Neural Networks

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Neural Networks

A **neural network** is a complex system of simple, interconnected units inspired by animal neurons.

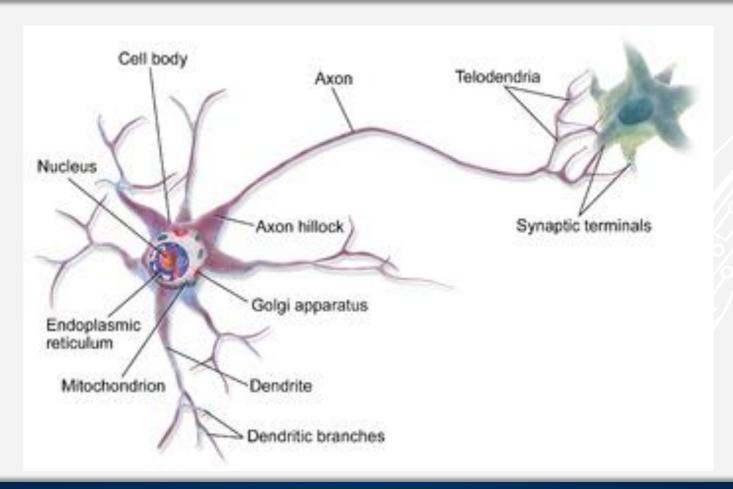
Each neuron has a simple rule which defines its value. It communicates this value to other neurons via weighted directed edges, and these values affect the nodes to which they are communicated.

Neural nets are capable of approximating complex functions.



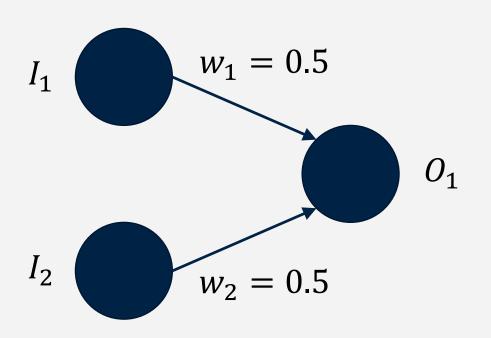


Animal Nervous Systems







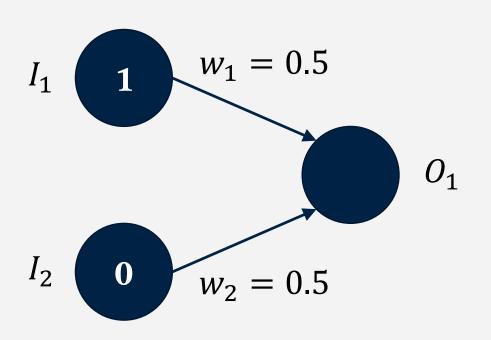


Input nodes I_1 and I_2 take 0 or 1 as input.

$$O_1 = I_1 w_1 + I_2 w_2$$





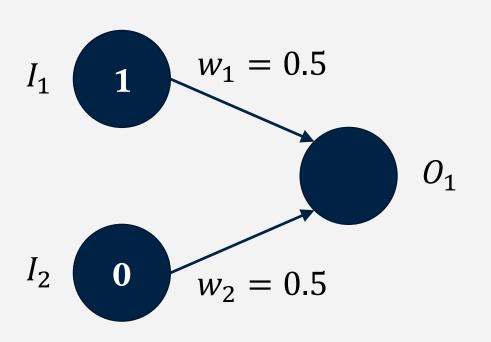


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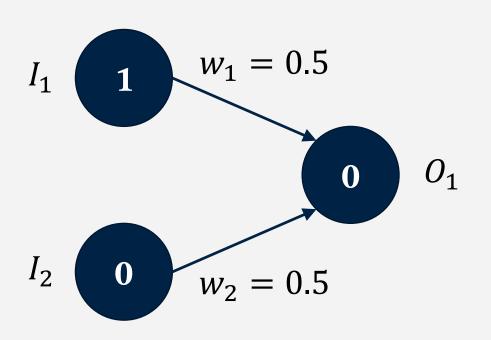


Input nodes I_1 and I_2 take 0 or 1 as input.

$$O_1 = 1 \cdot 0.5 + 0 \cdot 0.5$$





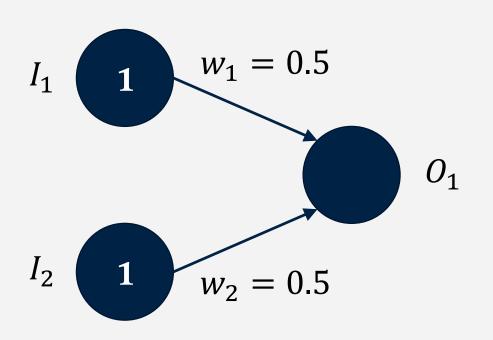


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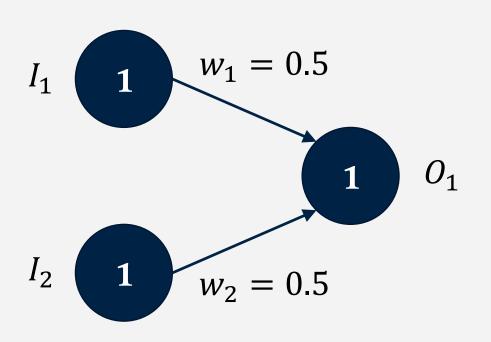


Input nodes I_1 and I_2 take 0 or 1 as input.

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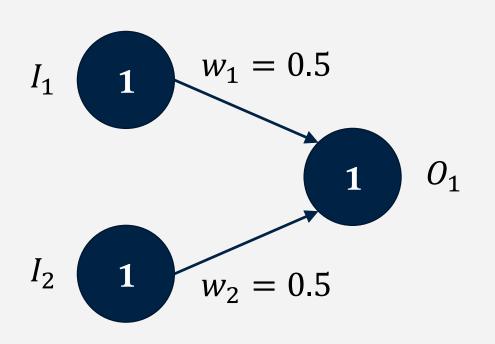


Input nodes I_1 and I_2 take 0 or 1 as input.

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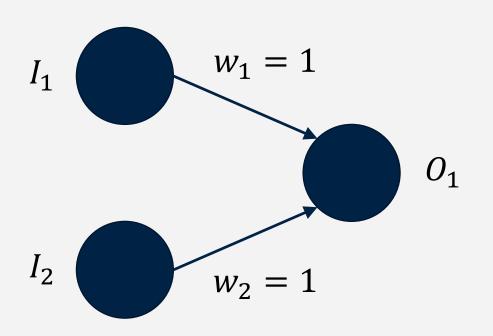
$$O_1 = 1 \cdot 0.5 + 1 \cdot 0.5$$

Output node O_1 outputs 1 if its value is ≥ 1 , 0 otherwise.

Boolean AND





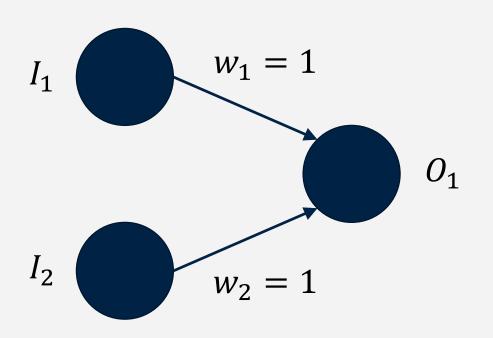


Input nodes I_1 and I_2 take 0 or 1 as input.

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Boolean OR





Structure of a Neural Net

- 1 or more input nodes in the input layer.
- 1 or more output nodes in the output layer.
- Directed, weighted edges between nodes.
- Nodes have an activation function the defines its output given the sum of its inputs.
- Optionally, the network has 1 or more hidden nodes, possibly organized into hidden layers.





Types of Neural Nets

A neural net with no hidden layers or cycles and a threshold activation function is called a **perceptron**. Perceptrons are one popular kind of linear classifier.

A neural net with no cycles is called a **feed-forward** network. These are simple and probably the most common kind of neural nets.

A neural net which contains cycles is called **recurrent**, and can model a kind of short term memory.





Neural Nets in AI History

- First work on neural nets (perceptrons) started 1957 and was a source of much excitement.
- In 1969, Minsky and Papert published *Perceptrons*, which demonstrated that many kinds of functions could not be learned by perceptrons.
- Excitement for neural nets decreased dramatically for more than a decade. Some consider this an inciting incident for AI Winter.
- Neural nets experiencing a resurgence since 80's.





Value of Neural Nets

- Input and output can be thought of as vectors.
 - This is ideal for applications like computer vision, where the input might be a camera's pixels and the output might be a vector of all the possible things the network is trained to recognize.
- Neural nets with hidden layers are an excellent tool for performing non-linear regression.





Example Neural Net

We will consider a simple feed-forward example network with:

- 2 input nodes
- 1 output node
- 1 hidden layer with 2 nodes
- Sigmoid activation function



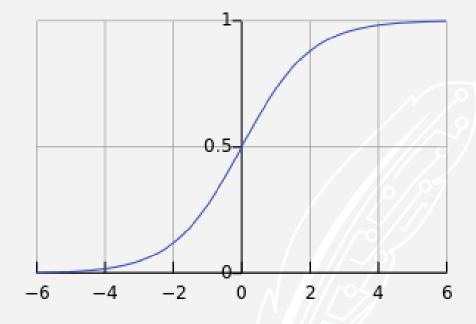


Sigmoid Activation Function

Maps any input number x to a number between 0 and 1.

$$f(-4) \approx 0.02$$

 $f(0) \approx 0.50$
 $f(2) \approx 0.88$



$$f(x) = \frac{1}{1 + e^{-x}}$$





Training a Neural Net

Like other machine learning tools, neural nets can be trained on a set of examples.

Training occurs by adjusting the weights of edges.





Back Propagation Learning

```
Set all edge weights to random values.
```

Calculate the network's output.

Calculate the error of this output.

Until the error cannot be reduced further:

For each layer, from output back to input:

Adjust the weights of the edges going to the nodes

in this layer to reduce the error in the last layer.





Updates Based on Error

Given some function, the **gradient** of that function is a vector that points in the direction of the greatest rate of increase, and its magnitude is the slope of the graph in that direction.

Practically speaking, we find the gradient of f(x) by differentiating with respect to x.





Updating Based on Error

In general, error is the difference between what you want and what you actually got:

correct — output

When we update the weights in a neural network, we want to update them to reduce error. We want to raise or lower them appropriately (direction) and we want to raise or lower them as much as is needed (magnitude). Hence, we need the gradient of the activation function.





Sigmoid Gradient

$$f(x) = \frac{1}{1 + e^{-x}}$$

$$f'(x) = \frac{\partial}{\partial x} \left(\frac{1}{1 + e^{-x}} \right)$$

$$f'(x) = f(x)(1 - f(x))$$





Sigmoid Error

When adjusting the weight of an edge in a network whose nodes use the sigmoid activation function, we need to calculate error like so:





Error Values

For each node X, we need to calculate its error value Δ by considering all its outgoing edges and the error values of the nodes in the next level:

$$\Delta(X) = X(1 - X) \sum_{Y} w_{X \to Y} \Delta(Y)$$

The idea here is that each edge is responsible for some of the error of the nodes that take its input.





Edge Weight Updates

- Consider some training example.
- Calculate the output of the network for the example.
- Calculate the error of the network.
- The output nodes are responsible for the error, so adjust the weights going into them.
- The node in the last hidden layer are responsible for some of the error of the edges going into the output, so adjust the weights of the edges going into them.
- So on back through the whole network.





Edge Weight Updates

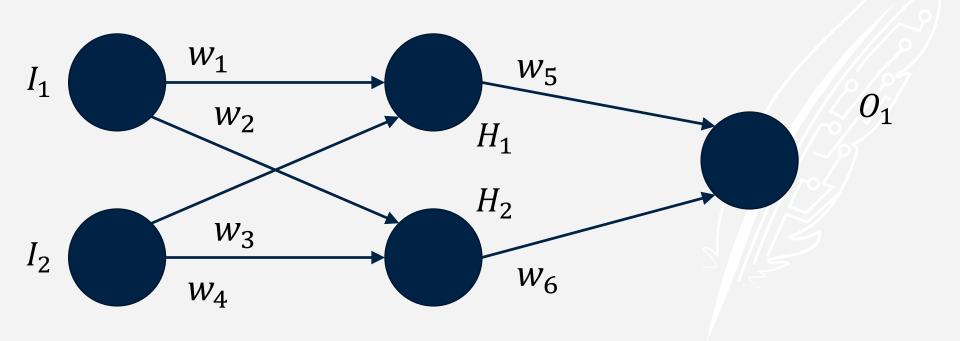
When updating an edge from node X to node Y with weight $w_{X\to Y}$, we assume that the edge is partially responsible for some of the error in Y. We need to adjust it based on that error and based on the weight of node X:

$$w_{X\to Y}=w_{X\to Y}+\big(X\cdot\Delta(Y)\big)$$





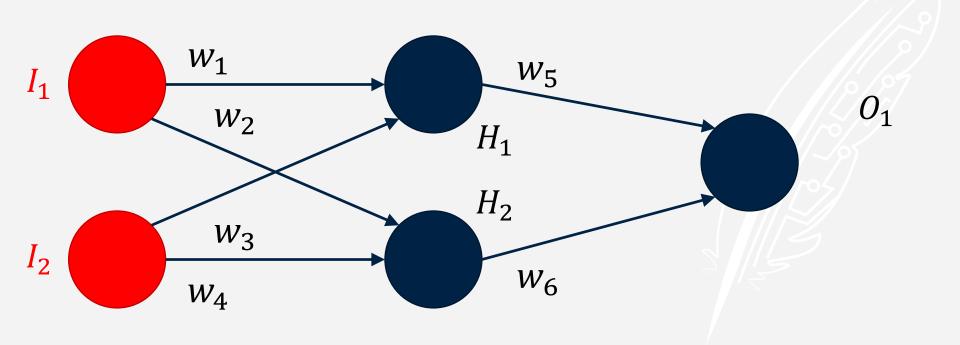
This network has 5 nodes and 3 layers.







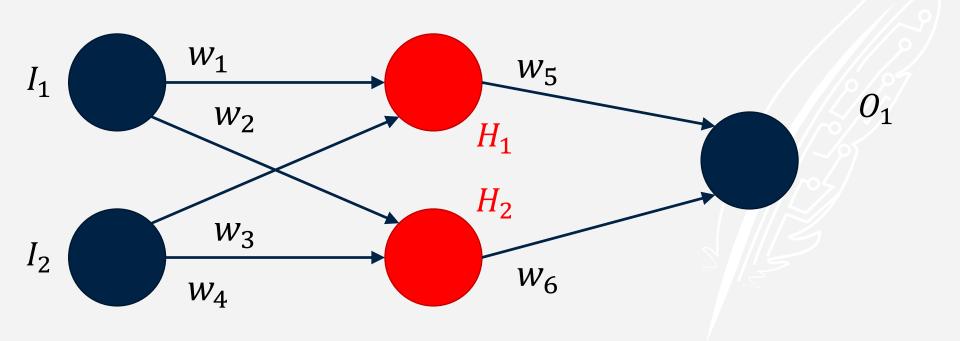
This network has 2 input nodes, I_1 and I_2 .







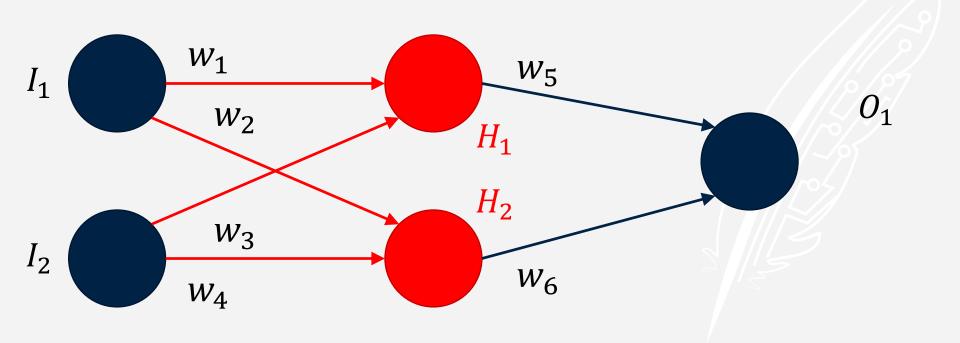
This network has 2 hidden nodes, H_1 and H_2 .







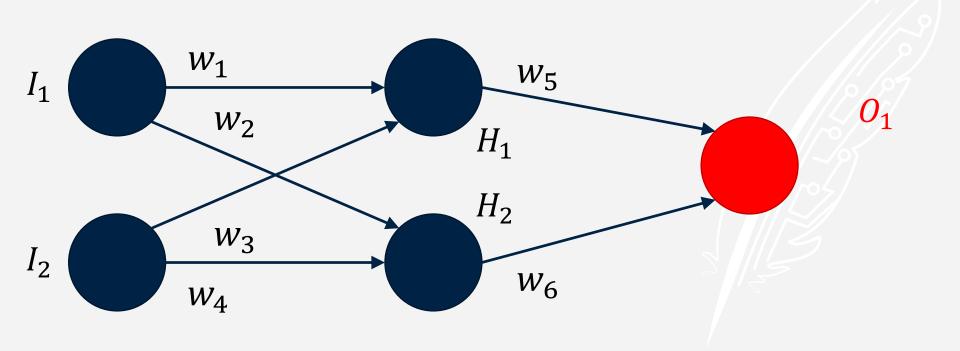
Each hidden node receives input from all input nodes.







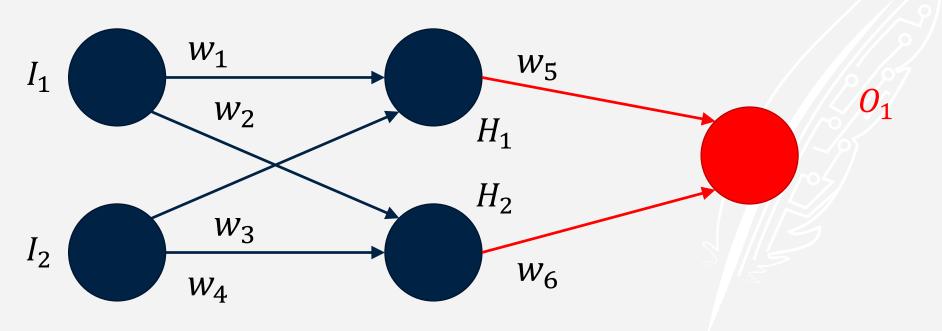
This network has 1 output node, O_1 .







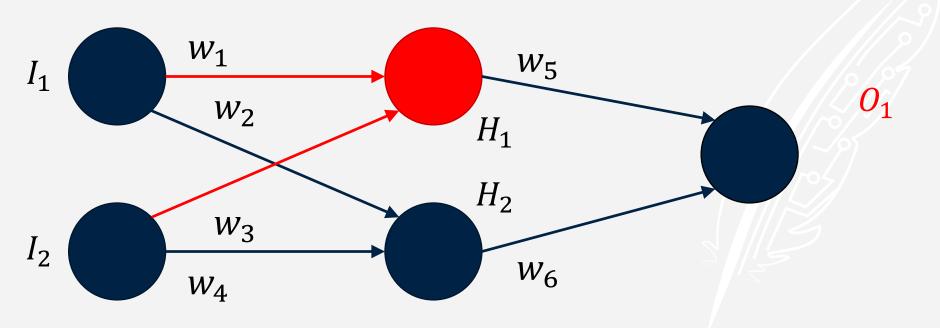
Each output node receives input from each hidden node in the layer before it.







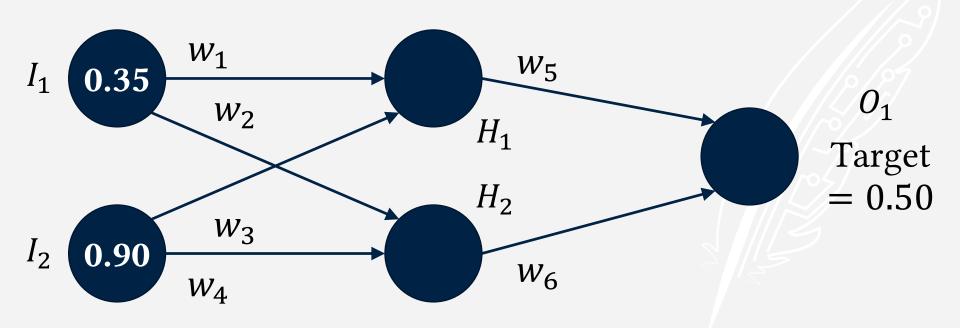
Each hidden node receives input from each node in the layer before it.







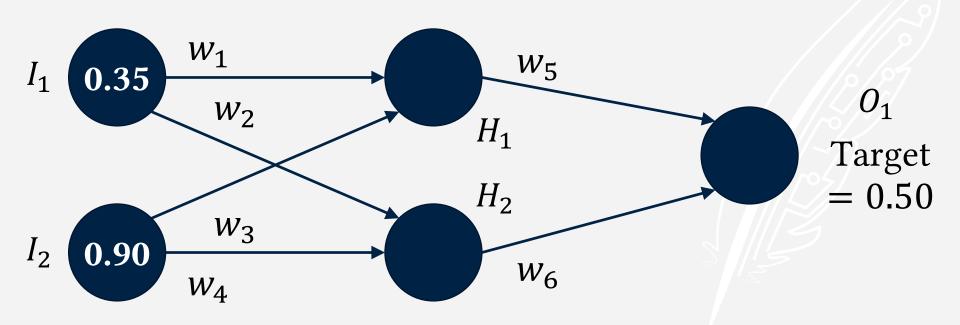
We want to train this network to output 0.5 given the inputs 0.35 and 0.9.







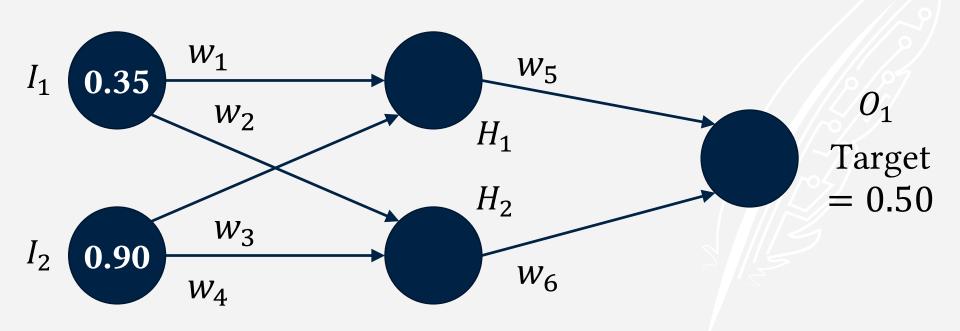
We will do a single iteration of back propagation learning.







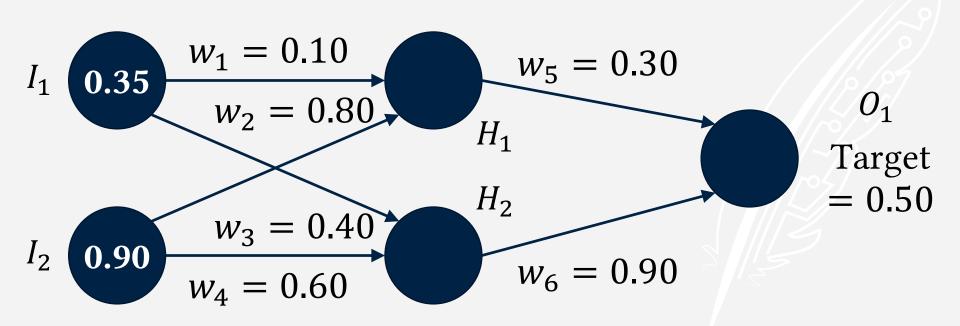
Start by setting all weights in the network to random numbers.







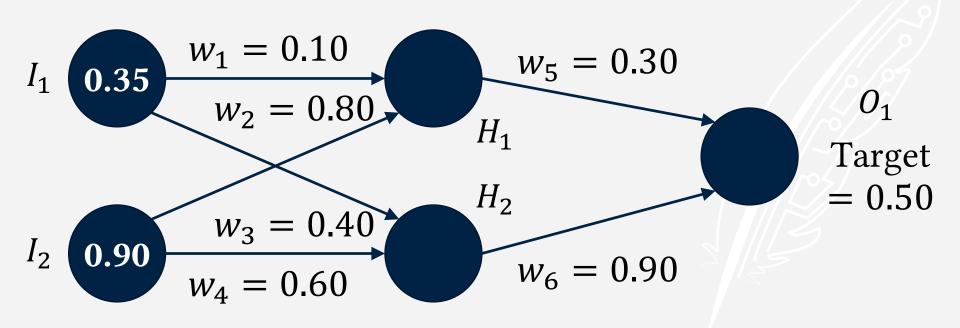
Start by setting all weights in the network to random numbers.







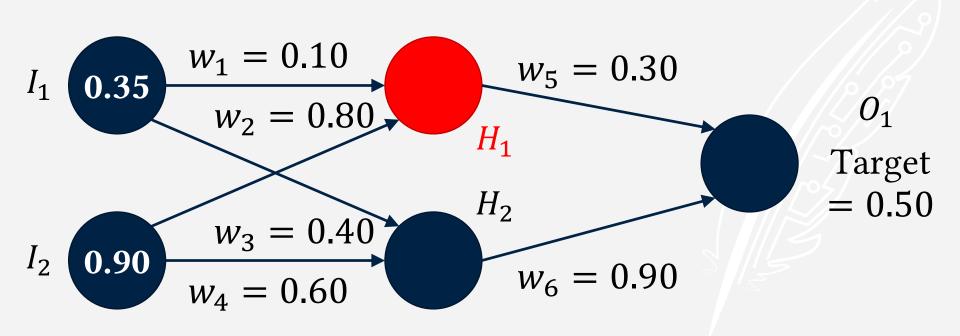
Feed values forward from the input nodes to the hidden nodes to calculate the output node value.







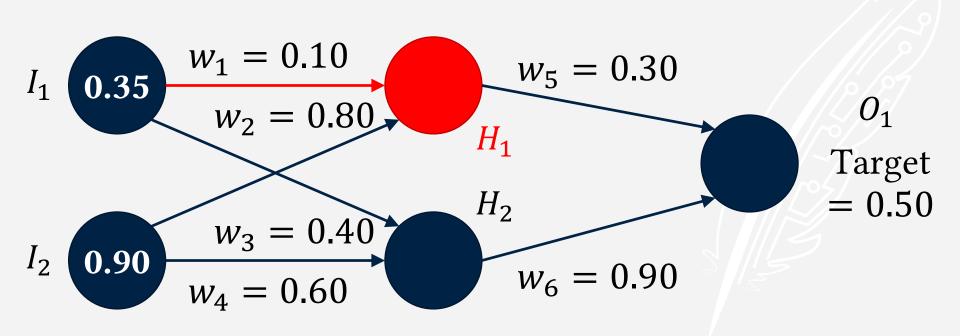
$$H_1 = ?$$







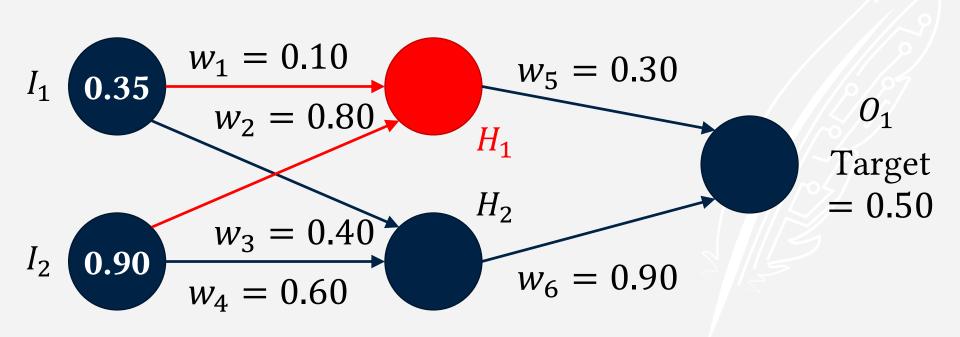
$$H_1 = (0.35 \cdot 0.10)$$







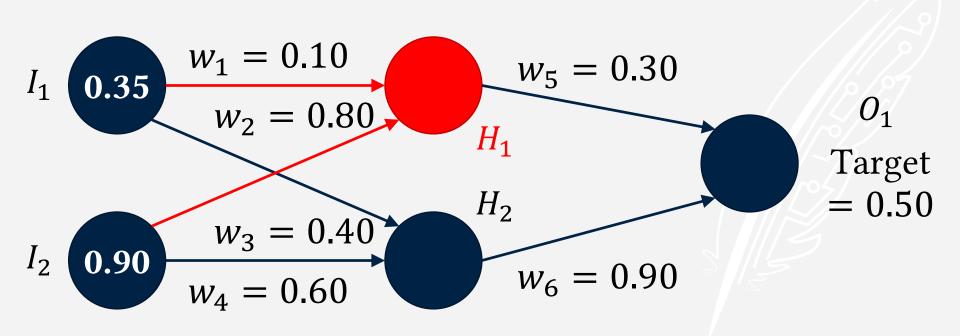
$$H_1 = (0.35 \cdot 0.10) + (0.90 \cdot 0.80)$$







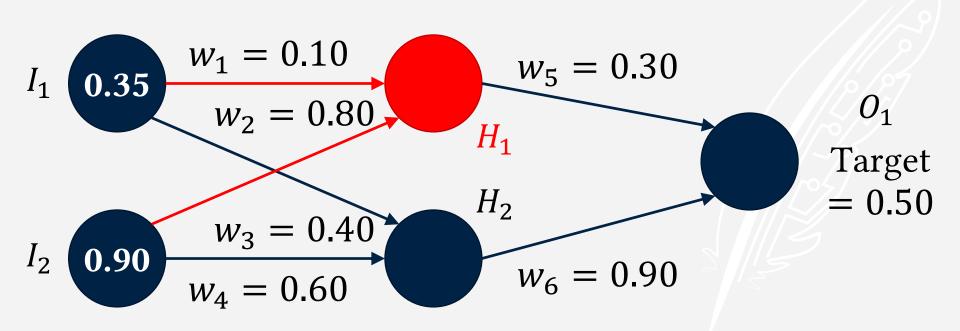
$$H_1 = 0.755$$







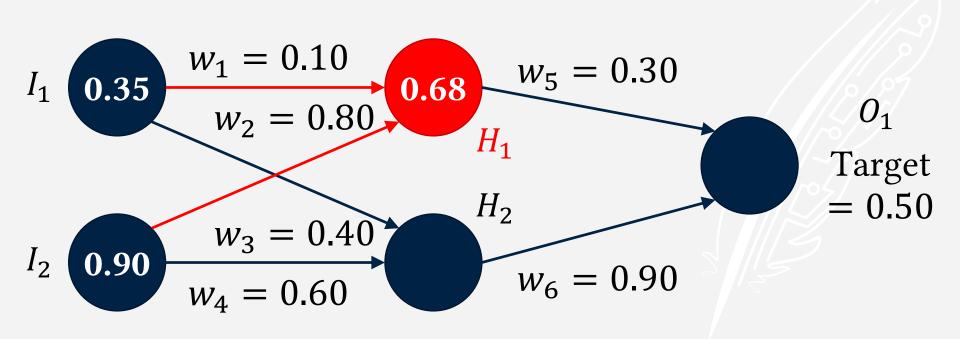
$$H_1 = \frac{1}{1 + e^{-0.755}}$$







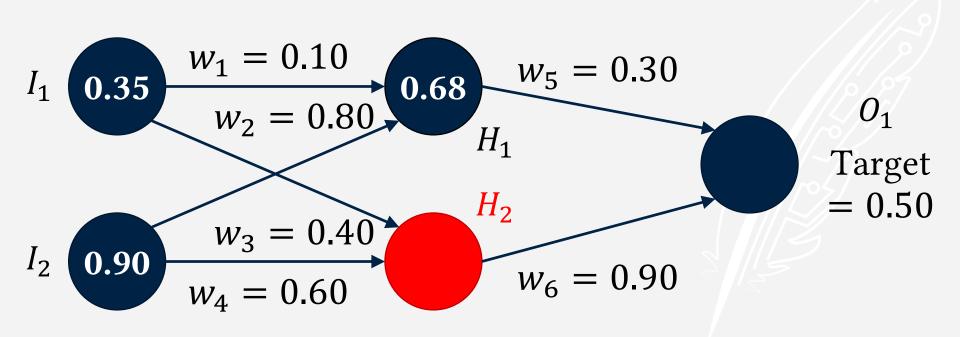
 $H_1 \approx 0.68$







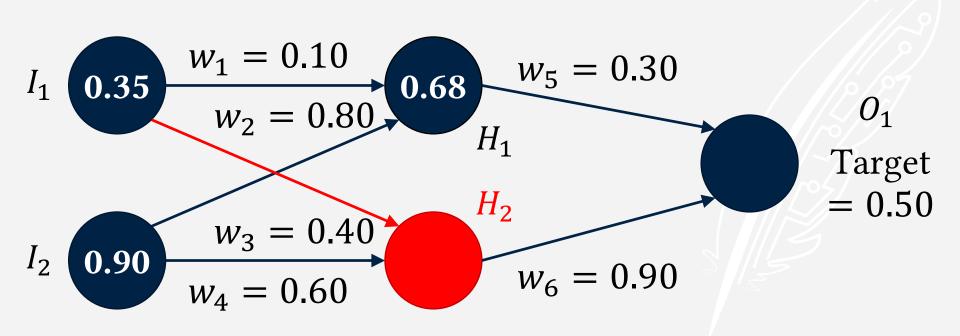
$$H_2 = ?$$







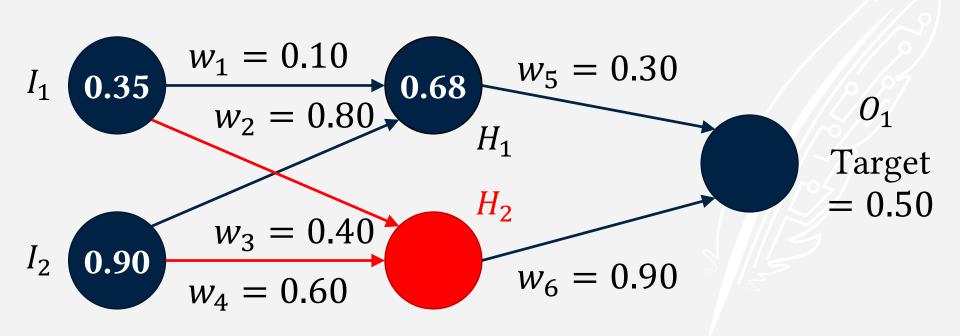
$$H_2 = (0.35 \cdot 0.40)$$







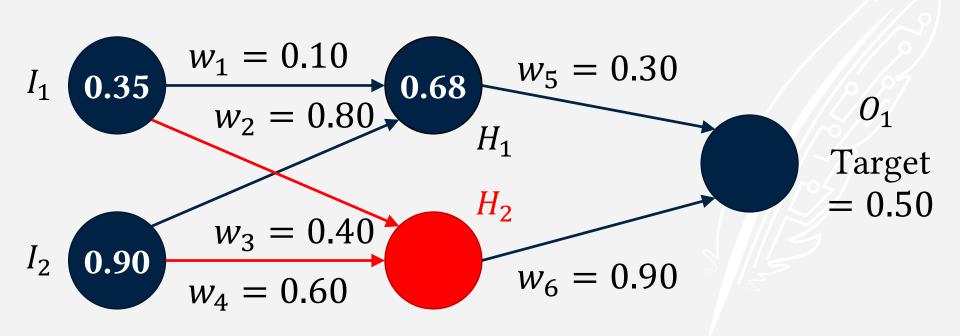
$$H_2 = (0.35 \cdot 0.40) + (0.90 \cdot 0.60)$$







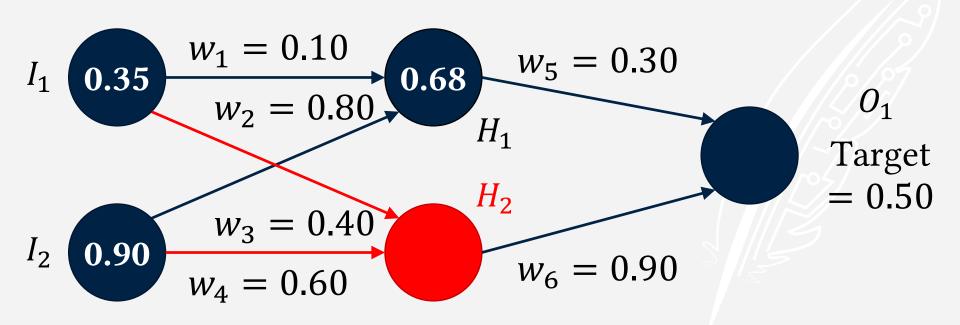
$$H_2 = 0.68$$







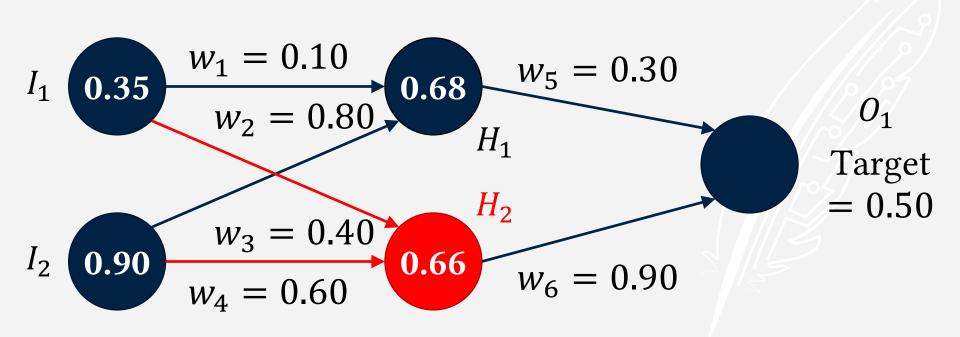
$$H_2 = \frac{1}{1 + e^{-0.68}}$$







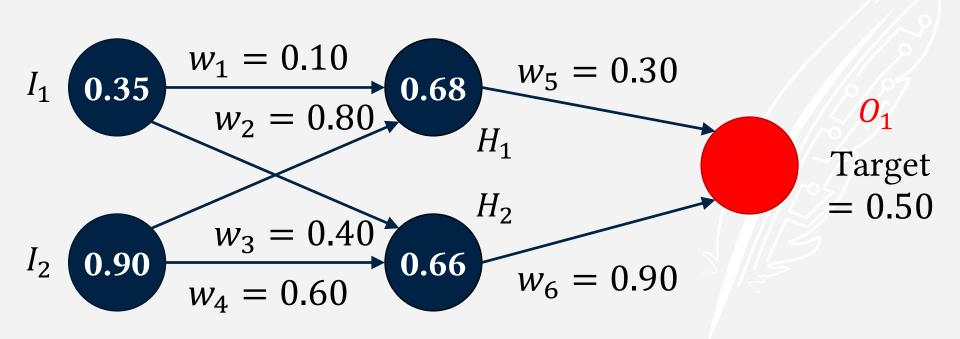
 $H_2 \approx 0.66$







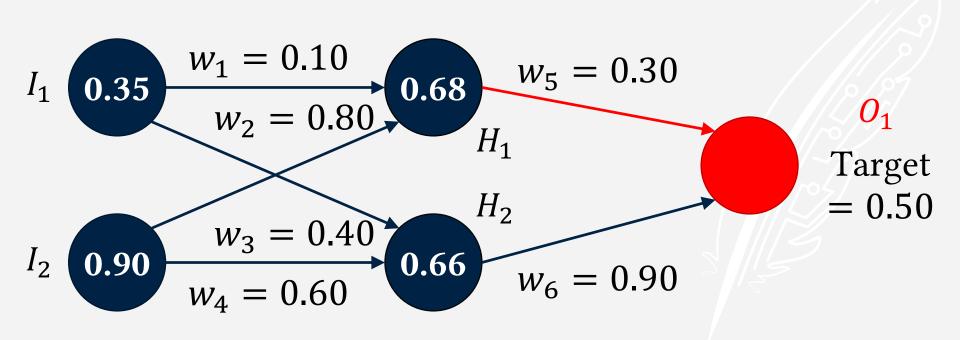
$$O_1 = ?$$







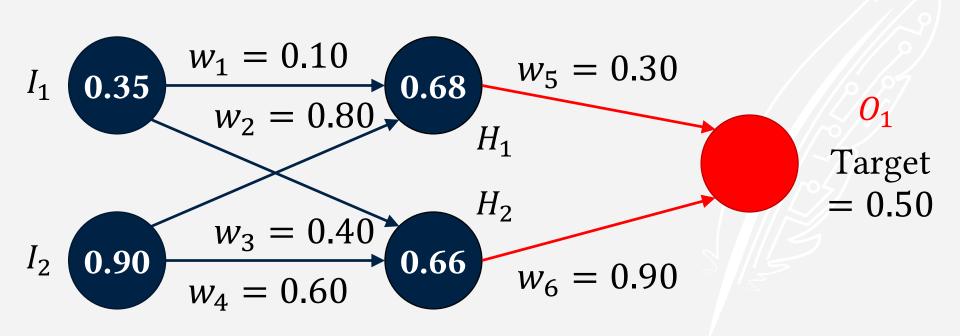
$$O_1 = (0.68 \cdot 0.30)$$







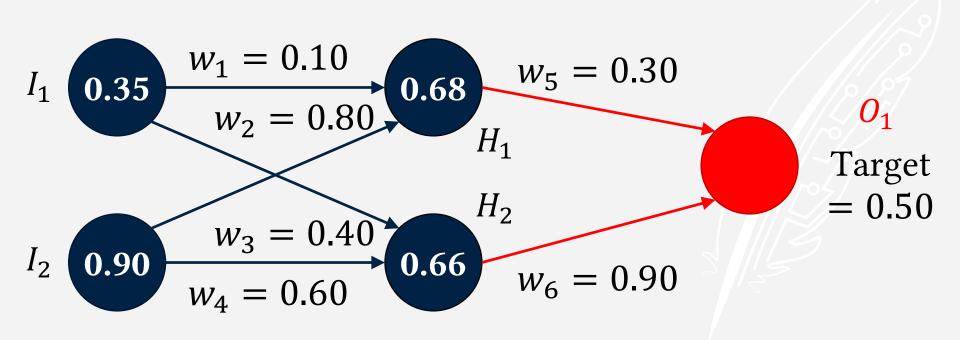
$$O_1 = (0.68 \cdot 0.30) + (0.66 \cdot 0.90)$$







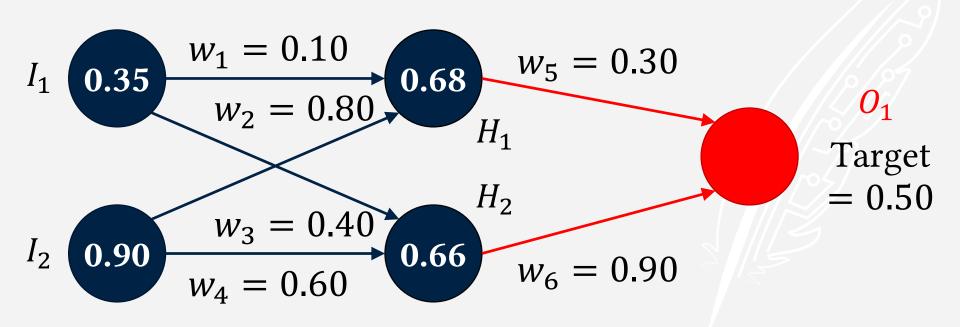
 $O_1 \approx 0.80$







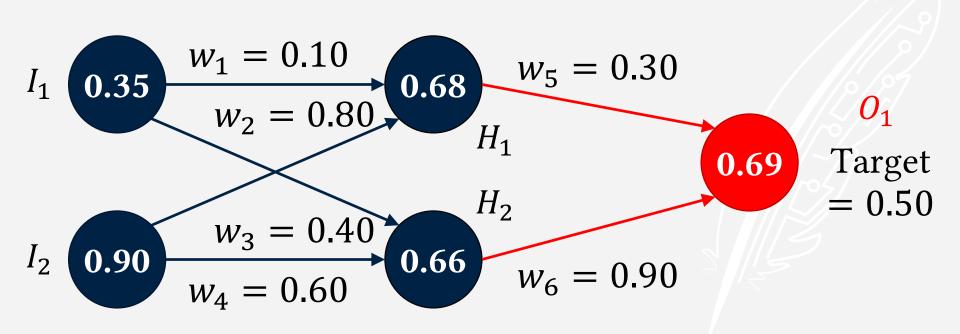
$$O_1 \approx \frac{1}{1 + e^{-0.80}}$$







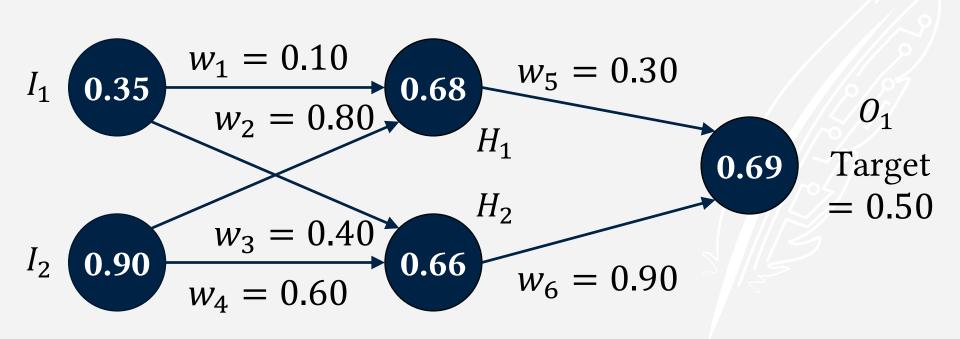
 $O_1 \approx 0.69$







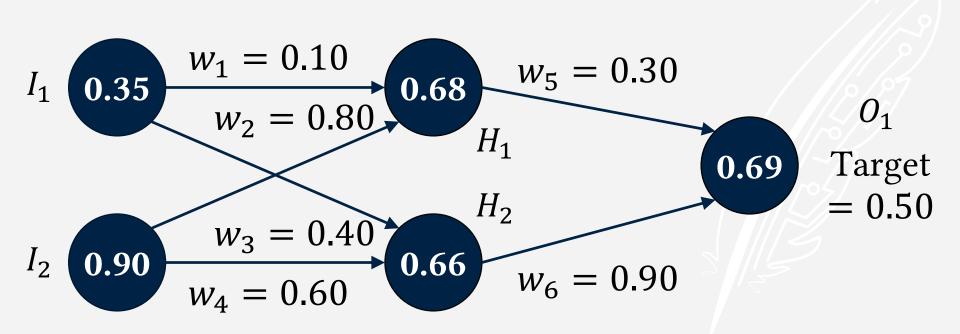
Now we calculate the error of our network.







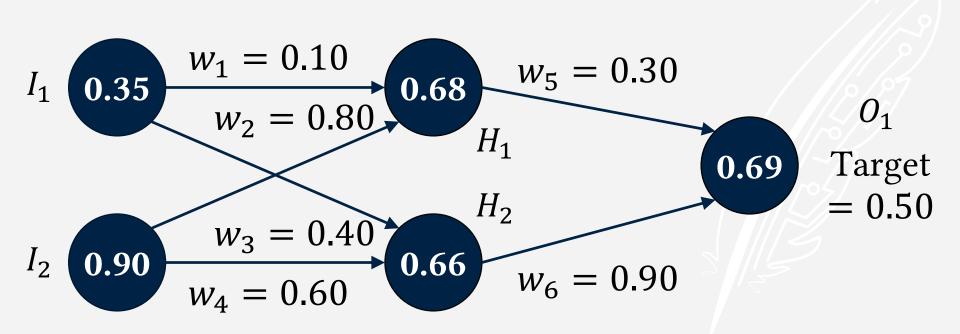
error = correct - output







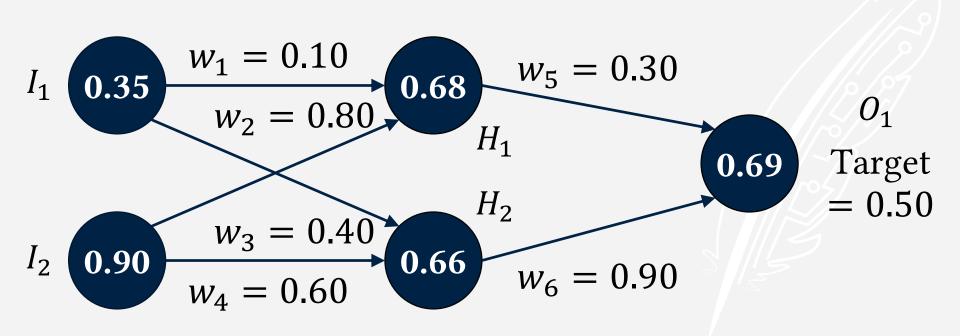
$$error = 0.5 - 0.69$$







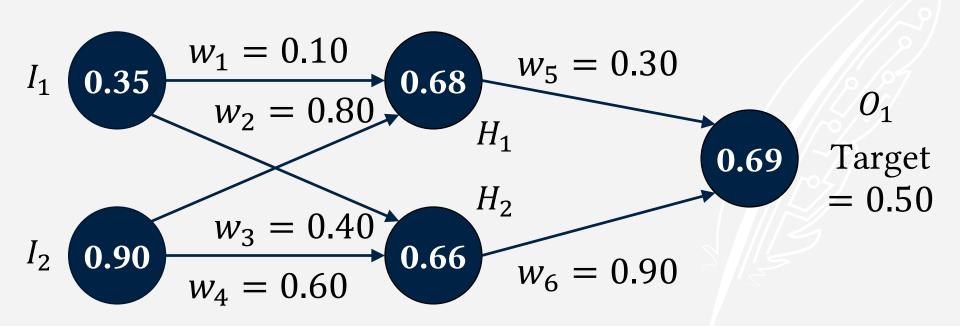
error = -0.19







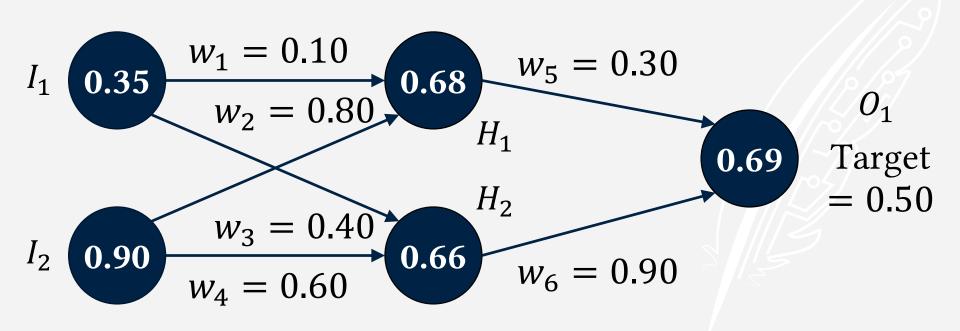
Now we need to adjust the weights to reduce the error in the network.







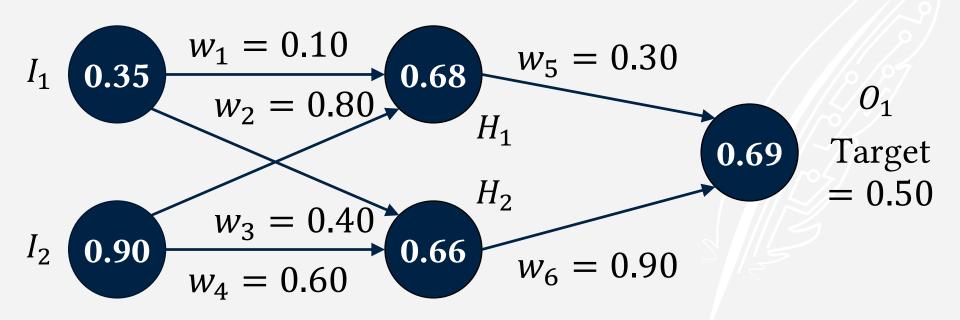
We start with the output node and work backwards to the input nodes.







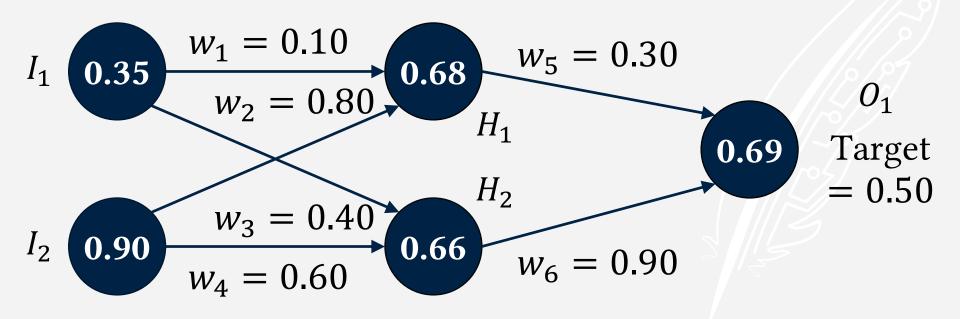
$$\Delta(X) = X(1 - X) \sum_{Y} w_{X \to Y} \Delta(Y)$$







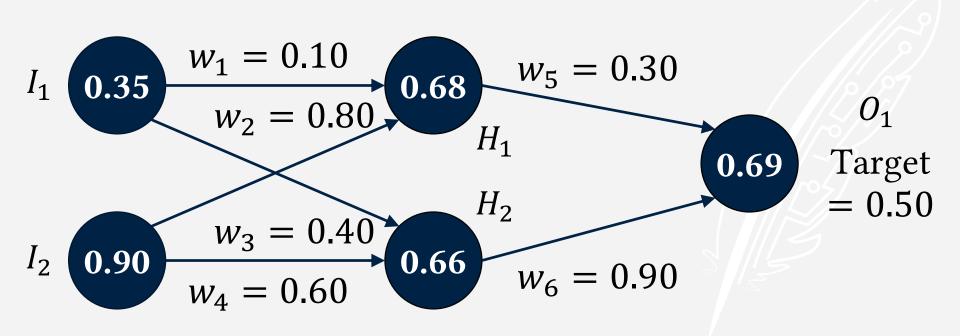
$$\Delta(O_1) = O_1(1 - O_1) \sum_{Y} w_{O_1 \to Y} \Delta(Y)$$







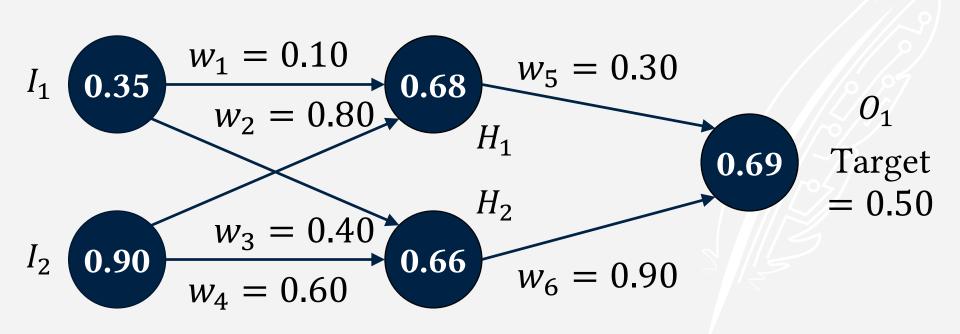
$$\Delta(O_1) = O_1(1 - O_1)(-0.19)$$







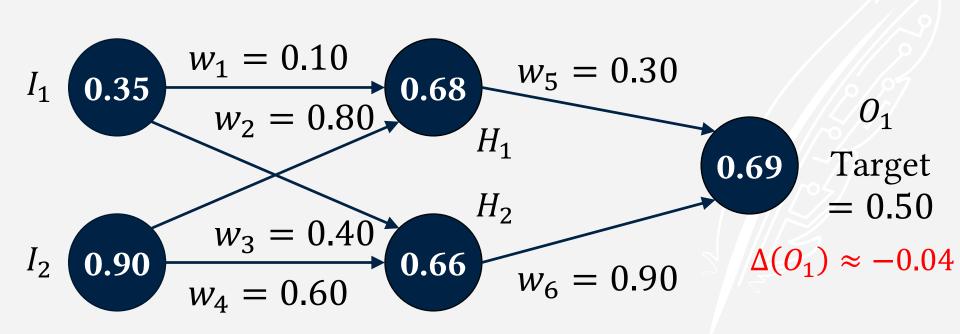
$$\Delta(O_1) = 0.69(1 - 0.69)(-0.19)$$







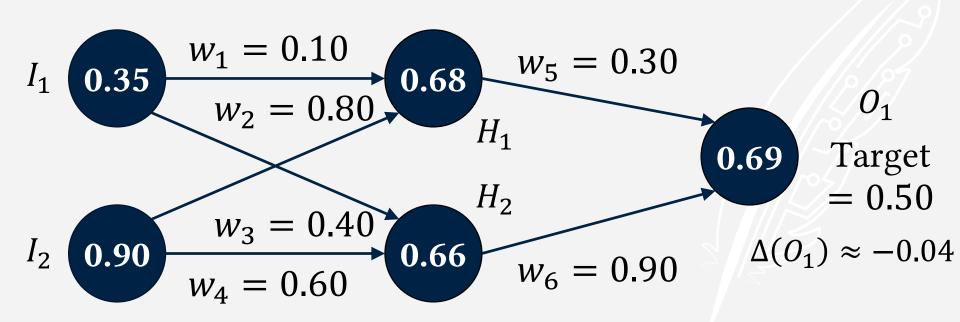
$$\Delta(O_1) \approx -0.04$$







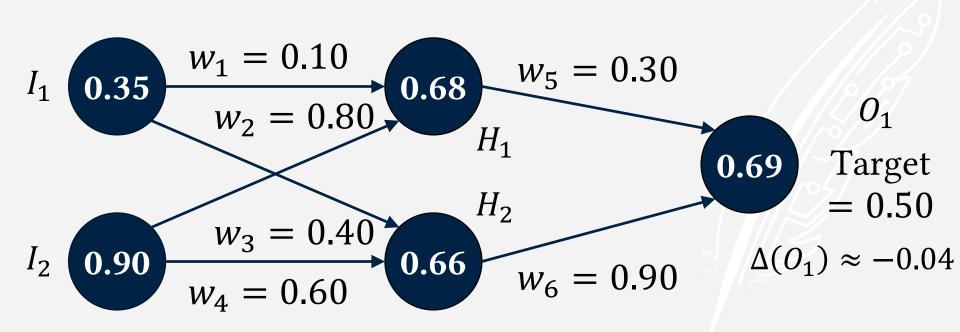
Now we need to update the weights of the edges leading to the output nodes.







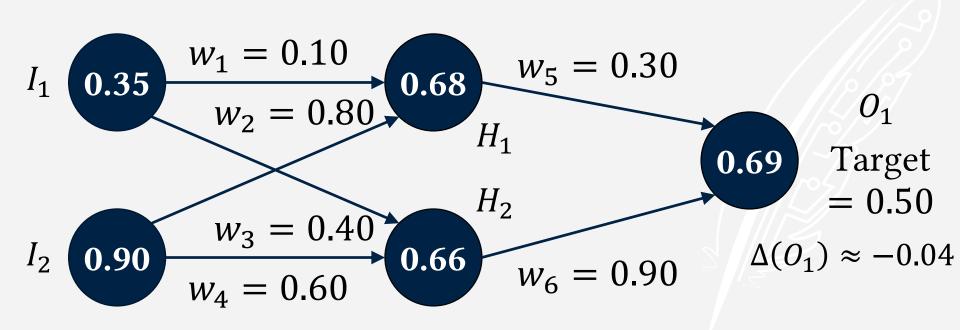
$$w_{X\to Y}=w_{X\to Y}+\big(X\cdot\Delta(Y)\big)$$







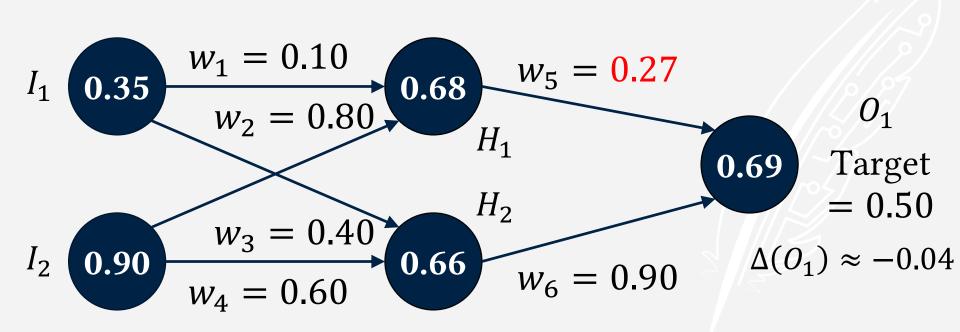
$$w_5 = w_5 + (H_1 \cdot \Delta(O_1))$$







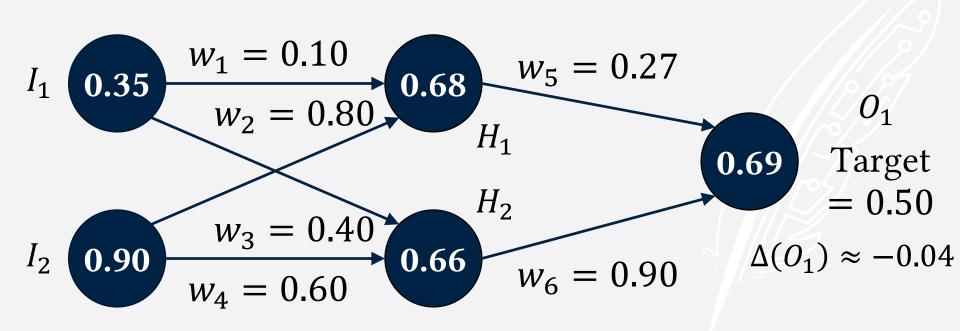
 $w_5 \approx 0.27$







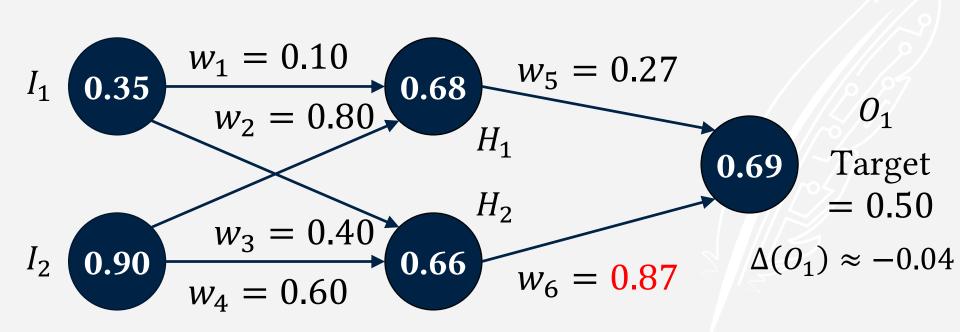
$$w_6 = w_6 + (H_2 \cdot \Delta(O_1))$$







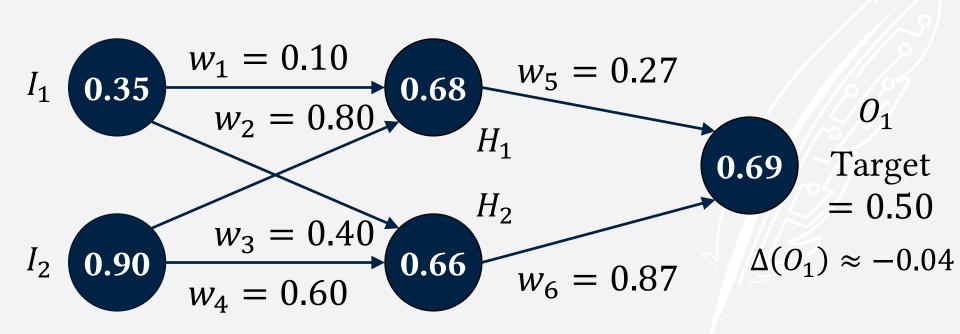
$$w_6 = 0.87$$







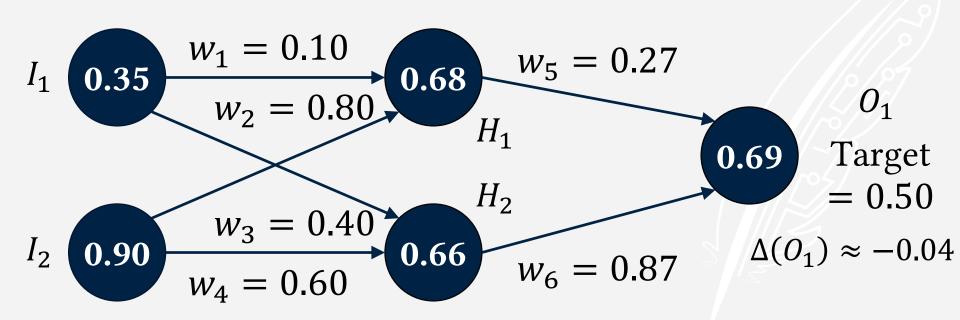
Now we update the hidden layer.







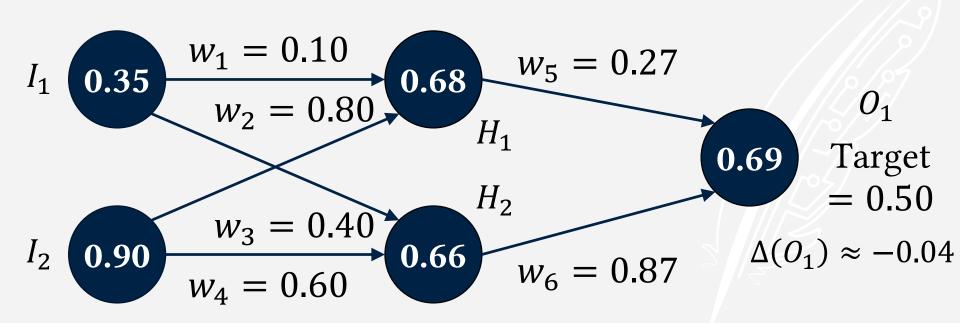
$$\Delta(H_1) = H_1(1 - H_1) \sum_{Y} w_{H_1 \to Y} \Delta(Y)$$







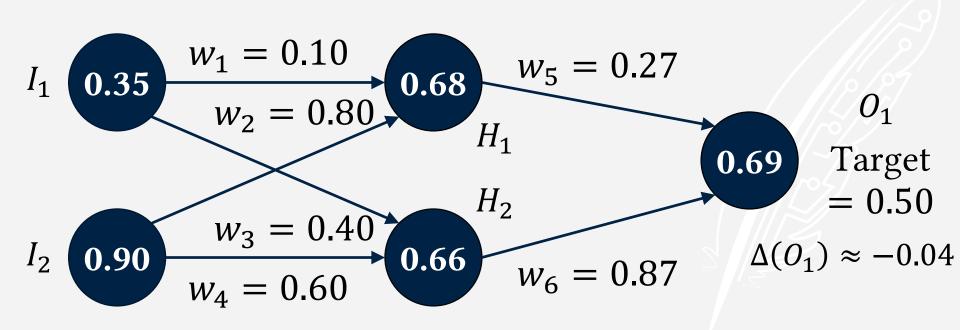
$$\Delta(H_1) = H_1(1 - H_1) \left(w_{H_1 \to O_1} \cdot \Delta(O_1) \right)$$







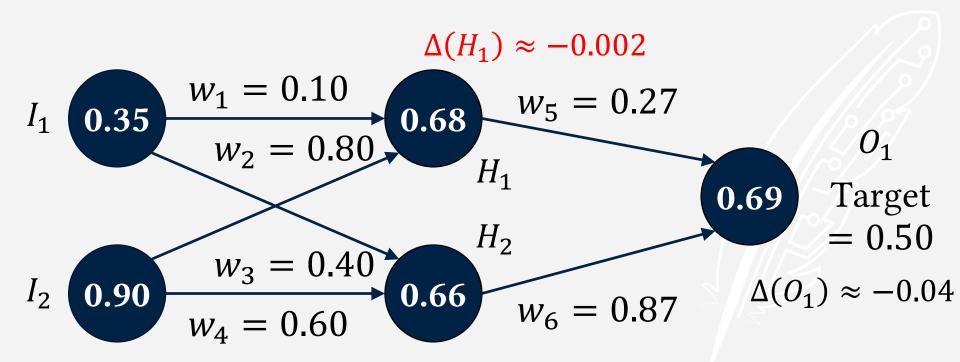
$$\Delta(H_1) = 0.68(1 - 0.68)(0.27 \cdot -0.04)$$







$$\Delta(H_1) \approx -0.002$$







$$\Delta(H_2) = H_2(1 - H_2) \left(w_{H_2 \to O_1} \cdot \Delta(O_1) \right)$$

$$\Delta(H_1) \approx -0.002$$

$$I_1 \quad 0.35 \quad w_1 = 0.10$$

$$w_2 = 0.80 \quad 0.68 \quad w_5 = 0.27$$

$$H_2 \quad 0.69 \quad \text{Target}$$

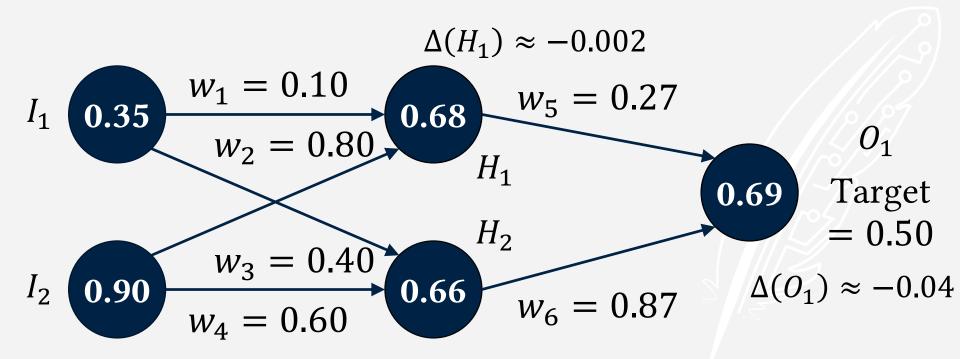
$$= 0.50$$

$$W_3 = 0.40 \quad 0.66 \quad w_6 = 0.87 \quad \Delta(O_1) \approx -0.04$$





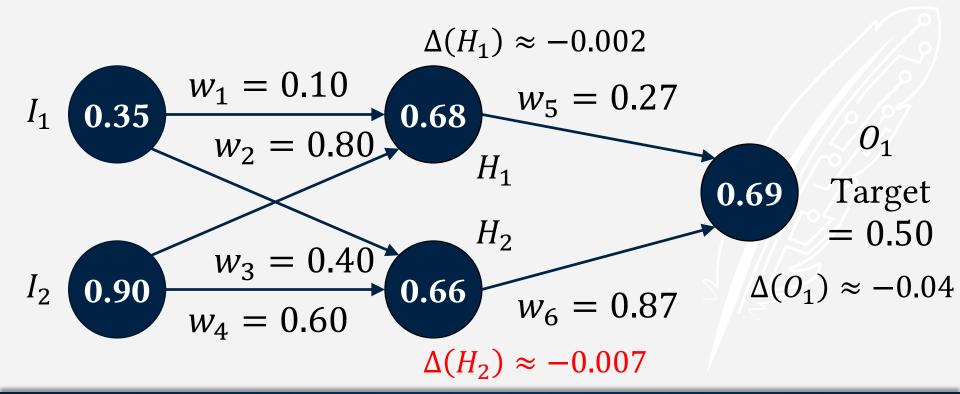
$$\Delta(H_2) = 0.66(1 - 0.66)(0.87 \cdot -0.04)$$







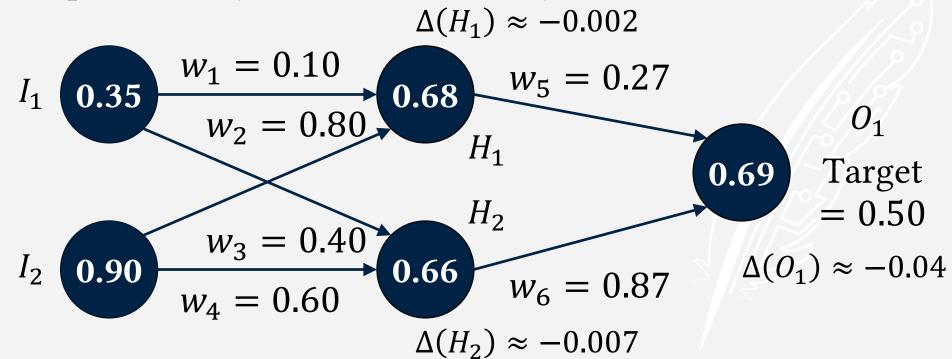
$$\Delta(H_2) \approx -0.007$$







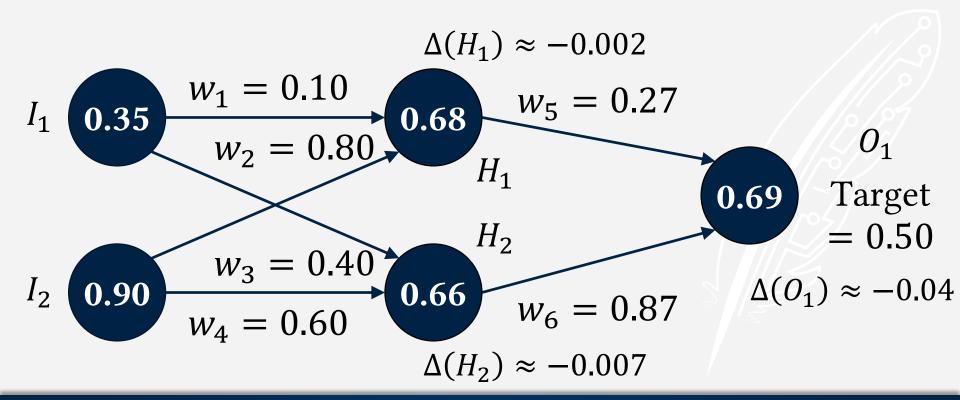
Now we need to update the edges leading from the previous layer to this hidden layer.







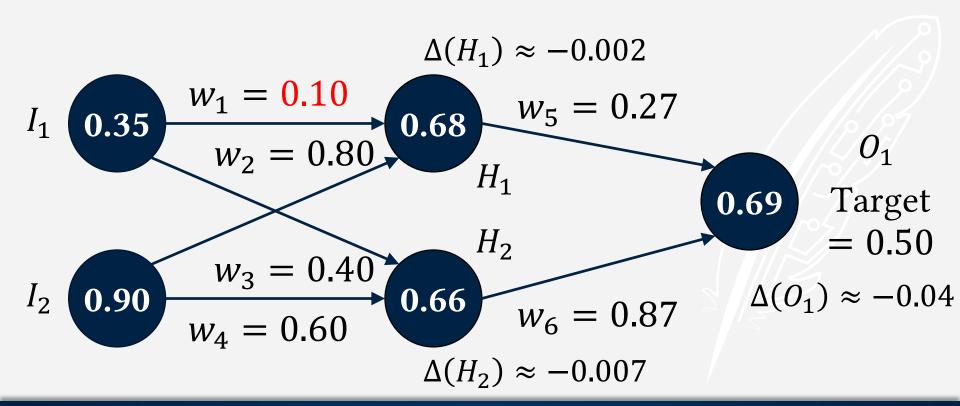
$$w_1 = w_1 + \left(I_1 \cdot \Delta(H_1)\right)$$







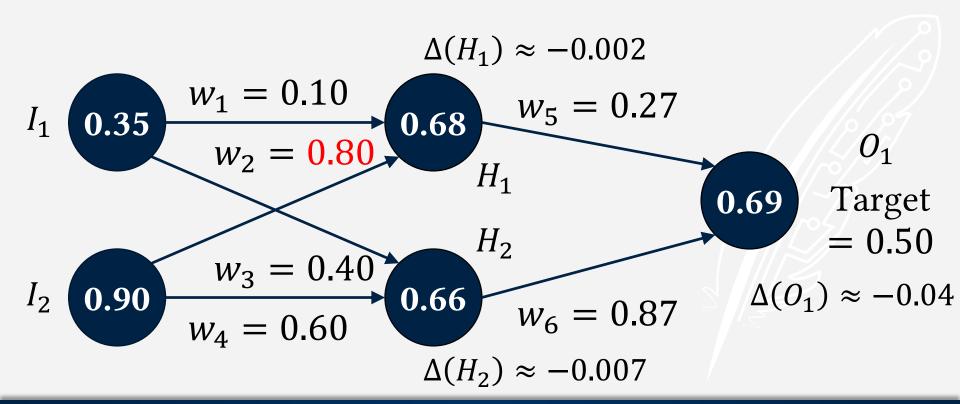
 $w_1 \approx 0.10$







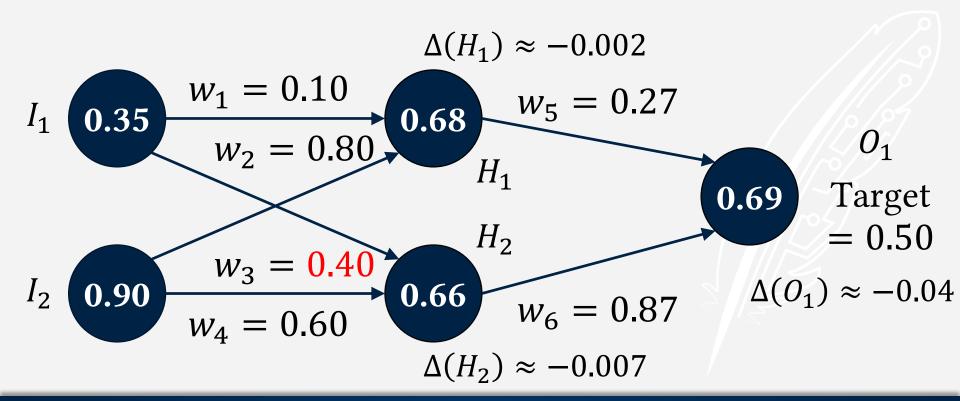
 $w_2 \approx 0.80$







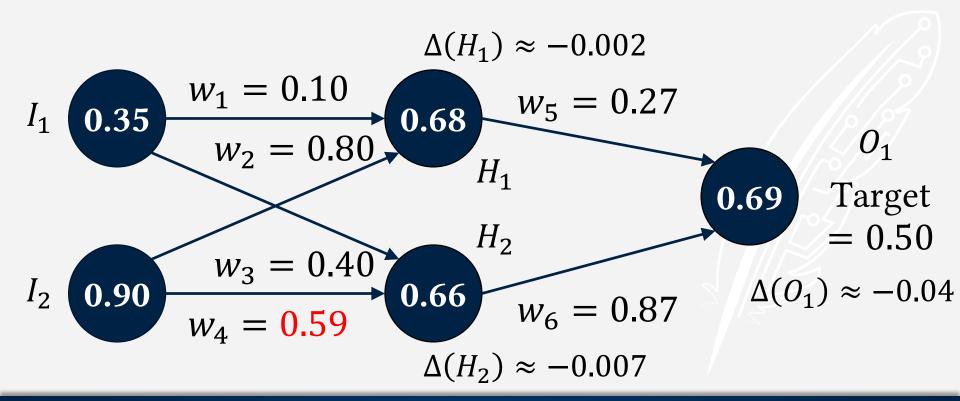
 $w_3 \approx 0.40$







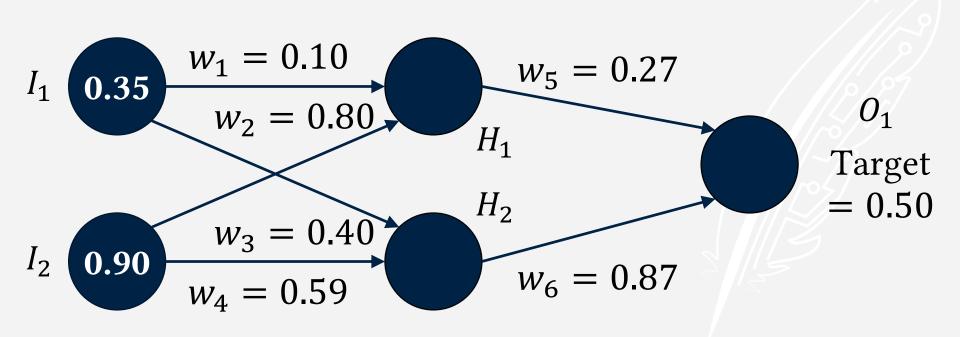
 $W_4 \approx 0.59$







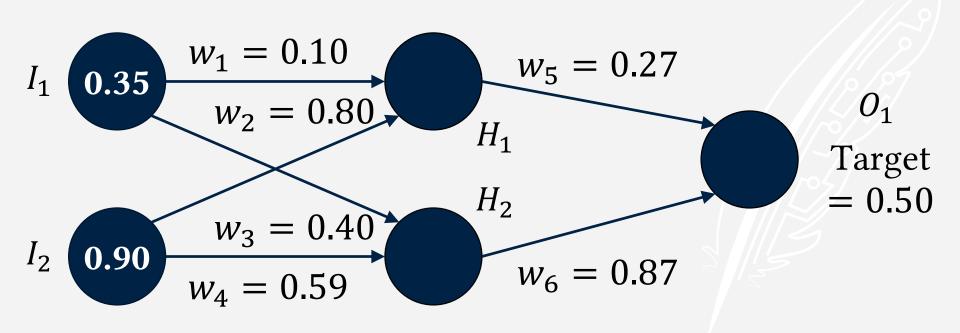
This iteration of back propagation has finished.







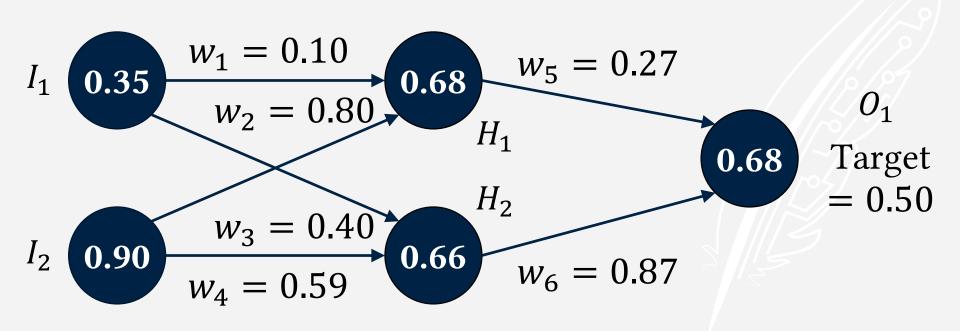
Now we feed values forward again to see what the new output will be.







Now we feed values forward again to see what the new output will be.

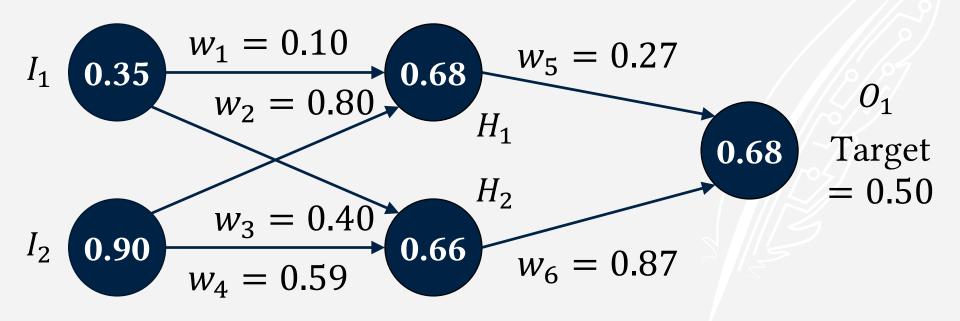






The previous error was 0.50 - 0.69 = -0.19.

The new error is 0.50 - 0.68 = -0.18.







Error has been reduced! We then repeat back propagation until we have reduced it as much as possible.

