

6. Develop a program to forecast future values in time series data, such as weather patterns, using RNN models like LSTM or GRU.

(Using Synthetic data)

```
In [2]: import numpy as np
import tensorflow as tf
import matplotlib.pyplot as plt
```

```
In [3]: data = np.sin(np.arange(100) * 0.1)
data.shape
```

```
Out[3]: (100,)
```

```
In [4]: X, y = [], []
for i in range(len(data) - 10):
    X.append(data[i:i+10])
    y.append(data[i+10])
```

```
In [5]: X, y = np.array(X), np.array(y)
X = X.reshape(-1, 10, 1)
```

```
In [6]: model = tf.keras.Sequential([
    tf.keras.layers.Input(shape=(10, 1)),
    tf.keras.layers.LSTM(20),
    tf.keras.layers.Dense(1)
])
```

```
In [7]: model.compile(optimizer='adam', loss='mse')
```

```
In [8]: model.fit(X, y, epochs=10, verbose=1)
```

```
Epoch 1/10
3/3 [=====] - 1s 6ms/step - loss: 0.4648
Epoch 2/10
3/3 [=====] - 0s 4ms/step - loss: 0.4124
Epoch 3/10
3/3 [=====] - 0s 4ms/step - loss: 0.3590
Epoch 4/10
3/3 [=====] - 0s 4ms/step - loss: 0.3142
Epoch 5/10
3/3 [=====] - 0s 3ms/step - loss: 0.2756
Epoch 6/10
3/3 [=====] - 0s 3ms/step - loss: 0.2407
Epoch 7/10
3/3 [=====] - 0s 4ms/step - loss: 0.2106
Epoch 8/10
3/3 [=====] - 0s 3ms/step - loss: 0.1876
Epoch 9/10
3/3 [=====] - 0s 6ms/step - loss: 0.1692
Epoch 10/10
3/3 [=====] - 0s 2ms/step - loss: 0.1547
```

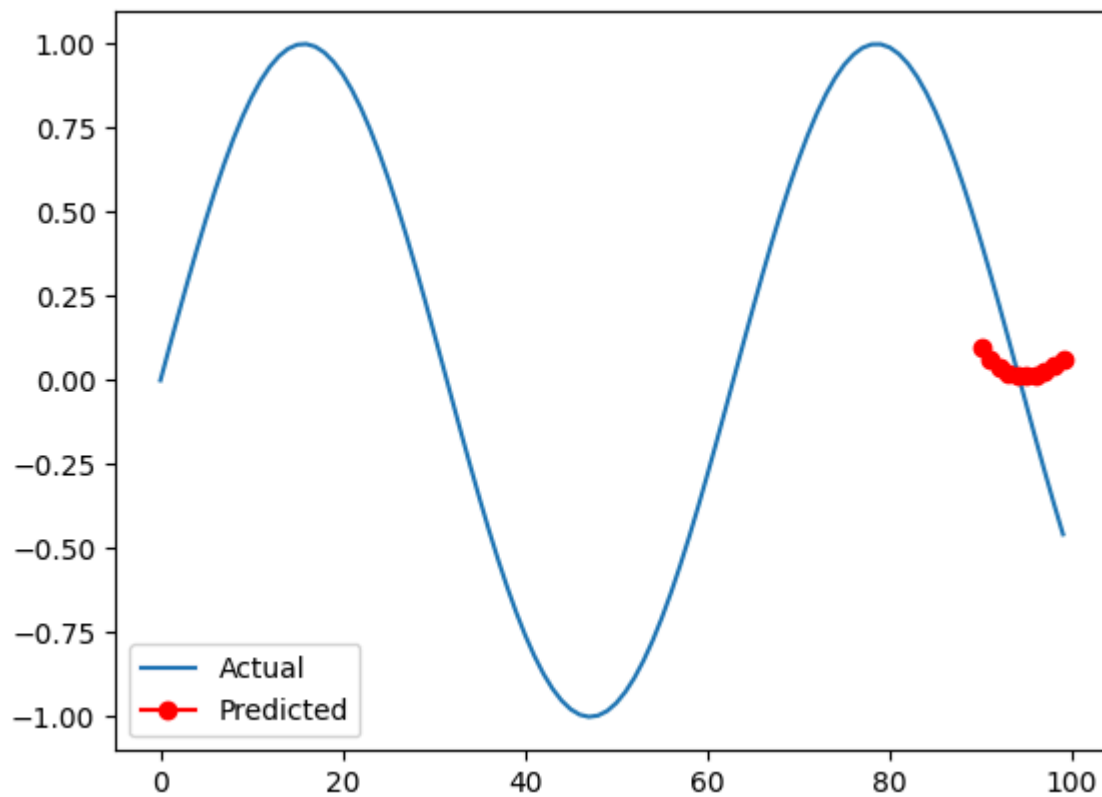
```
Out[8]: <keras.callbacks.History at 0x2225eff6710>
```

```
In [9]: preds = []
seq = X[-1]
```

```
In [10]: for _ in range(10):
    pred = model.predict(seq.reshape(1, 10, 1), verbose=0)[0, 0]
```

```
preds.append(pred)
seq = np.roll(seq, -1) # shift sequence
seq[-1] = pred # append predicted value
```

```
In [11]: plt.plot(data, label='Actual')
plt.plot(range(90, 100), preds, 'ro-', label='Predicted')
plt.legend()
plt.show()
```



```
In [ ]:
```