Morris water maze

Reinforcement learning assignment.

Computational Neuroscience

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Water maze with place cells - equations

- 1. Activity i^{th} place cell for current position rat x_t : $f_i(x_t) = exp\left(-\frac{(x_t s_i)^2}{2\sigma^2}\right)$.
- 2. Calculate value action cell activities $a_j = \sum_{i=1}^N z_{ij} f_i$ for 8 directions j, i sums over N place cells.
- 3. Actor chooses direction j with probability $P_j = exp(\beta a_j) / \sum_{j=1}^{n_j} exp(\beta a_j)$; $\beta = 2$.
- 4. Account for momentum: $d\mathbf{x}_t = (d\mathbf{x}(a_j, v \cdot dt) + m d\mathbf{x}_{t-1})/(m+1), m=3$; (dodgy!)

Calculate new position $x_{t+1} = x_t + dx(a_i, v \cdot dt)$.

Check whether new position is within pool ($x^2 < 1$), if not reverse by 180 degrees (='bounce'): dx = -dx (this is not an exact reflection but good enough for this problem).

Recalculate new position $x_{t+1} = x_t + dx(a_j, v \cdot dt)$.

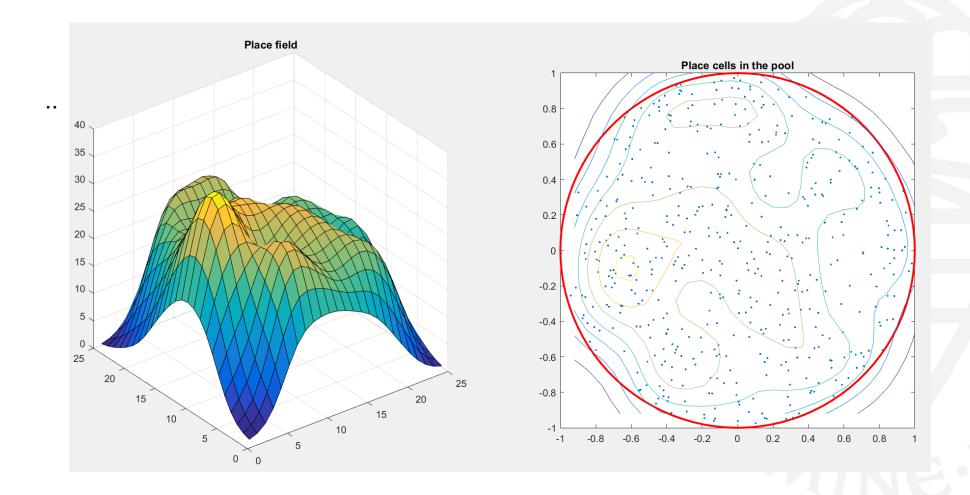


Water maze with place cells - equations

- 5. Critic evaluates outputs $C_t(x_t) = \sum_{i=1}^N w_i f_i(x_t)$ and $C_{t+1}(x_{t+1}) = \sum_{i=1}^N w_i f_i(x_{t+1})$.
- 6. Calculate prediction error $\delta_t = R_{t+1} + \gamma C_{t+1}(x_{t+1}) C_t(x_t)$. $R_{t+1} = 1$ if new position is on platform and 0 otherwise.
- 7. Critic weights are updated by $\Delta w_i = \varepsilon \ \delta_t f_i(x_t)$; $\varepsilon = 0.1$
- 8. Actor weights are updated by $\Delta z_{ij} = \varepsilon \ \delta_t f_i(x_t)$ for the selected $j; \ \varepsilon = 0.1$

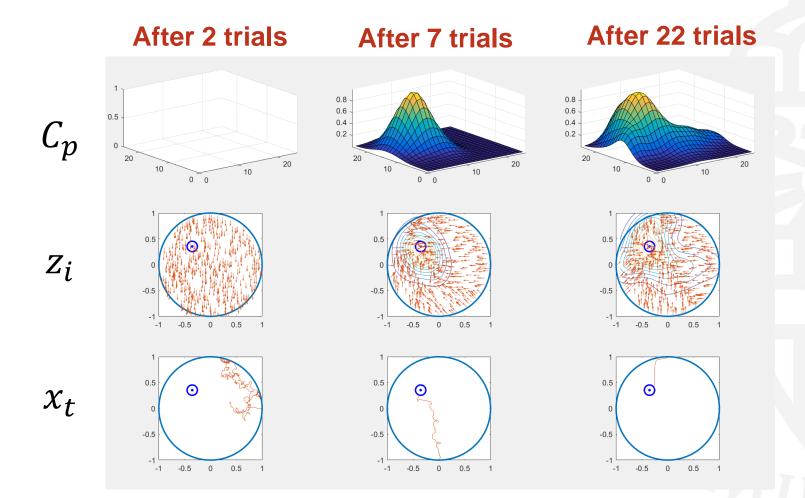


Water maze model setup





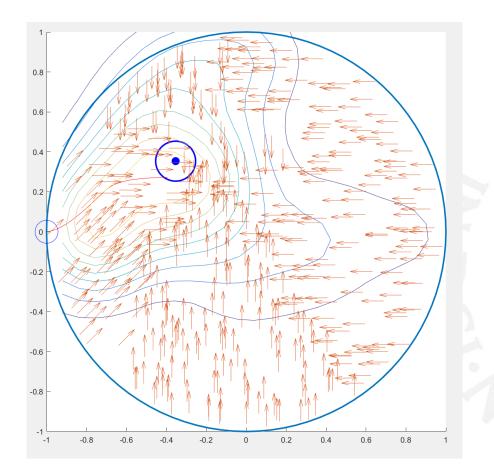
Water maze model results





Water maze model result after 25 trials

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Water maze with head direction cells - equations

- 1. Activity i^{th} place cell for current position rat x_t : $f_i(x_t) = exp\left(-\frac{(x_t s_i)^2}{2\sigma^2}\right)$.
- 2. Activity k^{th} head direction cell for current position rat x_t : $g_k(\theta_t) = exp\left(-\frac{(\theta_t \theta_k)^2}{2\sigma_\theta^2}\right)$.
- 3. Calculate value action cell activities $a_j = \sum_{i=1}^N \sum_{k=1}^8 z_{ikj} f_i g_k$ for 8 directions j, i sums over N place cells.
- 4. Actor chooses direction j with probability $P_j = exp(\beta a_j) / \sum_{j=1}^{n_j} exp(\beta a_j)$; $\beta = 2$.
- 5. Account for momentum: $d\mathbf{x}_t = (d\mathbf{x}(a_j, v \cdot dt) + m d\mathbf{x}_{t-1})/(m+1), m = 3$; (now ok!)

Calculate new position $\mathbf{x}_{t+1} = \mathbf{x}_t + d\mathbf{x}(a_j, v \cdot dt)$.

Check whether new position is within pool ($x^2 < 1$), if not reverse by 180 degrees (='bounce'): dx = -dx (this is not an exact reflection but good enough for this problem).

Recalculate new position $x_{t+1} = x_t + dx(a_i, v \cdot dt)$.

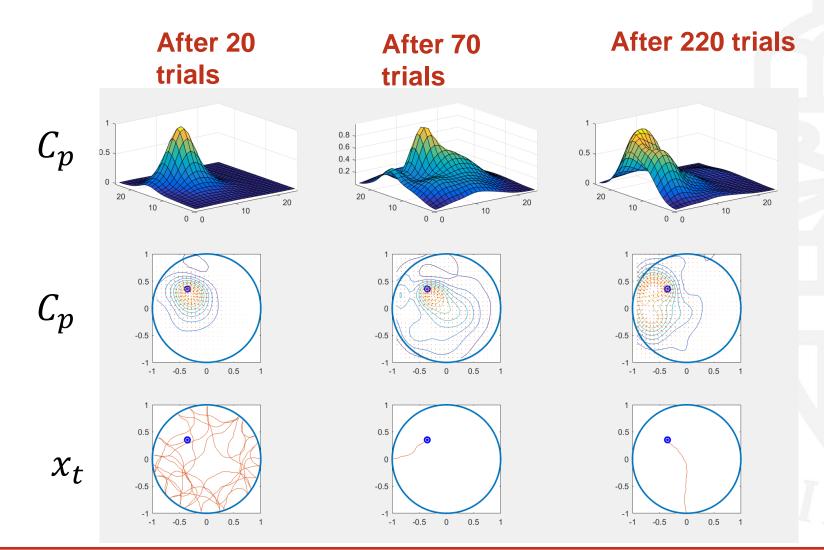


Water maze with head direction cells - equations

- 6. Critic evaluates outputs $C_t(x_t, \theta_t) = \sum_{i=1}^N \sum_{k=1}^8 w_{ik} f_i(x_t) g_k(\theta_t)$ and $C_{t+1}(x_{t+1}, \theta_{t+1}) = \sum_{i=1}^N \sum_{k=1}^8 w_{ik} f_i(x_{t+1}) g_k(\theta_{t+1})$.
- 7. Calculate prediction error $\delta_t = R_{t+1} + \gamma C_{t+1}(x_{t+1}, \theta_{t+1}) C_t(x_t, \theta_t)$. $R_{t+1} = 1$ if new position is on platform and 0 otherwise.
- 8. Critic weights are updated by $\Delta w_{ik} = \varepsilon \ \delta_t f_i(x_t) \ g_k(\theta_t)$; $\varepsilon = 0.1$
- 9. Actor weights are updated by $\Delta z_{ikj} = \varepsilon \ \delta_t f_i(x_t) \ g_k(\theta_t)$ for the selected $j; \ \varepsilon = 0.1$



Water maze model results





Water maze model result after 25 trials

