



# **IEEE International Conference on Engineering Reliable Autonomous Systems (ERAS 2025)**

*29-30 May 2025, Worcester, MA, USA*

## **Technical Program**

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## ERAS 2025' Program At A Glance

Local time	Thursday 29th May, 2025	Friday 30th May, 2025
8:30-8:45	Registration Desk (& Breakfast)	Registration Desk (& Breakfast)
8:45-9:00		
9:00-9:15	<b>Opening Session</b>	<b>Poster Session 1 (Online)</b>
9:15-9:30	<b>Keynote Talk 1</b>	Challenges in Engineering Reliable Autonomous Systems I
9:30-9:45	Reliable Robotics Research at the Robotics and AI Institute	
9:45-10:00	Ben Axelrod (Boston Dynamics, MA, USA)	
10:00-10:15		<b>Technical Session 4 on</b>
10:15-10:30	<b>Technical Session 1 on</b>	Evaluation of Reliable Autonomous Systems
10:30-10:45	Design of Reliable Autonomous Systems	
10:45-11:00		
11:00-11:15		
11:15-11:30	Coffee Break	Coffee Break
11:30-11:45	<b>Technical Session 2 on</b>	<b>Technical Session 5 on</b>
11:45-12:00	Reliable Autonomous Vehicles	Reliable Human-Robot Teaming
12:00-12:15		
12:15-12:30	Lunch	Lunch
12:30-12:45		
12:45-13:00		
13:00-13:15		
13:15-13:30		
13:30-13:45	<b>Keynote Talk 2</b>	<b>Keynote Talk 3</b>
13:45-14:00	Contributions to Assurance from Basic and Applied Research	Towards Verified Visual Autonomy
14:00-14:15	Craig Lennon (US Army)	Sayan Mitra (University of Illinois Urbana-Champaign, IL, USA)
14:15-14:30		
14:30-14:45	<b>Technical Session 3 on</b>	<b>Poster Session 2 (On-site)</b>
14:45-15:00	Reliable Vision Autonomous Systems	Challenges in Engineering Reliable Autonomous Systems II
15:00-15:15		<b>Workshop - SAFE</b>
15:15-15:30		Main Organizer: Amy Fang (MIT, MA, USA)
15:30-15:45	Coffee Break	Coffee Break
15:45-16:00		
16:00-16:15	<b>Tutorial - HEART</b>	
16:15-16:30	Main Organizer:	
16:30-16:45	Jordan Fischer	
16:45-17:00	(IBM, USA)	
17:00-17:15	Welcome Gathering	Farewell Gathering
17:15-17:30		<b>Closing Session</b>
17:30-17:45		
17:45-18:00		
18:00-18:15	Banquet	
18:15-18:30		
18:30-18:45		
18:45-19:00		
19:00-19:15		
19:15-19:30		
19:30-19:45		
19:45-20:00		
20:00-20:15		
20:15-20:30		
20:30-20:45		
20:45-21:00		

All times are provided in the local time (EDT, UTC-4) of the venue (Worcester, MA, USA).

As part of the Accessibility Policy, ERAS 2025 conference is fully hybrid.

The 2025 IEEE International Conference on Engineering Reliable Autonomous Systems (ERAS 2025) is technically sponsored by IEEE and IEEE Robotics and Automation Society and supported by IEEE RAS Technical Committees, as follows: IEEE TC PEBRAS – Performance Evaluation and Benchmarking of Robotic and Automation Systems, IEEE TC-SOFT – Software Engineering for Robotics and Automation, and IEEE TC VAS – Verification of Autonomous Systems.

**8:30-9:00 Registration Desk & Breakfast**

**9:00-9:15 Opening Session** [*Odeum* – Room 341-343] [[ZOOM LINK](#)]

**9:15-10:15 Plenary Talk 1** (Session Chair: Kevin Leahy, *WPI - Worcester Polytechnic Institute, MA, USA*) [*Odeum* – Room 341-343] [[ZOOM LINK](#)]

Title: **Reliable Robotics Research at the Robotics and AI Institute**

Speaker: **Ben Axelrod** (*Boston Dynamics, MA, USA*)

**10:15-11:15 Technical Session 1: Session on Design of Reliable Autonomous Systems** [Oral Presentations] (Session Chair: Marsha Chechik, *University of Toronto, Canada*) [*Odeum* – Room 341-343] [[ZOOM LINK](#)]

**10:15-10:30 Paper #16: Skill-Based Architectures in Autonomous Systems: An Empirical Study**

Pierre Malafosse (*LAAS-CNRS, Université de Toulouse, France*)

Alexandre Albore (*ONERA The French Aerospace Lab, France*)

Jérémie Guiochet (*LAAS-CNRS, Université de Toulouse, France*)

Charles Lesire (*ONERA The French Aerospace Lab, France*)

**10:30-10:45 Paper #31: Reliable Robot Missions in Dynamic Environments Using Agent-based Controllers**

Raynaldio Limarga (*University of Manchester, UK*)

Kwai Wa Tse (*University of Manchester, UK*)

Louise A. Dennis (*University of Manchester, UK*)

Clare Dixon (*University of Manchester, UK*)

Fatma Faruq (*University of Manchester, UK*)

Michael Fisher (*University of Manchester, UK*)

**10:45-11:00 Paper #44: From Developer Needs to Domain-Specific Languages: Specifying Sceneries for Simulation-Based Validation of Mobile Robots**

Argentina Ortega (*University of Bremen, Germany*)

Samuel Parra (*Hochschule Bonn-Rhein-Sieg, Germany*)

Sven Schneider (*KU Leuven, Belgium*)

Nico Hochgeschwender (*University of Bremen, Germany*)

11:00-11:15 Paper #02: Automatic Tuning of Autonomous System Design Parameters for Performance Robustness

Paul Stankiewicz (*Johns Hopkins Applied Physics Laboratory, MD, USA*)

Jordan Appler (*Johns Hopkins Applied Physics Laboratory, MD, USA*)

11:15-11:30 **Coffee Break** [*Mid-Century Room – Room 331*]

11:30-12:15 **Technical Session 2: Session on Reliable Autonomous Vehicles** [Oral Presentations]  
(Session Chair: Qin Yang, *Bradley University, IL, USA*) [*Odeum – Room 341-343*] [[ZOOM LINK](#)]

11:30-11:45 Paper #46: Advancing Autonomous Vehicle Safety: A Combined Fault Tree Analysis and Bayesian Network Approach

Lansu Dai (*University of Ottawa, Canada*)

Burak Kantarci (*University of Ottawa, Canada*)

11:45-12:00 Paper #43: Autonomous Robotic Swarms: A Corroborative Approach for Verification and Validation

Dhaminda B. Abeywickrama (*University of Manchester, UK*)

Suet Lee (*University of Bristol, UK*)

Chris Bennett (*University of Bristol, UK*)

Razanne Abu-Aisheh (*University of Bristol, UK*)

Tom Didiot-Cook (*University of Bristol, UK*)

Simon Jones (*University of Bristol, UK*)

Sabine Hauert (*University of Bristol, UK*)

Kerstin Eder (*University of Bristol, UK*)

12:00-12:15 Paper #20: Towards a Resilient Framework for Multirotor UAVs: Autonomous Adaptation to Failures and Disturbances

Luis Hector Manjarrez Muñoz (Center for Research and Advanced Studies of the National Polytechnic Institute, Mexico City, Mexico)

Eduardo Steed Espinoza Quesada (*Mexican Secretariat of Science, Humanities, Technology and Innovation, Mexico City, Mexico*)

Luis Rodolfo Garcia Carrillo (*New Mexico State University, NM, USA*)

12:15-13:30 **Lunch** [*Mid-Century Room – Room 331*]

13:30-14:30 **Plenary Talk 2** (Session Chair: Dejanira Araiza Illan, *Johnson & Johnson, Belgium*) [Odeum – Room 341-343] [\[ZOOM LINK\]](#)

Title: **Contributions to Assurance from Basic and Applied Research**

Speaker: **Craig Lennon (US Army)**

14:30-15:30 **Technical Session 3: Session on Reliable Vision Autonomous Systems** [Oral Presentations] (Session Chair: Joanna Olszewska, *University of the West of Scotland, UK*) [Odeum – Room 341-343] [\[ZOOM LINK\]](#)

14:30-14:45 Paper #08: Arguing Reliability of Machine Learning-based Components

Boyue Caroline Hu (*University of Toronto, Canada*)

Alessio Di Sandro (*University of Toronto, Canada*)

Lina Marsso (*University of Toronto, Canada*)

Krzysztof Czarnecki (*University of Waterloo, Canada*)

Marsha Chechik (*University of Toronto, Canada*)

14:45-15:00 Paper #26: Monitoring Safety Properties for Autonomous Driving Systems with Vision-Language Models

Felipe Toledo (*University of Virginia, VA, USA*)

Sebastian Elbaum (*University of Virginia, VA, USA*)

Divya Gopinath (*KBR Inc. / NASA Ames Research Center, CA, USA*)

Ramneet Kaur (*SRI, CA, USA*)

Ravi Mangal (*Colorado State University, CO, USA*)

Corina S. Păsăreanu (*KBR, NASA Ames Research Centre, CA, USA*)

Anirban Roy (*SRI, CA, USA*)

Susmit Jha (*SRI, CA, USA*)

15:00-15:15 Paper #11: NeRF-To-Real Tester: Neural Radiance Fields as Test Image Generators for Vision of Autonomous Systems

Laura Wehl (*IT University of Copenhagen, Denmark*)

Bilal Wehbe (*Robotics Innovation Centre, DFKI, Bremen, Germany*)

Andrzej Wąsowski (*IT University of Copenhagen, Denmark*)

15:15-15:30 Paper #39: Why Good Detectors Can Make Bad Trackers: mAP Worse than Random Chance at Model Selection

Trenton Tabor (*Carnegie Mellon University, PA, USA*)

Tomasz Swierzewski (*Carnegie Mellon University, PA, USA*)

Casidhe Hutchison (*Carnegie Mellon University, PA, USA*)

Oren Wright (*Carnegie Mellon University, PA, USA*)

Eric Heim (*Carnegie Mellon University, PA, USA*)

Christopher S. Timperley (*Carnegie Mellon University, PA, USA*)

15:30-16:00 **Coffee Break** [*Mid-Century Room* – Room 331]

16:00-17:00 **Tutorial** [*Odeum* – Room 341-343] [[ZOOM LINK](#)]

Title: **HEART - Hardened Extension of the Adversarial Robustness Toolbox (HEART): Evaluating and Hardening AI Models against Novel Attack Vectors**

Speaker: **Jordan Fischer** (*IBM, USA*)

17:00-18:00 **Welcome Gathering** [*Mid-Century Room* – Room 331] [[ZOOM LINK](#)]

18:00-21:00 **Banquet** [*Higgins House* – Building 13]



**8:30-9:00 Registration Desk & Breakfast**

**9:00-10:00 Technical Session 6a: Session on Challenges in Engineering Reliable Autonomous Systems (I)** [Online Poster Presentations] (Session Chair: Dejanira Araiza Illan, *Johnson & Johnson, Belgium*) [Odeum – Room 341-343] [\[ZOOM LINK\]](#)

9:00-9:10 Paper #30: Defining and Designing Reliable AI-Enabled and Autonomous Systems

Benjamin D. Werner (*US Army*)

Benjamin J. Schumeg (*US Army*)

Shawn P. Brady (*US Army*)

Nathan W. Herbert (*US Army*)

James J. Foerster (*US Army*)

9:10-9:20 Paper #29: C2HI: Towards a Command and Control Hierarchical Interface for Human-Robot Teams in Dynamic Social Environments

John A. Duncan (*University of Texas at Austin, TX, USA*)

Farshid Alambeigi (*University of Texas at Austin, TX, USA*)

Mitchell W. Pryor (*University of Texas at Austin, TX, USA*)

9:20-9:30 Paper #48: Human Systems Integration for Human Machine Integrated Formations

Elizabeth Mezzacappa (*US Army*)

Dominic T. Cheng (*US Army*)

Alexis M. Cady (*US Army*)

Florence Chua (*US Army*)

9:30-9:40 Paper #10: Digital Twin Synchronization: Bridging the Sim-RL Agent to a Real-Time Robotic Additive Manufacturing Control

Matsive Ali (*University of Louisiana at Lafayette, LA, USA*)

Sandesh Giri (*University of Louisiana at Lafayette, LA, USA*)

Sen Liu (*Bradley University, IL, USA*)

Qin Yang (*Bradley University, IL, USA*)

9:40-9:50 Paper #32: RailGoerl24: Görlitz Rail Test Center CV Dataset 2024

Rustam Tagiew (*German Centre for Rail Traffic Research at the Federal Railway Authority (DZSF), Dresden, Germany*)

Ilkay Wunderlich (*EYYES GmbH, Gedersdorf, Austria*)

Mark Sastuba (*German Centre for Rail Traffic Research at the Federal Railway Authority (DZSF), Dresden, Germany*)

Kilian Göller (*Dresden University of Technology, Germany*)

Steffen Seitz (*Dresden University of Technology, Germany*)

10:00-11:15 **Technical Session 4: Session on Evaluation of Reliable Autonomous Systems** [Oral Presentations] (Session Chair: Paul Stankiewicz, *Johns Hopkins Applied Physics Laboratory, MD, USA*) [Odeum – Room 341-343] [\[ZOOM LINK\]](#)

10:00-10:15 Paper #09: Diffusion-Based Failure Sampling for Evaluating Safety-Critical Autonomous Systems

Harrison Delecki (*Stanford University, CA, USA*)

Marc R. Schlichting (*Stanford University, CA, USA*)

Mansur Arief (*Stanford University, CA, USA*)

Anthony Corso (*Stanford University, CA, USA*)

Marcell Vazquez-Chanlatte (*Nissan Advanced Technology Center Silicon Valley, CA, USA*)

Mykel J. Kochenderfer (*Stanford University, CA, USA*)

10:15-10:30 Paper #54: Automation Testing Framework for Reliable Autonomous Agentic AI

Grant Martin (*University of the West Scotland, UK*)

Joanna Olszewska (*University of the West Scotland, UK*)

10:30-10:45 Paper #38: Democracy Saves Robot: Crowd Voting Dramatically Outperforms Individual Judgments at Validating System Specifications

Ho Chit Siu (*MIT – Massachusetts Institute of Technology, MA, USA*)

Isabelle Hurley (*MIT – Massachusetts Institute of Technology, MA, USA*)

Rohan Paleja (*MIT – Massachusetts Institute of Technology, MA, USA*)

Ashley Suh (*MIT – Massachusetts Institute of Technology, MA, USA*)

Jaime D. Peña (*MIT – Massachusetts Institute of Technology, MA, USA*)

10:45-11:00 Paper #33: Towards Systematic Maintenance of Assurance for Evolving Self-Adaptive Systems

Logan Murphy (*University of Toronto, Canada*)

Marc Carwehr (*Humboldt Universität zu Berlin, Germany*)

Juliane Päßler (*University of Oslo, Norway*)

Marsha Chechik (*University of Toronto, Canada*)

11:00-11:15 Paper #42: Conduct Governance Assurance - An Architecture Implementation for High-Risk Autonomous Systems

Andrew Schellenberg (*Carnegie Mellon University, PA, USA*)

Emily Newman (*Carnegie Mellon University, PA, USA*)

Charles Loughlin (*Carnegie Mellon University, PA, USA*)

Tyler Brooks (*Carnegie Mellon University, PA, USA*)

11:15-11:30 **Coffee Break** [*Mid-Century Room – Room 331*]

11:30-12:15 **Technical Session 5: Session on Reliable Human-Robot Teaming** [Oral Presentations] (Session Chair: Ho Chit Siu, *MIT – Massachusetts Institute of Technology, MA, USA*) [*Odeum – Room 341-343*] [[ZOOM LINK](#)]

11:30-11:45 Paper #06: Robot Competency Self-Assessments for Assured Mission Management in Uncertain Environments

Nicholas Conlon (*University of Colorado Boulder, CO, USA*)

Nisar R. Ahmed (*University of Colorado Boulder, CO, USA*)

Daniel Szafrir (*University of North Carolina Chapel Hill, NC, USA*)

11:45-12:00 Paper #45: Maximizing Reputation for Serving Time-Constrained Tasks with Distributed Heterogeneous Teams

Mela Coffey (*Boston University, MA, USA*)

Arnav Chaudhry (*Boston University, MA, USA*)

Alyssa Pierson (*Boston University, MA, USA*)

12:00-12:15 Paper #19: Explainability Pattern Specifications for Human-Robot Teamwork

Hazel M. Taylor (*University of Manchester, UK*)

Anastasia Mavridou (*KBR Inc. / NASA Ames Research Center, CA, USA*)

Marie Farrell (*University of Manchester, UK*)

Louise A. Dennis (*University of Manchester, UK*)

12:15-13:30 **Lunch** [*Mid-Century Room – Room 331*]

13:30-14:30 **Plenary Talk 3** (Session Chair: Jeffrey W. Herrmann, *The Catholic University of America, Washington, D.C., USA*) [*Odeum – Room 341-343*] [[ZOOM LINK](#)]

Title: **Towards Verified Visual Autonomy: Perception Contracts and Abstract Rendering**

Speaker: **Sayan Mitra** (*University of Illinois Urbana-Champaign, IL, USA*)

**14:30-16:30 Technical Session 6b: Session on Challenges in Engineering Reliable Autonomous Systems (II)** [On-site Poster Presentations] (Session Chair: Ivan Ruchkin, *University of Florida, FL, USA*) [Lobby outside the *Odeum*]

14:30-16:30 Paper #40: Look What You Made Me Do: Formal Methods and the Verification-Validation Gap in System Assurance

Ho Chit Siu (*MIT – Massachusetts Institute of Technology, MA, USA*)

Kevin J. Leahy (*WPI - Worcester Polytechnic Institute, MA, USA*)

Jaime D. Peña (*MIT – Massachusetts Institute of Technology, MA, USA*)

Zachary Serlin (*MIT – Massachusetts Institute of Technology, MA, USA*)

14:30-16:30 Paper #23: Consistency Measurement as a Means to Enhance Reliability in Autonomous Systems

Pragati Satpute (*Cambridge, MA, USA*)

14:30-16:30 Paper #17: Neuroimaging and Physiological Data-driven Autonomous Vehicle Driving Simulation System in Extended Reality

Curt Lynch (*University of Tennessee at Martin, TN, USA*)

Kyle Byassee (*University of Tennessee at Martin, TN, USA*)

Isaac Copeland (*University of Tennessee at Martin, TN, USA*)

Seth Hatchett (*University of Tennessee at Martin, TN, USA*)

Saman Sargolzaei (*University of Tennessee at Martin, TN, USA*)

14:30-16:30 Paper #53: A Framework for Filtering Neural Network Predictions for Robust State Estimation

Rohan Walia (*WPI - Worcester Polytechnic Institute, MA, USA*)

Kevin Leahy (*WPI - Worcester Polytechnic Institute, MA, USA*)

14:30-16:30 Paper #34: Artificial Intelligence on the Edge for Enabling Reliable Affordable Mass

Kin Gwn Lore (*RTX Technology Research Center, CT, USA*)

James P. Wilson (*RTX Technology Research Center, CT, USA*)

Subramanya Nagesh Rao (*RTX Technology Research Center, CT, USA*)

Gerald Wang (*RTX Technology Research Center, CT, USA*)

Timothy E. Wang (*RTX Technology Research Center, CT, USA*)

Mark Moulin (*RTX Technology Research Center, CT, USA*)

Amit Bhatia (*RTX Technology Research Center, CT, USA*)

Francesca Stramandinoli (*RTX Technology Research Center, CT, USA*)

15:30-16:00 **Coffee Break** [*Mid-Century Room* – Room 331]

**14:30-16:30 Workshop – SAFE** [*Odeum* – Room 341-343] [[ZOOM LINK](#)]

Title: **SAFE-Robotics: Safe, Assured, Formal methods-Enabled Robotics**

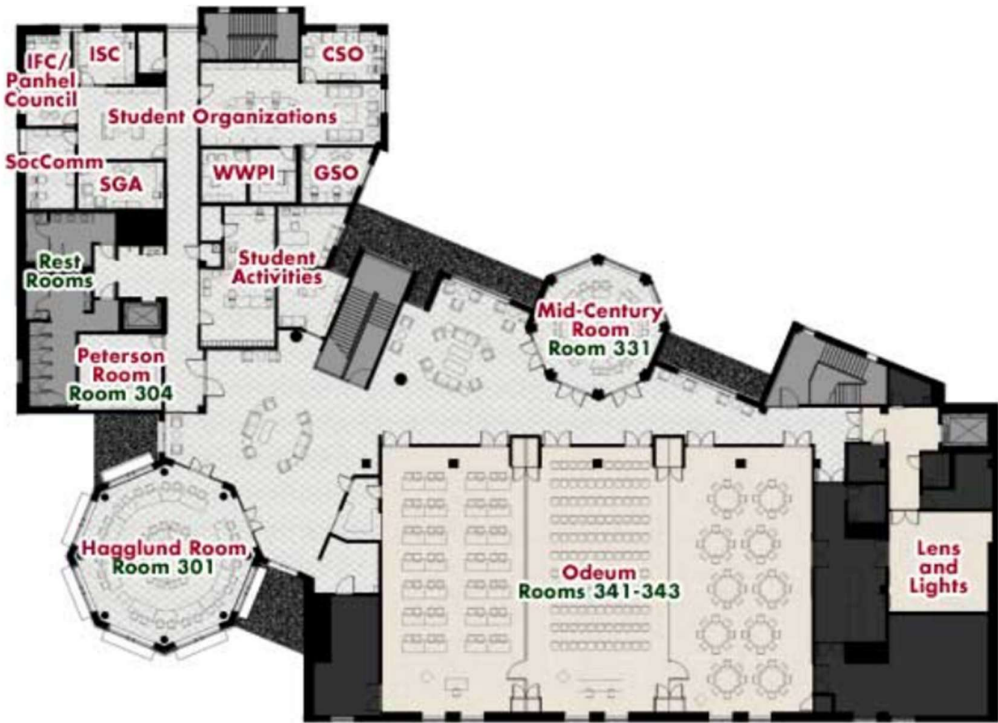
Main Organizer: **Amy Fang** (*MIT – Massachusetts Institute of Technology, MA, USA*)

URL: <https://sites.mit.edu/saferobotics/>

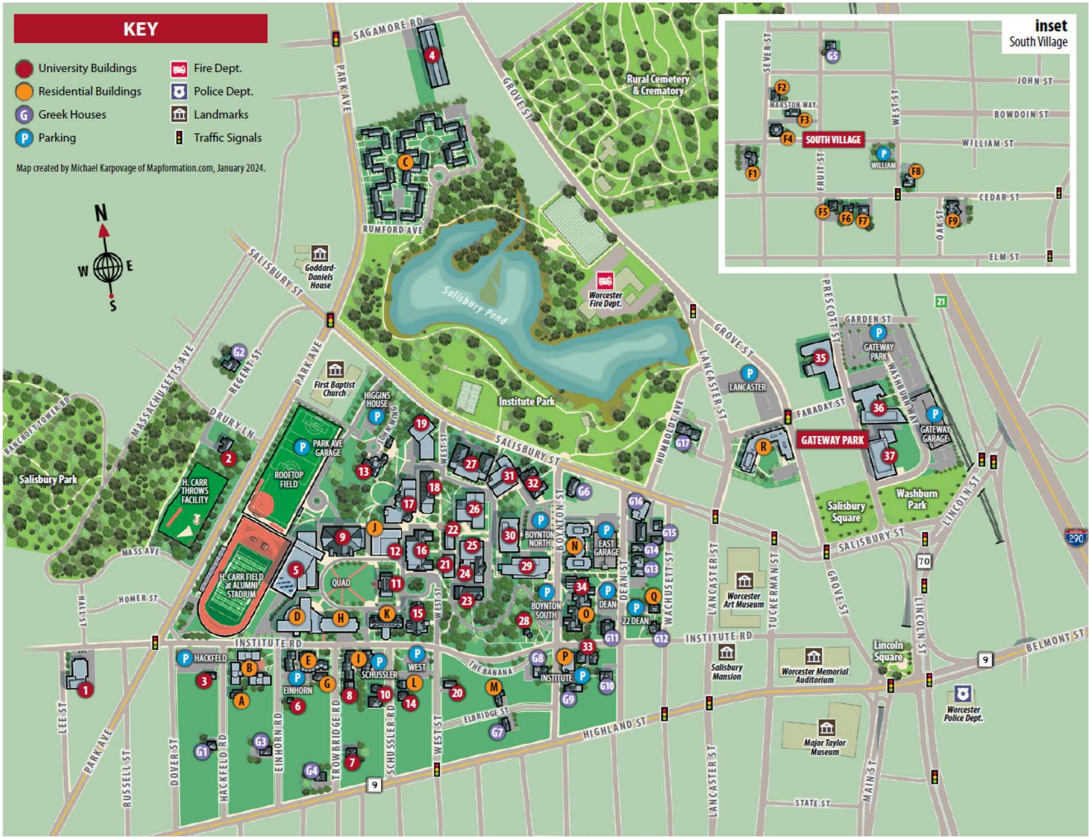
16:30-16:45 **Farewell Gathering** [*Mid-Century Room* – Room 331] [[ZOOM LINK](#)]

16:45-17:00 **Closing Session** [*Odeum* – Room 341-343] [[ZOOM LINK](#)]

Conference Venue – Building Floor Plan



Conference Venue – Campus Map



UNIVERSITY BUILDINGS		RESIDENTIAL BUILDINGS	GREEK HOUSES
1 Facilities Department (37 Lee Street)	20 157 West Street	A Hackfeld House	G1 Alpha Xi Delta
2 1 Drury Lane	21 Stratton Hall	B Stoddard Complex	G2 Alpha Tau Omega
3 27 Hackfeld Road	22 Laurie A. Leshin Global Project Center	C WPI Townhouses	G3 Alpha Phi
4 15 Sagamore Road	23 Boynton Hall	D Morgan Hall	G4 Alpha Gamma Delta
5 Sports & Recreation Center	24 Power House	E Ellsworth Apartments	G5 Beta Theta Pi
6 16 Einhorn Road	25 Washburn Shops/Stoddard Laboratories	F1 Sever House	G6 Phi Gamma Delta
7 20 Trowbridge Road	26 Salisbury Laboratories	F2 Marston House A	G7 Phi Sigma Sigma
8 28 Trowbridge Road	27 Atwater Kent Laboratories	F3 Marston House B	G8 Sigma Phi Epsilon
9 Harrington Auditorium	28 Skull Tomb	F4 William House	G9 Alpha Chi Rho
10 15-19 Schussler Road	29 Unity Hall	F5 Fruit House	G10 Phi Sigma Kappa
11 Bartlett Center	30 Gordon Library	F6 Cedar House B	G11 Sigma Pi
12 Innovation Studio	31 Fuller Laboratories	F7 Cedar House A	G12 Phi Kappa Theta
13 Higgins House	32 Kaven Hall	F8 West House	G13 Lambda Chi Alpha
14 20 Schussler Road	33 35/37 Institute Road	F9 Oak House	G14 Zeta Psi
15 Alden Memorial	34 Campus Police	G Trowbridge House	G15 Tau Kappa Epsilon
16 Higgins Laboratories	35 Gateway Park (85 Prescott Street)	H Daniels Hall	G16 Theta Chi
17 Rubin Campus Center	36 Gateway Park I (60 Prescott Street)	I Fuller Apartments	G17 Sigma Alpha Epsilon
18 Olin Hall	37 Gateway Park II (50 Prescott Street)	J Messenger Hall	
19 Goddard Hall		K Sanford Riley Hall	
		L Schussler House	
		M Elbridge House	
		N East Hall	
		O Founders Hall	
		P Institute Hall	
		Q Wachusett House	
		R Faraday Hall	

6.2024



100 Institute Road  
Worcester, MA, 01609  
GPS Address (Parking Garage):  
151 Salisbury Street



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