Week 5

Date: ....

Group : ....

Group members:

1. ....

2. ....

3. ....

4. ....

Observations sheet Run the robot for the following test points:

Test Point Inputs ($\theta 1, \dots \theta 6$)	Laser Position on Workbench (Measured) (x, y)
[0, -0.758, 0, 0.758, -1.571, 1.048]	
[-0.524, -1.048, 1.396, -0.175, -1.571, -0.524]	
[0.524, -1.222, 1.396, -0.175, -1.571, 0.175]	
[-0.524, -1.048, 1.048, -0.175, -1.571, -0.524]	