

# Introduction to OpenFOAM meshing

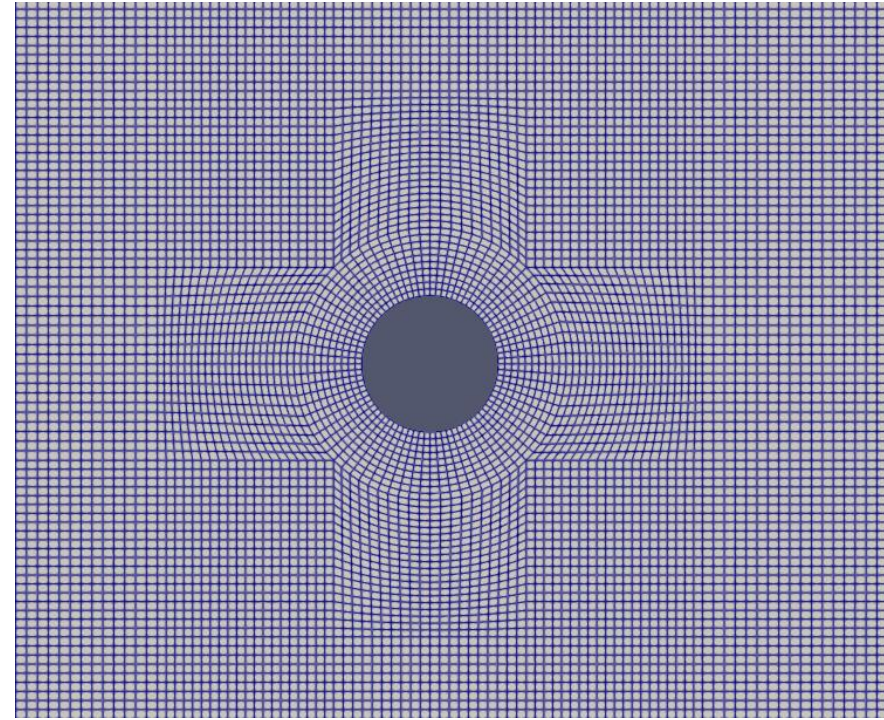
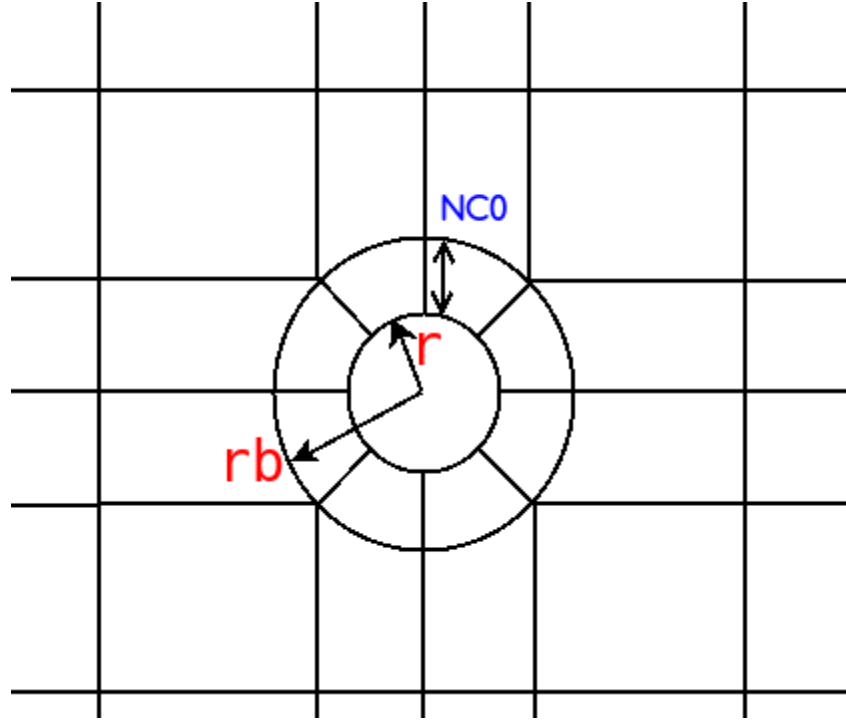
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- b1ockMesh – Block-structured hexahedral mesher.
- snappyHexMesh – Unstructured hexa-dominated mesher.
- cfMesh – Unstructured mesher with different available meshing strategies.

We will briefly look at the first two.

**NB:** you can also use your favourite commercial mesher!



By S. Rezaeiravesh

- Mesh fully defined in one dictionary: `blockMeshDict`. Lives in `system`.
- Manually define everything: vertices, blocks, curved edges, boundaries.
- Official guide:  
<https://www.openfoam.com/documentation/user-guide/4-mesh-generation-and-conversion/4.3-mesh-generation-with-the-blockmesh-utility>

# blockMeshDict



Global scaling of all  
Vertex locations

Vertices that will be use to  
define blocks.

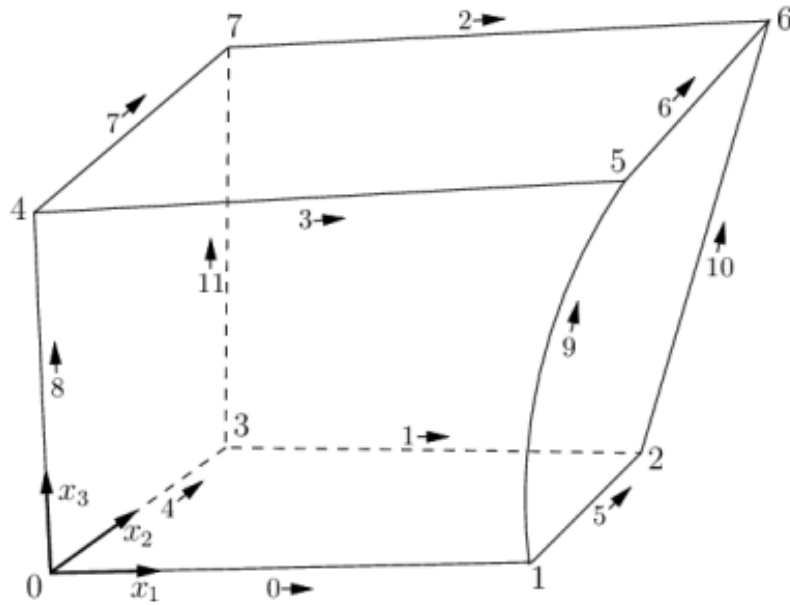
Numbering from 0.

```
16
17 scale 0.1;
18
19 vertices
20 (
21     (0 0 0)
22     (1 0 0)
23     (1 1 0)
24     (0 1 0)
25     (0 0 0.1)
26     (1 0 0.1)
27     (1 1 0.1)
28     (0 1 0.1)
29 );
30
31 blocks
32 (
33     hex (0 1 2 3 4 5 6 7) (20 20 1) simpleGrading (1 1 1)
34 );
35
36 edges
37 (
38 );
```

# blockMeshDict



## Vertex and edge order



From openfoam.com

## List of blocks

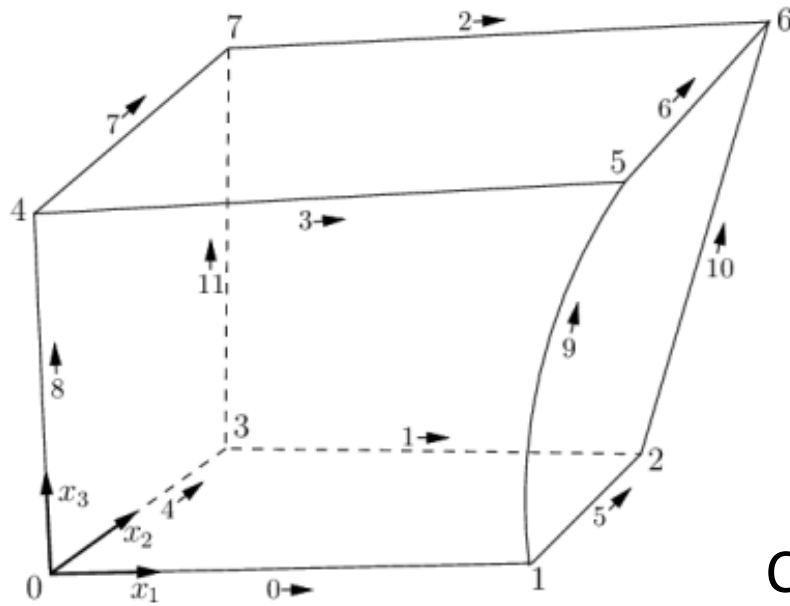
Vertex indices  
defining the block

```
16
17 scale 0.1;
18
19 vertices
20 (
21     (0 0 0)
22     (1 0 0)
23     (1 1 0)
24     (0 1 0)
25     (0 0 0.1)
26     (1 0 0.1)
27     (1 1 0.1)
28     (0 1 0.1)
29 );
30
31 blocks
32 (
33     hex (0 1 2 3 4 5 6 7) (20 20 1) simpleGrading (1 1 1)
34 );
35
36 edges
37 (
38 );
```

# blockMeshDict



## Vertex and edge order



From openfoam.com

Number of cells  
Along  $x_1, x_2, x_3$

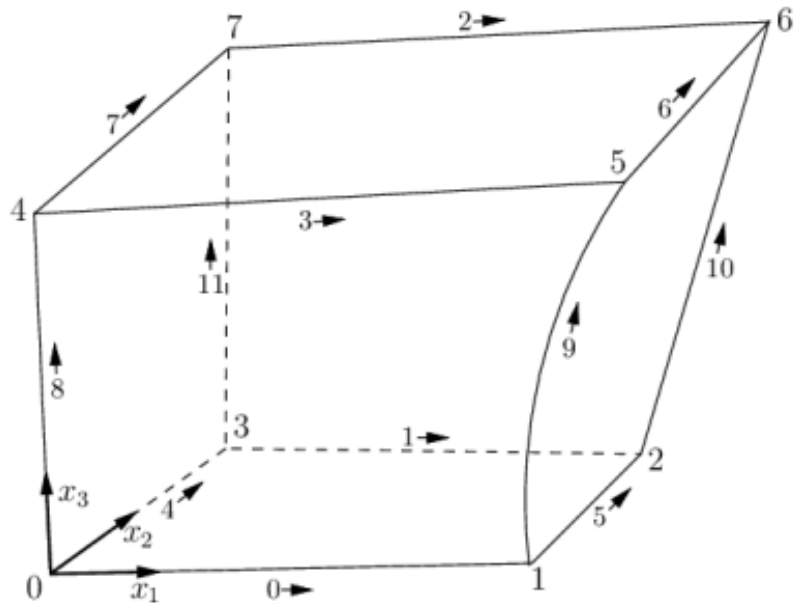
Cell size expansion  
ratio along  $x_1, x_2, x_3$

```
16
17 scale 0.1;
18
19 vertices
20 (
21     (0 0 0)
22     (1 0 0)
23     (1 1 0)
24     (0 1 0)
25     (0 0 0.1)
26     (1 0 0.1)
27     (1 1 0.1)
28     (0 1 0.1)
29 );
30
31 blocks
32 (
33     hex (0 1 2 3 4 5 6 7) (20 20 1) simpleGrading (1 1 1)
34 );
35
36 edges
37 (
38 );
```

# blockMeshDict



## Vertex and edge order



From openfoam.com

Non-linear edges

```
16
17 scale 0.1;
18
19 vertices
20 (
21     (0 0 0)
22     (1 0 0)
23     (1 1 0)
24     (0 1 0)
25     (0 0 0.1)
26     (1 0 0.1)
27     (1 1 0.1)
28     (0 1 0.1)
29 );
30
31 blocks
32 (
33     hex (0 1 2 3 4 5 6 7) (20 20 1) simpleGrading (1 1 1)
34 );
35
36 edges
37 (
38 );
```



# blockMeshDict



The physical boundaries of  
the case

Boundary type

List of faces, defined by vertex  
ids, forming the boundary

Get written to  
constant/polyMesh/boundary

```
40 boundary
41 (
42     movingWall
43     {
44         type wall;
45         faces
46         (
47             (3 7 6 2)
48         );
49     }
50     fixedWalls
51     {
52         type wall;
53         faces
54         (
55             (0 4 7 3)
56             (2 6 5 1)
57             (1 5 4 0)
58         );
59     }
60     frontAndBack
61     {
62         type empty;
63         faces
64         (
65             (0 3 2 1)
66             (4 5 6 7)
67         );
68     }
69 );
```

# Boundary types

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- “patch” – generic type used for most boundary boundaries.
- “wall” – for walls.
- “empty” – for a 2D case, defining the side boundaries parallel to the 2D plane in which the solution is obtained.
- “cyclic”, “cyclicAMI” – for periodic boundary conditions. Come in pairs.
- “symmetry” – symmetry boundary.

# Boundary types vs boundary conditions

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- Boundary conditions for fields are set in the 0 folder!
- But some boundary types essentially define the condition, e.g. cyclic.
- In this case, the conditions in the 0 folder must match the boundary type. E.g. cyclic boundary condition for the cyclic boundary type. Same with “empty”

# Boundary types vs boundary conditions



0/U

```
21 boundaryField
22 {
23     movingWall
24     {
25         type          fixedValue;
26         value          uniform (1 0 0);
27     }
28
29     fixedWalls
30     {
31         type          noSlip;
32     }
33
34     frontAndBack
35     {
36         type          empty;
37     }
38 }
```

blockMeshDict

```
40 boundary
41 (
42     movingWall
43     {
44         type wall;
45         faces
46         (
47             (3 7 6 2)
48         );
49     }
50     fixedWalls
51     {
52         type wall;
53         faces
54         (
55             (0 4 7 3)
56             (2 6 5 1)
57             (1 5 4 0)
58         );
59     }
60     frontAndBack
61     {
62         type empty;
63         faces
64         (
65             (0 3 2 1)
66             (4 5 6 7)
67         );
68     }
69 );
```

# Some stuff we skipped

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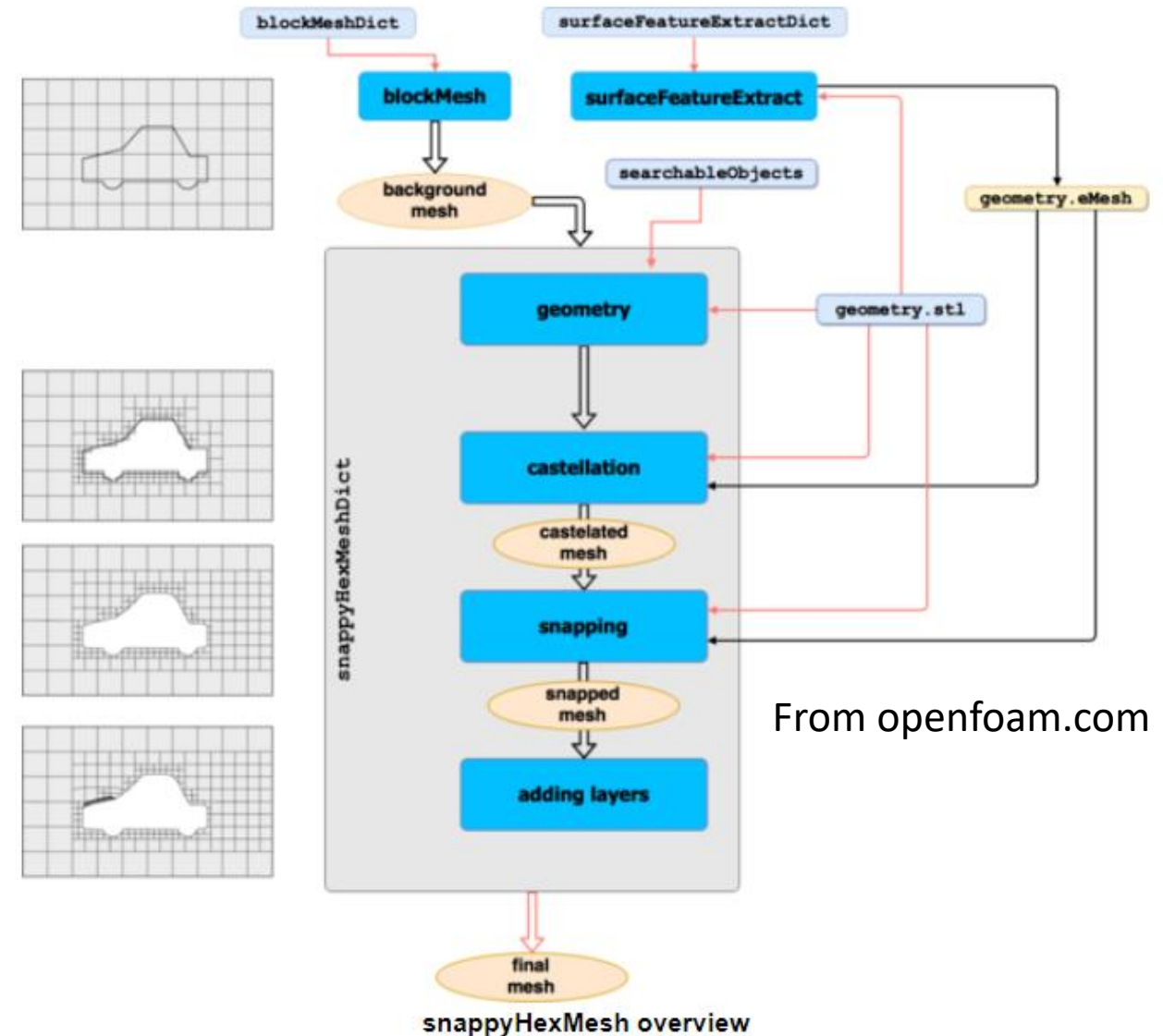


- Various curved edges.
- More complicated mesh grading.
- `mergePatchPairs` – block-unstructured hex meshes.
- Possibility to define variables and then use them in geometry definitions.

# snappyHexMesh



- For snappy we will only be able to give a rough overview.
- Creating the mesh is a 3-step process.
  1. Castellation
  2. Snapping
  3. Adding layers



- Put the stl of the geometry to constant/triSurface
- Create a blockMeshDict with one block of cubic cells. This will define the largest cell size.
- Create a surfaceFeatureExtractDict in system
- Run surfaceFeatureExtract
- Run blockMesh

```
17 flange.stl
18 {
19     // How to obtain raw features (extractFromFile || extractFromSurface)
20     extractionMethod    extractFromSurface;
21
22     // Mark edges whose adjacent surface normals are at an angle less
23     // than includedAngle as features
24     // - 0 : selects no edges
25     // - 180: selects all edges
26     includedAngle       150;
27
28     // Write options
29
30     // Write features to obj format for postprocessing
31     writeObj             yes;
32 }
```

- Lives in system
- Which of the 3 steps to run
- Define the geometry. Can add geometrical primitives for e.g. defining refinement regions.

```
18 // Which of the steps to run
19 castellatedMesh true;
20 snap          true;
21 addLayers     false;
```

```
30 geometry
31 {
32     flange.stl
33     {
34         type triSurfaceMesh;
35         name flange;
36     }
37
38     //- Refine a bit extra around the small centre hole
39     refineHole
40     {
41         type sphere;
42         origin (0 0 -0.012);
43         radius 0.003;
44     }
45 }
46
```



- A dictionary with MANY options for each step.
- We will now go through one example dictionary and highlight a few important ones.

```
49 castellatedMeshControls
50 {
51
52     // Refinement parameters
53     // ~~~~~
```

```
159 // Settings for the snapping.
160 snapControls
161 {
162     //- Number of patch smoothing iterations before finding correspondence
163     // to surface
164     nSmoothPatch 3;
165
```

```
197 // Settings for the layer addition.
198 addLayersControls
199 {
200     // Are the thickness parameters below relative to the undistorted
201     // size of the refined cell outside layer (true) or absolute sizes (false).
202     relativeSizes true;
203
204     // Per final patch (so not geometry!) the layer information
205     layers
206     {
207         "flange_.*"
208         {
209             nSurfaceLayers 3;
```

- Running snappyHexMesh will produce a separate directory for each step of the meshing process. The mesh in constant will be intact.
- Run snappyHexMesh `-overwrite` to write only the final mesh directly to constant.

# Conclusions

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- OpenFOAM has several meshing tools, suitable for both simple and complex geometries.
- It's possible to do a lot with snappy, including industrial flows.
- That being said, it seems to take a lot of parameter tweeking and one has to know the tool well.
- I have heard from many that cfMesh is less painful to work with. Try that as well.
- Generally, specialized commercial meshers are still quite a bit better in my opinion.