
Adaptive Sampling for Low-Rank Matrix Approximation in the Matrix-Vector Product Model

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Abstract

We consider the problem of low-rank matrix approximation when the matrix \mathbf{A} is accessible only via matrix-vector products. The Randomized Singular Value Decomposition (rSVD) is an effective algorithm for obtaining the low rank representation of a matrix developed by Halko, Martinsson, and Tropp [20] by sampling standard Gaussian vectors. Recently, Boullé and Townsend [6] generalized the rSVD to sample Gaussian vectors with non-standard Covariance to leverage information on the right singular vectors of the target matrix, \mathbf{A} . We consider the open problem posed by Boullé and Townsend [4] of adaptive covariance matrix selection. We develop a novel adaptive sampling algorithm to update the covariance matrix in each round of sampling vectors by incorporating knowledge of the dominant right singular space of \mathbf{A} obtained from the intermediate low-rank approximations. Our novel algorithm learns a low-rank approximation with lower Frobenius norm errors than the generalized randomized SVD without prior knowledge on the dominant right singular space of the target matrix. On the way, we also derive improved error upper bounds for the generalized rSVD and rSVD.

1 Introduction

Obtaining the Low-Rank Matrix Approximation by sketching has been a problem of interest at the intersection of computational linear algebra and machine learning for the past two decades. In many real-world applications, it is often not possible to run experiments in parallel. Consider the following setting, there are a set of n inputs and m outputs, and there exists a PDE such it maps any set of inputs in $\mathbb{C}^m \rightarrow \mathbb{C}^n$. However, to run experiments, it takes hours for set up, execution, or it is expensive, e.g. aerodynamics [17], fluid dynamics [22]. Thus, after each experimental run, we want to sample a function such that in expectation, we will be exploring an area of the PDE which we have the least knowledge of. For Low-Rank Approximation the Randomized SVD, [20], has been theoretically analyzed and used in various applications. Even more recently, [3] discovered if we have prior information on the right singular vectors of \mathbf{A} , we can modify the Covariance Matrix such that the sampled vectors are within the column space of \mathbf{A} . They extended the theory for Randomized SVD where the covariance matrix is now a general PSD matrix. The basis of our analysis is the idea of sampling vectors in the Null-Space of the Low-Rank Approximation. This idea has been introduced recently in Machine Learning in [34] for training neural networks for sequential tasks. In a Bayesian sense, we want to maximize the expected information gain of the PDE in each iteration by sampling in the space where we have no information. This leads to the formulation of our iterative algorithm for sampling vectors for the Low-Rank Approximation. The current state of the art algorithms for low-rank matrix approximation in the matrix-vector product model used a fixed covariance matrix structure. In this paper, we consider the adaptive setting where the algorithm \mathcal{A}

chooses a vector $\omega^{(k)}$ with access to the previous query vectors $\omega^{(1)}, \dots, \omega^{(k-1)}$, the matrix-vector products $\mathbf{A}\omega^{(1)}, \dots, \mathbf{A}\omega^{(k-1)}$, and the intermediate low-rank matrix approximations, $\mathbf{Q}^{(k)}\mathbf{Q}^{(k)*}\mathbf{A}$, where $\mathbf{Q}^{(k)}\mathbf{R}^{(k)}$ is the economized QR decomposition of $\mathbf{A}\Omega^{(k)}$, where $\Omega^{(k)}$ is the concatenation of vectors $\omega^{(1)}, \dots, \omega^{(k)}$.

Adaptive Sampling techniques for Low-Rank Matrix Approximation first appeared in CUR Matrix Decomposition in [18]. Optimal column-sampling for the CUR Matrix Decomposition received much attention as can be seen in the works [21, 14, 15]. More recently, [27] gave an algorithm for sampling the rows for CUR-Matrix Factorization and proved it is possible to improve upon any relative-error Column Subset Selection Problem by adaptive sampling.

Adaptively sampling vectors for matrix problems has been studied in detail in [32]. The theoretical properties of adaptively sampled matrix vector queries for estimating the minimum eigenvalue of a Wishart matrix have been studied in [10]. Their bounds are used in [1] to develop adaptive bounds for their low-rank matrix approximation method using Krylov Subspaces. To our knowledge, we are the first paper to give an algorithm for low-rank approximation in the non-symmetric matrix low-rank approximation in the matrix-vector product model. Our algorithm utilizes the SVD computation of the low-rank approximation at each step to sample the next vector. Although there are runtime limitations, both in theory under certain conditions and many real-world matrices, our algorithm obtains a closer estimate to the optimal in the Frobenius Norm.

We will now clearly state our contributions.

Main Contributions.

1. We develop a novel adaptive sampling algorithm for Low-Rank Matrix Approximation problem in the matrix-vector product model which does not utilize prior information of \mathbf{A} .
2. We provide a novel theoretical analysis for adaptive sampling in the matrix-vector product query model.
3. We derive improved relative-error bounds for the Generalized Randomized SVD for both the spectral and Frobenius norms [6, Theorem 2] and show the spectral-norm bound is also an improvement for the rSVD [20, Theorem 10.8].
4. We perform Numerical Experiments on real-world and synthetic matrices that confirm our theoretical claims.

2 Background and related works

The Randomized SVD is a method to find an orthonormal matrix that captures the range of the top left singular space of \mathbf{A} by multiplying the matrix \mathbf{A} with a matrix with Standard Normal entries [23]. One first samples $k + p$ gaussian vectors $\mathbf{x}_i \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$ for $i \in [k + p]$ where k is the target rank and p is the oversampling parameter. One then calculates an orthonormal basis for the range by the economized QR decomposition and obtains $\mathbf{QR} = \mathbf{AX}$. It is then proved by Halko et al. [20] that \mathbf{Q} is a good approximation of the range of the top right singular space of \mathbf{A} and thus the approximation $\mathbf{QQ}^*\mathbf{A}$ is close to \mathbf{A} in both the spectral and Frobenius Norms. The analysis has been extended to SRTT matrices by Boutsidis and Gittens [9]. More recently, Boullé and Townsend studied the Randomized SVD when the columns of the Gaussian Matrix are sampled from a Correlated Gaussian Matrix. Their results indicate that there exist Covariance Matrices that are able to obtain better approximation bounds than the standard rSVD. Correlated Gaussian Sketching is studied for the Nyström approximation by Persson et al. [29]

3 Adaptive Sampling

The adaptive range finder algorithm was proposed in [20] as a method to guarantee a high accuracy guarantee for the low-rank approximation by sampling vectors one at a time until a stop condition is reached, which is not fixed as the sampled vectors are Gaussian, hence the algorithm is adaptive. It does not modify the distribution of the sampling vectors to reduce sample complexity or error. To clarify the distinction in the meaning of the term *adaptive*, we give a formal definition of the problem we study.

Definition 1. Given access to $r(k+p)$ right matrix-vector products. Sample ω_i for $i \in [r(k+p)]$ such that, after each matrix-vector query, one has access to the low-rank approximation $\mathbf{Q}_t \mathbf{Q}_t^* \mathbf{A}$ for $t \in [r]$. Obtain a matrix $\mathbf{Q} \in \mathbb{O}_{m,r(k+p)}$ using maximally $r(k+p)$ left and right matrix-vector product queries to \mathbf{A} to find \mathbf{Q} s.t.

$$\|\mathbf{A} - \mathbf{Q}\mathbf{Q}^* \mathbf{A}\|_F \leq (1 + \epsilon) \min_{\mathbf{U}: \mathbf{U}^* \mathbf{U} = \mathbf{I}} \|\mathbf{A} - \mathbf{U}\mathbf{U}^* \mathbf{A}\|_F \quad (1)$$

Our definition of *adaptive* is standard in the Theoretical Computer Science literature (see e.g. [27, 15]), in that we are using our previous samples to inform our future choices. We define *continued* sampling as sampling all vectors at once.

3.1 Algorithm

The Pseudo Code for the optimal function sampling is given in Algorithm 1. Algorithm 1 is developed with the goal of minimizing the number of matrix-vector products necessary to obtain the same accuracy as the randomized SVD or generalized randomized SVD. We follow the convention in [27] to perform adaptive sampling in rounds.

Algorithm 1 Adaptive sampling for low-rank matrix approximation

input: Target matrix $\mathbf{A} \in \mathbb{C}^{m \times n}$, samples per round ℓ , number of rounds r

output: Low-rank approximation $\hat{\mathbf{A}}$ of \mathbf{A} to minimize $\|\hat{\mathbf{A}} - \mathbf{A}\|_F$

- 1: $\hat{\mathbf{A}}^{(0)} \leftarrow \mathbf{0}$
- 2: **for** $t \in [r]$ **do**
- 3: Form $\mathbf{\Omega}^{(t)} \in \mathbb{C}^{n \times \ell}$ with columns sampled i.i.d from $\mathcal{N}(\mathbf{0}, \mathbf{C}^{(t)})$
- 4: $\mathbf{Y} \leftarrow [\mathbf{Y}, \mathbf{A}\mathbf{\Omega}^{(t)}] \in \mathbb{C}^{m \times t\ell}$ and obtain the economized QR decomposition $\mathbf{Y} = \mathbf{Q}\mathbf{R}$
- 5: Update the low-rank approximation: $\hat{\mathbf{A}}^{(t)} = \hat{\mathbf{A}}^{(t-1)} + \mathbf{Q}_{-}^{t\ell} \mathbf{Q}_{-}^{t\ell*} \mathbf{A}$
- 6: Calculate the economized SVD: $\hat{\mathbf{U}} \hat{\mathbf{\Sigma}} \hat{\mathbf{V}}^* = \hat{\mathbf{A}}^{(t)}$
- 7: Update the covariance matrix: $\mathbf{C}_t^{1/2} \leftarrow [\hat{\mathbf{V}}_{k(t-1), \ell t} \mathbf{0}]$

return: $\mathbf{Q}_t \mathbf{Q}_t^* \mathbf{A}$

Algorithm 1 runs in multiple rounds. In each round, we use the information we have learned from the matrix to update the covariance matrix.

Covariance Update in Algorithm 1. In each round, we update our covariance matrix to be the projection matrix of the singular space of the low-rank approximation. It can be calculated either from an SVD calculation or from a pseudoinverse, as we have from an expansion of the SVD,

$$\hat{\mathbf{V}}_{t(k+p)} \hat{\mathbf{V}}_{t(k+p)}^* = \hat{\mathbf{V}}^{(t)} \hat{\mathbf{\Sigma}}^{(t)+} \hat{\mathbf{U}}^{(t)*} \hat{\mathbf{U}}^{(t)} \hat{\mathbf{\Sigma}}^{(t)} \hat{\mathbf{V}}^{(t)*} = \hat{\mathbf{A}}^{(t)+} \hat{\mathbf{A}}^{(t)} \quad (2)$$

Therefore, one can call a pseudoinverse procedure of SVD procedure to update the covariance matrix. **Algorithm 1 runtime analysis.** In total we sample $k+p$ Gaussian vectors from t different Gaussian Distributions and therefore the matrix-matrix product $\mathbf{A}\mathbf{\Omega}$ scales in $O(tmn(k+p))$. We perform t QR factorizations which scale in $O(tmn(k+p))$. We then must perform the SVD decomposition on the low-rank approximation $\mathbf{Q}\mathbf{Q}^* \mathbf{A} \in \mathbb{C}^{m \times n}$ a total of t times which can be done on the order of $O(tmn^2)$ as well. Thus the total complexity can be observed as $O(tmn^2)$. The dominating runtime is the economized SVD calculation.

4 Theoretical Analysis

In this section we will first give the mathematical setup for the theoretical analysis. We next derive improvements to the Generalized Randomized SVD Approximation Relative Error Bounds. We utilize our improved approximation bounds to derive relative error bounds for adaptive sampling. The proofs of all results presented in this section are deferred to Appendix A.

4.1 Notation

For any integer t , We define $[t]$ as the set of integers $\{1, \dots, t\}$. Let $a \wedge b = \min(a, b)$ and $a \vee b = \max(a, b)$ for any two real numbers a, b . We define $\mathbb{O}_{n,k}$ as the set of all $n \times k$ matrices with

orthonormal columns, i.e. $\{\mathbf{V} : \mathbf{V}^* \mathbf{V} = \mathbf{I}_{k \times k}\}$. We define $\mathbb{S}^{d-1} = \{\mathbf{x} \in \mathbb{C}^d : \|\mathbf{x}\|_2 = 1\}$. We use Big-O notation, $y = O(x)$, to denote there exists a constant x_0 and a positive constant C such that $y \leq Cx$ for all $x \geq x_0$. We define $\mathbf{E}[X]$ as expectation of random variable X , $\Pr\{A\}$ as probability of event A occurring.

4.2 Linear Algebra

Definition 2. The Moore-Penrose Inverse [25, 28] of $\mathbf{X} \in \mathbb{R}^{m \times n}$ is denoted as $\mathbf{X}^+ \in \mathbb{R}^{n \times m}$. The matrix \mathbf{X}^+ satisfies the following four conditions,

$$\mathbf{X}\mathbf{X}^+\mathbf{X} = \mathbf{X}, \quad \mathbf{X}^+\mathbf{X}\mathbf{X}^+ = \mathbf{X}^+, \quad (\mathbf{X}\mathbf{X}^+)^* = \mathbf{X}\mathbf{X}^+, \quad (\mathbf{X}^+\mathbf{X})^* = \mathbf{X}^+\mathbf{X}$$

If \mathbf{X} has full row-rank, then the pseudo-inverse can be given explicitly as $\mathbf{X}^+ = (\mathbf{X}^* \mathbf{X})^{-1} \mathbf{X}^*$. For any matrix \mathbf{X} with singular value decomposition $\mathbf{X} = \mathbf{U} \mathbf{\Sigma} \mathbf{V}^*$, the pseudoinverse is given as $\mathbf{X}^+ = \mathbf{V} \mathbf{\Sigma}^{-1} \mathbf{U}^*$. An orthogonal projector matrix is a Hermitian Matrix and satisfies $\mathbf{P}^2 = \mathbf{P}$. This property of the orthogonal projector matrix implies $\mathbf{0} \preceq \mathbf{P} \preceq \mathbf{I}$. Suppose \mathbf{Q} represents an orthonormal basis of the column space of a matrix \mathbf{Y} , then $\mathbf{P}_\mathbf{Y} = \mathbf{Q} \mathbf{Q}^*$ represents the unique projection matrix on to the range of \mathbf{Y} . We follow a similar setup as previous literature. We factorize \mathbf{A} as follows,

$$\mathbf{A} = \begin{bmatrix} k & n-k \\ \mathbf{U}_k & \mathbf{U}_{k,\perp} \end{bmatrix} \begin{bmatrix} k & n-k \\ \mathbf{\Sigma}_k & \mathbf{\Sigma}_{k,\perp} \end{bmatrix} \begin{bmatrix} \mathbf{V}_k^* \\ \mathbf{V}_{k,\perp}^* \end{bmatrix} \begin{bmatrix} k \\ n-k \end{bmatrix} = \sum_{i=1}^n \sigma_i \mathbf{u}_i \mathbf{v}_i^*$$

The trace of a matrix is given as $\text{Tr}(\mathbf{A}) = \sum_{i \in [n]} \sigma_i(\mathbf{A})$. We furthermore define for $\xi \in \{2, F\}$,

$$\mathbf{A}_k = \min_{\mathbf{B}: \text{rank}(\mathbf{B})=k} \|\mathbf{A} - \mathbf{B}\|_\xi$$

The Eckart-Young-Mirsky Theorem [16, 24] tells us for the spectral and Frobenius norms this matrix is equivalent to the k dominant singular matrix of \mathbf{A} . Throughout the paper, we utilize the following norms,

$$\text{Spectral Norm: } \|\mathbf{A}\|_2^2 = \|\mathbf{A}^* \mathbf{A}\|_2 = \sigma_1^2(\mathbf{A}) \quad (3)$$

$$\text{Frobenius Norm: } \|\mathbf{A}\|_F^2 = \text{Tr}(\mathbf{A}^* \mathbf{A}) = \sum_{i=1}^n \sigma_i^2(\mathbf{A}) \quad (4)$$

Our theoretical arguments rely on the following proposition given by Halko et al. [20].

Proposition 3 (Conjugation Rule). Suppose that $\mathbf{M} \succeq \mathbf{0}$. Then for any conformal matrix \mathbf{A} ,

$$\mathbf{M} \preceq \mathbf{N} \implies \mathbf{A}^* \mathbf{M} \mathbf{A} \preceq \mathbf{A}^* \mathbf{N} \mathbf{A}$$

We also utilize a corollary of Weyl's Inequality, a classical result in Perturbation Theory.

Lemma 4 (Weyl's Inequality). Suppose \mathbf{A}, \mathbf{B} have real eigenvalues (e.g. they are Hermitian), then for any $i \in [n]$,

$$\lambda_i(\mathbf{A} + \mathbf{B}) \leq \lambda_i(\mathbf{A}) + \lambda_1(\mathbf{B})$$

4.3 Generalized Randomized SVD

In this subsection we present our result for the Frobenius norm approximation bounds for the Generalized Randomized SVD presented by Boullé and Townsend [6]. To our knowledge these are the first relative-error upper bounds for the spectral and Frobenius norms for the generalized rSVD. **NB:** We need to remove the dependence on the dimension here using [29, Lem. 2.2]. This gives you a tighter bound than Prop.. 19 that you can replace simply later on in the proof. To control the expectation term in the Lem. 2.2, you can use [29, Lem.A.2].

Theorem 5. Let $\mathbf{A} \in \mathbb{C}^{m \times n}$, set $k \geq 1$ an integer, an oversampling parameter $p \geq 4$. Let $\mathbf{\Omega} \in \mathbb{R}^{n \times k+p}$ represent the test matrix with columns sampled from $\mathcal{N}(\mathbf{0}, \mathbf{C}')$ for $\mathbf{C}' = [\mathbf{C} \quad \mathbf{0}]$. Then, let $\mathbf{Q} \mathbf{R} = \mathbf{A} \mathbf{\Omega}$ represent the economized QR decomposition of $\mathbf{A} \mathbf{\Omega}$, then with probability at least $1 - \delta - t^{-p}$,

$$\|\mathbf{A} - \mathbf{Q} \mathbf{Q}^* \mathbf{A}\|_F \leq \|\mathbf{\Sigma}_{k,\perp}\|_F \left(1 + \sqrt{6t \log((n-k)(k+p)/\delta)} \|\mathbf{K}_{22}\|_2^{1/2} \sqrt{\text{Tr}(\mathbf{K}_{11}^{-1})} \sqrt{\frac{1}{p+1}} \right)$$

$$\|\mathbf{A} - \mathbf{Q}\mathbf{Q}^*\mathbf{A}\|_2 \leq \|\Sigma_{k,\perp}\|_2 \left(1 + \sqrt{2t \log((n-k)(k+p)/\delta)} \|\mathbf{K}_{22}\|_2^{1/2} \|\mathbf{K}_{11}^{-1}\|_2^{1/2} \frac{e\sqrt{k+p}}{p+1} \right)$$

where

$$\mathbf{K} = \mathbf{V}^* \mathbf{C} \mathbf{V} = \begin{bmatrix} \mathbf{V}_k^* \mathbf{C} \mathbf{V}_k & \mathbf{V}_k^* \mathbf{C} \mathbf{V}_{k,\perp} \\ \mathbf{V}_{k,\perp}^* \mathbf{C} \mathbf{V}_k & \mathbf{V}_{k,\perp}^* \mathbf{C} \mathbf{V}_{k,\perp} \end{bmatrix} = \begin{bmatrix} \mathbf{K}_{11} & \mathbf{K}_{12} \\ \mathbf{K}_{21} & \mathbf{K}_{22} \end{bmatrix}$$

The proof of Theorem 5 can be derived with the deterministic error bound of Theorem 9.1 in [20] and combining Lemma 12 with both relations of Proposition 20. From Theorem 5, we infer that we obtain a better theoretical bound than the randomized SVD when \mathbf{C} has better alignment with the top right singular space of \mathbf{A} than the identity. As example, choosing $\mathbf{C} = \mathbf{V}_k \mathbf{V}_k^*$, we obtain $\mathbf{K}_{22} = \mathbf{0}$ and we then obtain the optimal $\|\Sigma_{k,\perp}\|_F^2$ Frobenius norm approximation error. The weakness in the bound when compared to the probabilistic bound in [20] is the $O(\log(n(k+p)))$ term that is a result of Proposition 20. Our bounds presented in Theorem 5 are the strongest relative spectral and Frobenius norm error approximations to the generalized Randomized SVD presented in the literature to our knowledge. The difference between our bounds and the bounds derived in Theorem 2.4 of [29] is that we lose the additive constant that has no inverse dependence on the oversampling parameter p , giving us the desired $(1 + \epsilon)$ approximation results for low-rank approximation by choosing a sufficiently large oversampling parameter, p . We formalize our relative error bound in the following corollary.

Corollary 6. *Let $\mathbf{A} \in \mathbb{C}^{m \times n}$, set $k \geq 1$ an integer, an oversampling parameter $p \geq 4$. Let $\Omega \in \mathbb{R}^{n \times (k+p)}$ represent the test matrix with columns sampled from $\mathcal{N}(\mathbf{0}, \mathbf{C})$. Then, let $\mathbf{Q}\mathbf{R} = \mathbf{A}\Omega$ represent the economized QR decomposition of $\mathbf{A}\Omega$. Then if*

$$p \geq (12/\epsilon) \log(n^2/\delta) \|\mathbf{K}_{22}\|_2 \text{Tr}(\mathbf{K}_{11}^{-1})$$

With probability exceeding $1 - \delta - 0.0625$,

$$\|\mathbf{A} - \mathbf{Q}\mathbf{Q}^*\mathbf{A}\|_F^2 \leq (1 + \epsilon) \|\mathbf{A} - \mathbf{A}_k\|_F^2$$

Corollary 6 develops a relative Frobenius norm error bound for the Generalized Randomized SVD and can be derived from elementary algebraic manipulations after an application of the first relation in Theorem 5. Since Remark 2.5 in [29] does not obtain a $(1 + \epsilon)$ relative error bound, there exists sufficiently large oversampling parameter p such that our bound gives a stronger error bound. Furthermore, our relative-error bound for the spectral norm is stronger than the relative-error spectral norm bound given by Halko et al. [20, Equation (1.9)]. We are able to reduce the $O(\sqrt{n-k})$ upper bound to $O(\sqrt{\log(n-k)})$. We formalize our improvement and give numerical illustrations in Appendix C.

4.4 General Adaptive Sampling Theoretical Analysis

In this section, we make theoretical connections from Adaptive sampling in the implicit matrix model to the more well studied problem of Adaptive sampling in the column subselection problem. Adaptive sampling in works such as [15] and [27] for the column subselection problem (see e.g. [12] § 1 for a problem definition) sample columns from the residual matrix, $\mathbf{A} - \mathbf{Q}_t \mathbf{Q}_t^* \mathbf{A}$, at each iteration t instead of directly from \mathbf{A} . Our first result is to formalize this statement and prove that indeed, adaptive low rank matrix approximation in the implicit matrix model performs low-rank matrix approximation at each round. We require the following Lemma, which gives us theoretical insight on where we can derive advantages with adaptive sampling.

Lemma 7. *Let $\Omega_+ = [\Omega, \Omega_-]$, $\mathbf{Y} = \mathbf{A}\Omega$, $\mathbf{Q} = \text{orth}(\mathbf{Y})$, and $\mathbf{Q}_+ = \text{orth}([\mathbf{Y}, \mathbf{A}\Omega_-])$. Finally, for shorthand, define $\mathbf{P}_\perp = \mathbf{I} - \mathbf{Q}\mathbf{Q}^*$, then for $\xi \in \{2, F\}$,*

$$\|\mathbf{A} - \mathbf{Q}_+ \mathbf{Q}_+^* \mathbf{A}\|_\xi = \|\mathbf{P}_\perp \mathbf{A} - \mathbf{Q}_- \mathbf{Q}_-^* \mathbf{P}_\perp \mathbf{A}\|_\xi \quad (5)$$

From Lemma 7, to minimize the RHS of Equation (5) we observe that \mathbf{Q}_- is equal to the dominant left singular space of $\mathbf{P}_\perp \mathbf{A}$. From this result, we then see that at each iteration, the optimal vector query is the top right singular vector of $\mathbf{P}_\perp \mathbf{A}$. Thus, if one has knowledge of the matrix $(\mathbf{I} - \mathbf{P}_{\mathbf{Y}_t})\mathbf{A}$ at any iteration, then performing a power iteration by sampling \mathbf{X} as a Gaussian matrix, then calculate

$$\mathbf{X}_q = (\mathbf{I} - \mathbf{P}_{\mathbf{Y}_t})((\mathbf{I} - \mathbf{P}_{\mathbf{Y}_t})^*(\mathbf{I} - \mathbf{P}_{\mathbf{Y}_t}))^q \mathbf{X}$$

Then, sample \mathbf{X}_q as the sampling vectors for the next round.

Theorem 8. Let $\mathbf{A} \in \mathbb{C}^{m \times n}$ and let $\mathbf{C} \in \mathbb{C}^{n \times n}$ be a PSD covariance matrix. Let the sampling matrix be decomposed as $\mathbf{\Omega} = [\mathbf{\Omega}_+, \mathbf{\Omega}_-]$, the matrix-matrix products $\mathbf{Y} = \mathbf{A}\mathbf{\Omega}$, $\mathbf{Y}_- = \mathbf{A}\mathbf{\Omega}_-$, then let \mathbf{Q}_+ be the orthonormal matrix from an economized QR decomposition of $[\mathbf{A}\mathbf{\Omega}_-, \mathbf{Y}]$. Let $p \geq 4$ be the oversampling parameter, then with probability exceeding $1 - \delta - t^{-p}$,

$$\|\mathbf{A} - \mathbf{Q}_+ \mathbf{Q}_+^* \mathbf{A}\|_{\text{F}}^2 \leq \epsilon(1 + \epsilon)\|\mathbf{A} - \mathbf{A}_k\|_{\text{F}}^2 + (1 + \epsilon)\|\mathbf{A} - \mathbf{A}_{2k}\|_{\text{F}}^2$$

From Theorem 8, we observe that our choice of covariance matrix reduces the number of matrix-vector products required to obtain the same accuracy as the Randomized SVD or even generalized randomized SVD.

Comparison to Continued Sampling. Consider the case where $t = 2$. In the continued sampling model, we sample all the $2k$ vectors initially. Continued sampling incurs Frobenius Norm Error

$$\|\mathbf{A} - \mathbf{Q}_+ \mathbf{Q}_+ \mathbf{A}\|_{\text{F}}^2 \leq \left(1 + \frac{\epsilon}{2}\right)\|\mathbf{A} - \mathbf{A}_k\|_{\text{F}}^2$$

Next, we consider the bound given in Theorem 8. From some simple algebraic manipulations, we obtain when

$$\|\mathbf{A} - \mathbf{A}_{2k}\|_{\text{F}}^2 \leq \left(\frac{1 - \epsilon/2 - \epsilon^2}{1 + \epsilon}\right)\|\mathbf{A} - \mathbf{A}_k\|_{\text{F}}^2 \leq (1 - \epsilon)\|\mathbf{A} - \mathbf{A}_k\|_{\text{F}}^2$$

The adaptive bound is stronger than the classical bound given sufficient singular decay when the goal is a $(1 + \epsilon)\|\mathbf{A} - \mathbf{A}_k\|_{\text{F}}^2$ approximation. Even stronger, is we can note there exists an ϵ for which the adaptive bound is always stronger than the classical bound,

$$\sum_{i=2k+1}^n \sigma_i^2 \leq (1 - \epsilon) \sum_{i=k+1}^n \sigma_i^2 \iff \epsilon \sum_{i=k+1}^n \sigma_i^2 \leq \sum_{i=k+1}^{2k} \sigma_i^2$$

Therefore, we see there exists a sufficiently small ϵ that gives a stronger $(1 + \epsilon)\|\mathbf{A} - \mathbf{A}_k\|_{\text{F}}$ approximation. We now consider the analysis for T steps.

Theorem 9. Let $\mathbf{A} \in \mathbb{C}^{m \times n}$ and let $\mathbf{C}_i \in \mathbb{C}^{n \times n}$ be PSD covariance matrices. The sampling matrix is given as $\mathbf{\Omega} = [\mathbf{C}_1 \mathbf{G}_1, \dots, \mathbf{C}_t \mathbf{G}_t]$. Let \mathbf{Q} be the orthonormal basis of $\mathbf{A}\mathbf{\Omega}$, then with probability exceeding $1 - T(\delta - t^{-p})$,

$$\|\mathbf{A} - \mathbf{Q}\mathbf{Q}^* \mathbf{A}\|_{\text{F}}^2 \leq \|\mathbf{A} - \mathbf{A}_{tk}\|_{\text{F}}^2 + \epsilon \sum_{i=1}^{T-1} (1 + \epsilon)^{T-i} \|\mathbf{A} - \mathbf{A}_{ik}\|_{\text{F}}^2$$

The theorem can be proved by induction, see Theorem 1 in [27]. Interestingly, without any algorithmic modifications to the randomized SVD, the fact that \mathbf{Q} is an orthonormal basis of $\mathbf{A}\mathbf{\Omega}$ gives us the same result as in [27] without explicit knowledge of the matrix $\mathbf{A} - \mathbf{Y}\mathbf{Y}^+ \mathbf{A}$.

4.5 Analysis of Algorithm 1

Our covariance update in Algorithm 1 of Algorithm 1 does not align with the theory we have developed in Section 4.4. Consider Lemma 7, it is optimal to sample in the dominant right singular subspace of $\mathbf{A} - \mathbf{P}_Y \mathbf{A}$. However, in the implicit matrix problem, we do not have access to $\mathbf{A} - \mathbf{P}_Y \mathbf{A}$. We first show for one round of our adaptive procedure in Algorithm 1, it is sufficient to sample in our estimation of the dominant right singular subspace of \mathbf{A} .

Theorem 10. Consider one round of Algorithm 1 with a covariance matrix $\mathbf{C} \in \mathbb{C}^{n \times n}$. Suppose $\mathbf{G}_1, \mathbf{G}_2 \in \mathbb{C}^{n \times (k+p)}$ are Gaussian Matrices. If $\hat{\mathbf{V}}_{k+p}^* \mathbf{G}_1$ and $\mathbf{V}_k^* \mathbf{C}^{1/2} \mathbf{G}_2$ have full-row rank, then for $\xi \in \{2, \text{F}\}$, with probability at least 0.95,

$$\|\mathbf{A} - \mathbf{Q}\mathbf{Q}^* \mathbf{A}\|_{\xi} \lesssim \left(1 + \sqrt{8 \log(10(k+p))} \|\mathbf{V}_{k,\perp}^* \mathbf{C}^{1/2}\|_2 \|(\mathbf{V}_k^* \mathbf{C}^{1/2})^+\|_2 \frac{e\sqrt{k+p}}{p+1}\right) \|\mathbf{A} - \mathbf{A}_{2k}\|_{\xi}$$

We can now note that $(1 + \epsilon)^2 = 1 + O(\epsilon)$. Then, from ideas in subspace perturbation theory (see e.g. [26]), the sample complexity to obtain a $(1 + \epsilon)\|\mathbf{A} - \mathbf{A}_{2k}\|_{\text{F}}$ is reduced. We will now extend Theorem 10 to multiple rounds.

Theorem 11. Consider t rounds of Algorithm 1 with covariance matrices $\mathbf{C}_i \in \mathbb{C}^{n \times n}$ for $i \in [t]$. Suppose $\Psi_i \in \mathbb{C}^{n \times (k+p)}$ for $i \in [t]$ are Gaussian Matrices. If $\widehat{\mathbf{V}}_{k+p}^* \mathbf{G}_1$ and $\mathbf{V}_k^* \mathbf{C}^{1/2} \mathbf{G}_2$ have full-row rank, then for $\xi \in \{2, F\}$, with probability at least 0.95,

$$\|\mathbf{A} - \mathbf{Q}\mathbf{Q}^* \mathbf{A}\|_\xi \lesssim \prod_{i=1}^t \left(1 + \sqrt{8 \log(10n)} \|\mathbf{V}_{\mathcal{I}_i, \perp}^* \mathbf{C}_i^{1/2}\|_2 \|(\mathbf{V}_{\mathcal{I}_t}^* \mathbf{C}_i^{1/2})^+\|_2 \frac{e\sqrt{k+p}}{p+1} \right) \|\mathbf{A} - \mathbf{A}_{tk}\|_\xi$$

Theorem 11 implies we can first sample $k + p$ standard Gaussian vectors. Then, at the i th iteration, we can sample vectors that align with $\mathbf{V}_{\mathcal{I}_i}$. When given the intermediate low-rank matrix approximations, from obtaining the SVD, we can then sample our approximation of $\mathbf{V}_{\mathcal{I}_i}$. We have nearly arrived at the covariance update given in Algorithm 1. We next note in practice minimizing $\|\mathbf{A} - \mathbf{Q}\mathbf{Q}^* \mathbf{A}\|_\xi$ is not equivalent to minimizing ϵ for $(1 + \epsilon)\|\mathbf{A} - \mathbf{A}_k\|_\xi$. Therefore, it is often the case even if we know the optimal covariance matrix $\mathbf{V}_k \mathbf{V}_k^*$ it might not be optimal since $\|\mathbf{A} - \mathbf{A}_k\|_\xi \geq \Omega(\|\mathbf{A} - \mathbf{A}_k\|_\xi)$.

4.6 Randomized Nyström Approximation

When the matrix $\mathbf{A} \in \mathbb{R}^{n \times n}$ is symmetric positive semi-definite (SPSD), the *randomized Nyström Approximation* is a stronger method for low-rank approximation when compared to the Randomized SVD [33]. The Nyström Approximation is given as,

$$\widehat{\mathbf{A}} = \mathbf{A}\mathbf{\Omega}(\mathbf{\Omega}^* \mathbf{A} \mathbf{\Omega})^+ \mathbf{\Omega}^* \mathbf{A} \approx \mathbf{A}$$

Adaptive Sampling for the Nyström Approximation is known to be difficult to study theoretically (see discussion in e.g. [19]). Recently, Persson et al. studied the Nyström Approximation in the Matrix-Vector Product Query Model with the columns of $\mathbf{\Omega}$ sampled from a Gaussian matrix with correlated covariance matrix [29]. It is known for $\xi \in \{2, F\}$ that

$$\|\mathbf{A} - \widehat{\mathbf{A}}\|_\xi \leq \|\Sigma_{k, \perp}\|_\xi + \|(\Sigma_{k, \perp}^{1/2} \mathbf{\Omega}_{k, \perp} \mathbf{\Omega}_k^+)^* \Sigma_{k, \perp}^{1/2} \mathbf{\Omega}_{k, \perp} \mathbf{\Omega}_k^+\|_\xi$$

From Equation (3), we can apply our relative spectral error bound in Theorem 5 to possibly give improvements to the relative spectral norm bound implied by Theorem 2.4 of [29].

5 Numerical experiments

In this section, we will test various Synthetic Matrices and Differential Operators in real-world applications with Algorithm 1 and compare against state-of-the-art non-adaptive algorithms for low-rank matrix approximation. All experiments are run in MATLAB R2022b on a 3.60 GHz processor and 16.0 GB RAM. All points in the plots for Fig. 1 are the average over 10 randomized runs. Each point represents one round of sampling. We define

$$\text{OPT} = \min_{\mathbf{Z} \in \mathbb{C}^{m \times t(k+p)}} \|\mathbf{A} - \mathbf{Z}\mathbf{Z}^* \mathbf{A}\|_F$$

From an application of the Eckart-Young-Mirsky Theorem for the Frobenius Norm [16, 24], we find that the minimizing $\mathbf{Z} = \mathbf{U}_{t(k+p)}$ and therefore,

$$\text{OPT} = \sqrt{\sum_{i=t(k+p)+1}^n \sigma_i^2(\mathbf{A})}$$

Experiment 1: Learning an Inverse Differential Operator. In our first experiment we attempt to learn the discretized $10^3 \times 10^3$ matrix of the inverse of the following differential operator:

$$\mathcal{L}u = \frac{\partial^2 u}{\partial x^2} - 100 \sin(5\pi x) u, \quad x \in [0, 1] \quad (6)$$

Learning the inverse operator of a PDE is equivalent to learning the Green's Function of a PDE. This has been theoretically proven for certain classes of PDEs (Linear Parabolic [5, 7]) as the inverse Differential operator is compact. Furthermore, there are multiple works suggesting the learning of inverse differential operators is provably efficient [3, 4].

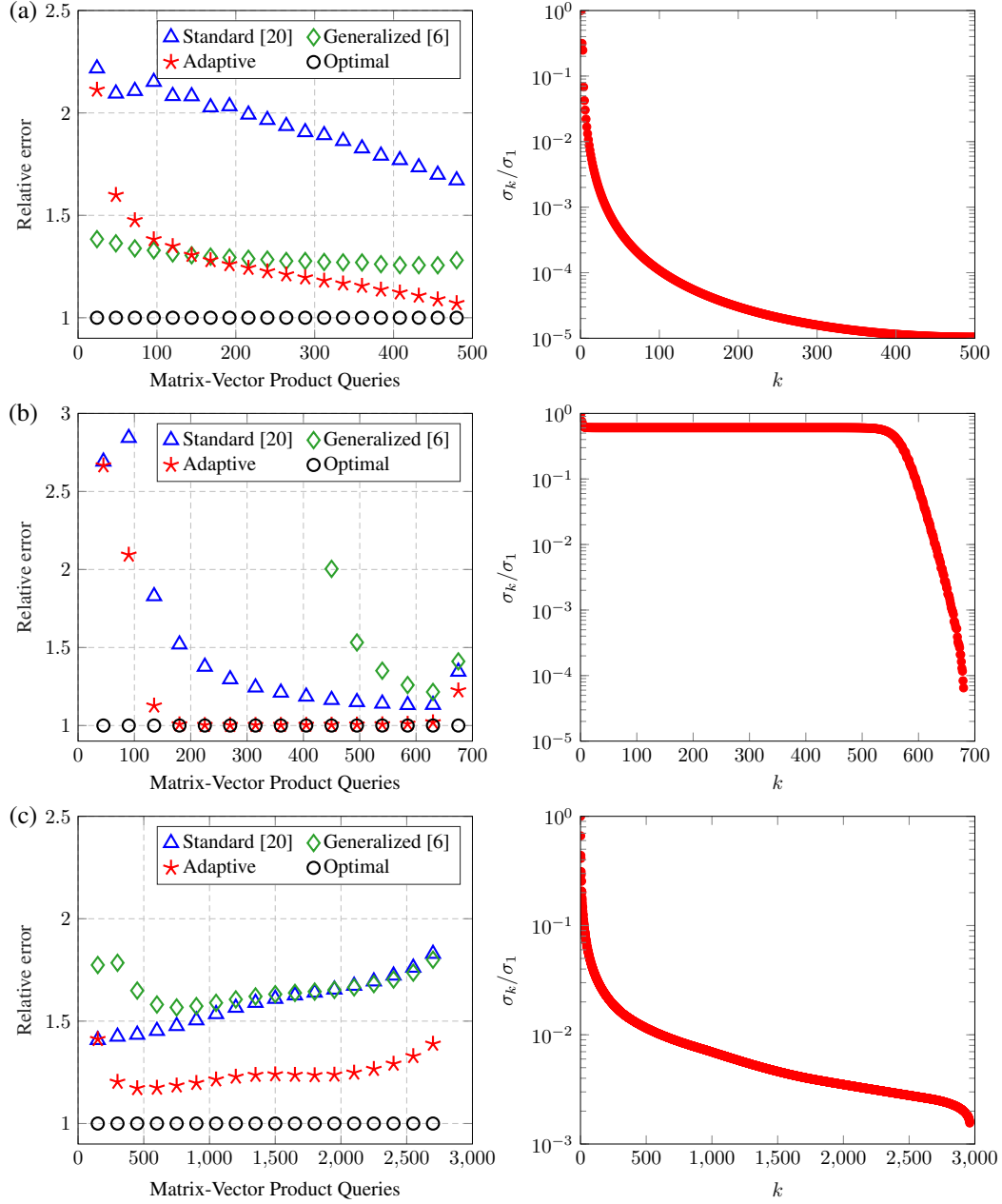


Figure 1: Left panels: Relative error (in the Frobenius norm) of the low-rank matrix approximation with respect to the number of matrix-vector products. Right panels: Singular value decay of the matrix. (a) Inverse of a discretized Laplacian differential operator (see Eq. (6) and [6, Fig. 2]), $k = 8, p = 16, t = 20$. (b) Matrix fs-680-1 from [13], $k = 8, p = 8, t = 20$. (c) Matrix pde2961 from [13], $k = 50, p = 100, t = 18$. **Need to compare against best $k + p$ -approximation, need to call batch size = $k + p$**

Experiment 2: Matrices with Polynomial and Exponential Singular Value Decay. We sample \mathbf{U} uniformly randomly from the Haar Measure over $\mathbb{O}_{m,m}$ and \mathbf{V} uniformly randomly from the Haar Measure over $\mathbb{O}_{n,n}$. We then form the matrices \mathbf{A} in the scheme described in Equation (7) and Equation (8), respectively.

$$\mathbf{A} = \sum_{i \in [n]} i^{-p} \cdot \mathbf{U}_{(:,i)} \mathbf{V}_{(:,i)}^*, \quad \mathbf{U} \in \mathbb{O}_{m,m}, \mathbf{V} \in \mathbb{O}_{n,n} \quad (7)$$

$$\mathbf{A} = \sum_{i \in [n]} (1 - \delta)^i \cdot \mathbf{U}_{(:,i)} \mathbf{V}_{(:,i)}^*, \quad \mathbf{U} \in \mathbb{O}_{m,m}, \mathbf{V} \in \mathbb{O}_{n,n} \quad (8)$$

Experiment 3: Learning an Inverse Differential Operator in the Real World. We attempt to learn the inverse of the discretized differential operator given in matrix `pde2961`, sourced from the TAMU Matrix Suite [13]. `pde2961` is the matrix associated with a Model Partial Differential Equations Problem.

Experiment 4: Learning a forward matrix in the Real World. We learn the a low rank matrix approximation of `fs-680-1`, also sourced from the TAMU Sparse Matrix Suite [13]. `fs-680-1` is the associated matrix for a chemical kinetics problem.

Observation 1: We observe in Fig. 1(a), even without prior knowledge of the dominant right singular space of \mathbf{A} , after approximately 150 matrix-vector products, adaptive sampling learns a better low-rank approximation with respect to the Frobenius norm.

Observation 2: In Fig. 1(b), we find that Algorithm 1 obtains nearly-optimal Frobenius norm error from 175 to 650 matrix-vector product queries.

Observation 3: Algorithm 1 performs well in large matrices after considering the results in Fig. 1(c). The `pde2961` matrix is of size 2961×2961 and Algorithm 1 outperforms rSVD and the generalized rSVD.

Observation 4: Algorithm 1 works well in a wide variety of singular value spectra. This can be concluded from observing that Fig. 1 display a diverse range of singular value spectra and cover both real and synthetic scenarios.

Our experiments on real-world matrices are promising and indicate that our algorithm and implementation can be used in real-world applications of learning low-rank approximations of matrices that are only accessible via matrix-vector products.

6 Conclusions

We have theoretically and empirically analyzed a novel Covariance Update to iteratively construct the sampling matrix, $\mathbf{\Omega}$ in the Randomized SVD algorithm. We introduce a new adaptive sampling framework for low-rank matrix approximation when the matrix is only accessible by matrix-vector products by giving the algorithm access to intermediate low-rank matrix approximations. Our covariance update for generating sampling vectors and functions can find use various PDE learning applications, [3, 11]. Numerical Experiments indicate without prior knowledge of the matrix, we are able to obtain superior performance to the Randomized SVD and generalized Randomized SVD with covariance matrix utilizing prior information of the PDE. Theoretically, we provide an analysis of our update extended to k -steps and show in expectation, under certain singular value decay conditions, we obtain better performance expectation.

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A Proofs

In this section we give proofs for results we deferred from the main text.

A.1 Distribution of $\mathbf{V}^*\Omega$

We devote this section to the matrix $\mathbf{V}^*\Omega$. We will derive various concentration inequalities which allow us to give the main theorems.

Lemma 12. *Let $\Omega = [\omega_1, \dots, \omega_\ell] \in \mathbb{C}^{n \times \ell}$ such that $\omega_i \sim \mathcal{N}(\mathbf{0}, \mathbf{C})$ for all $i \in [\ell]$ and $\mathbf{C} \succeq 0$ is symmetric. Then, let $\mathbf{V} \in \mathbb{O}_{n \times k}$, it then follows the columns of $\mathbf{V}^*\Omega$ are sampled from a centered multivariate Gaussian Distribution with second-moment matrix $\mathbf{K} = \mathbf{V}^*\mathbf{C}\mathbf{V}$.*

Proof. The matrix $\mathbf{V}^*\Omega$ can be decomposed as follows,

$$\mathbf{V}^*\Omega = \begin{bmatrix} \mathbf{v}_1^*\omega_1 & \cdots & \mathbf{v}_1^*\omega_\ell \\ \vdots & \ddots & \vdots \\ \mathbf{v}_k^*\omega_1 & \cdots & \mathbf{v}_k^*\omega_\ell \end{bmatrix}$$

Let $\mathcal{D} = \mathcal{N}(\mathbf{0}, \mathbf{I})$. We will first show that the entries of each column of $\mathbf{V}^*\Omega$ are Gaussian. From the fact that \mathbf{C} is symmetric, we have that $\mathbf{C} = \mathbf{U}\Sigma\mathbf{U}$ for a unitary \mathbf{U} and diagonal $\Sigma \succeq 0$. Then for any $i \in [k]$ and $j \in [\ell]$, we have for $\mathbf{x} \sim \mathcal{D}$,

$$\mathbf{v}_i^*\omega_j = \mathbf{v}_i^*\mathbf{C}^{1/2}\mathbf{x} = \mathbf{v}_i^*\mathbf{U}\Sigma^{1/2}\mathbf{x} = \sum_{k \in [n]} \mathbf{v}_i^*\mathbf{u}_k \sqrt{\lambda_k(\mathbf{C})} x_k$$

In the above, we have that each $[\mathbf{V}^*\Omega]_{i,j}$ is Gaussian for $(i, j) \in [k] \times [\ell]$ as a linear combination of Gaussians is Gaussian. We will calculate the mean and covariance. We first calculate the mean of a column of $\mathbf{V}^*\Omega$. For any $(i, j) \in [k] \times [\ell]$,

$$\begin{aligned} \mathbf{E}_{\omega_j \sim \mathcal{N}(\mathbf{0}, \mathbf{C})} [\mathbf{v}_i^*\omega_j] &= \mathbf{E}_{\mathbf{x} \sim \mathcal{D}} [\mathbf{v}_i^*\mathbf{C}^{1/2}\mathbf{x}] = \mathbf{v}_i^*\mathbf{C}^{1/2} \mathbf{E}_{\mathbf{x} \sim \mathcal{D}} [\mathbf{x}] \\ &= \sum_{p \in [n]} \mathbf{v}_i^*\mathbf{u}_p \sqrt{\lambda_p(\mathbf{C})} \mathbf{E}_{\mathbf{x} \sim \mathcal{D}} [x_p] = 0 \end{aligned}$$

Now we calculate the covariance matrix. Let $\mathbf{v} \in \mathbb{S}^{n-1}$, then for any $(i, i', j) \in [k] \times [k] \times [\ell]$, and $i \neq i'$, we have

$$\begin{aligned} \mathbf{E}_{\omega_j \sim \mathcal{N}(\mathbf{0}, \mathbf{C})} \left[(\mathbf{v}_i^*\omega_j - \mathbf{E}_{\omega_j \sim \mathcal{N}(\mathbf{0}, \mathbf{C})} [\mathbf{v}_i^*\omega_j]) (\mathbf{v}_{i'}^*\omega_j - \mathbf{E}_{\omega_j \sim \mathcal{N}(\mathbf{0}, \mathbf{C})} [\mathbf{v}_{i'}^*\omega_j]) \right] \\ = \mathbf{E}_{\omega_j \sim \mathcal{N}(\mathbf{0}, \mathbf{C})} [\mathbf{v}_i^*\omega_j \omega_j^* \mathbf{v}_{i'}] = \mathbf{v}_i^* \mathbf{C} \mathbf{v}_{i'} \end{aligned} \quad (9)$$

For the diagonal covariance elements, we have

$$\mathbf{E}_{\omega_j \sim \mathcal{N}(\mathbf{0}, \mathbf{C})} [(\mathbf{v}_i^*\omega_j - \mathbf{E}_{\omega_j \sim \mathcal{N}(\mathbf{0}, \mathbf{C})} [\mathbf{v}_i^*\omega_j])^2] = \mathbf{E}_{\omega_j \sim \mathcal{N}(\mathbf{0}, \mathbf{C})} [\mathbf{v}_i^*\omega_j \omega_j^* \mathbf{v}_i] = \mathbf{v}_i^* \mathbf{C} \mathbf{v}_i \quad (10)$$

Then combining Equations (9) and (10), we have

$$\mathbf{K} = \mathbf{V}^*\mathbf{C}\mathbf{V}$$

Our proof is complete. ■

A.2 Proof of Theorem 5

We now give an improvement to the deterministic error bound given in Theorem 9.1 of [20] by Boutsidis et al. [8].

Lemma 13 (Lemma 3.2 in [8]). *Let $\mathbf{A} \in \mathbb{R}^{m \times n}$, and let \mathbf{Q} be an orthonormal basis of $\mathbf{A}\Omega$ for $\Omega \in \mathbb{R}^{n \times (k+p)}$, then*

$$\|\mathbf{A} - \mathbf{Q}(\mathbf{Q}\mathbf{A})_k\|_{\text{F}}^2 \leq \|\mathbf{A} - \mathbf{A}_k\|_{\text{F}}^2 + \|\Sigma_{k,\perp} \mathbf{V}_{k,\perp} \Omega (\mathbf{V}_k \Omega)^+\|_{\text{F}}^2$$

Before we give our improvement to the Generalized Randomized SVD, we present the following necessary lemma on the concentration of $\|(\mathbf{V}_k^* \Omega)^+\|_{\text{F}}$ for Ω with columns sampled from $\mathcal{N}(\mathbf{0}, \mathbf{C})$.

Lemma 14 (Lemma 3 in [7]). *Suppose $\mathbf{V}_k \in \mathbb{O}^{n,k}$ and $\Omega \in \mathbb{C}^{n \times k+p}$ with columns sampled i.i.d from $\mathcal{N}(\mathbf{0}, \mathbf{K})$ and $p \geq 4$. Then with probability at least $1 - t^{-p}$,*

$$\|(\mathbf{V}_k^* \Omega)^+\|_{\text{F}} \leq \sqrt{\frac{3 \text{Tr}(\mathbf{K}^{-1})}{p+1}} \cdot t^2$$

For our improvement to the Generalized Randomized SVD for the spectral norm, we present the following necessary lemma.

Lemma 15 (Proposition 10.4 in [20]). *Let $\mathbf{G} \in \mathbb{R}^{k \times (k+p)}$ have elements sampled i.i.d from $\mathcal{N}(0, 1)$ for $p \geq 4$. Then for $t \geq 1$, with probability exceeding $1 - t^{-(p+1)}$,*

$$\|\mathbf{G}^+\|_2 \leq \frac{e\sqrt{k+p}}{p+1} \cdot t$$

We are now ready to prove our relative Spectral and Frobenius Error Norm Bounds for the Generalized Randomized SVD originally presented in [6].

Proof.[Proof of Theorem 5] Recall $\mathbf{A} = \mathbf{U}\Sigma\mathbf{V}^*$, $\Omega_k = \mathbf{V}_k^* \Omega$ and $\Omega_{k,\perp} = \mathbf{V}_{k,\perp}^* \Omega$ where the columns of $\Omega \in \mathbb{R}^{n \times (k+p)}$ are sampled from $\mathcal{N}(\mathbf{0}, \mathbf{C})$. Let

$$\mathbf{K} = \begin{bmatrix} \mathbf{V}_k^* \mathbf{C} \mathbf{V}_k & \mathbf{V}_k^* \mathbf{C} \mathbf{V}_{k,\perp} \\ \mathbf{V}_{k,\perp}^* \mathbf{C} \mathbf{V}_k & \mathbf{V}_{k,\perp}^* \mathbf{C} \mathbf{V}_{k,\perp} \end{bmatrix} = \begin{bmatrix} \mathbf{K}_{11} & \mathbf{K}_{12} \\ \mathbf{K}_{21} & \mathbf{K}_{22} \end{bmatrix}$$

We then have the following manipulations, from Lemma 13,

$$\begin{aligned} \|\mathbf{A} - \mathbf{Q}(\mathbf{Q}^* \mathbf{A})_k\|_{\text{F}} &\leq (\|\Sigma_{k,\perp}\|_{\text{F}}^2 + \|\Sigma_{k,\perp} \Omega_{k,\perp} \Omega_k^+\|_{\text{F}}^2)^{1/2} \\ &= \left(\|\Sigma_{k,\perp}\|_{\text{F}}^2 + \|\Sigma_{k,\perp} \mathbf{V}_{k,\perp}^* \mathbf{C}^{1/2} \mathbf{X} (\mathbf{V}_k^* \mathbf{C}^{1/2} \mathbf{X})^+\|_{\text{F}}^2 \right)^{1/2} \\ &= \left(\|\Sigma_{k,\perp}\|_{\text{F}}^2 + \|\Sigma_{k,\perp} \mathbf{V}_{k,\perp}^* \mathbf{K}_{22}^{1/2} \mathbf{X}_2 (\mathbf{K}_{11}^{1/2} \mathbf{X}_1)^+\|_{\text{F}}^2 \right)^{1/2} \\ &\leq \left(\|\Sigma_{k,\perp}\|_{\text{F}}^2 + 2 \log((n-k)(k+p)/\delta) \|\Sigma_{k,\perp} \mathbf{K}_{22}^{1/2}\|_{\text{F}}^2 \|(\mathbf{K}_{11}^{1/2} \mathbf{X}_1)^+\|_{\text{F}}^2 \right)^{1/2} \\ &\leq \|\Sigma_{k,\perp}\|_{\text{F}} \left(1 + t^2 \sqrt{6 \log((n-k)(k+p)/\delta)} \|\mathbf{K}_{22}\|_2^{1/2} \sqrt{\text{Tr}(\mathbf{K}_{11}^{-1})} \sqrt{\frac{1}{p+1}} \right)^{1/2} \end{aligned}$$

In the above, the first relation follows from the deterministic error bound in Lemma 13. The second relation follows from noting that the columns of Ω are sampled from $\mathcal{N}(\mathbf{0}, \mathbf{C})$, thus $\Omega = \mathbf{C}^{1/2} \mathbf{X}$ where $\mathbf{X} \in \mathbb{R}^{n \times (k+p)}$ is a standard Gaussian matrix. In the third relation, we apply Lemma 12 to note that $\mathbf{V}_{k,\perp}^* \mathbf{C}^{1/2} \mathbf{X} = \mathbf{K}_{22} \mathbf{X}_2$ and $\mathbf{V}_k^* \mathbf{C}^{1/2} \mathbf{X} = \mathbf{K}_{11} \mathbf{X}_1$ for standard Gaussian matrices $\mathbf{X}_1 \in \mathbb{R}^{k \times (k+p)}$ and $\mathbf{X}_2 \in \mathbb{R}^{(n-k) \times (k+p)}$. The fourth relation follows from Proposition 20 for the Frobenius norm with failure probability at most δ , and the final inequality follows from noting by the sub-multiplicativity of the Frobenius Norm, which gives us

$$\|\Sigma_{k,\perp} \mathbf{V}_{k,\perp}^* \mathbf{C}^{1/2}\|_{\text{F}}^2 \leq \|\Sigma_{k,\perp}\|_{\text{F}}^2 \|\mathbf{V}_{k,\perp}^* \mathbf{C}^{1/2}\|_2^2 = \|\Sigma_{k,\perp}\|_{\text{F}}^2 \|\mathbf{K}_{22}\|_2$$

and Lemma 14 which holds with failure probability at most t^{-p} . We then apply the elementary inequality $\sqrt{a+b} \leq \sqrt{a} + \sqrt{b}$ to complete our proof for the probabilistic bound for the Frobenius norm. We now can prove the spectral norm bound,

$$\|\mathbf{A} - \mathbf{Q}\mathbf{Q}^* \mathbf{A}\|_2 \leq (\|\Sigma_{k,\perp}\|_2^2 + \|\Sigma_{k,\perp} \Omega_{k,\perp} \Omega_k^+\|_2^2)^{1/2}$$

$$\begin{aligned}
&= \left(\|\Sigma_{k,\perp}\|_2^2 + \|\Sigma_{k,\perp} \mathbf{V}_{k,\perp}^* \mathbf{C}^{1/2} \mathbf{X} (\mathbf{V}_k^* \mathbf{C}^{1/2} \mathbf{X})^+ \|_2^2 \right)^{1/2} \\
&= \left(\|\Sigma_{k,\perp}\|_2^2 + \|\Sigma_{k,\perp} \mathbf{K}_{22}^{1/2} \mathbf{X}_2 (\mathbf{K}_{11}^{1/2} \mathbf{X}_1)^+ \|_2^2 \right)^{1/2} \\
&\leq \left(\|\Sigma_{k,\perp}\|_2^2 + 2 \log((n-k)(k+p)/\delta) \|\Sigma_{k,\perp} \mathbf{K}_{22}^{1/2}\|_2^2 \|(\mathbf{K}_{11}^{1/2} \mathbf{X}_1)^+ \|_2^2 \right)^{1/2} \\
&\leq \|\Sigma_{k,\perp}\|_2 \left(1 + \sqrt{2t \log((n-k)(k+p)/\delta)} \|\mathbf{K}_{22}\|_2^{1/2} \|\mathbf{K}_{11}^{-1}\|_2^{1/2} \frac{e\sqrt{k+p}}{p+1} \right)
\end{aligned}$$

The first inequality follows from the deterministic error bound in Theorem 9.1 of [20]. The second relation follows from noting $\Omega = \mathbf{C}^{1/2} \mathbf{X}$ where \mathbf{X} is a Gaussian matrix. The third relation follows from Lemma 12 which gives Gaussian matrices $\mathbf{X}_1 \in \mathbb{R}^{k \times (k+p)}$ and $\mathbf{X}_2 \in \mathbb{R}^{(n-k) \times (k+p)}$. The final relation follows from noting by Cauchy-Schwarz,

$$\|\Sigma_{k,\perp} \mathbf{V}_{k,\perp}^* \mathbf{C}^{1/2}\|_2^2 \leq \|\Sigma_{k,\perp}\|_2^2 \|\mathbf{V}_{k,\perp}^* \mathbf{C}^{1/2}\|_2^2 = \|\Sigma_{k,\perp}\|_2^2 \|\mathbf{K}_{22}\|_2$$

Furthermore, from noting that for any rank- k matrix $\|\mathbf{B}^+\|_2 = \sigma_k^{-1}(\mathbf{B})$, we have

$$\|(\mathbf{V}_k^* \mathbf{C}^{1/2} \mathbf{X})^+ \|_2^2 = \sigma_k^{-2}(\mathbf{V}_k^* \mathbf{C}^{1/2} \mathbf{X}_1) \leq \lambda_k^{-1}(\mathbf{K}_{11}) \sigma_k^{-2}(\mathbf{X}_1) = \|\mathbf{K}_{11}^{-1}\|_2 \|\mathbf{X}_1^+\|_2^2$$

Then, applying the bound in Lemma 15 with failure probability at most t^{-p+1} completes the proof. \blacksquare

A.3 Proof of Lemma 7

Proof. Recall that \mathbf{Q}_{12} is an orthonormal basis of $[\mathbf{A}\Omega_1, \mathbf{A}\Omega_2]$. Let \mathbf{Q}_1 be an orthonormal basis of $\mathbf{A}\Omega_1$, it thus follows that \mathbf{Q}_{12} is also an orthonormal basis of $[\mathbf{A}\Omega_1, (\mathbf{I} - \mathbf{Q}_1 \mathbf{Q}_1^*) \mathbf{A}\Omega_2]$. This can be seen from the Classical Gram-Schmidt Procedure [31]. Thus, we have

$$\mathbf{Q}_{12} \mathbf{Q}_{12}^* = \mathbf{Q}_1 \mathbf{Q}_1^* + \mathbf{Q}_{2|1} \mathbf{Q}_{2|1}^*$$

Then, expanding out the residual matrix, we have

$$\mathbf{A} - \mathbf{Q}_{12} \mathbf{Q}_{12}^* \mathbf{A} = \mathbf{A} - \mathbf{Q}_1 \mathbf{Q}_1^* \mathbf{A} - \mathbf{Q}_{2|1} \mathbf{Q}_{2|1}^* \mathbf{A}$$

Then from noting, $\mathbf{Q}_1^* \mathbf{Q}_{2|1} = \mathbf{0}$, we have

$$\mathbf{A} - \mathbf{Q}_1 \mathbf{Q}_1^* \mathbf{A} - \mathbf{Q}_{2|1} \mathbf{Q}_{2|1}^* \mathbf{A} = (\mathbf{A} - \mathbf{Q}_1 \mathbf{Q}_1^* \mathbf{A}) - \mathbf{Q}_{2|1} \mathbf{Q}_{2|1}^* (\mathbf{A} - \mathbf{Q}_1 \mathbf{Q}_1^* \mathbf{A})$$

Our proof is complete. \blacksquare

We now require the following linear algebraic lemma.

Lemma 16. Let $\mathbf{A} \in \mathbb{C}^{m \times n}$ and $\mathbf{B} \in \mathbb{C}^{m \times n}$ and $\mathbf{Q} \in \mathbb{O}_{m,\ell}$ for $\ell > k$. Then for any $i \in [n]$,

$$\sigma_i^2(\mathbf{A} - \mathbf{Q} \mathbf{Q}^* \mathbf{A}) \leq \sigma_i^2(\mathbf{A} - \mathbf{Q}(\mathbf{Q}^* \mathbf{A})_k)$$

Proof. We can note that $\sigma_i(\mathbf{Q} \mathbf{Q}^* \mathbf{A}) \leq \sigma_i(\mathbf{A})$ for all $i \in [n]$ by noting $\mathbf{Q} \mathbf{Q}^* \preceq \mathbf{I}$ as $\mathbf{Q} \in \mathbb{O}_{m,k}$. We first note that for any matrix $\mathbf{B} \in \mathbb{C}^{m \times n}$, the singular values and eigenvalues are related by $\sigma_i^2(\mathbf{B}) = \lambda_i(\mathbf{B}^* \mathbf{B})$ for any $i \in [n]$. Then let us consider any $i \in [n]$.

$$\lambda_i((\mathbf{A} - \mathbf{Q} \mathbf{Q}^* \mathbf{A})^* (\mathbf{A} - \mathbf{Q} \mathbf{Q}^* \mathbf{A})) = \lambda_i(\mathbf{A}^* \mathbf{A} - \mathbf{A}^* \mathbf{Q} \mathbf{Q}^* \mathbf{A})$$

Let us now consider the matrix in the RHS of the Lemma statement,

$$\begin{aligned}
&\lambda_i((\mathbf{A} - \mathbf{Q}(\mathbf{Q}^* \mathbf{A})_k)^* (\mathbf{A} - \mathbf{Q}(\mathbf{Q}^* \mathbf{A})_k)) \\
&= \lambda_i(\mathbf{A}^* \mathbf{A} - \mathbf{A}^* \mathbf{Q}(\mathbf{Q}^* \mathbf{A})_k - (\mathbf{Q}^* \mathbf{A})_k^* \mathbf{Q}^* \mathbf{A} + (\mathbf{Q}^* \mathbf{A})_k^* \mathbf{Q}^* \mathbf{Q}(\mathbf{Q}^* \mathbf{A})_k) \\
&= \lambda_i(\mathbf{A}^* \mathbf{A} - (\mathbf{A}^* \mathbf{Q} \mathbf{Q}^* \mathbf{A})_k - (\mathbf{A}^* \mathbf{Q} \mathbf{Q}^* \mathbf{A})_k + (\mathbf{A}^* \mathbf{Q} \mathbf{Q}^* \mathbf{A})_k) \\
&= \lambda_i(\mathbf{A}^* \mathbf{A} - (\mathbf{A}^* \mathbf{Q} \mathbf{Q}^* \mathbf{A})_k)
\end{aligned} \tag{11}$$

In the above, the final relation follows noting $\mathbf{Q}^* \mathbf{Q} = \mathbf{I}$ because $\mathbf{Q} \in \mathbb{O}_{m,\ell}$, and for any matrix \mathbf{B} , we have that $\mathbf{B}_k^* \mathbf{B} = (\mathbf{B}^* \mathbf{B})_k$ by an expansion of the SVD. We can now conclude our Lemma,

$$\sigma_i^2(\mathbf{A} - \mathbf{Q} \mathbf{Q}^* \mathbf{A}) = \lambda_i(\mathbf{A}^* \mathbf{A} - \mathbf{A}^* \mathbf{Q} \mathbf{Q}^* \mathbf{A})$$

$$\begin{aligned}
&= \lambda_i(\mathbf{A}^* \mathbf{A} - (\mathbf{A}^* \mathbf{Q} \mathbf{Q}^* \mathbf{A})_k - (\mathbf{A}^* \mathbf{Q} \mathbf{Q}^* \mathbf{A})_{k,\perp}) \\
&\leq \lambda_i(\mathbf{A}^* \mathbf{A} - (\mathbf{A}^* \mathbf{Q} \mathbf{Q}^* \mathbf{A})_k) \quad \text{Lemma 4} \\
&= \sigma_i^2(\mathbf{A} - \mathbf{A}(\mathbf{Q}^* \mathbf{A})_k) \quad \text{Equation (11)}
\end{aligned}$$

In the above, the third relation follows from noting $(\mathbf{A}^* \mathbf{Q} \mathbf{Q}^* \mathbf{A})_{k,\perp} \succeq \mathbf{0}$. Our proof is complete. ■
We are now ready to prove our general adaptive sampling error bound for one round.

A.4 Proof of Theorem 8

Proof. From Lemma 7, we obtain

$$\|\mathbf{A} - \mathbf{Q}_{t+1} \mathbf{Q}_{t+1}^* \mathbf{A}\|_F = \|(\mathbf{I} - \mathbf{Q}_t \mathbf{Q}_t^*) \mathbf{A} - \tilde{\mathbf{Q}}_{t+1} \tilde{\mathbf{Q}}_{t+1}^* (\mathbf{I} - \mathbf{Q}_t \mathbf{Q}_t^*) \mathbf{A}\|_F$$

The above equation follows from the same argument as Lemma 7. Then from our relative-error accuracy bound in Corollary 6, we have

$$\|(\mathbf{I} - \mathbf{Q}_- \mathbf{Q}_-^*) \mathbf{A} - \mathbf{Q} \mathbf{Q}^* (\mathbf{I} - \mathbf{Q}_- \mathbf{Q}_-^*) \mathbf{A}\|_F^2 \leq (1 + \epsilon) \|(\mathbf{A} - \mathbf{Q}_- \mathbf{Q}_-^* \mathbf{A})_{k,\perp}\|_F^2$$

We then have from Lemma 16,

$$\begin{aligned}
\|(\mathbf{A} - \mathbf{Q}_- \mathbf{Q}_-^* \mathbf{A})_{k,\perp}\|_F^2 &= \sum_{i \in [n] \setminus [k]} \sigma_i^2(\mathbf{A} - \mathbf{Q}_- \mathbf{Q}_-^* \mathbf{A}) \quad \text{Equation (4)} \\
&\leq \sum_{i \in [n] \setminus [k]} \sigma_i^2(\mathbf{A} - \mathbf{Q}_- (\mathbf{Q}_-^* \mathbf{A})_k) \quad \text{Lemma 16} \\
&= \|(\mathbf{A} - \mathbf{Q}_- (\mathbf{Q}_-^* \mathbf{A})_k)_{k,\perp}\|_F^2 \quad \text{Equation (4)}
\end{aligned}$$

Then, from expanding out the Frobenius Norm, we have

$$\|(\mathbf{A} - \mathbf{Q}_- (\mathbf{Q}_-^* \mathbf{A})_k)_{k,\perp}\|_F^2 = \|\mathbf{A} - \mathbf{Q}_- (\mathbf{Q}_-^* \mathbf{A})_k\|_F^2 - \sum_{i \in [k]} \sigma_i^2(\mathbf{A} - \mathbf{Q}_- (\mathbf{Q}_-^* \mathbf{A})_k)$$

We now leverage the Eckart-Young-Mirsky Theorem [16, 24], and obtain

$$\sum_{i \in [k]} \sigma_i^2(\mathbf{A} - \mathbf{Q}_- (\mathbf{Q}_-^* \mathbf{A})_k) \geq \inf_{\substack{\mathbf{B} \in \mathbb{C}^{m \times n} \\ \text{rank}(\mathbf{B})=k}} \sum_{i \in [k]} \sigma_i^2(\mathbf{A} - \mathbf{B}) = \|\mathbf{A}_k - \mathbf{A}_{2k}\|_F^2 \quad (12)$$

Then, from our improved Generalized Randomized SVD error bound in Theorem 5, we have with probability at least $0.99 - t^{-p}$,

$$\|\mathbf{A} - \mathbf{Q}_- (\mathbf{Q}_-^* \mathbf{A})_k\|_F^2 \leq \|\mathbf{A} - \mathbf{A}_k\|_F^2 \left(1 + 6t^2 \log(100n\ell) \|\mathbf{V}_{k,\perp}^* \mathbf{C}^{1/2}\|_2^2 \frac{\text{Tr}((\mathbf{V}_k^* \mathbf{C} \mathbf{V}_k)^{-1})}{p+1} \right) \quad (13)$$

Then, from choosing our oversampling parameter sufficiently large in accordance to Corollary 6,

$$p \geq (6t^2/\epsilon) \|\mathbf{V}_{k,\perp}^* \mathbf{C}^{1/2}\|_2^2 \text{Tr}((\mathbf{V}_k^* \mathbf{C} \mathbf{V}_k)^{-1})$$

We can then combine our results in Equations (12) and (13) to obtain

$$\begin{aligned}
\|\mathbf{A} - \mathbf{Q}_+ \mathbf{Q}_+^* \mathbf{A}\|_F^2 &\leq (1 + \epsilon)^2 \|\mathbf{A} - \mathbf{A}_k\|_F^2 - (1 + \epsilon) \|\mathbf{A}_k - \mathbf{A}_{2k}\|_F^2 \\
&= \epsilon(1 + \epsilon) \|\mathbf{A} - \mathbf{A}_k\|_F^2 + (1 + \epsilon) \|\mathbf{A} - \mathbf{A}_{2k}\|_F^2
\end{aligned}$$

Our proof is complete. ■

A.5 Proof of Theorem 10

We first give necessary lemmata for our proof.

Lemma 17 (Lemma 5.3 in [9]). *Let $\mathbf{A} \in \mathbb{R}^{m \times n}$ and $\mathbf{Y} \in \mathbb{R}^{m \times \ell}$, then for all $\mathbf{X} \in \mathbb{R}^{\ell \times n}$ and $\xi \in \{2, F\}$*

$$\|\mathbf{A} - \mathbf{Y} \mathbf{Y}^+ \mathbf{A}\|_\xi \leq \|\mathbf{A} - \mathbf{Y} \mathbf{X}\|_\xi$$

Lemma 18 (Matrix Pythagoras). *Let \mathbf{X}, \mathbf{Y} be conformal matrices, then if $\mathbf{X}^* \mathbf{Y} = \mathbf{0}$ or $\mathbf{Y}^* \mathbf{X} = \mathbf{0}$, then*

$$\|\mathbf{X} + \mathbf{Y}\|_2^2 \leq \|\mathbf{X}\|_2^2 + \|\mathbf{Y}\|_2^2 \quad \text{and} \quad \|\mathbf{X} + \mathbf{Y}\|_F^2 = \|\mathbf{X}\|_F^2 + \|\mathbf{Y}\|_F^2$$

Proof. The proof for the Spectral norm follows directly from Equation (3).

$$\|\mathbf{X} + \mathbf{Y}\|_2^2 = \|\mathbf{X}^* \mathbf{X} + \mathbf{X}^* \mathbf{Y} + \mathbf{Y}^* \mathbf{X} + \mathbf{Y}^* \mathbf{Y}\|_2 = \|\mathbf{X}^* \mathbf{X} + \mathbf{Y}^* \mathbf{Y}\|_2 \leq \|\mathbf{X}\|_2^2 + \|\mathbf{Y}\|_2^2$$

In the above, the final relation follows from the sub-additivity of the spectral norm. The proof for the Frobenius norm follows directly from Equation (4).

$$\|\mathbf{X} + \mathbf{Y}\|_F^2 = \text{Tr}(\mathbf{X}^* \mathbf{X} + \mathbf{X}^* \mathbf{Y} + \mathbf{Y}^* \mathbf{X} + \mathbf{Y}^* \mathbf{Y}) = \text{Tr}(\mathbf{X}^* \mathbf{X}) + \text{Tr}(\mathbf{Y}^* \mathbf{Y}) = \|\mathbf{X}\|_F^2 + \|\mathbf{Y}\|_F^2$$

In the above, we use the fact that $\text{Tr}(\mathbf{A} + \mathbf{B}) = \text{Tr}(\mathbf{A}) + \text{Tr}(\mathbf{B})$ for conformal matrices, \mathbf{A}, \mathbf{B} . ■

Proof.[Proof of Theorem 10] Our argument relies on an equivalence for the range of \mathbf{Q} . Since we have that \mathbf{Q} is an orthonormal basis of $[\mathbf{Y}_1 \quad \mathbf{Y}_2]$. Then we have that \mathbf{Q} is also the unique orthonormal basis of $[\mathbf{Y}_1 \mathbf{Y}_1^+ \mathbf{Y}_1 \quad (\mathbf{I} - \mathbf{Y}_1 \mathbf{Y}_1^+) \mathbf{Y}_2]$ by the definition of the Moore-Penrose Inverse (see the first property of Definition 2) and the classical Gram-Schmidt orthonormalization procedure [31]. Let $\mathbf{X} \in \mathbb{R}^{2\ell \times n}$, then we have from Lemma 17,

$$\begin{aligned} \|\mathbf{A} - \mathbf{Y} \mathbf{Y}^+ \mathbf{A}\|_\xi^2 &\leq \left\| \mathbf{A} - [\mathbf{P}_{\mathbf{Y}_1} \mathbf{A} \Psi_1 \quad (\mathbf{I} - \mathbf{P}_{\mathbf{Y}_1}) \mathbf{A} \mathbf{C}^{1/2} \Psi_2] \begin{bmatrix} \mathbf{X}_1 \\ \mathbf{X}_2 \end{bmatrix} \right\|_\xi^2 \\ &\leq \underbrace{\|\mathbf{P}_{\mathbf{Y}_1} \mathbf{A} - \mathbf{P}_{\mathbf{Y}_1} \mathbf{A} \Psi_1 \mathbf{X}_1\|_\xi^2}_I + \underbrace{\|(\mathbf{A} - \mathbf{P}_{\mathbf{Y}_1} \mathbf{A}) - (\mathbf{A} - \mathbf{P}_{\mathbf{Y}_1} \mathbf{A}) \mathbf{C}^{1/2} \Psi_2 \mathbf{X}_2\|_\xi^2}_{II} \end{aligned}$$

In the above, the second relation follows from Matrix Pythagoras (see Lemma 18). Let the SVD of $\mathbf{P}_{\mathbf{Y}_1} \mathbf{A}$ be $\hat{\mathbf{U}} \hat{\Sigma} \hat{\mathbf{V}}^*$, we then choose $\mathbf{X}_1 = (\hat{\mathbf{V}}_{k+p}^* \Psi_1)^+ \hat{\mathbf{V}}_{k+p}^*$, then we have $\hat{\mathbf{V}}_{k+p}^* \Psi_1 (\hat{\mathbf{V}}_{k+p}^* \Psi_1)^+ \hat{\mathbf{V}}_{k+p}^* = \hat{\mathbf{V}}_{k+p}^*$ from our assumption that $\hat{\mathbf{V}}_{k+p}^* \Psi_1$ is full-rank. Then we can note that $\hat{\mathbf{V}}_{k+p}^* \Psi_1$ is invertible almost surely with probability 1. We then obtain,

$$I = \|\mathbf{P}_{\mathbf{Y}_1} \mathbf{A} - \mathbf{P}_{\mathbf{Y}_1} \mathbf{A} \Psi_1 \mathbf{X}_1\|_\xi^2 = \|\mathbf{P}_{\mathbf{Y}_1} \mathbf{A} - \mathbf{P}_{\mathbf{Y}_1} \mathbf{A}\|_\xi^2 = 0$$

We then have for the second term,

$$\begin{aligned} II &= \|(\mathbf{A} - \mathbf{P}_{\mathbf{Y}_1} \mathbf{A}) - (\mathbf{A} - \mathbf{P}_{\mathbf{Y}_1} \mathbf{A}) \mathbf{C}^{1/2} \Psi_2 \mathbf{X}_2\|_\xi^2 \\ &= \|(\mathbf{A} - \mathbf{A} \mathbf{C}^{1/2} \Psi_2 \mathbf{X}_2) - (\mathbf{P}_{\mathbf{Y}_1} \mathbf{A} - \mathbf{P}_{\mathbf{Y}_1} \mathbf{A} \mathbf{C}^{1/2} \Psi_2 \mathbf{X}_2)\|_\xi^2 \end{aligned}$$

Then, setting $\mathbf{X}_2 = (\mathbf{V}_k^* \mathbf{C}^{1/2} \Psi_2)^+ \mathbf{V}_k^*$, we obtain

$$\begin{aligned} \sqrt{II} &\leq \|\mathbf{A}_{k,\perp} - \mathbf{P}_{\mathbf{Y}_1} \mathbf{A}_{k,\perp}\|_\xi + \|(\mathbf{A}_{k,\perp} - \mathbf{P}_{\mathbf{Y}_1} \mathbf{A}_{k,\perp}) \mathbf{C}^{1/2} \Psi_2 (\mathbf{V}_k^* \mathbf{C}^{1/2} \Psi_2)^+\|_\xi \\ &\leq \|\mathbf{A}_{k,\perp} - \mathbf{P}_{\mathbf{A}_{k,\perp} \Psi_1} \mathbf{A}_{k,\perp}\|_\xi + \|(\mathbf{A}_{k,\perp} - \mathbf{P}_{\mathbf{A}_{k,\perp} \Psi_1} \mathbf{A}_{k,\perp}) \mathbf{C}^{1/2} \Psi_2 (\mathbf{V}_k^* \mathbf{C}^{1/2} \Psi_2)^+\|_\xi \\ &\leq \|\mathbf{A}_{k,\perp} - \mathbf{P}_{\mathbf{A}_{k,\perp} \Psi_1} \mathbf{A}_{k,\perp}\|_\xi \left(1 + \|\mathbf{V}_{k,\perp}^* \mathbf{C}^{1/2} \Psi_2 (\mathbf{V}_k^* \mathbf{C}^{1/2} \Psi_2)^+\|_2\right) \\ &\leq (1 + \epsilon) \|\mathbf{A} - \mathbf{A}_{2k}\|_\xi \left(1 + \sqrt{4 \log(10n(k+p))} \|\mathbf{V}_{k,\perp}^* \mathbf{C}^{1/2}\|_2 \|(\mathbf{V}_k^* \mathbf{C}^{1/2})^+\|_2 \frac{e\sqrt{k+p}}{p+1}\right) \end{aligned}$$

In the above, the second inequality follows from the Conjugation Rule (see Proposition 3) with $\mathbf{P}_{\mathbf{A}_{k,\perp} \Psi_1} \preceq \mathbf{P}_{\mathbf{A} \Psi_1}$. Suppose for two conformal matrices, $\mathbf{Z}_1, \mathbf{Z}_2$ such that $\text{range}(\mathbf{Z}_1) \subset \text{range}(\mathbf{Z}_2)$, it then follows that $\mathbf{P}_{\mathbf{Z}_1} \preceq \mathbf{P}_{\mathbf{Z}_2}$, and we have for the Frobenius norm,

$$\begin{aligned} \|(\mathbf{I} - \mathbf{P}_{\mathbf{Z}_2}) \mathbf{A}\|_F^2 &= \sum_{i \in [n]} \|(\mathbf{I} - \mathbf{P}_{\mathbf{Z}_2}) \mathbf{A} \mathbf{e}_i\|_2^2 = \sum_{i \in [n]} \mathbf{e}_i^* \mathbf{A}^* (\mathbf{I} - \mathbf{P}_{\mathbf{Z}_2}) \mathbf{A} \mathbf{e}_i \\ &\leq \sum_{i \in [n]} \mathbf{e}_i^* \mathbf{A}^* (\mathbf{I} - \mathbf{P}_{\mathbf{Z}_1}) \mathbf{A} \mathbf{e}_i = \|(\mathbf{I} - \mathbf{P}_{\mathbf{Z}_1}) \mathbf{A}\|_F^2 \end{aligned}$$

In the above, the first and final relations follow from an alternative definition of the Frobenius Norm, the second relation follows from Equation (3), and the third relation follows from the Conjugation Rule. Then, noting that $\text{range}(\mathbf{A}_{k,\perp} \Psi_1) \subset \text{range}(\mathbf{A} \Psi_1)$, we obtain the desired result. A similar result for the spectral norm follows from a simpler argument. The final inequality follows from the

standard rSVD Frobenius norm error bound (see e.g. Theorem 10.6 in [20]) for $k + p$ samples on the matrix $\mathbf{A} - \mathbf{A}_k$, we thus obtain

$$\|\mathbf{A}_{k,\perp} - \mathbf{P}_{\mathbf{A}_{k,\perp}\Psi_1}\mathbf{A}_{k,\perp}\|_\xi \leq (1 + \epsilon)\|\mathbf{A} - \mathbf{A}_{2k}\|_\xi$$

and the second term follows from the manipulations in the Spectral Norm bound proof given in Theorem 5 with failure probability less than $\delta + t^{-p+1} \leq 0.01 + 0.0325 \leq 0.05$. ■

Theorem 19. Consider Algorithm 1 for t steps, then

$$\|\mathbf{A} - \mathbf{Q}\mathbf{Q}^*\mathbf{A}\|_\mathbb{F} \lesssim \prod_{i=1}^t \left(1 + \sqrt{8 \log(n(n - ki))} \|\mathbf{V}_{\mathcal{I},\perp}^* \mathbf{C}_i^{1/2}\|_2 \|(\mathbf{V}_{\mathcal{I},i}^* \mathbf{C}_i^{1/2})^+\|_2\right) \|\mathbf{A} - \mathbf{A}_{tk}\|_\xi$$

Proof. Proof follows similarly to the above theorem. Let $\tilde{\boldsymbol{\Omega}} = [\boldsymbol{\Omega} \quad \boldsymbol{\Omega}_t]$ be all the sampled vectors. We furthermore decompose $\boldsymbol{\Omega} = [\boldsymbol{\Omega}_1 \quad \cdots \quad \boldsymbol{\Omega}_{t-1}]$. Note $\boldsymbol{\Omega}_i \in \mathbb{R}^{n \times (k+p)}$ for all $i \in [t]$. Let $\mathbf{Y} = \mathbf{A}\boldsymbol{\Omega}$ and $\mathbf{Y}_i = \mathbf{A}\boldsymbol{\Omega}_i$ for $i \in [t]$.

$$\begin{aligned} \|\mathbf{A} - \mathbf{Q}\mathbf{Q}^*\mathbf{A}\|_\mathbb{F}^2 &\leq \left\| \mathbf{A} - [\mathbf{P}_\mathbf{Y}\mathbf{A}\boldsymbol{\Omega} \quad (\mathbf{I} - \mathbf{P}_\mathbf{Y})\mathbf{A}\boldsymbol{\Omega}_t] \begin{bmatrix} \mathbf{X} \\ \mathbf{X}_t \end{bmatrix} \right\|_\xi^2 \\ &= \sum_{i=1}^{t-1} \|\mathbf{P}_{\mathbf{Y}_i}\mathbf{A} - \mathbf{P}_{\mathbf{Y}_i}\mathbf{A}\mathbf{C}_i^{1/2}\Psi_i\mathbf{X}_i\|_\xi^2 + \underbrace{\|(\mathbf{A} - \mathbf{P}_\mathbf{Y}\mathbf{A}) - (\mathbf{A} - \mathbf{P}_\mathbf{Y}\mathbf{A})\mathbf{C}_t^{1/2}\Psi_t\mathbf{X}_t\|_\xi^2}_{II} \end{aligned}$$

We can then note that by choosing $\mathbf{C}_i^{1/2} = (\mathbf{P}_{\mathbf{Y}_i}\mathbf{A})^+(\mathbf{P}_{\mathbf{Y}_i}\mathbf{A})$, we have that $\mathbf{P}_{\mathbf{Y}_i}\mathbf{A}\mathbf{C}_i^{1/2} = \mathbf{P}_{\mathbf{Y}_i}\mathbf{A}$ and then choosing $\mathbf{X}_i = (\hat{\mathbf{V}}_{k+p}^* \Psi)^+ \hat{\mathbf{V}}_{k+p}^*$, with probability almost surely unitary, we obtain

$$\sum_{i=1}^{t-1} \|\mathbf{P}_{\mathbf{Y}_i}\mathbf{A} - \mathbf{P}_{\mathbf{Y}_i}\mathbf{A}\mathbf{C}_i^{1/2}\Psi_i\mathbf{X}_i\|_\xi^2 = \sum_{i=1}^{t-1} \|\mathbf{P}_{\mathbf{Y}_i}\mathbf{A} - \mathbf{P}_{\mathbf{Y}_i}\mathbf{A}\|_\xi^2 = 0$$

Then, considering the second term, we have

$$\begin{aligned} II &= \|(\mathbf{A} - \mathbf{P}_\mathbf{Y}\mathbf{A}) - (\mathbf{A} - \mathbf{P}_\mathbf{Y}\mathbf{A})\mathbf{C}_t^{1/2}\Psi_t\mathbf{X}_t\|_\xi^2 \\ &= \|(\mathbf{A} - \mathbf{A}\mathbf{C}_t^{1/2}\Psi_t\mathbf{X}_t) - (\mathbf{P}_\mathbf{Y}\mathbf{A} - \mathbf{P}_\mathbf{Y}\mathbf{A}\mathbf{C}_t^{1/2}\Psi_t\mathbf{X}_t)\|_\xi^2 \end{aligned}$$

Let $\mathcal{I} = \{kt, \dots, k(t+1)\}$. We now set $\mathbf{X}_t = (\mathbf{V}_{\mathcal{I}}^* \mathbf{C}_t^{1/2} \Psi_t)^+ \mathbf{V}_{\mathcal{I}}^*$. We then obtain,

$$\begin{aligned} \sqrt{II} &\leq \|\mathbf{A}_{\mathcal{I}} - \mathbf{P}_\mathbf{Y}\mathbf{A}_{\mathcal{I}}\|_\xi \left(1 + \|\mathbf{V}_{\mathcal{I},\perp}^* \mathbf{C}_t^{1/2} \Psi_t (\mathbf{V}_{\mathcal{I}}^* \mathbf{C}_t^{1/2} \Psi_t)^+\|_2\right) \\ &\leq \|\mathbf{A}_{\mathcal{I},\perp} - \mathbf{P}_{\mathbf{A}_{\mathcal{I},\perp}\boldsymbol{\Omega}}\mathbf{A}_{\mathcal{I},\perp}\|_\xi \left(1 + \sqrt{8 \log(n/\delta)} \|\mathbf{V}_{\mathcal{I},\perp}^* \mathbf{C}_t^{1/2}\|_2 \|(\mathbf{V}_{\mathcal{I}}^* \mathbf{C}_t^{1/2})^+\|_2 \frac{e\sqrt{k+p}}{p+1}\right) \end{aligned}$$

In the above, we observe when \mathbf{C}_t is a good approximation of $\mathbf{V}_{\mathcal{I}}$ we obtain an improvement. Let us now consider the term $\|\mathbf{A}_{\mathcal{I}} - \mathbf{P}_{\mathbf{A}_{\mathcal{I}}\boldsymbol{\Omega}}\mathbf{A}_{\mathcal{I}}\|_\xi$.

$$\begin{aligned} \|\mathbf{A}_{\mathcal{I}} - \mathbf{P}_{\mathbf{A}_{\mathcal{I}}\boldsymbol{\Omega}}\mathbf{A}_{\mathcal{I}}\|_\xi^2 &\leq \left\| \mathbf{A}_{\mathcal{I}} - [\mathbf{P}_{\mathbf{A}_{\mathcal{I}}\boldsymbol{\Omega}}\mathbf{A}_{\mathcal{I}}\boldsymbol{\Omega} \quad (\mathbf{I} - \mathbf{P}_{\mathbf{A}_{\mathcal{I}}\boldsymbol{\Omega}})\mathbf{A}_{\mathcal{I}}\boldsymbol{\Omega}_{t-1}] \begin{bmatrix} \mathbf{X} \\ \mathbf{X}_{t-1} \end{bmatrix} \right\|_\xi^2 \\ &\leq \underbrace{\|\mathbf{P}_{\mathbf{A}_{\mathcal{I}}\boldsymbol{\Omega}}\mathbf{A}_{\mathcal{I}} - \mathbf{P}_{\mathbf{A}_{\mathcal{I}}\boldsymbol{\Omega}}\mathbf{A}_{\mathcal{I}}\boldsymbol{\Omega}\mathbf{X}\|_\xi^2}_I + \underbrace{\|(\mathbf{A}_{\mathcal{I}} - \mathbf{P}_{\mathbf{A}_{\mathcal{I}}\boldsymbol{\Omega}}\mathbf{A}_{\mathcal{I}}) - (\mathbf{A}_{\mathcal{I}} - \mathbf{P}_{\mathbf{A}_{\mathcal{I}}\boldsymbol{\Omega}}\mathbf{A}_{\mathcal{I}})\mathbf{C}_{t-1}^{1/2}\Psi_{t-1}\mathbf{X}_{t-1}\|_\xi^2}_{II} \end{aligned}$$

We will now consider I . Let the SVD of $\mathbf{P}_{\mathbf{A}_{\mathcal{I}}\boldsymbol{\Omega}_i}\mathbf{A}_{\mathcal{I}} = \mathbf{U}_{\mathcal{I},i}\boldsymbol{\Sigma}_{\mathcal{I},i}\mathbf{V}_{\mathcal{I},i}^*$. Then we choose

$$\mathbf{X}_i = \left((\mathbf{V}_{\mathcal{I},i}^*)_{k+p} \mathbf{C}_i^{1/2} \Psi_i \right)^+ (\mathbf{V}_{\mathcal{I},i}^*)_{k+p}$$

From which we obtain,

$$I = \sum_{i=1}^{t-1} \|\mathbf{P}_{\mathbf{A}_{\mathcal{I}}\boldsymbol{\Omega}_i}\mathbf{A}_{\mathcal{I}} - \mathbf{P}_{\mathbf{A}_{\mathcal{I}}\boldsymbol{\Omega}_i}\mathbf{A}_{\mathcal{I}}\mathbf{C}_i^{1/2}\Psi_i\mathbf{X}_i\|_\xi^2 = \sum_{i=1}^{t-1} \|\mathbf{P}_{\mathbf{A}_{\mathcal{I}}\boldsymbol{\Omega}_i}\mathbf{A}_{\mathcal{I}} - \mathbf{P}_{\mathbf{A}_{\mathcal{I}}\boldsymbol{\Omega}_i}\mathbf{A}_{\mathcal{I}}\|_\xi^2 = 0$$

Let $\mathcal{F} = \{k(t-1), \dots, k(t+1)\}$. Next, we set $\mathbf{X}_{t-1} = (\mathbf{V}_{\mathcal{I}}^* \mathbf{C}_{t-1}^{1/2} \boldsymbol{\Psi}_{t-1})^+ \mathbf{V}_{\mathcal{I}}^*$, we then obtain

$$\begin{aligned} \sqrt{II} &\leq \|\mathbf{A}_{\mathcal{F},\perp} - \mathbf{P}_{\mathbf{A}_{\mathcal{F},\perp}} \boldsymbol{\Omega} \mathbf{A}_{\mathcal{F},\perp}\|_{\xi} \left(1 + \|\mathbf{V}_{\mathcal{I},\perp}^* \mathbf{C}_t^{1/2} \boldsymbol{\Psi}_{t-1} (\mathbf{V}_{\mathcal{I}}^* \mathbf{C}_{t-1}^{1/2} \boldsymbol{\Psi}_{t-1})^+ \mathbf{V}_{\mathcal{I}}^*\|_2\right) \\ &\leq \|\mathbf{A}_{\mathcal{F},\perp} - \mathbf{P}_{\mathbf{A}_{\mathcal{F},\perp}} \boldsymbol{\Omega} \mathbf{A}_{\mathcal{F},\perp}\|_{\xi} \left(1 + \sqrt{8 \log(n/\delta)} \|\mathbf{V}_{\mathcal{I},\perp}^* \mathbf{C}_{t-1}^{1/2}\|_2 \|(\mathbf{V}_{\mathcal{I}}^* \mathbf{C}_{t-1}^{1/2})^+\|_2 \frac{e\sqrt{k+p}}{p+1}\right) \end{aligned}$$

We can then complete the proof with induction, which gives us the desired result. \blacksquare

B Probability Theory

In this section we will present and prove an interesting property of Gaussian Matrices that gives us the improved bounds for the generalized rSVD.

Proposition 20. Fix matrices $\mathbf{S} \in \mathbb{R}^{k \times n}$ and $\mathbf{T} \in \mathbb{R}^{m \times \ell}$, then for a conformal matrix \mathbf{G} with elements sampled i.i.d from $\mathcal{N}(0, 1)$, then for $\xi \in \{2, F\}$, with probability exceeding $1 - \delta$,

$$\|\mathbf{SGT}\|_{\xi} \leq \|\mathbf{S}\|_{\xi} \|\mathbf{T}\|_{\xi} \sqrt{2 \log(nm/\delta)}$$

Proof. The proof for the Frobenius norm follows from a brute-force calculation followed by a maximal tail bound on a sample of Gaussians.

$$\begin{aligned} \|\mathbf{SGT}\|_F^2 &= \sum_{i \in [k]} \sum_{j \in [\ell]} \sum_{(k_1, k_2) \in [n] \times [m]} \mathbf{S}_{i, k_1}^2 \mathbf{T}_{k_2, j}^2 \mathbf{G}_{k_1, k_2}^2 \\ &\leq \sum_{i \in [k]} \sum_{j \in [\ell]} \sum_{(k_1, k_2) \in [n] \times [m]} \mathbf{S}_{i, k_1}^2 \mathbf{T}_{k_2, j}^2 \max_{(k_1, k_2) \in [n] \times [m]} \mathbf{G}_{k_1, k_2}^2 \\ &= \|\mathbf{S}\|_F^2 \|\mathbf{T}\|_F^2 \max_{(k_1, k_2) \in [n] \times [m]} \mathbf{G}_{k_1, k_2}^2 \end{aligned}$$

We now show an analogous result for the spectral norm with just a few more steps to recover the result. We will use classical techniques in probability theory to obtain a similar proof structure as the Frobenius norm result. From [30], we have the following relation for any matrix $\mathbf{B} \in \mathbb{R}^{m \times n}$,

$$\|\mathbf{B}\|_2 = \sup_{\mathbf{v} \in \mathbb{S}^{n-1}} \|\mathbf{B}\mathbf{v}\|_2 = \sup_{\mathbf{u} \in \mathbb{S}^{m-1}} \sup_{\mathbf{v} \in \mathbb{S}^{n-1}} |\mathbf{u}^* \mathbf{B} \mathbf{v}| \quad (14)$$

With the relation given in Equation (14) in hand, we have

$$\begin{aligned} \|\mathbf{SGT}\|_2^2 &= \sup_{\mathbf{u} \in \mathbb{S}^{k-1}} \sup_{\mathbf{v} \in \mathbb{S}^{\ell-1}} (\mathbf{u}^* \mathbf{SGT} \mathbf{v})^2 \\ &= \sup_{\mathbf{u} \in \mathbb{S}^{k-1}} \sup_{\mathbf{v} \in \mathbb{S}^{\ell-1}} \sum_{(i, j) \in [n] \times [m]} (\mathbf{u}^* \mathbf{S})_i^2 \mathbf{G}_{i, j}^2 (\mathbf{T} \mathbf{v})_j^2 \\ &\leq \sup_{\mathbf{u} \in \mathbb{S}^{k-1}} \sup_{\mathbf{v} \in \mathbb{S}^{\ell-1}} \sum_{(i, j) \in [n] \times [m]} (\mathbf{u}^* \mathbf{S})_i^2 (\mathbf{T} \mathbf{v})_j^2 \max_{(i, j) \in [n] \times [m]} \mathbf{G}_{i, j}^2 \\ &\leq \sup_{\mathbf{u} \in \mathbb{S}^{k-1}} \sup_{\mathbf{v} \in \mathbb{S}^{\ell-1}} \|\mathbf{S}^* \mathbf{u}\|_2^2 \|\mathbf{T} \mathbf{v}\|_2^2 \max_{(i, j) \in [n] \times [m]} \mathbf{G}_{i, j}^2 \\ &= \|\mathbf{S}\|_2^2 \|\mathbf{T}\|_2^2 \max_{(i, j) \in [n] \times [m]} \mathbf{G}_{i, j}^2 \end{aligned}$$

We now bound the maximum Gaussian over a finite sample.

$$\begin{aligned} \Pr \left\{ \max_{(k_1, k_2) \in [n] \times [m]} G_{k_1, k_2}^2 \geq t \right\} &= \Pr \left\{ \max_{(k_1, k_2) \in [n] \times [m]} |G_{k_1, k_2}| \geq \sqrt{t} \right\} \\ &\leq \frac{\sqrt{2nm}}{\sqrt{\pi}} \int_{\sqrt{t}}^{\infty} e^{-x^2/2} dx \leq \frac{\sqrt{2nm}}{\sqrt{\pi}} \int_{\sqrt{t}}^{\infty} \frac{x e^{-x^2/2}}{\sqrt{t}} dx = \frac{\sqrt{2nm}}{\sqrt{\pi}} e^{-t/2} \leq \delta \end{aligned}$$

In the above, the first inequality follows from a union bound over $[n] \times [m]$ and then integrating over the PDF of a standard normal Gaussian [2]. Then, from elementary algebraic manipulations, we obtain with probability exceeding $1 - \delta$,

$$\|\mathbf{SGT}\|_{\xi}^2 \leq 2 \log(nm/\delta) \|\mathbf{S}\|_{\xi}^2 \|\mathbf{T}\|_{\xi}^2$$

Taking the square root of both sides completes the proof. \blacksquare

C Theoretical Improvements to rSVD

In this section, we take a closer look at our spectral norm bound given in Theorem 5. We show that our bound implies a stronger relative spectral norm error bound than Theorem 10.8 in [20]. We will first restate the implication of Theorem 10.8 given by Halko et al. [20].

Theorem 21. *Let $\mathbf{A} \in \mathbb{C}^{m \times n}$, choose target rank $k \geq 2$ and oversampling parameter $p \geq 4$. Then sample $\mathbf{\Omega} \in \mathbb{R}^{m \times n}$ with standard normal entries. Construct the sample matrix $\mathbf{Y} = \mathbf{A}\mathbf{\Omega}$ and let $\mathbf{Q}\mathbf{R}$ be the economized QR decomposition of \mathbf{Y} . Then,*

$$\|\mathbf{A} - \mathbf{Q}\mathbf{Q}^*\mathbf{A}\|_2 \leq \|\mathbf{A} - \mathbf{A}_k\|_2 \left(1 + t\sqrt{12k/p} + t \cdot \frac{e\sqrt{k+p}}{p+1}\sqrt{n-k} + ut \cdot \frac{\sqrt{k+p}}{p+1} \right)$$

with failure probability at most $5t^{-p} + e^{-u^2/2}$.

This upper bound arises from Chevet's Inequality.

Lemma 22 (Chevet's Inequality). *Fix matrices $\mathbf{S} \in \mathbb{R}^{k \times n}$ and $\mathbf{G} \in \mathbb{R}^{m \times \ell}$, then for a conformal matrix \mathbf{G} with elements sampled i.i.d from $\mathcal{N}(0, 1)$, then*

$$\mathbb{E}\|\mathbf{S}\mathbf{G}\mathbf{T}\|_2 \leq \|\mathbf{S}\|_2\|\mathbf{T}\|_F + \|\mathbf{S}\|_F\|\mathbf{T}\|_2$$

The dependence on the Frobenius norm in the implication shows as the upper bound is

$$\|\mathbf{A} - \mathbf{A}_k\|_F \leq \sqrt{n-k}\|\mathbf{A} - \mathbf{A}_k\|_2$$

as we have $\mathbf{S} = \mathbf{A} - \mathbf{A}_k$ from the deterministic error bound in Theorem 9.1 of [20]. Although this upper bound is loose with strong singular value decay, we show we can give a stronger bound without any assumptions on the singular value spectra. We now will formalize our comparison by giving a corollary where we set $\mathbf{C} = \mathbf{I}$ and plug in our result from Theorem 5.

Corollary 23. *Consider the same hypothesis as Theorem 21, then*

$$\|\mathbf{A} - \mathbf{Q}\mathbf{Q}^*\mathbf{A}\|_2 \leq \|\mathbf{A} - \mathbf{A}_k\|_2 \left(1 + \sqrt{2t \log((n-k)(k+p)/\delta)} \frac{e\sqrt{k+p}}{p+1} \right)$$

with failure probability at most $\delta + t^{-p}$.

We find our results are able to remove the $O(\sqrt{n-k})$ term and reduce it to a $O(\log(n-k))$ term, giving us a stronger bound. We showcase the improved relative-error bound in the following synthetic experiment. Empirical Mean Error points in Figure 2 are averaged over 10 randomized runs. We observe our bounds offer a significant improvement for relative-error spectral norm compared to Theorem 21 and also are bounds are a proper upper bound.

D Additional details on the numerical experiments

In this section we perform additional experiments on synthetic matrices with polynomial and exponential singular value decay. We observe Algorithm 1 is stronger than rSVD and generalized rSVD in both experiments.

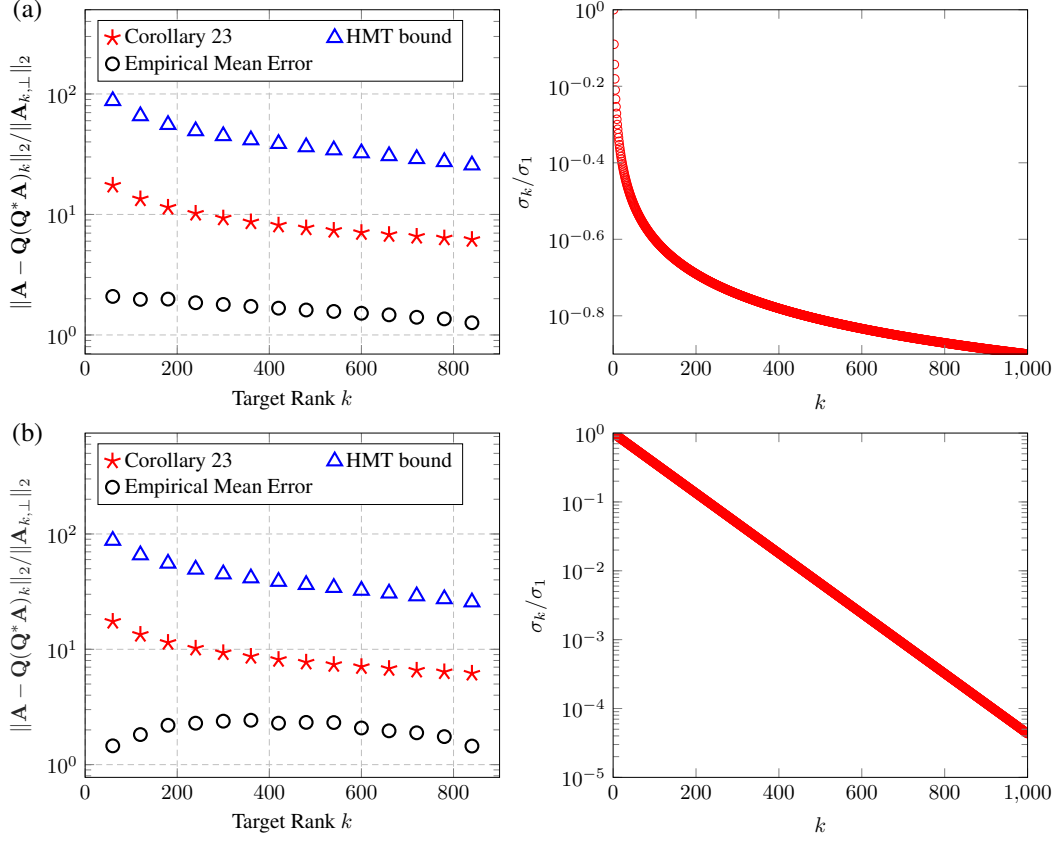


Figure 2: Left panels: Relative error (in the spectral norm) of the low-rank matrix approximation with respect to the number of matrix-vector products. At each target rank k , we set the oversampling parameter $p = \lceil k/4 \rceil$. Right panels: Singular value decay of the matrix. (a) Polynomial singular value decay (see Equation (7) with $p = 0.3$). (b) Exponential singular value decay (see Equation (8) with $\delta = 0.05$).

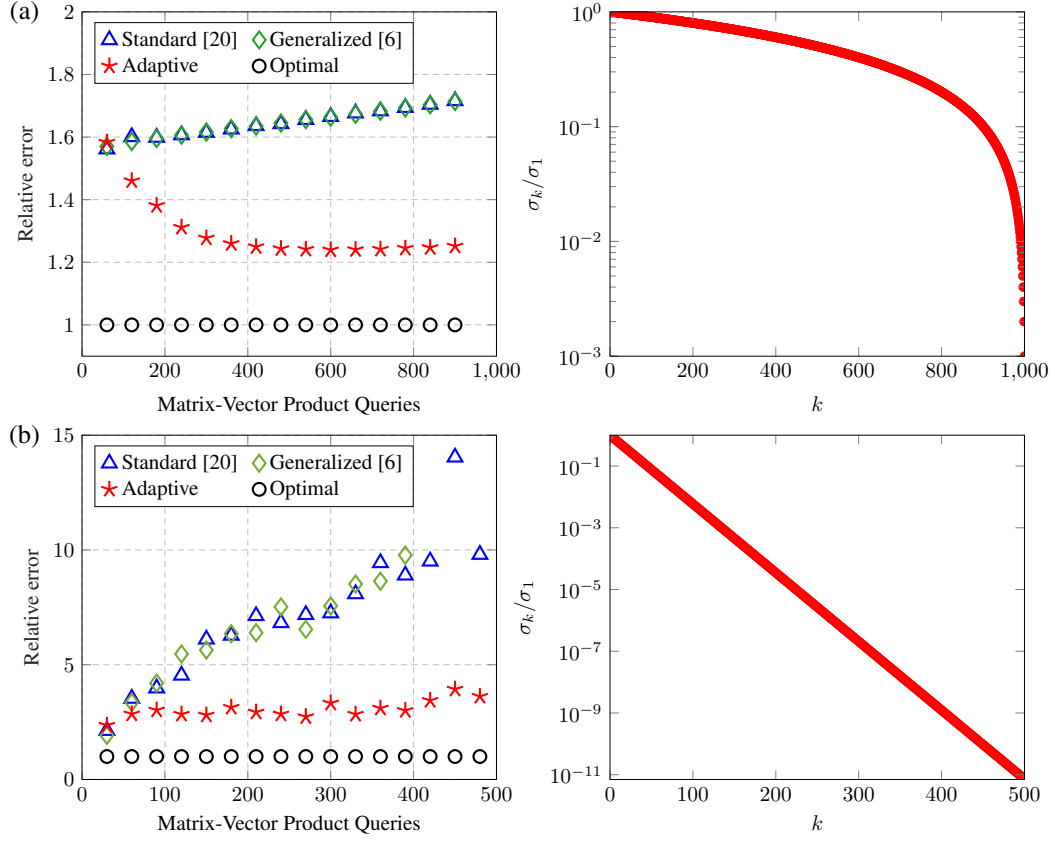


Figure 3: Left panels: Relative error (in the Frobenius norm) of the low-rank matrix approximation with respect to the number of matrix-vector products. Right panels: Singular value decay of the matrix. (a) Polynomial singular value decay (see Equation (7) with $p = 1$). (b) Exponential singular value decay (see Equation (8) with $\delta = 0.05$).