DID & Synthetic Control

Myeongcheol Seo

Department of Economics, SNU

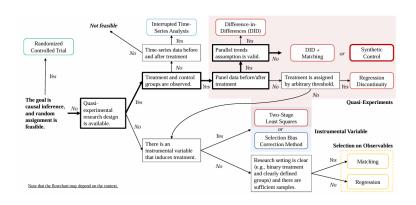
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January 9, 2025

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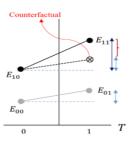
Intro



Setting & Idea

- DID : Difference between the change in outcome before and after a treatment in a treatment vs control group
- Consider a canonical 2x2 setting:
 - Y_{it} : outcome value of i in t
 - i: 0 if control, 1 if treatment, t: 0 if pretreated, 1 if post-treated

	Treatment group	Control group	Differences
Pre-treated	Y_10	Y_00	Y_10 - Y_00
Post-treated	Y_11	Y_01	Y_11 - Y_01
Differences	Y_11 - Y_10	Y_01 - Y_00	(Y_11 - Y_10) - (Y_01 - Y_00)
Treatment	e + Time e	Time e	Treatment e



Potential Outcome Framework(2x2)

• Causal Effect:

$$\delta = Y(1)_{it} - Y(0)_{it}$$
 (Homogeneous Treatment Effect)

Observed Outcomes:

$$Y_{it} = Y(0)_{it} + [Y(1)_{it} - Y(0)_{it}] \cdot D_{it}$$

• Untreated Potential Outcome:

$$Y(0)_{it} = \beta_0 + \beta_1 T_i + \beta_2 P_t + \epsilon_{it}$$

- T_i : Group Dummy (0 if i = 0, 1 if i = 1)
- P_t : Time Dummy (0 if t = 0, 1 if t = 1)
- Regression Form:

$$Y_{it} = \beta_0 + \beta_1 T_i + \beta_2 P_t + \delta D_{it} + \epsilon_{it}$$

• Interaction Term:

$$D_{it} = T_i \times P_t$$

• The 2x2 DID design is intuitive, but it does not accommodate the complexity in applications (e.g., treatment for multiple groups, multiple time periods).

Potential Outcome Framework(NXT)

• Like the 2x2 setting:

$$\delta = Y(1)_{it} - Y(0)_{it}$$

• Recall:

$$Y_{it} = \beta_0 + \beta_1 T_i + \beta_2 P_t + \delta D_{it} + \epsilon_{it} \quad (2x2)$$

• Regression Form:

$$Y_{it} = u_i + v_t + \delta D_{it} + \epsilon_{it}$$
 (Two-way Fixed Effects)

- Regression DID is an easy method for estimation and standard error calculation.
- ullet Using FWFE regression models, we may consistently estimate $\delta.$
- Note: There is no variation in the timing of treatment implementation.
 - See more on Andrew Goodman-Bacon (2021).



Potential Outcome Framework(NXT)

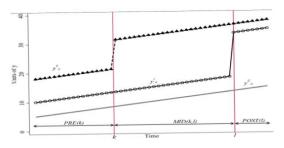


Figure: Timing Heterogeneity

Key Assumption: CTA for DID Identification

- CTA (Common Trend Assumption) is a key assumption for DID identification.
- Roughly speaking, a graph of the time series should look like a set of parallel lines.
- Formally, for t > 1:

$$E[Y_{it}(0) - Y_{i(t-1)}(0)]$$
 does not vary across i.

• In the panel data framework:

$$Y_{it} = u_i + v_t + \delta D_{it} + \epsilon_{it}$$

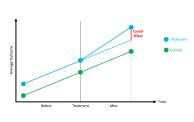
Exogeneity assumption:

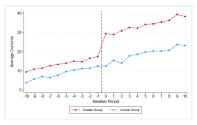
$$E[D_{it}\epsilon_{is}] = 0$$
 for all t, s .

• This assumption is not fully testable, but it is partially testable.



Key Assumption: CTA for DID Identification





Other assumptions for validation

- No Confounding Factors:
 - No other policies were changed concurrently, except for the treatment.
- No Compositional Differences:
 - Repeated cross-section data, regional specific data.
 - This is not an issue in the panel data framework.

Replication: Police Forces After a Terrorist Attack (DiTella, 2004)

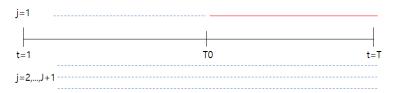
- DiTella and Schargrodsky (2004) investigated whether police presence reduces car thefts.
- Exogenous Event
 - In 1994, after a terrorist attack in Buenos Aires, the government increased police presence.
 - Using the exogenous event (the terrorist attack) to identify causal effects.
- Methodology: DID approach
 - Comparing car theft rates before and after the terrorist attack, and between areas with and without police protection.
- Heterogeneous Treatment Effect
 - The presence of police would reduce car thefts, with the effect being stronger closer to the deployed police.
- Results: Car thefts decreased in areas with police protection.

Replication: Police Forces After a Terrorist Attack (DiTella, 2004)

- Timeline of Events
- Descriptive Statistics
- Estimation Equations
 - Simple Model
 - Hetero Model
- Test of Hypothesis

Synthetic Control

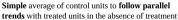
- Aim to estimate the effects of aggregate interventions.
- Aggregate level treatment affecting a small number of large units:
 - Cities, regions, or countries.
- Useful when the **common trend assumption** is not satisfied.
- When the units of observation are a small number of aggregate entities:
 - A combination of controlled units is often a better choice than any single controlled unit.
- Blue dotted line: untreated, Red solid line: treated.

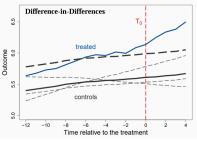


DID vs Synthetic Control

- In approximating the counterfactual for treated units,
- Type of counterfactual estimated:
 - DID: 'Counterfactual trend' (Common trend assumption is needed).
 - Synthetic Control: 'Counterfactual outcome' weighted combination of untreated units.
- How units are utilized:
 - DID: Uses the entire control units with equal weight.
 - Synthetic Control: Uses a non-uniform weighted average of control units.

DID vs Synthetic Control





Weighted average of control units to mimic the outcome trajectory of treated units in the absence of treatment

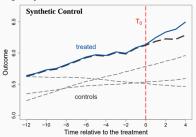


Figure: DID vs Synthetic Control

Synthetic Control: Setting & Idea

- J+1 units of data, j=1 for treated unit, j=2,...,J+1 for untreated ("donor pool").
- T periods of time, with the first T_0 periods before the intervention.
- Y_{it} : outcome of interest.
- $k \times 1$ vectors $\mathbf{X}_1, ..., \mathbf{X}_{J+1}$ contain the values of predictors.
 - $X_j = (X_{1j}, ..., X_{kj})'$
- $k \times J$ matrix $\mathbf{X}_0 = [\mathbf{X}_2, ..., \mathbf{X}_{J+1}]$ consists of row-stacked predictors of untreated units.

Example: Abadie et al. (2015)

- Economic Cost of Germany Reunification
- **Time Horizon:** 1960-2003, where 1990 is the intervention T_0 .
- Donor Pool: 16 OECD member countries.
- Predictors (X):
 - Per capita GDP.
 - Inflation rate.
 - Industry share of value added.
 - Investment rate.
 - Schooling.
 - Measure of trade openness.

Estimation

- Y_{it}^N : Potential response without intervention.
- Y_{it}^I : Potential response with intervention.
- Interest of estimation:
 - Effect of intervention for the treated unit in period t ($t > T_0$).
- The treatment effect for the treated unit at time t.

$$\tau_{1t} = Y_{1t}^I - Y_{1t}^N$$

- What we know:
 - $Y_{1t} = Y'_{1t}$ for $t > T_0$ (observed outcome after intervention).
- Need to estimate:
 - Y_{1t}^N : The counterfactual outcome (i.e., the outcome without the intervention).

Estimation

• Synthetic control can be represented by a $J \times 1$ vector of weights:

$$W = (w_2, \ldots, w_{J+1})'$$

• Synthetic control estimator:

$$\hat{Y}_{1t}^{N} = \sum_{j=2}^{J+1} w_j Y_{jt}$$

• The treatment effect for the treated unit at time t:

$$\hat{\tau}_{1t} = Y_{1t} - \hat{Y}_{1t}^N$$

- Restrictions for weights: Non-negative, sum to one.
 - Synthetic controls are weighted averages of the units in the donor pool.



Choice of W

• Choose the synthetic control, $\mathbf{W}^* = (W_2^*, \dots, W_{J+1}^*)'$ under the constraints that minimizes

$$\|\mathbf{X}_1 - \mathbf{X}_0 \mathbf{W}\| = \left(\sum_{h=1}^k v_h \left(X_{h1} - w_2 X_{h2} - \dots - w_{J+1} X_{hJ+1}\right)^2\right)^{1/2}$$

for some v_h 's.

- Positive constants w_2, \ldots, w_{J+1} reflect the **relative importance of each of the** j **units** for constructing the synthetic control.
- Positive constants v_1, \ldots, v_k reflect the relative importance of **each of the** k **predictors** for constructing the synthetic control.
- The synthetic control $\mathbf{W}(\mathbf{V}) = (w_2(\mathbf{V}), \dots, w_{J+1}(\mathbf{V}))$ is a function of \mathbf{V} , where $\mathbf{V} = (v_1, \dots, v_k)$.

Choice of V

- Divide the pre-intervention periods into an initial training period and a subsequent validation period.
- Assume that T_0 is even, and the training and validation periods span:

$$t = 1, \ldots, t_0$$
 (Training period)

and

$$t = t_0 + 1, \dots, T_0$$
 (Validation period)

where $t_0 = \frac{T_0}{2}$.



Figure: Training & Validation periods

Choice of V

• For every value of V, let $\tilde{w}_2(\mathbf{V}), \ldots, \tilde{w}_{J+1}(\mathbf{V})$ be the synthetic control weights computed with the **Training Period**, which minimizes:

$$\|\mathbf{X}_1 - \mathbf{X}_0 \mathbf{W}\| = \left(\sum_{h=1}^k v_h \left(X_{h1} - w_2 X_{h2} - \dots - w_{J+1} X_{h(J+1)}\right)^2\right)^{1/2}$$

This can be conducted by quadratic optimization.

 Select a value V* such that the Mean Squared Prediction Error (MSPE) for the outcome prediction in the validation set is minimized:

$$\sum_{t=t_0+1}^{T_0} \left(Y_{1t} - ilde{w}_2(\mathbf{V}) Y_{2t} - \dots - ilde{w}_{J+1}(\mathbf{V}) Y_{J+1t}
ight)^2$$

• Use the resulting V^* and data on the predictors for $t = t_0 + 1, ..., T_0$ to calculate the final synthetic control weights:

$$\mathbf{W}^* = \mathbf{W}(\mathbf{V}^*)$$



Abadie, Alberto. (2021)

ullet For the training period 1971-1980, choose $ilde{\mathbf{W}}$ that minimizes:

$$\|\mathbf{X}_1 - \mathbf{X}_0 \mathbf{W}\| = \left(\sum_{h=1}^k v_h \left(X_{h1} - w_2 X_{h2} - \dots - w_{J+1} X_{h(J+1)}\right)^2\right)^{1/2}$$

• For the validation period 1981-1990, minimize the following MSPE:

$$\sum_{t=t_0+1}^{T_0} \left(Y_{1t} - \tilde{w}_2(\mathbf{V}) Y_{2t} - \dots - \tilde{w}_{J+1}(\mathbf{V}) Y_{J+1t} \right)^2$$

• Use the resulting \mathbf{V}^* and predictors in 1981-1990 (validation period) to choose the final synthetic control weights \mathbf{W}^* that minimize:

$$\|\mathbf{X}_1 - \mathbf{X}_0 \mathbf{W}\| = \left(\sum_{h=1}^k v_h \left(X_{h1} - w_2 X_{h2} - \dots - w_{J+1} X_{h(J+1)}\right)^2\right)^{1/2}$$

• Then, the treatment effect is:

$$\hat{ au}_{1t} = Y_{1t} - \sum_{j=2}^{J+1} w_j^* Y_{jt}, \quad ext{where} \quad \mathbf{W}^* = (w_2^*, \dots, w_{J+1}^*)'$$

Inference: Placebo Test

- Tricky: It is not possible to rely on asymptotic theory.
- Placebo tests: Apply synthetic control to other units.
- Synthetic control may not fit the trajectory of the outcome for the units in the donor pool.
- **RMSPE** of the synthetic control estimator for unit j and time t_1, \ldots, t_2 :

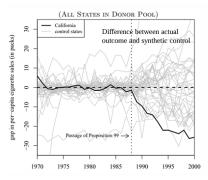
$$R_j(t_1, t_2) = \left(\frac{1}{t_2 - t_1 + 1} \sum_{t=t_1}^{t_2} (Y_{jt} - \hat{Y}_{jt}^N)^2\right)^{1/2}$$

• Ratio between the post-intervention RMSPE and pre-intervention RMSPE for unit *j*:

$$r_j := \frac{R_j(T_0 + 1, T)}{R_i(1, T_0)}$$



Inference: Placebo Test



Root Mean Squared Prediction Error (RMSPE)

$$egin{split} R_{j}(t_{1},t_{2}) \ &= \left(rac{1}{t_{2}-t_{1}+1}\sum_{t=t_{1}}^{t_{2}}\left(Y_{jt}-\hat{Y}_{jt}^{N}
ight)^{2}
ight)^{1/2} \end{split}$$

Figure: Permutation test

Inference: Placebo Test

- Use the permutation distribution of r_j for inference.
- Synthetic control may not fit the trajectory of the outcome for the units in the donor pool.
- Let $H_0: Y_{jt}^I = Y_{jt}^N$ for each $j = 1, \dots, J+1$ and $t = 1, \dots, T$.
- Compute p-value:

$$\rho = \frac{1}{J+1} \sum_{j=1}^{J+1} I_+(r_j - r_1)$$

• Indicator function:

$$I_+(r_j-r_1) = \begin{cases} 1, & \text{if } r_j \geq r_1 \\ 0, & \text{otherwise} \end{cases}$$

 Reject the null hypothesis if p is less than some pre-specified significance level.



Contextual Requirements

Convex Hull Condition:

- A convex combination of donor pool measures should approximate the pre-intervention characteristics of the treated unit.
- (Similar to Parallel pre-trend in DID)

No Anticipation:

• No forward-looking economic agents react in advance of the intervention.

No Confounding Events:

• No concurrent confounding shocks.

No Interference:

• No spillover effects of the intervention of interest.

No Structural Breaks:

SCM is predicated on structural stability.

Contextual Requirements

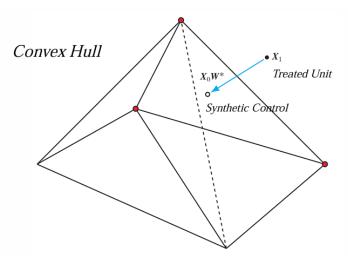


Figure: Convex Hull

Contextual Requirements

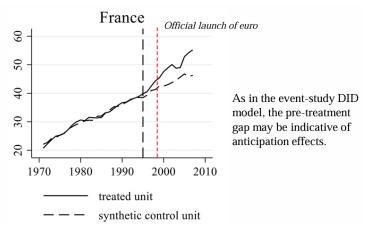
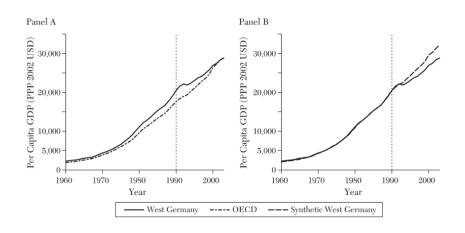


Figure: Anticipation

Application: Impact of Reunification on West Germany (Abadie et al, 2015)



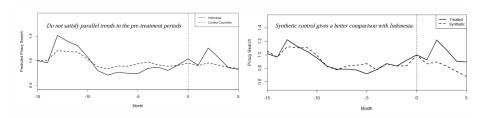
Application: Impact of Reunification on West Germany (Abadie et al, 2015)

TABLE 2 Synthetic Control Weights for West Germany		TABLE 3 REGRESSION WEIGHTS FOR WEST GERMANY	
Australia	_	Australia	0.12
Austria	0.42	Austria	0.26
Belgium	_	Belgium	0.00
Denmark	_	Denmark	0.08
France	_	France	0.04
Greece	_	Greece	-0.09
Italy	_	Italy	-0.05
Japan	0.16	Japan	0.19
Netherlands	0.09	Netherlands	0.14
New Zealand	_	New Zealand	0.12
Norway	_	Norway	0.04
Portugal	_	Portugal	-0.08
Spain	_	Spain	-0.01
Switzerland	0.11	Switzerland	0.05
United Kingdom	_	United Kingdom	0.06
United States	0.22	United States	0.13

Replication: Impact of OTT Services on Piracy Search

- In 2016, Netflix made a major market expansion of its services into 130 countries
- However, it failed to enter Indonesia due to conflicts with a state-owned telecom company.
- Synthetic Indonesia:
 - Constructed using a combination of 40 Asian countries where Netflix was introduced in January 2016 and remained available.

Replication: Impact of OTT Services on Piracy Search



Lu, S., Rajavi, K. and Dinner, I., 2021. The effect of over-the-top media services on piracy search: Evidence from a natural experiment. Marketing Science, 40(3), pp.548-568.

Figure: DID vs Synthetic Control

Replication: Impact of OTT Services on Piracy Search(WP)

- DID Analysis (Table 1)
- Checking Parallel Trend Assumption (Fig 2)
- Weights of Synthetic Indonesia (Table 2)
- Mean of Pretreatment Characteristics (Table 3)
- Trends of Piracy Search Volume: Indonesia vs Synthetic Control Country (Figure 3)
- Gaps in Piracy Search Volume Between Indonesia and Synthetic Control Country (Figure 4)
- Ratio of Posttreatment MSPE to Pretreatment MSPE Across the Countries (Figure 5)
- Placebo Test (Figure 6)
- Others: Treatment Effect, Robustness Check

DID Analysis (Table 1)

- Summarizes the results of the DID analysis for Netflix's market expansion.
- Compares changes in piracy search between treated and control countries.

Table1 DID result.	
	(1)
	Piracy Search
Event	-0.075***
	(0.017)
Event x Treated	0.177**
	(0.064)
N	820
R^2	0.382
Standard errors in parentheses * p <	< 0.1, ** p < 0.05, *** p < 0.001

Table: DID Results: Impact of Netflix Expansion on Piracy Search

Checking Parallel Trend Assumption (Fig 2)

- Validates the parallel trend assumption critical for DID analysis.
- Visualizes pre-intervention trends for treated and control groups.

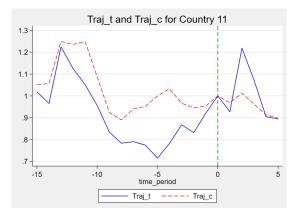


Figure: Parallel Trend Test: Piracy Search Trends Before Netflix Expansion

Weights of Synthetic Indonesia (Table 2)

- Displays weights assigned to countries in constructing Synthetic Indonesia.
- Countries with higher weights resemble Indonesia in pre-intervention characteristics.

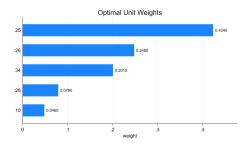


Table: Synthetic Control Weights for Indonesia

Mean of Pretreatment Characteristics (Table 3)

- Compares pre-intervention characteristics of Indonesia and Synthetic Indonesia.
- Evaluates the similarity of treated and synthetic control units.

	Treated	Synthetic
sv_piracy_normalized	.9097321	.9685764
sv_title	468524	694113
sv_netflix	89066.67	109953.4
sv_generalpiracy	92636.67	472578
sv_comp	37726	62753.36
internetuser_mean_2014	4.36e+07	2.65e+07
internetuser_mean_2015	5.01e+07	9169259

Table: Pretreatment Characteristics: Indonesia vs Synthetic Indonesia

Trends of Piracy Search Volume (Figure 3)

- Plots piracy search trends for Indonesia and Synthetic Indonesia.
- Deviations in post-intervention implies the treatment effects.

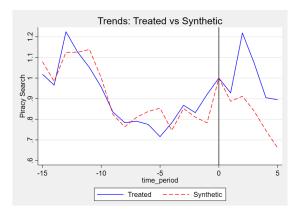


Figure: Piracy Search Trends: Indonesia vs Synthetic Control

Gaps in Piracy Search Volume (Figure 4)

 Visualizes differences in piracy search volume between Indonesia and its synthetic counterpart.

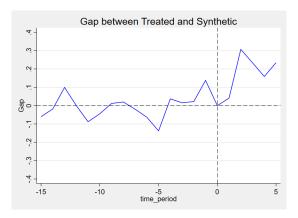


Figure: Gaps in Piracy Search Volume: Indonesia vs Synthetic Control

Ratio of MSPE: Posttreatment to Pretreatment (Figure 5)

 Compares the fit of synthetic control pre- and post-intervention across countries.

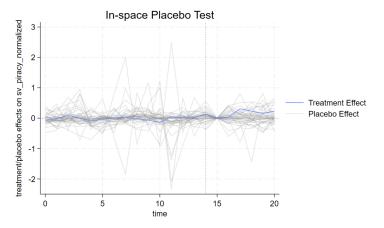


Figure: MSPE Ratio: Post- vs Pre-treatment Across Countries

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Placebo Test (Figure 6)

- Tests the robustness of the results by applying the intervention to other countries.
- Helps assess the likelihood of observing the treatment effect by chance.

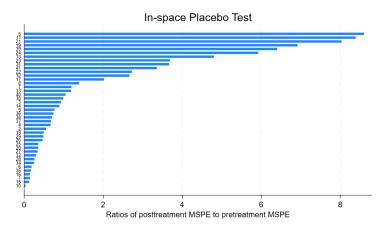


Figure: Placebo Test: Piracy Search Trends Across Countries

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Treatment Effect and Robustness Check

Treatment Effect:

- Estimated impact of Netflix's entry on piracy search in Indonesia.
- Results highlight the causal effect and policy implications.

Robustness Check:

- Validate assumptions such as no interference, convex hull, and structural stability.
- Examine sensitivity to alternative specifications and donor pools.

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