

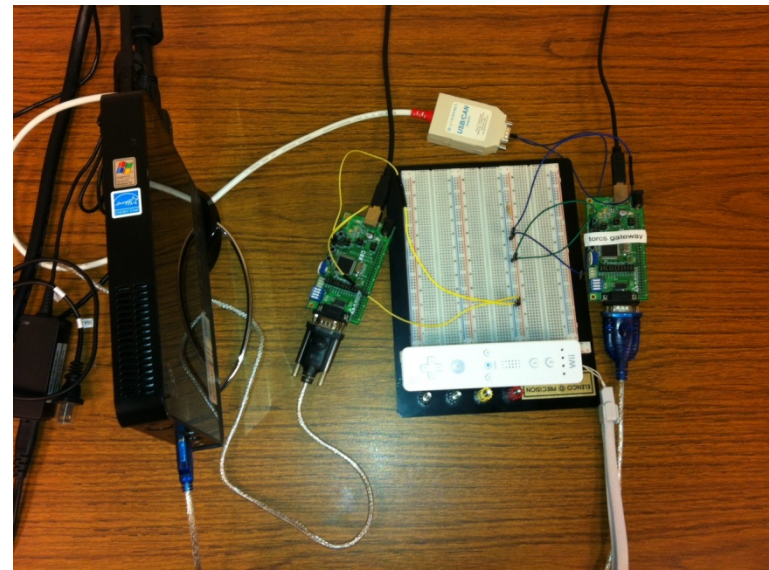
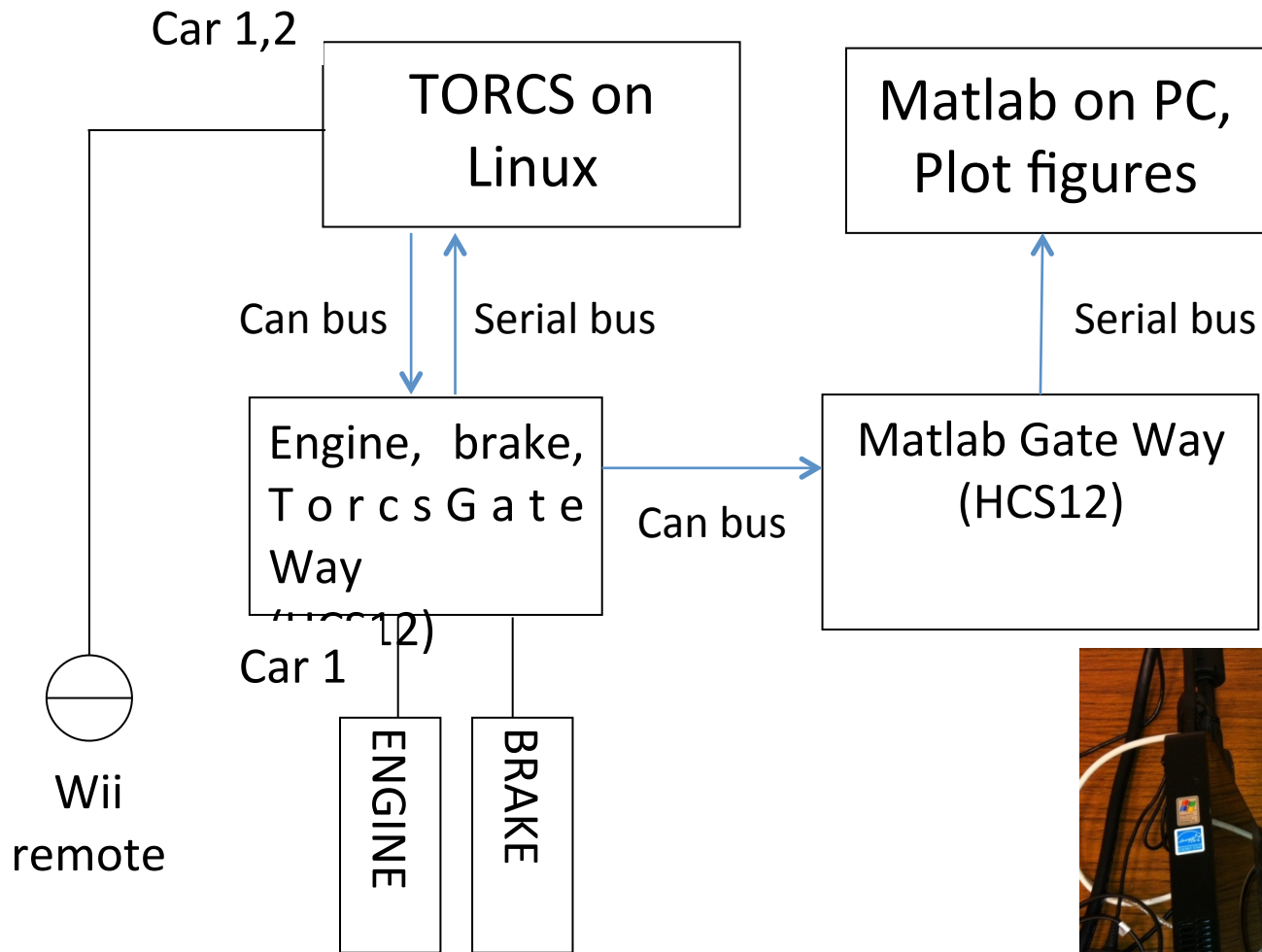
Autoplug 3.0

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Architecture Diagram



What we accomplished

- 1. Catch up with the front car.
- 2. Brake if two cars are too close.
- 3. Change tracking distance as you wish.
- 4. Introduce real radar error in distance detection.
- 5. Multiple car detection.

short video showing ACC's
performance

Thank you!