

1. Let $A = \begin{bmatrix} 1 & 2 & 3 & -4 & 8 \\ 1 & 2 & 0 & 2 & 8 \\ 2 & 4 & -3 & 10 & 17 \\ 3 & 6 & 0 & 6 & 24 \end{bmatrix}$. Find a basis for $\text{Col}(A)$, $\text{Null}(A)$ and $\text{Row}(A)$. What is $\text{rank}(A)$?

Solution.

$$\begin{bmatrix} 1 & 2 & 3 & -4 & 8 \\ 1 & 2 & 0 & 2 & 8 \\ 2 & 4 & -3 & 10 & 17 \\ 3 & 6 & 0 & 6 & 24 \end{bmatrix} \begin{array}{l} \sim \\ R_2 - R_1 \\ R_3 - 2R_1 \\ R_4 - 3R_1 \end{array} \begin{bmatrix} 1 & 2 & 3 & -4 & 8 \\ 0 & 0 & -3 & 6 & 0 \\ 0 & 0 & -9 & 18 & 1 \\ 0 & 0 & -9 & 18 & 0 \end{bmatrix} \begin{array}{l} \sim \\ -1/3R_2 \end{array} \begin{bmatrix} 1 & 2 & 3 & -4 & 8 \\ 0 & 0 & 1 & -2 & 0 \\ 0 & 0 & -9 & 18 & 1 \\ 0 & 0 & -9 & 18 & 0 \end{bmatrix} \begin{array}{l} R_1 - 3R_2 \\ \sim \\ R_3 + 9R_2 \\ R_4 + 9R_2 \end{array}$$

$$\begin{bmatrix} 1 & 2 & 0 & 2 & 8 \\ 0 & 0 & 1 & -2 & 0 \\ 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \begin{array}{l} R_1 - 8R_3 \\ \sim \end{array} \begin{bmatrix} 1 & 2 & 0 & 2 & 0 \\ 0 & 0 & 1 & -2 & 0 \\ 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

A basis for $\text{Col}(A)$ is $\left\{ \begin{bmatrix} 1 \\ 1 \\ 2 \\ 3 \end{bmatrix}, \begin{bmatrix} 3 \\ 0 \\ -3 \\ 0 \end{bmatrix}, \begin{bmatrix} 8 \\ 8 \\ 17 \\ 24 \end{bmatrix} \right\}$.

A basis for $\text{Row}(A)$ is $\left\{ \begin{bmatrix} 1 \\ 2 \\ 0 \\ 2 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \\ -2 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 1 \end{bmatrix} \right\}$.

A basis for $\text{Null}(A)$ is $\left\{ \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} -2 \\ 0 \\ 2 \\ 1 \\ 0 \end{bmatrix} \right\}$.

$\text{rank}(A) = 3$.

2. Let $A = \begin{bmatrix} -1 & 0 & 0 \\ 3 & 1 & -1 \\ 3 & 6 & -4 \end{bmatrix}$.

- a) (3 points) Find the characteristic polynomial of A .
 b) (2 points) Find the eigenvalues of A .

Solution.

a)

$$\begin{aligned} C_A(\lambda) = \det(A - \lambda I_3) &= \begin{vmatrix} -1-\lambda & 0 & 0 \\ 3 & 1-\lambda & -1 \\ 3 & 6 & -4-\lambda \end{vmatrix} = -(1+\lambda)(-1)^{1+1} \begin{vmatrix} 1-\lambda & -1 \\ 6 & -4-\lambda \end{vmatrix} \\ &= -(1+\lambda)((1-\lambda)(-4-\lambda)+6) = -(1+\lambda)(-4-\lambda+4\lambda+\lambda^2+6) \\ &= -(\lambda+1)^2(\lambda+2) \end{aligned}$$

b) $\lambda_1 = -1, \lambda_2 = -2$.

3. Let $A = \begin{bmatrix} -2 & -1 & -2 \\ 2 & 1 & 4 \\ 1 & 1 & 1 \end{bmatrix}$. The eigenvalues of A are $\lambda_1 = -1$, with $a_{\lambda_1} = 2$, and $\lambda_2 = 2$, with $a_{\lambda_2} = 1$.

- a) (4 points) Find a basis for each eigenspace of A .
 b) (2 point) Is A diagonalizable? Explain. If so, find an invertible matrix P and a diagonal matrix D such that $A = PDP^{-1}$. *Note:* You **do not** have to find P^{-1} .

Solution.

a) • $E_{\lambda_1}(A) = \text{Null}(A + I_3)$:

$$A + I_3 = \begin{bmatrix} -1 & -1 & -2 \\ 2 & 2 & 4 \\ 1 & 1 & 2 \end{bmatrix} \xrightarrow{-R_1} \begin{bmatrix} -1 & -1 & -2 \\ 2 & 2 & 4 \\ 1 & 1 & 2 \end{bmatrix} \xrightarrow{\sim} \begin{bmatrix} 1 & 1 & 2 \\ 2 & 2 & 4 \\ 1 & 1 & 2 \end{bmatrix} \xrightarrow{\begin{matrix} R_2 - 2R_1 \\ R_3 - R_1 \end{matrix}} \begin{bmatrix} 1 & 1 & 2 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\text{A basis for } E_{\lambda_1}(A) \text{ is } \left\{ \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -2 \\ 0 \\ 1 \end{bmatrix} \right\}.$$

• $E_{\lambda_2}(A) = \text{Null}(A - 2I_3)$:

$$\begin{aligned} A - 2I_3 &= \begin{bmatrix} -4 & -1 & -2 \\ 2 & -1 & 4 \\ 1 & 1 & -1 \end{bmatrix} \xrightarrow{R_1 \leftrightarrow R_3} \begin{bmatrix} 1 & 1 & -1 \\ 2 & -1 & 4 \\ -4 & -1 & -2 \end{bmatrix} \xrightarrow{\sim} \begin{bmatrix} 1 & 1 & -1 \\ 2 & -1 & 4 \\ -4 & -1 & -2 \end{bmatrix} \xrightarrow{\begin{matrix} R_2 - 2R_1 \\ R_3 + 4R_1 \end{matrix}} \begin{bmatrix} 1 & 1 & -1 \\ 0 & -3 & 6 \\ 0 & 3 & -6 \end{bmatrix} \xrightarrow{-1/3R_2} \\ &\begin{bmatrix} 1 & 1 & -1 \\ 0 & 1 & -2 \\ 0 & 3 & -6 \end{bmatrix} \xrightarrow{\begin{matrix} R_1 - R_2 \\ R_3 - 3R_2 \end{matrix}} \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & -2 \\ 0 & 0 & 0 \end{bmatrix} \end{aligned}$$

$$\text{A basis for } E_{\lambda_2}(A) \text{ is } \left\{ \begin{bmatrix} -1 \\ 2 \\ 1 \end{bmatrix} \right\}.$$

b) A is diagonalizable because $g_{\lambda_1} = 2 = a_{\lambda_1}$ and $g_{\lambda_2} = 1 = a_{\lambda_2}$.

$$P = \begin{bmatrix} -1 & -2 & -1 \\ 1 & 0 & 2 \\ 0 & 1 & 1 \end{bmatrix}, \quad D = \begin{bmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 2 \end{bmatrix}.$$

4. Let $\vec{x} = \begin{bmatrix} 3 \\ 1 \\ 1 \end{bmatrix}$ and $\vec{u} = \begin{bmatrix} 2 \\ -1 \\ -2 \end{bmatrix}$. Find the closest point to \vec{x} in $H = \text{Span}\{\vec{u}\}$. What is the shortest distance from \vec{x} to H ? You do not need to simplify your answer.

Solution. The closest point to \vec{x} in H is given by

$$\begin{aligned} \text{proj}_{\vec{u}} \vec{x} &= \frac{\vec{x} \cdot \vec{u}}{\vec{u} \cdot \vec{u}} \vec{u} = \frac{3(2) + 1(-1) + 1(-2)}{2^2 + (-1)^2 + (-2)^2} \begin{bmatrix} 2 \\ -1 \\ -2 \end{bmatrix} \\ &= \frac{3}{9} \begin{bmatrix} 2 \\ -1 \\ -2 \end{bmatrix} = \begin{bmatrix} 2/3 \\ -1/3 \\ -2/3 \end{bmatrix} \end{aligned}$$

The shortest distance is given by $\|\vec{x} - \text{proj}_{\vec{u}} \vec{x}\|$.

$$\vec{x} - \text{proj}_{\vec{u}} \vec{x} = \begin{bmatrix} 7/3 \\ 4/3 \\ 5/3 \end{bmatrix} \Rightarrow \|\vec{x} - \text{proj}_{\vec{u}} \vec{x}\| = \frac{1}{3} \sqrt{7^2 + 4^2 + 5^2} = \frac{1}{3} \sqrt{90}.$$

5. For each of the following, determine if the statement is true or false. You do not need to justify your answer.
- a) If $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_p\}$ is a linearly independent set of vectors in a subspace H , then $\dim(H) \geq p$.
 - b) If A is an $n \times n$ matrix and the equation $A\vec{x} = \vec{b}$ is inconsistent for some $\vec{b} \in \mathbb{R}^n$, then the equation $A\vec{x} = \vec{0}$ has infinitely many solutions.
 - c) If -1 is an eigenvalue of a square invertible matrix A , then -1 is also an eigenvalue of A^{-1} .

Solution. All true.

6. (BONUS) Let $\{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$ be an orthogonal set of vectors in \mathbb{R}^n and let t_1, t_2, t_3 be real numbers. Show that $\{t_1\vec{v}_1, t_2\vec{v}_2, t_3\vec{v}_3\}$ is an orthogonal set.

Solution. For $i \neq j$:

$$(t_i\vec{v}_i) \cdot (t_j\vec{v}_j) = (t_it_j)(\vec{v}_i \cdot \vec{v}_j) = 0.$$