# Virtual Classes & Polymorphism

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# Example (revisited)

• We want to implement a graphics system

 We plan to have lists of shape. Each shape should be able to draw itself, compute its size, etc.

```
class Shape { float x,y; public:
  void draw() const {cout<<'h';}</pre>
  double area() const;
  void drawTwice() const {draw(); draw();}
};
class Square: public Shape { float size; public:
  void draw() const {cout<<'q';}</pre>
  double area() const;
};
class Circle: public Shape {float radius; public:
  void draw() const {cout<<'c';}</pre>
  double area() const;
```

Now if we write
Shape myShapes[2];
Circle c;
myShapes[0] = c;
myShapes[1] = Square();
for (...) myShapes[i].draw();

What will happen?

Now if we write

Shape myShapes[2];

myShapes[0] = Circle();

myShapes[1] = Square();

What will happen?

— The Circle and Square will be constructed and then *sliced* to fit inside the Shape objects.

"myShapes[0] = Circle()" copies from the circle, its hidden "Shape" field.

```
Now if we write (like in Java):
Circle c;
Square s;
Shape* myShapes[2];
myShapes[0] = &c;
myShapes[1] = &s;
```

What will happen when we call myShapes[0]->draw(); ?

```
Now if we write (like in Java):

Shape* myShapes[2];

myShapes[0] = new Circle();

myShapes[1] = new Square();
```

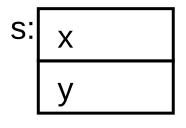
What will happen when we call myShapes[0]->draw(); ?

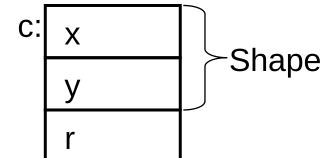
No slicing, but still, h will be printed!

# Underneath the Hood: Static Resolution

```
class Shape
   double x;
   int y;
};
class Circle:
  public Shape
   double r;
```

```
Shape s;
Circle c;
```





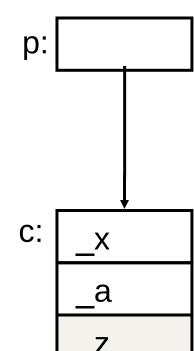
# Pointing to an Inherited Class

```
Circle c;
Shape* p = &c;
p points to the hidden
```

"Shape" field inside c.

When using \*p, we treat c as though it was a Shape object.

The compiler cannot know if \*p is from a derived class or not!



# **Dynamic Resolution**

# Static/early resolution

- Based on the type of the variable.
- Determined at compile time.

## **Dynamic/late resolution:**

- Based on the type of the object
  - Determined at run time

[Java Like]

# dynamic resolution

The virtual keyword states that the method can be overridden in a dynamic manner.

```
class Shape
public:
 virtual void draw() const
    {cout<<'h';}
virtual double area() const;
};
class Square: public Shape
public:
 virtual void draw() const
    {cout<<'q';}
 virtual double area() const;
};
```

```
class Circle: public Shape
{
public:
  void draw() const
      {cout<<'c';}
  double area() const;
};</pre>
```

# dynamic resolution

Returning to the shapes example, using virtual methods gives the desired result:

```
Shape* s=new Circle;
s->draw();
```

Will print 'c'

#### Virtual Methods

Class Base defines a *virtual method* foo()
The resolution of foo() is dynamic in **all**subclasses of Base.

- If the subclass Derived overrides foo(), then Derived::foo() is called
- If not, Base::foo() is called

#### Virtual & references int main() struct Base Derived d; virtual void f() Base b = d; b.f(); //B cout << "B" << endl;</pre> Base& bref= d; **}**; bref.f(); //D struct Derived: public Base Base\* bp = &d; bp->f(); //D void f() Base b1; cout << "D" << endl;</pre> // Derived d1 = b1; // won't compile

#### Base function that calls virtual function

```
struct Base {
  virtual void f() { cout<< "Base f()" <<endl; }</pre>
           void g() { f(); }
};
struct Derived : public Base {
  void f() { cout<< "Derived f()" <<endl; }</pre>
};
int main(){
  Derived d;
  d.g()
will print "Derived f()". Why??
```

#### Base function that calls virtual function

```
struct Base {
  virtual void f() { cout<< "Base f()" <<endl; }</pre>
          void g(Base* this) {this->f(); }
};
struct Derived : public Base {
  void f() { cout<< "Derived f()" <<endl; }</pre>
};
int main(){
  Derived d;
  Base::g(&d)
```

## Calling virtual function from a constructor

```
struct Base {
  Base() { f(); }
  virtual void f(){ cout<<"Base"<<endl;}</pre>
};
struct Derived: public Base {
  virtual void f(){ cout<<"Derived"<<endl;}</pre>
};
int main(){
  Derived d; // would print "Base"
```

Why? Because when Base() is called, Derived is not constructed yet! https://stackoverflow.com/q/962132/827927s

# Calling virtual function from a destructor

```
struct Base {
  ~Base() { f(); }
  virtual void f() { cout<<"Base"<<endl;}</pre>
};
struct Derived: public Base {
  virtual void f() { cout<<"Derived"<<endl;}</pre>
};
int main(){
  Derived d; // would print "Base"
```

already destructed! https://stackoverflow.com/q/962132/827927

Why? Because when ~Base() is called, Derived is

# Polymorphism rules:

When calling a method, polymorphism will take place if:

- We call a method through pointer or reference to a base class that actually points to a derived object.
- The method must be virtual in the base.
- We are not in ctor / dtor
- The derived class must override the base method with exactly the same signature (C++11 put override between () and { } to check that the method really overrides in compile time)

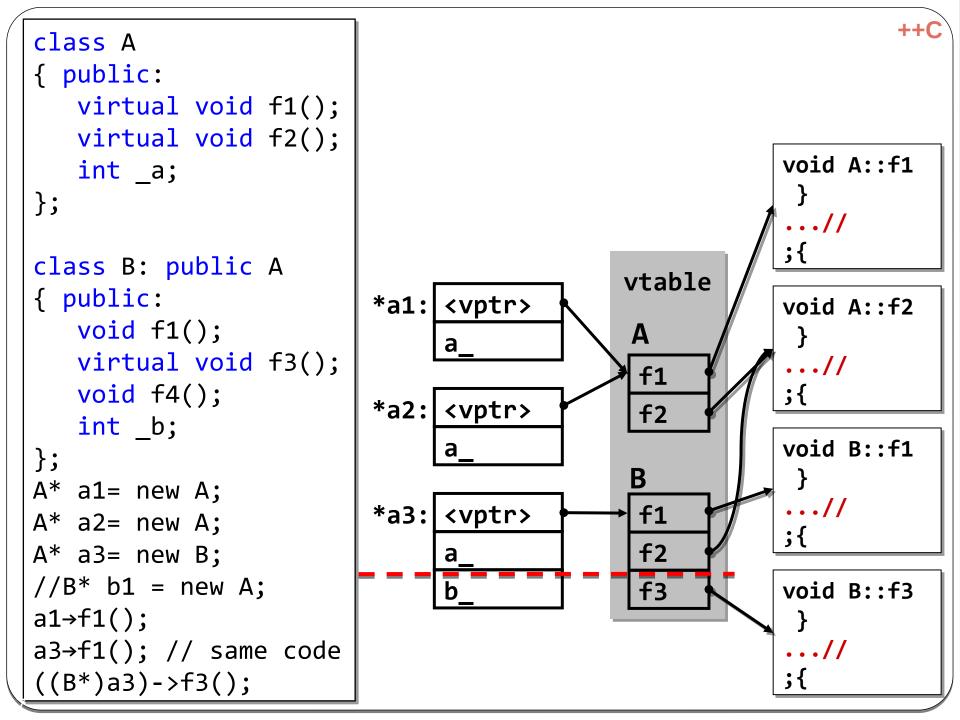
# Implementation of Virtual Methods

#### Solution:

- Each object has a single pointer to an array of function pointers.
- This array contains pointers to the appropriate functions.

#### Cost:

- For each class, we store one table.
- Each object contains one field that points to the right table.



#### Through \*a3 everything below the red dashed line will be hidden. virtual void f1(); virtual void f2(); void A::f1 int \_a; **}**; ;{ **VTBLs** class B: public A \*a1: | <vptr> void A::f2 { public: Α virtual void f1(); ...// f1 virtual void f3(); ;{ \*a2: < vptr> f2 void f4(); int b; void B::f1 **}**; ...// \*a3: | <vptr> f1 ;{ A\* a1= new A; f2 A\* a2= new A; **f**3 void B::f3 A\* a3= new B; a3→f3(); // comp.err.

a3→f4(); // comp.err.

...//



# Virtual Functions - demo

Either view folder 2

Or put the following code in https://godbolt.org/

```
class Base { public: int x, y;
  int f() { return 111; }
  virtual int g() { return 222; }
  virtual int h() { return 333;}
};
class Derived: public Base {
  int g() { return 444; }
};
int main() {
   Base* p = new Derived;
  p->f();
  p->g();
  p->h();
  delete p;
  return 0;
```



# Virtual functions in ctor/dtor - explained

- In the code of Base::Base, the vptr is set to Base::vtable, so the calls are to the Base functions.
- Only after Base::Base is finished,
   Derived::Derived is called and sets the vptr to Derived::vtable.
- The vptr is set in the destructors, too.

#### Virtual – cost

- Time: Calling a virtual method is more expensive than standard calls
  - Two pointers are "chased" to get to the address of the function
  - No inlining
- Memory: objects with virtual methods have an additional field (about 8 bytes).
- Conclusion: Declare a function "virtual" only if you need polymorphism.

#### Destructors & Inheritance

```
class Base
{ public:
   ~Base() { delete p1; }
};
class Derived : public Base
{ public:
   ~Derived() { delete p2; }
};
Base *p = new Derived;
delete p;
Question: what is the problem here?
```

#### Destructors & Inheritance

```
class Base
{ public:
   ~Base() { delete p1; }
};
class Derived : public Base
{ public:
   ~Derived() { delete p2; [~Base();] }
};
Base *p = new Derived;
delete p;
Answer: memory leak! Base::~Base is called.
```

#### Virtual Destructor

- Destructor is like any other method
- The example uses static resolution, and hence the wrong destructor is called
- To fix that, we need to declare virtual destructor at the base class!

#### Destructors & Inheritance

```
class Base
{ public:
   virtual ~Base() { delete p1; }
};
class Derived : public Base
{ public:
   ~Derived() { delete p2; [~Base();] }
};
Base *p = new Derived;
delete p;
Which destructor is called? Derived::~Derived()!
```

# Pure-virtual (abstract) methods & classes

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### Abstract classes

Revisiting our example, we write:

```
class Shape
public:
   virtual ~Shape();
   virtual void draw() const;
   virtual double area() const;
};
```

How do we implement Shape::draw()?

#### Inheritance & Interfaces

- In this example, we never want to deal with objects of type Shape
  - Shape serves the role of an interface
- All shapes need to be specific shapes instances of derived classes of Shape.
- How do we enforce this?

#### **Pure Virtual**

We can specify that Shape::draw() must be implemented in derived class

```
class Shape {
public: // pure virtuals:
    virtual void draw() const = 0;
    virtual double area() const = 0;
    virtual setName(string s) { name = s;}
    // dtor must have a body
     // (- it is called by derived dtor):
    virtual ~Shape() {}
```

### **Pure Virtual**

```
class Circle: public Shape {
public:
    void draw() const { ... }
    double area() const { ... }
};
```

## Pure Virtual

We cannot create objects of a Pure Virtual class – that is an object that contains at least one Pure Virtual method:

```
Shape* p; // legal
Shape s; // illegal
p = new Shape; // illegal
Circle c; // legal
p = &c; // legal
p = new Circle; // legal
```

#### Interfaces

 To create an equivalent to java interface – declare a base class with all methods pure virtual and no fields.

 Inheritance can be used to hide implementation. But, you will need a factory and a pimpl pattern.

# C++ pimpl

```
In List.hpp file:
class List {
public:
   virtual void Add()=0;
   virtual ~List(){};
   static List* make();
};
In main.cpp:
```

```
#include "List.hpp"
List* L = List::make();
L→Add();
```

```
In List.cpp file:
class ListImpl: public List {
   int* theInts;
   int numInts;
public:
   ListImpl(): theInts
     (new int[...]) {...}
   void Add() { ... }
};
List* List::make() {
   return new ListImpl;
```

# Virtual Methods - Tips

- 1. If you have virtual methods in a class, always declare its destructor virtual
- 2. Never call virtual methods during construction and destruction
- 3. Use pure virtual classes without any fields to define interfaces