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/*****
MPLAB Harmony Application Source File

Company:
    Microchip Technology Inc.

File Name:
    app.c

Summary:
    This file contains the source code for the MPLAB Harmony application.

Description:
    This file contains the source code for the MPLAB Harmony application.  It
    implements the logic of the application's state machine and it may call
    API routines of other MPLAB Harmony modules in the system, such as drivers,
    system services, and middleware.  However, it does not call any of the
    system interfaces (such as the "Initialize" and "Tasks" functions) of any of
    the modules in the system or make any assumptions about when those functions
    are called.  That is the responsibility of the configuration-specific system
    files.
*****/

// DOM-IGNORE-BEGIN
/*****
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*****/

// DOM-IGNORE-END

// ****
// ****
// Section: Included Files
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// *****
// *****

#include <stddef.h>           // Defines NULL
#include <stdbool.h>          // Defines true
#include <stdlib.h>           // Defines EXIT_FAILURE
#include "app.h"
#include "Gest_LED.h"
#include "dac_ad5620.h"
#include "Gestion_Filtre.h"

// *****
// *****
// Section: Global Data Definitions
// *****
// *****

// *****
/* Application Data

Summary:
    Holds application data

Description:
    This structure holds the application's data.

Remarks:
    This structure should be initialized by the APP_Initialize function.

    Application strings and buffers are be defined outside this structure.
*/

APP_DATA appData;

uint8_t wait = 0;
uint8_t ON_OFF = 1;
uint8_t Color = 1;
uint16_t value = 1241 ;
uint32_t value_ADC = 0;
uint16_t Value_Mes [100000];
uint16_t Index = 0;
bool one_iteration = false;
// *****
// *****
// Section: Application Callback Functions
// *****
// *****

/* TODO:  Add any necessary callback functions.
*/
```

```
// *****
// *****
// Section: Application Local Functions
// *****
// *****

/* TODO: Add any necessary local functions.
*/

// *****
// *****
// Section: Application Initialization and State Machine Functions
// *****
// *****

/*****
Function:
    void APP_Initialize ( void )

Remarks:
    See prototype in app.h.
*/

void APP_Initialize ( void )
{
    /* Place the App state machine in its initial state. */
    appData.state = APP_STATE_INIT;

    /* TODO: Initialize your application's state machine and other
    * parameters.
    */
}

/*****
Function:
    void APP_Tasks ( void )

Remarks:
    See prototype in app.h.
*/

void APP_Tasks ( void )
{
    /* Check the application's current state. */
    switch ( appData.state )
    {
```

```
/* Application's initial state. */
case APP_STATE_INIT:
{
    bool appInitialized = true;
    DRV_TMR0_Start();
    DRV_TMR1_Start();
    All_LED_Off();

    DRV_ADC0_Open();
    DRV_ADC_Start();
    Dac_Init();

    if (appInitialized)
    {
        appData.state = APP_STATE_WAIT;
    }
    break;
}

case APP_STATE_SERVICE_TASKS:
{

    DRV_TMR0_Stop();
    uint16_t Value_max = 0;
    uint16_t Value_min = 0;
    uint16_t Val_Zero = 0;
    uint16_t Tension_max = 0;
    uint16_t Nb_ech_pos = 0;

    if (one_iteration == true)
    {
        Value_search(Value_Mes, &Value_max, &Value_min, &Val_Zero);

        //calcul de la tension max
        Tension_max = Value_max - Val_Zero;
        //mesure temps demi-période
        Conv_Values (Value_Mes, &Nb_ech_pos, Val_Zero);
        //affichage LED d'après fréquence
        Calcul_Frequence_Led(Nb_ech_pos, Tension_max);

        Dac_Write(Val_Zero);

        Nb_ech_pos = 0;
    }
    else
    {
        one_iteration = true;
    }

    //LED0_GToggle();
}
```

```
        DRV_TMR0_Start();

        UpdateAppState(APP_STATE_WAIT);
        break;
    }

    case APP_STATE_WAIT:
    {
        //attend de recevoir 10'000 échantillons
        break;
    }
    default:
    {
        /* TODO: Handle error in application's state machine. */
        break;
    }
}

//fonction de la machine d'état
void UpdateAppState(APP_STATES newState)
{
    appData.state = newState;
}

//fonction de lecture de l'ADC

void Get_ADC_Values(uint16_t index)
{
    Value_Mes[index] = DRV_ADC_SamplesRead(2U);
}

/*****
End of File
*/
```