

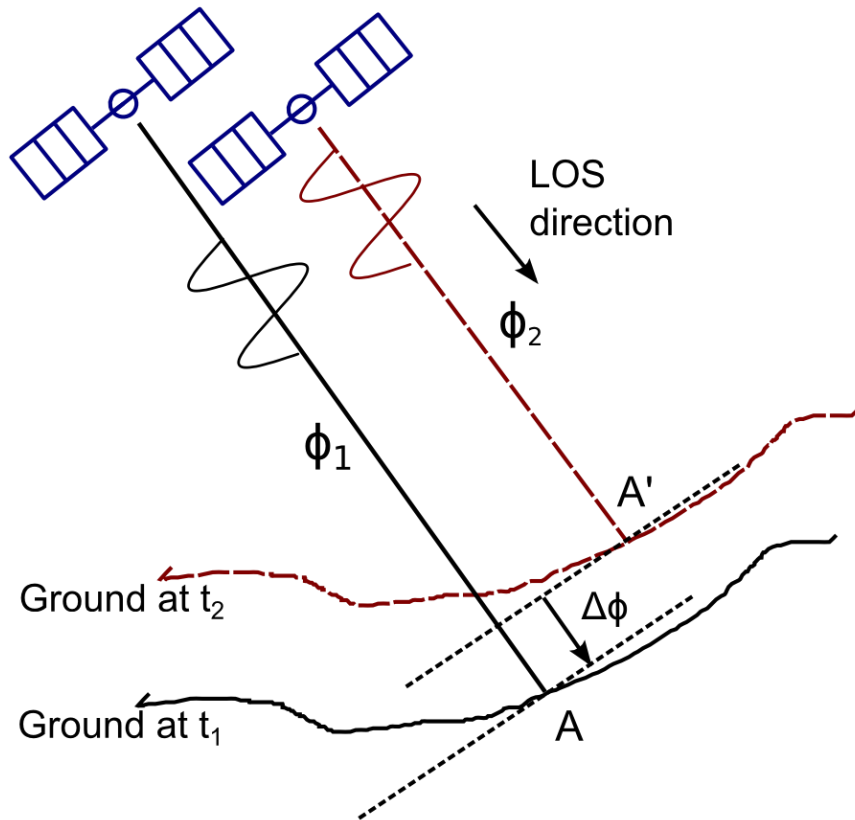
# **InSAR Timeseries Analysis: theory and overview**

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# Interferometric Synthetic Aperture Radar (InSAR)



- We can measure any small ground deformation  $\Delta d$  along LOS direction occurring between  $t_1$  and  $t_2$  using the InSAR phase difference  $\Delta\phi$ :

$$\Delta\phi = \frac{4\pi}{\lambda} \Delta d$$

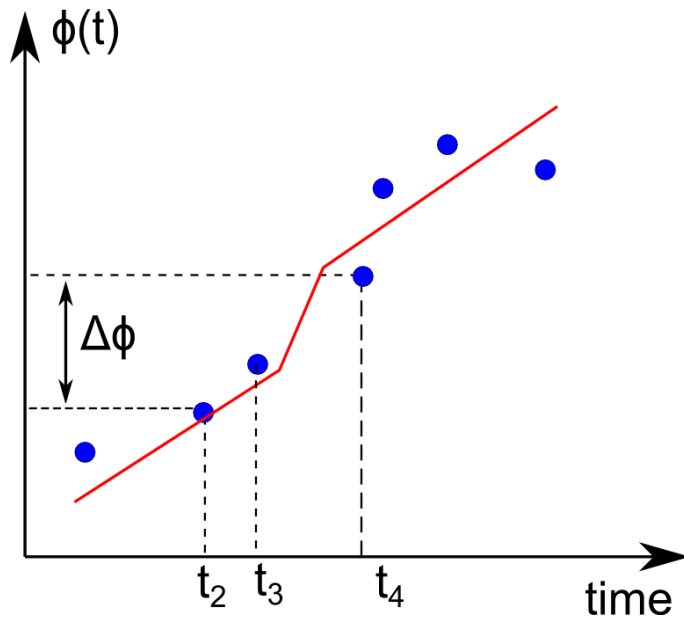
- Temporal and Spatial Baselines

# InSAR time series analysis

*LOS InSAR phase history of a pixel in the interferogram:*

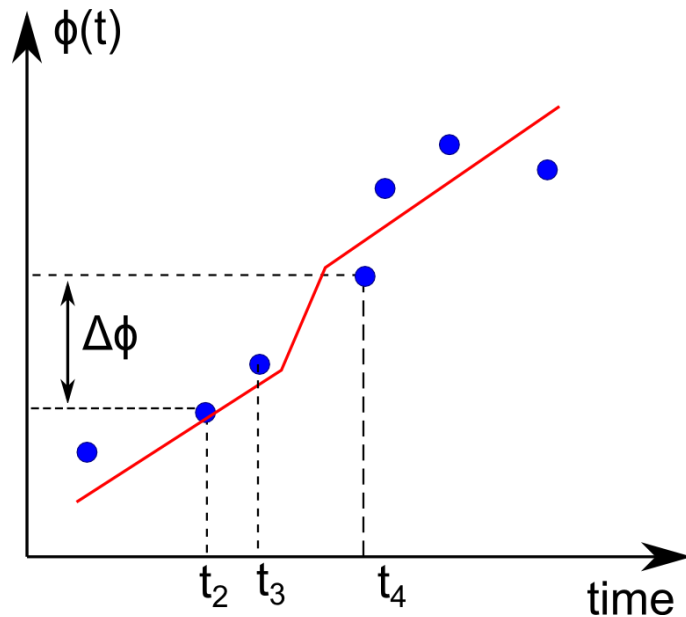
Define  $v_k$  as the average velocity between  $t_k$  and  $t_{k+1}$ , we have:

$$(t_3 - t_2)v_2 + (t_4 - t_3)v_3 + \Delta\phi_{noise} = \Delta\phi$$



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We use 7 SAR data to form M small baseline interferograms. The matrix form of the SBAS system is:

$$B_{M \times 6} v_{6 \times 1} = \Delta\Phi_{M \times 1}$$

# The impact of noise terms

- The accuracy of the SBAS time series results depends on the quality of the input data!
- InSAR measurement noise:

$$\Delta\phi = \frac{4\pi}{\lambda} \Delta d_{LOS} + \Delta\phi_{orb} + \Delta\phi_{decor} + \Delta\phi_{unwrap} + \Delta\phi_{dem} + \Delta\phi_{iono} + \Delta\phi_{tropo} + \Delta\phi_n$$

- InSAR time series analysis can reduce the impact of noise that are random in time (e.g. tropospheric turbulence noise) through the use of temporal filtering and deformation models.

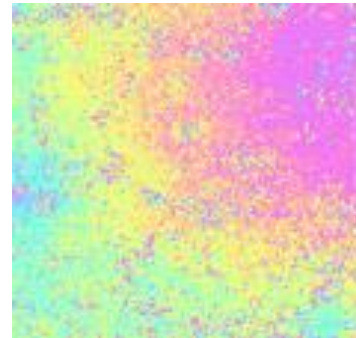
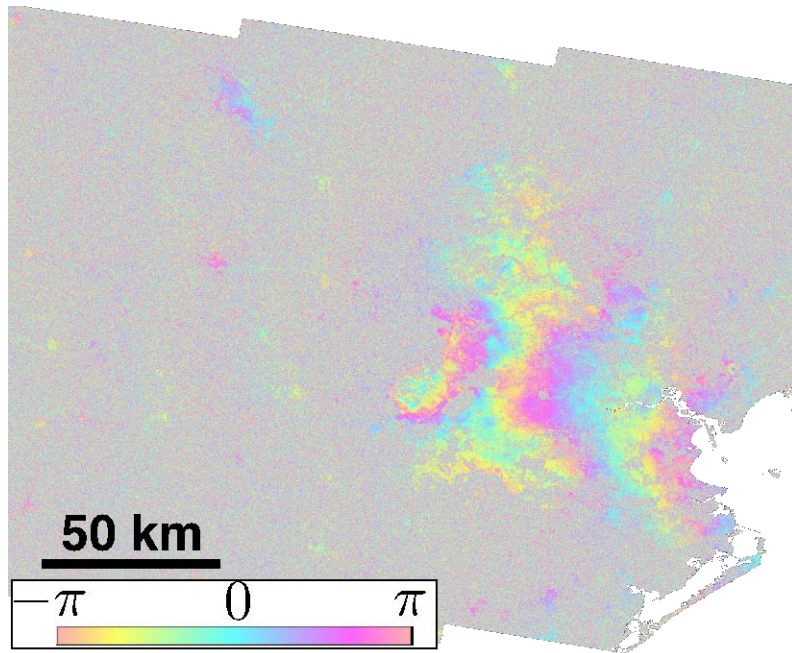
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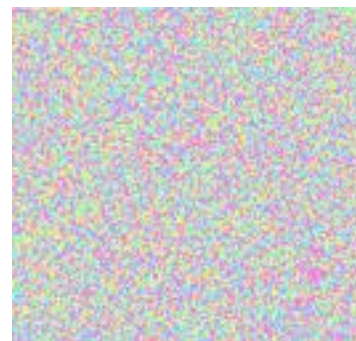
$$\Delta\phi = \frac{4\pi}{\lambda} \Delta d_{LOS} + \Delta\phi_{orb} + \Delta\phi_{decor} + \Delta\phi_{unwrap} + \Delta\phi_{dem} + \Delta\phi_{iono} + \Delta\phi_{tropo} + \Delta\phi_n$$

- In many cases, the dominant errors are tropospheric noise and decorrelation noise and the associated unwrapping errors.

# Decorrelation noise



Without severe decorrelation, phase measurements are spatially coherent.

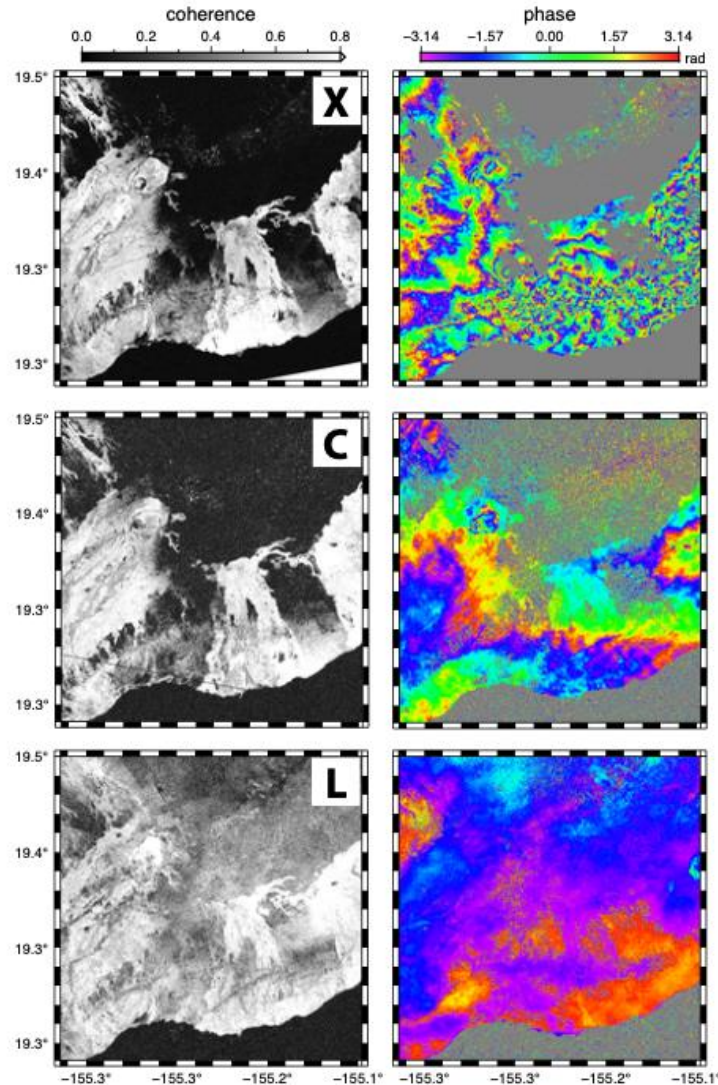


With decorrelation, phases are random and not predictable.

Sentinel-1 Interferogram over the Greater Houston area  
(Jan. 03, 2018 – Nov. 06, 2019)



# Decorrelation Noise Characteristics



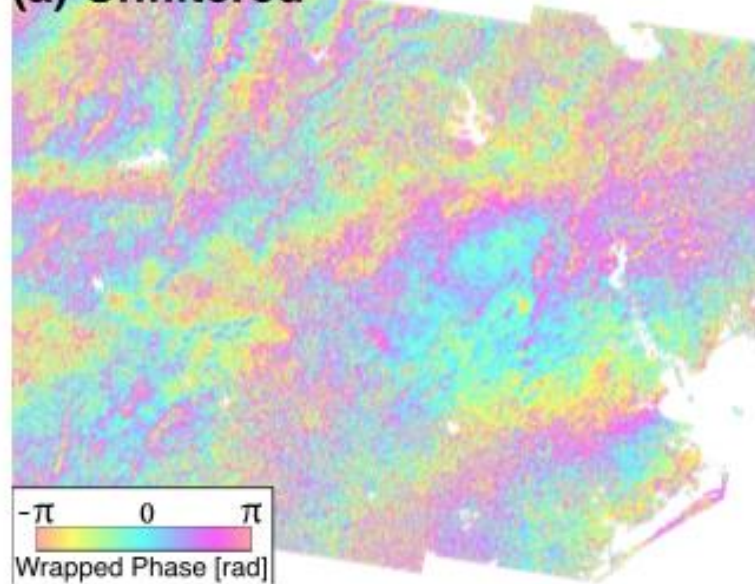
- A major issue over densely vegetated terrain
- Radar sensors with shorter wavelengths are more prone to decorrelation noise.



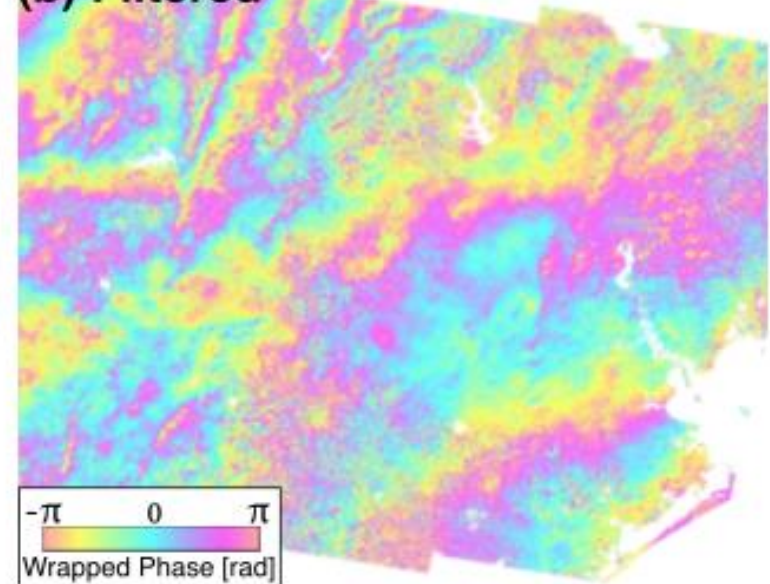
# Mitigation Strategies

- Spatial Filtering or Multi-looking

**(a) Unfiltered**



**(b) Filtered**



# Mitigation Strategies

- Using a subset of interferograms with small baselines
  - Works well if your study site suffers from minimal or moderate decorrelation
  - In vegetated regions, the SBAS solutions may be unreliable (e.g., different temporal thresholds lead to very different solutions).
- Persistent Scatterers

