IEEE International Conference on Engineering Reliable Autonomous Systems (ERAS 2025)

29-30 May 2025, Worcester, MA, USA

Technical Program

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Kevin Leahy *(WPI - Worcester Polytechnic Institute, MA, USA)*

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Zachary Serlin *(MIT – Massachusetts Institute of Technology, MA, USA)*

Zvikomborero Murahwi *(Gratia ICT, Australia)*

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ERAS 2025⁺ Program At A Glance

Local time	Thursday 29th May, 2025	Friday 30th May, 2025	
8:30-8:45	Registration Desk (& Breakfast)	Registration Desk (& Breakfast)	
8:45-9:00			
9:00-9:15	Opening Session	Poster Session 1 (Online)	
9:15-9:30	Keynote Talk 1	Challenges in Engineering Reliable Autonomous Systems I	
9:30-9:45	Reliable Robotics Research at the Robotics and AI Institute		
9:45-10:00	Ben Axelrod (Boston Dynamics, MA, USA)		
10:00-10:15		Technical Session 4 on	
10:15-10:30	Technical Session 1 on	Evaluation of Reliable Autonomous Systems	
10:30-10:45	Design of Reliable Autonomous Systems		
10:45-11:00			
11:00-11:15			
11:15-11:30	Coffee Break	Coffee Break	
11:30-11:45	Technical Session 2 on	Technical Session 5 on	
11:45-12:00	Reliable Autonomous Vehicles	Reliable Human-Robot Teaming	
12:00-12:15			
12:15-12:30	Lunch	Lunch	
12:30-12:45			
12:45-13:00			
13:00-13:15			
13:15-13:30			
13.30-13:45	Keynote Talk 2	Keynote Talk 3	Workshop - SAFE
13:45-14:00	Contributions to Assurance from Basic and Applied Research	Towards Verified Visual Autonomy	Main Organizer:
14:00-14:15	Craig Lennon (US Army)	Sayan Mitra (UIUC, IL, USA)	Amy Fang
14:15-14:30			(MIT, MA, USA)
14:30-14:45	Technical Session 3 on	Poster Session 2 (On-site)	
14:45-15:00	Reliable Vision Autonomous Systems	Challenges in Engineering Reliable Autonomous Systems II	
15:00-15:15			
15:15-15:30			
15:30-15:45	Coffee Break	Coffee Break	
15:45-16:00			
16:00-16:15	Tutorial - HEART		
16:15-16:30	Main Organizer:		
16:30-16:45	Jordan Fischer	Farewell Gathering	
16:45-17:00	(IBM, USA)	Closing Session	
17:00-17:15	Welcome Gathering		
17:15-17:30			
17:30-17:45			
17:45-18:00			
18:00-18:15	Banquet		
18:15-18:30			
18:30-18:45			
18:45-19:00			
19:00-19:15			
19:15-19:30			
19:30-19:45			
19:45-20:00			
20:00-20:15			
20:15-20:30			
20:30-20:45			
20:45-21:00			

All times are provided in the local time (EDT, UTC-4) of the venue (Worcester, MA, USA).

As part of the Accessibility Policy, ERAS 2025 conference is fully hybrid.

⁺ The 2025 IEEE International Conference on Engineering Reliable Autonomous Systems (ERAS 2025) is technically sponsored by IEEE and IEEE Robotics and Automation Society and supported by IEEE RAS Technical Committees, as follows: IEEE TC PEBRAS – Performance Evaluation and Benchmarking of Robotic and Automation Systems, IEEE TC-SOFT – Software Engineering for Robotics and Automation, and IEEE TC VAS – Verification of Autonomous Systems.

8:30-9:00 **Registration Desk & Breakfast**

9:00-9:15 **Opening Session** [*Odeum* – Room 341-343] [ZOOM LINK]

9:15-10:15 **Plenary Talk 1** (Session Chair: Kevin Leahy, *WPI - Worcester Polytechnic Institute, MA, USA*) [*Odeum* – Room 341-343] [ZOOM LINK]

Title: **Reliable Robotics Research at the Robotics and AI Institute**

Speaker: **Ben Axelrod *(Boston Dynamics, MA, USA)***

10:15-11:15 **Technical Session 1: Session on Design of Reliable Autonomous Systems** [Oral Presentations] (Session Chair: Marsha Chechik, *University of Toronto, Canada)* [*Odeum* – Room 341-343] [ZOOM LINK]

10:15-10:30 Paper #16: Skill-Based Architectures in Autonomous Systems: An Empirical Study

Pierre Malafosse *(LAAS-CNRS, Université de Toulouse, France)*

Alexandre Albore *(ONERA The French Aerospace Lab, France)*

Jérémie Guiochet *(LAAS-CNRS, Université de Toulouse, France)*

Charles Lesire *(ONERA The French Aerospace Lab, France)*

10:30-10:45 Paper #31: Reliable Robot Missions in Dynamic Environments Using Agent-based Controllers

Raynaldio Limarga *(University of Manchester, UK)*

Kwai Wa Tse *(University of Manchester, UK)*

Louise A. Dennis *(University of Manchester, UK)*

Clare Dixon *(University of Manchester, UK)*

Fatma Faruq *(University of Manchester, UK)*

Michael Fisher *(University of Manchester, UK)*

10:45-11:00 Paper #44: From Developer Needs to Domain-Specific Languages: Specifying Sceneries for Simulation-Based Validation of Mobile Robots

Argentina Ortega *(University of Bremen, Germany)*

Samuel Parra *(Hochschule Bonn-Rhein-Sieg, Germany)*

Sven Schneider *(KU Leuven, Belgium)*

Nico Hochgeschwender *(University of Bremen, Germany)*

11:00-11:15 Paper #02: Automatic Tuning of Autonomous System Design Parameters for Performance Robustness

Paul Stankiewicz *(Johns Hopkins Applied Physics Laboratory, MD, USA)*

Jordan Appler *(Johns Hopkins Applied Physics Laboratory, MD, USA)*

11:15-11:30 **Coffee Break** [*Mid-Century Room* – Room 331]

11:30-12:15 **Technical Session 2: Session on Reliable Autonomous Vehicles** [Oral Presentations] (Session Chair: TBC) [*Odeum* – Room 341-343] [ZOOM LINK]

11:30-11:45 Paper #46: Advancing Autonomous Vehicle Safety: A Combined Fault Tree Analysis and Bayesian Network Approach

Lansu Dai *(University of Ottawa, Canada)*

Burak Kantarci *(University of Ottawa, Canada)*

11:45-12:00 Paper #43: Autonomous Robotic Swarms: A Corroborative Approach for Verification and Validation

Dhaminda B. Abeywickrama *(University of Manchester, UK)*

Suet Lee *(University of Bristol, UK)*

Chris Bennett *(University of Bristol, UK)*

Razanne Abu-Aisheh *(University of Bristol, UK)*

Tom Didiot-Cook *(University of Bristol, UK)*

Simon Jones *(University of Bristol, UK)*

Sabine Hauert *(University of Bristol, UK)*

Kerstin Eder *(University of Bristol, UK)*

12:00-12:15 Paper #20: Towards a Resilient Framework for Multirotor UAVs: Autonomous Adaptation to Failures and Disturbances

Luis Hector Manjarrez Muñoz (Center for Research and Advanced Studies of the National Polytechnic Institute, Mexico City, Mexico)

Eduardo Steed Espinoza Quesada *(Mexican Secretariat of Science, Humanities, Technology and Innovation, Mexico City, Mexico)*

Luis Rodolfo Garcia Carrillo *(New Mexico State University, NM, USA)*

12:15-13:30 **Lunch** [*Mid-Century Room* – Room 331]

13:30-14:30 **Plenary Talk 2** (Session Chair: TBC) [*Odeum* – Room 341-343] [ZOOM LINK]

Title: **Contributions to Assurance from Basic and Applied Research**

Speaker: **Craig Lennon** *(US Army)*

14:30-15:30 **Technical Session 3: Session on Reliable Vision Autonomous Systems** [Oral Presentations] (Session Chair: Joanna Olszewska, *University of the West of Scotland, UK*) [*Odeum –* Room 341-343] [ZOOM LINK]

14:30-14:45 Paper #08: Arguing Reliability of Machine Learning-based Components

Boyue Caroline Hu *(University of Toronto, Canada)*

Alessio Di Sandro *(University of Toronto, Canada)*

Lina Marsso *(University of Toronto, Canada)*

Krzysztof Czarnecki *(University of Waterloo, Canada)*

Marsha Chechik *(University of Toronto, Canada)*

14:45-15:00 Paper #26: Monitoring Safety Properties for Autonomous Driving Systems with Vision-Language Models

Felipe Toledo *(University of Virginia, VA, USA)*

Sebastian Elbaum *(University of Virginia, VA, USA)*

Divya Gopinath *(KBR Inc. / NASA Ames Research Center, CA, USA)*

Ramneet Kaur *(SRI, CA, USA)*

Ravi Mangal *(Colorado State University, CO, USA)*

Corina S. Păsăreanu *(KBR, NASA Ames Research Centre, CA, USA)*

Anirban Roy *(SRI, CA, USA)*

Susmit Jha *(SRI, CA, USA)*

15:00-15:15 Paper #11: NeRF-To-Real Tester: Neural Radiance Fields as Test Image Generators for Vision of Autonomous Systems

Laura Weihl *(IT University of Copenhagen, Danmark)*

Bilal Wehbe *(Robotics Innovation Centre, DFKI, Bremen, Germany)*

Andrzej Wąsowski *(IT University of Copenhagen, Danmark)*

15:15-15:30 Paper #39: Why Good Detectors Can Make Bad Trackers: mAP Worse than Random Chance at Model Selection

Trenton Tabor *(Carnegie Mellon University, PA, USA)*

Tomasz Swierzewski *(Carnegie Mellon University, PA, USA)*

Casidhe Hutchison *(Carnegie Mellon University, PA, USA)*

Oren Wright *(Carnegie Mellon University, PA, USA)*

Eric Heim *(Carnegie Mellon University, PA, USA)*

Christopher S. Timperley *(Carnegie Mellon University, PA, USA)*

15:30-16:00 **Coffee Break** [*Mid-Century Room* – Room 331]

16:00-17:00 **Tutorial** [*Odeum* – Room 341-343] [ZOOM LINK]

Title: **HEART - Hardened Extension of the Adversarial Robustness Toolbox (HEART): Evaluating and Hardening AI Models against Novel Attack Vectors**

Speaker: **Jordan Fischer** *(IBM, USA)*

17:00-18:00 **Welcome Gathering** [*Mid-Century Room* – Room 331] [ZOOM LINK]

18:00-21:00 **Banquet** [*Higgins House* – Building 13]

8:30-9:00 **Registration Desk & Breakfast**

9:00-10:00 **Technical Session 6a: Session on Challenges in Engineering Reliable Autonomous Systems (I)** [Online Poster Presentations] (Session Chair: TBC) [*Odeum* – Room 341-343] [ZOOM LINK]

9:00-9:10 Paper #30: Defining and Designing Reliable AI-Enabled and Autonomous Systems

Benjamin D. Werner *(US Army)*

Benjamin J. Schumeg *(US Army)*

Shawn P. Brady *(US Army)*

Nathan W. Herbert *(US Army)*

James J. Foerster *(US Army)*

9:10-9:20 Paper #29: C2HI: Towards a Command and Control Hierarchical Interface for Human-Robot Teams in Dynamic Social Environments

John A. Duncan *(University of Texas at Austin, TX, USA)*

Farshid Alambeigi *(University of Texas at Austin, TX, USA)*

Mitchell W. Pryor *(University of Texas at Austin, TX, USA)*

9:20-9:30 Paper #48: Human Systems Integration for Human Machine Integrated Formations

Elizabeth Mezzacappa *(US Army)*

Dominic T. Cheng *(US Army)*

Alexis M. Cady *(US Army)*

Florence Chua *(US Army)*

9:30-9:40 Paper #10: Digital Twin Synchronization: Bridging the Sim-RL Agent to a Real-Time Robotic Additive Manufacturing Control

Matsive Ali *(University of Louisiana at Lafayette, LA, USA)*

Sandesh Giri *(University of Louisiana at Lafayette, LA, USA)*

Sen Liu *(Bradley University, IL, USA)*

Qin Yang *(Bradley University, IL, USA)*

9:40-9:50 Paper #32: RailGoerl24: Görlitz Rail Test Center CV Dataset 2024

Rustam Tagiew *(German Centre for Rail Traffic Research at the Federal Railway Authority (DZSF), Dresden, Germany)*

Ilkay Wunderlich *(EYYES GmbH, Gedersdorf, Austria)*

Mark Sastuba *(German Centre for Rail Traffic Research at the Federal Railway Authority (DZSF), Dresden, Germany)*

Kilian Göller *(Dresden University of Technology, Germany)*

Steffen Seitz *(Dresden University of Technology, Germany)*

10:00-11:15 **Technical Session 4: Session on Evaluation of Reliable Autonomous Systems** [Oral Presentations] (Session Chair: TBC) [*Odeum* – Room 341-343] [ZOOM LINK]

10:00-10:15 Paper #09: Diffusion-Based Failure Sampling for Evaluating Safety-Critical Autonomous Systems

Harrison Delecki *(Standford University, CA, USA)*

Marc R. Schlichting *(Standford University, CA, USA)*

Mansur Arief *(Standford University, CA, USA)*

Anthony Corso *(Standford University, CA, USA)*

Marcell Vazquez-Chanlatte *(Nissan Advanced Technology Center Silicon Valley, CA, USA)*

Mykel J. Kochenderfer *(Standford University, CA, USA)*

10:15-10:30 Paper #54: Automation Testing Framework for Reliable Autonomous Agentic AI

Grant Martin *(University of the West Scotland, UK)*

Joanna Olszewska *(University of the West Scotland, UK)*

10:30-10:45 Paper #38: Democracy Saves Robot: Crowd Voting Dramatically Outperforms Individual Judgments at Validating System Specifications

Ho Chit Siu *(MIT – Massachusetts Institute of Technology, MA, USA)*

Isabelle Hurley *(MIT – Massachusetts Institute of Technology, MA, USA)*

Rohan Paleja *(MIT – Massachusetts Institute of Technology, MA, USA)*

Ashley Suh *(MIT – Massachusetts Institute of Technology, MA, USA)*

Jaime D. Peña *(MIT – Massachusetts Institute of Technology, MA, USA)*

10:45-11:00 Paper #33: Towards Systematic Maintenance of Assurance for Evolving Self-Adaptive Systems

Logan Murphy *(University of Toronto, Canada)*

Marc Carwehl *(Humboldt Universität zu Berlin, Germany)*

Juliane Päßler *(University of Oslo, Norway)*

Marsha Chechik *(University of Toronto, Canada)*

11:00-11:15 Paper #42: Conduct Governance Assurance - An Architecture Implementation for High-Risk Autonomous Systems

Andrew Schellenberg *(Carnegie Mellon University, PA, USA)*

Emily Newman *(Carnegie Mellon University, PA, USA)*

Charles Loughlin *(Carnegie Mellon University, PA, USA)*

Tyler Brooks *(Carnegie Mellon University, PA, USA)*

11:15-11:30 **Coffee Break** [*Mid-Century Room* – Room 331]

11:30-12:15 **Technical Session 5: Session on Reliable Human-Robot Teaming** [Oral Presentations] (Session Chair: Ho Chit Siu, *MIT – Massachusetts Institute of Technology, MA, USA*) [*Odeum* – Room 341-343] [ZOOM LINK]

11:30-11:45 Paper #06: Robot Competency Self-Assessments for Assured Mission Management in Uncertain Environments

Nicholas Conlon *(University of Colorado Boulder, CO, USA)*

Nisar R. Ahmed *(University of Colorado Boulder, CO, USA)*

Daniel Szafir *(University of North Carolina Chapel Hill, NC, USA)*

11:45-12:00 Paper #45: Maximizing Reputation for Serving Time-Constrained Tasks with Distributed Heterogeneous Teams

Mela Coffey *(Boston University, MA, USA)*

Arnav Chaudhry *(Boston University, MA, USA)*

Alyssa Pierson *(Boston University, MA, USA)*

12:00-12:15 Paper #19: Explainability Pattern Specifications for Human-Robot Teamwork

Hazel M. Taylor *(University of Manchester, UK)*

Anastasia Mavridou *(KBR Inc. / NASA Ames Research Center, CA, USA)*

Marie Farrell *(University of Manchester, UK)*

Louise A. Dennis *(University of Manchester, UK)*

12:15-13:30 **Lunch** [*Mid-Century Room* – Room 331]

13:30-14:30 **Plenary Talk 3** (Session Chair: Jeffrey W. Herrmann, *The Catholic University of America, Washington, D.C., USA*) [*Odeum* – Room 341-343] [ZOOM LINK]

Title: **Towards Verified Visual Autonomy: Perception Contracts and Abstract Rendering**

Speaker: **Sayan Mitra *(University of Illinois Urbana-Champaign, IL, USA)***

14:30-16:30 **Technical Session 6b: Session on Challenges in Engineering Reliable Autonomous Systems (II)** [On-site Poster Presentations] (Session Chair: Ivan Ruchkin, *University of Florida, FL, USA*) [Lobby outside the *Odeum*]

14:30-16:30 Paper #40: Look What You Made Me Do: Formal Methods and the Verification-Validation Gap in System Assurance

Ho Chit Siu *(MIT – Massachusetts Institute of Technology, MA, USA)*

Kevin J. Leahy *(WPI - Worcester Polytechnic Institute, MA, USA)*

Jaime D. Peña *(MIT – Massachusetts Institute of Technology, MA, USA)*

Zachary Serlin *(MIT – Massachusetts Institute of Technology, MA, USA)*

14:30-16:30 Paper #23: Consistency Measurement as a Means to Enhance Reliability in Autonomous Systems

Pragati Satpute *(Cambridge, MA, USA)*

14:30-16:30 Paper #17: Neuroimaging and Physiological Data-driven Autonomous Vehicle Driving Simulation System in Extended Reality

Curt Lynch *(University of Tennessee at Martin, TN, USA)*

Kyle Byassee *(University of Tennessee at Martin, TN, USA)*

Isaac Copeland *(University of Tennessee at Martin, TN, USA)*

Seth Hatchett *(University of Tennessee at Martin, TN, USA)*

Saman Sargolzaei *(University of Tennessee at Martin, TN, USA)*

14:30-16:30 Paper #53: A Framework for Filtering Neural Network Predictions for Robust State Estimation

Rohan Walia *(WPI - Worcester Polytechnic Institute, MA, USA)*

Kevin Leahy *(WPI - Worcester Polytechnic Institute, MA, USA)*

14:30-16:30 Paper #34: Artificial Intelligence on the Edge for Enabling Reliable Affordable Mass

Kin Gwn Lore *(RTX Technology Research Center, CT, USA)*

James P. Wilson *(RTX Technology Research Center, CT, USA)*

Subramanya Nageshrao *(RTX Technology Research Center, CT, USA)*

Gerald Wang *(RTX Technology Research Center, CT, USA)*

Timothy E. Wang *(RTX Technology Research Center, CT, USA)*

Mark Moulin *(RTX Technology Research Center, CT, USA)*

Amit Bhatia *(RTX Technology Research Center, CT, USA)*

Francesca Stramandinoli *(RTX Technology Research Center, CT, USA)*

15:30-16:00 **Coffee Break** [*Mid-Century Room* – Room 331]

13:30-16:30 Workshop – SAFE [*Odeum* – Room 341-343] [ZOOM LINK]

Title: **SAFE-Robotics: Safe, Assured, Formal methods-Enabled Robotics**

Main Organizer: **Amy Fang** *(MIT – Massachusetts Institute of Technology, MA, USA)*
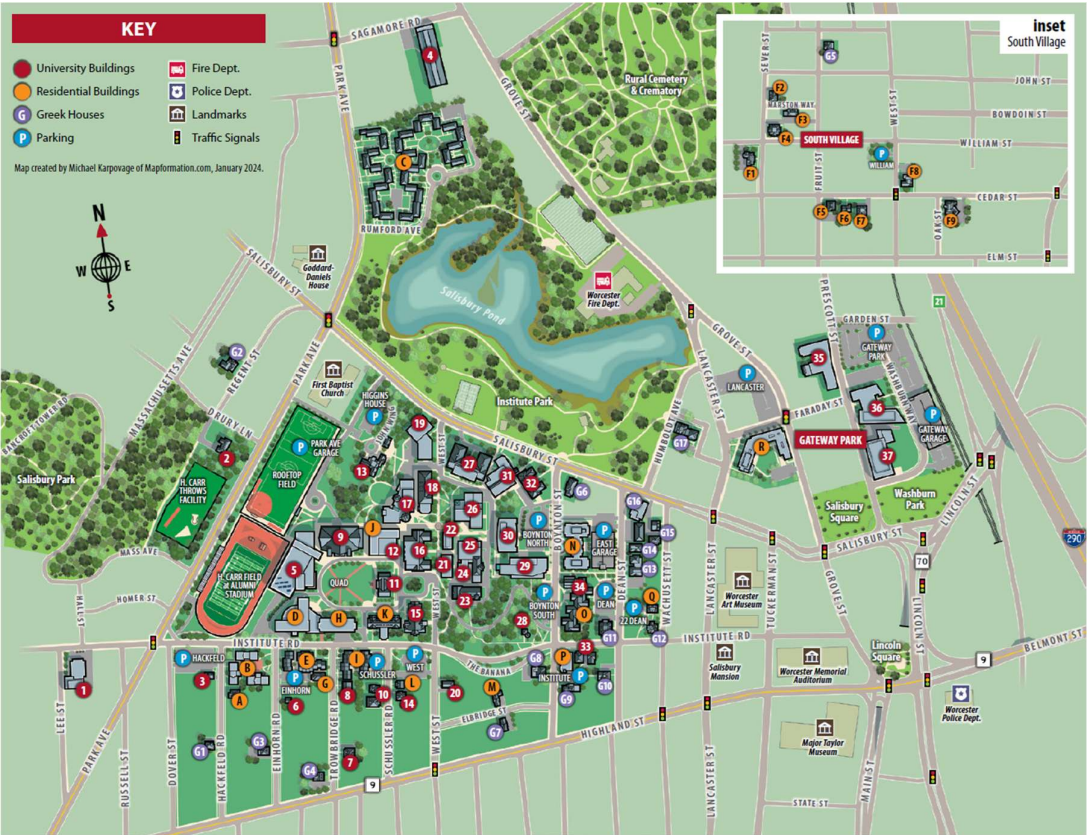
URL: https://sites.mit.edu/saferobotics/

16:30-16:45 **Farewell Gathering** [*Mid-Century Room* – Room 331] [ZOOM LINK]

16:45-17:00 **Closing Session** [*Odeum* – Room 341-343] [ZOOM LINK]

Conference Venue – Building Floor Plan

Conference Venue – Campus Map

KEY

- ● University Buildings
- ● Residential Buildings
- G Greek Houses
- P Parking
- ▮ Fire Dept.
- ▮ Police Dept.
- ▮ Landmarks
- ▮ Traffic Signals

Map created by Michael Karpovage of Mapformation.com, January 2024.

inset
South Village

UNIVERSITY BUILDINGS		
1	Facilities Department (37 Lee Street)	
2	1 Drury Lane	
3	27 Hackfeld Road	
4	15 Sagamore Road	
5	Sports & Recreation Center	
6	16 Einhorn Road	
7	20 Trowbridge Road	
8	28 Trowbridge Road	
9	Harrington Auditorium	
10	15–19 Schussler Road	
11	Bartlett Center	
12	Innovation Studio	
13	Higgins House	
14	20 Schussler Road	
15	Alden Memorial	
16	Higgins Laboratories	
17	Rubin Campus Center	
18	Olin Hall	
19	Goddard Hall	
20	157 West Street	
21	Stratton Hall	
22	Laurie A. Leshin Global Project Center	
23	Boynton Hall	
24	Power House	
25	Washburn Shops/Stoddard Laboratories	
26	Salisbury Laboratories	
27	Atwater Kent Laboratories	
28	Skull Tomb	
29	Unity Hall	
30	Gordon Library	
31	Fuller Laboratories	
32	Kaven Hall	
33	35/37 Institute Road	
34	Campus Police	
35	Gateway Park (85 Prescott Street)	
36	Gateway Park I (60 Prescott Street)	
37	Gateway Park II (50 Prescott Street)	

RESIDENTIAL BUILDINGS	
A	Hackfeld House
B	Stoddard Complex
C	WPI Townhouses
D	Morgan Hall
E	Ellsworth Apartments
F1	Sever House
F2	Marston House A
F3	Marston House B
F4	William House
F5	Fruit House
F6	Cedar House B
F7	Cedar House A
F8	West House
F9	Oak House
G	Trowbridge House
H	Daniels Hall
I	Fuller Apartments
J	Messenger Hall
K	Sanford Riley Hall
L	Schussler House
M	Elbridge House
N	East Hall
O	Founders Hall
P	Institute Hall
Q	Wachusett House
R	Faraday Hall

GREEK HOUSES	
G1	Alpha Xi Delta
G2	Alpha Tau Omega
G3	Alpha Phi
G4	Alpha Gamma Delta
G5	Beta Theta Pi
G6	Phi Gamma Delta
G7	Phi Sigma Sigma
G8	Sigma Phi Epsilon
G9	Alpha Chi Rho
G10	Phi Sigma Kappa
G11	Sigma Pi
G12	Phi Kappa Theta
G13	Lambda Chi Alpha
G14	Zeta Psi
G15	Tau Kappa Epsilon
G16	Theta Chi
G17	Sigma Alpha Epsilon

6.2024

WPI

100 Institute Road
Worcester, MA, 01609

GPS Address (Parking Garage):
151 Salisbury Street

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Scan QR code or visit **maps.wpi.edu** for interactive map.