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chapter 9 The global EPLL Algorithm.

We howe P obeys a GMM model and 
$$\vec{P}$$
 is a noisy observation of P with a gaussian isotropic noise of variance  $\vec{q}^{(2)}$ .

Thus,  $\vec{P}(\vec{P}|\vec{P}) = \frac{1}{(2\pi)^{d/2} det(\Sigma_R)^{1/2}} e^{-\frac{1}{2}(\vec{P}-\vec{P})^T \sum_{k=1}^{n} (\vec{P}-\vec{P})^T \sum_{k=1}^{n} (\vec{P}$ 

(2) That 
$$order = \frac{1}{2\pi^2} ||P - P||^2$$
(2) The log  $(|P(P)| \times C - \frac{1}{2\pi^2} ||P - P||^2)$ 

$$P(P) \times \frac{1}{2\pi^{2}} |P-P||^{2}$$

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$$P(P) \times P(P| \times P(P|P))$$

We found that minimizing the above energy amounts to compute a maximum a posteriori estimate of P given P.

Exercice n 9.20:

The log-likelihood of the image is given by:

log (P(U)) = log (P(n {PU}))

In the case of independent patches:

$$\log (P(U)) = \log (P(\frac{3}{2}PU))$$

$$= \log (TP(PU))$$

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$$= \sum_{P \in P} \log (P(\frac{3}{2}PU))$$

= EPLL (U)

Thus, the EPLL p (U) can be interpreted as the

log\_ like likeod of the image of only in the corre when all the patches in the image are independent which is not always the corse.

In the general core, we could not interpret the EPLL as a log\_ likelihood of the image. \_2