

# Outline: Linear Models in Large Feature Spaces (supervised) Dimension Reduction (F. Chiaromonte)

Back to more traditional statistical approaches:

- **Feature (Subset) Selection**
  - **Best Subset Selection**
  - **Step-wise Selection**

Followed by LS fit of the (smaller) model comprising the selected features.

- **Dimension Reduction**
  - **Principal Components** (unsupervised reduction)
  - **Sufficient Dimension Reduction** (supervised reduction)

Followed by LS fit of the (smaller) model comprising the selected linear combinations  
also, in the case of a binary or categorical response (Generalized Linear Models)

- **Linear Discriminant Analysis** (seen as supervised reduction)

Followed by ML fit of the (smaller) model comprising the selected linear combinations

Also these can be thought of in the framework of constrained LS: **Linear constraints** to force  $\beta$  in a coordinate space, or a generic linear subspace, of  $\mathbb{R}^p$ . **BUT WE NEED AN ADDITIONAL "INGREDIENT"!**

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Dimension Reduction: ISLR also describes **Partial Least Squares**. But does not describe Sufficient Dimension Reduction techniques.

*Dimension Reduction: How do we produce a  $p \times p$  matrix  $V$  expressing an O.N. basis in the feature space?*

(we then focus on its last  $(p-d)$  rows to create the linear constraints  $V_{DR}$ )

Dimension Reduction:

Take the O.N. basis provided by the Eigen decomposition of an appropriate positive definite matrix. The eigenvectors express the directions, and the corresponding eigenvalues their ordering.

This corresponds to a rotation of the elements of the Canonical O.N. basis  $\{e_1, \dots, e_p\}$ , and provides

**$V$  – a rotation matrix**

Other approaches to dimension reduction exist, but some of the most popular (e.g. **Principal Components Analysis**, unsupervised; **Sliced Inverse Regression** supervised) use Eigen decompositions.

**Principal Components** (see also ISLR Chapter 10, Sections 1,2)

Units\Features	$X_1$	$X_2$	...	$X_p$
Unit 1	$x_{11}$	$x_{12}$		$x_{1p}$
Unit 2	$x_{21}$	$x_{22}$		$x_{2p}$
.				
.				
.				
Unit n	$x_{n1}$	$x_{n2}$		$x_{np}$

p features measured on n units:

- An  $n \times p$  data matrix  $X$
- A data cloud of n points in  $\mathbf{R}^p$ .

Location is irrelevant; assume each feature is centered, mean 0.

$$\bar{X} = \mathbf{0}_p \quad \text{mean vector in } \mathbf{R}^p; \text{ cloud is centered/located at origin}$$

$$S \propto X'X \quad \text{(sample) } p \times p \text{ variance/covariance matrix}$$

Create orthogonal directions in  $\mathbf{R}^p$  (and corresponding linear combinations) ranked by variability of the data cloud.

In many applications (but not all) these are the most informative, capturing structure in the data. ***Here, we think of them as generating composite features to be used in a linear model – but we do not consider  $Y$  in creating them!***

Take the Eigen decomposition of S:

$$S = \sum_{m=1}^p \lambda_m \phi_m \phi_m^T$$

eigenvalues are variances along the directions identified by eigenvectors; in non-increasing order.

$$\lambda_1 \geq \dots \geq \lambda_p \geq 0 \quad (\text{eigenvalues})$$

$$\|\phi_m\| = \phi_m^T \phi_m = 1, \phi_m^T \phi_k = 0 \quad m, k = 1, 2, \dots, p \quad (\text{eigenvectors})$$

For any given dimension  $m$ , identify the linear subspaces closest to the data:

$$\|P_{\text{Span}(\phi_1 \dots \phi_p)} X\|^2 = \max$$

$m$ -dimensional representation most likely to be useful in capturing structure, most informative (not always!)

*Here, the reduced feature space we use to formulate a linear model once we chose  $m^*=d$ .*

$V = (\phi_1, \phi_2 \dots \phi_p) \quad (p \times p)$       **ROTATION MATRIX** provided by the eigenvectors of S

**LOADINGS:** coefficients expressing the m-th component in terms of the original features

$$\phi_m^T = (\phi_{m1}, \phi_{m2} \dots \phi_{mp})$$

coordinates of each element (m-th) of the new rotated basis in terms of the original Canonical basis.

**SCORES:** values of the m-th component on the n units

$$z_{im} = \phi_{m1}x_{i1} + \phi_{m2}x_{i2} \dots + \phi_{mp}x_{ip} \quad , \quad i = 1, 2 \dots n$$

coordinates of the n data points in terms of each element (m-th) of the new rotated basis. These express the values of the new composite features on each unit.

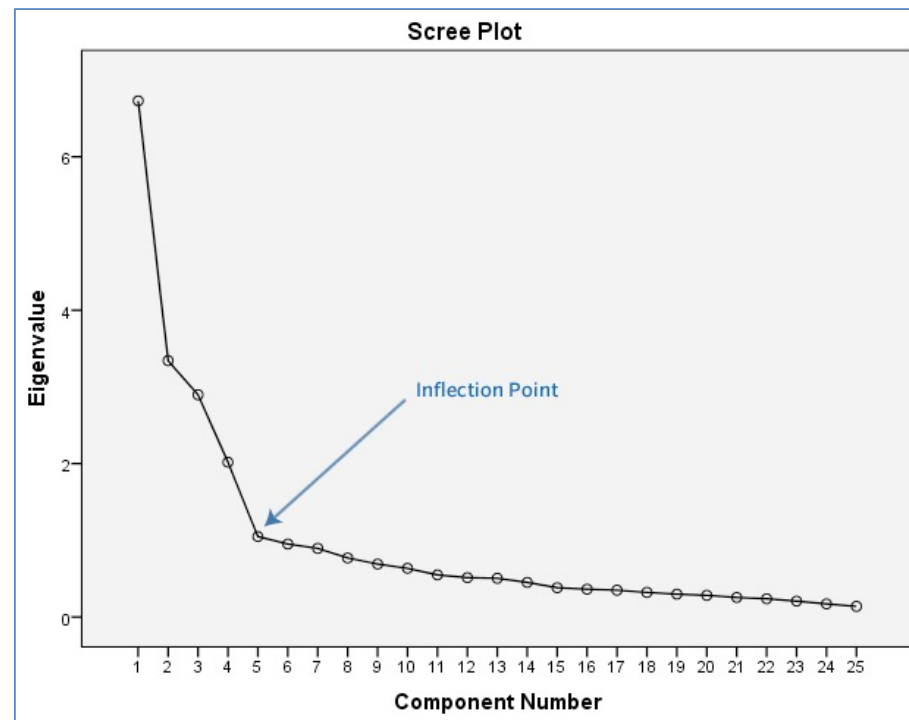
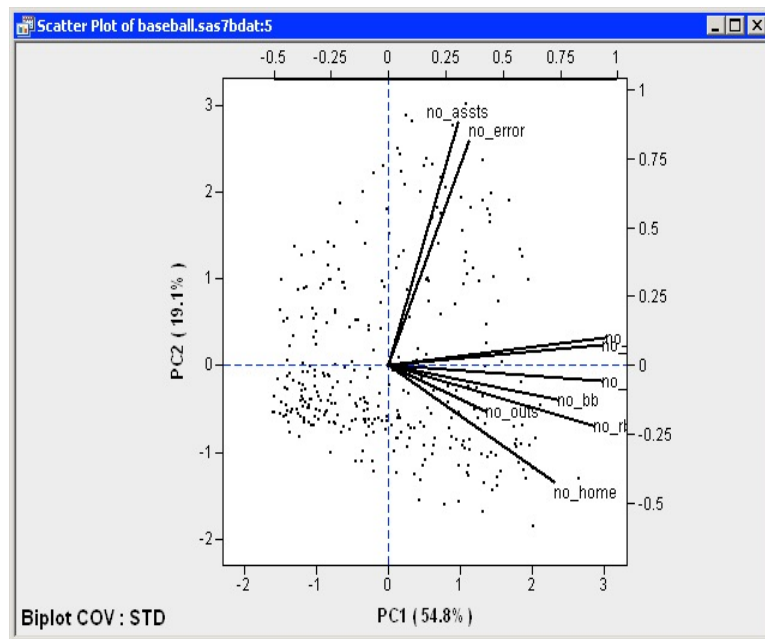
**PERCENTAGE OF VARIANCE EXPLAINED (PVE)** by the m-th component

$$PVM_m = \frac{\lambda_m}{\sum_{k=1}^p \lambda_k} = \frac{\text{var}(\phi_m^T X)}{\sum_{k=1}^p \text{var}(\phi_k^T X)}$$

Also, **CUMULATIVE PVE** up to the m-th component

$$CPVM_m = \sum_{j=1}^m PVM_j = \frac{\sum_{j=1}^m \lambda_j}{\sum_{k=1}^p \lambda_k}$$

**Biplot:** shows the scores for two specified components (e.g. 1<sup>st</sup> and 2<sup>nd</sup>; projection of the points on the first PCA plane) along with the loadings represented by arrows.



**Scree plot:** Show the variances (eigenvalues) or PVEs in non-increasing order (graphical diagnostic to aid in the selection of  $m^*=d$ )

## Sliced Inverse Regression (SIR):

Method for supervised (sufficient) dimension reduction.

Main limitation of PC regression is that the composite features are identified as to capture variability in the feature space; the response  $Y$  plays no role.

Directions of maximal variability are not necessarily directions of maximal explanatory power with respect to  $Y$ !

Can we perform ***supervised*** dimension reduction?

Yes, ~30 years old field of statistical research named ***Sufficient Dimension Reduction*** (SDR)

Some references:

- Li, K. C. (1991) Sliced inverse regression for dimension reduction (with discussion). Journal of the American Statistical Association, 86, 316–327.
- Cook, R. D. (1998) Regression Graphics: Ideas for Studying Regressions through Graphics. New York: Wiley.
- Ma, Y. and Zhu, L. (2013) A review on dimension reduction. International Statistical Review, 81, 134–150.

R package:

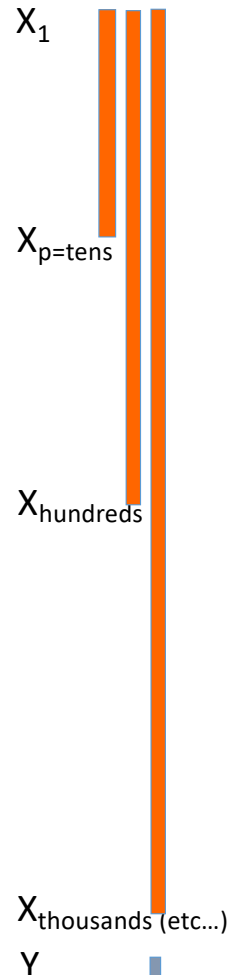
<https://cran.r-project.org/web/packages/dr/index.html>

<https://cran.r-project.org/web/packages/dr/vignettes/overview.pdf>



high dimensional feature vector (p)

Small composite feature vector  
(d=1,2,3)



Response (any nature)

**(1) Sufficient Dimension Reduction (SDR):** inference on the **Central Subspace (CS)**, which retains information on the dependence between  $Y$  and  $X$

$$S_{Y|X} \text{ smallest s.t. } Y \perp X | P_{S_{Y|X}} X$$

$$S_{Y|X} = \text{Span}(A_{p \times d}), \quad Y \perp X | A^T X \text{ basis version}$$

$$d = \dim(S_{Y|X}) \text{ structural dimension}$$

**(2) Modeling:**  $Y$  as a function of the composite feature vector and random error

$$Y = m(\tilde{X}; \varepsilon) \quad \text{e.g.} \quad Y = \beta_o + \beta^T \tilde{X} + \varepsilon$$

need methods for inference on the CS (on the spanning matrix  $A$ ) and on  $d$ !

**SIR**: simplest SDR method, based on an Eigen decomposition

- Consider the regression of X on Y (this is the inverse regression)
- Slice the range of Y in  $h=1,2,\dots,H$  slices (if continuous, otherwise use classes) and form the sample covariance matrix of  $E(X|Y)$

$$\bar{X}_h = \frac{1}{n_h} \sum_{y_i \in h} X_i \quad h = 1, 2, \dots, H \quad (\text{we always assume overall mean vector} = 0)$$

$$M = \frac{1}{n} \sum_{h=1}^H n_h \bar{X}_h \bar{X}_h^T$$

- Take the Eigen decomposition of

$$S^{-1}M = \sum_{m=1}^p \lambda_m \phi_m \phi_m^T$$

**Rescaling by  $S^{-1}$  very important! Weighing directions in the feature space**  
(also, cannot apply as is if  $n < p$ ,  $\text{rank}(S)$  cannot exceed  $n-1$ )

$\lambda_1 \geq \dots \geq \lambda_p \geq 0$  (eigenvalues)    Note: only  $H-1$  of the eigenvalues can be  $> 0$ ,  $\text{rank}(M)$  cannot exceed  $H-1$

$\|\phi_m\| = \phi_m^T \phi_m = 1, \phi_m^T \phi_k = 0 \quad m, k = 1, 2, \dots, p$  (eigenvectors)

- Under conditions on the joint distribution of X (linearity), for any given dimension  $m$ , we identify the linear subspaces with highest explanatory power (directions within the CS).
- If we know  $d$ , we estimate the whole CS.

Remarks:

- Can make bi-plots and scree plots exactly as for PCA.

Also, If  $d=1,2$

- Can plot Y vs the composite features to visualize the data and create a satisfactory model.
- Can use non-parametric regression fits.
- Like in feature selection (LASSO and related techniques), large literature. Some relevant developments:
  - Chiaromonte et al. (2002). *Sufficient dimension reduction in regressions with categorical predictors*. Annals of Statistics.
  - Li et al. (2010). *Groupwise dimension reduction*. JASA.
  - Guo et al. (2014). *Groupwise dimension reduction via envelope methods*. JASA.
  - Liu et al. (2017). *Structured Ordinary Least Squares: A Sufficient Dimension Reduction approach for regressions with partitioned predictors and heterogeneous units*. Biometrics.

***Dimension Reduction:*** the relevant (structural) dimension  $d$  is selected

- Based on diagnostic statistics and their plots; e.g., for methods based on an Eigen decomposition, statistics and plots can be derived from eigenvalues.
- Using tests. For methods based on an Eigen decomposition, one can test how many tail eigenvalues are significantly  $> 0$ . More generally, one can use a sequence of tests, e.g. for any  $q=0,1,\dots,(p-1)$  test whether  $H_0: d=q$  vs  $H_a: d>q$ .
- Minimizing BIC or BIC-like criteria.
- Assessing stability through the Bootstrap (rather different approach; see Ye and Weiss (2003))

## Linear Discriminant Analysis (LDA):

as a method for supervised dimension reduction when Y is categorical, again based on an Eigen decomposition.

Works just like SIR, but uses a *different rescaling*.

- Consider predicting Y based on X looking at how X varies in each of the Y classes (inverse approach)
- Say Y has H levels  $h=1,2,\dots,H$ . Without having to slice, form the sample covariance matrix of  $E(X|Y)$

$$\bar{X}_h = \frac{1}{n_h} \sum_{y_i \in h} X_i \quad h = 1, 2, \dots, H \quad (\text{we always assume overall mean vector} = 0)$$

$$M = \frac{1}{n} \sum_{h=1}^H n_h \bar{X}_h \bar{X}_h^T$$

**This is the between var/cov matrix  $S_B$**

- Take the Eigen decomposition of

$$\boxed{S_W^{-1}} \cancel{S}^{-1} M = \sum_{m=1}^p \lambda_m \phi_m \phi_m^T$$

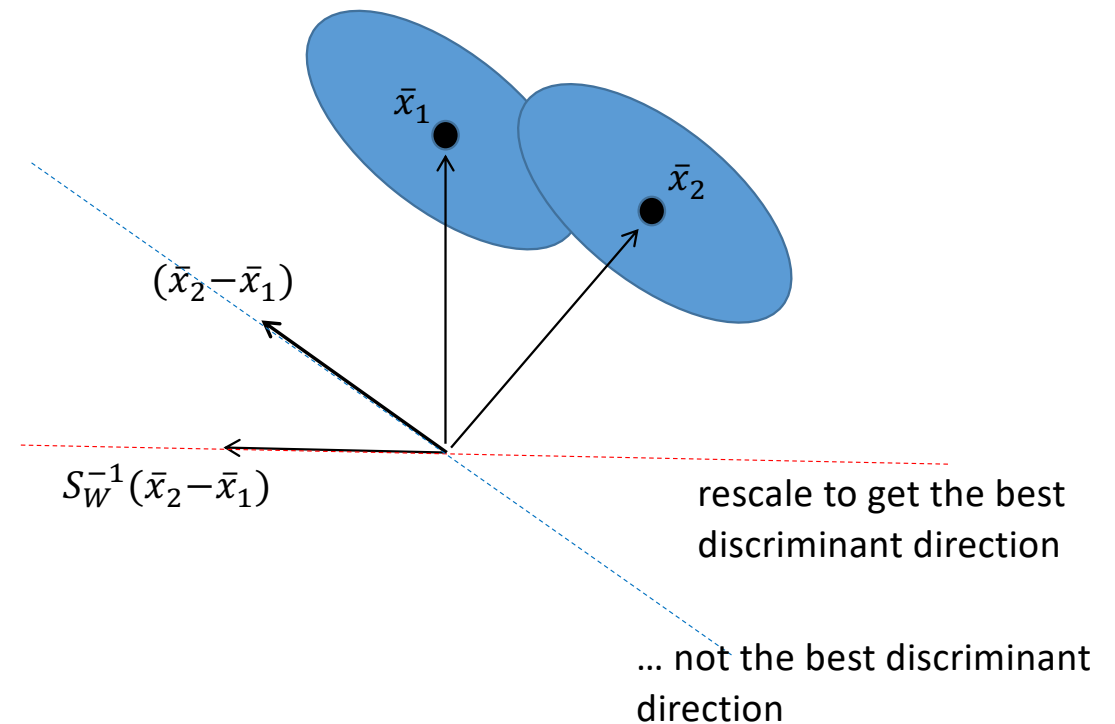
**In rescaling, instead of S (overall sample var/cov matrix) use  $S_W$  (within sample var/cov matrix). A different way of weighing directions in the feature space! (cannot apply as is if  $\text{rank}(S_W) < p$ )**

$\lambda_1 \geq \dots \geq \lambda_p \geq 0$  (eigenvalues)     Note: only H-1 of the eigenvalues can be  $> 0$ ,  $\text{rank}(M)$  cannot exceed H-1

$\|\phi_m\| = \phi_m^T \phi_m = 1, \phi_m^T \phi_k = 0 \quad m, k = 1, 2, \dots, p$  (eigenvectors)

Decomposition of the var/cov matrix; within and between variation

$$S = S_B + S_W \propto \sum_{k=1 \dots H} \sum_{i: y_i \in k} (x_i - \bar{x}_k)(x_i - \bar{x}_k)' + \sum_{k=1 \dots H} n_k (\bar{x}_k - \bar{x})(\bar{x}_k - \bar{x})'$$



LDA discriminant function (classify to highest)

$$\hat{\delta}_k(x) = (S_W^{-1} \bar{x}_k)'x - \frac{1}{2} \bar{x}_k' S_W^{-1} \bar{x}_k + \log \frac{n_k}{n}$$

$$\hat{\delta}_2(x) - \hat{\delta}_1(x) = (S_W^{-1} (\bar{x}_2 - \bar{x}_1))'x + const$$

for simplicity H=2