

Week 5

Date:

Group :

Group members:

1.
2.
3.
4.

Observations sheet Run the robot for the following test points:

Test Point Inputs ($\theta 1, \dots \theta 6$)	Laser Position on Workbench (Measured) (x, y)
[0, -45, 0, 45, -90, 60]	
[-30, -60, 80, -10, -90, -30]	
[30 -70 80 -10 -90 10]	
[-30, -60, 60, -10, -90, -30]	