EXP 2:

```
parent(pam, bob). /*pam is parent of bob.*/
parent(tom, bob). /*tom is parent of bob.*/
parent(tom, liz). /*tom is parent of liz.*/
parent(bob, ann). /*bob is parent of ann.*/
parent(bob, pat). /*bob is parent of pat.*/
parent(pat, jim). /*pat is parent of jim.*/
female(pam). /*pam is female.*/
male(tom). /*tom is male.*/
male(bob). /*bob is male.*/
female(liz). /*liz is female.*/
female(pat). /*pat is female.*/
female(ann). /*ann is female.*/
male(jim). /*jim is male.*/
mother(X,Y):-parent(X,Y),female(X).
father(X,Y):-parent(X,Y),male(X).
haschild(X):-parent(X,_).
sister(X,Y):-parent(Z,X),parent(Z,Y),female(X),X==Y.
brother(X,Y):-parent(Z,X),parent(Z,Y),male(X),X==Y.
```

```
Warning: /home/universe/Desktop/Students' Folders/9609/AI/exp19609.pl:10:
    Clauses of female/1 are not together in the source-file
        Earlier definition at /home/universe/Desktop/Students' Folders/9609/AI/exp19609.pl:7
        Current predicate: male/1
        Use :- discontiguous female/1. to suppress this message
Warning: /home/universe/Desktop/Students' Folders/9609/AI/exp19609.pl:13:
    Clauses of male/1 are not together in the source-file
        Earlier definition at /home/universe/Desktop/Students' Folders/9609/AI/exp19609.pl:8
        Current predicate: female/1
        Use :- discontiguous male/1. to suppress this message
Welcome to SWI-Prolog (threaded, 64 bits, version 7.6.4)
SWI-Prolog comes with ABSOLUTELY NO WARRANTY. This is free software.
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For online help and background, visit http://www.swi-prolog.org
For built-in help, use ?- help(Topic). or ?- apropos(Word).

?- mother(pam, bob).
true.

?- father(tom, bob).
true.

?- sister(ann, pat).
true.

?- sister(ann, pat).
true.

?- brother(jim, ann).
false.

?- Index (jim, ann).
```

EXP 3:

```
move(state(middle,onbox,middle,hasnot),
 grasp,
 state(middle,onbox,middle,has)).
move(state(P,onfloor,P,H),
 climb,
  state(P,onbox,P,H)).
move(state(P1,onfloor,P1,H),
 drag(P1,P2),
 state(P2,onfloor,P2,H)).
move(state(P1,onfloor,B,H),
 walk(P1,P2),
 state(P2,onfloor,B,H)).
canget(state(_,_,,has)).
canget(State1):-
  move(State1, ,State2),
 canget(State2).
```

```
EXP 7:
% A Tic-Tac-Toe program in Prolog. S. Tanimoto, May 11, 2003.
% To play a game with the computer, type
% playo.
% To watch the computer play a game with itself, type
% selfgame.
% Predicates that define the winning conditions:
win(Board, Player):- rowwin(Board, Player).
win(Board, Player) :- colwin(Board, Player).
win(Board, Player):-diagwin(Board, Player).
rowwin(Board, Player) :- Board = [Player,Player,Player,__,_,_,_].
rowwin(Board, Player) :- Board = [_,_,_,Player,Player,Player,__,_].
rowwin(Board, Player) :- Board = [_,_,_,_,Player,Player,Player].
colwin(Board, Player) :- Board = [Player,_,_,Player,_,_,Player,_,_].
colwin(Board, Player):- Board = [ ,Player, , ,Player, , ,Player, ].
colwin(Board, Player) :- Board = [_,_,Player,_,_,Player,_,_,Player].
diagwin(Board, Player) :- Board = [Player,__,_,Player,__,_,Player].
diagwin(Board, Player):- Board = [ , ,Player, ,Player, ,Player, ,].
% Helping predicate for alternating play in a "self" game:
other(x,o).
other(o,x).
game(Board, Player) :- win(Board, Player), !, write([player, Player, wins]).
game(Board, Player) :-
 other(Player, Otherplayer),
 move(Board, Player, Newboard),
 !,
 display(Newboard),
 game(Newboard,Otherplayer).
move([b,B,C,D,E,F,G,H,I], Player, [Player,B,C,D,E,F,G,H,I]).
move([A,b,C,D,E,F,G,H,I], Player, [A,Player,C,D,E,F,G,H,I]).
move([A,B,b,D,E,F,G,H,I], Player, [A,B,Player,D,E,F,G,H,I]).
move([A,B,C,b,E,F,G,H,I], Player, [A,B,C,Player,E,F,G,H,I]).
move([A,B,C,D,b,F,G,H,I], Player, [A,B,C,D,Player,F,G,H,I]).
move([A,B,C,D,E,b,G,H,I], Player, [A,B,C,D,E,Player,G,H,I]).
```

```
move([A,B,C,D,E,F,b,H,I], Player, [A,B,C,D,E,F,Player,H,I]).
move([A,B,C,D,E,F,G,b,I], Player, [A,B,C,D,E,F,G,Player,I]).
move([A,B,C,D,E,F,G,H,b], Player, [A,B,C,D,E,F,G,H,Player]).
display([A,B,C,D,E,F,G,H,I]) :- write([A,B,C]),nI,write([D,E,F]),nI,
write([G,H,I]),nI,nI.
selfgame :- game([b,b,b,b,b,b,b,b,b],x).
% Predicates to support playing a game with the user:
x can win in one(Board):- move(Board, x, Newboard), win(Newboard, x).
% The predicate orespond generates the computer's (playing o) reponse
% from the current Board.
orespond(Board, Newboard) :-
 move(Board, o, Newboard),
 win(Newboard, o),
 1.
orespond(Board, Newboard) :-
 move(Board, o, Newboard),
 not(x can win in one(Newboard)).
orespond(Board, Newboard) :-
 move(Board, o, Newboard).
orespond(Board, Newboard) :-
 not(member(b,Board)),
 !,
 write('Cats game!'), nl,
 Newboard = Board.
% The following translates from an integer description
% of x's move to a board transformation.
xmove([b,B,C,D,E,F,G,H,I], 1, [x,B,C,D,E,F,G,H,I]).
xmove([A,b,C,D,E,F,G,H,I], 2, [A,x,C,D,E,F,G,H,I]).
xmove([A,B,b,D,E,F,G,H,I], 3, [A,B,x,D,E,F,G,H,I]).
xmove([A,B,C,b,E,F,G,H,I], 4, [A,B,C,x,E,F,G,H,I]).
xmove([A,B,C,D,b,F,G,H,I], 5, [A,B,C,D,x,F,G,H,I]).
xmove([A,B,C,D,E,b,G,H,I], 6, [A,B,C,D,E,x,G,H,I]).
xmove([A,B,C,D,E,F,b,H,I], 7, [A,B,C,D,E,F,x,H,I]).
xmove([A,B,C,D,E,F,G,b,I], 8, [A,B,C,D,E,F,G,x,I]).
xmove([A,B,C,D,E,F,G,H,b], 9, [A,B,C,D,E,F,G,H,x]).
xmove(Board, N, Board) :- write('Illegal move.'), nl.
```

```
% The 0-place predicate playo starts a game with the user.

playo :- explain, playfrom([b,b,b,b,b,b,b,b]).

explain :-
    write('You play X by entering integer positions followed by a period.'),
    nl,
    display([1,2,3,4,5,6,7,8,9]).

playfrom(Board) :- win(Board, x), write('You win!').
playfrom(Board) :- win(Board, o), write('I win!').
playfrom(Board) :- read(N),
    xmove(Board, N, Newboard),
    display(Newboard),
    orespond(Newboard, Newnewboard),
    display(Newnewboard),
    playfrom(Newnewboard).
```

OUTPUT:



```
EXP 6:
import heapq
class PuzzleNode:
       def init (self, state, parent=None, move="Initial"):
       self.state = state
       self.parent = parent
       self.move = move
       self.depth = 0
       if parent:
       self.depth = parent.depth + 1
       def __lt__(self, other):
       return self.depth < other.depth
       def __eq__(self, other):
       return self.state == other.state
       def hash (self):
       return hash(str(self.state))
       def str (self):
       return str(self.state)
       def get blank position(self):
       for i, row in enumerate(self.state):
       if 0 in row:
               return (i, row.index(0))
       def expand(self):
       blank pos = self.get blank position()
       children = []
       moves = [(0, 1), (0, -1), (1, 0), (-1, 0)] # right, left, down, up
       for move in moves:
       new_row, new_col = blank_pos[0] + move[0], blank_pos[1] + move[1]
       if 0 \le \text{new row} \le 3 and 0 \le \text{new col} \le 3:
               new_state = [row[:] for row in self.state]
               new_state[blank_pos[0]][blank_pos[1]] = new_state[new_row][new_col]
               new state[new row][new col] = 0
               children.append(PuzzleNode(new_state, self, move))
       return children
```

```
def is_goal(self):
       return self.state == [[0, 1, 2],
                       [3, 4, 5],
                       [6, 7, 8]]
       def heuristic(self):
       # Manhattan distance heuristic
       distance = 0
       for i in range(3):
       for j in range(3):
               if self.state[i][j] != 0:
               row, col = divmod(self.state[i][j], 3)
               distance += abs(row - i) + abs(col - j)
       return distance + self.depth
def a_star_search(initial_state):
       initial node = PuzzleNode(initial state)
       frontier = []
       heapq.heappush(frontier, initial_node)
       explored = set()
       while frontier:
       current_node = heapq.heappop(frontier)
       if current_node.is_goal():
       return current_node
       explored.add(current_node)
       for child in current_node.expand():
       if child not in explored:
               heapq.heappush(frontier, child)
       return None
def print_solution(solution_node):
       path = []
       current node = solution node
       while current_node:
       path.append(current node)
       current_node = current_node.parent
```

```
path.reverse()

for i, node in enumerate(path):
    print("Step:", i, "Move:", node.move)
    print(node.state)

if __name__ == "__main__":
    initial_state = [[1, 2, 3], [0, 4, 6], [7, 5, 8]]
    solution_node = a_star_search(initial_state)
    if solution_node:
    print("Solution found!")
    print_solution(solution_node)
    else:
    print("No solution found!")
```

Output:

