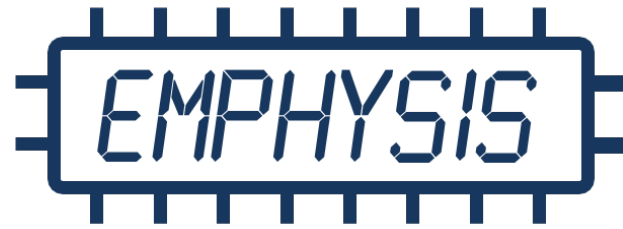
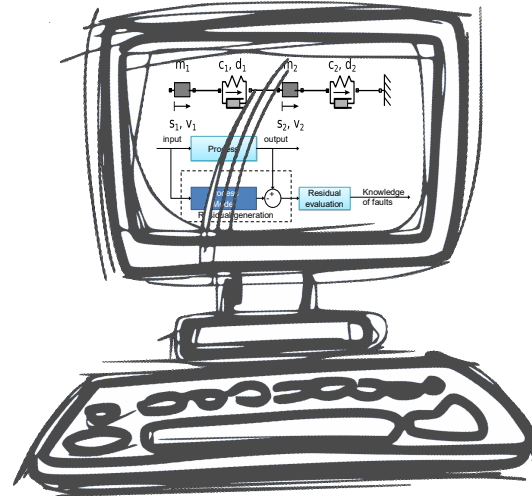


eFMI vs. FMI

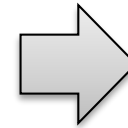
From Physical Models to ECU Software

Recorded July 15, 2021

Oliver Lenord (Bosch Research)



Aug. 2017 - Feb. 2021



Modelica
Association

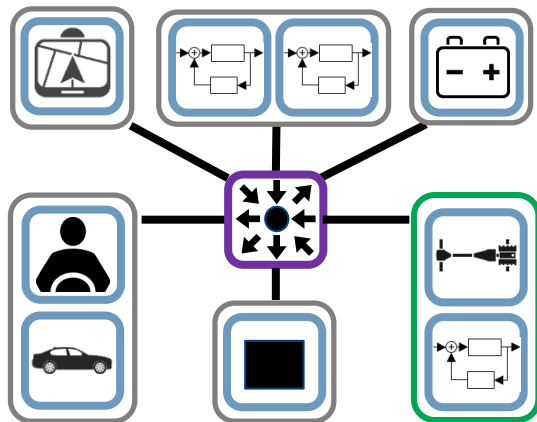
March 2021-



How?

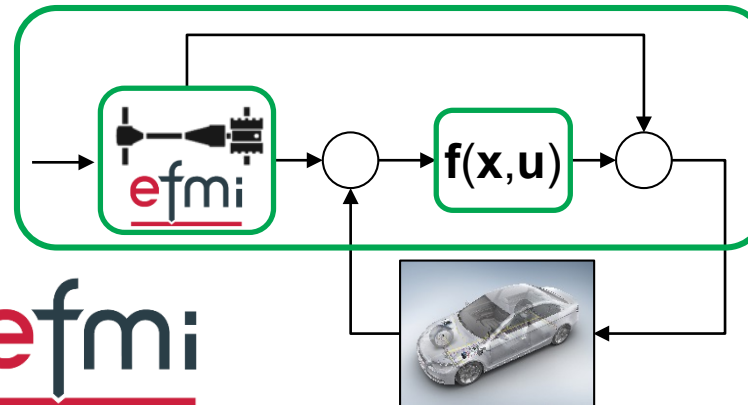
FMI vs. eFMI (FMI for embedded systems)

Model-based Systems Engineering

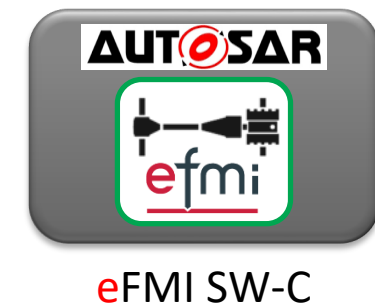
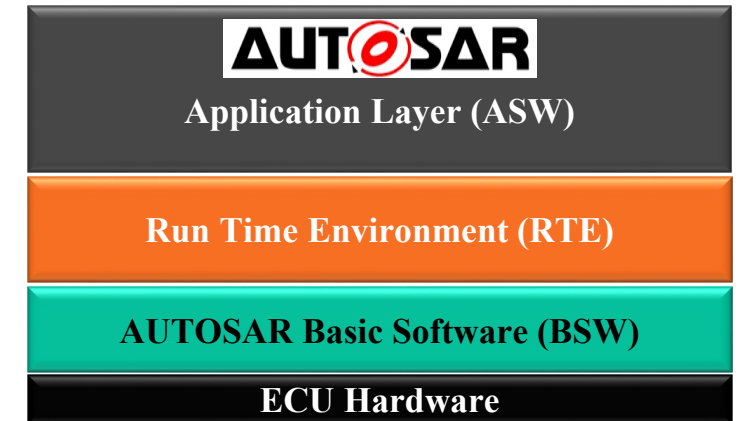


Model-based Control Design

- Virtual Sensors
- Feed-forward Control
- Model-based Diagnosis
- Model Predictive Control
- Advanced operating strategies
- ...



Software Engineering



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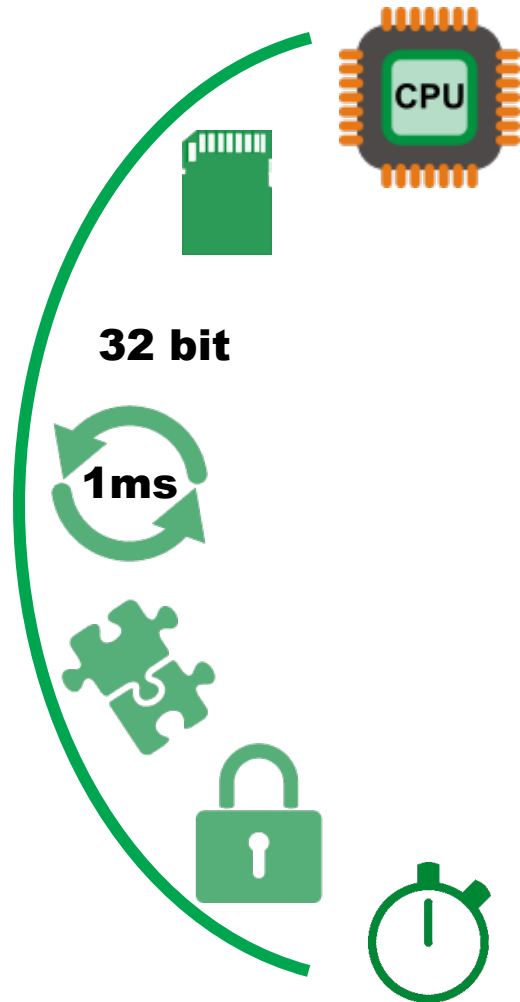
MINISTÈRE DE L'ÉCONOMIE
ET DES FINANCES



AGENTSCAP
INNOVEREN &
ONDERNEMEN

How?

Special requirements of automotive embedded systems



- Limited computation power
- Limited memory,
- Single precision
- Limited sampling rate
- No exception handling
- Static memory allocation.
- Inbound guarantees.
- Guaranteed execution time.

- Specialized Hardware



Bosch MDG1 ECU

- SW Architectures



- Rules & Regulations



Motor Industry Software Reliability Association

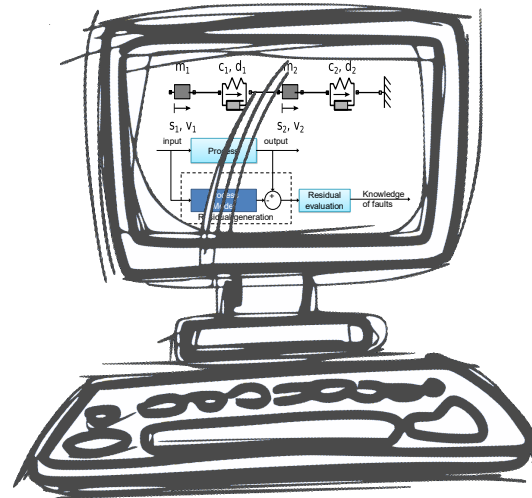
Model-based development with “eFMI”

From Physical Models to ECU Software

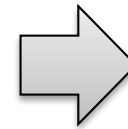
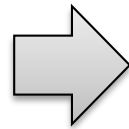
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- ➔ Look-up EMPHYSIS results: <https://emphysis.github.io/>
- ➔ Visit us on <https://efmi-standard.org/>
- ➔ Join the MAP-efmi: <https://modelica.org/>



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