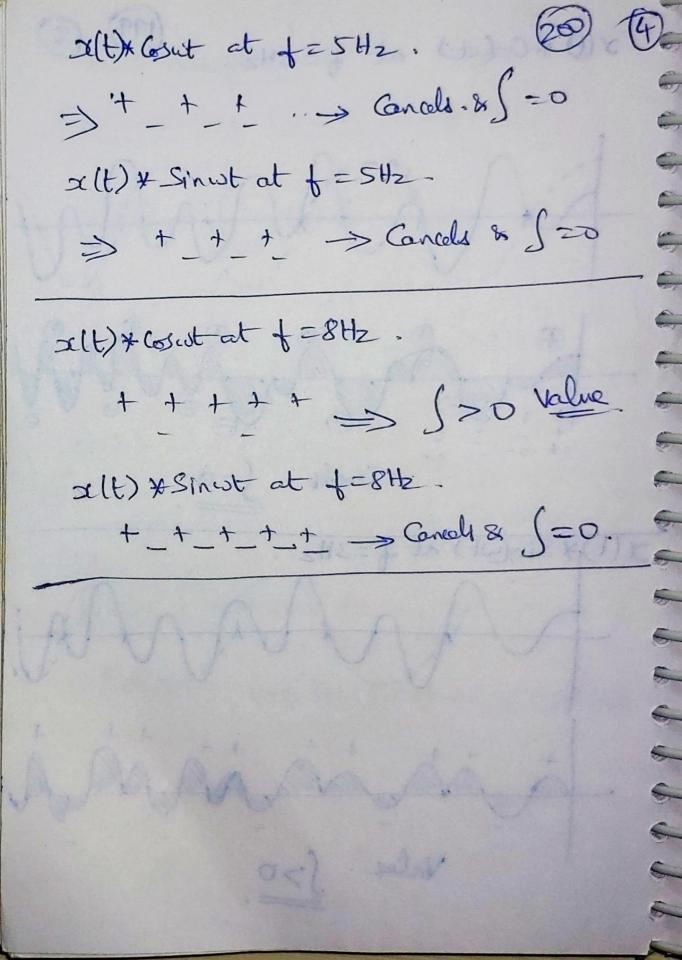
FOURIER TRANSFORM. From Fourier series Analysis egn; $a_{k} = \frac{1}{T} \int_{0}^{T} x(t) e^{-jku_{0}t} dt$. Synthesis equ, $\chi(t) = \xi^{t}$ q_{k} Analyzing function: - Correlating with Sine and paralyze that the function

as sine Component (ex) Cosine Component.

Synthesis function: After analyzing whether the function has sine (or) cosine Component, the original function has to be generated by utilizing all the homories.

Fourier Transform: Continuous time Fourier Transform: X(jw)= jost dt. ak= - [x(t) e dt] X(w)= fx(t) cosut dt + fx(t) is in wt dt. Example: - 0.6 Sin (3Hz) +0.8.68(8Hz)

3 Y (1) * Cos(wet) at f=3Hz. THE MANAGER # Carrel 5=0 3x(t) * Sin(wt) at f=3Hz. MAM to faster aster as faster as faster



Determine the Facien transporm of the (216)

briangular function shown below,

$$\Delta(t/r).$$

$$\begin{array}{c|c} & & & & & & & \\ & & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ &$$

$$\frac{y}{x+\eta_{0}} = \frac{2}{\gamma}$$

$$y = \frac{2}{\gamma}(t+\eta_{0})$$

少二十学

$$y = \frac{\lambda}{\gamma} \left[\frac{2t+\gamma}{\lambda} \right]$$

$$= \frac{2t+\gamma}{\gamma}$$

 $\alpha(t) = \Delta(t/r) = \int (1+\frac{2t}{r}) tr - \frac{\tau}{2} ct 20.$ 1-25 to Octo7/2. o elsewhere. > X(w) = F[x(t)] = \$\int \D(t/x).e^{-jwt} dt. $=\int \left(1+\frac{2t}{7}\right) \xrightarrow{-\int wt} dt + \int \left(1-\frac{2t}{7}\right) \xrightarrow{-\int wt} dt.$ $=\int^{\gamma/2} \left(1-\frac{2b}{\gamma}\right) e^{j\omega t} dt + \int^{\gamma/2} \left(1-\frac{2b}{\gamma}\right) e^{-j\omega t} dt.$ $=\int_{0}^{12} \int_{0}^{12} dt - \int_{0}^{2} \int_{0}^{10} dt + \int_{0}^{2} \int_{0}^{10} dt - \int_{0}^{2} \int_{0}^{10} dt$ 1/2 [jut - jut] dt - 2 5 = [jut - jut] dt. 7/2 = \int 2 Cos wt dt - \frac{2}{7} \int t. (2 Cos wt) dt.

$$= \begin{cases} 2 \cos \omega t dt - \frac{2}{\gamma} \begin{cases} 2 t \cos \omega t dt \end{cases}$$

$$= 2 \begin{cases} \sin \omega t \\ \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \sin \omega t \\ \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \sin \omega t \\ \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \sin \omega t \\ \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \sin \omega t \\ \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \sin \omega t \\ \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \cos \omega t \\ \cos \omega t \end{cases}$$

$$= \frac{2}{\omega} \begin{cases} \sin \omega t \\ 2 - \sin \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \sin \omega t \\ \cos \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \cos \omega t \\ \cos \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \cos \omega t \\ \cos \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \cos \omega t \\ \cos \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \cos \omega t \\ \cos \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \cos \omega t \\ \cos \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \cos \omega t \\ \cos \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \cos \omega t \\ \cos \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \cos \omega t \\ \cos \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \cos \omega t \\ \cos \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \cos \omega t \\ \cos \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \cos \omega t \\ \cos \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \cos \omega t \\ \cos \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \cos \omega t \\ \cos \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \cos \omega t \\ \cos \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \cos \omega t \\ \cos \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \cos \omega t \\ \cos \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \cos \omega t \\ \cos \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \cos \omega t \\ \cos \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \cos \omega t \\ \cos \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \cos \omega t \\ \cos \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \cos \omega t \\ \cos \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \cos \omega t \\ \cos \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \cos \omega t \\ \cos \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \cos \omega t \\ \cos \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \cos \omega t \\ \cos \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \cos \omega t \\ \cos \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \cos \omega t \\ \cos \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \cos \omega t \\ \cos \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \cos \omega t \\ \cos \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \cos \omega t \\ \cos \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \cos \omega t \\ \cos \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \cos \omega t \\ \cos \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \cos \omega t \\ \cos \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \cos \omega t \\ \cos \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \cos \omega t \\ \cos \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \cos \omega t \\ \cos \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \cos \omega t \\ \cos \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \cos \omega t \\ \cos \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \cos \omega t \\ \cos \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \cos \omega t \\ \cos \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \cos \omega t \\ \cos \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \cos \omega t \\ \cos \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \cos \omega t \\ \cos \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \cos \omega t \\ \cos \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \cos \omega t \\ \cos \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \cos \omega t \\ \cos \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \cos \omega t \\ \cos \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \cos \omega t \\ \cos \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \cos \omega t \\ \cos \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \cos \omega t \\ \cos \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \cos \omega t \\ \cos \omega t \end{cases} - \frac{4}{\gamma} \end{cases} - \frac{4}{\gamma} \begin{cases} \cos \omega t \\ \cos \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \cos \omega t \\ \cos \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \cos \omega t \\ \cos \omega t \end{cases} - \frac{4}{\gamma} \end{cases} - \frac{4}{\gamma} \begin{cases} \cos \omega t \\ \cos \omega t \end{cases} - \frac{4}{\gamma} \begin{cases} \cos \omega t \\ \cos \omega t \end{cases} - \frac{4}{\gamma} \end{cases} - \frac{4}{\gamma} \begin{cases} \cos \omega t \\ \cos \omega t \end{cases} - \frac{4}{\gamma} \end{cases} - \frac{4}{\gamma} \begin{cases} \cos \omega t \\ \cos \omega t \end{cases} - \frac{4}{\gamma} \end{cases} - \frac{4}{\gamma} \end{cases} - \frac{4}{\gamma} \end{cases} - \frac{4}{\gamma} \begin{cases} \cos \omega t \\ \cos \omega t \end{cases} - \frac{4}{\gamma} \end{cases} - \frac{4}{\gamma} \end{cases}$$

$$=\frac{8}{\omega^2 \tau} \cdot \sin^2\left(\frac{\omega \tau}{4}\right)$$
 (219)

$$= \frac{8}{\omega^2 \gamma} \left(\frac{\omega \gamma}{4}\right)^2 \cdot \frac{\sin^2\left(\frac{\omega \gamma}{4}\right)}{\left(\omega \gamma/4\right)^2}.$$

$$=\frac{\gamma}{2}\cdot\frac{\sin^2(\frac{\omega\tau}{4})}{[\omega\tau/4]^2}$$

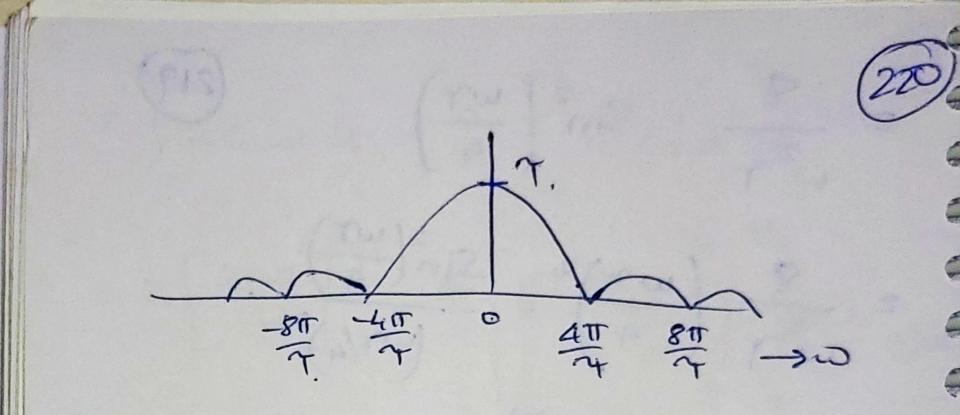
$$= \frac{\gamma}{2} \cdot \operatorname{Sinc}\left(\frac{\omega \gamma}{4}\right).$$

$$\Rightarrow \left[\Delta(t/r) \longleftrightarrow \frac{\gamma}{2} \operatorname{Sinc}^{2}(\frac{\omega r}{4})\right]$$

$$\Rightarrow \left[\Delta(t/\tau) \longleftrightarrow \frac{\gamma}{2} \operatorname{Sin}^{2}(\frac{\omega \tau}{4})\right]$$

$$\Rightarrow \omega \cdot \kappa \cdot t \cdot F\left[\Delta(t/\tau)\right] = \frac{\gamma}{2} \frac{\operatorname{Sin}^{2}(\frac{\omega \tau}{4})}{|\omega \tau/4|^{2}}$$

$$\omega \tau = \pi \kappa .$$



1. Determine the Fourier Transform of the following signal, -4. -2 2 4 >t $T(t) = \begin{cases} 2 & \text{for } -4ctc-2. \\ 4. & \text{for } -2ctc2. \end{cases}$ otherwise. $= \int_{-4}^{2} 2e^{-j\omega t} dt + \int_{-2}^{2} 4e^{-j\omega t} dt + \int_{2}^{2} 2e^{-j\omega t} dt$ $= \left[\frac{-j\omega + -j\omega}{2} + \left[\frac{-j\omega + -j\omega}{2} + \left[\frac{2j-j\omega + -j\omega}{2} \right] \right] + \left[\frac{2j-j\omega + -j\omega}{2} \right] + \left[\frac{2j-j\omega + -j\omega + -j\omega}{2} \right] + \left[\frac{2j-j\omega + -j\omega + -j\omega}{2} \right] + \left[\frac{2j-j\omega + -j\omega}{2} \right] + \left[\frac{2j-j$

$$= \frac{2}{j\omega} \left[\frac{12\omega}{2} + \frac{12\omega}{2} - \frac{12\omega}{2} + \frac{12\omega}{2} \right] + \frac{12\omega}{2} +$$