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Enercia m 18 We have 
$$p_m = P(x=m) = \frac{\lambda^n e^{-t}}{m!}$$

\* The expectation:  $E_x = \frac{1}{n e \ln n} = \frac{m!}{m!} = \frac{m!}{m!} = \frac{1}{m!} = \frac{1}{m!}$ 

$$= \sum_{\substack{m \geq 1 \\ m \geq 1}} \frac{m^{2} A^{m} e^{-\lambda}}{m!} - \lambda^{2}$$

$$= \lambda e^{-\lambda} \left[ \sum_{\substack{m \geq 1 \\ m \geq 1}} \frac{m^{2} A^{m} e^{-\lambda}}{m!} + \sum_{\substack{m \geq 0 \\ m \geq 1}} \frac{\lambda^{m}}{m!} + \sum_{\substack{m \geq 0 \\ m \geq 1}} \frac{\lambda^{m}}{m!} - \lambda^{2}$$

$$= \lambda e^{-\lambda} \left[ \lambda \sum_{\substack{m \geq 0 \\ m \geq 1}} \frac{\lambda^{m-1}}{m!} + \sum_{\substack{m \geq 0 \\ m \geq 0}} \frac{\lambda^{m}}{n!} - \lambda^{2} \right]$$

$$= \lambda e^{-\lambda} \left[ \lambda e^{\lambda} + e^{\lambda} \right] - \lambda^{2}$$

$$= \lambda^{2} + \lambda - \lambda^{2} = \lambda$$

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thereice u 2.

\* (xi) i = 1, ..., n ou in de peu dont ~ P(li) We howe \* \lambda = \sum\_{i=1} \lambda\_i \text{ and } y = \sum\_{i=1} y\_i The aim of the exercic is to show that y is a poisson Variable with parameter 1. To do this, let's take first y= xx + x2 with x1 ~ P(1) XX NP(Nx)

Now, we have:

$$P(y=k) = \sum_{i=0}^{k} P(x_i = i), x_2 = k-i) = P(x_1 + x_2 = k)$$

$$X_1 \text{ and } x_2 \text{ independent } k$$

$$= \sum_{i=0}^{k} \frac{\lambda_1}{i!} e^{-\lambda_1} \times \frac{\lambda_2}{k!} e^{-\lambda_2} \times \frac{\lambda_2}{(k-i)!}$$

$$= e^{-\lambda_1} e^{-\lambda_2} \times \frac{\lambda_2}{(k-i)!} e^{-\lambda_2} \times \frac{\lambda_2}{(k-i)!} e^{-\lambda_2}$$

$$= e^{-\lambda_1} e^{-\lambda_2} \times \frac{\lambda_2}{(k-i)!} e^{-\lambda_2} \times \frac{\lambda_2}{(k-i)!} e^{-\lambda_2}$$

$$= e^{-\lambda_1} e^{-\lambda_2} \times \frac{\lambda_2}{(k-i)!} e^$$

stabilizing transformation (VST) follows three Steps: @ apply VST to approximate homoscedosticity @ Denoise the transformed data 3 Apply an inverse VST

First, we have a noisy image in = 4 + g(u) m with { n ~ N(0,1) u is a noiseless image.

(1) Applying VST: Let's take f. a soft function. we have f(") ~ f(u) + f'(u) g(u) m Ming Taylor approximation 2.

We hove also: g(u) = Vor (u) = u ( assuming that we have a linear moise) Thus, of(u) = Vu. Now, we want to take a real and smooth function of such that f(i) gets a uniform standord deviation independent of u. The easy case is: f(u) = a Tut; with a is a constant (2) The denoising post consists in eliminating the noise term from the previous result and thus, we opt: f(m) n f(m) A pplying the inverse of VST; which is not j'ustam algebric inverse of the VST and must be optimed to avoid biais. u\* = f (f(m)) m f (f(u)) m u. Following these three steps, we found that we have denoised the noisy image using the standard variance Stabilizing traws formation. Enercie n 5: The operator Ding minimizing the mean square error (MSE) Ding = Organin E { 11 U-DUIND } We want to show that  $\frac{1}{|x|} = \frac{1}{|x|} = \frac{1}{|x$ E(110-Dü112) = [ Ku,61> [ 702] We have: Ding = arg min E{ 11 U - DO 1123 E { 11 U - D" 112 } = E { 11 U - [ a(i) < U'Gi>Gi) } = E { | | [ (U,Gi) Gi - [ a(i) (U,Gi) Gi | ] } .3.

-4

Enercie nb:

If we restricts a (i) E \ \ 0.1] the projection operator that minimizes the MSE is obtained with acre 1 1 / U.G. >1> CEP for some well chosen c >1 the corres ponding MSE Satisfies E(110- Dy or 12) « I min (Kubixticar) and this inequality becomes on equality for c = 1.

We have the projector all = { 1 is | < U, Gi>1° ; Coi2 \* if cx1 -> / < 0,61>1 > C T2 => a(1) = 1. => MSE = \( \int \frac{1}{\sqrt{1}^2} \) \( \sqrt{1} \langle \frac{1}{\sqrt{1}} \langle \frac{1}{\sqrt  $= \sum_{i=1}^{n-1} \Delta_{i,n} \quad \sigma(i) = \sum_{i=1}^{n-1} \Delta_{i,n} \quad \langle \sum_{i=1}^{n-1} C \Delta_{i,n} \rangle$ =) MSE { \ \ min{cm2, Kuigisle } be come KiGis/2 > Core => min { C 412 , 1 < 0,6:>12 } = C 12 - 1 (0,6;>12 (CDID =) a (i) = 0 MSE = [ (1-a(1)) 2 / (U161) 12 + a(1) 172 = [ 1 < 0,61 > | 0 = I min { | < 0.617 | con2 } become Kuisisto / cmo => min { | \( \alpha \text{!} \( \alpha \text{!} \) \\ \( \alpha \text{!} \) \\\ \( \alpha \text{!} \) \\\\ \alpha \text{!} \) \\\\ \( \alpha \text{!} \) \\\\ \alp => MSE { min { | < 0,61>12, C 12 } fact # 9 C = 1 -> / (0,61) 12 > The => a(1) = 1 MSE = [" (1-a a))2/ (1.61)2 72 = I min { \tau 2 | Ku Gi> |2) - / < U, (61 > )2 < 012 = 0 a(1) = 0 MSE = [ " (1 - a (1)) 2 / < U (61 > 12 + a (1)) 412 = [ ] / < U, G; > 1 = [ ] min { 42, KO, G; > 12} - [ ]

=> MSE = I min { Ti2, IXU, Gi>12}

To conclude : given the projector aci); MSE / I min {CT? KUGI}

Enercice m7: "DCT and IDCT are isometries in IR" and inverse of each other."

\*DCT for  $0 \le k \le N-1$  ; for  $0 \le d \le N-1$   $\forall k = 2 \le k \le N-1$ With  $d_k = \begin{cases} \sqrt{\frac{1}{4N}} & k = 0 \\ \sqrt{\frac{1}{2N}} & k = 1, ..., N-1 \end{cases}$ 

DCT:  $X \leftarrow AX$  { with  $A_{ij} = 2\alpha_i \cos(T(i+i))$  } with  $\alpha_i = \begin{cases} \sqrt{\frac{1}{4}n^2} & i=0 \\ \sqrt{\frac{1}{2}n^2} & \forall i \leq n-1 \end{cases}$ 

The DCT is a luicax transformation in function of X. Now, if h is an orthogonal matrix, this transformation will act as an isometry.

In other words: DCT is an isometry  $\Leftrightarrow$  ATA = Id. ATA | ATA

$$= \sum_{k=0}^{N-1} A_{ki} A_{kj}$$

$$= \sum_{k=0}^{N-1} 2d_k (e_2) (\pi (i+\frac{1}{2})\frac{k}{N}) \times 2d_k (e_2) (\pi (d+\frac{1}{2})\frac{k}{N})$$

$$= \frac{1}{2} \sum_{k=0}^{N-1} 2d_k (e_2) (\pi (i+\frac{1}{2})\frac{k}{N}) (e_2) (\pi (d+\frac{1}{2})\frac{k}{N})$$

$$= \frac{1}{2} \sum_{k=0}^{N-1} 2d_k (e_2) (\pi (i+\frac{1}{2})\frac{k}{N}) (e_2) (\pi (d+\frac{1}{2})\frac{k}{N})$$

$$= \frac{1}{2} \sum_{k=0}^{N-1} 2d_k (e_2) (\pi (i+\frac{1}{2})\frac{k}{N}) (e_2) (\pi (d+\frac{1}{2})\frac{k}{N})$$

$$= \frac{1}{2} \sum_{k=0}^{N-1} 2d_k (e_2) (\pi (i+\frac{1}{2})\frac{k}{N}) (e_2) (\pi (d+\frac{1}{2})\frac{k}{N})$$

$$= \frac{1}{2} \sum_{k=0}^{N-1} 2d_k (e_2) (\pi (i+\frac{1}{2})\frac{k}{N}) (e_2) (\pi (d+\frac{1}{2})\frac{k}{N})$$

$$= \frac{1}{2} \sum_{k=0}^{N-1} 2d_k (e_2) (\pi (i+\frac{1}{2})\frac{k}{N}) (e_2) (\pi (d+\frac{1}{2})\frac{k}{N})$$

$$= 2 \sum_{k=0}^{N-1} d_k^2 \left[ \cos \left( \frac{Tk}{N} \left( i + \delta + 1 \right) \right) + \cos \left( \frac{Tk}{N} \left( i - \delta \right) \right) \right]$$

$$= 2 \sum_{k=0}^{N-1} d_k^2 \left[ \cos \left( \frac{Tk}{N} \left( i + \delta + 1 \right) \right) + 2 \sum_{k=0}^{N-1} d_k^2 \left[ \cos \left( \frac{Tk}{N} \left( i - \delta \right) \right) \right]$$

$$= 2 \sum_{k=0}^{N-1} d_k^2 \left[ \cos \left( \frac{Tk}{N} \left( i + \delta + 1 \right) \right) + 2 \sum_{k=0}^{N-1} d_k^2 \left[ \cos \left( \frac{Tk}{N} \left( i - \delta \right) \right) \right]$$

$$= 2 Re \left( \sum_{k=0}^{N-1} d_k^2 \left[ \cos \left( \frac{Tk}{N} \left( i + \delta + 1 \right) \right) + 2 \sum_{k=0}^{N-1} d_k^2 \left[ \cos \left( \frac{Tk}{N} \left( i - \delta \right) \right) \right] \right]$$

$$= 2 Re \left( 2 d_0^2 + \sum_{k=1}^{N-1} d_k^2 \left[ \cos \left( \frac{Tk}{N} \left( i + \delta + 1 \right) \right) + 2 \sum_{k=1}^{N-1} d_k^2 \left[ \cos \left( \frac{Tk}{N} \left( i + \delta + 1 \right) \right) + 2 \sum_{k=1}^{N-1} d_k^2 \left[ \cos \left( \frac{Tk}{N} \left( i + \delta + 1 \right) \right) + 2 \sum_{k=1}^{N-1} d_k^2 \left[ \cos \left( \frac{Tk}{N} \left( i + \delta + 1 \right) \right) + 2 \sum_{k=1}^{N-1} d_k^2 \left[ \cos \left( \frac{Tk}{N} \left( i + \delta + 1 \right) \right) + 2 \sum_{k=1}^{N-1} d_k^2 \left[ \cos \left( \frac{Tk}{N} \left( i + \delta + 1 \right) \right) + 2 \sum_{k=1}^{N-1} d_k^2 \left[ \cos \left( \frac{Tk}{N} \left( i + \delta + 1 \right) \right) + 2 \sum_{k=1}^{N-1} d_k^2 \left[ \cos \left( \frac{Tk}{N} \left( i + \delta + 1 \right) \right) + 2 \sum_{k=1}^{N-1} d_k^2 \left[ \cos \left( \frac{Tk}{N} \left( i + \delta + 1 \right) \right) + 2 \sum_{k=1}^{N-1} d_k^2 \left[ \cos \left( \frac{Tk}{N} \left( i + \delta + 1 \right) \right) + 2 \sum_{k=1}^{N-1} d_k^2 \left[ \cos \left( \frac{Tk}{N} \left( i + \delta + 1 \right) \right) + 2 \sum_{k=1}^{N-1} d_k^2 \left[ \cos \left( \frac{Tk}{N} \left( i + \delta + 1 \right) \right) + 2 \sum_{k=1}^{N-1} d_k^2 \left[ \cos \left( \frac{Tk}{N} \left( i + \delta + 1 \right) \right) + 2 \sum_{k=1}^{N-1} d_k^2 \left[ \cos \left( \frac{Tk}{N} \left( i + \delta + 1 \right) \right) + 2 \sum_{k=1}^{N-1} d_k^2 \left[ \cos \left( \frac{Tk}{N} \left( i + \delta + 1 \right) \right) + 2 \sum_{k=1}^{N-1} d_k^2 \left[ \cos \left( \frac{Tk}{N} \left( i + \delta + 1 \right) \right) + 2 \sum_{k=1}^{N-1} d_k^2 \left[ \cos \left( \frac{Tk}{N} \left( i + \delta + 1 \right) \right) + 2 \sum_{k=1}^{N-1} d_k^2 \left[ \cos \left( \frac{Tk}{N} \left( i + \delta + 1 \right) \right) + 2 \sum_{k=1}^{N-1} d_k^2 \left[ \cos \left( \frac{Tk}{N} \left( i + \delta + 1 \right) \right] + 2 \sum_{k=1}^{N-1} d_k^2 \left[ \cos \left( \frac{Tk}{N} \left( i + \delta + 1 \right) \right] + 2 \sum_{k=1}^{N-1} d_k^2 \left[ \cos \left( \frac{Tk}{N} \left( i + \delta + 1 \right) \right] + 2 \sum_{k=1}^{N-1} d_k^2 \left[ \cos \left( \frac{Tk}{N} \left( i + \delta + 1 \right) \right] + 2 \sum_{k=1}^{N-1} d_k^2 \left[ \cos \left( \frac{Tk}{N} \left( i + \delta + 1 \right) \right] + 2 \sum_{k=1}^{N-1} d_k^2 \left[ \cos \left( \frac{Tk}{N} \left( i + \delta + 1 \right) \right] + 2 \sum_{k=1}^{N-1} d_k^2 \left[ \cos \left( \frac{Tk}{N} \left( i + \delta + 1 \right) \right] + 2 \sum_{k=1}^{N-1} d_k^2 \left[ \cos \left( \frac{Tk}{N} \left( i + \delta + 1 \right) \right]$$

$$= 1 + \frac{1}{N} \operatorname{Re} \left( \begin{array}{c} \frac{e^{i\pi} \left( \frac{3i+1}{N} \right)}{N} + \frac{1}{N} \\ \frac{e^{i\pi} \left( \frac{3i+1}{N} \right)}{N} + \frac{e^{i\pi} \left( \frac{3i+1}{N} \right)}{N} + \frac{e^{i\pi} \left( \frac{3i+1}{N} \right)}{N} \right)$$

$$= 1 + \frac{1}{N} \operatorname{Re} \left( \begin{array}{c} \frac{e^{i\pi} \left( \frac{3i+1}{N} \right)}{N} + \frac{e^{i\pi} \left( \frac{3i+1}{N} \right)}{N} + \frac{e^{i\pi} \left( \frac{3i+1}{N} \right)}{N} \right)$$

$$= 1 + \frac{1}{N} \operatorname{Re} \left( \begin{array}{c} \frac{2i\pi}{N} \left( \frac{3i+1}{N} \right) + \frac{e^{i\pi} \left( \frac{3i+1}{N} \right)}{N} + \frac{e^{i\pi} \left( \frac{3i+1}{N} \right)}{N} \right)$$

$$= 1 + \frac{1}{N} \operatorname{Re} \left( \begin{array}{c} \frac{2i\pi}{N} \left( \frac{3i+1}{N} \right) + \frac{e^{i\pi} \left( \frac{3i+1}{N} \right)}{N} + \frac{e^{i\pi} \left( \frac{3i+1}{N} \right)}{N} \right)$$

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$$= 1 + \frac{1}{N} \operatorname{Re} \left( \begin{array}{c} \frac{2i\pi}{N} \left( \frac{3i+1}{N} \right) + \frac{e^{i\pi} \left( \frac{3i+1}{N} \right)}{N} + \frac{e^{i\pi} \left( \frac{3i+1}{N} \right)}{N} \right)$$

$$= 1 + \frac{1}{N$$

we have Aij = & di ces (TT (++1) in) and  $B_{ij} = \delta \beta_i \cos \left( \pi \left( i + \frac{1}{2} \right) \frac{d}{N} \right)$ we have  $\beta_0' = \alpha_i \implies A_{ij} = B_{ii}$  =  $B_{ij} = A_{ji}$ => IDCT = Y | ATY is an isometry because (AT) (ATT = ATA = Id. In addition, the two matrices we transposed of each other then, the I Dit is an inverse transform of the DCT. DCT and the IDCT are isometries on IRN and inverse of each other (DCT: X+ AX; IDCT: Y+3BY with B=AT) Exercise m 8; Let's howe the problem: { Him I x = E(Pk))2) St Z xk = 1

R xk >0 Yk We want demontrate that this problem implies the existence of Some heR such that: 2xx ork2 = 1 Yk \* We suppose  $\{f(\alpha) = \sum_{k} d_{k}^{2} \nabla I_{k}^{2} \}$  which is a convex function of  $\alpha$ .  $g(\alpha) = 1 - \sum_{k} \alpha_{k} \text{ which is an affine function}$ C= { & \in IR" | \sum \alpha \k = 1} is a convex and compact => of is a convex and lower semi continuous on C which is a convex and a compact set => the optimization problem is convex and feasible => 3 & EC / f(d) = inff(a). Now, we can write the Pagrangin: 2(d,1) = I dk = Tk + 1(1- I dk)

Using KKT conditions: ( & id) is a saddle point E) 2 dk The - ) =0

(e) \( \lambda = 2 dk \tau \text{L}^2 \) \( \frac{1}{2} \) => The constrained optimization problem implies the existence of AEIR such that 2 dk TIK2 = 1 4k. Exercise m9; ak : coeffuit of thresholding. Under the board thrusholding: ake { 0,13 and N.A. is the number of non mull values. Parseval theorem: for a patch xk: Var (xk) = E((Xk-E(xx)))  $\nabla T_k^2 = \sum_{k} \nabla r^2 \alpha_k^2 = N \rho_k \nabla r^2$  $\Rightarrow \forall k = \frac{\sqrt{1-2} N p_k^{-2}}{\sqrt{1-2} N p_k^{-2}} = \frac{N p_k^{-2}}{\sqrt{1-2} N p_k^{-2}} (4.22)$ \* Now, the coefficients are given by winer coefficient: for a patch Xk; we have ak = Pk. => TIE = TIE PPE = TIENTERIN  $\Rightarrow dk = \frac{\sqrt{|k|^{2}}}{\sum_{k=1}^{N} \sqrt{|k|^{2}}} = \frac{\sqrt{|k|^{2}}}{\sqrt{|k|^{2}}} = \frac{\sqrt{|k|^{$