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 $\mathbf{Q1}$ Use o método iterativo de Newton, com estimativa inicial $X^{(1)} = [1.69, 1.17]$, para encontrar a aproximação $X^{(4)}$ da solução do sistema

$$\begin{cases} x_1^2 - 3x_2^2 + 5 = 0 \\ x_1^2 + 2x_2^2 - 5 = 0 \end{cases}$$

- a) [1.00005084, 1.41422694]
- b) [1.000051, 1.4142271]
- c) [1.00005146, 1.41422756]
- d) [1.0000517, 1.4142278]
- **(1.00003749, 1.41421359)**
- f) [1.00005327, 1.41422937]

```
X1
1.69 1.17
X2
1.14085799 1.43970085
X3
1.00869564 1.41443917
X4
1.00003748 1.41421358
```

def F(x):

```
return [(x[0]**2 - 3 * x[1]**2 + 5), (x[0]**2 + 2 * x[1]**2 - 5)]
```

```
def JF(x):
    yaux1 = [2*x[0], -6*x[1]]
    yaux2 = [2*x[0], 4*x[1]]
    return [yaux1, yaux2]

def inv(x):
```

yaux1 = [4*x[1], 6*x[1]] yaux2 = [-2*x[0], 2*x[0]] return [yaux1, yaux2]

def det(y):

```
return y[0][0] * y[1][1] - y[0][1] * y[1][0]
```

```
x = [1.69, 1.17]

for i in range(3):
    print(f"X{i + 1}")
    print(*[round(i, 8) for i in x])

r = [0, 0]

for y in range(2):
    r[y] = inv(x)[y][0] * F(x)[0]
    r[y] += inv(x)[y][1] * F(x)[1]
    r[y] *= (1 / det(JF(x)))

x[0] -= r[0]
    x[1] -= r[1]

print(f"X4")
print(*[round(i, 8) for i in x])
```