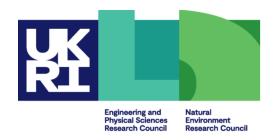
# Message Passing Programming

Tips and tricks











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#### Aims

- To write correct MPI programs
  - that are portable to many systems
  - that are efficient
  - that are easy to maintain





# Common problems in MPI

- Assuming MPI\_Send is asynchronous
- Data sizes
- Non-portability
- Programs with specific process counts
- Not calling collectives collectively
- Incorrect use of non-blocking
- Sending lots of small messages
- Array allocation issues in C
- Array syntax issues in Fortran
- Code readability
- Debugging problems





#### Assuming MPI\_Send is asynchronous

#### Potential deadlock

- you may be assuming that MPI Send is asynchronous
- it often is buffered for small messages
  - but threshold will vary with implementation
- you code may run on one machine and deadlock on another
- correct code will run with all MPI\_Send calls replaced by MPI\_Ssend

#### Buffer space

- cannot assume that there will be space for MPI\_Bsend
- default buffer space may be zero!
- be sure to use MPI\_Buffer\_attach
  - some advice in MPI standard regarding required size
  - allow for space for message headers: MPI\_BSEND\_OVERHEAD





#### **Data Sizes**

- Be careful of data sizes or layout
  - use runtime enquiry functions for Fortran types
  - be careful of compiler-dependent padding for structures
- Do not use magic compiler flags to change precision!

```
cc -convert-floats-to-doubles *.c
```

- Changing precision
  - when changing from, say, float to double, must change all the MPI types from MPI FLOAT to MPI DOUBLE as well
- Easiest to achieve with an include file
  - e.g. every routine includes precision.h





# Changing Precision: C

Define a header file called, e.g. precision.h

```
    typedef float RealNumber
    #define MPI_REALNUMBER MPI_FLOAT
    Include in every function
```

```
- #include "precision.h"
```

```
- RealNumber x;
- MPI Routine(&x, MPI REALNUMBER, ...);
```

- Global change of precision now easy
  - edit 2 lines in one file: float -> double, MPI\_FLOAT -> MPI\_DOUBLE





#### Changing Precision: Fortran

• Define a module called, e.g., precision

```
- integer, parameter :: REALNUMBER=kind(1.0e0)
- integer, parameter :: MPI_REALNUMBER = MPI_REAL

• Use in every subroutine
- use precision
- . . .
- REAL(kind=REALNUMBER) :: x
- call MPI_ROUTINE(x, MPI_REALNUMBER, . . . .)
```

- Global change of precision now easy
  - change 1.0e0 -> 1.0d0, MPI\_REAL -> MPI\_DOUBLE\_PRECISION





## Non-portability

- Correct C code should compile correctly with any C compiler
- Correct MPI code should also run correctly with any MPI library
- Run on more than one machine
  - assuming the MPI libraries are different
  - many parallel clusters will use the same open-source MPI
    - e.g. OpenMPI or MPICH2
    - running on two different HPC systems may not be a good test
- More than one implementation on same machine
  - e.g. run using both MPICH2 and OpenMPI on your laptop
  - very useful test, and can give interesting performance numbers
- More than one compiler
  - user@cluster\$ module switch mpich2-gcc mpich2-intel



## **Code Readability**

- Adding MPI can destroy a code
  - would like to maintain a serial version
  - i.e. can compile and run identical code without an MPI library
  - not simply running MPI code with P=1!
- Need to separate off communications routines
  - put them all in a separate file
  - provide a dummy library for the serial code
  - no explicit reference to MPI in main code





#### **Example: Initialisation**

```
! parallel routine
subroutine par begin(size, procid)
  implicit none
  integer :: size, procid
  include "mpif.h"
  call mpi init(ierr)
  call mpi comm size (MPI COMM WORLD, size, ierr)
  call mpi comm rank (MPI COMM WORLD, procid, ierr)
 procid = procid + 1
end subroutine par begin
! dummy routine for serial machine
subroutine par begin(size, procid)
  implicit none
  integer :: size, procid
  size = 1
 procid = 1
end subroutine par begin
```





#### Example: Global Sum

```
! parallel routine
subroutine par dsum(dval)
  implicit none
  include "mpif.h"
  double precision :: dval, dtmp
  call mpi allreduce (dval, dtmp, 1, MPI DOUBLE PRECISION, &
                     MPI SUM, comm, ierr)
  dval = dtmp
end subroutine par dsum
! dummy routine for serial machine
subroutine par dsum(dval)
  implicit none
  double precision dval
end subroutine par dsum
```





#### Example Makefile

```
SEQSRC= \
 demparams.f90 demrand.f90 demcoord.f90 demhalo.f90 \
 demforce.f90 demlink.f90 demcell.f90 dempos.f90
 demons.f90
MPISRC= \
 demparallel.f90 \
 demcomms.f90
FAKESRC= \
 demfakepar.f90 \
 demfakecomms.f90
#PARSRC=$ (FAKESRC)
PARSRC=$ (MPISRC)
```





# Advantages of Comms Library

- Can compile serial program from same source
  - makes parallel code more readable
- Enables code to be ported to other libraries
  - more efficient but less versatile routines may exist
  - e.g. Cray-specific SHMEM library
  - can even choose to only port a subset of the routines
- Library can be optimised for different MPIs
  - e.g. choose the fastest send (Ssend, Send, Bsend?)





## Not calling collectives correctly

- Collectives must be called by all processes in communicator
  - this will not work correctly on more than a single process

```
if (rank == 0) MPI_Bcast(x, 10, MPI_INT, 0, MPI_COMM_WORLD);
```

- an Allreduce called like this would deadlock
- Compute everything everywhere
  - e.g. use routines such as Allreduce in preference to Reduce
  - perhaps the value only really needs to be know on the master
    - but using Allreduce makes things simpler
    - no serious performance implications





## Error checking and reductions

- Do not use reduce + broadcast!
  - use allreduce





## Sending lots of small messages

```
for (j=0; j < N; j++)
{
    MPI_Send(&x[0][j], 1, MPI_INT, dest, 0, comm);
}</pre>
```

Send a single message of size N

```
MPI\_Send(&x[0][0], N, MPI\_INT, dest, 0, comm);
```

Use a derived type, e.g. a vector, for equivalent loop over i

```
MPI\_Send(&x[0][0], 1, my\_mpi\_vector, dest, 0, comm);
```





# Programs with specific process counts

Do not write code like:

```
if (rank == 0) {
  for (i=1; i <= N/4; i++)
    pi = pi + 1.0/(1.0 + pow((((double)i)-0.5)/((double) N),2.0));
} else if (rank == 1)
  for (i=N/4+1; i <= N/2; i++)
    pi = pi + 1.0/(1.0 + pow((((double)i)-0.5)/((double) N),2.0));
} else ...</pre>
```

- Often easiest to make P a compile-time constant
  - may not seem elegant but can make coding much easier
    - e.g. definition of array bounds
  - put definition in an include file and *check at runtime* that size = *P* !!
  - a clever Makefile can reduce the need for recompilation
    - only recompile routines that define arrays rather than use them





#### Incorrect use of non-blocking

```
if (rank == 0) {
  for (i=1; i < size; i++) {
    MPI_Issend(x, 10, MPI_INT, i, 0, comm, &request);
  }
} else MPI_Irecv(x, 10, MPI_INT, 0, 0, comm, &request);
// now start computation</pre>
```

- Need multiple requests on rank 0
  - and they *must* be waited on at some later point
- Why use non-blocking here at all?
  - avoid complication unless this is performance critical





# Debugging

- Parallel debugging can be hard
- Don't assume it's a parallel bug!
  - run the serial code first
  - then the parallel code with *P*=1
  - then on a small number of processes ...
- Writing output to separate files can be useful
  - e.g. log.00, log.01, log.02, .... for ranks 0, 1, 2, ...
  - need some way easily to switch this on and off
- Some parallel debuggers exist
  - Allinea DDT is becoming more common across the board
  - a commercial product
  - debuggers can powerful tools but also very complicated





## General Debugging

- People seem to write programs DELIBERATELY to make them impossible to debug!
  - my favourite: the silent program
  - "my program doesn't work"
    - \$ mpirun -n 6 ./program.exe
    - \$ SEGV core dumped
  - where did this crash?
  - did it run for 1 second? 1 hour? in a batch job this may not be obvious
  - did it even start at all?

#### Why don't people write to the screen!!!





## Program should output like this

```
$ mprun -np 6 ./program.exe
Program running on 6 processes
Reading input file input.dat ...
... done
Broadcasting data ...
... done
rank 0: x = 3
rank 1: x = 5
etc etc
Starting iterative loop
iteration 100
iteration 200
finished after 236 iterations
writing output file output.dat ...
... done
rank 0: finished
rank 1: finished
Program finished
```





## Typical mistakes

- Don't write raw numbers to the screen!
  - what does this mean?

```
$ mprun -np 6 ./program.exe
1 3 5.6
3 9 8.37
```

- programmer has written

```
$ printf("%d %d %f\n", rank, j, x);
$ write(*,*) rank, j, x
```

Takes an extra 5 seconds to type:

```
$ printf("rank, j, x: %d %d %f\n", rank, j, x);
$ write(*,*) 'rank, j, x: ', rank, j, x
```

- and will save you HOURS of debugging time
- Why oh why do people write raw numbers?!?!





#### Common mistake

- There was a bug, but I changed something ...
  - and it now works (but I don't know why)
- All is OK!
- No!
  - there is a bug
  - you MUST find it
  - if not, it will come back later to bite you HARD
- Debugging is an experimental science
  - start with the serial code
  - then P=1
  - then a small process count ...





# Verification: Is My Code Working?

- Should the output be identical for any P?
  - very hard to accomplish in practice due to rounding errors
    - may have to look hard to see differences in the last few digits
  - typically, results vary slightly with number of processes
  - need some way of quantifying the differences from serial code
  - and some definition of "acceptable"
- What about the same code for fixed P?
  - identical output for two runs on same number of processes?
  - should be achievable with some care
    - not in specific cases like dynamic task farms
    - possible problems with global sums
    - MPI doesn't require reproducibility, but most implementations are
  - without this, debugging is almost impossible





## **Optimisation**

- Keep running your code
  - on a number of input data sets
  - with a range of MPI processes
- If scaling is poor
  - find out what parallel routines are the bottlenecks
  - again, much easier with a separate comms library
- If performance is poor
  - work on the serial code
  - return to parallel issues later on





## Fortran array syntax

- MPI derived types enable strided data to be sent/received
  - no explicit copy in/out required
- For Fortran
  - why not use Fortran array syntax?
- Some subtleties for non-blocking operations





## Non-blocking operations

What is wrong with this code?

```
allocate(buf(n))
call MPI_Issend(buf, n, ....)
deallocate(buf)
```

- Non-blocking send may still be ongoing at deallocation
  - code could crash or give unpredictable behaviour
  - only safe to deallocate the memory after the matching wait
- Identical issues in C using malloc and free
  - however, the problem arises in a more subtle way in Fortran
  - due to its more sophisticated array handling





#### Fortran array syntax

```
real, dimension(m,n) :: array
call MPI_Issend(array(1,1:n), n, MPI_REAL, ...)
```

Looks ok but compiler will probably do:

```
allocate buf(n)
buf(1:n) = array(1,1:n)
call MPI_Issend(buf, n, MPI_REAL, ...)
array(1,1:n) = buf(1:n)
deallocate(buf)
```

- so buf may not exist when message is sent
- issue even more severe for non-blocking receive





#### Solutions

- Note this only an issue for non-blocking operations
  - e.g. can do normal blocking send and receive using array syntax
- Advice
  - avoid array syntax, even for contiguous sections (e.g. columns)

```
call MPI Issend(array(1,1), m, ...)
```

- rather than

```
call MPI Issend(array(1:m,1), m, ...)
```

Derived datatypes (e.g. vectors) for non-contiguous rows

```
call MPI_Issend(array(1,1), 1, rowtype, ...)
```





#### Array allocation issues with C

C: x[16] F: x(16)

C: x[4][4]

4	8	12	16
3	7	11	15
2	6	10	14
1	5	9	13

j ↑

13	14	15	16
9	10	11	12
5	6	7	8
1	2	3	4

F: x(4,4)

- Data is contiguous in memory
  - different conventions in C and Fortran
  - for statically allocated C arrays x == &x[0][0]





# Aside: Dynamic Arrays in C

```
float **x = (float **) malloc(4, sizeof(float *));
for (i=0; i < 4; i++)
{
  x[i] = (float *) malloc(4, sizeof(float));
              X
                                                           4
                                                                      12
                                                          9
                                                             10
                                                                  11
                   \mathbf{x}[0]\mathbf{x}[1]\mathbf{x}[2]\mathbf{x}[3]
                                                      8
    13
            15
        14
                16
```

- Data non-contiguous, and x != &x[0][0]
  - cannot use regular templates such as vector datatypes
  - cannot pass x to any MPI routine





#### Arralloc

```
float **x = (float **) arralloc(sizeof(float), 2, 4, 4);
/* do some work */
free((void *) x);

x x[0]x[1]x[2]x[3] 1 2 3 4 5 6 7 8 9 10 11 12 13
```

- Data is now contiguous, but still x != &x[0][0]
  - can now use regular template such as vector datatype
  - must pass &x [0] [0] (start of contiguous data) to MPI routines
  - see MPP-arralloc.tar for example of use in practice
- Clearest to use always use &x[i][j] syntax
  - correct for both static and (contiguously allocated) dynamic arrays



#### Conclusions

- Run on a variety of machines
- Keep it simple
- Maintain a serial version
- Don't assume all bugs are parallel bugs
- Find a debugger you like (good luck to you)



