

1. Environment Setup

```
from google.colab import files
files.upload()
!unzip /content/Backdoor.v2i.yolov8.zip
```

Choose Files | Backdoor.v2i.yolov8.zip

- **Backdoor.v2i.yolov8.zip** (application/x-zip-compressed) - 1309787 bytes, last modified: 4/15/2025 - 100% done

Saving Backdoor.v2i.yolov8.zip to Backdoor.v2i.yolov8.zip

Archive: /content/Backdoor.v2i.yolov8.zip

inflating: README.dataset.txt
inflating: README.roboflow.txt
inflating: data.yaml
creating: train/
creating: train/images/
extracting: train/images/expected-output-of-task5_png.rf.0836c89ca57169198e58c31830ae64ce.jpg
extracting: train/images/expected-output-of-task5_png.rf.580e558983f1dc91a4129ae082c8adcf.jpg
extracting: train/images/expected-output-of-task5_png.rf.5db217d79fdff4cd1708d4c3219b7f04.jpg
extracting: train/images/suggested-8QVd4a4j1JPhrrza2kNh_.jpg.rf.690e6a10adb2c64a3a7d9d0f823b82d9.jpg
extracting: train/images/suggested-8QVd4a4j1JPhrrza2kNh_.jpg.rf.6ab2cc6eaff6bbff7e114fbcd0bf3dd.jpg
extracting: train/images/suggested-8QVd4a4j1JPhrrza2kNh_.jpg.rf.b2292c338d6bf75da3976df6860462e3.jpg
extracting: train/images/suggested-LsRLygFjdRNj91H0KU7A_.jpg.rf.551b489d3e8994025acee8d6da3e485f.jpg
extracting: train/images/suggested-LsRLygFjdRNj91H0KU7A_.jpg.rf.8416a0a2c976393ecb1e5733e25906ce.jpg
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extracting: train/images/task5_img.png.rf.280d2aa52d143970e6b61d9de10b2310.jpg
extracting: train/images/task5_img.png.rf.ba9f58498df3821a5fbdd12b63d1062c.jpg
extracting: train/images/task5_img.png.rf.ed8c7a6fbbc7cdf1945ed8482f2d11f0.jpg
 creating: train/labels/
inflating: train/labels/expected-output-of-task5_png.rf.0836c89ca57169198e58c31830ae64ce.txt
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inflating: train/labels/suggested-8QVd4a4j1JPhrrza2kNh_.jpg.rf.690e6a10adb2c64a3a7d9d0f823b82d9.txt
inflating: train/labels/suggested-8QVd4a4j1JPhrrza2kNh_.jpg.rf.6ab2cc6eaff6bbff7e114fbcd0bf3dd.txt
inflating: train/labels/suggested-8QVd4a4j1JPhrrza2kNh_.jpg.rf.b2292c338d6bf75da3976df6860462e3.txt
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inflating: train/labels/task5_img.png.rf.ed8c7a6fbbc7cdf1945ed8482f2d11f0.txt

```
!pip install ultralytics
```

Collecting ultralytics

 Downloading ultralytics-8.3.108-py3-none-any.whl.metadata (37 kB)

Requirement already satisfied: numpy<=2.1.1,>=1.23.0 in /usr/local/lib/python3.11/dist-packages (from ultralytics) (2.0.2)

Requirement already satisfied: matplotlib>=3.3.0 in /usr/local/lib/python3.11/dist-packages (from ultralytics) (3.10.0)

Requirement already satisfied: opencv-python>=4.6.0 in /usr/local/lib/python3.11/dist-packages (from ultralytics) (4.11.0.86)

Requirement already satisfied: pillow>=7.1.2 in /usr/local/lib/python3.11/dist-packages (from ultralytics) (11.1.0)

Requirement already satisfied: pyyaml>=5.3.1 in /usr/local/lib/python3.11/dist-packages (from ultralytics) (6.0.2)

Requirement already satisfied: requests>=2.23.0 in /usr/local/lib/python3.11/dist-packages (from ultralytics) (2.32.3)

Requirement already satisfied: scipy>=1.4.1 in /usr/local/lib/python3.11/dist-packages (from ultralytics) (1.14.1)

Requirement already satisfied: torch>=1.8.0 in /usr/local/lib/python3.11/dist-packages (from ultralytics) (2.6.0+cu124)

Requirement already satisfied: torchvision>=0.9.0 in /usr/local/lib/python3.11/dist-packages (from ultralytics) (0.21.0+cu124)

Requirement already satisfied: tqdm>=4.64.0 in /usr/local/lib/python3.11/dist-packages (from ultralytics) (4.67.1)

Requirement already satisfied: psutil in /usr/local/lib/python3.11/dist-packages (from ultralytics) (5.9.5)

Requirement already satisfied: py-cpuinfo in /usr/local/lib/python3.11/dist-packages (from ultralytics) (9.0.0)

Requirement already satisfied: pandas>=1.1.4 in /usr/local/lib/python3.11/dist-packages (from ultralytics) (2.2.2)

Requirement already satisfied: seaborn>=0.11.0 in /usr/local/lib/python3.11/dist-packages (from ultralytics) (0.13.2)

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Requirement already satisfied: contourpy>=0.1.0 in /usr/local/lib/python3.11/dist-packages (from matplotlib>=3.3.0->ultralytics)

Requirement already satisfied: cycler>=0.10 in /usr/local/lib/python3.11/dist-packages (from matplotlib>=3.3.0->ultralytics) (0.1.1)

Requirement already satisfied: fonttools>=4.22.0 in /usr/local/lib/python3.11/dist-packages (from matplotlib>=3.3.0->ultralytics)

Requirement already satisfied: kiwisolver>=1.3.1 in /usr/local/lib/python3.11/dist-packages (from matplotlib>=3.3.0->ultralytics)

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Requirement already satisfied: pytz>=2020.1 in /usr/local/lib/python3.11/dist-packages (from pandas>=1.1.4->ultralytics) (2025.2)

Requirement already satisfied: tzdata>=2022.7 in /usr/local/lib/python3.11/dist-packages (from pandas>=1.1.4->ultralytics) (2025.2)

Requirement already satisfied: charset-normalizer<4,>=2 in /usr/local/lib/python3.11/dist-packages (from requests>=2.23.0->ultralytics) (3.10.0)

Requirement already satisfied: idna<4,>=2.5 in /usr/local/lib/python3.11/dist-packages (from requests>=2.23.0->ultralytics) (3.10.0)

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Requirement already satisfied: urllib3<3,>=1.21.1 in /usr/local/lib/python3.11/dist-packages (from requests>=2.23.0->ultralytics)
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Requirement already satisfied: filelock in /usr/local/lib/python3.11/dist-packages (from torch>=1.8.0->ultralytics) (3.18.0)
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Requirement already satisfied: fsspec in /usr/local/lib/python3.11/dist-packages (from torch>=1.8.0->ultralytics) (2025.3.2)
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  Downloading nvidia_cusparse_cu12-12.3.1.170-py3-none-manylinux2014_x86_64.whl.metadata (1.6 kB)
Requirement already satisfied: nvidia-cusparseelt-cu12==0.6.2 in /usr/local/lib/python3.11/dist-packages (from torch>=1.8.0->ultralytics)
Requirement already satisfied: nvidia-nccl-cu12==2.21.5 in /usr/local/lib/python3.11/dist-packages (from torch>=1.8.0->ultralytics)
Requirement already satisfied: nvidia-tac-cu12==1.0.0 in /usr/local/lib/python3.11/dist-packages (from torch>=1.8.0->ultralytics)
```

```
!echo -e "train: /content/train/images\nval: /content/train/images\nnc: 1\nnames: ['container_door']" > /content/data.yaml
```

▼ Task 5: Object Extraction - Back Door of a Container

Objective: Extract only the back door from the container image(task5_img).

▼ Yolo8-Seg With Cropped

```
from ultralytics import YOLO
model = YOLO('yolov8n-seg.pt')
model.train(data='/content/data.yaml', epochs=20, imgsz=640, patience=5)
```

0.40841,	0.40941,	0.41041,	0.41141,	0.41241,	0.41341,	0.41441,	0.41542,	0.41642,	
0.41742,	0.41842,	0.41942,	0.42042,	0.42142,	0.42242,	0.42342,	0.42442,	0.42543,	0.42643,
0.42743,	0.42843,	0.42943,	0.43043,	0.43143,	0.43243,	0.43343,	0.43443,	0.43544,	0.43644,
0.44144,	0.44244,	0.44344,	0.44444,	0.44545,	0.44645,	0.44745,	0.44845,	0.44945,	0.45045,
0.45145,	0.45245,	0.45345,	0.45445,	0.45546,	0.45646,	0.45746,	0.45846,	0.45946,	0.46046,
0.46547,	0.46647,	0.46747,	0.46847,	0.46947,	0.47047,	0.47147,	0.47247,	0.47347,	0.47447,
0.47548,	0.47648,	0.47748,	0.47848,	0.47948,	0.48048,	0.48148,	0.48248,	0.48348,	0.48448,
0.48949,	0.49049,	0.49149,	0.49249,	0.49349,	0.49449,	0.49549,	0.49649,	0.49749,	0.49849,
0.4995,	0.5005,	0.5015,	0.5025,	0.5035,	0.5045,	0.50551,	0.50651,	0.50751,	0.50851,
0.51351,	0.51451,	0.51552,	0.51652,	0.51752,	0.51852,	0.51952,	0.52052,	0.52152,	0.52252,
0.52352,	0.52452,	0.52553,	0.52653,	0.52753,					

```
model = YOLO('/content/runs/segment/train/weights/best.pt')
results = model.predict(source='/content/task5_img.png', conf=0.015, save=True)
```

→ image 1/1 /content/task5_img.png: 352x640 1 container_door, 215.8ms
Speed: 2.8ms preprocess, 215.8ms inference, 18.5ms postprocess per image at shape (1, 3, 352, 640)
Results saved to runs/segment/predict

```
from IPython.display import Image
Image('/content/runs/segment/predict/task5_img.jpg')
```



Double-click (or enter) to edit

```
# 1. Import the necessary libraries
from ultralytics import YOLO
import cv2
import matplotlib.pyplot as plt

# 2. Load the trained model
model = YOLO('/content/runs/segment/train/weights/best.pt')

# 3. Perform prediction on the image
results = model.predict(source='/content/task5_img.png', conf=0.0148, save=True)

# 4. Read the original image using OpenCV
image = cv2.imread('/content/task5_img.png')

# 5. Extract the Bounding Box Coordinates
for result in results:
    if result.boxes: # If there are detections
        for box in result.boxes:
            # Extract the coordinates
            x_min, y_min, x_max, y_max = box.xyxy[0] # xyxy is the bounding box coordinates
            x_min, y_min, x_max, y_max = int(x_min), int(y_min), int(x_max), int(y_max)

            # 6. Crop the image using the coordinates
            cropped_image = image[y_min:y_max, x_min:x_max]

            # 7. Save the cropped image
            cv2.imwrite('/content/cropped_container_door.png', cropped_image)

            # 8. (Optional) Display the cropped image
            plt.imshow(cv2.cvtColor(cropped_image, cv2.COLOR_BGR2RGB))
            plt.axis('off')
            plt.show()
```



image 1/1 /content/task5_img.png: 352x640 1 container_door, 71.5ms
 Speed: 14.8ms preprocess, 71.5ms inference, 12.2ms postprocess per image at shape (1, 3, 352, 640)
 Results saved to runs/segment/predict2



▼ Cropped_Coordinate_container_door

```
import cv2
import numpy as np
import matplotlib.pyplot as plt

# 1. Read the original image
image_path = '/content/task5_img.png' # Replace with the path to your image
image = cv2.imread(image_path)
height, width = image.shape[:2] # Dimensions of the image (height and width)

# 2. Polygon coordinates from the label file
label = "0 0.4854489796875 0.90787209375 0.7487017265625 0.699909884375 0.797004709375 0.04025 0.4866562015625 0.1654738375 0.4854489796875"
label = label.split() # Split the line into a list

# Extract the coordinates (ignore the first value as it is the class ID)
coords = list(map(float, label[1:])) # Convert the values to numeric data
points = [(coords[i], coords[i+1]) for i in range(0, len(coords), 2)] # Convert the values into (x, y) pairs

# 3. Convert the coordinates from normalized to pixels
points_pixels = [(int(x * width), int(y * height)) for x, y in points]

# 4. Create an empty mask with the same size as the image
mask = np.zeros((height, width), dtype=np.uint8)

# 5. Draw the polygon on the mask
points_array = np.array(points_pixels, dtype=np.int32)
cv2.fillPoly(mask, [points_array], 255) # Fill the polygon with white (255)

# 6. Apply the mask to the original image
masked_image = cv2.bitwise_and(image, image, mask=mask)

# 7. (Optional) Extract the bounding box for precise cropping around the polygon
x, y, w, h = cv2.boundingRect(points_array) # Get the bounding rectangle around the polygon
cropped_image = masked_image[y:y+h, x:x+w]

# 8. Save the cropped image
cv2.imwrite('/content/segmented_container_door.png', cropped_image)

# 9. Display the cropped image
plt.imshow(cv2.cvtColor(cropped_image, cv2.COLOR_BGR2RGB))
plt.axis('off')
plt.show()
```



Start coding or [generate](#) with AI.