Machine Learning I Lecture III: Gaussian models

AMIT DHOMNE

Plan for today

Wrap up: Continuous random variables

Gaussians

Bayesian inference for Gaussians

Mean, variance, and conditioning on events are the same as the discrete case, just with sums replaced by integrals.

- Mean: $E(X) = \int_{\mathcal{X}} x \cdot p(x) dx$
- ▶ Variance: $Var(X) = E(X^2) E(X)^2$
- ▶ Example: Uniform, Exponential [on board]
- ▶ If X has pdf p(x), then $X|(X \in A)$ has pdf

$$p_{X|A}(x) = \frac{p(x)}{P(A)} = \frac{p(x)}{\int_{x \in A} p(x) dx}$$
 (1)

- ▶ Only makes sense if P(A) > 0!
- ► Examples: Uniform, Exponential [on board]

Bivariate continuous distributions: Marginalization, Conditioning and Independence

- $\triangleright p_{X,Y}(x,y)$, joint probability density function of X and Y
- ▶ Marginal distribution: $p(x) = \int_{-\infty}^{\infty} p(x, y) dy$
- ► Conditional distribution: $p(x|y) = \frac{p(x,y)}{p(y)}$
- ▶ Note: P(Y = y) = 0! Formally, conditional probability in the continuous case can be derived using infinitesimal events.
- ► Independence: X and Y are independent if $p_{X,Y}(x,y) = p_X(x)p_Y(y)$

The univariate Gaussian

$$t \sim \mathcal{N}(\mu, \sigma^2) \tag{2}$$

$$p(t|\mu, \sigma^2) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{1}{2} \left(\frac{t-\mu}{\sigma}\right)^2\right)$$
 (3)

- ▶ The Gaussian has mean μ and variance σ^2 and precision $\beta = 1/\sigma^2$
- ▶ Q: What are the mode and the median of the Gaussian?
- ▶ Maximum Likelihood estimation of μ and β : [on board]
- ▶ Q: How would you find the conjugate prior for the Gaussian?

A (very important) aside: Products of Gaussian pdfs are (unnormalized) Gaussians pdfs

▶ Suppose $p_1(x) = \mathcal{N}(x, \mu_1, 1/\beta_1)$ and $p_2(x) = \mathcal{N}(x, \mu_2, 1/1\beta_2)$, then

$$p_1(x)p_2(x) \propto \mathcal{N}(x,\mu,1/\beta)$$
 (4)

$$\beta = \beta_1 + \beta_2 \tag{5}$$

$$\mu = \frac{1}{\beta} (\beta_1 \mu_1 + \beta_2 \mu_2) \tag{6}$$

In general:

$$p_1(x)p_2(x)...p_n(x) \propto \mathcal{N}(x,\mu,1/\beta) \tag{7}$$

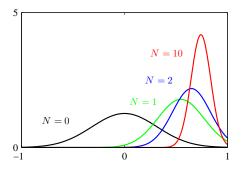
$$\beta = \sum_{n} \beta_n \tag{8}$$

$$\mu = \frac{1}{\beta} \sum_{n} \mu_n \beta_n \tag{9}$$

This is also true for multivariate Gaussians!

Bayesian Inference for the Gaussian

- ▶ Suppose we are given data $D = \{x_1, \ldots, x_N\}$.
- We assume that the data is Gaussian-distribution with known variance σ^2 and unknown mean μ .
- Our prior for μ is Gaussian: $\mu \sim \mathcal{N}(\mu_o, \sigma_o^2)$
- ▶ Posterior distribution over μ given the data: [on board]



[Bishop PRML Figure 2.12]

Behaviour for large N: [on board]

What if the variance is not given?

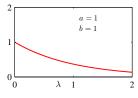
- ▶ For simplicity, assume mean to be known.
- ▶ More convenient to work with precision $\lambda = 1/\sigma^2$.
- \blacktriangleright Conjugate prior: Gamma distribution $\operatorname{Gam}(\lambda|a,b)$

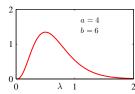
$$p(\lambda|a,b) = \frac{1}{\Gamma(a)} b^a \lambda^{a-1} exp(-b\lambda)$$
 (10)

▶ Posterior is $Gam(\lambda|a_N, b_B)$

$$a_N = a + \frac{N}{2} \tag{11}$$

$$b_N = b + \frac{1}{2} \sum_{n=1}^{N} (x_n - \mu)^2$$
 (12)

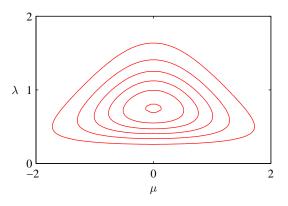




What if both the mean and the variance are unknown?

▶ Conjugate prior: Gaussian-Gamma distribution

$$p(\mu, \lambda) = \mathcal{N}\left(\mu | \mu_o(\beta \lambda)^{-1}\right) \operatorname{Gam}(\lambda | a, b)$$
 (13)



S [Bishop PRML Page 102]