-1	SLO-1	Definition of Quality	Customer satisfaction – Customer Perception of Quality	The seven tools of quality	Benchmarking	ISO 9000 Systems
0-1	SLO-2	Dimensions of Quality	Customer Complaints	Cause-and-effect diagram	Reasons to Benchmark	ISO 9000 Systems
S-2	SLO-1	Quality Planning	Service Quality	Check sheet	Benchmarking Process	ISO 9000:2000 Quality System – Elements
3-2	SLO-2	Quality Planning	Customer Retention	Check sheet	Benchmarking Process	ISO 9000:2000 Quality System – Elements
S-3	SLO-1	Quality costs	Employee Involvement	Control chart	Quality Function Deployment (QFD)	Need for Accreditation of hospitals
0-3	SLO-2	Quality costs	Motivation	Control chart	Quality Function Deployment (QFD)	Need for Accreditation of hospitals
S-4	SLO-1	Basic concepts of Total Quality Management	Empowerment	Histogram	House of Quality	FDA Regulations
0-4	SLO-2	Principles of TQM	Teams and Team Work	Histogram	House of Quality	FDA Regulations
S-5	SLO-1	Leadership – Concepts	Recognition and Reward	Pareto chart	QFD Process - Benefits	Joint Commission
3-3	SLO-2	Role of Senior Management	Performance Appraisal	Pareto chart	QFD Process - Benefits	Joint Commission
S-6	SLO-1	Quality Council	Juran Trilogy	Scatter diagram	Total Productive Maintenance (TPM) – Concept	Regulatory Bodies of India

	SLO-2	Quality Statements	Juran Trilogy	Scatter diagram	Total Productive Maintenance	Medical Council of India
S-7	SLO-1	Strategic Planning	PDSA Cycle	Stratification	Improvement Needs	Pharmacy Council Of India
3-1	SLO-2	Strategic Planning	PDSA Cycle	Stratification	Improvement Needs	Pharmacy Council Of India
S-8	SLO-1	Deming Philosophy	Kaizen	Six sigma	FMEA	Indian Nursing Council
3-0	SLO-2	Deming Philosophy	Kaizen	Six sigma	FMEA	Indian Nursing Council
S-9	SLO-1	Barriers to TQM Implementation	5S	Six sigma	Stages of FMEA	Dental Council of India
3-9	SLO-2	Barriers to TQM Implementation	5S	Six sigma	Stages of FMEA	Homeopathy Central Council

Learning Resources	 Rose J.E, Total Quality Management, Kogan Page Ltd., 1993 Cesar A. Cacere, Albert Zana, The Practise of clinical Engineering, Academic Press, 1997 Greg Bounds, Beyond Total Quality Management-Toward the emerging paradigm, McGraw Hill, 2013 	 Joseph J.Carr, Elements of Electronics Instrumentation and Measurement, 2nd ed., Pearson Education, 2003 Jerrold T. Bushberg, John M. Boone, The essential physics of medical imaging, 3rd ed., Lippincott Williams & Wilkins, 2011
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Learning Asses	arning Assessment											
	Bloom's		Final Examination (50% weightage)									
	Level of Thinking	CLA –	1 (10%)	CLA –	2 (15%)	CLA -	3 (15%) CLA –		I (10%)#	Tillal Examination (50% weightage)		
	Level of Thirtking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	
Level 1	Remember	40 %		30 %		30 %	_	30 %		30%		
Level I	Understand	40 /0	-	30 70	-	30 70	-	30 70	-	3070	-	
Level 2	Apply	40 %	_	40 %	_	40 %	_	40 %	_	40%	_	
Level 2	Analyze	70 /0	_	40 /0	_	40 /0	_	40 70	_	4070	_	
Level 3	Evaluate	20 %		30 %	_	30 %	_	30 %		30%		
LEVEL 3	Create	20 70	_	30 /0	_	30 /0	_	30 /0	_	3070	-	
	Total	100) %	100	0 %	10	0 %	100	0 %	10	0 %	

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Course	19ECO126T	Course		Course	_	Professional Elective	L		Р	С
Code	18ECO1261	Name	Sports Diomechanics	Category		Professional Elective	3	0	0	3

Pre-requisite Courses	18ECE267J	Co-requisite Courses		Progressive Courses
Course Offering	Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR): The purpose of learning this course is to:			Learning				Program Learning Outcomes (PLO)										
CLR-1: Understand the fundamental muscle action and locomotion in biomechanical point of view	1	2	3	İ	1	2	3	4	5	6	7	8	9	10	11	12	13 14 15
CLR-2: Get an idea about the movement patterns and causes of movements	<u>_</u>	(9	(0								λ.						the ne
CLR-3: Understand the qualitative and quantitative analysis of sports movements	Thinking (Bloom)	%	Attainment (%)					arch			Sustainability						ing at Medicir velop ary
CLR-4: Acquire an idea about the basic concept of jumping & aerial movement and throwing & hitting	<u>B</u>	5	jeu		gge		eut	ese			aj.		Work		Finance		S Med S Med Develc linary
CLR-5: Get an idea about the injury prevention, rehabilitation and special Olympic sports	ing	ig.	in		Ne l	S	Development	, Re	Usage	ө	Sust		m V		inar	ng	Sol & Sol
CLR-6: Get an overall idea about the applications of biomechanics in sports	i i i i i	<u>م</u>	Λtta		줄	Analysis	svelc	Design,	l Ns	Culture	∞ŏ		Team	igi	∞	arni	roblem of Enga Sesign & Design & Devices on Itidisc for heal
		교			ing	Ans	å D	۾	T00	& Cl	nen		∞ ∞	E	∕lgt.	ong Learning	1: Problem Solving ce of Enaa & Medica C: Design & Develca Devices al Devices i: multidisciplinary or for her her her east
Course Learning Outcomes (CLO): At the end of this course, learners will be able to:	Level of	Expected Proficiency (%)	Expected		Engineering Knowledge	Problem	Design 8	Analysis,	Modern	Society &	Environment	Ethics	Individual &	Communication	Project Mgt.	Life Lon	PSO-1: Interface PSO-:2: Medical PSO-3: IPSO-3: IPSO-3
CLO-1: Illustrate the muscle action in sport and locomotion	1	80	70		М												L
CLO-2: Analyze the movement patterns and its causes	1,2	80	70		Μ												М
CLO-3: Describe the Qualitative and Quantitative analysis of sports movements	2	80	70		М												М
CLO-4: Analyze the movement of action such as jumping, throwing, hitting and aerial movement	2	80	70				L										L L L
CLO-5: Identify the injury scenario and special Olympic sports	2	80	70														L L L
CLO-6: Outline the major concepts in sports biomechanics																	

	ıration	Muscle Action in Sport and Exercise and locomotion- Biomechanical view	Movement patterns and its causes	Qualitative and Quantitative analysis of sports movements	Jumping and Aerial Movement, Throwing and Hitting	Injury Prevention, Rehabilitation and Special Olympic Sports
(1	nour)	9	9	9	9	9
S-1	SLO-1	Introduction to Biomechanics	Introduction to Movement patterns Introduction to Analysis of Sport Movements		Introduction to Aerial movement	Mechanisms of Musculoskeletal Injury
3-1	SLO-2	Applications of Biomechanics	Defining human movements	A structured analysis framework	Types of Aerial Movement - Rotation during flight, Motion of the mass centre	Musculoskeletal Loading During Landing
0.0	3LU-1		Running	Preparation stage	Types of Aerial Movement : Somersaulting, Twisting,	Sport-Related Spinal Injuries and their Prevention
S-2	SLO-2	Mechanical Properties and Performance in Skeletal Muscles	Fundamental movements-Throwing, Jumping	Observation stage	Control of aerial movement	Sport-Related Spinal Injuries and their Prevention
	SLO-1	Muscle-Tendon Architecture	qualitative and quantitative movement	Evaluation and diagnosis stage	Introduction : High Jump	Impact Propagation and its Effects on the Human Body
S-3	SLO-2	Athletic Performance	Comparison of qualitative and quantitative movement analysis	Intervention stage – providing appropriate feedback	Techniques of Jumping - Skating, Springboard and Platform Diving	Impact Propagation and its Effects on the Human Body
S-4	SI ()-1	Eccentric Muscle Action in Sport and Exercise	Movement patterns-geometry of motion	identifying chitcal features of a movement	Determinants of Successful Ski-Jumping Performance	Neuromechanics of the Initial Phase of Eccentric Contraction
3-4	SI ()-/	Stretch–Shortening Cycle of Muscle Function	Fundamentals of movement		Determinants of Successful Ski-Jumping Performance	Induced Muscle Injury

S-5	SLO-1	Biomechanical Foundations of Strength	Linear motion and the centre of mass	The use of videography in recording sports movements	Principles of Throwing	Manual Wheelchair Propulsion	
3-0	SLO-2	Power Training	The geometry of angular motion and the coordination of joint rotations	The use of videography in recording sports movements	The Flight of Sports Projectiles		
S-6	SLO-1	Factors Affecting Preferred Rates of Movement in Cyclic Activities	Forces in sport Recording the movement Ja		Javelin Throwing: an Approach to	Sports after Amputation	
3-0	SLO-2	The Dynamics of Running	Combinations of forces on the sports performer	Experimental procedures -Two dimensional videography	Performance Development	Sports alter Amputation	
S-7	SLO-1	Resistive Forces in Swimming		Experimental procedures -Three dimensional videography	Shot Putting	Biomechanics of Dance	
3-1	SLO-2	Propulsive Forces in Swimming	Force-time graphs as movement patterns	Data processing	Hammer Throwing: Problems and Prospects	biomechanics of Dance	
	SLO-1	Performance-Determining Factors in Speed Skating	Determination of the centre of mass of the human body	Projectile motion	Hammer Throwing: Problems and Prospects		
S-8	SLO-2	Cross-Country Skiing: Technique	Fundamentals of angular kinetics and Generation and control of angular momentum	Linear velocities and accelerations caused by rotation	Hitting	Biomechanics of Martial arts	
S-9	SLO-1	Cross-Country Skiing: Equipment	Measurement of force	Rotation in three-dimensional space	Kicking	Biomechancis of YOGA	
	SLO-2	Factors Affecting Performance	Measurement of pressure	Rotation in three-dimensional space	Simple concept problems		

Learning Resources
Resources

- Susan J Hall, "Basic Biomechanics", McGraw-Hill Higher Education, 7th edition, 2014
 Vladimir M. Zatsiorsky, Biomechanics in Sports: Performance Enhancement and Injury Prevention, 1st ed., Blackwell Science Ltd, 2000
- Jules Mitchell, "Yoga Biomechanics", 1 edition, Handspring Publishing Limited, 2018
 Roger Bartlett, Introduction to Sports Biomechanics: Analysing Human Movement Patterns, 2nd ed., Routledge,

Learning Assessment													
	Bloom's		Final Evamination (F0% weighteds)										
	Level of Thinking			CLA – 2 (15%)		CLA -	3 (15%)	CLA – 4	1 (10%)#	Final Examination (50% weightage)			
	Level of Thirking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice		
Level 1	Remember Understand	40 %	-	40 %	-	40 %	-	30 %	-	30%	-		
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-		
Level 3	Evaluate Create	20 %	-	20 %	-	20 %	-	30 %	-	30%	-		
	Total 100 %		10	100 % 100 %			10	0 %	100 %				

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Course Code	18ECO131J	Course Name	VIRTUAL INSTRUM	ENTATION I	Course Category	0	Open Elective	2	T 0	P 2	C 3
Pre-requis Courses	INII		Co-requisite Courses		Progres Cours	sive ses	Nil				
Course Offe	ring Department	Electro	nics and Communication Engineering	Data Book / Codes/Standards	Nil						

					,															
Course L	earning Rationale (CLR): The purpose of learning this course is to:	L	earnii	ng						Prog	ram L	_earn	ing O	utcor	nes (PLO)				
CLR-1:	Study the concepts of Virtual instrumentation and to learn the programming concepts in VI.	1	2	3		1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Study about the various real time data acquisition methods.								ا			ity						for ms	o for	
CLR-3:	Study about the various Instrument Interfacing concepts.	(mo	(%)	(%)		e		Ħ	earc			nabil		논		m		control te syste	200	
CLR-4:	To study the programming techniques for various control techniques using VI software	(Bloom)				/led		Development	Res	ge		Sustainability		ı Work		Finance	D		∞ ∞	v
CLR-5:	To study various analysis tools for Process control applications.	king	Proficiency	Attainment		Š	alysis	/elop	Design,	Usage	ulture	S S		Team	ation	& Fin	earning		e PLC tems	five skill
CLR-6:	To study various real time measurement systems	Thinking	P			ing.	Ana		Ğ	T00	O	ent		∞ŏ	icati	Mgt. 8		Automatic is & discre	Utilize of syste	:ffec
		of.	xpected	Expected		Engineering Knowledge	oblem	esign &	Analysis,		ety &	Environment	ςς	ndividual	ommunic	oct N	Long	÷. g	-2: L	-3: E
Course L	earning Outcomes (CLO): At the end of this course, learners will be able to:	Leve	EX D	Exp		Engi	Prob	Desi	Anal	Modern	Soci	ĒN	Ethics	Indiv	Com	Project	Life	PSO conti	PSC	PSC
CLO-1:	An ability to understand the purpose of virtual instrumentation and understand the construction of VI	1,2	80	70		Н												Н		
CLO-2:	An ability to understand and apply various data acquisition methods.	2	85	75		Н												Н	Н	
CLO-3:	An ability to understand and implement the available interfacing instruments	2	75	70		Н	Н	Н	Н	Н								Н	Н	Н
CLO-4:	An ability to understand and implement various control techniques using VI software	2,3	85	80		Н	Н	Н	Н	Н								Н		Н
CLO-5:	An ability to understand and develop a program foran engineering application.	2,3	85	75		Н	Н	Н	Н	Н				Н	Н	Н	Н	Н	Н	
CLO-6:	An ability to understand and implement various, measurement systems	2.3	80	70	ĺ	Н	Н	Н	Н	Н				Н	Н	Н	Н	Н	Н	

D		Learning Unit / Module 1	Learning Unit / Module 2	Learning Unit / Module 3	Learning Unit / Module 4	Learning Unit / Module 5
Duratio	n (hour)	12	12	12	12	12
	SL0-1	Historical perspective, Need of VI, Advantages of VI, Virtual Instruments versus Traditional Instruments	A/D Converters, Organization of the DAQ VI system -	Introduction to PC Buses	Introduction to Non continuous controllers in LabVIEW	PC based digital storage oscilloscope
S-1	SLO-2 Review of software in Virtual Instrumentation , Software environment Architecture of VI, Introduction to the block diagram and Front panel Pallets		D/A Converters, Types of D/A	Local Buses-ISA, PCI,	Introduction to continuous controllers in LabVIEW	Sensor Technology
	Creating and saving a VI, Front Panel SLO-1 Tool Bar, Block diagram Tool Bar, Palettes		r, Block diagram Tool Bar, Input and Output Cards - Digital Input and Output Cards		Design of ON/OFF controller	Applications of sensor Technology
S-2	SLO-2	Creating sub VI, Creating an ICON, Building a connector pane, Displaying VI'S, Placing and Saving Sub VI'S on block diagram, Example of full adder circuit using half adder circuit	Organization of the DAQ VI system -	RS485	Proportional controller for a mathematically described processes using VI software	Signal processing Techniques
	SLO-1	Lab-1: Front Panel controls and Indicator	Lab-12: Measurement of diode I-V		Lab-22: On-off temperature controller	
S-3	51 ()-7	Lab-2: Verification of Arithmetic Operations	characteristics using LabVIEW	Lab-17: Load cell Data acquisition	using LabVIEW	Lab-28: Design of DSO
S-4	SLO-1 Lab-3: Verification of Half Adder Lab-13: Temp		Lab-13: Temperature measurement using	using RS232	Lab-23: Continuous Control of temperature	Lab-29: Analysis of different signal
3-4	SLO-2	Lab-4: Verification of Full adder.	LabVIEW and DAQ hardware.		using LabVIEW	Filters using LabVIEW
S-5	SLO-1	Loops-For Loop,	Opto Isolation need	Interface Buses-USB,PXI	Modeling of level process	Spectrum Analyzer

	SLO-2	While Loop	Performing analog input and analog output	VXI,	Basic control of level process in LabVIEW	Waveform Generator
S-6	SLO-1	Arrays,	Scanning multiple analog channels	SCXI	Modeling of Reactor Processes	Data visualization from multiple locations
3-0	SLO-2	Clusters, plotting data	Issues involved in selection of Data acquisition cards	PCMCIA	Basic control of Reactor process in LabVIEW	Distributed monitoring and control
S-7	SLU-1	Lab-5: Program to find Addition of First n natural numbers using for loop		Lab-18: DC motor control using VXI	Lab-24: On-off Level controller using	Lab-30: Real time spectrum analysis
3-1		Lab-6: Program to find Addition of First n odd numbers using while loop.	Lab-14: Flow measurement in water using		LabVIEW	using LabVIEW
S-8		Lab-7: Implementation of Array functions.	LabVEW and DAQ hardware	Lab-19: GPIB with VISA functions	Lab-25: Continuous Control of pressure	Lab-31: Arbitratory Waveform
	SLO-2	Lab-8: Calculation of BMI using cluster			controller using LabVIEW	Generator using LabVIEW
S-9	SLO-1	Charts	Data acquisition modules with serial communication	Instrumentation Buses - Modbus and GPIB	Case studies on development of HMI in VI	Vision and Motion Control
2-9	SLO-2	Graphs	Design of digital voltmeters with transducer input	Networked busses – ISO/OSI	Case studies on development of HMI in VI	Examples on Integrating Measurement with vision and motion
S-10	SLO-1	Case and Sequence Structures	Timers and Counters	Reference model,	Case studies on development of SCADA in VI	NI Motion control
5-10	SLO-2	Formula nodes, String and File Input/Output.	Timers and Counters	Ethernet and TCP / IP Protocols	Case studies on development of SCADA in VI	Speed control system
S-11	SLO-1	Lab-9: Monitoring of temperature using Charts and Graphs	Lab-15: Design of digital voltmeters with	Lab-20: Online temperature control	Lab-26: On-off pressure controller using	
3-11		Lab-10: Program for implementing Seven segment display	transducer input using LabVIEW	using LabVIEW using TCP/IP	LabVIEW	Lab-32: Minor Project
S-12	SLO-1 Lab-11: Program to perform Traffic light Lab-16		Lab-16: Pressure measurement using LabVEW and DAQ hardware DAQ.	Lab-21: Online temperature control using Web publishing tool	Lab-27: Continuous Control of pressure controller using LabVIEW	

Learning
Resources
Resources

- Nadovich, C., Synthetic Instruments Concepts and Applications, Elsevier, 2005
 Bitter, R., Mohiuddin, T. and Nawrocki, M., Labview Advanced Programming Techniques, 2nd ed., CRC Press, 2007
 Gupta, S. and Gupta, J. P., PC Interfacing for Data Acquisition and Process Control", 2nd ed., Instrument Society of America, 1994
- Jamal, R., Picklik, H., Labview Applications and Solutions, National Instruments Release.
 Johnson, G., Labview Graphical programming, McGraw-Hill, 1997
 Wells, L.K., Travis, J., Labview for Everyone, Prentice Hall, 1997
 Buchanan, W., Computer Busses, CRC Press, 2000

Learning Ass	sessment												
	Bloom's			Conti	nuous Learning Ass	essment (50% weig	htage)			Final Evamination	n (50% weightage)		
	Level of Thinking	CLA – 1 (10%)		CLA – 2 (15%)		CLA -	3 (15%)	CLA – 4	(10%)#	FIIIai Examinatio	ii (50% weightage)		
	Level of Thirking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice		
Level 1	Remember Understand	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%		
Level 2	Apply Analyze	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%		
Level 3	Evaluate Create	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%		
	Total	Total 100 %			0 %	10	0 %	100) %	100 %			

[#] CLA - 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. D. Karthikeyan, Controlsoft Engineering India Pvt Ltd, karthikeyan.d@controlsoftengg.in	1. Dr. J. Prakash, MIT, Chennai, prakaiit@rediffmail.com	1. Dr. K. A. Sunitha, SRMIST
2. V. Venkateswaran, Instrumentation Consultant, wvenkat99@gmail.com	2. Dr. D. Nedumaran, Madras University, dnmaran@qmail.com	2. Mrs. A. Brindha, SRMIST

Course	18ECO132T	Course	ANALYTICAL INICTOLIMENTATION	Course	0	Open Elective	L	T	Р	С
Code	10ECO 1321	Name	ANALTHOAL INSTRUMENTATION	Category	U	Open Elective	3	0	0	3

Pre-requisite Nil	Co-requisite Courses	Nil		Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engine	ering	Data Book / Codes/Standards	Nil	

Course Learning Rationale (CLR): The purpose of learning this course is to:	L	earning Program Learning Outcomes (PLO)																
CLR-1: Understand the principle and theory of analytical instruments	1	2	3		1	2	3	4	5	6	7	8	9	10	11	12 1	3 14	15
CLR-2: Understand the quantitative analysis of dissolved components											≥					j.	or Jo	ent
CLR-3: Study the concept of separation science and its applications	Ê	(%)			_			arch			iig		_					management
CLR-4: Study the various spectroscopic techniques and its instrumentation	(Bloom)	()	ıt (%)		gge		ent	ese			ain		Work		8	ontro	& D	aua (
CLR-5: Identify and solve engineering problems associated with Radiation Techniques	9 (B	roficiency	Attainment		× e	S	mdo	œ.	age	Ф	Sustainability		E .		Finance		, # O	Ĕ
CLR-6: Understand the working of Analytical Instrument and their importance in industries	Thinking	ofici	ā		호	ılysi	velc	sigr	Ns	Culture			Team	io	∞ŏ	earning	disc re P	tive
	Ę				ing	Analysis	& Development	å	Tool Usage	S C	neu			ica	Mgt.		% <u>#</u> %	ı iii
Course Learning Outcomes (CLO): At the end of this course, learners will be able to:	Level of	Expected	Expected		Engineering Knowledge	Problem	Design 8	Analysis, Design, Research	Modem -	Society &	Environment &	Ethics	Individual &	Communication	Project N	Life Long	continou PSO-2: 1	PSO-3: I skills
CLO-1: Apply the principles and theory of instrumental analysis	1,2	80	70		Н	Н	L	L	Н	Н	Н					1	H	L
CLO-2: Apply the principles of various chemical analysis instruments in industries	1,2	85	75		Н	Н	L	L	Н	Н						ı	H	L
CLO-3: Analyze and understand the operation of various radio chemical methods of analysis	1,2	75	70		Н	Н	L	L	Н	Н						I	H	L
CLO-4: To analyze and understand the operation of instruments based on optical properties	1,2	85	80		Н	Н	L	L	Н	Н						ı	H	L
CLO-5: To identify and solve engineering problems associated with Radiation Techniques	1,2	85	75		Н	Н	L	L	Н	Н						I	Н	L
CLO-6: To understand the working of analytical Instruments in industries	1,2	80	70		Н	Н	L	L	Н	Н						I	Н	L

D	(1	Learning Unit / Module 1	Learning Unit / Module 2	Learning Unit / Module 3	Learning Unit / Module 4	Learning Unit / Module 5
Duratio	n (hour)	9	9	9	9	9
S-1	SLO-1	Introduction to Chemical instrumental analysis	Dissolved oxygen analyzer, Importance of measuring dissolved oxygen in Industry, Principle working	Chromatography, Importance, Basic working of Chromatography	Spectral methods of analysis- Properties or parameters of electromagnetic radiation	NMR spectrometers ,Importance and basic working of NMR Spectroscopy
	SLO-2	Spectral method of analysis	Working of Dissolved oxygen analyzer	Gas chromatography Instrumentation	Electromagnetic spectrum Types of spectrometers	Magnetic assembly, Probe unit, Instrument stabilization
S-2	SLO-1	Electro analytical and seperative methods	sodium analyzer, Importance of measuring sodium in Industry, Principle working	Basic parts of a gas chromatography	Beer's law UV-visible spectrophotometers Transmittance and absorbance	Types of NMR spectrometer, Minimal type
3-2	SLO-2	Instrumental methods of analysis-basic components and their classification	Working of sodium analyzer	Carrier gas supply Sample injection system	Beer's law Application of beer's law	Multipurpose NMR, Wideline
S-3	SLO-1	Sampling systems	Silica analyzer, Importance of measuring Silica in Industry, Principle working	Chromatographic column, Selection of column	Derivations of beer's law	Applications of NMR Spectrometer
3-3	SLO-2	Importance of Sampling system in chemical Industries and Safety aspects	Working of Silica Analyzer	Thermal compartment, Detection system, Recording system	Single beam and double beam instruments	Mass Spectrometers, Basic working and Importance
S-4	SLO-1	PH Measurement, Principle of PH measurement & Importance of PH measurement in Industries	Moisture measurement Importance of Moisture measurement	Liquid chromatography-Principles, types and applications	IR spectrophotometers Instruments of IR	Components of Mass Spectrometers
3-4	SLO-2	Types of Electrodes, Reference Electrodes and types	Types of Moisture measurement	High pressure liquid chromatography	Types of IR Components required for three types of IR	Types of Mass spectrometers Magnetic Sector analyzer, Double focusing spectrometers
S-5	SLO-1	Secondary Electrodes and Types	Oxygen analyzer Methods of oxygen analyzers and importance	Instrumentation or basic component of HPLC	Instruments of dispersive instrument , IR Radiation Sources and types	Time of flight analyzers, Quadrupole Mass analyzers

	SLO-2	Indicator electrodes	Paramagnetic oxygen analyzer Electro analytical method	Solvent reservoir and its treatment system	Importance of Monochromators and types of Monochromators	Application of mass spectrophotometers
		pH meters direct reading type pH meter null detector type pH meter	CO monitor,Importance of measuring CO	Pumping system, Types of working systems and Importance	Samples And Sample Cells detectors	nuclear radiation detectors, importance of measurement
S-6	SLO-2	ion selective electrodes Types of ion selective electrodes Glass membrane electrodes Liquid membrane electrodes Solid membrane Electrodes	Types of CO monitor	Pulse dampers	FTIR spectrometers, Main components Advantages, disadvantages	GM counter
S- 7	SLO-1	Biosensors Features of Biosensor Block diagram of bio sensor	NO2 analyzer, Importance of NO ₂ measurement	Sample injection system and types	Types of sources Selection factors	Working setup, advantages of GM Counter
	SLO-2	Applications of Biosensors in industries	Types of NO₂ measurement	Liquid chromatographic column working , Types of Column thermostats	Types of detectors Selection factors	proportional counter, Basic Principle
S-8	SLO-1	conductivity meters ,Importance in Chemical Industries	H ₂ S analyzer, Importance of H ₂ S Measurement	Detection system types	atomic absorption spectrophotometer instruments for atomic absorption spectroscopy	Working setup, advantages of GM Counter
	SLO-2	Types of Conductivity meters	Types of H ₂ S measurement	Types of Recording system	radiation source chopper	solid state detectors, Basic Principle
	SLO-1	Air pollution Monitoring Instruments	Dust and smoke measurement- dust measurement and Importance Types of dust measurement	Application of HPLC, Advantages of HPLC over gas chromatography	production of atomic vapor by flame, Parts by flame photometer Emission system	Working setup, advantages of Solid state detectors
S-9	SLO-2	Estimation of Air pollution	Thermal analyzer , Importance of Thermal analyzers, Types of Thermal analyzer	Detectors types, Factors Influencing the Selection of Detectors	Monochromators And types, Types of Detectors and recording systems and their selection criteria	scintillation counter, Basic principle

Learning
Resources

- Khandpur. R.S, "Handbook of Analytical Instruments", Tata McGraw Hill publishing Co. Ltd., 2006
 Bella. G, Liptak, "Process Measurement and analysis"., CRC press LLC., 2003.
 Francis Rousseau and Annick Rouesssac "Chemical analysis Modern Instrumentation Methods and Techniques", John wiley & sons Ltd. 2007.
- James W.Robinson, "Undergraduate Instrumental Analysis", Marcel Dekker., 2005.
 Dwayne Heard, "Analytical Techniques for atmospheric measurement", Blackwell Publishing, 2006.

Learning Ass	sessment										
	Bloom's				Einal Evamination	n (50% weightage)					
	Level of Thinking	CLA -	1 (10%)	CLA –	2 (15%)	CLA –	3 (15%)	CLA – 4	(10%)#		i (50 % weightage)
	Level of Thirking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %		30 %		30 %		30 %		30%	
Level I	Understand	40 //	-	30 /0	-	30 //	-	30 /0	-	3070	-
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create		2 0/		2.04		2 0/		2.01	40	2.01
	Total 100 % 100 %			100	0 %) %	100 %			

[#] CLA - 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. D. Karthikeyan, Controlsoft Engineering India Pvt Ltd, karthikeyan.d@controlsoftengg.in	1. Dr. J. Prakash, MIT, Chennai, prakaiit@rediffmail.com	Dr. K. A. Sunitha, SRMIST
2. V. Venkateswaran, Instrumentation Consultant, wvenkat99@gmail.com	2. Dr. D. Nedumaran, Madras University, dnmaran@qmail.com	Mrs. A. Brindha, SRMIST

Course	18ECO133T Course	LOCIC AND DISTRIBUTED CONTROL SYSTEM	Course	Open Elective	L	Т	Р	С
Code	Name	LOGIC AND DISTRIBUTED CONTROL SYSTEM	Category	Open Elective	3	0	0	3

Pre-requisite Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication	Data Book / Codes/Standards	Nil	

Course Learning Rationale (CLR): The purpose of learning this course is to:		Learning				Program Learning Outcomes (PLO)														
CLR-1: Understand basic components of PLC		1	2	3		1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2: Understand the use of timers and counters in process automation												y						for ns	for	ent
CLR-3: Understand DCS architecture		Ê		<u></u>					arch			iji ge							SS	management
CLR-4: Understand operator and engineering interface in DCS		(Bloom)	y (%)	t (%)		dge		ent	Se			aji		/or		9		control e syste	& DC	inaç in
CLR-5: Understand HART signal standard and Field bus		9 (B	enc	l eu		w e	S	md	, Re	age	Φ	Sustainability		Team Work		Finance	Вu	U +=		
CLR-6: Understand Field bus signal standard.		hinking	Proficiency	Attainment		호	Analysis	Development	Design,	l ns	Culture			Tea	ion	∞ŏ	arni	mat	ze PL stems	Stive
		Ę	- L	Αt		ing	Ang	& De	9	Tool Usage	ರ ಶ	neu		∞	ica	∕lgt.	J Le	Automatic is & discre	Utilize of syste	Effective
Course Learning Outcomes (CLO): At the end of this course, learners will be able to:		Level of	Expected	Expected		Engineering Knowledge	Problem	Design 8	Analysis,	Modem	Society &	Environment &	Ethics	Individual	Communication	Project Mgt.	Life Long Learning	PSO 1: /	성실	PSO-3: I
CLO-1: Select PLC based on I/O's		2,3	80	80	Ī	Н	М	L	-	-	-	-	-	М	-	М	L	М		М
CLO-2: Apply timers and counters in process automation		1,2	80	80		Н	Η	Н	Н	Н	-	L	-	Н	Μ	L	L	Н	Н	Η
CLO-3: Select LCU based on application		1	80	80		Н	М	-	-	-	-		-	L	-	-	L	М	L	М
CLO-4: Analyse data's in Operator displays				80		Н	Н	-	Н	-	-	-	-	Н	Μ	-	L	Н	L	М
CLO-5: Interpret industrial data communication modes				80	Ī	Н	-	-	-	-	-	-	-	-	L	-	L	Н	-	L
CLO-6: Gain knowledge on field bus		3	80	80	Ī	Н	L	-	-	-	-	-	-	-	-	-	L	Н	-	L

Duratio	n (hour)	9	9	9	9	9
	SLO-1	Programmable logic controllers	PLC Programming Languages	Evolution of DCS	Operator Interfaces Requirements	Introduction to HART
S-1	SLO-2	PLC vs Computer	Ladder Diagram	Hybrid System Architecture	Process Monitoring	Evolution of Signal standard
S-2	SLO-1	Parts of a PLC	Functional block	Central Computer system Architecture	Process Control	HART Networks: Point-to-Point
	SLO-2	Architecture	hitecture Sequential Function Chart DCS Arci		Process Diagnostics	Multi-drop
S-3	SLO-1	PLC size and Application.	Instruction List	Comparison of Architecture	Process Record Keeping	Split range control valve
3-3	SLO-2	Fixed and Modular I/O	Structured Text	Local Control Unit Architecture	Low Level Operator Interface	HART Field Controller Implementation
	SLO-1	Discrete Input Modules	Wiring Diagram	Architectural Parameters	High Level Operator Interface	Hart Commends: Universal
S-4	SLO-2	Discrete Output Modules	Ladder logic Program	Comparison Of LCU Architecture	Hardware Elements In The Operator Interface	Common Practice
S-5	SLO-1	Analog Input Modules	On-Delay Timer Instruction	LCU Language Requirements	Operator Input And Output Devices	Device Specific
3-3	SLO-2	Analog Output Modules	Off-Delay Timer Instruction	Function Blocks	Operator Display Hierarchy	Wireless Hart
S-6	SLO-1	Special I/O Modules	Retentive Timer	Function Block Libraries	Plant-Level Display	Field Bus Basics
3-0	SLO-2	High Speed Counter Module	Cascading Timer	Problem-Oriented Language	Area- Level Display	Field Bus Architecture
S-7	SLO-1	Power Supplies	Up-Counter	LCU Process Interfacing Issues	Group- Level Display	Field Bus Standard
3-1	SLO-2	Isolators	Down-Counter	Security Requirements	Loop- Level Display	Field Bus Topology
	SLO-1	Input/output Devices: Switches	Cascading Counters	Security Design Approach	Engineering Interface Requirements	H1 Field Bus
S-8	SLO-2	sensors	Combining Counter And Timer Functions	On-Line Diagnostics	Requirement For Operator Interface Configuration	H2 Field Bus
S-9	SLO-1	Relays	Math Operation	Redundant Controller Design	Low Level Engineering Interface,	Interoperability
3-9	SLO-2	Solenoid valve	Program	One-On-One, One-On-Many Redundancy	High Level Engineering Interfaces	Interchangeability

Learning
Resources

- Frank D. Petruzella, <u>Programmable Logic Controller, Tata McGraw Hill Fifth Edition, 2017</u>
 Bolton. W, Programmable Logic Controllers, 6th Edition, Elsevier Newnes, Sixth Edition 2016.
 Krishna Kant, Computer Based Industrial Control, Second edition, Prentice Hall of India, New Delhi,2015
- Bowten, R HART Application Guide, HART Communication foundation, 2015.
 Berge, J, Field Busses for process control: Engineering, operation, maintenance, ISA press,2015

Learning Ass	sessment												
	Bloom's			Conti	inuous Learning Ass	essment (50% weig	htage)			Final Examination (50% weightage)			
	Level of Thinking	CLA -	1 (10%)	CLA –	2 (15%)	CLA -	3 (15%)	CLA – 4	(10%)#	FIIIai Examinatio	ii (50% weightage)		
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice		
Level 1	Remember Understand	40 %	-	30 %	-	30 %	-	30 %	-	30%	-		
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-		
Level 3	Evaluate Create	20 %	-	30 %	-	30 %	-	30 %	-	30%	-		
" 01 4 4	Total		0 %	10	0 %	10	0 %) %	10	0 %		

[#] CLA - 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. D. Karthikeyan, Controlsoft Engineering India Pvt Ltd, karthikeyan.d@controlsoftengg.in	1. Dr. J. Prakash, MIT, Chennai, <u>prakaiit@rediffmail.com</u>	Mr. J. Sam Jeba Kumar, SRMIST
2. V. Venkateswaran, Instrumentation Consultant, wenkat99@gmail.com	2. Dr. D. Nedumaran, Madras University, dnmaran@gmail.com	Dr. G. Joselin Retna Kumar, SRMIST

Course Code	18ECO134T	Course Name	SENSORS AND TRANSDUCERS	Course	0	Open Floative	L	T	Р	С
Course Code	10ECO 1341	Course Name	SENSORS AND TRANSDUCERS	Category	U	Open Elective	3	0	0	3

Pre-requisite Nil	Co-requisite Courses		Progressive Courses
Course Offering Department	Electronics and Instrumentation Engineering	Data Book / Codes/Standards	Nil

Learning 2

Course Lea	rning Rationale (CLR):	The purpose of learning this course is to:					
CLR-1:	Gain knowledge on classification	, and characteristics of transducers					
CLR-2:	CLR-2: Acquire the knowledge of different types of inductive and capacitive sensors						
CLR-3:	Acquire the knowledge of differen	nt types of thermal and radiation sensors					
CLR-4:	Acquire the knowledge of differen	nt types of magnetic sensors					
CLR-5:	Acquire the knowledgeof differen	t types of sensors measuring non-Electrical quantity					
CLR-6:	Locate the Applications of senso	ors in industries and home appliances					
Course Lea	rning Outcomes (CLO):	At the end of this course, learners will be able to:					
CLO-1:	CLO-1: To demonstrate the various types of basic sensors.						

Understand the inductive and capacitive sensors which are used for measuring various

To demonstrate the various types of basic sensors measuring non electrical quantity

کی Level of Thinking (Bloom)	S Expected Proficiency (%)	S Expected Attainment (%)	
2,3	80	80	
1,2	80	80	
1	80	80	
3 3	80	80	
3	80	80	
3	80	80	

	Program Learning Outcomes (PLO)													
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO 1: Automatic control for continuous& discrete systems	PSO-2: Utilize PLC & DCS for control of systems	PSO-3: Effective management skills
Н	-	Н	-	-	Η	Н	Η	-	-	-	Н	Н	-	-
Н	-	-	Н	-	Н	-	-	-	-	-	Н	-	Н	-
-	-	-	-	-	Н	-	-	Н	Н	-	-	Н	-	-
-	Н	Н	-	-	-	-	-	-	-	-	-	-	Н	-
-	-	Н	-	Н	-	-	-	-	-	-	Н	-	1	Н
Н	-	Н	-	-	Н	Н	Н	-	-	-	Н	Н	-	-

Duratio	n (hour)	9	9	9	9	9
S-1	SLO-1	Introduction to sensors/ transducers, Principles	Introduction to Inductive sensor	Thermal sensors: Introduction	Magnetic sensors: Introduction	Measurement of Non-Electrical quantity: Introduction
	SLO-2	Classification based on different criteria	Sensitivity and linearity of the sensor	Thermal Expansion type.	Villari effect	Flow Measurement – Introduction.
	SLO-1	Characteristics of measurement systems	Transformer type transducer	Acoustics temperature sensors.	Wiedmann effect	Ultrasonic Flow Meters.
S-2	SLO-2	Static characteristics Accuracy, Precision, Resolution, Sensitivity	Electromagnetic transducer	Thermo-emf sensor.	Hall effect	Hot Wire Anemometers.
S-3	SLO-1	Dynamic characteristics.	Magnetosrtictive transducer	Materials for thermos-emf sensors.	Construction,	Electromagnetic Flow meters.
3-3	SLO-2	Environmental Parameters	Materials used in inductive sensor	Thermocouple construction	performance characteristics,	Principle and types.
	SLO-1	Characterization and its type	Mutual Inductance change type	Types.	and its Application	Measurement of Displacement.
S-4	SLO-2	Electrical characterization.	LVDT: Construction.	Thermo-sensors using semiconductor device	Introduction to smart sensors	Introduction and types.
S-5	SLO-1	Mechanical Characterization.	Material, input output relationship,	Pyroelectric thermal sensors	Film sensors: Introduction	Measurement of Velocity/ Speed.
3-3	SLO-2	Thermal Characterization	Synchros-Construction	Introduction	Thick film sensors	Introduction and types.
S-6	SLO-1	Optical Characterization.	Capacitive sensor: Introduction	characteristics	Microelectromechanical systems	Measurement of Liquid Level.
3-0	SLO-2	Errors and its classification.	Parallel plate capacitive sensor	Application	Micromachining.	Introduction and types.
S-7	SLO-1	Selection of transducers.	Variable thickness dielectric capacitive sensor	Radiation sensors.	Nano sensors	Measurement of Pressure.

CLO-2:

CLO-3:

CLO-4:

CLO-5:

CLO-6:

parameters.

Understand the thermal and radiation sensors

Select the right transducer for the given application

Have an adequate knowledge on the various magnetic sensors

	SLO-2	Introduction to mechanical sensors	Electrostatic transducer	Introduction	Applications: Industrial weighing systems: Link–lever mechanism.	Introduction and types.
S-8	SLO-1 Resistive potentiometer and types		Piezoelectric elements	I C.naracteristics	Load cells – pneumatic, elastic and their mounting.	Measurement of Vibration.
3-0	SLO-2	Strain gauge: Theory, type, design consideration, sensitivity.	Ultrasonic Sensors	Geiger counters	different designs of weighing systems.	Introduction and types.
S-9	SI O-1	Resistive transducer: RTD, materials used in RTD	Calculation of sensitivity.	Scintillation detectors	conveyors type.	Application of sensors in industries
3-9	SLO-2		Capacitor microphone, response characteristics	Application on radiation sensors	weighfeeder type.	Application of sensors in home appliances

Learning Resources	1. 2. 3.	Patranabis, D., "Sensors and Transducers", 2 nd Edition, Prentice Hall India Pvt. Ltd, 2010. Doeblin, E.O., "Measurement Systems: Applications and Design", 6 th Edition, Tata McGraw-Hill Book Co., 2011. Bentley, J. P., "Principles of Measurement Systems", 4 th Edition, Addison Wesley Longman Ltd.,	5.	Murthy, D.V.S., "Transducers and Instrumentation", Prentice Hall of India Pvt. Ltd., New Delhi, 2010. Neubert H.K.P., "Instrument Transducers – An Introduction to their performance and Design", Oxford University Press, Cambridge, 2003.
	5.	UK, 2004.		University Fress, Cambridge, 2003.

Learning Asses	sment												
	Bloom's		Continuous Learning Assessment (50% weightage)										
	Level of Thinking	CLA –	1 (10%)	CLA –	2 (15%)	CLA –	3 (15%)	CLA – 4	(10%)#	Final Examination (50% weightage)			
	Level of Thirtking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice		
Level 1	Remember Understand	40 %	-	30 %	-	30 %	-	30 %	-	30%	-		
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-		
Level 3	Evaluate Create	20 %	-	30 %	-	30 %	-	30 %	-	30%	-		
	Total	10	0 %	10	0 %	100	0 %	100 %					

[#] CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers										
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts								
1. D. Karthikeyan, Controlsoft Engineering India Pvt Ltd, karthikeyan.d@controlsoftengg.in	1. Dr. J. Prakash, MIT, Chennai, <u>prakaiit@rediffmail.com</u>	Mrs. K. Vibha, SRMIST								
2. V. Venkateswaran, Instrumentation Consultant, wvenkat99@gmail.com	2. Dr. D. Nedumaran, Madras University, dnmaran@gmail.com	Dr. G. Joselin Retna Kumar, SRMIST								

Course	18ECO135T	Course	FUNDAMENTALS OF MEMS	Course	0	Open Elective	L	Т	Р	С
Code	10ECO 1331	Name	FUNDAMENTALS OF MEMS	Category	U	Open Elective	3	0	0	3

Pre-requisite Courses	lil .	Co-requisite Nil	Progre Cour	NII
Course Offering De	epartment Electronics and Comm	munication Engineering Data Boo	ok / Codes/Standards Nil	

Course Learning Rationale (CLR): The purpose of learning this course is to:		Learn	ing					Progr	ram L	.earni	ng O	utcon	nes (l	PLO)			
CLR-1: Understand the importance of micro system technology	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13 14	15
CLR-2: Learn the operating principle of various micro sensors and actuators	æ															for ms for	ent
CLR-3: Impart the applications of various micro fabrication techniques	(Bloom)	(%)	(%):				arch			i E							E H
CLR-4: Understand the differences and need for microfabrication	<u>a</u>	5	ent	ge		ent	Se			aina		Work		9		control ste syst	nag
CLR-5: Operate MEMS design tools to design simple micro devices	Thinking	Proficiency	Attainment	× e	S	E E	, Re	Usage	Φ	Sustainability		<u>د</u>		Finance	ng	atic o iscreti PLC	ms ms
CLR-6: Understand recent developments and challenges in MEMS	.≧	g.	∖tta	Ϋ́	Analysis	Vel Ve	Design,	ns	Culture	∞ర		Team	io	∞ర	earning.	E P B	ctive
	1 È	<u>8</u>		ing	Ans	& Development	9	Tool	ರ ಶ	neu		య	ica	Mgt.		Auto Lus& Utiliz	f sv
Course Learning Outcomes (CLO): At the end of this course, learners will be able to:	Level of	Expected	Expected	Engineering Knowledge	Problem	Design 8	Analysis,	Modern .	Society 8	Environment	Ethics	Individual	Communication	Project N	Life Long	PSO 1: / continuo PSO-2: 1	control o PSO-3: I skills
CLO-1: Appreciate the fundamental concepts in MEMS technology	2,3	80%	80%	Н	-	-	-	-	Н	-	-	-	-	-	Н	Н -	Н
CLO-2: Understand the fabrication and machining techniques of MEMS devices	1,2	80%	80%	Н	-	-	-	-	Н		-	-	-	-	Н		Н
CLO-3: Familiarize with the concepts of packaging of MEMS devices	1	80%	80%	Н	-	-	Н	-	Н	-	-	-	-	-	Н	Н -	Н
CLO-4: Appreciate the significance of micro fabrication processes	3	80%	80%	Н	-	-	Н		-				-	-	Н		Н
CLO-5: Design and Simulate simple structures using MEMS software			80%	Н	-	Н	Н	Н	-	-	Н	Н	-	-	Н	Н -	Н
CLO-6: Analyze recent trends and developments in MEMS technology				Н	-	-	Н	-	-	-	-	-	-	-	Н	Н -	Н

Du	ration	Introduction	Fabrication overview	Micromachining	Bonding & Sealing	Recent trends
(1	our)	9	9	9	9	9
S-1	SLO-1	Introduction to MEMS and Brief recap of Macro devices	Introduction to Micro fabrication process	Introduction of micro machining(MMC) process	Introduction to MEMS packaging	Introduction to design tools and simulation
	SLO-2	Microelectronics and Micro systems	Significance of each technique	Significance of MMC	Challenges in packaging	FEM analysis
S-2	SLO-1	Scaling laws in geometry	Process Description of Photolithography	Bulk MMC process – merits and demerits	Different levels of Packaging	Design of a silicon die for a micro pressure sensor
	SLO-2	Silicon as ideal material and as substrate	Implementation of Photolithography	Sequence of steps	Die, device and system level	Simulation in software
S-3	SLO-1	Si wafer production	Process Description of CVD	Significance of Isotropic etching	Differences in IC packaging technology	Application of MEMS in automotive industry
3-3	SLO-2	Cz process	Implementation, merits and demerits of CVD	Anisotropic etching	And MEMS packaging	Airbag deployment
S-4	SLO-1	Sequential steps in wafer processing	Process Description of PVD	Surface MMC process	Die Preparation	Optical MEMS Application
	SLO-2		Implementation, merits and demerits of PVD	Sequence of steps	Plastic encapsulation and its significance	Micro mirrors
S-5	SLO-1	Chemical and mechanical properties of Si and compounds	Process Description, implementation of Ion implantation	Challenges in surface MMC	Types of wire bonding Thermo compression type	Micro fluidics Application
3-3	SLO-2	Chemical and mechanical properties of Polymers, Quartz and GaAs	Oxidation process	Interfacial & Residual stresses	Thermo sonic, Ultra sonic type	Lab on chip module
S-6	SLO-1	Chemical, Biomedical type Micro sensors	Diffusion process	LIGA process- description merits and demerits	Types of surface bonding – Adhesive	IR and Gas sensing

	SLO-2	Piezoelectric type of Micro sensors	Wet etching methods	Implementation	soldering, SOI type of bonding	Thermal sensors
S-7	SLO-1	Thermal, SMA, Piezoelectric actuators	Properties of etchants	Process Design-block diagram and description	Anodic bonding and lift off process	Micro power generation
	SLO-2	Electro static type Micro Actuators	Dry etching methods	Electro-mechanical design, Thermo- electric design	Precautions to be taken	Micro TEG
6 0	S-8 SLO-1 a SLO-2 A SLO-1	Micro devices- operation of Micro gears and micromotors	Production of plasma	CAD- block diagram description and	Types of sealing- Micro shells, Hermetic sealing	Chemical sensors
3-0		Micro devices –operation of Micro valves and pumps	Etch stop methods	implementation	Micro 'O' rings,Reactive seal	Micro humidity sensors
8.0		Case study	Case study	Case study	Selection of packaging materials	Micro pressure sensors
3-9	SLO-2	Case study	Case study	Case study	Material requirements	Paper MEMS

Learning	1.	Tai-Ran Hsu, "MEMS and MICROSYSTEMS", 22 nd reprint edition, Wiley & sons, 2015	3.	VardhanGardener,"Micro sensors and smart devices", John Wiley & Sons,2001
Resources	2.	M. Madou, "Fundamentals of Micro fabrication", Taylor and Francis group, 2002	4.	NPTEL link: https://nptel.ac.in/downloads/112108092/

Learning Assess	sment											
	Bloom's		Final Evamination	(E00/ weightege)								
		CLA – 1 (10%)		CLA – 2 (15%)		CLA –	3 (15%)	CLA – 4 (10%)#		Final Examination (50% weightage)		
	Remember	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	
Level 1	Remember	30 %		30 %		30 %		30 %		30%		
Level I	Understand	30 /0	-	30 /0	-	30 //	-	30 /0	-	3070	-	
Level 2	Apply	40 %		40 %		40 %	_	40 %		40%		
Level 2	Analyze	40 /0	-	40 /0	-	40 /0	-	40 /0	-	4070	-	
Level 3	Evaluate	30 %		30 %	_	30 %	_	30 %		30%		
Cr	Create	30 /0	-	30 /0	-	30 //	-	30 /0	-	3070	-	
	Total	al 100 % 100 %		0 %	10	0 %	100	0 %	10	0 %		

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Course Designers										
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1. D. Karthikeyan, Controlsoft Engineering India Pvt Ltd, karthikeyan.d@controlsoftengg.in	1. Dr. J. Prakash, MIT, Chennai, <u>prakaiit@rediffmail.com</u>	1. Dr. A. Vimala Juliet, SRMIST								
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. D. Nedumaran, Madras University, dnmaran@gmail.com	2. R.Bakiyalakshmi,SRMIST								

B. Tech in Electronics and Communication Engineering

(with Specialization in Instrumentation Engineering)

2018 Regulations

Project Work, Seminar, Internship in Industry / Higher Technical Institutions (P)

Department of Electronics and Communication Engineering SRM Institute of Science and Technology SRM Nagar, Kattankulathur – 603203, Kancheepuram District, Tamilnadu

Course	18ECP109L /	Course	D	ROJECT / SEMESTE	D INTEDNICUID	Cours	se		Project Work, Seminar, Internship	In Industry / Higher	L	Т	Р	С
Code	18ECP110L	Name	r	NOCE OF THE COLUMN TO THE COLU		Catego	ory	P	Technical Institution	ns (P)	0	0	20	10
Pre-requisi Courses				requisite Nil			rogress Course		Nil					
Course Offer	ing Department	Е	lectronics and Commun	ication Engineering	Data Book / Codes/Standards	As	required	d for th	ne project work					
Course Learn	ning Rationale (C	CLR):		The purpose of learn	ing this course is to:									
CLR-1:	To prepare	the student to	gain major design and	or research experienc	e as applicable to the profession									
CLR-2:	Apply know	ledge and skill	s acquired through earli	er course work in the	chosen project									
CLR-3:	Make conve	ersant with the	codes, standards , appl	lication software and e	quipment									
CLR-4:	Carry out th	e projects with	in multiple design const	traints										
CLR-5:	Incorporate	multidisciplina	ry components											
CLR-6:	Acquire the	skills of comp	rehensive report writing											
				1										
Course Learn	ning Outcomes (CLO):		At the end of this course, learners will be able to:										
CLO-1 :	Design a sy	stem / process	or gain research insigh	t into a defined proble	m as would be encountered in engin	eering pra	nctice tak	king in	to consideration its impact on global, ec	onomic, environmental a	and so	cial co	ontext.	
Learning Ass	sessment													
Continuous I	Learning	Assessment to	pol F	Review I	Review II				Review III Total					
Assessment	•	Weightage	Ę	5%	20%				25%	50%				
Assessment tool				Project Report	Viva Voce *	1	Total							
Final Evaluat	tion	Weightage	2	20% 30% 50%						50%				

^{*} Student has to be present for the viva voce for assessment. Otherwise it will be treated as non-appearance for the examination with final grade as 'Ab'

Course	40500407	Course		MINOR PRO		Course	e		Proiect Work. Seminar	r, Internship In Industry / Higher	L	Т	Р	С
Code	18ECP107L	Name		MINOR PROJECT		Catego	ry	P		Technical Institutions (P)		0	6	3
Pre-requis Courses				equisite ourses			ogressiv Courses		Nil					
Course Offe	ring Departmen	: El	lectronics and Communi	ication Engineering	Data Book / Codes/Standards	As r	equired t	for th	ne project work					
Course Lear	ning Rationale	CLR):		The purpose of learn	ning this course is to:									
CLR-1:	Prepare ti	e student to form	mulate an engineering p	problem within the do	main of the courses undergone									
CLR-2:	Seek solu	ion to the proble	em by applying codes / s	standards/ software o	r carrying out experiments or through	h programm	ing							
Course Lear	ning Outcomes	(CLO):		At the end of this course, learners will be able to:										
CLO-1:	Identify a	mall part of majo	or system or process, ur	nderstand a problem	associated with it and find solution o	r suggest a	procedui	re lea	ading to its solution.					
Learning Ass	essment													
Continuous L	ontinuous Learning Assessment tool			Review I	Review II		Fir		Final Review *	Total				
Assessment	Weightage		2	20%	30%			50%		100%	100%			

^{*} Student has to be present for final review for assessment. Otherwise it will be treated as non-appearance for the examination with final grade as 'Ab'

Course Code	18ECP102L / 18ECP105L	Course Name		Indu	strial Trainir	ng I/II	Course Category	P		Project Work, Seminar, Internship In Industry / Higher Technical Institutions (P)	L 0	T 0	P 2	C 1
Pre-requisi Courses Course Offer		E	Electronics and Com	Co-requisite Courses nmunication Eng	Nil	Data Book / Codes/Standards	U	gressive burses posed to		Vil ring the duration of training				
Course Learn						ng this course is to:	arch institut	9						
Course Learn	ning Outcomes (C					se, learners will be able to:								
CLO-1 :	Gain confider	ce to carry o	out supervisory, mar	nagerial, and de	esign roles in	an industrial context.								
Learning Ass	sessment													
					sment tool					Final review				
Continuous I	tinuous Learning Assessment			Weigh	Weightage			Training Report Presentation * 75% 25%						

^{*} Student has to be present for the presentation for assessment. Otherwise it will be treated as non-appearance for the examination with final grade as 'Ab'

Course	18ECP108L	Course		Intern	nip	Course Category	P		, Internship In Industry / Higher	L	Т	Р	С
Code		Name		Ca				recnnica	al Institutions (P)	0	0	6	3
Pre-requis			Co-rec Cou	quisite rses		Progre Cour	essive eses	Nil					
Course Offe	ering Department	E	lectronics and Communica	ation Engineering	on Engineering Data Book / Codes/Standards As exposed to during the duration of internship								
		,				,							
Course Lea	rning Rationale (CL	.R):	7	he purpose of le	ning this course is to:								
CLR-1 :	Provide an ex	cposure to the	e students on the practical	application of th	oretical concepts in an industry or res	earch institute a	nd also	to gain hands on experience	in the context of design, production	n and n	nainte	nance	е
Course Lea	rning Outcomes (C	LO):	A	t the end of this o	urse, learners will be able to:								
CLO-1:	Gain confider	ice to carry o	ut supervisory, manageria	l, and design role	in an industrial context or research e	environment							
Looming As													
Learning As	ssessment			Assessment to				Final review					
Continuous	ontinuous Learning Assessment							Training Report	Presentation*				
				vveigntage	Weightage			75%	25%				

^{*} Student has to be present for the presentation for assessment. Otherwise it will be treated as non-appearance for the examination with final grade as 'Ab'

Course Code	18ECP103L / 18ECP106L	Course Name		Seminar I/II C			P		nternship In Industry / Higher Institutions (P)	L 0	T 0	P (C 1
Pre-requisi Courses	IVII		Cou	equisite Nil	Det Dest (October Constant	Cou	rses	Nil					
Course Offer	ing Department	EIG	ectronics and Communic	auon Engineering	Data Book / Codes/Standards	As appl	Ісаріе						
Course Learn	ning Rationale (CL	R):	7	The purpose of learni	ng this course is to:								
CLR-1:	Identify an are	ea of interest	within the program or a	related one (multidis	ciplinary), carry out a literature surve	y on it, gain u	nderstand	ding and present the same bef	ore an audience.				
Course Learn	ning Outcomes (CI	_0):	A	At the end of this cour	se, learners will be able to:								
CLO-1 :	Carry out a se	elf-study of an	area of interest and com	communicate the same to others with clarity.									
Learning Ass	sessment												
				Assessment tool			Prese	entation					
Continuous I	ntinuous Learning Assessment			Weightage			Prese	entation material	Presentation skills / abilir / understanding of the to		nswer	questio	าร
				0 0	Toghago			60% 40%					

^{*} Student has to be present for the presentation for assessment. Otherwise it will be treated as non-appearance for the examination with final grade as 'Ab'