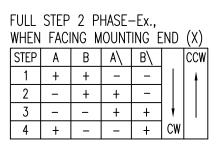


CONNECTION	BIPOLAR		DEDITIONE DADIA		-000			
SPECIFICATION				PERMISSIBLE RADIAL+AXIAL FORCE ROTOR SPRING- SPRING				
VOLTAGE (VDC)	2.8		ROTOR SPRING— MOUNTED IN		} ? →			
AMPS/PHASE	1.4		AXIAL DIRECTION	BEARI		. /		
RESISTANCE/PHASE (Ohms)@25°C	2.0±15%							
INDUCTANCE/PHASE (mH) @1KHz			1					
HOLDING TORQUE (Nm) [lb-in]	0.09 [0.797]		Fa	]				
DETENT TORQUE (Nm) [lb-in]	3.1x10 <sup>-4</sup> [2.79x1	10 <sup>-3</sup> ]		)				
STEP ANGLE (*)	1.8		]   Ц					
STEP ACCURACY (NON-ACCUM)	±5%							
ROTOR INERTIA (Kg-m <sup>2</sup> ) [lb-in <sup>2</sup> ] 2.0x10 <sup>-6</sup> [6.83x10 <sup>-4</sup> ] $\angle$			<u>a</u>					
WEIGHT (Kg) [lb]	0.15 [0.33]							
TEMPERATURE RISE: MAX.80°C (MOTO	AXIAL—FORCE Fa (N)	Fa	=7					
AMBIENT TEMPERATURE −10°~ 50°C	DISTANCE a (mm)	5 1	0 15	20				
INSULATION RESISTANCE 100 MOhm (	RADIAL-FORCE Fr (N)	58 3	6 26	20				
INSULATION CLASS B 130' [266'F]			AXIAL F		RA	RADIAL		
DIELECTRIC STRENGTH 500VAC FOR 1 MIN. (BETWEEN THE MOTOR COILS AND THE MOTOR CASE)			SHAFT PLAY (mm)	0.08	0.0	0.02		
AMBIENT HUMIDITY MAX. 85% (NO CONDENSATION)			AT LOAD MAX: (N) 4.5		4.	4.5		
7   rowert draw /ohange depth NO F	ב∖עוז וחח חα זובו אוכו	.⇔.		®		1 400		

TYPE (	OF CONNECTION EXTERN)	MOTOR			
PIN NO	BIPOLAR	LEADS	WINDING		
1	A —	BRN	Α 📑		
2	A\ —	ORG	A\		
3	В —	RED	В		
4	B\ —	YEL	B\		



	WIRING	DIAGRAM
(A)BRN	~ {	
	{ (	)
(A\)ORG	~ ك	
	ļ	ļ
	)RED	)YEL
	(B	<u>,6</u>

3	rework draw/change depth M2.5/M3	09.02.16	A.S.		Vanote	<b>8</b>	APVD	S.Ha.	06.10.06	STEPPING MOTOR
2	NEW UL NO.	14.04.09	J.W.		PLUG & D		CHKD			SIDITIVO MOTOR
1	NEW VALUE OF ROTOR INERTIA	25.06.08	J.W.	Surface	General	Work piece	DRN	J.W.	06.10.06	] DWG.NO
REV	DESCRIPTION	DATE	DRN	specification DIN ISO 1302	tolerances DIN ISO 2768- cH	edge DIN ISO 13715	SIGN	ATURE	DATE	ST4118X1404-B