

Homework 2: Image Denoising

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Chapter 5: Multi-scale DCT Denoising:

Exercise n 5.1 :

We have :

- n : the dimension of the initial image.
- k : the dimension of the image at a lower scale.
- u_0 : the initial image
- u_1 : the image at the lower scale
- DCT_n^{iso} and DCT_k^{iso} are the isometric DCTs at scale n and k respectively.
- ZP_k is the zero padding operator extracting the first $k \times k$ subimage from an $n \times n$ image.

The construction of the image at a lower scale is divided into several steps:

- 1- The first step consists in transforming the initial image u_0 to the frequency space. Thus, we will apply the function DCT_n^{iso} to the initial image. We obtain: $u' = DCT_n^{iso}(u_0)$
- 2- To construct the resulted image with dimension $k \times k$, we need to apply the zero padding operator. By definition, this operator extracts a subimage from an $n \times n$ image. We obtain: $u'' = ZP_k(DCT_n^{iso}(u_0))$
- 3- Before we transform the image to the original image space, we need to adjust the scale. Since we have transformed the image from $n \times n$ size to $k \times k$ size, we have:

- * $N_{unpixel}(initial)$ is the number of pixels in the original image which is equal to $n \times n$.
- * $N_{unpixel}(lower)$ is the number of pixels of the image at the lower scale which is equal to $k \times k$.

Now, we need to scale the image with a factor equal to:

$$\sqrt{\frac{N_{\text{pix}}(\text{layer})}{N_{\text{pix}}(\text{input})}} = \frac{\sqrt{k \times k}}{\sqrt{m \times n}}$$

We obtain : $u'' = \frac{\sqrt{k \times k}}{\sqrt{m \times n}} \text{ZP}_k \left(\text{DCT}_m^{\text{iso}}(u_0) \right)$

4- The final step consist in transforming the resulted image to the image space. Thus, we obtain:

$$u_1 = \text{IDCT}_k^{\text{iso}} \left(\frac{\sqrt{k \times k}}{\sqrt{m \times n}} \text{ZP}_k \left(\text{DCT}_m^{\text{iso}}(u_0) \right) \right)$$

$$\Rightarrow u_1 = \frac{\sqrt{N_{\text{pix}}(\text{layer})}}{\sqrt{N_{\text{pix}}(\text{input})}} \text{IDCT}_k^{\text{iso}} \left(\text{ZP}_k \left(\text{DCT}_m^{\text{iso}}(u_0) \right) \right)$$

We know that the images at different scale contain a white gaussian noise. Therefore, the image u_1 and u_0 can be written as a sum of a denoised image and a white gaussian noise.

$$\Rightarrow u_1 = u + n_1$$

$$\Rightarrow \text{Var}(n) = \text{Var}(u_1 - u); \text{ with } u \text{ deterministic}$$

$$\Rightarrow \text{Var}(n) = \text{Var}(u_1)$$

$$= \frac{N_{\text{pix}}(\text{layer})}{N_{\text{pix}}(\text{input})} \underbrace{\text{Var} \left(\text{IDCT}_k^{\text{iso}} \left(\text{ZP}_k \left(\text{DCT}_m^{\text{iso}}(u_0) \right) \right) \right)}_{= \text{constant (white noise)}}$$

$$= \frac{N_{\text{pix}}(\text{layer})}{N_{\text{pix}}(\text{input})} \sigma^2(u_0)$$

$$\Rightarrow \sigma(u_1) = \sqrt{\frac{N_{\text{pix}}(\text{layer})}{N_{\text{pix}}(\text{input})}} \sigma(u_0)$$

We can say that the standard deviation of the noise is

scaled with a factor equal to : $\sqrt{\frac{N_{\text{pix}}(\text{layer})}{N_{\text{pix}}(\text{input})}}$

Chapter 6: Image self-similarity and denoising:

Exercise n 6.1:

• We want to show:

"The convolution of the image with a gaussian kernel ensures a fixed noise standard deviation reduction factor"

• We have: $x \star n(i)$; $i \in \mathbb{Z}$ (not necessarily Gaussian)

* Discrete finite filter $a(i) \geq 0$ supported in $[-m, m]$ such that $\sum_{j'} a(j') = 1$.

$$\bullet \quad a \star n(i) = \sum_{j'} n(i-j') a(j')$$

$$\begin{aligned} \text{Var}(a \star n(i)) &= \text{Var}\left(\sum_{j'} n(i-j') a(j')\right) \\ &= \sum_{j'} \text{Var}(a(j') n(i-j')) + 2 \sum_{k < l} \text{Cov}(a(k) n(i-k), a(l) n(i-l)) \\ &= \sum_{j'=-m}^m \text{Var}(a(j') n(i-j')) + 2 \sum_{k < l} \text{Cov}(a(k) n(i-k), a(l) n(i-l)) \end{aligned}$$

or: $n(i)$ is a white noise. Thus, its terms are independent. It has a null mean and a constant variance.

$$\text{Therefore, } \begin{cases} \text{Var}(a(j') n(i-j')) = a^2(j') \text{Var}(n(i-j')) = \sigma^2 a^2(j') \\ \text{Cov}(a(k) n(i-k), a(l) n(i-l)) = 0 \end{cases}$$

$$\Rightarrow \boxed{\text{Var}(a \star n(i)) = \sum_{j'=-m}^m a^2(j') \sigma^2}$$

• We have $a(j') \geq 0$; $\sum_{j'=-m}^m a(j') = 1$

$$\Rightarrow a(j') \leq 1 \quad \forall j'$$

$$\Rightarrow a^2(j') \leq a(j')$$

$$\Rightarrow \sigma^2 a^2(j') \leq \sigma^2 a(j')$$

$$\Rightarrow \sigma^2 \sum_{j=-m}^m a^2(j) \ll \sigma^2 \sum_{j=-m}^m a(j)$$

$$\Rightarrow \sum_{j=-m}^m \sigma^2 a^2(j) \ll \sigma^2$$

$$\Rightarrow \boxed{\text{Var}(a * n(i)) \ll \text{Var}(n(i))}$$

• Now, we want to determine the optimal values of $a(i)$.

Let's define the problem:

$$\begin{cases} \text{Min Var}(a * n(i)) \\ \text{st} \\ \sum_{j=-m}^m a(j) = 1 \end{cases}$$

$$\Leftrightarrow \begin{cases} \text{Min} \sum_{j=-m}^m \sigma^2 a^2(j) \\ \text{st} \\ \sum_{j=-m}^m a(j) = 1 \end{cases} \Leftrightarrow \begin{cases} \text{Min} \sum_{j=-m}^m a^2(j) \\ \text{st} \\ \sum_{j=-m}^m a(j) = 1 \end{cases}$$

To solve this problem, we need to write the Lagrangian function:

$$\mathcal{L} = \sum_{j=-m}^m a^2(j) + \nu \left(1 - \sum_{j=-m}^m a(j) \right)$$

Using the KKT conditions:

$$\frac{\partial \mathcal{L}}{\partial a(j)} = 0 \quad (\Rightarrow) \quad 2a(j) - \nu = 0 \quad \forall j$$

$$\Rightarrow a(j) = \nu/2 = c \quad \forall j \text{ and } a(j) \geq 0$$

$$\text{We have } \sum_{j=-m}^m a(j) = 1$$

$$\Rightarrow \sum_{j=-m}^m c = 1 \quad (\Rightarrow) \quad c \times (2m+1) = 1$$

$$\Rightarrow c = \frac{1}{2m+1} \geq 0$$

$$\text{Conclusion: } \boxed{a(j) = \frac{1}{2m+1} \quad \forall j}$$