

Morris water maze

Reinforcement learning assignment.

Computational Neuroscience

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Water maze with place cells - equations

1. Activity i^{th} place cell for current position rat x_t : $f_i(x_t) = \exp\left(-\frac{(x_t - s_i)^2}{2\sigma^2}\right)$.
2. Calculate value action cell activities $a_j = \sum_{i=1}^N z_{ij} f_i$ for 8 directions j , i sums over N place cells.
3. Actor chooses direction j with probability $P_j = \exp(\beta a_j) / \sum_{j=1}^{n_j} \exp(\beta a_j)$; $\beta = 2$.
4. Account for momentum: $d\mathbf{x}_t = (d\mathbf{x}(a_j, v \cdot dt) + m d\mathbf{x}_{t-1}) / (m + 1)$, $m = 3$; (dodgy!)

Calculate new position $\mathbf{x}_{t+1} = \mathbf{x}_t + d\mathbf{x}(a_j, v \cdot dt)$.

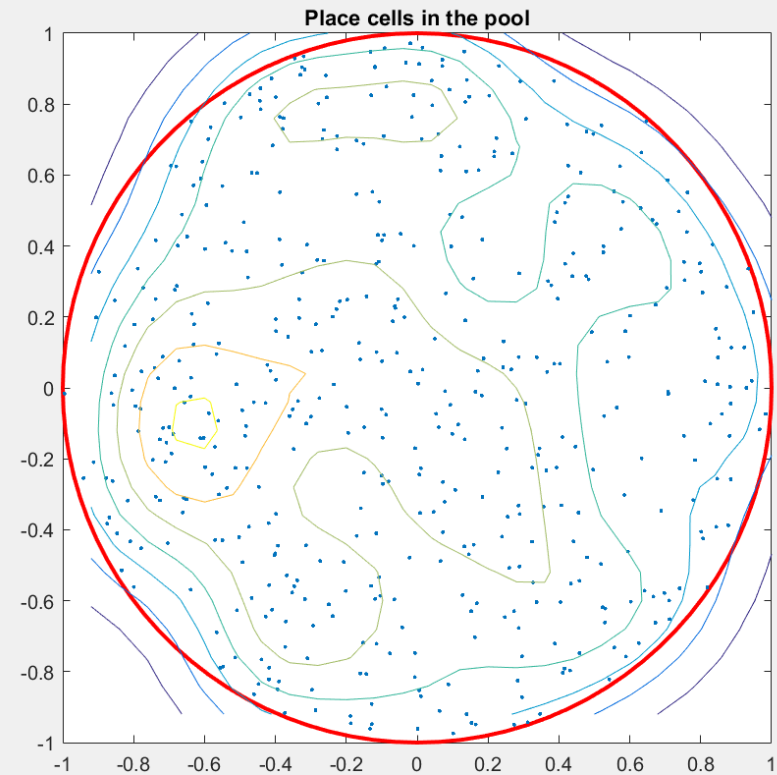
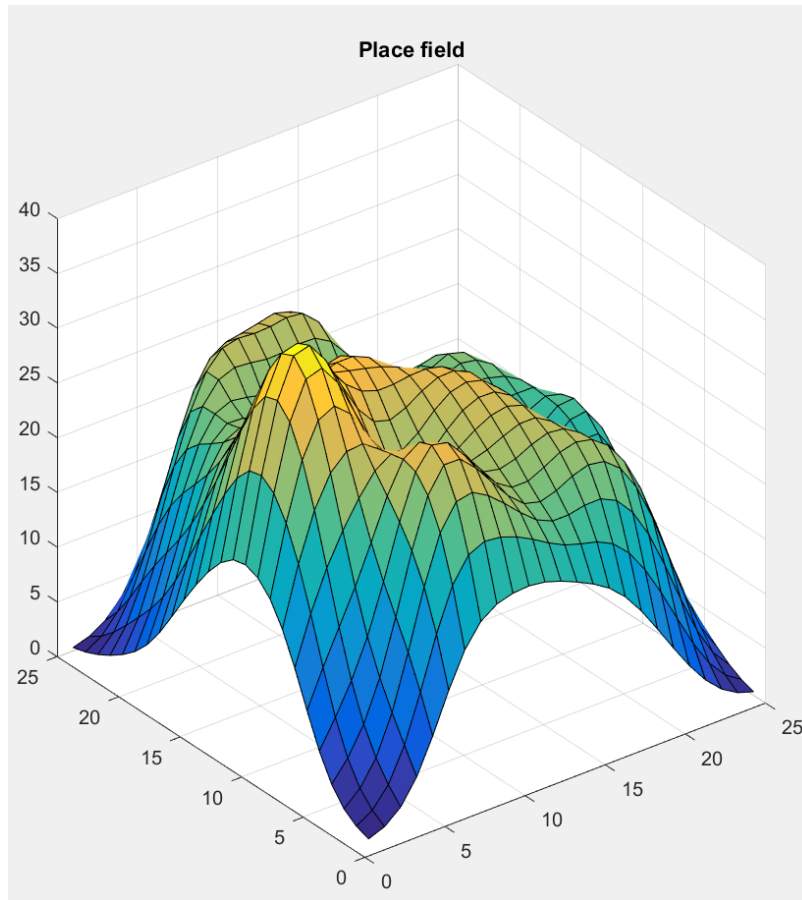
Check whether new position is within pool ($\mathbf{x}^2 < 1$), if not reverse by 180 degrees (=‘bounce’):
 $d\mathbf{x} = -d\mathbf{x}$ (this is not an exact reflection but good enough for this problem).

Recalculate new position $\mathbf{x}_{t+1} = \mathbf{x}_t + d\mathbf{x}(a_j, v \cdot dt)$.

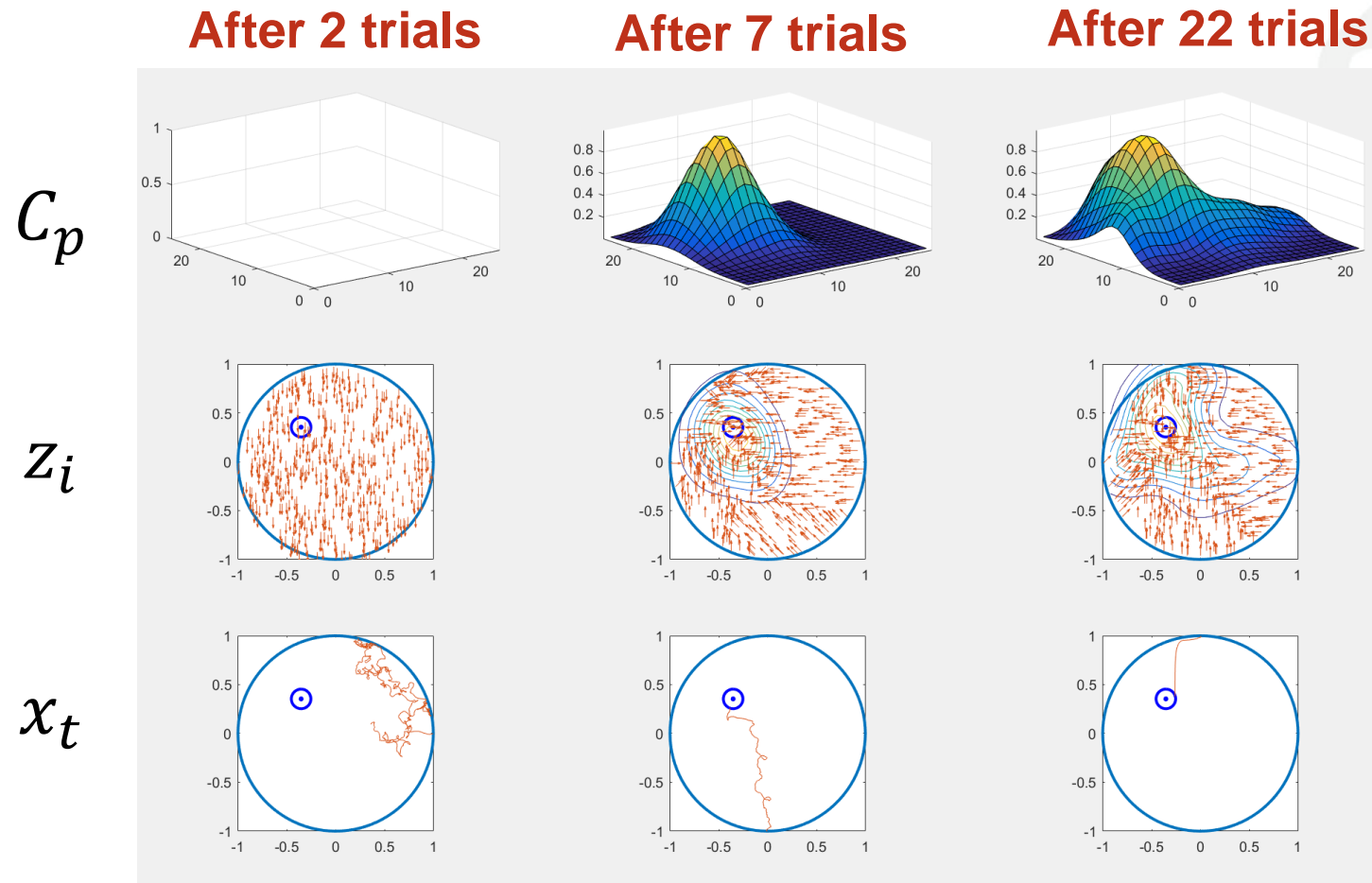
Water maze with place cells - equations

5. Critic evaluates outputs $C_t(x_t) = \sum_{i=1}^N w_i f_i(x_t)$ and $C_{t+1}(x_{t+1}) = \sum_{i=1}^N w_i f_i(x_{t+1})$.
6. Calculate prediction error $\delta_t = R_{t+1} + \gamma C_{t+1}(x_{t+1}) - C_t(x_t)$.
 $R_{t+1} = 1$ if new position is on platform and 0 otherwise.
7. Critic weights are updated by $\Delta w_i = \varepsilon \delta_t f_i(x_t)$; $\varepsilon = 0.1$
8. Actor weights are updated by $\Delta z_{ij} = \varepsilon \delta_t f_i(x_t)$ for the selected j ; $\varepsilon = 0.1$

Water maze model setup

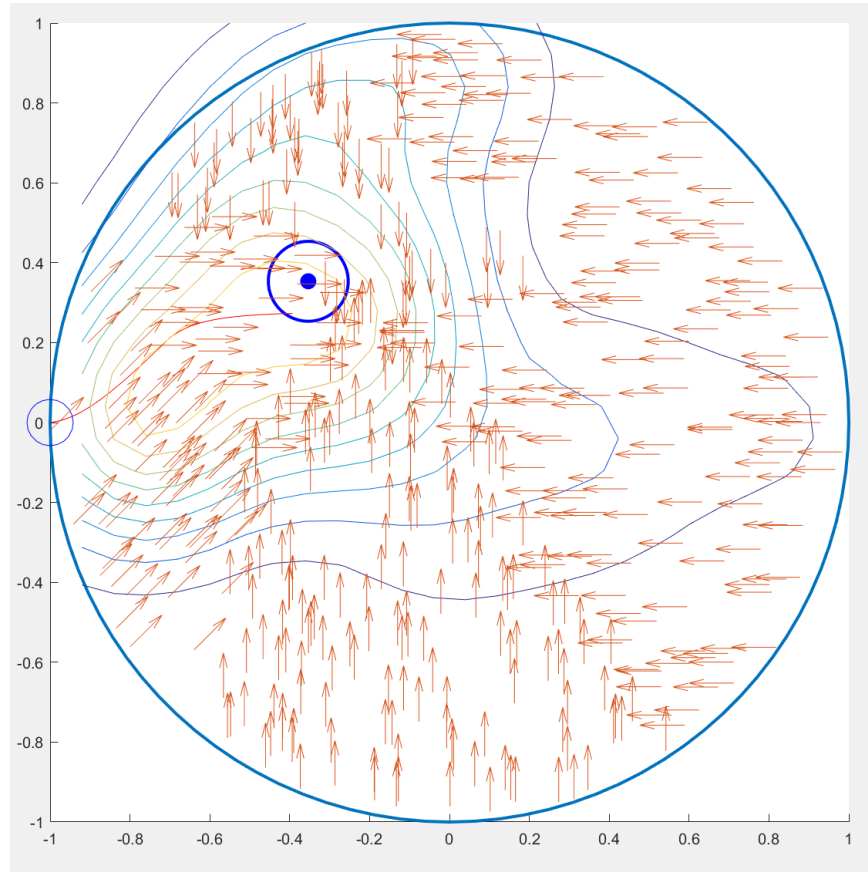


Water maze model results



Water maze model result after 25 trials

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Z_i

Water maze with head direction cells - equations

1. Activity i^{th} place cell for current position rat x_t : $f_i(x_t) = \exp\left(-\frac{(x_t - s_i)^2}{2\sigma^2}\right)$.
2. Activity k^{th} head direction cell for current position rat x_t : $g_k(\theta_t) = \exp\left(-\frac{(\theta_t - \theta_k)^2}{2\sigma_\theta^2}\right)$.
3. Calculate value action cell activities $a_j = \sum_{i=1}^N \sum_{k=1}^8 z_{ikj} f_i g_k$ for 8 directions j , i sums over N place cells.
4. Actor chooses direction j with probability $P_j = \exp(\beta a_j) / \sum_{j=1}^{n_j} \exp(\beta a_j)$; $\beta = 2$.
5. Account for momentum: $\theta_t = \frac{m}{1+m} \cdot \theta_j + \theta_{t-1}$. (better?)

Calculate new position $\mathbf{x}_{t+1} = \mathbf{x}_t + d\mathbf{x}(\theta_t, v \cdot dt)$.

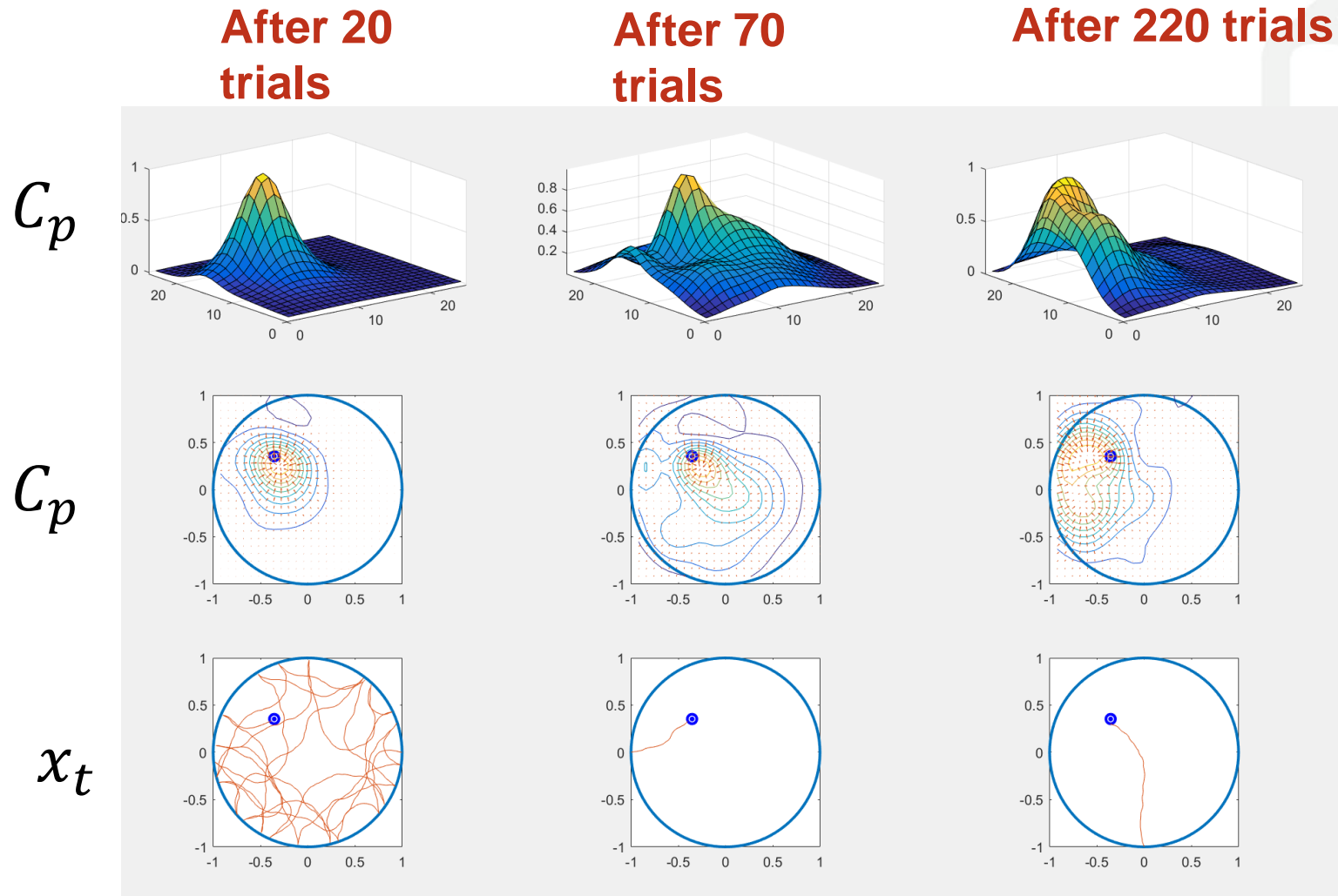
Check whether new position is within pool ($\mathbf{x}^2 < 1$), if not reverse by 180 degrees (=‘bounce’): $\theta_t = -\theta_t$ (this is not an exact reflection but good enough for this problem).

Recalculate new position $\mathbf{x}_{t+1} = \mathbf{x}_t + d\mathbf{x}(\theta_t, v \cdot dt)$.

Water maze with head direction cells - equations

6. Critic evaluates outputs $C_t(x_t, \theta_t) = \sum_{i=1}^N \sum_{k=1}^8 w_{ik} f_i(x_t) g_k(\theta_t)$ and $C_{t+1}(x_{t+1}, \theta_{t+1}) = \sum_{i=1}^N \sum_{k=1}^8 w_{ik} f_i(x_{t+1}) g_k(\theta_{t+1})$.
7. Calculate prediction error $\delta_t = R_{t+1} + \gamma C_{t+1}(x_{t+1}, \theta_{t+1}) - C_t(x_t, \theta_t)$.
 $R_{t+1} = 1$ if new position is on platform and 0 otherwise.
8. Critic weights are updated by $\Delta w_{ik} = \varepsilon \delta_t f_i(x_t) g_k(\theta_t)$; $\varepsilon = 0.1$
9. Actor weights are updated by $\Delta z_{ikj} = \varepsilon \delta_t f_i(x_t) g_k(\theta_t)$ for the selected j ; $\varepsilon = 0.1$

Water maze model results



Water maze model result after 25 trials

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