



In [3]:

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# quantitative modeling of infectious disease dynamics
# dynamics are modeled using a standard SEIR
# (Susceptible-Exposed-Infected-Removed) model of disease spread
# The states are: susceptible (S), exposed (E), infected (I) and removed (R).
#  $\theta(t)$  is called the transmission rate or effective contact rate
# (the rate at which individuals bump into others and expose them to the virus).
#  $\sigma$  is called the infection rate (the rate at which those who are exposed become infected)
#  $\gamma$  is called the recovery rate (the rate at which infected people recover or die)
# https://julia.quantecon.org/continuous\_time/seir\_model.html

import matplotlib.animation as animation
from scipy.integrate import odeint
from numpy import arange
from pylab import *

def CovidSystem(state, t):
    s, e, i, r = state
     $\gamma = 1/18$ 
     $R_0 = 3.0$  # basic reproduction number for the SEIR model
     $\sigma = 1/5.2$ 

    d_s =  $-\gamma R_0 s i$  #  $ds/dt = -\gamma R_0 s i$ 
    d_e =  $\gamma R_0 s i - \sigma e$  #  $de/dt = \gamma R_0 s i - \sigma e$ 
    d_i =  $\sigma e - \gamma i$  #  $di/dt = \sigma e - \gamma i$ 
    d_r =  $\gamma i$  #  $dr/dt = \gamma i$ 

    return [d_s, d_e, d_i, d_r]

t = arange(0.0, 350.0) #  $\approx 350$  days

i_0 =  $1E-7$  #  $33 = 1E-7 * 330$  million population = initially infected
e_0 =  $4.0 * i_0$  #  $132 = 1E-7 * 330$  million = initially exposed
s_0 =  $1.0 - i_0 - e_0$ 
r_0 =  $0.0$ 

init_state = [s_0, e_0, i_0, r_0]

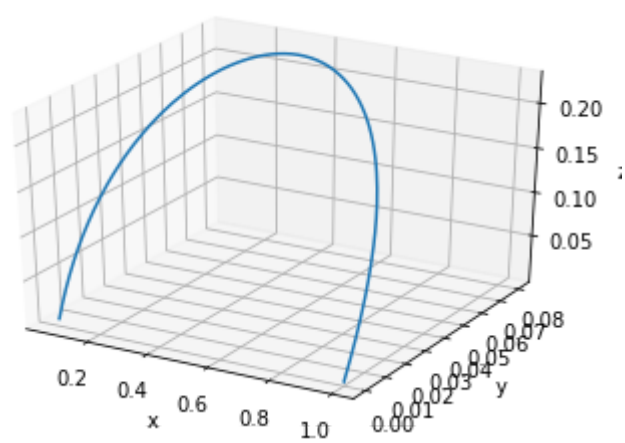
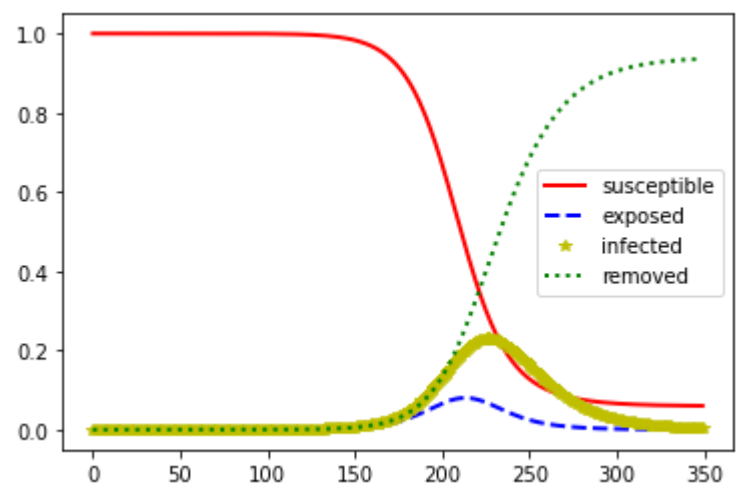
state = odeint(CovidSystem, init_state, t)

plot(t, state[:, 0], 'r-', linewidth=2, label='susceptible')
plot(t, state[:, 1], 'b--', linewidth=2, label='exposed')
plot(t, state[:, 2], 'y*', linewidth=2, label='infected')
plot(t, state[:, 3], 'g:', linewidth=2, label='removed')
legend()
show()

from mpl_toolkits.mplot3d import Axes3D
fig = figure()
ax = fig.gca(projection='3d')
# portretul de faza pentru 'susceptible', 'exposed', 'infected'
ax.plot(state[:,0], state[:,1], state[:,2])
ax.set_xlabel('x')
ax.set_ylabel('y')
ax.set_zlabel('z')
show()

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In [ ]: