

ENV797 - TIME SERIES ANALYSIS FOR ENERGY AND ENVIRONMENT APPLICATIONS

Module 12 - Scenario Generation

Prof. Luana Medeiros Marangon Lima, Ph.D.

Learning Goals

- Understand the concept of scenario generation
- Connect optimization and decision making under uncertainty
 - Intro to stochastic optimization
- Learn how to represented uncertainty with a scenario tree
 - Give an idea of how the tree is generated
 - How to generate correlated scenarios
- Learn how to generate scenarios based on the time series models we learned in R

Scenario Generation

Motivation

"Wide range of real-world problems involve decision-making under uncertainty."

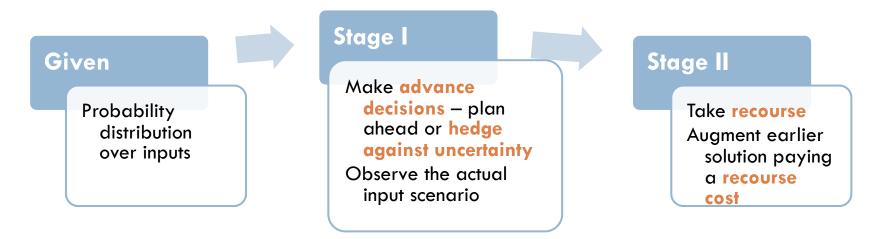
"If a statistical model can be used to describe this uncertainty, the decision problem can be modeled as a stochastic optimization problem."

Stochasticity or Uncertainty

- Origin
 - Future information (e.g. prices or demand)
 - Lack of reliable data
 - Measurement errors
- In electric energy systems planning
 - Demand (yearly, seasonal or daily variation, load growth
 - Hydro, Wind and Solar (natural resources)
 - Availability of generation or network elements
 - Electricity or Fuel Prices

Stochastic Optimization

- Optimizing or making decisions under uncertainty
- Why uncertainty?
 - Exact data is unavailable or expensive
 - Instead, data is specified by a probability distribution
- Obj.: Make the best decisions given the uncertainty
- Approach: Multi-stage Model



Decision Under Uncertainty

- Determinist optimization
 - Best decision when future is known

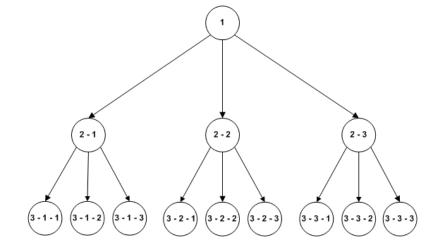


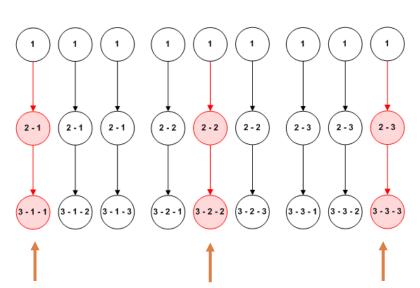
- Stochastic Optimization
 - Better decision when future is uncertain but with a known probability

- But how??
 - Scenario Analysis or scenario tree

Scenario Tree

- Tree: represents how the stochasticity is revealed over time, i.e., the different states of the random parameters
- Nodes: where decisions are taken
- Scenarios: path going from the root to the leaves
- Allow the solution of huge problem by solving iteratively small size problems





Scenario Tree Generation

- Correlation among random parameters should be considered
- Number of scenarios generated should be enough for observing parameter variability
- Common methods
 - Monte Carlo sampling methods



- Quasi-Monte Carlo methods
- Optimal quantization of probability distributions
- And others....

Simulations in R

- Possible to simulate data with R using random number generators of different kinds of variables
- Sampling from

Multinomial distributions

sample(1:4,1000,rep=TRUE,prob=c(.2,.3,.2,.3))

Uniform distribution

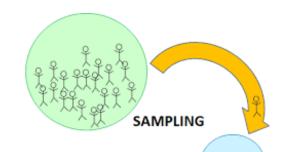
runif(n, min = 0, max = 25)

Normal distribution

rnorm(n, mean = 0, sd = 1)

Exponential distributions

rexp(n, rate = 1)



Other examples available at:

Sampling from Multivariate Normal Distribution

- When sampling the scenarios for multiple variables one need to take into account correlation
- Easiest way to deal with this is to draw independently $N[\mu,\sigma^2]$ and then pass the correlation through Cholesky decomposition
- $\hfill \Box$ Let R be correlation matrix $(n_{var} \ x \ n_{var})$ among the variables. The Cholesky decomposition of R is a lower triangular matrix such that

$$R = LL^T$$

□ How to get L?

Sampling from Multivariate Normal Distribution (c'ed)

- Let X be a matrix $(n_{var} \times n_{step})$ with independent identically distributed draws from a N[0, 1]
- Define Y such that

$$Y = LX$$

Recall L is the Cholesky decomposition of R

- lacktriangle Note that the resulting matrix Y will have order $n_{var} \ x \ n_{step}$
- Y corresponds to the correlated draws

Connecting Scenario and Models Learned in TSA

ARIMA Forecasting

Recall the ARMA(1,1) model equation

$$Y_t = \phi_1 Y_{t-1} + a_t - \theta_1 a_{t-1}$$
 for $t = 1, 2, ..., n$ where $a_t \sim N.I.D.(0, \sigma^2)$

- $_{ extstyle }$ From the estimation step you have $\phi = (\phi_1 \ \phi_2 \ ... \ \phi_p)$ ' and σ^2
- One can rewrite this equation as

$$Y_t \sim N.I.D.(\phi_1 Y_{t-1} - \theta_1 a_{t-1}, \sigma^2)$$

 Same principle is extended for the more general class of ARIMA Models

State Space BSM

Model equations

$$y_{t} = \mu_{t} + \gamma_{t} + \varepsilon_{t} \qquad \varepsilon_{t} \sim \mathcal{NID}(0, \sigma_{\varepsilon}^{2})$$

$$\mu_{t+1} = \beta_{t} + \mu_{t} + \eta_{t} \qquad \eta_{t} \sim \mathcal{NID}(0, \sigma_{\eta}^{2})$$

$$\beta_{t+1} = \beta_{t} + \xi_{t} \qquad \xi_{t} \sim \mathcal{NID}(0, \sigma_{\xi}^{2})$$

$$\gamma_{t+1} = -\sum_{j=1}^{s-1} \gamma_{t+1-j} + \omega_{t} \qquad \omega_{t} \sim \mathcal{NID}(0, \sigma_{\omega}^{2})$$

The observation equation can be rewritten

$$y_t \sim \mathcal{NID}(\mu_t + \gamma_t, \sigma_{\varepsilon}^2)$$



THANK YOU!

luana.marangon.lima@duke.edu

Master of Environmental Management Program
Nicholas School of the Environment - Duke University